# Infinite generation of the kernels of the Magnus and Burau representations

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Consider the kernel  $\mathrm{Mag}_g$  of the Magnus representation of the Torelli group and the kernel  $\mathrm{Bur}_n$  of the Burau representation of the braid group. We prove that for  $g \geq 2$  and for  $n \geq 6$  the groups  $\mathrm{Mag}_g$  and  $\mathrm{Bur}_n$  have infinite rank first homology. As a consequence we conclude that neither group has any finite generating set. The method of proof in each case consists of producing a kind of "Johnson-type" homomorphism to an infinite rank abelian group, and proving the image has infinite rank. For the case of  $\mathrm{Bur}_n$ , we do this with the assistance of a computer calculation.

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### 1 Introduction

#### 1.1 The Magnus kernel

Let  $S := S_{g,1}$  be a compact, connected, oriented surface of genus  $g \ge 2$  with one boundary component. Let  $\operatorname{Mod}_{g,1}$  denote the *mapping class group* of S, which is the group of homotopy classes of orientation-preserving homeomorphisms of S which fix  $\partial S$  pointwise. Let  $\mathcal{I}_{g,1}$  denote the *Torelli group*, which is the subgroup of  $\operatorname{Mod}_{g,1}$  consisting of elements that act trivially on  $H := H_1(S, \mathbb{Z})$ .

The group  $\operatorname{Mod}_{g,1}$  acts on the fundamental group  $\pi_1(S)$ , inducing an action on the solvable quotient  $\Gamma/\Gamma^3$ , where  $\Gamma:=\pi_1(S)$ ,  $\Gamma^2=[\Gamma,\Gamma]$  and  $\Gamma^3=[\Gamma^2,\Gamma^2]$  are the first three terms of the derived series of  $\Gamma$ . In this paper we consider the group

$$\operatorname{Mag}_g := \ker(\operatorname{Mod}(S) \to \operatorname{Aut}(\Gamma/\Gamma^3)).$$

It follows from work of Fox [4, Theorem 4.9] that  $Mag_g$  coincides with the kernel of the so-called *Magnus representation* (see Birman [2, Chapter 3])

$$r: \mathcal{I}_{g,1} \to \mathrm{GL}_{2g}(\mathbb{Z}H).$$

The group  $\operatorname{Mag}_g$  is called the *Magnus kernel*. It was an open question for some time whether or not  $\operatorname{Mag}_g$  is nontrivial. This was settled in the affirmative by Suzuki in [12]. The first main result of this paper is that  $\operatorname{Mag}_g$  is in fact quite large.

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**Theorem 1.1** For  $g \ge 2$  the group  $H_1(\operatorname{Mag}_g, \mathbb{Z})$  has infinite rank.

As the abelianization of a finitely-generated group has finite rank, we deduce the following.

**Corollary 1.2** For  $g \ge 2$  the group Mag<sub>g</sub> has no finite generating set.

The idea of our proof of Theorem 1.1 is to define a kind of "Johnson-type" homomorphism (see Johnson [5]):

$$\Psi: \operatorname{Mag}_{g} \to \operatorname{Hom}\left(G^{\operatorname{ab}}, \bigwedge^{2} G^{\operatorname{ab}}\right)$$

where  $G = [\Gamma, \Gamma]$  and  $G^{ab}$  denotes the abelianization of G. We then construct infinitely many linearly independent elements contained in the image.

It will follow from the definition of  $\Psi$  that  $\Psi$  extends to Mag $(F_n)$ , the "Magnus kernel" for Aut $(F_n)$ . Thus as an immediate corollary we obtain that Mag $(F_n)$  is not finitely generated. Since the first posting of this paper, a different proof of this last result has been given by Satoh [11]. Satoh's approach shows that the image of Mag $(F_n)$  under  $\Psi$  has abelian quotients of arbitrarily large finite rank.

#### 1.2 The Burau kernel

Let  $B_n$  denote the braid group on n strands.  $B_n$  can be realized (see Section 4 below) as a subgroup of the automorphism group  $\operatorname{Aut}(F_n)$  of the free group of rank n. The Burau representation is a homomorphism

$$\rho_n: B_n \to \mathrm{GL}_n(\mathbb{Z}[t, t^{-1}]).$$

We define the *Burau kernel*, denoted  $\operatorname{Bur}_n$ , to be the kernel of  $\rho_n$ . Let K be the kernel of the homomorphism  $F_n \to \mathbb{Z}$  taking each fixed generator of  $F_n$  to 1. It follows easily from Fox [4] that

$$\operatorname{Bur}_n = \ker(B_n \to \operatorname{Aut}(F_n/[K, K])).$$

While  $\rho_3$  is faithful, it was a longstanding problem as to whether or not  $\rho_n$  is faithful (that is, whether Bur<sub>n</sub> is nontrivial) for n > 3. This was solved by Moody [9], Long–Paton [7], and Bigelow [1] in various cases, with the result that Bur<sub>n</sub> is nontrivial for  $n \ge 5$ ; the case of n = 4 is still open. Our next main result is that Bur<sub>n</sub> is in fact quite large for  $n \ge 6$ .

