

# ANALYSIS & PDE

Volume 9

No. 4

2016

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**CHARACTERIZING REGULARITY OF DOMAINS  
VIA THE RIESZ TRANSFORMS ON THEIR BOUNDARIES**



# CHARACTERIZING REGULARITY OF DOMAINS VIA THE RIESZ TRANSFORMS ON THEIR BOUNDARIES

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Under mild geometric measure-theoretic assumptions on an open subset  $\Omega$  of  $\mathbb{R}^n$ , we show that the Riesz transforms on its boundary are continuous mappings on the Hölder space  $C^\alpha(\partial\Omega)$  if and only if  $\Omega$  is a Lyapunov domain of order  $\alpha$  (i.e., a domain of class  $C^{1+\alpha}$ ). In the category of Lyapunov domains we also establish the boundedness on Hölder spaces of singular integral operators with kernels of the form  $P(x - y)/|x - y|^{n-1+l}$ , where  $P$  is any odd homogeneous polynomial of degree  $l$  in  $\mathbb{R}^n$ . This family of singular integral operators, which may be thought of as generalized Riesz transforms, includes the boundary layer potentials associated with basic PDEs of mathematical physics, such as the Laplacian, the Lamé system, and the Stokes system. We also consider the limiting case  $\alpha = 0$  (with  $VMO(\partial\Omega)$  as the natural replacement of  $C^\alpha(\partial\Omega)$ ), and discuss an extension to the scale of Besov spaces.

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## 1. Introduction

Let  $\Omega \subset \mathbb{R}^n$  be an open set. Singular integral operators mapping functions on  $\partial\Omega$  into functions defined either on  $\partial\Omega$  or in  $\Omega$  arise naturally in many branches of mathematics and engineering. From the work of G. David and S. Semmes [1991; 1993] we know that uniformly rectifiable (UR) sets make up the most general context in which Calderón–Zygmund-like operators are bounded on Lebesgue spaces  $L^p$ , with  $p \in (1, \infty)$  (see [Theorem 3.1](#) in the body of the paper for a concrete illustration of the scope of this theory). David and Semmes have also proved that, under the background assumption of Ahlfors regularity, uniform rectifiability is implied by the simultaneous  $L^2$ -boundedness of all integral convolution-type operators on  $\partial\Omega$ , whose kernels are smooth, odd, and satisfy standard growth conditions (see [\[David and Semmes 1993, Definition 1.20, p. 11\]](#)). In fact, a remarkable recent result proved by F. Nazarov, X. Tolsa,

*MSC2010:* primary 42B20, 42B37; secondary 35J15, 15A66.

*Keywords:* singular integral, Riesz transform, uniform rectifiability, Hölder space, Lyapunov domain, Clifford algebra, Cauchy–Clifford operator, BMO, VMO, Reifenberg flat, SKT domain, Besov space.

and A. Volberg [Nazarov et al. 2014] states that the  $L^2$ -boundedness of the Riesz transforms alone yields uniform rectifiability. The corresponding result in the plane was proved much earlier in [Mattila et al. 1996].

The above discussion points to uniform rectifiability as being intimately connected with the boundedness of a large class of Calderón–Zygmund-like operators on Lebesgue spaces. This being said, uniform rectifiability is far too weak to guarantee, by itself, analogous boundedness properties in other functional analytic contexts, such as the scale of Hölder spaces  $\mathcal{C}^\alpha$ , with  $\alpha \in (0, 1)$ .

The goal of this paper is to identify the category of domains for which the Riesz transforms are bounded on Hölder spaces as the class of Lyapunov domains (see Definition 2.1), and also show that, in fact, a much larger family of singular integral operators (generalizing the Riesz transforms) act naturally in this setting. On this note we wish to remark that the trademark property of Lyapunov domains is the Hölder continuity of their outward unit normals. Alternative characterizations, of a purely geometric flavor, may be found in [Alvarado et al. 2011]. The issue of boundedness of singular integral operators on Hölder spaces has a long history, with early work focused on Cauchy-type operators in the plane (see [Muskhelishvili 1953; Gakhov 1966], and the references therein). More recently this topic has been considered in [Dyn'kin 1979; 1980; Fabes et al. 1999; García-Cuerva and Gatto 2005; Gatto 2009; Kress 1989; Mateu et al. 2009; Meyer 1990, Chapter X, §4; Taylor 2000; Wittmann 1987].

Consider an Ahlfors regular subset  $\Sigma$  of  $\mathbb{R}^n$  (i.e., a closed, nonempty set satisfying (2-21)), and equip it with  $\mathcal{H}^{n-1}$ , the  $(n-1)$ -dimensional Hausdorff measure in  $\mathbb{R}^n$  restricted to  $\Sigma$ . The latter measure happens to be a positive, locally finite, complete, doubling, Borel regular (hence Radon) measure on  $\Sigma$ . In particular, the Lebesgue scale  $L^p(\Sigma)$ ,  $0 < p \leq \infty$ , is always understood with respect to the aforementioned measure. A good deal of analysis goes through in this setting, such as the  $L^p$ -boundedness of the Hardy–Littlewood maximal operator on  $\Sigma$ , Lebesgue's differentiation theorem for locally integrable functions on  $\Sigma$ , and the density of Hölder functions with bounded support in  $L^p(\Sigma)$ . See, e.g., [Alvarado and Mitrea 2015; Coifman and Weiss 1971; 1977; Christ 1990], and the references therein.

Classically, given an Ahlfors regular subset  $\Sigma$  of  $\mathbb{R}^n$ , the Riesz transforms are defined as principal value singular integral operators on  $\Sigma$  with kernels  $(x_j - y_j)/(\omega_{n-1}|x - y|^n)$  for  $1 \leq j \leq n$ . Specifically, if  $\omega_{n-1}$  is the area of the unit sphere in  $\mathbb{R}^n$ , for each  $j \in \{1, \dots, n\}$  define the  $j$ -th principal value Riesz transform

$$R_j^{\text{pv}} f(x) := \lim_{\varepsilon \rightarrow 0^+} R_{j,\varepsilon} f(x), \quad (1-1)$$

where, for each  $\varepsilon > 0$ ,

$$R_{j,\varepsilon} f(x) := \frac{1}{\omega_{n-1}} \int_{\substack{y \in \Sigma \\ |x-y|>\varepsilon}} \frac{x_j - y_j}{|x - y|^n} f(y) d\mathcal{H}^{n-1}(y), \quad x \in \Sigma. \quad (1-2)$$

It turns out that if  $\Sigma$  is countably rectifiable (of dimension  $n - 1$ ) then for each  $f \in L^2(\Sigma)$  the above limit exists at  $\mathcal{H}^{n-1}$ -a.e. point  $x \in \Sigma$ . In fact, a result of Tolsa [2008] states that if an arbitrary set  $\Sigma \subset \mathbb{R}^n$  has  $\mathcal{H}^{n-1}(\Sigma) < +\infty$  then:

$\Sigma$  is countably rectifiable (of dimension  $n - 1$ ) if and only if, for each  $j \in \{1, \dots, n\}$ ,

$$\lim_{\varepsilon \rightarrow 0^+} \int_{\substack{y \in \Sigma \\ |y-x|>\varepsilon}} \frac{x_j - y_j}{|x-y|^n} d\mathcal{H}^{n-1}(y) \quad (1-3)$$

exists for  $\mathcal{H}^{n-1}$ -a.e. point  $x$  belonging to  $\Sigma$ .

There is yet another related brand of Riesz transforms whose definition places no additional demands on the underlying Ahlfors regular set  $\Sigma$  of  $\mathbb{R}^n$ . The definition in question is of a distribution theory flavor and proceeds by fixing  $\alpha \in (0, 1)$  and considering  $\mathcal{C}_c^\alpha(\Sigma)$ , the space of Hölder functions of order  $\alpha$  with compact support in  $\Sigma$ . This is a Banach space, and we denote by  $(\mathcal{C}_c^\alpha(\Sigma))^*$  its dual. Then, for each  $j \in \{1, \dots, n\}$ , one defines the  $j$ -th distributional Riesz transform as the operator

$$R_j : \mathcal{C}_c^\alpha(\Sigma) \longrightarrow (\mathcal{C}_c^\alpha(\Sigma))^* \quad (1-4)$$

with the property that for every  $f, g \in \mathcal{C}_c^\alpha(\Sigma)$  one has

$$\langle R_j f, g \rangle = \frac{1}{2\omega_{n-1}} \int_{\Sigma} \int_{\Sigma} \frac{x_j - y_j}{|x-y|^n} [f(y)g(x) - f(x)g(y)] d\mathcal{H}^{n-1}(y) d\mathcal{H}^{n-1}(x), \quad (1-5)$$

where, in this context,  $\langle \cdot, \cdot \rangle$  stands for the natural pairing between  $(\mathcal{C}_c^\alpha(\Sigma))^*$  and  $\mathcal{C}_c^\alpha(\Sigma)$ . It may be checked without difficulty that the above integral is absolutely convergent, ultimately rendering the distributional Riesz transform  $R_j$  linear and continuous in the context of (1-4). Moreover, the distributional Riesz transform  $R_j$  just introduced is associated with the kernel  $(x_j - y_j)/(\omega_{n-1}|x-y|^n)$  in the sense that, for each  $f \in \mathcal{C}_c^\alpha(\Sigma)$ , the functional  $R_j f \in (\mathcal{C}_c^\alpha(\Sigma))^*$  is of function type on the set  $\Sigma \setminus \text{supp } f$  and

$$R_j f(x) = \frac{1}{\omega_{n-1}} \int_{\Sigma} \frac{x_j - y_j}{|x-y|^n} f(y) d\mathcal{H}^{n-1}(y) \quad \text{for } x \in \Sigma \setminus \text{supp } f. \quad (1-6)$$

The above definition of the distributional Riesz transforms is very much in line with the point of view adopted in the statement of the classical  $T(1)$  theorem of David and J.-L. Journé [1984]. Originally formulated in the entire Euclidean space, the latter result turned out to be remarkably resilient, in terms of the demands it places on the ambient space. Indeed, the  $T(1)$  theorem has been subsequently generalized to spaces of homogeneous type (in the sense of Coifman and Weiss [1971; 1977]), a setting where only the existence of a quasidistance and a doubling measure is postulated (see, e.g., [Auscher and Hytönen 2013, Theorem 12.3; Christ 1990, Chapter IV; Han et al. 2008, Theorem 5.56, p. 166]). This is a framework in which an Ahlfors regular set  $\Sigma \subset \mathbb{R}^n$ , equipped with the Euclidean distance and the  $(n-1)$ -dimensional Hausdorff measure, fits in naturally.

As it turns out, much information (of both analytic and geometric flavor) is encapsulated in the action of the distributional Riesz transforms (1-4)–(1-5) on the constant function 1. Since the function 1 may not belong to  $\mathcal{C}_c^\alpha(\Sigma)$  (which happens precisely when  $\Sigma$  is unbounded), one should be careful defining  $R_j(1)$ . In agreement with the procedures set in place by the  $T(1)$  theorem, we consider  $R_j(1)$  to be the linear functional acting on each function  $g \in \mathcal{C}_c^\alpha(\Sigma)$  that satisfies the cancellation condition  $\int_{\Sigma} g d\mathcal{H}^{n-1} = 0$

according to

$$\begin{aligned} \langle R_j(1), g \rangle := & \frac{1}{2\omega_{n-1}} \int_{\Sigma} \int_{\Sigma} \frac{x_j - y_j}{|x - y|^n} [\phi(y)g(x) - \phi(x)g(y)] d\mathcal{H}^{n-1}(y) d\mathcal{H}^{n-1}(x) \\ & - \frac{1}{\omega_{n-1}} \int_{\Sigma} \int_{\Sigma} \frac{x_j - y_j}{|x - y|^n} (1 - \phi(x))g(y) d\mathcal{H}^{n-1}(y) d\mathcal{H}^{n-1}(x), \end{aligned} \quad (1-7)$$

where  $\phi \in \mathcal{C}_c^{\alpha}(\Sigma)$  is an auxiliary function chosen to satisfy  $\phi \equiv 1$  near  $\text{supp } g$ . In this vein, let us remark that, in the case when  $\Sigma$  is compact, we do have  $\mathcal{C}_c^{\alpha}(\Sigma) = \mathcal{C}^{\alpha}(\Sigma)$ ; hence, in particular, we now have  $1 \in \mathcal{C}_c^{\alpha}(\Sigma)$ . In such a scenario, it may be readily verified that  $R_j(1)$ , defined as in (1-7), is the restriction of the functional  $R_j 1 \in (\mathcal{C}_c^{\alpha}(\Sigma))^*$ , defined as in (1-5) with  $f = 1$ , to the space consisting of functions in  $\mathcal{C}_c^{\alpha}(\Sigma)$  which integrate to zero. It is therefore reassuring to know that the various points of view on the nature of the action of the distributional Riesz transform  $R_j$  on the constant function 1 are consistent.

At the analytical level, the  $T(1)$  theorem (for operators associated with odd kernels) gives that, for each fixed  $j \in \{1, \dots, n\}$ :

The distributional Riesz transform  $R_j$  from (1-4)–(1-5) extends to a bounded linear operator on  $L^2(\Sigma)$  if and only if  $R_j(1) \in \text{BMO}(\Sigma)$ , (1-8)

where  $\text{BMO}(\Sigma)$  is the John–Nirenberg space of functions of bounded mean oscillations on  $\Sigma$  (regarded as a space of homogeneous type).

At this stage, a few comments are in order, about the specific manner in which the various brands of Riesz transforms introduced earlier relate to one another. Assume that  $\Sigma$  is an Ahlfors regular subset of  $\mathbb{R}^n$  which is countably rectifiable (of dimension  $n - 1$ ). First, it turns out that if for some  $j \in \{1, \dots, n\}$  one (hence both) of the two equivalent conditions in (1-8) holds then the extension of the distributional Riesz transform  $R_j$  to a bounded linear operator on  $L^2(\Sigma)$  (mentioned in (1-8)) is realized precisely by the principal value Riesz transform  $R_j^{\text{pv}}$  (defined for each  $f \in L^2(\Sigma)$  as in (1-1) at  $\mathcal{H}^{n-1}$ -a.e.  $x \in \Sigma$ ). In particular, for each  $j \in \{1, \dots, n\}$ :

If  $\Sigma \subset \mathbb{R}^n$  is a compact Ahlfors regular set which is countably rectifiable (of dimension  $n - 1$ ) and  $R_j(1) \in \text{BMO}(\Sigma)$  then, for  $\mathcal{H}^{n-1}$ -a.e.  $x \in \Sigma$ ,

$$R_j(1)(x) = \lim_{\varepsilon \rightarrow 0^+} \int_{\substack{y \in \Sigma \\ |y-x|>\varepsilon}} \frac{x_j - y_j}{|x - y|^n} d\mathcal{H}^{n-1}(y). \quad (1-9)$$

Second, if for some  $j \in \{1, \dots, n\}$  the principal value Riesz transform  $R_j^{\text{pv}}$ , originally acting on  $\mathcal{C}_c^{\alpha}(\Sigma)$ , is known to extend to a bounded linear operator on  $L^2(\Sigma)$ , then  $R_j^{\text{pv}}$  coincides on  $\mathcal{C}_c^{\alpha}(\Sigma)$  with the distributional Riesz transform  $R_j$  defined as in (1-4)–(1-5). Third, having fixed  $j \in \{1, \dots, n\}$ , the principal value Riesz transform  $R_j^{\text{pv}}$  extends to a bounded linear operator on  $L^2(\Sigma)$  if and only if for each  $\varepsilon > 0$  the  $j$ -th truncated Riesz transform  $R_{j,\varepsilon}$ , defined as in (1-2), is bounded on  $L^2(\Sigma)$  uniformly in  $\varepsilon$ , which happens if and only if the  $j$ -th maximal Riesz transform  $R_{j,*}$  is bounded on  $L^2(\Sigma)$ , where, for each  $f \in L^2(\Sigma)$ ,

$$R_{j,*}f(x) := \sup_{\varepsilon > 0} |(R_{j,\varepsilon}f)(x)|, \quad x \in \Sigma. \quad (1-10)$$

All these results may be established via arguments of Calderón–Zygmund theory flavor, such as Cotlar’s inequality, the Calderón–Zygmund decomposition, Marcinkiewicz’s interpolation theorem and the boundedness of the Hardy–Littlewood maximal operator.

At the geometric level, the recent main result in [Nazarov et al. 2014] mentioned earlier may be rephrased, in light of (1-8), as follows: under the background assumption that  $\Sigma$  is an Ahlfors regular subset of  $\mathbb{R}^n$ , one has

$$\Sigma \text{ is a uniformly rectifiable set} \iff R_j(1) \in \text{BMO}(\Sigma) \text{ for each } j \in \{1, \dots, n\}. \quad (1-11)$$

Hence, within the class of Ahlfors regular subsets of  $\mathbb{R}^n$ , the membership of all  $R_j(1)$  to the John–Nirenberg space BMO characterizes uniform rectifiability. As mentioned previously in the introduction, this result refines earlier work of David and Semmes [1991], who proved that uniform rectifiability within the class of Ahlfors regular subsets of  $\mathbb{R}^n$  is equivalent to the  $L^2$ -boundedness in that ambient of all truncated singular integral operators, uniform with respect to the truncation, (or, equivalently, the  $L^2$ -boundedness of all maximal operators), associated with all kernels of the form  $k(x - y)$ , where the function  $k \in \mathcal{C}^\infty(\mathbb{R}^n \setminus \{0\})$  is odd and satisfies

$$\sup_{x \in \mathbb{R}^n \setminus \{0\}} [|x|^{(n-1)+|\gamma|} |(\partial^\gamma k)(x)|] < +\infty \quad \text{for all } \gamma \in \mathbb{N}_0^n. \quad (1-12)$$

In relation to the brands of Riesz transforms introduced earlier, the results of [David and Semmes 1991] imply<sup>1</sup> that, for each  $j \in \{1, \dots, n\}$ :

Whenever  $\Sigma$  is a uniformly rectifiable set in  $\mathbb{R}^n$ , the principal value Riesz transform  $R_j^{\text{PV}}$  is a well-defined, linear and bounded operator on  $L^2(\Sigma)$ , which agrees on  $\mathcal{C}_c^\alpha(\Sigma)$  with the distributional Riesz transform  $R_j$ . (1-13)

From the perspective of (1-11), one of the issues addressed by our first main result is that of extracting more geometric regularity for  $\Sigma$  if more analytic regularity for the  $R_j(1)$  is available. We shall study this issue in the case when  $\Sigma := \partial\Omega$ , the topological boundary of an open subset  $\Omega$  of  $\mathbb{R}^n$ . This fits into the paradigm of describing geometric characteristics (such as regularity of a certain nature) of a given set in terms of properties of suitable analytical entities (such as singular integral operators) associated with this environment. Specifically, we have the following theorem (for all relevant definitions the reader is referred to Section 2).

**Theorem 1.1.** *Assume  $\Omega \subseteq \mathbb{R}^n$  is an Ahlfors regular domain with a compact boundary, satisfying  $\partial\Omega = \partial(\bar{\Omega})$ . Set  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  and define  $\Omega_+ := \Omega$  and  $\Omega_- := \mathbb{R}^n \setminus \bar{\Omega}$ .*

*Then for each  $\alpha \in (0, 1)$  the following claims are equivalent:*

- (a)  *$\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$  (or a Lyapunov domain of order  $\alpha$ ).*
- (b) *The distributional Riesz transforms, defined as in (1-4)–(1-5) with  $\Sigma := \partial\Omega$ , satisfy*

$$R_j 1 \in \mathcal{C}^\alpha(\partial\Omega) \quad \text{for each } j \in \{1, \dots, n\}. \quad (1-14)$$

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<sup>1</sup>In concert with the Calderón–Zygmund machinery alluded to earlier, and bearing in mind (2-48).

(c)  $\Omega$  is a UR domain and, given any odd homogeneous polynomial  $P$  of degree  $l \geq 1$  in  $\mathbb{R}^n$ , the singular integral operator

$$Tf(x) := \lim_{\varepsilon \rightarrow 0^+} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon}} \frac{P(x-y)}{|x-y|^{n-1+l}} f(y) d\sigma(y), \quad x \in \partial\Omega, \quad (1-15)$$

is meaningfully defined for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$ , and maps  $\mathcal{C}^\alpha(\partial\Omega)$  boundedly into itself.

(d)  $\Omega$  is a UR domain and one has

$$\mathcal{R}_j^\pm 1 \in \mathcal{C}^\alpha(\Omega_\pm) \quad \text{for each } j \in \{1, \dots, n\}, \quad (1-16)$$

where, for  $j \in \{1, \dots, n\}$ ,

$$\mathcal{R}_j^\pm f(x) := \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \frac{x_j - y_j}{|x-y|^n} f(y) d\sigma(y), \quad x \in \Omega_\pm. \quad (1-17)$$

(e)  $\Omega$  is a UR domain and, for each odd homogeneous polynomial  $P$  of degree  $l \geq 1$  in  $\mathbb{R}^n$ , the integral operators

$$\mathbb{T}_\pm f(x) := \int_{\partial\Omega} \frac{P(x-y)}{|x-y|^{n-1+l}} f(y) d\sigma(y), \quad x \in \Omega_\pm, \quad (1-18)$$

map  $\mathcal{C}^\alpha(\partial\Omega)$  boundedly into  $\mathcal{C}^\alpha(\Omega_\pm)$ .

Moreover, if  $\Omega$  is a  $\mathcal{C}^{1+\alpha}$  domain for some  $\alpha \in (0, 1)$ , there exists a finite constant  $C > 0$ , depending only on  $n$ ,  $\alpha$ ,  $\text{diam}(\partial\Omega)$ , the upper Ahlfors regularity constant of  $\partial\Omega$ , and  $\|v\|_{\mathcal{C}^\alpha(\partial\Omega)}$  (where  $v$  is the outward unit normal to  $\Omega$ ), with the property that for each odd homogeneous polynomial  $P$  of degree  $l \geq 1$  in  $\mathbb{R}^n$  the integral operators (1-18) and (1-15) satisfy

$$\|\mathbb{T}_\pm f\|_{\mathcal{C}^\alpha(\bar{\Omega}_\pm)} \leq C^l 2^l \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad \text{for all } f \in \mathcal{C}^\alpha(\partial\Omega), \quad (1-19)$$

$$\|Tf\|_{\mathcal{C}^\alpha(\partial\Omega)} \leq C^l 2^l \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad \text{for all } f \in \mathcal{C}^\alpha(\partial\Omega). \quad (1-20)$$

The operators described in (1-15) may be thought of as generalized Riesz transforms since they correspond to (1-15) with

$$P(x) := \frac{x_j}{\omega_{n-1}} \quad \text{for } x = (x_1, \dots, x_n) \in \mathbb{R}^n, \quad 1 \leq j \leq n. \quad (1-21)$$

For the same choices of the polynomials, the claim in Theorem 1.1(e) implies that the harmonic single-layer operator (see (5-66) for a definition) is well-defined, linear and bounded as a mapping

$$\mathcal{S} : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^{1+\alpha}(\Omega_\pm). \quad (1-22)$$

In concert with the above comments, intended to clarify how the distributional Riesz transforms relate to the principal value Riesz transforms, Theorem 1.1 readily implies the following corollary:

**Corollary 1.2.** *Let  $\Omega$  be a nonempty, proper, open subset of  $\mathbb{R}^n$  with compact boundary, satisfying  $\partial\Omega = \partial(\bar{\Omega})$ . Then for every  $\alpha \in (0, 1)$  the following statements are equivalent:*

(i)  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$ .

(ii)  $\Omega$  is an Ahlfors regular domain and, for each  $j \in \{1, \dots, n\}$ , the distributional Riesz transform  $R_j$  defined as in (1-4)–(1-5) with  $\Sigma := \partial\Omega$  induces a linear and bounded operator in the context

$$R_j : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^\alpha(\partial\Omega). \quad (1-23)$$

(iii)  $\Omega$  is an Ahlfors regular domain and

$$R_j 1 \in \mathcal{C}^\alpha(\partial\Omega) \quad \text{for each } j \in \{1, \dots, n\}. \quad (1-24)$$

(iv)  $\Omega$  is a UR domain and, for each  $j \in \{1, \dots, n\}$ , the principal value Riesz transform  $R_j^{\text{PV}}$  defined as in (1-1) with  $\Sigma := \partial\Omega$  induces a linear and bounded operator in the context

$$R_j^{\text{PV}} : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^\alpha(\partial\Omega). \quad (1-25)$$

(v)  $\Omega$  is a UR domain and

$$R_j^{\text{PV}} 1 \in \mathcal{C}^\alpha(\partial\Omega) \quad \text{for each } j \in \{1, \dots, n\}. \quad (1-26)$$

In dimension two, there is a variant of [Theorem 1.1](#) starting from the demand that the boundary of the domain in question be an upper Ahlfors regular Jordan curve and, in lieu of the Riesz transforms, using the following version of the classical Cauchy integral operator in the principal value sense:

$$\mathfrak{C}^{\text{PV}} f(z) := \lim_{\varepsilon \rightarrow 0^+} \frac{1}{2\pi i} \int_{\substack{\zeta \in \partial\Omega \\ |z-\zeta|>\varepsilon}} \frac{f(\zeta)}{\zeta - z} d\mathcal{H}^1(\zeta), \quad z \in \partial\Omega. \quad (1-27)$$

**Theorem 1.3.** *Let  $\Omega \subseteq \mathbb{C}$  be a bounded open set whose boundary is an upper Ahlfors regular Jordan curve and fix  $\alpha \in (0, 1)$ . Then  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$  if and only if the operator (1-27) satisfies  $\mathfrak{C}^{\text{PV}} 1 \in \mathcal{C}^\alpha(\partial\Omega)$ .*

Under the initial background hypotheses on  $\Omega$  made in [Theorem 1.1](#),  $\Omega$  being a  $\mathcal{C}^1$  domain is equivalent to  $v \in \mathcal{C}^0(\partial\Omega)$  (see [\[Hofmann et al. 2007\]](#) in this regard). This being said, the limiting case  $\alpha = 0$  of the equivalence (a)  $\iff$  (b) in [Theorem 1.1](#) requires replacing the space of continuous functions by the (larger) Sarason space VMO, of functions of vanishing mean oscillations (on  $\partial\Omega$ , viewed as a space of homogeneous type, in the sense of Coifman and Weiss, when equipped with the measure  $\sigma$  and the Euclidean distance). Specifically, the following result holds:

**Theorem 1.4.** *Let  $\Omega \subseteq \mathbb{R}^n$  be an Ahlfors regular domain with a compact boundary, and denote by  $v$  the geometric measure-theoretic outward unit normal to  $\Omega$ . Then*

$$v \in \text{VMO}(\partial\Omega) \text{ and } \partial\Omega \text{ is uniformly rectifiable} \iff R_j 1 \in \text{VMO}(\partial\Omega) \text{ for all } j \in \{1, \dots, n\}. \quad (1-28)$$

The equivalence (1-28) should be contrasted with (1-11). In the present context, the additional background assumption  $\mathcal{H}^{n-1}(\partial\Omega \setminus \partial_* \Omega) = 0$  (which is part of the definition of an Ahlfors regular domain; see [Definition 2.3](#)) merely ensures that the geometric measure-theoretic outward unit normal  $v$  to  $\Omega$  is well-defined  $\sigma$ -a.e. on  $\partial\Omega$ .

The collection of all geometric conditions in [Theorem 1.4](#), i.e., that  $\Omega \subseteq \mathbb{R}^n$  is an Ahlfors regular domain such that  $\partial\Omega$  is a uniformly rectifiable set, amounts to saying that  $\Omega$  is a UR domain (see [Definition 2.7](#)).

Concerning this class of domains, it has been noted in [Hofmann et al. 2010, Corollary 3.9, p. 2633] that:

If  $\Omega \subset \mathbb{R}^n$  is an open set satisfying a two-sided corkscrew condition (in the sense of [Jerison and Kenig 1982]) and whose boundary is Ahlfors regular, then  $\Omega$  is a UR domain. (1-29)

In fact, the same circle of techniques yielding [Theorem 1.4](#) also allows us to characterize the class of regular SKT domains, originally introduced in [Hofmann et al. 2010, Definition 4.8, p. 2690] by demanding  $\delta$ -Reifenberg flatness for some sufficiently small  $\delta > 0$  (see [Definition 7.6](#)), Ahlfors regular boundary, and vanishing mean oscillations for the geometric measure-theoretic outward unit normal. Specifically, combining (1-29), [Theorem 1.4](#), [Theorem 7.7](#), and [Hofmann et al. 2010, Theorem 4.21, p. 2711] gives the following theorem:

**Theorem 1.5.** *If  $\Omega \subseteq \mathbb{R}^n$  is an open set with a compact Ahlfors regular boundary, satisfying a two-sided John condition as described in [Definition 7.3](#) (which, in particular, implies the two-sided corkscrew condition) then*

$$R_j 1 \in \text{VMO}(\partial\Omega) \text{ for every } j \in \{1, \dots, n\} \iff \Omega \text{ is a regular SKT domain.} \quad (1-30)$$

It turns out that the equivalence (a)  $\iff$  (b) in [Theorem 1.1](#) essentially self-extends to the larger scale of Besov spaces  $B_s^{p,p}(\partial\Omega)$  with  $p \in [1, \infty]$  and  $s \in (0, 1)$  satisfying  $sp > n - 1$ , for which the Hölder spaces occur as a special, limiting case, corresponding to  $p = \infty$ . For a precise statement, see [Theorem 7.11](#).

The category of singular integral operators falling under the scope of [Theorem 1.1](#) already includes boundary layer potentials associated with basic PDEs of mathematical physics, such as the Laplacian, the Helmholtz operator, the Lamé system, the Stokes system, and even higher-order elliptic systems (see, e.g., [Colton and Kress 1983; Hsiao and Wendland 2008; Mitrea 2013; Mitrea and Mitrea 2013]). This being said, granted the estimates established in the last part of [Theorem 1.1](#), the method of spherical harmonics then allows us to prove the following result, dealing with a more general class of operators:

**Theorem 1.6.** *Let  $\Omega$  be a  $\mathcal{C}^{1+\alpha}$  domain,  $\alpha \in (0, 1)$ , with compact boundary, and let  $k \in \mathcal{C}^\infty(\mathbb{R}^n \setminus \{0\})$  be an odd function satisfying  $k(\lambda x) = \lambda^{1-n}k(x)$  for all  $\lambda \in (0, \infty)$  and  $x \in \mathbb{R}^n \setminus \{0\}$ . In addition, assume that there exists a sequence  $\{m_l\}_{l \in \mathbb{N}_0} \subseteq \mathbb{N}_0$  for which*

$$\sum_{l=0}^{\infty} 4^{l^2} l^{-2m_l} \|(\Delta_{S^{n-1}})^{m_l}(k|_{S^{n-1}})\|_{L^2(S^{n-1})} < +\infty, \quad (1-31)$$

where  $\Delta_{S^{n-1}}$  is the Laplace–Beltrami operator on the unit sphere  $S^{n-1}$  in  $\mathbb{R}^n$ .

Then the singular integral operators

$$\mathbb{T}f(x) := \int_{\partial\Omega} k(x - y) f(y) d\sigma(y), \quad x \in \Omega, \quad (1-32)$$

$$Tf(x) := \lim_{\varepsilon \rightarrow 0^+} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon}} k(x - y) f(y) d\sigma(y), \quad x \in \partial\Omega, \quad (1-33)$$

induce linear and bounded mappings

$$\mathbb{T} : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^\alpha(\bar{\Omega}) \quad \text{and} \quad T : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^\alpha(\partial\Omega). \quad (1-34)$$

We wish to note that [Theorem 1.6](#) refines the implication (a)  $\Rightarrow$  (e) in [Theorem 1.1](#) since, as explained in [Remark 6.1](#), condition (1-31) is satisfied whenever the kernel  $k$  is of the form  $P(x)/|x|^{n-1+l}$  for some homogeneous polynomial  $P$  of degree  $l \in 2\mathbb{N} - 1$  in  $\mathbb{R}^n$ . In fact, condition (1-31) holds for kernels  $k$  that are real-analytic away from 0 with lacunary Taylor series (involving sufficiently large gaps between the nonzero coefficients of their expansions, depending on  $n, \alpha, \text{diam}(\partial\Omega), \|v\|_{\mathcal{C}^\alpha(\partial\Omega)}$ , and the upper Ahlfors regularity constant of  $\partial\Omega$ ). Thus, the conclusions in [Theorem 1.6](#) are valid for such kernels which are also odd and positive homogeneous of degree  $1 - n$ .

Even though the statement does not reflect it, the proof of [Theorem 1.1](#) makes essential use of the Clifford algebra  $\mathcal{Cl}_n$ , a highly noncommutative generalization of the field of complex numbers to  $n$  dimensions, which also turns out to be geometrically sensitive. Indeed, this is a tool which has occasionally emerged at the core of a variety of problems at the interface between geometry and analysis. For us, one key aspect of this algebraic setting is the close relationship between the Riesz transforms and the principal value<sup>2</sup> Cauchy–Clifford integral operator  $\mathcal{C}^{\text{PV}}$  (defined in [\(5-2\)](#)). For the purpose of this introduction we single out the remarkable formula

$$v = -4\mathcal{C}^{\text{PV}} \left( \sum_{j=1}^n (R_j^{\text{PV}} 1) e_j \right) \quad \text{at } \sigma\text{-a.e. point on } \partial\Omega, \quad (1-35)$$

expressing the (geometric measure-theoretic) outward unit normal to  $\Omega$  as the Clifford algebra cocktail  $\sum_{j=1}^n (R_j^{\text{PV}} 1) e_j$  of principal value Riesz transforms acting on the constant function 1, coupled with the imaginary units  $e_j$  in  $\mathcal{Cl}_n$ , then finally distorted through the action of the Cauchy–Clifford operator  $\mathcal{C}^{\text{PV}}$ . Identity (1-35) plays a basic role in the proof of (b)  $\Rightarrow$  (a) in [Theorem 1.1](#), together with a higher-dimensional generalization in a rough setting of the classical Plemelj–Privalov theorem stating that the principal value Cauchy integral operator on a piecewise smooth Jordan curve without cusps in the plane is bounded on Hölder spaces (see [Plemelj 1908; Privalov 1918; 1941]; see also [Iftimie 1965] for a higher-dimensional version for Lyapunov domains with compact boundaries). Specifically, in [Theorem 5.6](#) we show that, whenever  $\Omega \subset \mathbb{R}^n$  is a Lebesgue measurable set whose boundary is compact, upper Ahlfors regular, and satisfies  $\mathcal{H}^{n-1}(\partial\Omega \setminus \partial_*\Omega) = 0$ , it follows that for each  $\alpha \in (0, 1)$  the principal value Cauchy–Clifford operator  $\mathcal{C}^{\text{PV}}$  induces a well-defined, linear and bounded mapping

$$\mathcal{C}^{\text{PV}} : \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{Cl}_n \longrightarrow \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{Cl}_n. \quad (1-36)$$

The strategy employed in the proof of the implication (a)  $\Rightarrow$  (e) in [Theorem 1.1](#) is somewhat akin to that of establishing a “ $T(1)$ -theorem” in the sense that matters are reduced to checking that  $\mathbb{T}_\pm$  act reasonably on the constant function 1 (see [\(3-42\)](#) in this regard). In turn, this is accomplished via a proof by induction on  $l \in 2\mathbb{N} - 1$ , the degree of the homogeneous polynomial  $P$ . The base case  $l = 1$ , corresponding to linear combinations of polynomials as in [\(1-21\)](#), is dealt with by viewing  $(x_j - y_j)/|x - y|^n$  as a dimensional multiple of  $\partial_j E_\Delta(x - y)$ , where  $E_\Delta$  is the standard fundamental solution for the Laplacian in  $\mathbb{R}^n$ . As such, the key cancellation property that eventually allows us to establish the desired Hölder estimate in this base case may be ultimately traced back to the PDE satisfied by  $(x_j - y_j)/|x - y|^n$ . In carrying out the inductive step

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<sup>2</sup>In the standard sense of removing balls centered at the singularity and taking the limit as the radii shrink to zero.

we make essential use of elements of Clifford analysis permitting us to relate  $\mathbb{T}_{\pm 1}$  to the action of certain integral operators constructed as in (1-18) but relative to lower-degree polynomials acting on components of the outward unit normal  $v$  to  $\Omega$ . In this scenario, what allows the use of the induction hypothesis is the fact that, since  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$ , the components of the outward unit normal belong to  $\mathcal{C}^\alpha(\partial\Omega)$ .

The layout of the paper is as follows. Section 2 contains a discussion of background material of geometric measure-theoretic nature, along with some auxiliary lemmas which are relevant in our future endeavors. In Section 3 we first recall a version of the Calderón–Zygmund theory for singular integral operators on Lebesgue spaces in UR domains, and then proceed to establish several useful preliminary estimates for general singular integral operators. Next, Section 4 is reserved for a presentation of those aspects of Clifford analysis which are relevant for the present work. Section 5 is devoted to a study of Cauchy–Clifford integral operators (of both boundary-to-domain and boundary-to-boundary type) in the context of Hölder spaces. In contrast with the Calderón–Zygmund theory for singular integrals in UR domains reviewed in the first part of Section 3, the novelty here is the consideration of a much larger category of domains (see Theorem 5.6 for details). In the last part of Section 5 we also discuss the harmonic single and double layer potentials (involved in the initial induction step in the proof of the implication (a)  $\Rightarrow$  (e) in Theorem 1.1). Finally, in Section 6, the proofs of Theorems 1.1, 1.3 and 1.6 are presented, while Section 7 contains the proofs of Theorem 1.4 and the Besov space version of the equivalence (a)  $\Leftrightarrow$  (b) in Theorem 1.1 (see Theorem 7.11), and also a more general version of (1-30) in Theorem 7.7.

## 2. Geometric measure-theoretic preliminaries

Throughout,  $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$  and we shall denote by  $\mathbf{1}_E$  the characteristic function of a set  $E$ . For  $\alpha \in (0, 1)$  and  $U \subseteq \mathbb{R}^n$  an arbitrary set (implicitly assumed to have cardinality at least 2), define the *homogeneous Hölder space of order  $\alpha$*  on  $U$  as

$$\dot{\mathcal{C}}^\alpha(U) := \{u : U \rightarrow \mathbb{C} : [u]_{\dot{\mathcal{C}}^\alpha(U)} < +\infty\}, \quad (2-1)$$

where  $[\cdot]_{\dot{\mathcal{C}}^\alpha(U)}$  stands for the seminorm

$$[u]_{\dot{\mathcal{C}}^\alpha(U)} := \sup_{\substack{x, y \in U \\ x \neq y}} \frac{|u(x) - u(y)|}{|x - y|^\alpha}. \quad (2-2)$$

The *inhomogeneous Hölder space of order  $\alpha$*  on  $U$  is then defined as

$$\mathcal{C}^\alpha(U) := \{u \in \dot{\mathcal{C}}^\alpha(U) : u \text{ is bounded in } U\}, \quad (2-3)$$

and is equipped with the norm

$$\|u\|_{\mathcal{C}^\alpha(U)} := \sup_U |u| + [u]_{\dot{\mathcal{C}}^\alpha(U)} \quad \text{for all } u \in \mathcal{C}^\alpha(U). \quad (2-4)$$

Also, denote by  $\mathcal{C}_c^\alpha(U)$  the subspace of  $\mathcal{C}^\alpha(U)$  consisting of functions vanishing outside of a relatively compact subset of  $U$ . Moreover, if  $\mathcal{O}$  is an open, nonempty subset of  $\mathbb{R}^n$ , then for given  $\alpha \in (0, 1)$  define

$$\mathcal{C}^{1+\alpha}(\mathcal{O}) := \{u \in \mathcal{C}^1(\mathcal{O}) : \|u\|_{\mathcal{C}^{1+\alpha}(\mathcal{O})} < +\infty\}, \quad (2-5)$$

where

$$\|u\|_{\mathcal{C}^{1+\alpha}(\mathcal{O})} := \sup_{x \in \mathcal{O}} |u(x)| + \sup_{x \in \mathcal{O}} |(\nabla u)(x)| + \sup_{\substack{x, y \in \mathcal{O} \\ x \neq y}} \frac{|(\nabla u)(x) - (\nabla u)(y)|}{|x - y|^\alpha}. \quad (2-6)$$

The following observations will be tacitly used in the sequel. For each set  $U \subseteq \mathbb{R}^n$  and any  $\alpha \in (0, 1)$ , we have that  $\mathcal{C}^\alpha(U)$  is an algebra and the spaces  $\dot{\mathcal{C}}^\alpha(U)$  and  $\mathcal{C}^\alpha(U)$  are contained in the space of uniformly continuous functions on  $U$ , with  $\dot{\mathcal{C}}^\alpha(U) = \dot{\mathcal{C}}^\alpha(\bar{U})$  and  $\mathcal{C}^\alpha(U) = \mathcal{C}^\alpha(\bar{U})$ . Moreover,  $\dot{\mathcal{C}}^\alpha(U) = \mathcal{C}^\alpha(U)$  if  $U$  is bounded. Finally, we shall make no notational distinction between a Hölder space of scalar functions and its version involving vector-valued functions. A similar convention is employed for other function spaces used in this work.

**Definition 2.1.** A nonempty, open, proper subset  $\Omega$  of  $\mathbb{R}^n$  is called a *domain of class  $\mathcal{C}^{1+\alpha}$*  for some  $\alpha \in (0, 1)$  (or a *Lyapunov domain of order  $\alpha$* ), if there exist  $r, h > 0$  with the following significance. For every point  $x_0 \in \partial\Omega$  one can find a coordinate system  $(x_1, \dots, x_n) = (x', x_n)$  in  $\mathbb{R}^n$  which is isometric to the canonical one and has origin at  $x_0$ , along with a real-valued function  $\varphi \in \mathcal{C}^{1+\alpha}(\mathbb{R}^{n-1})$  such that

$$\Omega \cap \mathcal{C}(r, h) = \{x = (x', x_n) \in \mathbb{R}^{n-1} \times \mathbb{R} : |x'| < r \text{ and } \varphi(x') < x_n < h\}, \quad (2-7)$$

where  $\mathcal{C}(r, h)$  stands for the cylinder

$$\{x = (x', x_n) \in \mathbb{R}^{n-1} \times \mathbb{R} : |x'| < r \text{ and } -h < x_n < h\}. \quad (2-8)$$

Strictly speaking, the traditional definition of a Lyapunov<sup>3</sup> domain  $\Omega \subseteq \mathbb{R}^n$  of order  $\alpha$  requires that  $\partial\Omega$  is locally given by the graph of a differentiable function  $\varphi : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$  whose normal  $v$  to its graph  $\Sigma$  has the property that the acute angle  $\theta_{x,y}$  between  $v(x)$  and  $v(y)$  for two arbitrary points  $x, y \in \Sigma$  satisfies  $\theta_{x,y} \leq C|x - y|^\alpha$ ; see, e.g., [Iftimie 1965, Définition 2.1, p. 301]. This being said, it is easy to see that the latter condition implies that  $v$  is Hölder continuous of order  $\alpha$  and, ultimately, that  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$  in the sense of our Definition 2.1.

We shall now present a brief summary of a number of definitions and results from geometric measure theory which are relevant for the current work (see the monographs of H. Federer [1969], W. Ziemer [1989], L. Evans and R. Gariepy [1992] for more details). We say a Lebesgue measurable set  $\Omega \subset \mathbb{R}^n$  has *locally finite perimeter* provided  $\nabla \mathbf{1}_\Omega$  is a locally finite, Borel regular,  $\mathbb{R}^n$ -valued measure. Given a Lebesgue measurable set  $\Omega \subset \mathbb{R}^n$  of locally finite perimeter we denote by  $\sigma$  the total variation measure of  $\nabla \mathbf{1}_\Omega$ . Then  $\sigma$  is a locally finite positive measure, supported on  $\partial\Omega$ . In the sequel, we shall frequently identify  $\sigma$  with its restriction to  $\partial\Omega$ , with no special mention. By  $L^p(\partial\Omega, \sigma)$ , where  $0 < p \leq \infty$ , we shall denote the usual scale of Lebesgue spaces on  $\partial\Omega$  with respect to the measure  $\sigma$ .

Clearly, each component of  $\nabla \mathbf{1}_\Omega$  is absolutely continuous with respect to  $\sigma$ , so from the Radon–Nikodym theorem it follows that

$$\nabla \mathbf{1}_\Omega = -v\sigma, \quad (2-9)$$

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<sup>3</sup>Also spelled as Liapunov.

where

$v$  is an  $\mathbb{R}^n$ -valued function with components in  $L^\infty(\partial\Omega, \sigma)$  and which satisfies  $|v(x)| = 1$  at  $\sigma$ -a.e. point  $x \in \partial\Omega$ . (2-10)

Moreover, Besicovitch's differentiation theorem implies that at  $\sigma$ -a.e. point  $x \in \partial\Omega$  we have

$$\lim_{r \rightarrow 0^+} \bar{\int}_{B(x,r)} v(y) d\sigma(y) = v(x), \quad (2-11)$$

where the barred integral indicates mean average. We shall refer to  $v$  and  $\sigma$  as the (geometric measure-theoretic) *outward unit normal* to  $\Omega$  and the *surface measure* on  $\partial\Omega$ , respectively.

Next, denote by  $\mathcal{L}^n$  the Lebesgue measure in  $\mathbb{R}^n$  and recall that the *measure-theoretic boundary*  $\partial_*\Omega$  of a Lebesgue measurable set  $\Omega \subseteq \mathbb{R}^n$  is defined by

$$\partial_*\Omega := \left\{ x \in \partial\Omega : \limsup_{r \rightarrow 0^+} \frac{\mathcal{L}^n(B(x,r) \cap \Omega)}{r^n} > 0 \text{ and } \limsup_{r \rightarrow 0^+} \frac{\mathcal{L}^n(B(x,r) \setminus \Omega)}{r^n} > 0 \right\}. \quad (2-12)$$

Also, the *reduced boundary*  $\partial^*\Omega$  of  $\Omega$  is defined as

$$\partial^*\Omega := \{x \in \partial\Omega : (2-11) \text{ holds and } |v(x)| = 1\}. \quad (2-13)$$

As is well-known (see [Ziemer 1989, Lemma 5.9.5, p. 252; Evans and Gariepy 1992, p. 208]), one has

$$\partial^*\Omega \subseteq \partial_*\Omega \subseteq \partial\Omega \quad \text{and} \quad \mathcal{H}^{n-1}(\partial_*\Omega \setminus \partial^*\Omega) = 0, \quad (2-14)$$

where  $\mathcal{H}^{n-1}$  is the  $(n-1)$ -dimensional Hausdorff measure in  $\mathbb{R}^n$ . Also,

$$\sigma = \mathcal{H}^{n-1}|_{\partial^*\Omega}. \quad (2-15)$$

Hence, if  $\Omega$  has locally finite perimeter, it follows from (2-14) that the outward unit normal is defined  $\sigma$ -a.e. on  $\partial_*\Omega$ . In particular, if

$$\mathcal{H}^{n-1}(\partial\Omega \setminus \partial_*\Omega) = 0, \quad (2-16)$$

then from (2-13)–(2-14) we see that the outward unit normal  $v$  is defined  $\sigma$ -a.e. on  $\partial\Omega$ , and (2-15) becomes  $\sigma = \mathcal{H}^{n-1}|_{\partial\Omega}$ . Works of Federer and De Giorgi also give that

$$\partial^*\Omega \text{ is countably rectifiable (of dimension } n-1\text{)}, \quad (2-17)$$

in the sense that it is a countable disjoint union

$$\partial^*\Omega = N \cup \left( \bigcup_{k \in \mathbb{N}} M_k \right) \quad (2-18)$$

where each  $M_k$  is a compact subset of an  $(n-1)$ -dimensional  $\mathscr{C}^1$  surface in  $\mathbb{R}^n$  and  $\mathcal{H}^{n-1}(N) = 0$ . It then happens that  $v$  is normal to each such surface, in the usual sense. For further reference let us remark here that, as is apparent from (2-17), (2-14), and (2-18):

If  $\Omega \subset \mathbb{R}^n$  is a Lebesgue measurable set which has locally finite perimeter and for which (2-16) holds, then  $\partial\Omega$  is countably rectifiable (of dimension  $n-1$ ). (2-19)

The following characterization of the class of  $\mathcal{C}^{1+\alpha}$  domains from [Hofmann et al. 2007] is going to play an important role for us here.

**Theorem 2.2.** *Assume that  $\Omega$  is a nonempty, open, proper subset of  $\mathbb{R}^n$  of locally finite perimeter, with compact boundary, for which*

$$\partial\Omega = \partial(\bar{\Omega}), \quad (2-20)$$

*and denote by  $v$  the geometric measure-theoretic outward unit normal to  $\partial\Omega$ , as defined in (2-9)–(2-10). Also, fix  $\alpha \in (0, 1)$ . Then  $\Omega$  is a  $\mathcal{C}^{1+\alpha}$  domain if and only if, after altering  $v$  on a set of  $\sigma$ -measure zero, one has  $v \in \mathcal{C}^\alpha(\partial\Omega)$ .*

Condition (2-20) is designed to preclude pathological happenstances such as a slit disk. By the Jordan–Brouwer separation theorem (see [Alexander 1978, Theorem 1, p. 284]), (2-20) is automatically satisfied if  $\partial\Omega$  is a compact, connected,  $(n-1)$ -dimensional topological manifold without boundary (since in this scenario  $\mathbb{R}^n \setminus \partial\Omega$  consists of precisely two components, each with boundary  $\partial\Omega$ ; see [Alvarado et al. 2011] for details).