**Theorem 1.3** For  $n \ge 6$  the group  $H_1(\operatorname{Bur}_n, \mathbb{Z})$  has infinite rank; in particular,  $\operatorname{Bur}_n$  has no finite generating set.

To prove Theorem 1.3 we construct, similarly to the proof of Theorem 1.1 above, a homomorphism

Φ: Bur<sub>n</sub> → Hom 
$$(K^{ab}, \bigwedge^2 K^{ab})$$
.

The elements which have been constructed in the kernel of the Burau representation are geometrically elegant, but algebraically very complicated; for example, the element of Bur<sub>7</sub> found by Long-Paton can be described by a single diagram, but as a free group automorphism sends generators of  $F_7$  to words of length up to 475137. Thus we need the assistance of a computer in order to calculate  $\Phi$  explicitly (see Section 4 below for a full discussion). For the computations in this paper we use a simpler element  $\phi_B \in \operatorname{Bur}_n$  for  $n \geq 6$  found by Bigelow, which takes generators to words of length no more than 9841. Once we compute the form of  $\Phi(\phi_B)$ , we then use an equivariance property of  $\Phi$  to prove that the image of  $\Phi$  has infinite rank, from which Theorem 1.3 follows.

We remark that in [10, Problem 6.24] Morita posed the problem of determining the kernel of the Magnus and Burau (among other) representations. Theorem 1.1 and Theorem 1.3 can be viewed as a partial answer to this problem.

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# 2 Defining the homomorphisms

The following construction works for any group G whenever one considers automorphisms of the universal 2-step nilpotent quotient  $G/G_3$  acting trivially on the abelianization  $G^{ab}$ . Johnson [5] considered the case  $G = \Gamma = \pi_1(S)$ .

With  $\Gamma$  equal to  $\pi_1(S)$  or  $F_n$  as in the introduction, we take  $G := [\Gamma, \Gamma]$  or G := K respectively. In either case, let  $G_i$  be the lower central series of G, defined inductively by  $G_1 = G$  and  $G_{i+1} = [G, G_i]$ . Consider the exact sequence

$$(1) 1 \to G_2 \to G \to G^{ab} \to 1.$$

Centralizing (1) gives

$$(2) 1 \rightarrow G_2/G_3 \rightarrow G/G_3 \rightarrow G^{ab} \rightarrow 1.$$

Since G is free, taking (1) as a presentation for  $G^{ab}$ , Hopf's formula gives that

$$G_2/G_3 \approx \bigwedge^2 G^{ab}$$
.

Aut( $\Gamma$ ) acts on  $\Gamma$ , and thus on G, and the isomorphism  $\nu$ :  $G_2/G_3 \approx \bigwedge^2 G^{\mathrm{ab}}$  respects the action of Aut( $\Gamma$ ) on both sides. In particular, conjugation by  $\Gamma$  descends to an action on  $G^{\mathrm{ab}}$  by  $H = \Gamma/[\Gamma, \Gamma]$  or by  $\mathbb{Z} = \Gamma/K$  respectively. In the case  $G = [\Gamma, \Gamma]$ , the fact that Mag<sub>g</sub> acts trivially on  $\Gamma/\Gamma^3$  implies that Mag<sub>g</sub> acts trivially on  $G^{\mathrm{ab}} = \Gamma^2/\Gamma^3$  and on  $\Lambda^2 G^{\mathrm{ab}}$ . Similarly, in the case G = K, we have that Bur<sub>n</sub> acts trivially on  $G^{\mathrm{ab}}$  and on  $\Lambda^2 G^{\mathrm{ab}}$ .

Let  $f \in \operatorname{Mag}_g$  (respectively,  $f \in \operatorname{Bur}_n$ ) be given. For  $x \in G^{\operatorname{ab}}$ , pick any lift  $\widetilde{x} \in G$ . Since f acts trivially on both the quotient and kernel of (2), we see that  $f(\widetilde{x})\widetilde{x}^{-1}$  lies in the kernel  $G_2/G_3$ , which we identify with  $\bigwedge^2 G^{\operatorname{ab}}$  via the isomorphism above. One checks, exactly as in Johnson [5], that

$$\delta_f \colon G^{ab} \to \bigwedge^2 G^{ab}$$

defined by  $\delta_f(x) := f(\widetilde{x})\widetilde{x}^{-1}$  is a well-defined homomorphism; in fact, the resulting map  $\delta_f$  is  $\mathbb{Z}H$ -linear (respectively,  $\mathbb{Z}[t,t^{-1}]$ -linear) with respect to the conjugation action on  $G^{ab}$ . This is equivalent to the claim that

$$\delta_f(\gamma x \gamma^{-1}) \equiv \gamma \delta_f(x) \gamma^{-1} \mod G_3$$
,

which can be checked as follows. The difference between the left and right side is

$$(f(\gamma x \gamma^{-1})\gamma x^{-1} \gamma^{-1})(\gamma f(x) x^{-1} \gamma^{-1})^{-1} = f(\gamma) f(x) f(\gamma)^{-1} \gamma f(x)^{-1} \gamma^{-1},$$

which is conjugate to  $[\gamma^{-1} f(\gamma), f(x)]$ . The condition on f implies that  $f(\gamma) \equiv \gamma \mod G_2$ , so  $\gamma^{-1} f(\gamma) \in G_2$  and  $[\gamma^{-1} f(\gamma), f(x)] \in G_3$  as desired.