Changing topics, we remind the reader that a set  $\Sigma \subset \mathbb{R}^n$  is called *Ahlfors regular* provided it is closed, nonempty, and there exists  $C \in (1, \infty)$  such that

$$C^{-1} r^{n-1} \leq \mathcal{H}^{n-1}(B(x, r) \cap \Sigma) \leq C r^{n-1} \quad (2-21)$$

for each  $x \in \Sigma$  and  $r \in (0, \text{diam } \Sigma)$ . When considered by itself, the second inequality above will be referred to as *upper Ahlfors regularity*. In this vein, we wish to remark that (see [Evans and Gariepy 1992, Theorem 1, p. 222]):

Any Lebesgue measurable subset of  $\mathbb{R}^n$  with an upper Ahlfors regular boundary is of locally finite perimeter. (2-22)

It is natural to make the following definition:

**Definition 2.3.** Call an open, nonempty, proper subset  $\Omega$  of  $\mathbb{R}^n$  an *Ahlfors regular domain* provided  $\partial\Omega$  is an Ahlfors regular set and  $\mathcal{H}^{n-1}(\partial\Omega \setminus \partial_* \Omega) = 0$ .

Let us remark here that (2-19) and (2-22) imply the following result:

If  $\Omega \subset \mathbb{R}^n$  is a Lebesgue measurable set with an upper Ahlfors regular boundary satisfying  $\mathcal{H}^{n-1}(\partial\Omega \setminus \partial_* \Omega) = 0$ , then  $\Omega$  is a set of locally finite perimeter and its topological boundary,  $\partial\Omega$ , is countably rectifiable (of dimension  $n-1$ ). (2-23)

For further use, we record the following consequence of (2-23) and Definition 2.3:

Any Ahlfors regular domain in  $\mathbb{R}^n$  has a countably rectifiable topological boundary (of dimension  $n-1$ ). (2-24)

Later on, the following result is going to be of significance to us:

**Proposition 2.4.** *Let  $\Sigma \subseteq \mathbb{R}^n$  be an Ahlfors regular set which is countably rectifiable (of dimension  $n - 1$ ). Define  $\sigma := \mathcal{H}^{n-1}|_{\Sigma}$  and consider an arbitrary function  $f \in L^1_{\text{loc}}(\Sigma, \sigma)$ . Then, for each  $j \in \{1, \dots, n\}$ ,*

$$\lim_{\varepsilon \rightarrow 0^+} \left\{ \sup_{r \in (\varepsilon/2, \varepsilon)} \left| \int_{\substack{y \in \Sigma \\ \varepsilon/4 < |y-x| \leq r}} \frac{x_j - y_j}{|x-y|^n} f(y) d\sigma(y) \right| \right\} = 0 \quad \text{for } \sigma\text{-a.e. } x \in \Sigma. \quad (2-25)$$

*Proof.* Fix  $j \in \{1, \dots, n\}$  and pick some large  $R > 0$ . For each  $\varepsilon \in (0, 1)$ ,  $r \in (\frac{1}{2}\varepsilon, \varepsilon)$ , and  $x \in \Sigma \cap B(0, R)$  split

$$\int_{\substack{y \in \Sigma \\ \varepsilon/4 < |y-x| \leq r}} \frac{x_j - y_j}{|x-y|^n} f(y) d\sigma(y) = I_{\varepsilon,r} + II_{\varepsilon,r}, \quad (2-26)$$

where

$$I_{\varepsilon,r} := \int_{\substack{y \in \Sigma \\ \varepsilon/4 < |y-x| \leq r}} \frac{x_j - y_j}{|x-y|^n} (f(y) - f(x)) d\sigma(y), \quad (2-27)$$

$$II_{\varepsilon,r} := f(x) \left\{ \int_{\substack{y \in \Sigma \cap B(0, R+1) \\ \varepsilon/4 < |y-x| < 1}} \frac{x_j - y_j}{|x-y|^n} d\sigma(y) - \int_{\substack{y \in \Sigma \cap B(0, R+1) \\ r < |y-x| < 1}} \frac{x_j - y_j}{|x-y|^n} d\sigma(y) \right\}. \quad (2-28)$$

The left-to-right implication in (1-3), used for the set  $\Sigma \cap B(0, R+1)$ , gives that  $\sigma$ -a.e. point  $x \in \Sigma \cap B(0, R)$  has the property that, for each  $\delta > 0$ , there exists  $\theta_\delta \in (0, 1)$  such that, for each  $\theta_1, \theta_2 \in (0, \theta_\delta)$ , we have

$$\left| \int_{\substack{y \in \Sigma \cap B(0, R+1) \\ \theta_1 < |y-x| < 1}} \frac{x_j - y_j}{|x-y|^n} d\sigma(y) - \int_{\substack{y \in \Sigma \cap B(0, R+1) \\ \theta_2 < |y-x| < 1}} \frac{x_j - y_j}{|x-y|^n} d\sigma(y) \right| < \delta. \quad (2-29)$$

In turn, this readily yields

$$\lim_{\varepsilon \rightarrow 0^+} \left\{ \sup_{r \in (\varepsilon/2, \varepsilon)} |II_{\varepsilon,r}| \right\} = 0 \quad \text{for } \sigma\text{-a.e. } x \in \Sigma \cap B(0, R). \quad (2-30)$$

Next, thanks to the upper Ahlfors regularity condition satisfied by  $\Sigma$ , we may estimate (recall that the barred integral stands for mean average)

$$|I_{\varepsilon,r}| \leq \left( \frac{4}{\varepsilon} \right)^{n-1} \int_{\Sigma \cap B(x, \varepsilon)} |f(y) - f(x)| d\sigma(y) \leq c \int_{\Sigma \cap B(x, \varepsilon)} |f(y) - f(x)| d\sigma(y). \quad (2-31)$$

Hence, on the one hand,

$$\lim_{\varepsilon \rightarrow 0^+} \left\{ \sup_{r \in (\varepsilon/2, \varepsilon)} |I_{\varepsilon,r}| \right\} = 0 \quad \text{if } x \text{ is a Lebesgue point for } f. \quad (2-32)$$

On the other hand, the triplet  $(\Sigma, |\cdot - \cdot|, \sigma)$  is a space of homogeneous type and the underlying measure is Borel regular. As such, Lebesgue's differentiation theorem gives that  $\sigma$ -a.e. point in  $\Sigma$  is a Lebesgue point for  $f$ . Bearing this in mind, the desired conclusion now follows from (2-26), (2-30), and (2-32).  $\square$

In the treatment of the principal value Cauchy–Clifford integral operator in Section 5, the following lemma plays a significant role:

**Lemma 2.5.** *Let  $\Omega \subset \mathbb{R}^n$  be a Lebesgue measurable set of locally finite perimeter such that (2-16) holds. Then, for each  $x \in \partial^*\Omega$ , there exists a Lebesgue measurable set  $\mathcal{O}_x \subset (0, 1)$  of density 1 at 0, i.e., satisfying*

$$\lim_{\varepsilon \rightarrow 0^+} \frac{\mathcal{L}^1(\mathcal{O}_x \cap (0, \varepsilon))}{\varepsilon} = 1, \quad (2-33)$$

with the property that

$$\lim_{\substack{r \rightarrow 0^+ \\ r \in \mathcal{O}_x}} \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, r))}{\omega_{n-1} r^{n-1}} = \frac{1}{2}. \quad (2-34)$$

*Proof.* We largely follow a suggestion of Taylor (personal communication, 2015). Given  $x \in \partial^*\Omega$ , there exists an approximate tangent plane  $\pi$  to  $\Omega$  at  $x$  (see the discussion in [Hofmann et al. 2010, p. 2627]) and we denote by  $\pi^\pm$  the two half-spaces into which  $\pi$  divides  $\mathbb{R}^n$  (with the convention that the outward unit normal to  $\pi^-$  is  $\nu(x)$ ). For each  $r > 0$ , set  $\partial^\pm B(x, r) := \partial B(x, r) \cap \pi^\pm$  and introduce

$$W(x, r) := \partial^- B(x, r) \Delta (\Omega \cap \partial B(x, r)), \quad (2-35)$$

where, generally speaking,  $U \Delta V$  denotes the symmetric difference  $(U \setminus V) \cup (V \setminus U)$ . With this notation, in the proof of [Hofmann et al. 2010, Proposition 3.3, p. 2628] it has been shown that

$$\int_0^R \mathcal{H}^{n-1}(W(x, r)) dr = o(R^n) \quad \text{as } R \rightarrow 0^+. \quad (2-36)$$

Thus, if we consider the function

$$\phi : (0, 1) \rightarrow [0, \infty), \quad \phi(r) := r^{1-n} \mathcal{H}^{n-1}(W(x, r)) \quad \text{for each } r \in (0, 1), \quad (2-37)$$

it follows from (2-36) that

$$\int_{R/2}^R \phi(r) dr \leq \left(\frac{R}{2}\right)^{1-n} \int_0^R \mathcal{H}^{n-1}(W(x, r)) dr = o(R) \quad \text{as } R \rightarrow 0^+. \quad (2-38)$$

We introduce the dyadic intervals  $I_k := [2^{-(k+1)}, 2^{-k}]$  for  $k \in \mathbb{N}_0$  and note that (2-38) entails

$$\delta_k := \int_{I_k} \phi(r) dr \longrightarrow 0^+ \quad \text{as } k \rightarrow \infty. \quad (2-39)$$

For each  $k \in \mathbb{N}_0$  split

$$I_k = A_k \cup B_k \quad \text{with} \quad B_k := \{r \in I_k : \phi(r) > \sqrt{\delta_k}\} \quad \text{and} \quad A_k := I_k \setminus B_k. \quad (2-40)$$

Then Chebyshev's inequality permits us to estimate

$$\frac{\mathcal{L}^1(B_k)}{\mathcal{L}^1(I_k)} \leq \frac{1}{\sqrt{\delta_k}} \int_{I_k} \phi(r) dr = \sqrt{\delta_k} \quad \text{for all } k \in \mathbb{N}_0. \quad (2-41)$$

In light of (2-39), this implies that if we now define

$$\mathcal{O}_x := \bigcup_{k \in \mathbb{N}_0} A_k \subset (0, 1), \quad (2-42)$$

then

$$\lim_{\substack{r \rightarrow 0^+ \\ r \in \mathcal{O}_x}} \phi(r) = 0. \quad (2-43)$$

We claim that (2-33) also holds for this choice of  $\mathcal{O}_x$ . To see that this is the case, assume that some arbitrary  $\theta > 0$  has been fixed. For each  $\varepsilon \in (0, 1)$ , let  $N_\varepsilon \in \mathbb{N}_0$  be such that  $2^{-N_\varepsilon-1} < \varepsilon \leq 2^{-N_\varepsilon}$ . Since  $N_\varepsilon \rightarrow \infty$  as  $\varepsilon \rightarrow 0^+$ , it follows from (2-39) that there exists  $\varepsilon_\theta > 0$  with the property that

$$\delta_k \leq \theta^2 \quad \text{whenever } 0 < \varepsilon < \varepsilon_\theta \text{ and } k \geq N_\varepsilon. \quad (2-44)$$

Assuming that  $0 < \varepsilon < \varepsilon_\theta$  we may then estimate

$$\begin{aligned} 0 &\leq \frac{\varepsilon - \mathcal{L}^1(\mathcal{O}_x \cap (0, \varepsilon))}{\varepsilon} = \varepsilon^{-1} \mathcal{L}^1((0, \varepsilon) \setminus \mathcal{O}_x) \\ &\leq \varepsilon^{-1} \mathcal{L}^1((0, 2^{-N_\varepsilon}) \setminus \mathcal{O}_x) = \varepsilon^{-1} \sum_{k=N_\varepsilon}^{\infty} \mathcal{L}^1(B_k) \\ &\leq \varepsilon^{-1} \sum_{k=N_\varepsilon}^{\infty} \mathcal{L}^1(I_k) \sqrt{\delta_k} \leq \varepsilon^{-1} \theta 2^{-N_\varepsilon} \leq \frac{\theta}{2}. \end{aligned} \quad (2-45)$$

This finishes the proof of (2-33). At this stage, there remains to observe that since, generally speaking,  $|\mathcal{H}^{n-1}(U) - \mathcal{H}^{n-1}(V)| \leq \mathcal{H}^{n-1}(U \Delta V)$ , from (2-35) we have

$$\left| \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, r))}{\omega_{n-1} r^{n-1}} - \frac{1}{2} \right| \leq \frac{\mathcal{H}^{n-1}(W(x, r))}{\omega_{n-1} r^{n-1}} = \frac{1}{\omega_{n-1}} \phi(r) \quad (2-46)$$

for each  $r \in (0, 1)$ . Then (2-34) is a consequence of this and (2-43).  $\square$

Following [David and Semmes 1991] we now make the following definition:

**Definition 2.6.** Call a subset  $\Sigma$  of  $\mathbb{R}^n$  a *uniformly rectifiable set* provided it is Ahlfors regular and the following holds: there exist  $\varepsilon, M \in (0, \infty)$  such that, for each  $x \in \Sigma$  and  $R \in (0, \text{diam } \Sigma)$ , there is a Lipschitz map  $\varphi : B_R^{n-1} \rightarrow \mathbb{R}^n$  (where  $B_R^{n-1}$  is a ball of radius  $R$  in  $\mathbb{R}^{n-1}$ ) with Lipschitz constant at most  $M$ , such that

$$\mathcal{H}^{n-1}(\Sigma \cap B(x, R) \cap \varphi(B_R^{n-1})) \geq \varepsilon R^{n-1}. \quad (2-47)$$

Informally speaking, uniform rectifiability is about the ability of identifying big pieces of Lipschitz images inside the given set (in a uniform, scale-invariant fashion) and can be thought of as a quantitative version of countable rectifiability. From [Hofmann et al. 2010, p. 2629] we know that:

$$\text{Any uniformly rectifiable set } \Sigma \subset \mathbb{R}^n \text{ is countably rectifiable (of dimension } n-1\text{).} \quad (2-48)$$

Following [Hofmann et al. 2010], we shall also make the following definition:

**Definition 2.7.** We call a nonempty open proper subset  $\Omega$  of  $\mathbb{R}^n$  a UR (*uniformly rectifiable*) domain provided  $\Omega$  is an Ahlfors regular domain whose topological boundary,  $\partial\Omega$ , is a uniformly rectifiable set.

For further use, it is useful to point out that, as is apparent from definitions:

If  $\Omega \subset \mathbb{R}^n$  is a UR domain with  $\partial\Omega = \partial(\bar{\Omega})$  then  $\mathbb{R}^n \setminus \bar{\Omega}$  is a UR domain with the same boundary. (2-49)

We now turn to the notion of nontangential boundary trace of functions defined in a nonempty, proper, open set  $\Omega \subset \mathbb{R}^n$ . Fix  $\kappa > 0$  and for each boundary point  $x \in \partial\Omega$  introduce the nontangential approach region

$$\Gamma_\kappa(x) := \{y \in \Omega : |x - y| < (1 + \kappa) \operatorname{dist}(y, \partial\Omega)\}. \quad (2-50)$$

It should be noted that, under the current hypotheses, it could happen that  $\Gamma_\kappa(x) = \emptyset$  for points  $x \in \partial\Omega$  (as is the case if, e.g.,  $\Omega$  has a suitable cusp with vertex at  $x$ ). Next, given a Lebesgue measurable function  $u : \Omega \rightarrow \mathbb{R}$ , we wish to consider its limit at boundary points  $x \in \partial\Omega$  taken from within nontangential approach regions with vertex at  $x$ . For such a limit to be meaningfully defined at  $\sigma$ -a.e. point on  $\partial\Omega$  (where, as usual,  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$ ), it is necessary that

$$x \in \bar{\Gamma}_\kappa(x) \quad \text{for } \sigma\text{-a.e. } x \in \partial\Omega. \quad (2-51)$$

We shall call an open set  $\Omega \subseteq \mathbb{R}^n$  satisfying (2-51) above *weakly accessible*. Assuming that this is the case, we say that  $u$  has a nontangential boundary trace almost everywhere on  $\partial\Omega$  if for  $\sigma$ -a.e. point  $x \in \partial\Omega$  there exists some  $N(x) \subset \Gamma_\kappa(x)$  of measure zero such that the limit

$$(u|_{\partial\Omega}^{\text{nt}})(x) := \lim_{\substack{y \rightarrow x \\ y \in \Gamma_\kappa(x) \setminus N(x)}} u(y) \quad \text{exists.} \quad (2-52)$$

When  $u$  is a continuous function in  $\Omega$ , we may take  $N(x) = \emptyset$ . For future use, let us also define the nontangential maximal operator of  $u$  as

$$(\mathcal{N}u)(x) := \|u\|_{L^\infty(\Gamma_\kappa(x))} \in [0, \infty] \quad \text{for all } x \in \partial\Omega, \quad (2-53)$$

where the essential supremum (taken to be 0 if  $\Gamma_\kappa(x) = \emptyset$ ) in the right-hand side is taken with respect to the Lebesgue measure in  $\mathbb{R}^n$ .

The following result has been proved in [Hofmann et al. 2010, Proposition 2.9, p. 2588]:

**Proposition 2.8.** *Any Ahlfors regular domain is weakly accessible. As a corollary, any UR domain is weakly accessible.*

We continue by recording the definition of the class of uniform domains introduced by O. Martio and J. Sarvas [1979].

**Definition 2.9.** Call a nonempty, proper, open set  $\Omega \subseteq \mathbb{R}^n$  a *uniform domain* if there exists a constant  $c \in (0, \infty)$  with the property:

For each  $x, y \in \Omega$  there exists a rectifiable curve  $\gamma : [0, 1] \rightarrow \Omega$  joining  $x$  and  $y$  such that  $\text{length}(\gamma) \leq c|x - y|$  and which has the property

$$\min\{\text{length}(\gamma_{x,z}), \text{length}(\gamma_{z,y})\} \leq c \text{ dist}(z, \partial\Omega) \quad (2-54)$$

for all  $z \in \gamma([0, 1])$ , where  $\gamma_{x,z}$  and  $\gamma_{z,y}$  are the two components of the path  $\gamma([0, 1])$  joining  $x$  with  $z$ , and  $z$  with  $y$ , respectively.

Condition (2-54) asserts that the length of  $\gamma([0, 1])$  is comparable to the distance between its endpoints and that, away from its endpoints, the curve  $\gamma$  stays correspondingly far from  $\partial\Omega$ . Hence, heuristically, condition (2-54) implies that points in  $\Omega$  can be joined in  $\Omega$  by a curvilinear (or twisted) double cone which is neither too crooked nor too thin. Here we wish to note that, given an open nonempty subset  $\Omega$  of  $\mathbb{R}^n$  with compact boundary along with some  $\alpha \in (0, 1)$ , the following implication holds:

$$\Omega \text{ is a } \mathcal{C}^{1+\alpha} \text{ domain} \implies \Omega \text{ is a uniform domain.} \quad (2-55)$$

Throughout, we make the convention that, given a nonempty, proper subset  $\Omega$  of  $\mathbb{R}^n$ , we abbreviate

$$\rho(z) := \text{dist}(z, \partial\Omega) \quad \text{for every } z \in \Omega. \quad (2-56)$$

**Lemma 2.10.** *Let  $\Omega \subset \mathbb{R}^n$  be a uniform domain. Then for each  $\alpha \in (0, 1)$  there exists a finite constant  $C > 0$ , depending only on  $\alpha$  and  $\Omega$ , such that the estimate*

$$[u]_{\dot{\mathcal{C}}^\alpha(\Omega)} \leq C \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla u(x)|\} \quad (2-57)$$

holds for every function  $u \in \mathcal{C}^1(\Omega)$ .

*Proof.* Consider  $c > 0$  such that condition (2-54) is satisfied. Let  $x, y \in \Omega$  be two arbitrary points and assume that  $\gamma$  is as in Definition 2.9. Denote by  $L$  and  $s$  the length of the curve  $\gamma^* := \gamma([0, 1])$  and the arc-length parameter on  $\gamma^*$ , respectively, with  $s \in [0, L]$ . Also, let  $s \mapsto \gamma(s) \in \gamma^*$  be the canonical arc-length parametrization of  $\gamma^*$ . In particular,  $s \mapsto \gamma(s)$  is absolutely continuous,  $|d\gamma/ds| = 1$  for almost every  $s$  and, for every continuous function  $f$  in  $\Omega$ ,

$$\int_{\gamma^*} f := \int_0^L f(\gamma(s)) ds. \quad (2-58)$$

Thus, from (2-54) and (2-58), for each  $\alpha \in (0, 1)$  we have

$$\begin{aligned} \int_{\gamma^*} \rho^{\alpha-1} &= \int_0^L \rho(\gamma(s))^{\alpha-1} ds \leq c^{1-\alpha} \int_0^L (\min\{s, L-s\})^{\alpha-1} ds \\ &\leq 2c^{1-\alpha} \int_0^{L/2} s^{\alpha-1} ds = C(c, \alpha)L^\alpha \leq C(c, \alpha)|x - y|^\alpha. \end{aligned} \quad (2-59)$$

Then, since  $|d\gamma/ds| = 1$  for almost every  $s$ , for every  $u \in \mathcal{C}^1(\Omega)$  we may write

$$\begin{aligned} |u(x) - u(y)| &= \left| \int_0^L \frac{d}{ds}[u(\gamma(s))] ds \right| \leq \int_0^L |(\nabla u)(\gamma(s))| ds = \int_{\gamma^*} |\nabla u| \\ &\leq \sup_{\gamma^*} \{|\nabla u| \rho^{1-\alpha}\} \int_{\gamma^*} \rho^{\alpha-1} \\ &\leq C|x-y|^\alpha \|\nabla u\|_{L^\infty(\Omega)} \rho^{1-\alpha}, \end{aligned} \quad (2-60)$$

finishing the proof of (2-57).  $\square$

Recall that for each  $k \in \mathbb{N}$  we let  $\mathcal{L}^k$  stand for the  $k$ -dimensional Lebesgue measure in  $\mathbb{R}^k$ . Also, we shall let  $\langle \cdot, \cdot \rangle$  denote the standard inner product of vectors in  $\mathbb{R}^n$ .

**Lemma 2.11.** *Assume that  $D \subseteq \mathbb{R}^n$  is a set of locally finite perimeter. Denote by  $v$  its geometric measure-theoretic outward unit normal and define  $\sigma := \mathcal{H}^{n-1}|_{\partial_* D}$ . Also, suppose that  $\vec{F} \in \mathcal{C}_0^1(\mathbb{R}^n, \mathbb{R}^n)$ . Then, for each  $x \in \mathbb{R}^n$ ,*

$$\int_{D \cap B(x,r)} \operatorname{div} \vec{F} d\mathcal{L}^n = \int_{\partial_* D \cap B(x,r)} \langle \vec{F}, v \rangle d\sigma + \int_{D \cap \partial B(x,r)} \langle \vec{F}, v \rangle d\mathcal{H}^{n-1} \quad (2-61)$$

and

$$\int_{D \setminus B(x,r)} \operatorname{div} \vec{F} d\mathcal{L}^n = \int_{\partial_* D \setminus B(x,r)} \langle \vec{F}, v \rangle d\sigma - \int_{D \cap \partial B(x,r)} \langle \vec{F}, v \rangle d\mathcal{H}^{n-1} \quad (2-62)$$

for  $\mathcal{L}^1$ -a.e.  $r \in (0, \infty)$ , where  $v$  in each of the last integrals in the above right-hand sides is the outward unit normal to  $B(x, r)$ .

*Proof.* Identity (2-61) is simply [Evans and Gariepy 1992, Lemma 1, p. 195]. Then (2-62) follows by combining this with the Gauss–Green formula [Evans and Gariepy 1992, Theorem 1, p. 209].  $\square$

We conclude this section by recording the following two-dimensional result, which is going to be relevant when dealing with the proof of [Theorem 1.3](#).

**Proposition 2.12.** *Let  $\Omega \subseteq \mathbb{C}$  be a bounded open set whose boundary is an upper Ahlfors regular Jordan curve. Then  $\Omega$  is a simply connected UR domain satisfying  $\partial\Omega = \partial(\bar{\Omega})$ . Hence, in particular,  $\mathcal{H}^1(\partial\Omega \setminus \partial_* \Omega) = 0$  and  $\mathbb{C} \setminus \bar{\Omega}$  is also a UR domain with the same boundary as  $\Omega$ .*

Moreover, the curve  $\partial\Omega$  is rectifiable and, if  $L$  denotes its length and  $[0, L] \ni s \mapsto z(s) \in \Sigma$  is its arc-length parametrization, then

$$\mathcal{H}^1(E) = \mathcal{L}^1(z^{-1}(E)) \quad \text{for all measurable sets } E \subseteq \partial\Omega, \quad (2-63)$$

where  $\mathcal{L}^1$  is the one-dimensional Lebesgue measure, and if  $v$  denotes the geometric measure-theoretic outward unit normal to  $\Omega$  then

$$v(z(s)) = -iz'(s) \quad \text{for } \mathcal{L}^1\text{-a.e. } s \in [0, L]. \quad (2-64)$$

A proof of [Proposition 2.12](#) may be found in [Mitrea et al. 2016].