One also checks, exactly as in [5], that in the case  $G = [\Gamma, \Gamma]$ , defining the map  $\Psi$  by  $\Psi(f) := \delta_f$  gives a well-defined homomorphism;

(3) 
$$\Psi: \operatorname{Mag}_{g} \to \operatorname{Hom}\left(G^{\operatorname{ab}}, \bigwedge^{2} G^{\operatorname{ab}}\right).$$

and, in the case G = K, defining  $\Phi(f) := \delta_f$  gives a well-defined homomorphism:

(4) 
$$\Phi: \operatorname{Bur}_n \to \operatorname{Hom}\left(G^{\operatorname{ab}}, \bigwedge^2 G^{\operatorname{ab}}\right).$$

The homomorphisms  $\Psi$  and  $\Phi$  are equivariant with respect to the natural actions of  $Aut(\Gamma)$  on the source and target.

## 3 Computing the image of $\Psi$

Let  $S_{0,4}$  denote the 2-sphere with 4 open disks removed. A *lantern* in S is an embedding  $S_{0,4} \hookrightarrow S$ . Consider the two simple closed curves  $\alpha$  and  $\beta$  and the three arcs  $A_1, A_2$  and  $A_3$  on  $S_{0,4}$  given in Figure 1.

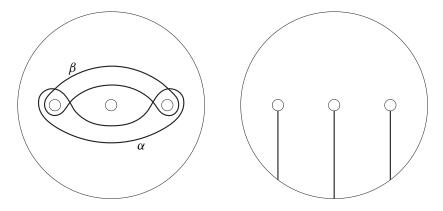


Figure 1: The simple closed curves  $\alpha$  and  $\beta$ , and the arcs  $A_1, A_2, A_3$ 

One directly computes the action of  $f := T_{\alpha}T_{\beta}^{-1}$  on  $A_1$ ,  $A_2$  and  $A_3$ , as follows (see Figure 2). Let x, y, and z be the loops which begin with  $A_1$ ,  $A_2$  and  $A_3$ , respectively, go clockwise around the appropriate boundary component of  $S_{0,4}$ , then come back along the same arc  $A_i$ . Let X, Y, Z be the inverses of x, y, z in  $\pi_1(S_{0,4})$ . Then:

$$f(A_1) = xyXzxYXZA_1 = [xyX, z]A_1$$
  

$$f(A_2) = ZXzxA_2 = [Z, X]A_2$$
  

$$f(A_3) = ZXzxYXZxzxyXA_3 = [ZXz, xYX]A_3$$

Let L be an embedding of a lantern in S with the property that each of the four boundary curves of L are separating in S. In this case we can observe that  $T_{\alpha}T_{\beta}^{-1} \in \operatorname{Mag}_g$ , as follows. Note that the elements corresponding to x, y, z all lie in  $\Gamma^2$ . Furthermore,  $\Gamma = \pi_1(S)$  has a basis where each element c is either disjoint from L, or else of the form  $c = A\gamma A^{-1}$ , where A is an arc intersecting L in some  $A_i$  and  $\gamma$  is a loop disjoint from L. In the former case the element  $f = T_{\alpha}T_{\beta}^{-1}$  fixes c. In the latter case, assume for example that A intersects L in  $A_2$ ; then we have

$$f(c) = f(A\gamma A^{-1}) = f(A)\gamma f(A)^{-1} = [Z, X]A\gamma A^{-1}[X, Z] = [Z, X]c[X, Z]$$

<sup>&</sup>lt;sup>1</sup>To formally identify x, y, z with elements of  $\Gamma = \pi_1(S)$ , we choose a basepoint on  $\partial S$ , and arcs from this basepoint to L meeting L in one point. Since f is the identity off of L, any ambiguity in the choice of these paths to L does not affect the computation.

Since  $x, y, z \in \Gamma^2$ , we have  $[Z, X] \in \Gamma^3$ ; thus  $f(c) \equiv c \mod \Gamma^3$ . The same is true for  $A_1$  and  $A_3$ , so we conclude that  $f(c) \equiv c \mod \Gamma^3$  for all elements of a basis for  $\Gamma$ , implying  $T_{\alpha}T_{\beta}^{-1} \in \mathrm{Mag}_g$ . Suzuki gave a more illuminating proof that elements of this form lie in  $\mathrm{Mag}_g$  in [13].



Figure 2: The arcs  $f(A_1)$ ,  $f(A_2)$  and  $f(A_3)$ 

We are now ready to compute  $\Psi$ . For  $a, b \in \Gamma$ , we denote by  $\{a, b\}$  the image in  $G^{ab}$  of  $[a, b] \in G$  under the abelianization map.