### 3. Background and preparatory estimates for singular integrals

The proofs of the main results require a number of prerequisites, and this section collects several useful estimates for singular integral operators. The first theorem in this regard essentially amounts to a version of the Calderón–Zygmund theory for singular integrals on uniformly rectifiable sets.

**Theorem 3.1.** *There exists a positive integer  $N = N(n)$  with the following significance: Suppose  $\Sigma \subseteq \mathbb{R}^n$  is a uniformly rectifiable set and define  $\sigma := \mathcal{H}^{n-1}|_{\Sigma}$ . Also consider a complex-valued function*

$$k \in \mathscr{C}^N(\mathbb{R}^n \setminus \{0\}) \quad \text{satisfying} \quad \begin{cases} k(-x) = -k(x) & \text{for each } x \in \mathbb{R}^n, \\ k(\lambda x) = \lambda^{-(n-1)}k(x) & \text{for all } \lambda > 0, x \in \mathbb{R}^n \setminus \{0\}. \end{cases} \quad (3-1)$$

For each  $\varepsilon > 0$ , consider the truncated singular integral operator

$$T_\varepsilon f(x) := \int_{\substack{y \in \Sigma \\ |x-y|>\varepsilon}} k(x-y) f(y) d\sigma(y), \quad x \in \Sigma, \quad (3-2)$$

and define the maximal operator  $T_*$  by setting

$$T_* f(x) := \sup_{\varepsilon > 0} |T_\varepsilon f(x)|, \quad x \in \Sigma. \quad (3-3)$$

Then for each  $p \in (1, \infty)$  there exists a constant  $C \in (0, \infty)$ , depending only on  $p$  and  $\Sigma$ , such that

$$\|T_* f\|_{L^p(\Sigma, \sigma)} \leq C \|k\|_{S^{n-1}} \|\mathscr{C}^N(S^{n-1})\| \|f\|_{L^p(\Sigma, \sigma)} \quad (3-4)$$

for every  $f \in L^p(\Sigma, \sigma)$ . Furthermore, given any  $p \in [1, \infty)$ , for each function  $f \in L^p(\Sigma, \sigma)$  the limit

$$Tf(x) := \lim_{\varepsilon \rightarrow 0^+} T_\varepsilon f(x) \quad (3-5)$$

exists for  $\sigma$ -a.e.  $x \in \Sigma$ , and the induced operators

$$T : L^p(\Sigma, \sigma) \longrightarrow L^p(\Sigma, \sigma), \quad p \in (1, \infty), \quad (3-6)$$

$$T : L^1(\Sigma, \sigma) \longrightarrow L^{1,\infty}(\Sigma, \sigma) \quad (3-7)$$

are well-defined, linear and bounded. In addition, for each  $p \in (1, \infty)$ , the adjoint of the operator  $T$  acting on  $L^p(\Sigma, \sigma)$  is  $-T$  acting on  $L^{p'}(\Sigma, \sigma)$  with  $1/p + 1/p' = 1$ . Finally, corresponding to the endpoint  $p = \infty$ , the operator  $T$  also induces a linear and bounded mapping

$$T : L^\infty(\Sigma, \sigma) \longrightarrow \text{BMO}(\Sigma). \quad (3-8)$$

Once the existence of the principal value singular integral operator  $T$  defined by the limit in (3-5) has been established, all other claims follow from [David and Semmes 1991] and standard harmonic analysis. As far as the issue of well-definedness of  $T$  is concerned, it is not difficult to reduce matters to the case when  $\Sigma$  is an  $(n-1)$ -dimensional Lipschitz graph (Taylor, personal communication, 2015). In the latter scenario, the desired result is known. For example, the desired conclusion is contained in [Hofmann et al. 2010, Theorem 3.33, p. 2669], where a more general result (applicable to variable coefficient operators on

boundaries of UR domains) can be found. A direct proof for Lipschitz graphs may be found in [Hofmann et al. 2015, Proposition B.2, p. 163]. In this vein, see also [David 1991, pp. 63–64] for a sketch of a proof.

Our next theorem deals with nontangential maximal function estimates and jump relations for integral operators on UR domains. For a proof, the reader is once again referred to [Hofmann et al. 2010, Theorem 3.33, p. 2669].

**Theorem 3.2.** *Assume  $\Omega \subset \mathbb{R}^n$  is a UR domain and let  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  and  $v$  denote the surface measure on  $\partial\Omega$  and the outward unit normal to  $\Omega$ , respectively. Select a function  $k$  as in (3-1) with  $N = N(n)$  sufficiently large, and define*

$$\mathcal{T}f(x) := \int_{\partial\Omega} k(x - y)f(y)d\sigma(y), \quad x \in \Omega. \quad (3-9)$$

*Then for each  $p \in (1, \infty)$  there exists a finite constant  $C = C(\Omega, k, p) > 0$  such that*

$$\|\mathcal{N}(\mathcal{T}f)\|_{L^p(\partial\Omega, \sigma)} \leq C\|f\|_{L^p(\partial\Omega, \sigma)} \quad \text{for all } f \in L^p(\partial\Omega, \sigma), \quad (3-10)$$

*and, corresponding to  $p = 1$ ,*

$$\|\mathcal{N}(\mathcal{T}f)\|_{L^{1,\infty}(\partial\Omega, \sigma)} \leq C\|f\|_{L^1(\partial\Omega, \sigma)} \quad \text{for all } f \in L^1(\partial\Omega, \sigma). \quad (3-11)$$

*Also, if “hat” denotes the Fourier transform in  $\mathbb{R}^n$  and  $i := \sqrt{-1} \in \mathbb{C}$ , then for every  $f \in L^p(\partial\Omega, \sigma)$  with  $p \in [1, \infty)$  the jump formula*

$$(\mathcal{T}f|_{\partial\Omega}^{\text{nt}})(x) = \lim_{\Gamma_k \ni z \rightarrow x} \mathcal{T}f(z) = \frac{1}{2i} \hat{k}(v(x))f(x) + Tf(x) \quad (3-12)$$

*is valid at  $\sigma$ -a.e. point  $x \in \partial\Omega$ , where  $T$  is the principal value singular integral operator associated with the kernel  $k$ , as in (3-5).*

The Fourier transform in  $\mathbb{R}^n$  employed in (3-12) is

$$\hat{\phi}(\xi) := \int_{\mathbb{R}^n} e^{-i\langle x, \xi \rangle} \phi(x) dx, \quad \xi \in \mathbb{R}^n. \quad (3-13)$$

Let us also note that the hypotheses (3-1) imposed on the kernel  $k$  imply that  $|k(x)| \leq \|k\|_{L^\infty(S^{n-1})}|x|^{1-n}$  for each  $x \in \mathbb{R}^n \setminus \{0\}$ . Hence,  $k$  is a tempered distribution in  $\mathbb{R}^n$  and  $\hat{k}$ , originally considered in the class of tempered distributions in  $\mathbb{R}^n$ , satisfies

$$\hat{k} \in \mathscr{C}^m(\mathbb{R}^n \setminus \{0\}) \text{ if } N \in \mathbb{N} \text{ is even and } m \in \mathbb{N}_0 \text{ is such that } m < N - 1 \quad (3-14)$$

(see [Mitrea 2013, Exercise 4.60, p. 133]). In particular, (3-14) ensures that  $\hat{k}(v(x))$  is meaningfully defined in (3-12) for  $\sigma$ -a.e.  $x \in \partial\Omega$  whenever  $N \geq 2$ .

**Lemma 3.3.** *Suppose  $\Omega$  is a nonempty, proper, open subset of  $\mathbb{R}^n$  with a compact boundary, satisfying an upper Ahlfors regularity condition with constant  $c \in (0, \infty)$ . In this setting, define  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  and consider an integral operator*

$$\mathcal{I}f(x) := \int_{\partial\Omega} k(x, y)f(y)d\sigma(y), \quad x \in \Omega, \quad (3-15)$$

whose kernel  $k : \Omega \times \partial\Omega \rightarrow \mathbb{R}$  has the property that there exists some finite positive constant  $C_0$  such that

$$|k(x, y)| \leq \frac{C_0}{|x - y|^{n-1}} \quad (3-16)$$

for each  $x \in \Omega$  and  $\sigma$ -a.e.  $y \in \partial\Omega$ . Also suppose that

$$\sup_{x \in \Omega} |\mathcal{T}1(x)| < +\infty. \quad (3-17)$$

Then for every  $\alpha \in (0, 1)$  one has

$$\begin{aligned} \sup_{x \in \Omega} |\mathcal{T}f(x)| \\ \leq cC_0 \frac{2^{2n-2+\alpha}}{2^\alpha - 1} (1 + [\text{diam}(\partial\Omega)]^\alpha) [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} + (\|\mathcal{T}1\|_{L^\infty(\Omega)} + cC_0[\text{diam}(\partial\Omega)]^{n-1}) \|f\|_{L^\infty(\partial\Omega)} \end{aligned} \quad (3-18)$$

for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$ .

*Proof.* Pick an arbitrary  $f \in \mathcal{C}^\alpha(\partial\Omega)$  and fix any  $x \in \Omega$ . Consider first the case when  $\text{dist}(x, \partial\Omega) \geq 1$ , in which we may directly estimate

$$|\mathcal{T}f(x)| \leq C_0\sigma(\partial\Omega)\|f\|_{L^\infty(\partial\Omega)} \leq cC_0[\text{diam}(\partial\Omega)]^{n-1}\|f\|_{L^\infty(\partial\Omega)}. \quad (3-19)$$

In the case when  $\text{dist}(x, \partial\Omega) < 1$ , select a point  $x_* \in \partial\Omega$  such that

$$|x - x_*| = \text{dist}(x, \partial\Omega) =: r \in (0, 1) \quad (3-20)$$

and split  $\mathcal{T}f(x)$  into  $I + II + III$ , where

$$I := \int_{\partial\Omega \cap B(x_*, 2r)} k(x, y)(f(y) - f(x_*)) d\sigma(y), \quad (3-21)$$

$$II := \int_{\partial\Omega \setminus B(x_*, 2r)} k(x, y)(f(y) - f(x_*)) d\sigma(y), \quad (3-22)$$

$$III := (\mathcal{T}1)(x)f(x_*). \quad (3-23)$$

Note that

$$\begin{aligned} |I| &\leq \int_{\partial\Omega \cap B(x_*, 2r)} |k(x, y)| |f(y) - f(x_*)| d\sigma(y) \\ &\leq C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \cap B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|x - y|^{n-1}} d\sigma(y) \\ &\leq C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \frac{(2r)^\alpha}{r^{n-1}} \sigma(\partial\Omega \cap B(x_*, 2r)), \end{aligned} \quad (3-24)$$

where the third inequality comes from the facts that  $|y - x_*|^\alpha \leq (2r)^\alpha$  on the domain of integration and that  $1/|x - y| \leq 1/|x - x_*| = 1/r$  for all  $y \in \partial\Omega$ . Hence,

$$|I| \leq 2^{n-1+\alpha} cC_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)}, \quad (3-25)$$

bearing in mind (3-20) and the upper Ahlfors regularity of  $\partial\Omega$ . Also,

$$|II| \leq C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \setminus B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|x - y|^{n-1}} d\sigma(y). \quad (3-26)$$

Note that if  $y \in \partial\Omega \setminus B(x_*, 2r)$  then

$$|y - x_*| \leq |y - x| + |x - x_*| \quad \text{and} \quad r \leq \frac{1}{2}|y - x_*| \quad \Rightarrow \quad |y - x_*| \leq 2|y - x|. \quad (3-27)$$

Hence,  $1/|x - y|^{n-1} \leq 2^{n-1}/|y - x_*|^{n-1}$  on the domain of integration  $\partial\Omega \setminus B(x_*, 2r)$ . Also, if we introduce

$$N := \left\lceil \log_2 \frac{\text{diam}(\partial\Omega)}{r} \right\rceil \in \mathbb{N}, \quad (3-28)$$

then  $\partial\Omega \setminus B(x_*, 2^k r) = \emptyset$  for each integer  $k > N$ . Together, these observations and (3-26) allow us to estimate

$$\begin{aligned} |II| &\leq 2^{n-1} C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \setminus B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|y - x_*|^{n-1}} d\sigma(y) \\ &\leq 2^{n-1} C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^N \int_{\partial\Omega \cap [B(x_*, 2^{k+1}r) \setminus B(x_*, 2^k r)]} \frac{1}{|y - x_*|^{n-1-\alpha}} d\sigma(y) \\ &\leq 2^{n-1} C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^N (2^k r)^{-(n-1-\alpha)} \sigma(\partial\Omega \cap B(x_*, 2^{k+1}r)). \end{aligned} \quad (3-29)$$

Thus, by the upper Ahlfors regularity condition,

$$\begin{aligned} |II| &\leq 2^{n-1} C_0[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^N (2^k r)^{-(n-1-\alpha)} c (2^{k+1} r)^{n-1} \\ &= 2^{2n-2} c C_0 r^\alpha [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^N (2^\alpha)^k \\ &\leq 2^{2n-2+\alpha} c C_0 r^\alpha [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \frac{(2^N)^\alpha}{2^\alpha - 1} \\ &\leq \frac{2^{2n-2+\alpha}}{2^\alpha - 1} c C_0 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} [\text{diam}(\partial\Omega)]^\alpha. \end{aligned} \quad (3-30)$$

Since, clearly,  $|III| \leq \|\mathcal{T}_1\|_{L^\infty(\Omega)} \|f\|_{L^\infty(\partial\Omega)}$ , the desired conclusion follows.  $\square$

**Lemma 3.4.** *Retain the same assumptions on  $\Omega$  as in Lemma 3.3 and consider an integral operator*

$$\mathcal{Q}f(x) := \int_{\partial\Omega} q(x, y) f(y) d\sigma(y), \quad x \in \Omega, \quad (3-31)$$

whose kernel  $q : \Omega \times \partial\Omega \rightarrow \mathbb{R}$  is assumed to satisfy

$$|q(x, y)| \leq \frac{C_1}{|x - y|^n} \quad \text{for all } x \in \Omega, y \in \partial\Omega, \quad (3-32)$$

for some finite positive constant  $C_1$ . Also, with  $\rho$  as in (2-56), suppose there exists  $\alpha \in (0, 1)$  with the property that

$$C_2 := \sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |(\mathcal{Q}1)(x)| \} < +\infty. \quad (3-33)$$

Then one has

$$\sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |\mathcal{Q}f(x)| \} \leq \frac{2^{2n-1+\alpha}}{1-2^{\alpha-1}} c C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} + C_2 \|f\|_{L^\infty(\partial\Omega)} \quad (3-34)$$

for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$ .

*Proof.* Select an arbitrary  $f \in \mathcal{C}^\alpha(\partial\Omega)$ . Pick some  $x \in \Omega$  and choose  $x_* \in \partial\Omega$  such that  $|x - x_*| = \rho(x) =: r$ . Split  $\mathcal{Q}f(x)$  into  $I + II + III$ , where

$$I := \int_{\partial\Omega \cap B(x_*, 2r)} q(x, y) [f(y) - f(x_*)] d\sigma(y), \quad (3-35)$$

$$II := \int_{\partial\Omega \setminus B(x_*, 2r)} q(x, y) [f(y) - f(x_*)] d\sigma(y), \quad (3-36)$$

$$III := (\mathcal{Q}1)(x) f(x_*). \quad (3-37)$$

Then

$$\begin{aligned} |I| &\leq \int_{\partial\Omega \cap B(x_*, 2r)} |q(x, y)| |f(y) - f(x_*)| d\sigma(y) \\ &\leq C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \cap B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|x - y|^n} d\sigma(y) \\ &\leq C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \frac{(2r)^\alpha}{r^n} \sigma(\partial\Omega \cap B(x_*, 2r)) \leq 2^{n-1+\alpha} c C_1 \rho(x)^{\alpha-1} [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)}. \end{aligned} \quad (3-38)$$

Next, keeping in mind that  $1/|x - y|^n \leq 2^n/|y - x_*|^n$  on  $\partial\Omega \setminus B(x_*, 2r)$  (see (3-27)), we may estimate

$$\begin{aligned} |II| &\leq C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \setminus B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|x - y|^n} d\sigma(y) \\ &\leq 2^n C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \int_{\partial\Omega \setminus B(x_*, 2r)} \frac{|y - x_*|^\alpha}{|y - x_*|^n} d\sigma(y) \\ &\leq 2^n C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^{\infty} \int_{\partial\Omega \cap [B(x_*, 2^{k+1}r) \setminus B(x_*, 2^k r)]} \frac{1}{|y - x_*|^{n-\alpha}} d\sigma(y) \\ &\leq 2^n C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^{\infty} (2^k r)^{-(n-\alpha)} \sigma(\partial\Omega \cap B(x_*, 2^{k+1}r)) \\ &\leq 2^n C_1 [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^{\infty} (2^k r)^{-(n-\alpha)} c (2^{k+1}r)^{n-1} \\ &= 2^{2n-1} c C_1 r^{\alpha-1} [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} \sum_{k=1}^{\infty} (2^{\alpha-1})^k = \frac{2^{2n-2+\alpha}}{1-2^{\alpha-1}} c C_1 \rho(x)^{\alpha-1} [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)}. \end{aligned} \quad (3-39)$$

Given that  $\rho(x)^{1-\alpha} |III| \leq C_2 \|f\|_{L^\infty(\partial\Omega)}$ , the estimate (3-34) is established.  $\square$

**Lemma 3.5.** *Let  $\Omega$  be a nonempty open proper subset of  $\mathbb{R}^n$  whose boundary is compact and satisfies an upper Ahlfors regularity condition with constant  $c \in (0, \infty)$ . In this setting, define  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  and consider an integral operator*

$$\mathcal{T}f(x) := \int_{\partial\Omega} K(x, y) f(y) d\sigma(y), \quad x \in \Omega, \quad (3-40)$$

whose kernel  $K : \Omega \times \partial\Omega \rightarrow \mathbb{R}$  has the property that there exists a finite constant  $B > 0$  such that

$$|K(x, y)| + |x - y| |\nabla_x K(x, y)| \leq \frac{B}{|x - y|^{n-1}} \quad (3-41)$$

for each  $x \in \Omega$  and  $\sigma$ -a.e.  $y \in \partial\Omega$ . Fix some  $\alpha \in (0, 1)$  and suppose that

$$A := \sup_{x \in \Omega} |(\mathcal{T}1)(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathcal{T}1)(x)|\} < +\infty. \quad (3-42)$$

Then for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$  one has

$$\begin{aligned} \sup_{x \in \Omega} |\mathcal{T}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathcal{T}f)(x)|\} &\leq cBC_{n,\alpha}(2 + [\text{diam}(\partial\Omega)]^\alpha)[f]_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\quad + (2A + cB[\text{diam}(\partial\Omega)]^{n-1}) \|f\|_{L^\infty(\partial\Omega)}, \end{aligned} \quad (3-43)$$

where

$$C_{n,\alpha} := 2^{2n-2-\alpha} \max\{(2^\alpha - 1)^{-1}, 2(1 - 2^{\alpha-1})^{-1}\}. \quad (3-44)$$

As a consequence, there exists a finite constant  $C_{n,\alpha,\Omega} > 0$  with the property that for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$  one has

$$\sup_{x \in \Omega} |\mathcal{T}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathcal{T}f)(x)|\} \leq C_{n,\alpha,\Omega}(A + B) \|f\|_{\mathcal{C}^\alpha(\partial\Omega)}. \quad (3-45)$$

*Proof.* This is an immediate consequence of Lemmas 3.3 and 3.4. □

#### 4. Clifford analysis

A key tool for us is Clifford analysis, and here we elaborate on those aspects used in the proof of Theorem 1.1. To begin, the *Clifford algebra* with  $n$  imaginary units is the minimal enlargement of  $\mathbb{R}^n$  to a unitary real algebra  $(\mathcal{C}\ell_n, +, \odot)$  that is not generated (as an algebra) by any proper subspace of  $\mathbb{R}^n$  and such that

$$x \odot x = -|x|^2 \quad \text{for any } x \in \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n. \quad (4-1)$$

This identity readily implies that, if  $\{e_j\}_{1 \leq j \leq n}$  is the standard orthonormal basis in  $\mathbb{R}^n$ , then

$$e_j \odot e_j = -1 \quad \text{and} \quad e_j \odot e_k = -e_k \odot e_j \quad \text{whenever } 1 \leq j \neq k \leq n. \quad (4-2)$$

In particular, identifying the canonical basis  $\{e_j\}_{1 \leq j \leq n}$  from  $\mathbb{R}^n$  with the  $n$  imaginary units generating  $\mathcal{C}\ell_n$ , yields the embedding<sup>4</sup>

$$\mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n, \quad \mathbb{R}^n \ni x = (x_1, \dots, x_n) \equiv \sum_{j=1}^n x_j e_j \in \mathcal{C}\ell_n. \quad (4-3)$$

Also, any element  $u \in \mathcal{C}\ell_n$  can be uniquely represented in the form

$$u = \sum_{l=0}^n \sum'_{|I|=l} u_I e_I, \quad u_I \in \mathbb{R}. \quad (4-4)$$

Here  $e_I$  stands for the product  $e_{i_1} \odot e_{i_2} \odot \cdots \odot e_{i_l}$  if  $I = (i_1, i_2, \dots, i_l)$  and  $e_0 := e_\emptyset := 1$  is the multiplicative unit. Also,  $\sum'$  indicates that the sum is performed only over strictly increasing multi-indices, i.e.,  $I = (i_1, i_2, \dots, i_l)$  with  $1 \leq i_1 < i_2 < \cdots < i_l \leq n$ . We endow  $\mathcal{C}\ell_n$  with the natural Euclidean metric

$$|u| := \left\{ \sum_I |u_I|^2 \right\}^{\frac{1}{2}} \quad \text{for each } u = \sum_I u_I e_I \in \mathcal{C}\ell_n. \quad (4-5)$$

The Clifford conjugation on  $\mathcal{C}\ell_n$ , denoted by “bar”, is defined as the unique real-linear involution on  $\mathcal{C}\ell_n$  for which  $\bar{e}_I e_I = e_I \bar{e}_I = 1$  for any multi-index  $I$ . More specifically, given  $u = \sum_I u_I e_I \in \mathcal{C}\ell_n$  we set  $\bar{u} := \sum_I u_I \bar{e}_I$  where, for each  $I = (i_1, i_2, \dots, i_l)$  with  $1 \leq i_1 < i_2 < \cdots < i_l \leq n$ ,

$$\bar{e}_I = (-1)^l e_{i_l} \odot e_{i_{l-1}} \odot \cdots \odot e_{i_1}. \quad (4-6)$$

Let us also define the scalar part of  $u = \sum_I u_I e_I \in \mathcal{C}\ell_n$  as  $u_0 := u_\emptyset$ , and endow  $\mathcal{C}\ell_n$  with the natural Hilbert space structure

$$\langle u, v \rangle := \sum_I u_I v_I \quad \text{if } u = \sum_I u_I e_I, v = \sum_I v_I e_I \in \mathcal{C}\ell_n. \quad (4-7)$$

It follows directly from definitions that

$$\bar{x} = -x \quad \text{for each } x \in \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n, \quad (4-8)$$

and other properties are collected in the lemma below.