**Proposition 3.1** Let L be a lantern embedded in S so that each of the four boundary curves of L are separating in S. Let a and b be loops intersecting L in  $A_1$  and  $A_2$ . Then

(5) 
$$\Psi(T_{\alpha}T_{\beta}^{-1})(\{a,b\}) = (a-1)(b-1)[x \wedge z + y \wedge z].$$

Note that the right hand side of (5) is an element of  $\bigwedge^2 G^{ab}$ , considered as a  $\mathbb{Z}H$ -module, and the action of a and b on this module factors through H.

**Proof** As in the computation above, we have

$$f([a,b]) = [f(a), f(b)] = [wa, vb]$$

where

$$w = [[xyX, z], a]$$
 and  $v = [[Z, X], b]$ .

From the assumption on the embedding of L we have  $x, y, z \in G$ , and thus  $w, v \in G_2$ . We will use the following commutator identities, which hold in any group; we write x for  $xyx^{-1}$ .

$$[wa, b] = {}^{w}[a, b] [w, b]$$
  $[a, vb] = [a, v] {}^{v}[a, b]$ 

We then find that

$$[wa, vb] = {}^{w}[a, v] {}^{wv}[a, b] [w, v] {}^{v}[w, b].$$

Note that the second term lies in G, the first and fourth in  $G_2$ , and the third in  $G_3$ .

We want to compute  $f([a,b])[a,b]^{-1}$  as an element of the quotient  $G_2/G_3$ . Note that  $[w,v] \equiv 0 \mod G_3$ , and that conjugating an element of G by an element of  $G_2$  is a trivial operation modulo  $G_3$ . Finally, since  $[[a,b],[w,b]] \in G_3$ , we can move [a,b] to the right to cancel  $[a,b]^{-1}$ . We thus obtain

$$f([a,b])[a,b]^{-1} = {}^{w}[a,v] {}^{wv}[a,b] [w,v] {}^{v}[w,b] [a,b]^{-1}$$
$$\equiv [a,v][a,b][w,b][a,b]^{-1} \bmod G_3$$
$$\equiv [a,v][w,b] \bmod G_3.$$

Recall that the action of  $\Gamma$  on  $\Gamma$  by conjugation descends to a  $\mathbb{Z}H$  action on  $G^{ab}$ . Recall from above the isomorphism  $\nu: G_2/G_3 \to \bigwedge^2 G^{ab}$ . Since the homology class of x is trivial in H, we have

$$\nu([xyX,z]) = y \wedge z \text{ and } \nu([Z,X]) = z \wedge x.$$

It follows that

$$\nu(w) = \nu([[xyX, z], a]) = (1 - a)y \wedge z$$

and

$$v(v) = v([[Z, X], b]) = (1 - b)z \wedge x.$$

We therefore have that

$$v([a, v][w, b]) = (a-1)v - (b-1)w = (a-1)(1-b)z \wedge x - (b-1)(1-a)v \wedge z.$$

We conclude that

$$\Psi(T_{\alpha}T_{\beta}^{-1})(\{a,b\}) = (a-1)(b-1)[x \wedge z + y \wedge z]$$

as desired.

#### **Theorem 3.2** The image of $\Psi$ has infinite rank for $g \geq 3$ .

**Proof** Let  $\gamma$  and  $\delta_k$  be the curves depicted in Figure 3. The figure depicts the case k=3; in general  $\delta_k$  has k twists around the upper right handle. (Specifically, the curve  $\delta_k$  is equal to  $T_{a_3}^k(\delta_0)$ , where  $a_3$  is as in Figure 5.) The regular neighborhood of  $\gamma \cup \delta_k$  is a lantern  $L_k$ , and we fix an identification of  $L_k$  with our reference lantern L by specifying that  $\gamma$  and  $\delta_k$  should correspond to xy and yz respectively. Let  $f_k \in \operatorname{Mag}_g$  be the element corresponding under this identification to the mapping class  $T_{\alpha}T_{\beta}^{-1}$  on L; it is easy to check using the lantern relation that  $f_k$  is in fact  $[T_{\gamma}^{-1}, T_{\delta_k}^{-1}]$ . We will show that the images  $\Psi(f_k)$  are linearly independent (over  $\mathbb{Z}$ ).

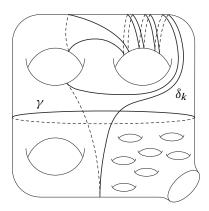


Figure 3: The curves  $\gamma$  and  $\delta_k$  for k=3

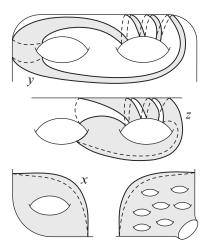


Figure 4: The boundary curves of  $L_k$ ; the subsurfaces cut off by these curves are shaded

The boundary curves of  $L_k$  are depicted in Figure 4.

With the basis  $a_1,b_1,\ldots,a_g,b_g$  for  $\pi_1(S_{g,1})$  as illustrated in Figure 5, we see that as curves x, y and z can be represented by  $[a_1,b_1]$ ,  $[a_2,b_3a_3^kb_2]$  and  $[b_2a_2^{-1}b_2^{-1}a_3,b_3a_3^k]$  respectively. As based loops, we actually have the conjugate  $z={}^c[b_2a_2^{-1}b_2^{-1}a_3,b_3a_3^k]$ , where  $c=[b_3,a_3][b_2,a_2]a_2$ . Note that with this representative for z, we have  $xyz=[a_1,b_1][a_2,b_2][a_3,b_3]$ , the fourth boundary curve in Figure 4.