**Lemma 4.1.** *For any  $u, v \in \mathcal{C}\ell_n$  one has*

$$|u|^2 = (u \odot \bar{u})_0 = (\bar{u} \odot u)_0, \quad (4-9)$$

$$\langle u, v \rangle = (u \odot \bar{v})_0 = (\bar{u} \odot v)_0, \quad (4-10)$$

$$\overline{u \odot v} = \bar{v} \odot \bar{u}, \quad (4-11)$$

---

<sup>4</sup>As the alert reader might have noted, for  $n = 2$  the identification in (4-3) amounts to embedding  $\mathbb{R}^2$  into the quaternions, i.e.,  $\mathbb{R}^2 \hookrightarrow \mathbb{H} := \{x_0 + x_1 \mathbf{i} + x_2 \mathbf{j} + x_3 \mathbf{k} : x_0, x_1, x_2, x_3 \in \mathbb{R}\}$  via  $(x_1, x_2) \equiv x_1 \mathbf{i} + x_2 \mathbf{j} \in \mathbb{H}$ . The reader is reassured that this is simply a matter of convenience, and we might as well have arranged that the embedding (4-3) comes down, when  $n = 2$ , to perhaps the more familiar identification  $\mathbb{R}^2 \cong \mathbb{C}$ , by taking  $x = (x_0, x_1, \dots, x_{n-1}) \equiv x_0 + x_1 e_1 + \dots + x_{n-1} e_{n-1} \in \mathcal{C}\ell_{n-1}$ . The latter choice leads to a parallel theory to the one presented here, entailing only minor natural alterations.

$$|\bar{u}| = |u|, \quad (4-12)$$

$$|u \odot v| \leq 2^{n/2} |u| |v|, \quad (4-13)$$

and

$$|u \odot v| = |u| |v| \quad \text{if either } u \text{ or } v \text{ belongs to } \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n. \quad (4-14)$$

*Proof.* Properties (4-9)–(4-12) are straightforward consequences of the definitions. To justify (4-13), assume  $u = \sum_I u_I e_I \in \mathcal{C}\ell_n$  and  $v = \sum_J v_J e_J \in \mathcal{C}\ell_n$  have been given. Then

$$\begin{aligned} |u \odot v| &= \left| \sum_I \left( \sum_J u_I v_J e_I \odot e_J \right) \right| \leq \sum_I \left| \sum_J u_I v_J e_I \odot e_J \right| = \sum_I \left( \sum_J |u_I v_J|^2 \right)^{\frac{1}{2}} = |v| \sum_I |u_I| \\ &\leq |v| \left( \sum_I |u_I|^2 \right)^{\frac{1}{2}} \left( \sum_I 1 \right)^{\frac{1}{2}} = 2^{n/2} |u| |v|. \end{aligned} \quad (4-15)$$

Above, the triangle inequality has been employed in the second step. The third step relies on (4-5) and the observation that, for each fixed  $I$ , the family of Clifford algebra elements  $\{e_I \odot e_J\}_J$  coincides modulo signs with the orthonormal basis  $\{e_K\}_K$ . The penultimate step is the discrete Cauchy–Schwarz inequality.

As regards (4-14), assume that  $v \in \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n$  and write

$$|u \odot v|^2 = ((u \odot v) \odot \bar{u} \odot \bar{v})_0 = (u \odot (v \odot \bar{v}) \odot \bar{u})_0 = |v|^2 (u \odot \bar{u})_0 = |u|^2 |v|^2, \quad (4-16)$$

by (4-9), (4-11), (4-8) and (4-1). Finally, the case when  $u \in \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n$  follows from what we have just proved, with the help of (4-11) and (4-12).  $\square$

Next, recall the *Dirac operator*

$$D := \sum_{j=1}^n e_j \partial_j. \quad (4-17)$$

In the sequel, we shall use  $D_L$  and  $D_R$  to denote the action of  $D$  on a  $\mathcal{C}^1$  function  $u : \Omega \rightarrow \mathcal{C}\ell_n$  (where  $\Omega$  is an open subset of  $\mathbb{R}^n$ ) from the left and from the right, respectively. For a sufficiently nice domain  $\Omega$  with outward unit normal  $\nu = (\nu_1, \dots, \nu_n)$  — identified with the  $\mathcal{C}\ell_n$ -valued function  $\nu = \sum_{j=1}^n \nu_j e_j$  — and surface measure  $\sigma$ , and for any two reasonable  $\mathcal{C}\ell_n$ -valued functions  $u$  and  $v$  in  $\Omega$ , the following integration by parts formula holds:

$$\int_{\partial\Omega} u(x) \odot v(x) \odot v(x) d\sigma(x) = \int_{\Omega} ((D_R u)(x) \odot v(x) + u(x) \odot (D_L v)(x)) dx. \quad (4-18)$$

More detailed accounts of these and related matters can be found in [Brackx et al. 1982; Mitrea 1994]. In general, if  $(\mathcal{X}, \|\cdot\|_{\mathcal{X}})$  is a Banach space then by  $\mathcal{X} \otimes \mathcal{C}\ell_n$  we shall denote the Banach space consisting of elements of the form

$$u = \sum_{l=0}^n \sum_{|I|=l} u_I e_I, \quad u_I \in \mathcal{X}, \quad (4-19)$$

equipped with the natural norm

$$\|u\|_{\mathcal{X} \otimes \mathcal{C}\ell_n} := \sum_{l=0}^n \sum'_{|I|=l} \|u_I\|_{\mathcal{X}}. \quad (4-20)$$

A simple but useful observation in this context is that:

If  $\Omega \subset \mathbb{R}^n$  is a domain of class  $\mathcal{C}^{1+\alpha}$  for some  $\alpha \in (0, 1)$  then  $v \odot : \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n \rightarrow \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  is an isomorphism whose norm and the norm of its inverse are at most  $2\|v\|_{\mathcal{C}^\alpha(\partial\Omega)}$ . (4-21)

Indeed, by (4-1), its inverse is  $-v \odot$  and the aforementioned norm estimates are simple consequences of (4-14), bearing in mind that  $\|v\|_{\mathcal{C}^\alpha(\partial\Omega)} \geq 1$ .

For each  $s \in \{1, \dots, n\}$  we let  $[\cdot]_s$  denote the projection onto the  $s$ -th Euclidean coordinate, i.e.,  $[x]_s := x_s$  if  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ . The following lemma, in the spirit of work of Semmes [1989], will play an important role for us.

**Lemma 4.2.** *For any odd, harmonic, homogeneous polynomial  $P(x)$ ,  $x \in \mathbb{R}^n$  (with  $n \geq 2$ ), of degree  $l \geq 3$ , there exist a family  $P_{rs}(x)$ ,  $1 \leq r, s \leq n$ , of harmonic, homogeneous polynomials of degree  $l - 2$ , as well as a family of odd  $\mathcal{C}^\infty$  functions*

$$k_{rs} : \mathbb{R}^n \setminus \{0\} \longrightarrow \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n, \quad 1 \leq r, s \leq n, \quad (4-22)$$

which are homogeneous of degree  $-(n - 1)$  and, for each  $x \in \mathbb{R}^n \setminus \{0\}$ , satisfy

$$\frac{P(x)}{|x|^{n-1+l}} = \sum_{r,s=1}^n [k_{rs}(x)]_s, \quad (4-23)$$

$$(D_R k_{rs})(x) = \frac{l-1}{n+l-3} \frac{\partial}{\partial x_r} \left( \frac{P_{rs}(x)}{|x|^{n+l-3}} \right), \quad 1 \leq r, s \leq n. \quad (4-24)$$

Moreover, there exists a finite-dimensional constant  $c_n > 0$  such that

$$\max_{1 \leq r, s \leq n} \|k_{rs}\|_{L^\infty(S^{n-1})} + \max_{1 \leq r, s \leq n} \|\nabla k_{rs}\|_{L^\infty(S^{n-1})} \leq c_n 2^l \|P\|_{L^1(S^{n-1})}. \quad (4-25)$$

*Proof.* Given an odd, harmonic, homogeneous polynomial  $P(x)$  of degree  $l \geq 3$  in  $\mathbb{R}^n$ , for  $r, s \in \{1, \dots, n\}$  introduce

$$P_{rs}(x) := \frac{1}{l(l-1)} (\partial_r \partial_s P)(x) \quad \text{for all } x \in \mathbb{R}^n. \quad (4-26)$$

Then each  $P_{rs}$  is an odd, harmonic, homogeneous polynomial of degree  $l - 2$  in  $\mathbb{R}^n$ , and Euler's formula for homogeneous functions gives

$$P(x) = \sum_{r,s=1}^n x_r x_s P_{rs}(x) \quad \text{for all } x \in \mathbb{R}^n \quad (4-27)$$

and, for each  $r, s \in \{1, \dots, n\}$ ,

$$\langle (\nabla P_{rs})(x), x \rangle = (l-2) P_{rs}(x) \quad \text{for all } x \in \mathbb{R}^n. \quad (4-28)$$

To proceed, assume first that  $n \geq 3$  and define the function  $k_{rs} : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n$  for each  $r, s \in \{1, \dots, n\}$  by setting

$$k_{rs}(x) := \frac{1}{(n+l-3)(n+l-5)} \sum_{j=1}^n \partial_r \partial_j \left( \frac{P_{rs}(x)}{|x|^{n+l-5}} \right) e_j \quad \text{for all } x \in \mathbb{R}^n \setminus \{0\}. \quad (4-29)$$

The fact that  $n, l \geq 3$  ensures that both  $n+l-3 \neq 0$  and  $n+l-5 \neq 0$ , so each  $k_{rs}$  is well-defined, odd,  $\mathcal{C}^\infty$  and homogeneous of degree  $-(n-1)$  in  $\mathbb{R}^n \setminus \{0\}$ . In addition,

$$k_{rs}(x) = \frac{1}{(n+l-3)(n+l-5)} D_R \left[ \partial_r \left( \frac{P_{rs}(x)}{|x|^{n+l-5}} \right) \right] \quad \text{for all } x \in \mathbb{R}^n \setminus \{0\}; \quad (4-30)$$

hence, for all  $x \in \mathbb{R}^n \setminus \{0\}$  we may write

$$\begin{aligned} (D_R k_{rs})(x) &= \frac{1}{(n+l-3)(n+l-5)} D_R^2 \left[ \partial_r \left( \frac{P_{rs}(x)}{|x|^{n+l-5}} \right) \right] \\ &= \frac{-1}{(n+l-3)(n+l-5)} \Delta \left[ \partial_r \left( \frac{P_{rs}(x)}{|x|^{n+l-5}} \right) \right] \\ &=: I + II + III, \end{aligned} \quad (4-31)$$

where

$$\begin{aligned} I &:= \frac{-1}{(n+l-3)(n+l-5)} \partial_r \left[ \frac{(\Delta P_{rs})(x)}{|x|^{n+l-5}} \right] = 0, \\ II &:= \frac{-1}{(n+l-3)(n+l-5)} \partial_r \left[ 2 \langle (\nabla P_{rs})(x), \nabla [|x|^{-(n+l-5)}] \rangle \right] \\ &= \frac{2}{n+l-3} \partial_r \left[ \frac{\langle (\nabla P_{rs})(x), x \rangle}{|x|^{n+l-3}} \right] = \frac{2(l-2)}{n+l-3} \partial_r \left[ \frac{P_{rs}(x)}{|x|^{n+l-3}} \right], \\ III &:= \frac{-1}{(n+l-3)(n+l-5)} \partial_r \left[ P_{rs}(x) \Delta [|x|^{-(n+l-5)}] \right] = \frac{-l+3}{n+l-3} \partial_r \left[ \frac{P_{rs}(x)}{|x|^{n+l-3}} \right], \end{aligned} \quad (4-32)$$

by the harmonicity of  $P$ , (4-28), and straightforward algebra. This proves that (4-23) holds when  $n \geq 3$ . Going further, from (4-29) and the fact that

$$\sum_{r=1}^n (\partial_r P_{rs})(x) = \sum_{s=1}^n (\partial_s P_{rs})(x) = 0 \quad \text{and} \quad \sum_{r=1}^n P_{rr}(x) = 0 \quad (4-33)$$

(as seen from (4-26) and the harmonicity of  $P$ ), we deduce that, for each  $x \in \mathbb{R}^n \setminus \{0\}$ ,

$$\begin{aligned} \sum_{r,s=1}^n [k_{rs}(x)]_s &= \frac{1}{(n+l-3)(n+l-5)} \sum_{r,s=1}^n \partial_r \partial_s \left( \frac{P_{rs}(x)}{|x|^{n+l-5}} \right) \\ &= \frac{1}{(n+l-3)(n+l-5)} \sum_{r,s=1}^n P_{rs}(x) \partial_r \partial_s [|x|^{-(n+l-5)}] \\ &= \frac{-1}{n+l-3} \sum_{r,s=1}^n P_{rs}(x) \left\{ \frac{\delta_{rs}}{|x|^{n+l-3}} - (n+l-3) \frac{x_r x_s}{|x|^{n+l-1}} \right\} = \frac{P(x)}{|x|^{n-1+l}}. \end{aligned} \quad (4-34)$$

This establishes (4-24) for  $n \geq 3$ . Moving on, for each  $\gamma \in \mathbb{N}_0^n$ , interior estimates for the harmonic function  $P$  give

$$\|\partial^\gamma P\|_{L^\infty(S^{n-1})} \leq c_{n,\gamma} \int_{B(0,2)} |P(x)| dx = c_{n,\gamma} \int_{S^{n-1}} |P(\omega)| \left( \int_0^2 r^{n-1+l} dr \right) d\omega = c_{n,\gamma} \frac{2^l}{n+l} \|P\|_{L^1(S^{n-1})}, \quad (4-35)$$

where we have also used the fact that  $P$  is homogeneous of degree  $l$ . The estimates in (4-25) now readily follow on account of (4-29), (4-26), and (4-35).

To treat the two-dimensional case, first we observe that, if  $Q_m(x)$  is an arbitrary homogeneous polynomial of degree  $m \in \mathbb{N}_0$  in  $\mathbb{R}^n$  with  $n \geq 2$  and  $\lambda > 0$ , then

$$\frac{Q_m(x)}{|x|^{n+m-\lambda}} \quad \text{is a tempered distribution in } \mathbb{R}^n. \quad (4-36)$$

If, in addition,  $Q_m(x)$  is harmonic and  $\lambda < n$  then (see [Stein 1970, p. 73]) also

$$\mathcal{F}_{x \rightarrow \xi} \left( \frac{Q_m(x)}{|x|^{n+m-\lambda}} \right) = \gamma_{n,m,\lambda} \frac{Q_m(\xi)}{|\xi|^{m+\lambda}} \quad \text{as tempered distributions in } \mathbb{R}^n, \quad (4-37)$$

where  $\mathcal{F}_{x \rightarrow \xi}$  is an alternative notation for the Fourier transform in  $\mathbb{R}^n$  from (3-13) and

$$\gamma_{n,m,\lambda} := (-1)^{3m/2} \pi^{n/2} 2^\lambda \frac{\Gamma(m/2 + \lambda/2)}{\Gamma(m/2 + n/2 - \lambda/2)}. \quad (4-38)$$

Now pick an odd, harmonic, homogeneous polynomial  $P(x)$  of degree  $l \geq 3$  in  $\mathbb{R}^2$  and define  $P_{rs}$  for  $r, s \in \{1, \dots, n\}$  as in (4-26). Hence, once again, each  $P_{rs}$  is an odd, harmonic, homogeneous polynomial of degree  $l-2$  in  $\mathbb{R}^2$ , and (4-27) holds. Moreover, (4-37) used for  $n=2$ ,  $m=l-2$ ,  $\lambda=1$  and  $Q_m=P_{rs}$  yields

$$\frac{P_{rs}(x)}{|x|^{l-1}} = -(-1)^{3l/2} 2\pi \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \frac{P_{rs}(\xi)}{|\xi|^{l-1}} \right). \quad (4-39)$$

Now, for each  $r, s \in \{1, 2\}$  define the function  $k_{rs} : \mathbb{R}^2 \setminus \{0\} \rightarrow \mathbb{R}^2 \hookrightarrow \mathcal{C}\ell_2$  by setting

$$k_{rs}(x) := (-1)^{3l/2} 2\pi \sum_{j=1}^2 \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \xi_j \frac{P_{rs}(\xi)}{|\xi|^{l+1}} \right) e_j \quad \text{for all } x \in \mathbb{R}^2 \setminus \{0\}. \quad (4-40)$$

By (4-36) used with  $n=2$ ,  $m=l$ ,  $\lambda=1$  and  $Q_m(\xi) = \xi_r \xi_j P_{rs}(\xi)$ , it follows that  $\xi_r \xi_j P_{rs}(\xi)/|\xi|^{l+1}$  is a tempered distribution in  $\mathbb{R}^2$ . Consequently,  $k_{rs}$  in (4-40) is meaningfully defined and, from [Mitrea 2013, Proposition 4.58, p. 132], we deduce that  $k_{rs} \in \mathcal{C}^\infty(\mathbb{R}^2 \setminus \{0\})$ . Also, based on standard properties of the Fourier transform (see, e.g., [Mitrea 2013, Chapter 4]) it follows that  $k_{rs}$  is odd and homogeneous of degree  $-1$  in  $\mathbb{R}^2 \setminus \{0\}$ . In addition,

$$\begin{aligned} (D_R k_{rs})(x) &= (-1)^{3l/2} 2\pi \sum_{\ell,j=1}^2 \partial_{x_\ell} \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \xi_j \frac{P_{rs}(\xi)}{|\xi|^{l+1}} \right) e_j \odot e_\ell \\ &= \sqrt{-1} (-1)^{3l/2} 2\pi \sum_{\ell,j=1}^2 \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \xi_j \xi_\ell \frac{P_{rs}(\xi)}{|\xi|^{l+1}} \right) e_j \odot e_\ell =: I + II, \end{aligned} \quad (4-41)$$

where  $I$  and  $II$  are the pieces produced by summing up over  $j = \ell$  and  $j \neq \ell$ , respectively. Since, in the latter scenario,  $\xi_\ell \xi_j = \xi_j \xi_\ell$  while  $e_j \odot e_\ell = -e_\ell \odot e_j$ , it follows that  $II = 0$ . Given that  $e_j \odot e_j = -1$  for each  $j \in \{1, 2\}$ , we conclude that

$$\begin{aligned} (D_R k_{rs})(x) &= -\sqrt{-1}(-1)^{3l/2} 2\pi \sum_{j=1}^2 \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \xi_j^2 \frac{P_{rs}(\xi)}{|\xi|^{l+1}} \right) \\ &= -\sqrt{-1}(-1)^{3l/2} 2\pi \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \frac{P_{rs}(\xi)}{|\xi|^{l-1}} \right) \\ &= -(-1)^{3l/2} 2\pi \partial_{x_r} \left[ \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \frac{P_{rs}(\xi)}{|\xi|^{l-1}} \right) \right] = \partial_{x_r} \left[ \frac{P_{rs}(x)}{|x|^{l-1}} \right], \end{aligned} \quad (4-42)$$

where the last step uses (4-39). Hence, (4-23) holds when  $n = 2$ . Finally, from (4-29), (4-27) and (4-37) (used for  $P$ ) we deduce that for each  $x \in \mathbb{R}^2 \setminus \{0\}$  we have

$$\sum_{r,s=1}^2 [k_{rs}(x)]_s = (-1)^{3l/2} 2\pi \sum_{r,s=1}^2 \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \xi_r \xi_s \frac{P_{rs}(\xi)}{|\xi|^{l+1}} \right) = (-1)^{3l/2} 2\pi \mathcal{F}_{\xi \rightarrow x}^{-1} \left( \frac{P(\xi)}{|\xi|^{l+1}} \right) = \frac{P(x)}{|x|^{l+1}}. \quad (4-43)$$

This establishes (4-24) when  $n = 2$ .

At this stage, it remains to justify (4-25) in the case  $n = 2$ . To this end, pick  $\psi \in \mathcal{C}_0^\infty(\mathbb{R}^2)$  with  $0 \leq \psi \leq 1$ ,  $\psi = 1$  on  $B(0, 1)$  and  $\psi = 0$  on  $\mathbb{R}^2 \setminus \overline{B(0, 2)}$ . Fix  $r, s, j \in \{1, 2\}$  and abbreviate  $u(\xi) := \xi_r \xi_j P_{rs}(\xi) / |\xi|^{l+1}$  for  $\xi \in \mathbb{R}^2 \setminus \{0\}$ . Then  $u$  is locally integrable and defines a tempered distribution in  $\mathbb{R}^2$ . Hence, for each  $\alpha \in \mathbb{N}_0^2$  with  $|\alpha| = 2$  and  $\xi \in \overline{B(0, 1)}$  we may write

$$\begin{aligned} |\mathcal{F}_{x \rightarrow \xi}(\psi(x) \partial^\alpha u(x))| &= |\langle \psi \partial^\alpha u, e^{-i\langle \xi, \cdot \rangle} \rangle| = |\langle u, \partial^\alpha (\psi e^{-i\langle \xi, \cdot \rangle}) \rangle| \\ &\leq C \int_{B(0,2)} |u(x)| dx \leq C \int_{S^1} |P_{rs}(\omega)| d\omega \leq C 2^l \|P\|_{L^1(S^1)} \end{aligned} \quad (4-44)$$

and

$$\begin{aligned} |\mathcal{F}_{x \rightarrow \xi}((1 - \psi(x)) \partial^\alpha u(x))| &\leq \|(1 - \psi) \partial^\alpha u\|_{L^1(\mathbb{R}^2)} \leq \int_{\mathbb{R}^2 \setminus B(0,1)} |\partial^\alpha u(x)| dx \\ &\leq C \int_{S^1} |\partial^\alpha u(\omega)| d\omega \leq C 2^l \|P\|_{L^1(S^1)}. \end{aligned} \quad (4-45)$$

Collectively, (4-44) and (4-45) give that, for each  $\alpha \in \mathbb{N}_0^2$  with  $|\alpha| = 2$  and  $\xi \in \overline{B(0, 1)}$ ,

$$|\mathcal{F}_{x \rightarrow \xi}(\partial^\alpha u(x))| \leq |\mathcal{F}_{x \rightarrow \xi}(\psi(x) \partial^\alpha u(x))| + |\mathcal{F}_{x \rightarrow \xi}((1 - \psi(x)) \partial^\alpha u(x))| \leq C 2^l \|P\|_{L^1(S^1)}; \quad (4-46)$$

hence, for each  $\xi \in \overline{B(0, 1)}$  we have

$$|\xi|^2 |\hat{u}(\xi)| = \sum_{\ell=1}^2 |\xi_\ell^2 \hat{u}(\xi)| = \sum_{\ell=1}^2 |\mathcal{F}_{x \rightarrow \xi}(\partial_\ell^2 u(x))| \leq C 2^l \|P\|_{L^1(S^1)}. \quad (4-47)$$

In particular,  $\|k_{rs}\|_{L^\infty(S^1)} \leq C \sup_{|\xi|=1} |\hat{u}(\xi)| \leq C 2^l \|P\|_{L^1(S^1)}$ . A similar combination of ideas also yields  $\|\nabla k_{rs}\|_{L^\infty(S^1)} \leq C 2^l \|P\|_{L^1(S^1)}$ . This proves (4-25) in the case  $n = 2$  and completes the proof of the lemma.  $\square$

## 5. Cauchy–Clifford operators on Hölder spaces

Let  $\Omega \subset \mathbb{R}^n$  be a set of locally finite perimeter satisfying (2-16). As before, we shall denote by  $v = (v_1, \dots, v_n)$  the outward unit normal to  $\Omega$  and by  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  the surface measure on  $\partial\Omega$ . Then the (boundary-to-domain) *Cauchy–Clifford operator* and its principal value (or boundary-to-boundary) version associated with  $\Omega$  are, respectively, given by

$$\mathcal{C}f(x) := \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \frac{x-y}{|x-y|^n} \odot v(y) \odot f(y) d\sigma(y), \quad x \in \Omega, \quad (5-1)$$

and

$$\mathcal{C}^{\text{pv}} f(x) := \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon}} \frac{x-y}{|x-y|^n} \odot v(y) \odot f(y) d\sigma(y), \quad x \in \partial\Omega, \quad (5-2)$$

where  $f$  is a  $\mathcal{C}\ell_n$ -valued function defined on  $\partial\Omega$ . At the present time, these definitions are informal as more conditions need to be imposed on the function  $f$  and the underlying domain  $\Omega$  in order to ensure that these operators are well-defined and enjoy desirable properties in various settings of interest. We start by recording the following result, in the context of uniformly rectifiable domains.

**Proposition 5.1.** *Let  $\Omega \subset \mathbb{R}^n$  be a UR domain. Then, for every  $f \in L^p(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n$  with  $p \in [1, \infty)$ , the function  $\mathcal{C}^{\text{pv}} f$  is meaningfully defined  $\sigma$ -a.e. on  $\partial\Omega$ , and the actions of the two Cauchy–Clifford operators on  $f$  are related via the boundary behavior*

$$(\mathcal{C}f|_{\partial\Omega}^{\text{nt}})(x) := \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \mathcal{C}f(z) = \left( \frac{1}{2} I + \mathcal{C}^{\text{pv}} \right) f(x) \quad \text{for } \sigma\text{-a.e. } x \in \partial\Omega, \quad (5-3)$$

where  $I$  is the identity operator. Moreover, for each  $p \in (1, \infty)$ , there exists a finite constant  $M = M(n, p, \Omega) > 0$  such that

$$\|\mathcal{N}(\mathcal{C}f)\|_{L^p(\partial\Omega, \sigma)} \leq M \|f\|_{L^p(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n}, \quad (5-4)$$

the operator  $\mathcal{C}^{\text{pv}}$  is well-defined and bounded on  $L^p(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n$ , and the formula

$$(\mathcal{C}^{\text{pv}})^2 = \frac{1}{4} I \quad \text{on } L^p(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n \quad (5-5)$$

holds.

*Proof.* With the exception of (5-5) (which has been proved in [Hofmann et al. 2010]; see also [Mitrea et al. 2015] for very general results of this type), all claims follow from Theorems 3.1–3.2.  $\square$

The goal in this section is to prove similar results when the Lebesgue scale is replaced by Hölder spaces, in a class of domains considerably more general than the category of uniformly rectifiable domains. We begin by proving the following result:

**Lemma 5.2.** *Let  $\Omega \subseteq \mathbb{R}^n$  be a Lebesgue measurable set whose boundary is compact and upper Ahlfors regular (hence, in particular,  $\Omega$  is of locally finite perimeter by (2-22)). Denote by  $v$  the geometric measure-theoretic outward unit normal to  $\Omega$  and define  $\sigma := \mathcal{H}^{n-1}|_{\partial_*\Omega}$ . Then there exists a number*

$N = N(n, c) \in (0, \infty)$ , depending only on the dimension  $n$  and the upper Ahlfors regularity constant  $c$  of  $\partial\Omega$ , with the property that

$$\left| \int_{\partial_*\Omega \setminus B(x, r)} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) \right| \leq N \quad \text{for all } x \in \mathbb{R}^n, r \in (0, \infty). \quad (5-6)$$

*Proof.* We shall first show that, whenever  $\Omega \subseteq \mathbb{R}^n$  is a bounded set of locally finite perimeter, having fixed an arbitrary  $x \in \mathbb{R}^n$ , for  $\mathcal{L}^1$ -a.e.  $\varepsilon > 0$  we have

$$\int_{\partial_*\Omega \setminus B(x, \varepsilon)} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) = \int_{\Omega \cap \partial B(x, \varepsilon)} \frac{x-y}{|x-y|^n} \odot v(y) d\mathcal{H}^{n-1}(y) = \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, \varepsilon))}{\varepsilon^{n-1}}. \quad (5-7)$$

To justify this claim, we start by noting that the second equality (which holds for any measurable set  $\Omega \subset \mathbb{R}^n$ ) is an immediate consequence of the fact that

$$y \in \partial B(x, \varepsilon) \implies (x-y) \odot v(y) = (x-y) \odot (y-x)/\varepsilon = \varepsilon. \quad (5-8)$$

As regards the first equality in (5-7), for each  $j, k \in \{1, \dots, n\}$  consider the vector field

$$\vec{F}_{jk}(y) := \left( 0, \dots, 0, \frac{x_j - y_j}{|x-y|^n}, 0, \dots, 0 \right) \quad \text{for all } y \in \mathbb{R}^n \setminus \{x\}, \quad (5-9)$$

with the nonzero component on the  $k$ -th slot. Thus, we have  $\vec{F}_{jk} \in \mathcal{C}^1(\mathbb{R}^n \setminus \{x\}, \mathbb{R}^n)$  and, if  $E_\Delta$  stands for the standard fundamental solution for the Laplacian  $\Delta = \partial_1^2 + \dots + \partial_n^2$  in  $\mathbb{R}^n$ , given by

$$E_\Delta(x) := \begin{cases} \frac{1}{\omega_{n-1}(2-n)} \frac{1}{|x|^{n-2}} & \text{if } n \geq 3, \\ \frac{1}{2\pi} \ln|x| & \text{if } n = 2, \end{cases} \quad \text{for all } x \in \mathbb{R}^n \setminus \{0\}, \quad (5-10)$$

then

$$(\operatorname{div} \vec{F}_{jk})(y) = -\omega_{n-1} (\partial_j \partial_k E_\Delta)(x-y) \quad \text{for all } y \in \mathbb{R}^n \setminus \{x\}. \quad (5-11)$$

As a consequence, in  $\mathbb{R}^n \setminus \{x\}$  we have

$$\begin{aligned} \sum_{j,k=1}^n (\operatorname{div} \vec{F}_{jk}) e_j \odot e_k &= \sum_{1 \leq j \neq k \leq n} (\operatorname{div} \vec{F}_{jk}) e_j \odot e_k - \sum_{j=1}^n \operatorname{div} \vec{F}_{jj} \\ &= -\omega_{n-1} \sum_{1 \leq j \neq k \leq n} (\partial_j \partial_k E_\Delta)(x-\cdot) e_j \odot e_k + \omega_{n-1} (\Delta E_\Delta)(x-\cdot) \\ &= 0, \end{aligned} \quad (5-12)$$

using the fact that  $e_j \odot e_k = -e_k \odot e_j$  for  $j \neq k$  and the harmonicity of  $E_\Delta(x-\cdot)$  in  $\mathbb{R}^n \setminus \{x\}$ .

At this stage, fix an arbitrary  $\varepsilon_o \in (0, \infty)$  and alter each  $\vec{F}_{jk}$  both inside  $B(x, \varepsilon_o)$  and outside an open neighborhood of  $\bar{\Omega}$  to a vector field  $\vec{G}_{jk} \in \mathcal{C}_0^1(\mathbb{R}^n, \mathbb{R}^n)$  (this is possible given the working assumption that  $\Omega$  is bounded). Then, for  $\mathcal{L}^1$ -a.e.  $\varepsilon \in (\varepsilon_o, \infty)$ , based on the formula (2-62) used for  $\vec{F} := \vec{G}_{jk}$ ,  $D := \Omega$

and  $r := \varepsilon$  we may write

$$\begin{aligned}
0 &= \sum_{j,k=1}^n \left( \int_{\Omega \setminus B(x, \varepsilon)} \operatorname{div} \vec{F}_{jk} d\mathcal{L}^n \right) e_j \odot e_k = \sum_{j,k=1}^n \left( \int_{\Omega \setminus B(x, \varepsilon)} \operatorname{div} \vec{G}_{jk} d\mathcal{L}^n \right) e_j \odot e_k \\
&= \sum_{j,k=1}^n \left( \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \langle \vec{G}_{jk}, v \rangle d\sigma \right) e_j \odot e_k - \sum_{j,k=1}^n \left( \int_{\Omega \cap \partial B(x, \varepsilon)} \langle \vec{G}_{jk}, v \rangle d\mathcal{H}^{n-1} \right) e_j \odot e_k \\
&= \sum_{j,k=1}^n \left( \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \langle \vec{F}_{jk}, v \rangle d\sigma \right) e_j \odot e_k - \sum_{j,k=1}^n \left( \int_{\Omega \cap \partial B(x, \varepsilon)} \langle \vec{F}_{jk}, v \rangle d\mathcal{H}^{n-1} \right) e_j \odot e_k \\
&= \sum_{j,k=1}^n \left( \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \frac{(x_j - y_j) v_k(y)}{|x - y|^n} d\sigma(y) \right) e_j \odot e_k \\
&\quad - \sum_{j,k=1}^n \left( \int_{\Omega \cap \partial B(x, \varepsilon)} \frac{(x_j - y_j) v_k(y)}{|x - y|^n} d\mathcal{H}^{n-1}(y) \right) e_j \odot e_k \\
&= \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) - \int_{\Omega \cap \partial B(x, \varepsilon)} \frac{x - y}{|x - y|^n} \odot v(y) d\mathcal{H}^{n-1}(y). \tag{5-13}
\end{aligned}$$

With this in hand, the first equality in (5-7) readily follows. Thus, (5-7) is fully proved.

To proceed, assume that  $\Omega \subseteq \mathbb{R}^n$  is a bounded Lebesgue measurable set whose boundary is upper Ahlfors regular. Then (5-7) implies that, for each  $x \in \mathbb{R}^n$ ,

$$\left| \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) \right| \leq \frac{\mathcal{H}^{n-1}(\partial B(x, \varepsilon))}{\varepsilon^{n-1}} = \omega_{n-1} \tag{5-14}$$

for  $\mathcal{L}^1$ -a.e.  $\varepsilon > 0$ . Now fix  $x \in \mathbb{R}^n$  and pick an arbitrary  $r \in (0, \infty)$ . Based on (5-14) we conclude that there exists  $\varepsilon \in (\frac{1}{2}r, r)$  such that

$$\left| \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) \right| \leq \omega_{n-1}. \tag{5-15}$$

For this choice of  $\varepsilon$  we may then estimate

$$\begin{aligned}
&\left| \int_{\partial_* \Omega \setminus B(x, r)} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) \right| \\
&\leq \left| \int_{\partial_* \Omega \setminus B(x, \varepsilon)} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) \right| + \left| \int_{[B(x, r) \setminus B(x, \varepsilon)] \cap \partial_* \Omega} \frac{x - y}{|x - y|^n} \odot v(y) d\sigma(y) \right| \\
&\leq \omega_{n-1} + \int_{[B(x, r) \setminus B(x, \varepsilon)] \cap \partial \Omega} \frac{d\mathcal{H}^{n-1}(y)}{|x - y|^{n-1}} \\
&\leq \omega_{n-1} + \int_{[B(x, 2\varepsilon) \setminus B(x, \varepsilon)] \cap \partial \Omega} \frac{d\mathcal{H}^{n-1}(y)}{|x - y|^{n-1}} \\
&\leq \omega_{n-1} + \varepsilon^{-(n-1)} \mathcal{H}^{n-1}(B(x, 2\varepsilon) \cap \partial \Omega). \tag{5-16}
\end{aligned}$$

If  $\text{dist}(x, \partial\Omega) \leq 2\varepsilon$ , pick a point  $x_0 \in \partial\Omega$  such that  $\text{dist}(x, \partial\Omega) = |x - x_0|$ . In particular,  $|x - x_0| \leq 2\varepsilon$ , which forces  $B(x, 2\varepsilon) \subseteq B(x_0, 4\varepsilon)$ . As such,

$$\mathcal{H}^{n-1}(B(x, 2\varepsilon) \cap \partial\Omega) \leq \mathcal{H}^{n-1}(B(x_0, 4\varepsilon) \cap \partial\Omega) \leq c(4\varepsilon)^{n-1}, \quad (5-17)$$

with  $c \in (0, \infty)$  standing for the upper Ahlfors regularity constant of  $\partial\Omega$ . On the other hand, if  $\text{dist}(x, \partial\Omega) > 2\varepsilon$  then  $\mathcal{H}^{n-1}(B(x, 2\varepsilon) \cap \partial\Omega) = 0$ . Thus, taking  $N := \omega_{n-1} + c 4^{n-1}$ , the desired conclusion follows from (5-16) and (5-17) in the case when  $\Omega$  is as in the statement of the lemma and also bounded.

Finally, when  $\Omega$  is as in the statement of the lemma but unbounded, consider  $\Omega^c := \mathbb{R}^n \setminus \Omega$ . Then  $\Omega^c \subseteq \mathbb{R}^n$  is a bounded, Lebesgue measurable set, with the property that  $\partial(\Omega^c) = \partial\Omega$  and  $\partial_*(\Omega^c) = \partial_*\Omega$ . Moreover, the geometric measure-theoretic outward unit normal to  $\Omega^c$  is  $-v$ . Then (5-6) follows from what we have proved so far applied to  $\Omega^c$ .  $\square$

It is clear from (5-1) that the boundary-to-domain Cauchy–Clifford operator is well-defined on  $L^1(\partial\Omega, \sigma)$ . To state our next lemma, recall that  $\rho(\cdot)$  has been introduced in (2-56).

**Lemma 5.3.** *Let  $\Omega$  be a nonempty, proper, open subset of  $\mathbb{R}^n$  whose boundary is compact, upper Ahlfors regular, and satisfies (2-16). Then the Cauchy–Clifford operator (5-1) has the property that, in  $\Omega$ ,*

$$\mathcal{C}1 = \begin{cases} 1 & \text{if } \Omega \text{ is bounded,} \\ 0 & \text{if } \Omega \text{ is unbounded,} \end{cases} \quad (5-18)$$

and for each  $\alpha \in (0, 1)$  there exists a finite  $M > 0$ , depending only on  $n, \alpha, \text{diam}(\partial\Omega)$ , and the upper Ahlfors regularity constant of  $\partial\Omega$ , such that for every  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  one has

$$\sup_{x \in \Omega} |(\mathcal{C}f)(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathcal{C}f)(x)|\} \leq M \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n}. \quad (5-19)$$

*Proof.* The fact that  $\mathcal{C}1 = 1$  in  $\Omega$  when  $\Omega$  is bounded follows from (5-7), written for  $x \in \Omega$  and suitably small  $\varepsilon > 0$ . That  $(\mathcal{C}1)(x) = 0$  for each  $x \in \Omega$  when  $\Omega$  is unbounded also follows from (5-7), this time considered for the bounded set  $\Omega^c := \mathbb{R}^n \setminus \Omega$  (since in this case  $\Omega^c \cap \partial B(x, \varepsilon) = \emptyset$  if  $\varepsilon > 0$  is sufficiently small). Having proved (5-18), the inequality (5-19) follows with the help of Lemma 3.5.  $\square$

In contrast to Lemma 5.3 (see also Lemma 5.4 below), we note that there exists a bounded open set  $\Omega \subset \mathbb{R}^2 \equiv \mathbb{C}$  whose boundary is a rectifiable Jordan curve, and there exists a complex-valued function  $f \in \mathcal{C}^{1/2}(\partial\Omega)$  with the property that the boundary-to-domain Cauchy operator naturally associated with  $\Omega$  acting on  $f$  is actually an unbounded function in  $\Omega$ . See the discussion in [Dyn'kin 1979; 1980].

**Lemma 5.4.** *Let  $\Omega \subset \mathbb{R}^n$  be a uniform domain whose boundary is compact, upper Ahlfors regular, and satisfies (2-16). Then the boundary-to-domain Cauchy–Clifford operator, for each  $\alpha \in (0, 1)$ , is well-defined, linear and bounded in the context*

$$\mathcal{C} : \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n \longrightarrow \mathcal{C}^\alpha(\bar{\Omega}) \otimes \mathcal{C}\ell_n, \quad (5-20)$$

with operator norm controlled in terms of  $n, \alpha, \text{diam}(\partial\Omega)$ , and the upper Ahlfors regularity constant of  $\partial\Omega$ .

*Proof.* This is a direct consequence of Lemmas 5.3 and 2.10.  $\square$

In the class of UR domains with compact boundaries that are also uniform domains, it follows from [Lemma 5.4](#) and the jump formula [\(5-3\)](#) that the principal value Cauchy–Clifford operator  $\mathcal{C}^{\text{pv}}$  defines a bounded mapping from  $\mathscr{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  into itself for each  $\alpha \in (0, 1)$ . The goal is to prove that this boundedness result actually holds under much more relaxed background assumptions on the underlying domain. In this regard, a key aspect has to do with the action of  $\mathcal{C}^{\text{pv}}$  on constants. Note that when  $\Omega \subset \mathbb{R}^n$  is a UR domain with compact boundary, it follows from [\(5-18\)](#) and [\(5-3\)](#) that the principal value Cauchy–Clifford operator satisfies, on  $\partial\Omega$ ,

$$\mathcal{C}^{\text{pv}} 1 = \begin{cases} +\frac{1}{2} & \text{if } \Omega \text{ is bounded,} \\ -\frac{1}{2} & \text{if } \Omega \text{ is unbounded.} \end{cases} \quad (5-21)$$

The lemma below establishes a formula similar in spirit to [\(5-21\)](#) but for a much larger class of sets  $\Omega \subset \mathbb{R}^n$  than the category of UR domains with compact boundaries.

**Lemma 5.5.** *Let  $\Omega \subset \mathbb{R}^n$  be a Lebesgue measurable set whose boundary is compact, Ahlfors regular, and such that [\(2-16\)](#) is satisfied (hence, in particular,  $\Omega$  has locally finite perimeter). As in the past, consider  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$  and let  $v$  denote the outward unit normal to  $\Omega$ . Then for  $\sigma$ -a.e.  $x \in \partial\Omega$  there holds*

$$\lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) = \begin{cases} +\frac{1}{2} & \text{if } \Omega \text{ is bounded,} \\ -\frac{1}{2} & \text{if } \Omega \text{ is unbounded.} \end{cases} \quad (5-22)$$

*Proof.* Consider first the case when  $\Omega$  is bounded. Fix  $x \in \partial^*\Omega$  and pick an arbitrary  $\delta > 0$ . From [Lemma 2.5](#) we know that there exist  $\mathcal{O}_x \subset (0, 1)$  of density 1 at 0 (i.e., satisfying [\(2-33\)](#)) and some  $r_\delta > 0$  with the property that

$$\left| \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, r))}{\omega_{n-1} r^{n-1}} - \frac{1}{2} \right| < \delta \quad \text{for all } r \in \mathcal{O}_x \cap (0, r_\delta). \quad (5-23)$$

Since [\(2-33\)](#) entails

$$\lim_{\varepsilon \rightarrow 0^+} \frac{\mathcal{L}^1(\mathcal{O}_x \cap (\frac{1}{2}\varepsilon, \varepsilon))}{\varepsilon} = \lim_{\varepsilon \rightarrow 0^+} \frac{\mathcal{L}^1(\mathcal{O}_x \cap (0, \varepsilon))}{\varepsilon} - \lim_{\varepsilon \rightarrow 0^+} \frac{\mathcal{L}^1(\mathcal{O}_x \cap (0, \frac{1}{2}\varepsilon))}{\varepsilon} = 1 - \frac{1}{2} = \frac{1}{2}, \quad (5-24)$$

it follows that there exists  $\varepsilon_\delta \in (0, r_\delta)$  with the property that

$$\mathcal{L}^1(\mathcal{O}_x \cap (\frac{1}{2}\varepsilon, \varepsilon)) > 0 \quad \text{for all } \varepsilon \in (0, \varepsilon_\delta). \quad (5-25)$$

From our assumptions on  $\Omega$  and [\(5-7\)](#) we also know that there exists  $N_x \subset (0, \infty)$  with  $\mathcal{L}^1(N_x) = 0$  such that for all  $r \in (0, \infty) \setminus N_x$  we have

$$\frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y|>r}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) = \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, r))}{\omega_{n-1} r^{n-1}}. \quad (5-26)$$

Consider next  $\varepsilon \in (0, \varepsilon_\delta)$  and note that  $[\mathcal{O}_x \cap (\frac{1}{2}\varepsilon, \varepsilon)] \setminus N_x \neq \emptyset$ , thanks to (5-25). As such, it is possible to select  $r \in [\mathcal{O}_x \cap (\frac{1}{2}\varepsilon, \varepsilon)] \setminus N_x$ , for which we then write

$$\begin{aligned} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) \\ = \int_{\substack{y \in \partial\Omega \\ r \geq |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) + \int_{\substack{y \in \partial\Omega \\ |x-y|>r}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y). \end{aligned} \quad (5-27)$$

In turn, (5-27), (5-26) and (5-23) permit us to estimate

$$\begin{aligned} \left| \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) - \frac{1}{2} \right| \\ \leq \left| \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ r \geq |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) \right| + \left| \frac{\mathcal{H}^{n-1}(\Omega \cap \partial B(x, r))}{\omega_{n-1} r^{n-1}} - \frac{1}{2} \right| \\ \leq \sup_{r \in (\varepsilon/2, \varepsilon)} \left| \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ r \geq |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) \right| + \delta, \end{aligned} \quad (5-28)$$

which, in light of Proposition 2.4 (whose applicability in the current setting is ensured by (2-19)), then yields (bearing in mind (2-14))

$$\limsup_{\varepsilon \rightarrow 0^+} \left| \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon/4}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) - \frac{1}{2} \right| \leq \delta \quad \text{for } \sigma\text{-a.e. } x \in \partial\Omega. \quad (5-29)$$

Given that  $\delta > 0$  has been arbitrarily chosen, the version of (5-22) for  $\Omega$  bounded readily follows from this. Finally, the version of (5-22) corresponding to  $\Omega$  unbounded is a consequence of what we have proved so far, applied to the bounded set  $\Omega^c := \mathbb{R}^n \setminus \Omega$  (whose geometric measure-theoretic outward unit normal is  $-v$ ).  $\square$

The stage has been set to show that, under much less restrictive conditions on the underlying set  $\Omega$  (than the class of UR domains with compact boundaries that are also uniform domains), the principal value Cauchy–Clifford operator  $\mathcal{C}^{\text{PV}}$  continues to be a bounded mapping from  $\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  into itself for each  $\alpha \in (0, 1)$ . In this regard, our result can be thought of as the higher-dimensional generalization of the classical Plemelj–Privalov theorem, according to which the Cauchy integral operator on a piecewise smooth Jordan curve without cusps in the plane is bounded on Hölder spaces (see [Plemelj 1908; Privalov 1918; 1941], as well as the discussion in [Muskhelishvili 1953, §19, pp. 45–49]). In addition, we also establish a natural jump formula and prove that  $2\mathcal{C}^{\text{PV}}$  is idempotent on  $\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  for  $\alpha \in (0, 1)$ . We wish to stress that, even in the more general geometric measure-theoretic setting considered below, we retain (5-2) as the definition of the Cauchy–Clifford operator  $\mathcal{C}^{\text{PV}}$ .

**Theorem 5.6.** *Let  $\Omega \subset \mathbb{R}^n$  be a Lebesgue measurable set whose boundary is compact, upper Ahlfors regular, and satisfies (2-16). As in the past, define  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$ , and fix an arbitrary  $\alpha \in (0, 1)$ .*

Then for each  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  the limit defining  $\mathcal{C}^{\text{PV}} f(x)$  as in (5-2) exists for  $\sigma$ -a.e.  $x \in \partial\Omega$ , and the operator  $\mathcal{C}^{\text{PV}}$  induces a well-defined, linear and bounded mapping

$$\mathcal{C}^{\text{PV}} : \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n \longrightarrow \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n. \quad (5-30)$$

Furthermore, under the additional assumption that the set  $\Omega$  is open, the jump formula

$$(\mathcal{C}f)|_{\partial\Omega}^{\text{int}} = \left(\frac{1}{2}I + \mathcal{C}^{\text{PV}}\right)f \quad \text{at } \sigma\text{-a.e. point in } \partial\Omega \quad (5-31)$$

is valid for every function  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ , and one also has

$$(\mathcal{C}^{\text{PV}})^2 = \frac{1}{4}I \quad \text{on } \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n. \quad (5-32)$$

Incidentally, given an open set  $\Omega$  in the plane, the fact that its boundary is a piecewise smooth Jordan curve implies that  $\partial\Omega$  is compact and upper Ahlfors regular, while the additional property that  $\partial\Omega$  lacks cusps implies that (2-16) holds. Hence, our demands on the underlying domain  $\Omega$  are weaker versions of the hypotheses in the formulation of the classical Plemelj–Privalov theorem mentioned earlier.

*Proof of Theorem 5.6.* Fix  $\alpha \in (0, 1)$  and pick an arbitrary function  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Then, for  $\sigma$ -a.e.  $x \in \partial\Omega$ , Lemma 5.5 allows us to write

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y| > \varepsilon}} \frac{x-y}{|x-y|^n} \odot v(y) \odot f(y) d\sigma(y) \\ = \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x-y| > \varepsilon}} \frac{x-y}{|x-y|^n} \odot v(y) \odot (f(y) - f(x)) d\sigma(y) \pm \frac{1}{2}f(x) \\ = \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \frac{x-y}{|x-y|^n} \odot v(y) \odot (f(y) - f(x)) d\sigma(y) \pm \frac{1}{2}f(x), \end{aligned} \quad (5-33)$$

where the sign of  $\frac{1}{2}f(x)$  is plus if  $\Omega$  is bounded and minus if  $\Omega$  is unbounded. For the last equality, we have used Lebesgue's dominated convergence theorem. Indeed, given that  $f(y) - f(x) = O(|x-y|^\alpha)$ , an estimate based on the upper Ahlfors regularity of  $\partial\Omega$  in the spirit of (3-39) shows that the last integrand above is absolutely integrable for each fixed  $x \in \partial\Omega$ . In turn, (5-33) allows us to conclude that the limit defining  $\mathcal{C}^{\text{PV}} f(x)$  in (5-2) exists for  $\sigma$ -a.e.  $x \in \partial\Omega$ . Furthermore, by redefining  $\mathcal{C}^{\text{PV}} f$  on a set of zero  $\sigma$ -measure, there is no loss of generality in assuming that, for each  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  with  $\alpha \in (0, 1)$ ,

$$\mathcal{C}^{\text{PV}} f(x) = \pm \frac{1}{2}f(x) + \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \frac{x-y}{|x-y|^n} \odot v(y) \odot (f(y) - f(x)) d\sigma(y) \quad \text{for all } x \in \partial\Omega, \quad (5-34)$$

with the sign dictated by whether  $\Omega$  is bounded (plus) or unbounded (minus).