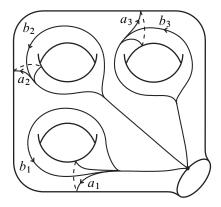


Figure 5: A basis for  $\pi_1(S_{g,1})$ 

Note that  $a_1$  and  $a_2$  intersect each  $L_k$  in arcs corresponding to  $A_1$  and  $A_2$ . Thus by Proposition 3.1, we have

$$\begin{split} \Psi(f_k)(\{a_1,a_2\}) = \\ (a_1-1)(a_2-1) \big[ \big(\{a_1,b_1\} + \{a_2,b_3a_3^kb_2\}\big) \wedge a_2 \{b_2a_2^{-1}b_2^{-1}a_3,b_3a_3^k\} \big]. \end{split}$$

Denote this element of  $\bigwedge^2 G^{ab}$  by  $\alpha_k$ . We now check that the elements  $\{\alpha_k\}$  are linearly independent as follows. There is a standard embedding  $G^{ab} \hookrightarrow (\mathbb{Z}H)^{2g}$  given by sending the class [x] to  $(\partial x/\partial z_1,\dots,\partial x/\partial z_{2g})$ , where  $\{z_i\}$  is our basis for  $\pi_1(S)=F_{2g}$  and where  $\partial/\partial z_i$  are the Fox derivatives (see, for example, Church–Pixton [3] for a detailed explanation of this embedding). The only property of this embedding that we will need is that the elements below, which together make up  $\alpha_k$ , are mapped as follows by the embedding. Here the  $A_i$  and  $B_i$  make up a  $\mathbb{Z}H$ -basis for  $(\mathbb{Z}H)^{2g}$ .

$$\begin{aligned} \{a_1, b_1\} &\mapsto (1 - b_1)A_1 - (1 - a_1)B_1 \\ \{a_2, b_3 a_3^k b_2\} &\mapsto (1 - b_3 a_3^k b_2)A_2 \\ &\quad - (1 - a_2) \left(B_3 + b_3 (1 + \dots + a_3^{k-1})A_3 + b_3 a_3^k B_2\right) \\ \{b_2 a_2^{-1} b_2^{-1} a_3, b_3 a_3^k\} &\mapsto (1 - b_3 a_3^k) \left((1 - a_2^{-1})B_2 - a_2^{-1} b_2 A_2 + a_2^{-1} A_3\right) \\ &\quad - (1 - a_2^{-1} a_3) \left(B_3 + b_3 (1 + \dots + a_3^{k-1})A_3\right) \end{aligned}$$

By expanding out  $\alpha_k$ , we see that  $\alpha_N$  is the only such element which contains the term  $A_1 \wedge b_3 a_3^N B_2$  with nonzero coefficient; it follows that the  $\alpha_k$  are linearly independent, as desired.

As the image of  $\Psi$  is abelian, Theorem 3.2 immediately implies Theorem 1.1 for  $g \ge 3$ . Note that the proof of Theorem 3.2 used in an essential way that  $g \ge 3$ . So in order to complete the proof of Theorem 1.1, we need another argument when g = 2.

**Theorem 3.3**  $H_1(Mag_2)$  has infinite rank; in fact,  $Mag_2$  surjects to a free group of infinite rank.

**Proof** Suzuki showed that the element  $f = [T_{\gamma}, T_{\delta}]$  is in Mag<sub>2</sub> for  $\gamma$  and  $\delta$  as in Figure 6; in particular Mag<sub>2</sub> is nontrivial. Let  $S_2$  be a closed surface of genus 2; we denote by  $\mathcal{I}_{2,*}$  the Torelli group of  $S_2$  with respect to a marked point \*, and by  $\mathcal{I}_2$  the Torelli group of the closed surface  $S_2$ . By Johnson [6], we have the exact sequence

$$1 \longrightarrow \mathbb{Z} \longrightarrow \mathcal{I}_{2,1} \xrightarrow{p} \mathcal{I}_{2,*} \longrightarrow 1,$$

where the kernel is generated by a twist  $T_{\omega}$  around the boundary  $\omega = \partial S_2$ . It is easy to check that the action of  $T_{\omega}$  on  $\pi_1(S_{2,1})$  is conjugation by  $\omega$ ; since  $\omega \notin \Gamma^3$ , we see that  $T_{\omega} \notin \operatorname{Mag}_2$ .

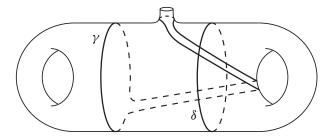


Figure 6: The commutator  $[T_{\gamma}, T_{\delta}]$  lies in Mag<sub>2</sub>

It follows that p restricts to an isomorphism between  $Mag_2$  and a subgroup  $p(Mag_2) < \mathcal{I}_{2,*}$ .