We now proceed to showing that, in the context of (5-30), the operator (5-34) is well-defined and bounded. To this end, fix distinct points  $x_1, x_2 \in \partial\Omega$  and, starting from (5-34), write

$$\mathcal{C}^{\text{PV}} f(x_1) - \mathcal{C}^{\text{PV}} f(x_2) = I + II, \quad (5-35)$$

where

$$I := \pm \frac{1}{2}(f(x_1) - f(x_2)) \quad (5-36)$$

and

$$II := \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \left\{ \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) \odot (f(y) - f(x_1)) - \frac{x_2 - y}{|x_2 - y|^n} \odot v(y) \odot (f(y) - f(x_2)) \right\} d\sigma(y). \quad (5-37)$$

Next, introduce  $r := |x_1 - x_2| > 0$  and estimate

$$|II| \leq II_1 + II_2 + II_3, \quad (5-38)$$

where

$$II_1 := \frac{1}{\omega_{n-1}} \left| \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) \odot (f(y) - f(x_1)) - \frac{x_2 - y}{|x_2 - y|^n} \odot v(y) \odot (f(y) - f(x_2)) d\sigma(y) \right|, \quad (5-39)$$

while

$$II_2 := \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| \leq 2r}} \left| \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) \odot (f(y) - f(x_1)) \right| d\sigma(y), \quad (5-40)$$

$$II_3 := \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| \leq 2r}} \left| \frac{x_2 - y}{|x_2 - y|^n} \odot v(y) \odot (f(y) - f(x_2)) \right| d\sigma(y). \quad (5-41)$$

Note that

$$II_2 \leq c_n [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| \leq 2r}} \frac{d\sigma(y)}{|x_1 - y|^{n-1-\alpha}}, \quad (5-42)$$

and, given that  $|x_1 - y| \leq 2r$  forces  $|x_2 - y| \leq |x_1 - x_2| + |x_1 - y| \leq 3r$ ,

$$\begin{aligned} II_3 &\leq \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_2 - y| \leq 3r}} \left| \frac{x_2 - y}{|x_2 - y|^n} \odot v(y) \odot (f(y) - f(x_2)) \right| d\sigma(y) \\ &\leq c_n [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \int_{\substack{y \in \partial\Omega \\ |x_2 - y| \leq 3r}} \frac{d\sigma(y)}{|x_2 - y|^{n-1-\alpha}}. \end{aligned} \quad (5-43)$$

On the other hand, with  $c \in (0, \infty)$  denoting the upper Ahlfors regularity constant of  $\partial\Omega$ , for every  $z \in \partial\Omega$  and  $R \in (0, \infty)$  we may estimate

$$\begin{aligned} \int_{\substack{y \in \partial\Omega \\ |z - y| < R}} \frac{d\sigma(y)}{|z - y|^{n-1-\alpha}} &= \sum_{j=1}^{\infty} \int_{[B(z, 2^{1-j}R) \setminus B(z, 2^{-j}R)] \cap \partial\Omega} \frac{d\sigma(y)}{|z - y|^{n-1-\alpha}} \\ &\leq \sum_{j=1}^{\infty} (2^{-j}R)^{-(n-1-\alpha)} \sigma(B(z, 2^{1-j}R) \cap \partial\Omega) \\ &\leq c 2^{n-1} \sum_{j=1}^{\infty} (2^{-j}R)^\alpha = MR^\alpha \end{aligned} \quad (5-44)$$

for some constant  $M = M(n, \alpha, c) \in (0, \infty)$ . In light of this, we obtain from (5-42) and (5-43) (keeping in mind the significance of the number  $r$ ) that there exists some constant  $M = M(n, \alpha, c) \in (0, \infty)$  with

the property that

$$II_2 + II_3 \leq M[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega)} |x_1 - x_2|^\alpha. \quad (5-45)$$

Going further, bound

$$II_1 \leq II_1^a + II_1^b, \quad (5-46)$$

where

$$\begin{aligned} II_1^a &:= \frac{1}{\omega_{n-1}} \left| \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) \odot (f(x_2) - f(x_1)) d\sigma(y) \right| \\ &= \frac{1}{\omega_{n-1}} \left| \left( \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) d\sigma(y) \right) \odot (f(x_2) - f(x_1)) \right| \\ &\leq \frac{2^{n/2}}{\omega_{n-1}} \left| \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{x_1 - y}{|x_1 - y|^n} \odot v(y) d\sigma(y) \right| |f(x_2) - f(x_1)| \\ &\leq M(n, c) r^\alpha [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n}, \end{aligned} \quad (5-47)$$

where the penultimate inequality uses (4-13) while the last inequality is based on (5-6), and

$$\begin{aligned} II_1^b &:= \frac{1}{\omega_{n-1}} \left| \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \left( \frac{x_1 - y}{|x_1 - y|^n} - \frac{x_2 - y}{|x_2 - y|^n} \right) \odot v(y) \odot (f(y) - f(x_2)) d\sigma(y) \right| \\ &\leq \frac{2^{n/2}}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \left| \frac{x_1 - y}{|x_1 - y|^n} - \frac{x_2 - y}{|x_2 - y|^n} \right| |f(y) - f(x_2)| d\sigma(y) \\ &\leq c_n r [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{d\sigma(y)}{|x_1 - y|^{n-\alpha}}, \end{aligned} \quad (5-48)$$

using the mean value theorem and the fact that  $f$  is Hölder of order  $\alpha$ . Here it helps to note that if  $y \in \partial\Omega$  and  $|x_1 - y| > 2r$  then  $|\xi - y| \approx |x_1 - y|$  for all  $\xi \in [x_1, x_2]$ , and also  $|y - x_2| < \frac{1}{2}|y - x_1|$ . To continue, with  $c \in (0, \infty)$  denoting the upper Ahlfors regularity constant of  $\partial\Omega$  we observe that

$$\begin{aligned} \int_{\substack{y \in \partial\Omega \\ |x_1 - y| > 2r}} \frac{d\sigma(y)}{|x_1 - y|^{n-\alpha}} &= \sum_{j=1}^{\infty} \int_{[B(x_1, 2^{j+1}r) \setminus B(x_1, 2^j r)] \cap \partial\Omega} \frac{d\sigma(y)}{|x_1 - y|^{n-\alpha}} \\ &\leq \sum_{j=1}^{\infty} (2^j r)^{-(n-\alpha)} \sigma(B(x_1, 2^{j+1}r) \cap \partial\Omega) \\ &\leq c^{n-1} \sum_{j=1}^{\infty} (2^j r)^{-1+\alpha} = Mr^{-1+\alpha} \end{aligned} \quad (5-49)$$

for some constant  $M = M(n, \alpha, c) \in (0, \infty)$ . Combining (5-46)–(5-49) we conclude that there exists a constant  $M = M(n, \alpha, c) \in (0, \infty)$  with the property that

$$II_1 \leq M[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} |x_1 - x_2|^\alpha. \quad (5-50)$$

From (5-35)–(5-36), (5-38), (5-45) and (5-50) we may then conclude that

$$|\mathcal{C}^{\text{PV}} f(x_1) - \mathcal{C}^{\text{PV}} f(x_2)| \leq M[f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} |x_1 - x_2|^\alpha \quad \text{for all } x_1, x_2 \in \partial\Omega \quad (5-51)$$

for some constant  $M = M(n, \alpha, c) \in (0, \infty)$ . The argument so far gives that the Cauchy–Clifford singular integral operator  $\mathcal{C}^{\text{PV}}$  maps  $\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  boundedly into itself. Having established this, Lemma 3.3 may be invoked—bearing in mind that (5-34) forces  $\mathcal{C}^{\text{PV}} 1 = \pm \frac{1}{2}$ —in order to finish the proof of the theorem.

Turning our attention to the last part of the statement of the theorem, make the additional assumption that the set  $\Omega$  is open. As far as the jump formula (5-31) is concerned, it has been already noted that the action of the boundary-to-domain Cauchy–Clifford operator (5-1) is meaningful on Hölder functions. Also, Proposition 2.8 ensures that it is meaningful to consider the nontangential boundary trace in the left-hand side of (5-31) given that  $\Omega \subseteq \mathbb{R}^n$  is an open set with an Ahlfors regular boundary satisfying (2-16) (hence,  $\Omega$  is an Ahlfors regular domain; see Definition 2.3). Assume now that some  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  with  $\alpha \in (0, 1)$  has been given and observe that  $\mathcal{C}f$  is continuous in  $\Omega$ . Fix  $x \in \partial^*\Omega$  and let  $\mathcal{O}_x$  be the set given by Lemma 2.5 applied with  $\Omega$  replaced by the Lebesgue measurable set  $\mathbb{R}^n \setminus \Omega$ . In particular,

$$\lim_{\substack{\varepsilon \rightarrow 0^+ \\ z \in \mathcal{O}_x}} \frac{\mathcal{H}^{n-1}(\partial B(x, \varepsilon) \setminus \Omega)}{\omega_{n-1} \varepsilon^{n-1}} = \frac{1}{2}. \quad (5-52)$$

For some  $\kappa > 0$  fixed, write

$$\begin{aligned} \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \mathcal{C}f(z) &= \lim_{\substack{\varepsilon \rightarrow 0^+ \\ z \in \mathcal{O}_x}} \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|>\varepsilon \\ y \in \partial\Omega}} \frac{z-y}{|z-y|^n} \odot v(y) \odot f(y) d\sigma(y) \\ &\quad + \lim_{\substack{\varepsilon \rightarrow 0^+ \\ z \in \mathcal{O}_x}} \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|<\varepsilon \\ y \in \partial\Omega}} \frac{z-y}{|z-y|^n} \odot v(y) \odot (f(y) - f(x)) d\sigma(y) \\ &\quad + \left( \lim_{\substack{\varepsilon \rightarrow 0^+ \\ z \in \mathcal{O}_x}} \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|<\varepsilon \\ y \in \partial\Omega}} \frac{z-y}{|z-y|^n} \odot v(y) d\sigma(y) \right) \odot f(x) \\ &=: I_1 + I_2 + I_3. \end{aligned} \quad (5-53)$$

For each fixed  $\varepsilon > 0$ , Lebesgue's dominated convergence theorem applies to the limit as  $z \rightarrow x$ ,  $z \in \Gamma_\kappa(x)$ , in  $I_1$  and yields

$$I_1 = \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|>\varepsilon \\ y \in \partial\Omega}} \frac{x-y}{|x-y|^n} \odot v(y) \odot f(y) d\sigma(y) = \mathcal{C}^{\text{PV}} f(x). \quad (5-54)$$

To handle  $I_2$ , we first observe that, for every  $x, y \in \partial\Omega$  and  $z \in \Gamma_\kappa(x)$ ,

$$|x-y| \leq |z-y| + |z-x| \leq |z-y| + (1+\kappa) \text{dist}(z, \partial\Omega) \leq |z-y| + (1+\kappa)|z-y| = (2+\kappa)|z-y|. \quad (5-55)$$

Hence, since  $f$  is Hölder of order  $\alpha$ ,

$$\left| \frac{z-y}{|z-y|^n} \odot v(y) \right| |f(y) - f(x)| \leq [f]_{\dot{\mathcal{C}}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \frac{(2+\kappa)^{n-1}}{|x-y|^{n-1-\alpha}}, \quad (5-56)$$

so that, based on the upper Ahlfors regularity of  $\partial\Omega$  and once again Lebesgue's dominated convergence theorem, we obtain that

$$I_2 = 0. \quad (5-57)$$

To treat  $I_3$  in (5-53), we first claim that, having fixed  $z \in \Omega$ , for  $\mathcal{L}^1$ -a.e  $\varepsilon > 0$  we have

$$\int_{\substack{|x-y|<\varepsilon \\ y \in \partial\Omega}} \frac{z-y}{|z-y|^n} \odot v(y) d\sigma(y) = \int_{\substack{|x-y|=\varepsilon \\ y \in \mathbb{R}^n \setminus \Omega}} \frac{z-y}{|z-y|^n} \odot v(y) d\sigma(y). \quad (5-58)$$

To justify this, pick a large  $R > 0$  and apply (2-61) to  $D := B(0, R) \setminus \Omega$  and, for each  $j, k \in \{1, \dots, n\}$ , to the vector field

$$\vec{F}_{jk}(y) := \left( 0, \dots, 0, \frac{z_j - y_j}{|z-y|^n}, 0, \dots, 0 \right) \quad \text{for all } y \in \mathbb{R}^n \setminus \{z\}, \quad (5-59)$$

with the nonzero component in the  $k$ -th slot. We can alter each  $\vec{F}_{jk}$  outside a compact neighborhood of  $\bar{D}$  to a vector field  $\vec{G}_{jk} \in \mathcal{C}_0^1(\mathbb{R}^n \setminus \{z\}, \mathbb{R}^n)$ . Then (5-58) follows by reasoning as in (5-11)–(5-13). Consequently, starting with (5-58), then using (5-8), and then (5-52), we obtain

$$\begin{aligned} \lim_{\substack{\varepsilon \rightarrow 0^+ \\ \varepsilon \in \mathcal{O}_x}} \lim_{\substack{z \rightarrow x \\ z \in \Gamma_\kappa(x)}} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|<\varepsilon \\ y \in \partial\Omega}} \frac{z-y}{|z-y|^n} \odot v(y) d\sigma(y) &= \lim_{\substack{\varepsilon \rightarrow 0^+ \\ \varepsilon \in \mathcal{O}_x}} \frac{1}{\omega_{n-1}} \int_{\substack{|x-y|=\varepsilon \\ y \in \mathbb{R}^n \setminus \Omega}} \frac{x-y}{|x-y|^n} \odot v(y) d\sigma(y) \\ &= \lim_{\substack{\varepsilon \rightarrow 0^+ \\ \varepsilon \in \mathcal{O}_x}} \frac{\mathcal{H}^{n-1}(\partial B(x, \varepsilon) \setminus \Omega)}{\omega_{n-1} \varepsilon^{n-1}} = \frac{1}{2}. \end{aligned} \quad (5-60)$$

A combination of (5-53), (5-54), (5-57) and (5-60) shows that the limit in the left-hand side of (5-53) exists and matches  $(\frac{1}{2}I + \mathcal{C}^{\text{PV}})f(x)$ . This proves that (5-31) holds for each  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  at every  $x \in \partial^*\Omega$ , hence at  $\sigma$ -a.e. point in  $\partial\Omega$ , by (2-14) and the assumption (2-16).

To finish the proof of the theorem, it remains to establish (5-32) assuming, again, that the set  $\Omega$  is open. Suppose this is the case and introduce the version of the Cauchy reproducing formula from [Mitrea et al. 2015, Section 3] to the effect that, under the current assumptions on the set  $\Omega$ ,

$$\begin{aligned} u : \Omega \rightarrow \mathcal{C}\ell_n \text{ continuous, with } D_L u = 0 \text{ in } \Omega, \mathcal{N}u \in L^1(\partial\Omega, \sigma) \text{ and } u|_{\partial\Omega}^{\text{nt}} \text{ exists } \sigma\text{-a.e. on } \partial\Omega \\ \implies u = \mathcal{C}(u|_{\partial\Omega}^{\text{nt}}) \text{ in } \Omega. \end{aligned} \quad (5-61)$$

Now, given any  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ , define  $u := \mathcal{C}f$  in  $\Omega$ . Then, by design,  $u \in \mathcal{C}^\infty(\Omega)$  and  $D_L u = 0$  in  $\Omega$ . Also, (5-19) gives that  $\sup_{x \in \Omega} |u(x)| \leq M \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n}$ , which, in turn, forces  $\mathcal{N}u$  to be in  $L^\infty(\partial\Omega, \sigma) \subset L^1(\partial\Omega, \sigma)$ , given that  $\partial\Omega$  has finite measure. Finally, the jump formula (5-3) for Hölder functions, established earlier in the proof, yields

$$(u|_{\partial\Omega}^{\text{nt}})(x) = (\frac{1}{2}I + \mathcal{C}^{\text{PV}})f(x) \quad \text{for } \sigma\text{-a.e. } x \in \partial\Omega. \quad (5-62)$$

Granted these, the premise of (5-61) holds and gives

$$u = \mathcal{C}(u|_{\partial\Omega}^{\text{nt}}) \quad \text{in } \Omega. \quad (5-63)$$

Moreover, since  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  and  $\mathcal{C}^{\text{PV}}$  is a well-defined mapping in the context of (5-30), from (5-62) we see that

$$u|_{\partial\Omega}^{\text{nt}} \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n. \quad (5-64)$$

Going to the boundary nontangentially in (5-63) and relying on (5-62) and (5-31) (bearing in mind (5-64)) then allows us to write

$$\left(\frac{1}{2}I + \mathcal{C}^{\text{PV}}\right)f = \left(\frac{1}{2}I + \mathcal{C}^{\text{PV}}\right)\left(\frac{1}{2}I + \mathcal{C}^{\text{PV}}\right)f \quad \text{at } \sigma\text{-a.e. point on } \partial\Omega, \quad (5-65)$$

from which (5-32) now readily follows.  $\square$

In the last part of this section we briefly consider harmonic layer potentials. Recall the standard fundamental solution  $E_\Delta$  for the Laplacian in  $\mathbb{R}^n$  from (5-10). Given a nonempty, open, proper subset  $\Omega$  of  $\mathbb{R}^n$ , let  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$ . Then the *harmonic single layer operator* associated with  $\Omega$  acts on a function  $f$  defined on  $\partial\Omega$  by

$$\mathcal{S}f(x) := \int_{\partial\Omega} E_\Delta(x - y) f(y) d\sigma(y), \quad x \in \Omega. \quad (5-66)$$

Assume that  $\Omega$  is a set of locally finite perimeter for which (2-16) holds and denote by  $v$  its (geometric measure-theoretic) outward unit normal. In this context, it follows from (4-17), (5-66), (5-1) and the fact that  $v \odot v = -1$  (see (4-1)) that the harmonic single layer operator and the Cauchy–Clifford operator are related via

$$D_L \mathcal{S}f = -\mathcal{C}(v \odot f) \quad \text{in } \Omega. \quad (5-67)$$

Parenthetically, we wish to note that, in the same setting, the *harmonic double layer operator* associated with  $\Omega$  is defined as

$$\mathcal{D}f(x) := \frac{1}{\omega_{n-1}} \int_{\partial\Omega} \frac{\langle v(y), y - x \rangle}{|x - y|^n} f(y) d\sigma(y), \quad x \in \Omega, \quad (5-68)$$

where  $\langle \cdot, \cdot \rangle$  is the standard inner product of vectors in  $\mathbb{R}^n$ . In particular, from (5-1), (4-10), (4-8) and (5-68), it follows that

$$f \text{ scalar-valued} \implies \mathcal{D}f = (\mathcal{C}f)_0 \text{ in } \Omega. \quad (5-69)$$

As a consequence of this and (5-20), we see that if  $\Omega \subset \mathbb{R}^n$  is a uniform domain whose boundary is compact, upper Ahlfors regular, and satisfies (2-16) then, for each  $\alpha \in (0, 1)$ , the harmonic double layer operator induces a well-defined, linear and bounded mapping

$$\mathcal{D} : \mathcal{C}^\alpha(\partial\Omega) \longrightarrow \mathcal{C}^\alpha(\bar{\Omega}). \quad (5-70)$$

Returning to the main discussion, make the convention that  $\nabla^2$  is the vector of all second-order partial derivatives in  $\mathbb{R}^n$ . Also, once again, recall (2-56).

**Lemma 5.7.** *Let  $\Omega$  be a domain of class  $\mathcal{C}^{1+\alpha}$  for some  $\alpha \in (0, 1)$  with compact boundary. Then*

$$A := \sup_{x \in \Omega} |\nabla(\mathcal{S}1)(x)| + \sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |\nabla^2(\mathcal{S}1)(x)| \} < +\infty \quad (5-71)$$

and, in fact, this quantity may be estimated in terms of  $n$ ,  $\alpha$ ,  $\text{diam}(\partial\Omega)$ ,  $\|v\|_{\mathcal{C}^\alpha(\partial\Omega)}$  and the upper Ahlfors regularity constant of  $\partial\Omega$ .

*Proof.* Via the identification (4-3) we obtain from (5-67) that

$$\nabla(\mathcal{S}1) \equiv D_L \mathcal{S}1 = -\mathcal{C}v \quad \text{in } \Omega. \quad (5-72)$$

Then, keeping in mind that  $v \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$  under the present assumption on  $\Omega$ , the claim in (5-71) readily follows by combining (5-72) with (5-19).  $\square$

## 6. The proofs of Theorems 1.1 and 1.3

We start by presenting the proof of Theorem 1.1.

*Proof of (a)  $\Rightarrow$  (e) in Theorem 1.1.* Let  $\Omega$  be a domain of class  $\mathcal{C}^{1+\alpha}$ ,  $\alpha \in (0, 1)$ , with compact boundary (hence, in particular,  $\Omega$  is a UR domain). Also, assume  $P(x)$  is an odd, homogeneous, harmonic polynomial of degree  $l \geq 1$  in  $\mathbb{R}^n$  and associate to it the singular integral operator

$$\mathbb{T}f(x) := \int_{\partial\Omega} \frac{P(x-y)}{|x-y|^{n-1+l}} f(y) d\sigma(y), \quad x \in \Omega. \quad (6-1)$$

In a first stage, the goal is to prove that there exists a constant  $C \in (1, \infty)$ , depending only on  $n$ ,  $\alpha$ ,  $\text{diam}(\partial\Omega)$ ,  $\|v\|_{\mathcal{C}^\alpha(\partial\Omega)}$  and the upper Ahlfors regularity constant of  $\partial\Omega$  (something we shall indicate by writing  $C = C(n, \alpha, \Omega)$ ), such that for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$  we have

$$\sup_{x \in \Omega} |\mathbb{T}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathbb{T}f)(x)|\} \leq C^l 2^{l^2} \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)}. \quad (6-2)$$

We shall do so by induction on  $l \in 2\mathbb{N} - 1$ , the degree of the homogeneous harmonic polynomial  $P$ . When  $l = 1$  we have  $P(x) = \sum_{j=1}^n a_j x_j$  for each  $x = (x_1, \dots, x_n) \in \mathbb{R}^n$ , where the  $a_j$  are some fixed constants. Hence, in this case,

$$\max_{1 \leq j \leq n} |a_j| \leq \|P\|_{L^\infty(S^{n-1})} \leq c_n \|P\|_{L^1(S^{n-1})}, \quad (6-3)$$

where the last inequality is a consequence of (4-35) (with  $c_n \in (0, \infty)$  denoting a dimensional constant), and

$$\mathbb{T} = \omega_{n-1} \sum_{j=1}^n a_j \partial_j \mathcal{S}. \quad (6-4)$$

Then (6-2) follows from (6-3), (6-4) and Lemmas 5.7 and 3.5. To proceed, fix some odd integer  $l \geq 3$  and assume that there exists  $C = C(n, \alpha, \Omega) \in (1, \infty)$  such that:

The estimate in (6-2) holds whenever  $\mathbb{T}$  is associated as in (6-1) with an odd harmonic homogeneous polynomial of degree at most  $l - 2$  in  $\mathbb{R}^n$ .  $\quad (6-5)$

Also, pick an arbitrary odd harmonic homogeneous polynomial  $P(x)$  of degree  $l$  in  $\mathbb{R}^n$  and let  $\mathbb{T}$  be as in (6-1) for this choice of  $P$ . Consider the family  $P_{rs}(x)$ ,  $1 \leq r, s \leq n$ , of odd harmonic homogeneous

polynomials of degree  $l - 2$ , as well as the family of odd  $\mathcal{C}^\infty$  functions  $k_{rs} : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n \hookrightarrow \mathcal{C}\ell_n$ , associated with  $P$  as in Lemma 4.2. For each  $1 \leq i, j \leq n$  set

$$k^{rs}(x) := \frac{P_{rs}(x)}{|x|^{n+l-3}} \quad \text{for } x \in \mathbb{R}^n \setminus \{0\}, \quad (6-6)$$

and introduce the integral operator, acting on Clifford algebra-valued functions  $f = \sum_I f_I e_I$  with Hölder scalar components  $f_I$  defined on  $\partial\Omega$ ,

$$\mathbb{T}^{rs} f(x) := \int_{\partial\Omega} k^{rs}(x - y) f(y) d\sigma(y) = \sum_I \left( \int_{\partial\Omega} k^{rs}(x - y) f_I(y) d\sigma(y) \right) e_I, \quad x \in \Omega. \quad (6-7)$$

Fix such an arbitrary  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Then, from the properties of the  $P_{rs}$  and the induction hypothesis (6-5) (used component-wise, keeping in mind that the sum in (6-7) is performed over a set of cardinality  $2^n$ ), we conclude that for each  $1 \leq r, s \leq n$  we have

$$\begin{aligned} \sup_{x \in \Omega} |(\mathbb{T}^{rs} f)(x)| + \sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |\nabla(\mathbb{T}^{rs} f)(x)| \} &\leq 2^{n/2} C^{l-2} 2^{(l-2)^2} \|P_{rs}\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \\ &\leq c_n C^{l-2} 2^{(l-2)^2} 2^l \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n}. \end{aligned} \quad (6-8)$$