Again by Johnson [6], we have the exact sequence

$$1 \longrightarrow \Lambda \longrightarrow \mathcal{I}_{2,*} \stackrel{\pi}{\longrightarrow} \mathcal{I}_2 \longrightarrow 1,$$

where  $\Lambda \approx \pi_1(S_2,*)$ ; note that  $\mathcal{I}_{2,*}$  acts on  $\pi_1(S_2,*)$ , and the restriction to  $\Lambda$  is just the action by conjugation. Mess [8] proved that  $\mathcal{I}_2$  is free of infinite rank. It is easy to see from Figure 6 that f lies in  $\ker \pi = \Lambda$ . We use the following well-known lemma.

**Lemma 3.4** Any nontrivial infinite index normal subgroup of a surface group or free group is an infinite rank free group.

If the image  $\pi \circ p(\mathrm{Mag}_2) < \mathcal{I}_2 \approx F_\infty$  is nontrivial, it is an infinite rank free group; it either has finite index in  $F_\infty$  and thus infinite rank, or infinite index, in which case Lemma 3.4 applies. Thus  $\mathrm{Mag}_2$  surjects to the infinite rank free group  $\pi \circ p(\mathrm{Mag}_2)$ , and we are done.

Otherwise  $p(\mathrm{Mag}_2) \subset \ker \pi = \Lambda$ . Any  $\varphi \in \mathrm{Mag}_2$  acts trivially on  $\Gamma/\Gamma^3$ ; thus  $p(\varphi)$  acts trivially on  $\pi_1(S_2)/\pi_1(S_2)^3$ . Since the action of  $\Lambda$  is by conjugation, this implies that  $p(\varphi)$  lies in  $\Lambda^3$ . Thus  $p(\mathrm{Mag}_2)$  has infinite index in  $\Lambda$ , and so by Lemma 3.4,  $p(\mathrm{Mag}_2) \approx \mathrm{Mag}_2$  is an infinite rank free group.

Theorem 1.1, and hence Corollary 1.2, follows immediately from Theorems 3.2 and 3.3.

**Remark** One can check by explicit computation that for Suzuki's element  $f \in \text{Mag}_2$  above,  $\Psi(f) = 0$ . It would be interesting to know whether  $\Psi$  in fact vanishes on  $\text{Mag}_2$ .

## 4 Computing the image of $\Phi$

The kernel K of the map from  $F_n = \langle x_1, \dots, x_n \rangle$  to  $\mathbb{Z} = \langle t \rangle$  which sends each  $x_i \mapsto t$  is normally generated by the elements  $x_i x_j^{-1}$ . If we set  $x_{i,k} := x_1^k x_i x_1^{-k-1}$  for  $i \neq 1$  and  $k \in \mathbb{Z}$ , then  $\{x_{i,k}\}$  gives a basis for K as a free group. As above, the action of  $F_n$  on K by conjugation descends to a  $\mathbb{Z}[t, t^{-1}]$  action on  $K^{ab}$ . With respect to this action we have  $x_{i,k} = t^k x_{i,0}$ , and thus  $K^{ab}$  is a free  $\mathbb{Z}[t, t^{-1}]$ -module with basis  $\{y_i = x_{i,0}\}_{i \neq 1}$ .

The braid group  $B_n$  has generators  $\sigma_1, \ldots, \sigma_{n-1}$ ; the action of  $\sigma_i$  on  $F_n$  sends  $x_i \mapsto x_i x_{i+1} x_i^{-1}$ ,  $x_{i+1} \mapsto x_i$ , and fixes the other generators. The action of  $B_n$  on  $K^{ab}$  commutes with the  $\mathbb{Z}[t, t^{-1}]$  action.

**Theorem 4.1** The image of  $\Phi$  has infinite rank for  $n \ge 6$ .

**Proof** The element of Bur<sub>6</sub> found by Bigelow in [1] is the commutator of the half-twists along the arcs displayed in Figure 7. In terms of the Artin generators, this is

$$\phi_B = [\psi_1 \sigma_3^{-1} \psi_1^{-1}, \psi_2 \sigma_3^{-1} \psi_2],$$

where

$$\psi_1 = \sigma_4 \sigma_5^{-1} \sigma_2^{-1} \sigma_1$$
 and  $\psi_2 = \sigma_4^{-1} \sigma_5^2 \sigma_2 \sigma_1^{-1}$ .

In Appendix A, we give the computation of  $\alpha := \Phi(\phi_B)([x_2x_1^{-1}]) = \Phi(\phi_B)(y_2)$ ; it has 262 terms. The only fact about  $\alpha$  that we will need is that its highest term of the form

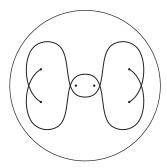


Figure 7: The two arcs defining Bigelow's element  $\phi_B$ 

 $y_2 \wedge t^j y_4$  is  $-2y_2 \wedge t^3 y_4$ , and its highest term of the form  $y_2 \wedge t^j y_5$  is  $+2y_2 \wedge t^2 y_5$  (these terms are set in boxes in the appendix).

It is easy to check that

$$\sigma_4^2(x_4) = x_4 x_5 x_4 x_5^{-1} x_4^{-1}$$

$$\sigma_4^2(x_5) = x_5 x_4 x_5^{-1}$$

$$\sigma_4^2(x_i) = x_i \text{ for } i \neq 4, 5.$$

By induction, for  $k \ge 1$  we have

$$\sigma_4^{2k}(x_4) = (x_4 x_5)^k x_4 (x_4 x_5)^{-k}$$

$$\sigma_4^{2k}(x_5) = (x_4 x_5)^{k-1} x_4 x_5 x_4^{-1} (x_4 x_5)^{k-1}$$

$$\sigma_4^{2k}(x_i) = x_i \text{ for } i \neq 4, 5.$$

The action of  $\sigma_4^{2k}$  on  $K^{ab}$  in terms of our basis is thus given by:

$$y_4 \mapsto (1 - t + t^2 - \dots - t^{k-1} + t^k) y_4 + (t - t^2 + \dots + t^{k-1} - t^k) y_5$$
  
$$y_5 \mapsto (1 - t + t^2 - \dots - t^{k-1}) y_4 + (t - t^2 + \dots + t^{k-1}) y_5$$
  
$$y_i \mapsto y_i \quad \text{for } i \neq 4, 5$$

Now for  $k \ge 0$  set

$$\alpha_k := \Phi(\sigma_4^{2k} \phi_B \sigma_4^{-2k})(y_2).$$

By the equivariance of  $\Phi$ , and since  $\sigma_4$  fixes  $y_2$ , we have  $\alpha_k = \sigma_4^{2k} \cdot \alpha$ . From the action of  $\sigma_4^{2k}$  on  $K^{ab}$ , we can see that the highest term in  $\alpha_N$  of the form  $y_2 \wedge t^j y_4$  will be  $-2y_2 \wedge t^{3+N}y_4$ . Thus  $\alpha_N$  is not contained in the span of  $\{\alpha_1, \ldots, \alpha_{N-1}\}$ ; it follows that the  $\alpha_k$  are linearly independent over  $\mathbb{Z}$ , and thus the image of  $\Phi$  has infinite rank.

Theorem 1.3 follows immediately.

## Appendix A Appendix

The following computation was made, with the method explained in Section 4, with the help of *Mathematica*. A *Mathematica* notebook implementing these computations can be found at http://math.uchicago.edu/~tchurch/infinitegeneration.html or from the abstract page for this article.

The output of this notebook is  $\Phi(\phi_B)(y_2)$ , which is:

```
-t^{-3}v_2 \wedge t^{-2}v_2 + t^{-3}v_2 \wedge t^{-1}v_2 - t^{-3}v_2 \wedge v_2
                                                        -t^{-2}y_2 \wedge y_2 + t^{-1}y_2 \wedge y_2
  +t^{-2}y_2 \wedge ty_2 + t^{-1}y_2 \wedge ty_2 -2y_2 \wedge t^2y_2 + ty_2 \wedge t^3y_2 + t^2y_2 \wedge t^3y_2
  -t^3y_2 \wedge t^4y_2 + t^{-3}y_2 \wedge t^{-4}y_3 - t^{-2}y_2 \wedge t^{-4}y_3 - t^{-3}y_2 \wedge t^{-3}y_3 + t^{-1}y_2 \wedge t^{-3}y_3
+y_4 \wedge ty_4 + 2t^{-1}y_2 \wedge t^2y_4 - t^{-1}y_3 \wedge t^2y_4 - t^3y_3 \wedge t^2y_4
    +t^3y_3\wedge ty_4
  -t^{-2}y_2 \wedge t^{-3}y_5 + t^{-3}y_2 \wedge t^{-2}y_5 - t^{-2}y_2 \wedge t^{-2}y_5 + y_2 \wedge t^{-2}y_5 - t^{-4}y_3 \wedge t^{-2}y_5
+t^{-3}y_3 \wedge t^{-2}y_5 -t^{-1}y_3 \wedge t^{-2}y_5 -t^{-3}y_4 \wedge t^{-2}y_5 +t^{-2}y_4 \wedge t^{-2}y_5 -y_4 \wedge t^{-2}y_5
-t^{-3}y_5 \wedge t^{-2}y_5 - 2t^{-3}y_2 \wedge t^{-1}y_5 + t^{-1}y_2 \wedge t^{-1}y_5 + y_2 \wedge t^{-1}y_5 - ty_2 \wedge t^{-1}y_5
+t^{-4}y_3 \wedge t^{-1}y_5 - t^{-2}y_3 \wedge t^{-1}y_5 + 2y_3 \wedge t^{-1}y_5 + t^{-3}y_4 \wedge t^{-1}y_5 - t^{-1}y_4 \wedge t^{-1}y_5
 +2ty_4 \wedge t^{-1}y_5 + t^{-3}y_5 \wedge t^{-1}y_5 + t^{-3}y_2 \wedge y_5 + 2t^{-2}y_2 \wedge y_5 - 2t^{-1}y_2 \wedge y_5
       -t y_3 \wedge y_5
                     -t^3y_4 \wedge y_5 + t^{-1}y_5 \wedge y_5 - t^{-3}y_2 \wedge ty_5 - t^{-1}y_2 \wedge ty_5
     -t^2 y_4 \wedge y_5
                      +ty_2 \wedge ty_5 + t^3 y_2 \wedge ty_5 + t^{-1} y_3 \wedge ty_5 - y_3 \wedge ty_5
      +y_2 \wedge ty_5
    +2y_2 \wedge t^2 y_5 -t^2 y_2 \wedge t^2 y_5 +t^3 y_2 \wedge t^2 y_5 -t^{-1} y_3 \wedge t^2 y_5 -t^2 y_3 \wedge t^2 y_5
    -t y_2 \wedge t^3 y_5
    +ty_5 \wedge t^3 y_5 + t^2 y_5 \wedge t^3 y_5 + t^2 y_2 \wedge t^4 y_5 + t^3 y_2 \wedge t^4 y_5 - ty_3 \wedge t^4 y_5
                                     +t^{4}y_{4}\wedge t^{4}y_{5}
                      -t^2 v_4 \wedge t^4 v_5
                                                        -t^2 y_5 \wedge t^4 y_5 \qquad -t^3 y_5 \wedge t^4 y_5
   +t^{3}v_{3}\wedge t^{4}v_{5}
```

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-t^3y_2\wedge t^5y_5 + t^2y_3\wedge t^5y_5 -t^3y_3\wedge t^5y_5 + t^3y_4\wedge t^5y_5 -t^4y_4\wedge t^5y_5
   +t^3y_5 \wedge t^5y_5 - t^{-3}y_2 \wedge t^{-3}y_6 + t^{-2}y_2 \wedge t^{-3}y_6 - t^{-2}y_5 \wedge t^{-3}y_6 + t^{-1}y_5 \wedge t^{-3}y_6
+t^{-3}y_2 \wedge t^{-2}y_6 - t^{-1}y_2 \wedge t^{-2}y_6 + t^{-2}y_5 \wedge t^{-2}y_6 - y_5 \wedge t^{-2}y_6 + t^{-3}y_2 \wedge t^{-1}y_6
-t^{-2}y_2 \wedge t^{-1}y_6 + y_2 \wedge t^{-1}y_6 - t^{-4}y_3 \wedge t^{-1}y_6 + t^{-3}y_3 \wedge t^{-1}y_6 - t^{-1}y_3 \wedge t^{-1}y_6
-t^{-3}y_4 \wedge t^{-1}y_6 + t^{-2}y_4 \wedge t^{-1}y_6 - y_4 \wedge t^{-1}y_6 - t^{-3}y_5 \wedge t^{-1}y_6 + ty_5 \wedge t^{-1}y_6
+t^{-3}y_6 \wedge t^{-1}y_6 - t^{-2}y_6 \wedge t^{-1}y_6 - t^{-3}y_2 \wedge y_6 - t^{-2}y_2 \wedge y_6 + t^{-1}y_2 \wedge y_6
      -t^{-1}y_3 \wedge y_6
    -t^{-1}y_4 \wedge y_6
                       +ty_5 \wedge y_6 \qquad -2t^2 y_5 \wedge y_6
-y_2 \wedge ty_6 \qquad -ty_2 \wedge ty_6
-2ty_3 \wedge ty_6 \qquad -t^3 y_3 \wedge ty_6
                                                                      -t^{-2}y_6 \wedge y_6 + t^{-3}y_2 \wedge ty_6
        -y_5 \wedge y_6
                                                                      -t^3y_2 \wedge ty_6 \qquad -t^{-1}y_3 \wedge ty_6
   +t^{-2}y_2 \wedge ty_6
                                                                                                 +ty_4 \wedge ty_6
                                                                           -y_4 \wedge ty_6
       +y_3 \wedge ty_6
                       -t^4y_4 \wedge ty_6 + t^{-2}y_5 \wedge ty_6
                                                                      +t^{-1}y_5 \wedge ty_6 + t^2y_5 \wedge ty_6
    -2t^2y_4 \wedge ty_6
                                                                      -t^{-2}y_2 \wedge t^2y_6 - t^{-1}y_2 \wedge t^2y_6
    +t^3y_5 \wedge ty_6 + t^{-1}y_6 \wedge ty_6 + 2y_6 \wedge ty_6
   +t^2y_2\wedge t^2y_6 + t^{-1}y_3\wedge t^2y_6 + t^2y_3\wedge t^2y_6 + t^3y_3\wedge t^2y_6 + y_4\wedge t^2y_6
   +t^3y_4\wedge t^2y_6 + t^4y_4\wedge t^2y_6 - t^{-1}y_5\wedge t^2y_6 + ty_5\wedge t^2y_6 - t^2y_5\wedge t^2y_6
 -t^2y_3 \wedge t^5y_6 + t^3y_3 \wedge t^5y_6
                                                -t^3 y_4 \wedge t^5 y_6 + t^4 y_4 \wedge t^5 y_6 - t^3 y_5 \wedge t^5 y_6
   +t^3 v_6 \wedge t^5 v_6
                       -t^{4}v_{6}\wedge t^{5}v_{6}
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