Moving on, for every  $r, s \in \{1, \dots, n\}$  and  $f : \partial\Omega \rightarrow \mathcal{C}\ell_n$  with Hölder scalar components, we set

$$\mathbb{T}_{rs} f(x) := \int_{\partial\Omega} k_{rs}(x - y) \odot f(y) d\sigma(y), \quad x \in \Omega. \quad (6-9)$$

Then, thanks to (4-23), whenever the function  $f$  is actually scalar-valued (i.e.,  $f : \partial\Omega \rightarrow \mathbb{R} \hookrightarrow \mathcal{C}\ell_n$ ) the original operator  $\mathbb{T}$  from (6-1) may be recovered from the above  $\mathbb{T}_{rs}$  by means of the identity

$$\mathbb{T}f(x) = \sum_{r,s=1}^n [\mathbb{T}_{rs} f(x)]_s \quad \text{for all } x \in \Omega. \quad (6-10)$$

To proceed, consider first the case when  $\Omega$  is unbounded. In this scenario, fix some  $x \in \Omega$  and select

$$R_1 \in (0, \text{dist}(x, \partial\Omega)) \quad \text{and} \quad R_2 > \text{dist}(x, \partial\Omega) + \text{diam}(\partial\Omega). \quad (6-11)$$

Set  $\Omega_{R_1, R_2} := (B(x, R_2) \setminus \overline{B(x, R_1)}) \cap \Omega$ , which is a bounded  $\mathcal{C}^{1+\alpha}$  domain in  $\mathbb{R}^n$  with the property that

$$\partial\Omega_{R_1, R_2} = \partial B(x, R_2) \cup \partial B(x, R_1) \cup \partial\Omega. \quad (6-12)$$

We continue to denote by  $\nu$  and  $\sigma$  the outward unit normal and surface measure for  $\Omega_{R_1, R_2}$ . As a consequence of (4-18) (used with  $\Omega_{R_1, R_2}$  in place of  $\Omega$ ,  $u = k_{rs}(x - \cdot) \in \mathcal{C}^\infty(\bar{\Omega}_{R_1, R_2})$  and  $v \equiv 1$ )

and (4-24), we then obtain that, for each  $r, s \in \{1, \dots, n\}$ ,

$$\begin{aligned} \int_{\partial\Omega_{R_1, R_2}} k_{rs}(x-y) \odot v(y) d\sigma(y) &= - \int_{\Omega_{R_1, R_2}} (D_R k_{rs})(x-y) dy \\ &= \frac{l-1}{n+l-3} \int_{\Omega_{R_1, R_2}} \frac{\partial}{\partial y_r} \left( \frac{P_{rs}(x-y)}{|x-y|^{n+l-3}} \right) dy \\ &= \frac{l-1}{n+l-3} \int_{\partial\Omega_{R_1, R_2}} k^{rs}(x-y) v_r(y) d\sigma(y). \end{aligned} \quad (6-13)$$

Hence,

$$\begin{aligned} (\mathbb{T}_{rs} v)(x) &= \int_{\partial\Omega} k_{rs}(x-y) \odot v(y) d\sigma(y) \\ &= \int_{\partial\Omega_{R_1, R_2}} k_{rs}(x-y) \odot v(y) d\sigma(y) - \int_{\partial B(x, R_1)} k_{rs}(x-y) \odot \frac{x-y}{|x-y|} d\sigma(y) \\ &\quad + \int_{\partial B(x, R_2)} k_{rs}(x-y) \odot \frac{x-y}{|x-y|} d\sigma(y) \\ &= \frac{l-1}{n+l-3} \int_{\partial\Omega_{R_1, R_2}} k^{rs}(x-y) v_r(y) d\sigma(y) - \int_{S^{n-1}} k_{rs}(\omega) \odot \omega d\omega + \int_{S^{n-1}} k_{rs}(\omega) \odot \omega d\omega \\ &= \frac{l-1}{n+l-3} \int_{\partial\Omega} k^{rs}(x-y) v_r(y) d\sigma(y) - \frac{l-1}{n+l-3} \int_{\partial B(x, R_1)} k^{rs}(x-y) \frac{x_r - y_r}{|x-y|} d\sigma(y) \\ &\quad + \frac{l-1}{n+l-3} \int_{\partial B(x, R_2)} k^{rs}(x-y) \frac{x_r - y_r}{|x-y|} d\sigma(y) \\ &= \frac{l-1}{n+l-3} (\mathbb{T}^{rs} v_r)(x) - \frac{l-1}{n+l-3} \int_{S^{n-1}} k^{rs}(\omega) \omega_r d\omega + \frac{l-1}{n+l-3} \int_{S^{n-1}} k^{rs}(\omega) \omega_r d\omega \\ &= \frac{l-1}{n+l-3} (\mathbb{T}^{rs} v_r)(x). \end{aligned} \quad (6-14)$$

From (6-14) and (6-8) used with  $f = v_r \in \mathcal{C}^\alpha(\partial\Omega)$ , for  $1 \leq r, s \leq n$  we obtain

$$\begin{aligned} \sup_{x \in \Omega} |(\mathbb{T}_{rs} v)(x)| + \sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |\nabla(\mathbb{T}_{rs} v)(x)| \} &\leq \sup_{x \in \Omega} |(\mathbb{T}^{rs} v_r)(x)| + \sup_{x \in \Omega} \{ \rho(x)^{1-\alpha} |\nabla(\mathbb{T}^{rs} v_r)(x)| \} \\ &\leq c_n C^{l-2} 2^{(l-2)^2} 2^l \|P\|_{L^1(S^{n-1})} \|v\|_{\mathcal{C}^\alpha(\partial\Omega)} \end{aligned} \quad (6-15)$$

in the case when  $\Omega$  is an unbounded domain.

When  $\Omega$  is a bounded domain, we once again consider  $\Omega_{R_1, R_2}$  as before and carry out a computation similar in spirit to what we have just done above. This time, however,  $\Omega_{R_1, R_2} = \Omega \setminus \overline{B(x, R_1)}$  and in place of (6-12) we have  $\partial\Omega_{R_1, R_2} = \partial B(x, R_1) \cup \partial\Omega$ . Consequently, in place of (6-14) we now obtain

$$(\mathbb{T}_{rs} v)(x) = \frac{l-1}{n+l-3} (\mathbb{T}^{rs} v_r)(x) - \frac{l-1}{n+l-3} \int_{S^{n-1}} k^{rs}(\omega) \omega_r d\omega - \int_{S^{n-1}} k_{rs}(\omega) \odot \omega d\omega. \quad (6-16)$$

To estimate the integrals on the unit sphere we note that, in view of (6-6), (4-26), (4-35) and (4-25), we have

$$\|k^{rs}\|_{L^\infty(S^{n-1})} + \|k_{rs}\|_{L^\infty(S^{n-1})} \leq c_n 2^l \|P\|_{L^1(S^{n-1})}. \quad (6-17)$$

Upon observing that  $\|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \geq 1$ , from (6-16) and (6-17) we deduce that an estimate similar to (6-15) also holds in the case when  $\Omega$  is a bounded domain (this time replacing the constant  $c_n$  appearing in (6-15) by  $2c_n$ , which is inconsequential for our purposes). In summary, (6-16) may be assumed to hold whether  $\Omega$  is bounded or not.

Going further, let  $\tilde{\mathbb{T}}_{rs}$  be the version of  $\mathbb{T}_{rs}$  from (6-9) in which  $\nu(y)$  has been absorbed into the integral kernel. That is, for  $f : \partial\Omega \rightarrow \mathcal{C}\ell_n$  with Hölder scalar components set

$$\tilde{\mathbb{T}}_{rs}f(x) := \int_{\partial\Omega} (k_{rs}(x-y) \odot \nu(y)) \odot f(y) d\sigma(y), \quad x \in \Omega, \quad (6-18)$$

for each  $r, s \in \{1, \dots, n\}$ . Since  $\tilde{\mathbb{T}}_{rs}1 = \mathbb{T}_{rs}\nu$ , from (6-15) we conclude that, for each  $r, s \in \{1, \dots, n\}$ ,

$$\sup_{x \in \Omega} |(\tilde{\mathbb{T}}_{rs}1)(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\tilde{\mathbb{T}}_{rs}1)(x)|\} \leq c_n C^{l-2} 2^{(l-2)^2} 2^l \|P\|_{L^1(S^{n-1})} \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)}. \quad (6-19)$$

Given that the integral kernel of  $\tilde{\mathbb{T}}_{rs}$  satisfies

$$|k_{rs}(x-y) \odot \nu(y)| \leq \frac{\|k_{rs}\|_{L^\infty(S^{n-1})}}{|x-y|^{n-1}} \leq \frac{c_n 2^l \|P\|_{L^1(S^{n-1})}}{|x-y|^{n-1}}, \quad (6-20)$$

$$|\nabla_x [k_{rs}(x-y) \odot \nu(y)]| \leq \frac{\|\nabla k_{rs}\|_{L^\infty(S^{n-1})}}{|x-y|^n} \leq \frac{c_n 2^l \|P\|_{L^1(S^{n-1})}}{|x-y|^n}, \quad (6-21)$$

we may invoke Lemma 3.5 with

$$A := c_n C^{l-2} 2^{(l-2)^2} 2^l \|P\|_{L^1(S^{n-1})} \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad \text{and} \quad B := c_n 2^l \|P\|_{L^1(S^{n-1})} \quad (6-22)$$

in order to conclude that if  $1 \leq r, s \leq n$  then

$$\begin{aligned} \sup_{x \in \Omega} |\tilde{\mathbb{T}}_{rs}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\tilde{\mathbb{T}}_{rs}f)(x)|\} \\ \leq C_{n,\alpha,\Omega} \{C^{l-2} 2^{(l-2)^2} 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} + 2^l\} \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \end{aligned} \quad (6-23)$$

for every  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Writing (6-23) for  $f$  replaced by  $\nu \odot f$  then yields—in light of (6-18), (6-9) and (4-21) (bearing in mind that  $\nu \odot \nu = -1$ )—that for  $1 \leq r, s \leq n$  we have

$$\begin{aligned} \sup_{x \in \Omega} |\mathbb{T}_{rs}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathbb{T}_{rs}f)(x)|\} \\ \leq C_{n,\alpha,\Omega} \{C^{l-2} 2^{(l-2)^2} 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} + 2^l\} \times 2 \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n} \end{aligned} \quad (6-24)$$

for every  $f \in \mathcal{C}^\alpha(\partial\Omega) \otimes \mathcal{C}\ell_n$ . In turn, from this and (6-10) we finally conclude that

$$\begin{aligned} \sup_{x \in \Omega} |\mathbb{T}f(x)| + \sup_{x \in \Omega} \{\rho(x)^{1-\alpha} |\nabla(\mathbb{T}f)(x)|\} \\ \leq n^2 C_{n,\alpha,\Omega} \{C^{l-2} 2^{(l-2)^2} 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} + 2^l\} \times 2 \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \end{aligned} \quad (6-25)$$

for every  $f \in \mathcal{C}^\alpha(\partial\Omega)$ . Having established (6-25), we now see that (6-2) holds provided the constant  $C \in (1, \infty)$  is chosen in such a way that

$$n^2 C_{n,\alpha,\Omega} \{C^{l-2} 2^{(l-2)^2} 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} + 2^l\} 2 \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \leq C' 2^l \quad (6-26)$$

for each odd number  $l \in \mathbb{N}$ ,  $l \geq 3$ . Since  $2^{(l-2)^2} 2^l \leq 2 \cdot 2^{l^2}$  and  $2^l \leq C^{l-2} 2^{l^2}$ , it follows that the left-hand side of (6-26) is at most  $C(n, \alpha, \Omega) C^{l-2} 2^{l^2}$ . This, in turn, is bounded by the right-hand side of (6-26) provided  $C \geq \max\{1, \sqrt{C(n, \alpha, \Omega)}\}$ . In summary, choosing such a  $C$  ensures that (6-2) holds.

Next, we aim to show that (6-2) continues to be valid if the harmonicity condition on  $P$  is dropped, that is, when

$$P(x) \text{ is a homogeneous polynomial in } \mathbb{R}^n \text{ of degree } l \in 2\mathbb{N} - 1. \quad (6-27)$$

Indeed, a standard fact about arbitrary homogeneous polynomials  $P(x)$  is the decomposition (see [Stein 1970, §3.1.2, p. 69])

$$P(x) = P_1(x) + |x|^2 Q_1(x) \quad \text{for every } x \in \mathbb{R}^n, \quad (6-28)$$

where  $P_1$  and  $Q_1$  are homogeneous polynomials and  $P_1$  is harmonic. Hence, if  $P(x)$  is a homogeneous polynomial of degree  $l = 2N+1$  in  $\mathbb{R}^n$  for some  $N \in \mathbb{N}_0$ , not necessarily harmonic, then by iterating (6-28) we obtain

$$P(x) = \sum_{j=1}^{N+1} |x|^{2(j-1)} P_j(x) \quad \text{for every } x \in \mathbb{R}^n, \quad (6-29)$$

where each  $P_j$  is a harmonic homogeneous polynomial of degree  $l - 2(j-1)$ . Since the restrictions to the unit sphere of any two homogeneous harmonic polynomials of different degrees are orthogonal in  $L^2(S^{n-1})$  (see [Stein 1970, §3.1.1, p. 69]), it follows from (6-29) that

$$\|P\|_{L^2(S^{n-1})}^2 = \sum_{j=1}^{N+1} \|P_j\|_{L^2(S^{n-1})}^2. \quad (6-30)$$

In particular, for each  $j$ , Hölder's inequality and (6-30) permit us to estimate

$$\|P_j\|_{L^1(S^{n-1})} \leq c_n \|P_j\|_{L^2(S^{n-1})} \leq c_n \|P\|_{L^2(S^{n-1})}. \quad (6-31)$$

Combining (6-1) and (6-29), for any  $x \in \Omega$  and  $f \in \mathcal{C}^\alpha(\partial\Omega)$  we obtain

$$\mathbb{T}f(x) = \sum_{j=1}^{N+1} \int_{\partial\Omega} \frac{P_j(x-y)}{|x-y|^{n-1+(l-2(j-1))}} f(y) d\sigma(y), \quad (6-32)$$

and each integral operator appearing in the sum above is constructed according to the same blueprint as the original  $\mathbb{T}$  in (6-1), including the property that the intervening homogeneous polynomial is harmonic. As such, repeated applications of (6-2) yield

$$\sup_{x \in \Omega} |\mathbb{T}f(x)| + \sup_{x \in \Omega} \left\{ \rho(x)^{1-\alpha} |\nabla(\mathbb{T}f)(x)| \right\} \leq c_n l C^l 2^{l^2} \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad (6-33)$$

for each  $f \in \mathcal{C}^\alpha(\partial\Omega)$ . Since if  $C$  is bigger than a suitable dimensional constant, we have  $c_n l \leq C^l$  for all  $l$ , by eventually replacing  $C$  by  $C^2$  in (6-33). Ultimately, with the help of Lemma 2.10 (while keeping (2-55) in mind), we deduce that (1-19) holds for  $\mathbb{T}_+$  in  $\Omega_+$ . That  $\mathbb{T}_-$  also satisfies similar properties follows in a similar manner, working in  $\Omega_-$  (in place of  $\Omega_+$ ), which is also a domain of class  $\mathcal{C}^{1+\alpha}$  with compact boundary.  $\square$

*Proof of (e)  $\Rightarrow$  (d) in Theorem 1.1.* This is obvious, since the operators  $\mathcal{R}_j^\pm$  from (1-17) are particular cases of those considered in (1-18).  $\square$

*Proof of (d)  $\Rightarrow$  (a) in Theorem 1.1.* Since we are currently assuming that  $\Omega$  is a UR domain, Theorem 3.2 applies in  $\Omega_\pm$  and yields (bearing (2-49) in mind) the jump formulas

$$(\mathcal{R}_j^\pm f|_{\partial\Omega_\pm}^{\text{nt}})(x) = \mp \frac{1}{2} v_j(x) f(x) + \lim_{\varepsilon \rightarrow 0^+} \int_{\partial\Omega \setminus B(x, \varepsilon)} (\partial_j E_\Delta)(x - y) f(y) d\sigma(y) \quad (6-34)$$

for each  $f \in L^p(\partial\Omega, \sigma)$  with  $p \in [1, \infty)$ , each  $j \in \{1, \dots, n\}$ , and  $\sigma$ -a.e.  $x \in \partial\Omega$ . Hence, by (6-34) and (1-16), we have

$$v_j = \mathcal{R}_j^- 1|_{\partial\Omega_-} - \mathcal{R}_j^+ 1|_{\partial\Omega_+} \in \mathcal{C}^\alpha(\partial\Omega) \quad \text{for all } j \in \{1, \dots, n\}. \quad (6-35)$$

Given the present background assumptions on  $\Omega$ , Theorem 2.2 then gives that  $\Omega$  is a  $\mathcal{C}^{1+\alpha}$  domain.  $\square$

*Proof of (a)  $\Rightarrow$  (c) in Theorem 1.1.* Assume that  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$ ,  $\alpha \in (0, 1)$ , with compact boundary. Here, the task is to prove that the principal value singular integral operator  $T$ , originally defined in (1-15), is a well-defined, linear and bounded mapping from  $\mathcal{C}^\alpha(\partial\Omega)$  into itself. In the process, we shall also show that (1-20) holds. Since (a)  $\Rightarrow$  (e) has already been established, we know that the singular integral operator (6-1) maps  $\mathcal{C}^\alpha(\partial\Omega)$  boundedly into  $\mathcal{C}^\alpha(\bar{\Omega})$  with

$$\|\mathbb{T}f\|_{\mathcal{C}^\alpha(\bar{\Omega})} \leq C^l 2^l \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad \text{for all } f \in \mathcal{C}^\alpha(\partial\Omega). \quad (6-36)$$

For starters, let us operate under the additional assumption that the homogeneous polynomial  $P$  is harmonic, and abbreviate

$$k(x) := \frac{P(x)}{|x|^{n-1+l}} \quad \text{for all } x \in \mathbb{R}^n \setminus \{0\}. \quad (6-37)$$

In this scenario, (4-37) gives that

$$\hat{k}(\xi) = \mathcal{F}_{x \rightarrow \xi} \left( \frac{P(x)}{|x|^{n+l-1}} \right) = \gamma_{n,l,1} \frac{P(\xi)}{|\xi|^{l+1}} \quad \text{for all } \xi \in \mathbb{R}^n \setminus \{0\}. \quad (6-38)$$

Moreover, a direct computation, using Stirling's approximation formula

$$\sqrt{2\pi} m^{m+1/2} e^{-m} \leq m! \leq em^{m+1/2} e^{-m} \quad \text{for all } m \in \mathbb{N}, \quad (6-39)$$

shows that

$$\gamma_{n,l,1} = \begin{cases} O(l^{-(n-2)/2}) & \text{if } n \text{ is even,} \\ O(l^{-(n-4)/2}) & \text{if } n \text{ is odd,} \end{cases} \quad \text{as } l \rightarrow \infty. \quad (6-40)$$

We continue by observing that, thanks to (4-35),

$$\sup_{x \in \partial\Omega} |P(v(x))| \leq \|P\|_{L^\infty(S^{n-1})} \leq c_n 2^l l^{-1} \|P\|_{L^1(S^{n-1})}. \quad (6-41)$$

Next we note that  $|v(x) - v(y)| \geq \frac{1}{2}$  forces  $|x - y|^\alpha \geq 1/(2\|v\|_{\mathcal{C}^\alpha(\partial\Omega)})$ , which further implies

$$\frac{|P(v(x)) - P(v(y))|}{|x - y|^\alpha} \leq 4\|v\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^\infty(S^{n-1})} \leq c_n 2^l l^{-1} \|v\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})} \quad (6-42)$$

by virtue of (4-35), while, if  $|\nu(x) - \nu(y)| \leq \frac{1}{2}$ , the mean value theorem and (4-35) permit us to once again estimate

$$\begin{aligned} \frac{|P(\nu(x)) - P(\nu(y))|}{|x - y|^\alpha} &\leq \left( \sup_{z \in [\nu(x), \nu(y)]} |(\nabla P)(z)| \right) \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \leq \|\nabla P\|_{L^\infty(S^{n-1})} \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq c_n 2^l l^{-1} \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})}. \end{aligned} \quad (6-43)$$

By combining (6-38) and (6-40)–(6-43) we therefore arrive at the conclusion that the mapping  $\partial\Omega \rightarrow \mathbb{C}$ ,  $x \mapsto \hat{k}(\nu(x))$ , belongs to  $\mathcal{C}^\alpha(\partial\Omega)$  and

$$\text{the mapping } \partial\Omega \ni x \mapsto \hat{k}(\nu(x)) \text{ belongs to } \mathcal{C}^\alpha(\partial\Omega) \text{ and } \|\hat{k}(\nu(\cdot))\|_{\mathcal{C}^\alpha(\partial\Omega)} \leq c_n 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})}. \quad (6-44)$$

Next, the assumptions on  $\Omega$  imply (see the discussion in Section 2) that this is both a UR domain and a uniform domain. As such, Theorem 3.2 applies. Since  $\mathbb{T}$  from (6-1) corresponds to the operator  $T$  defined in (3-9) with  $k$  as in (6-37), for each  $f \in \mathcal{C}^\alpha(\partial\Omega)$  we obtain from (3-12), (6-44), and (6-36) that

$$\begin{aligned} \|Tf\|_{\mathcal{C}^\alpha(\partial\Omega)} &\leq \left\| \frac{1}{2i} \hat{k}(\nu(\cdot)) f + Tf \right\|_{\mathcal{C}^\alpha(\partial\Omega)} + \left\| \frac{1}{2i} \hat{k}(\nu(\cdot)) f \right\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq \|\mathbb{T}f\|_{\partial\Omega}^{\text{nt}} + 2^{-1} \|\hat{k}(\nu(\cdot))\|_{\mathcal{C}^\alpha(\partial\Omega)} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &= \|\mathbb{T}f\|_{\partial\Omega} + c_n 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^1(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq \|\mathbb{T}f\|_{\mathcal{C}^\alpha(\bar{\Omega})} + c_n 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)} \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq \{C^l 2^{l^2} + c_n 2^l \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)}\} \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq (C^2)^l 2^{l^2} \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)}, \end{aligned} \quad (6-45)$$

assuming, without loss of generality, that  $C \geq 2 + c_n \|\nu\|_{\mathcal{C}^\alpha(\partial\Omega)}$  to begin with. Note that the estimate just derived has the format demanded in (1-20).

To treat the general case, when  $P$  is merely as in (6-27), consider the decomposition (6-29) and, for each  $f \in \mathcal{C}^\alpha(\partial\Omega)$ , write

$$Tf(x) = \sum_{j=1}^{N+1} \lim_{\varepsilon \rightarrow 0^+} \int_{\substack{y \in \partial\Omega \\ |x-y|>\varepsilon}} \frac{P_j(x-y)}{|x-y|^{n-1+(l-2(j-1))}} f(y) d\sigma(y), \quad x \in \partial\Omega. \quad (6-46)$$

Since every integral operator appearing in the right-hand side of (6-46) is of the same type as the original  $T$  in (1-15), with the additional property that the intervening homogeneous polynomial is harmonic, repeated applications of (6-45) give

$$\|Tf\|_{\mathcal{C}^\alpha(\partial\Omega)} \leq l(C^2)^l 2^{l^2} \|P\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \quad \text{for all } f \in \mathcal{C}^\alpha(\partial\Omega). \quad (6-47)$$

Using  $l \leq (C^2)^l$  for all  $l$  if  $C$  is sufficiently large and relabelling  $C^4$  simply as  $C$ , the estimate (1-20) finally follows.  $\square$

*Proof of (c)  $\Rightarrow$  (b) in Theorem 1.1.* Observe that the principal value Riesz transforms  $R_j^{\text{PV}}$  from (1-1) with  $\Sigma := \partial\Omega$  are special cases of the principal value singular integral operators defined in (1-15) (corresponding

to  $P$  as in (1-21)). Hence, on the one hand,  $R_j^{\text{PV}} 1 \in \mathcal{C}^\alpha(\partial\Omega)$ . On the other hand, since  $\Omega$  is presently assumed to be a UR domain, from (1-13) it follows that each of the distributional Riesz transforms  $R_j$  from (1-4)–(1-5) with  $\Sigma := \partial\Omega$  agrees with  $R_j^{\text{PV}}$  on  $\mathcal{C}^\alpha(\partial\Omega)$ . Combining these, we conclude that (1-14) holds.  $\square$

*Proof of (b)  $\Rightarrow$  (a) in Theorem 1.1.* Granted the background hypotheses on  $\Omega$ , the assumption made in (1-14) allows us to invoke the  $T(1)$  theorem (for operators associated with odd kernels, on spaces of homogeneous type). Thanks to this, (2-24) and the Calderón–Zygmund machinery mentioned earlier, we conclude that each of the distributional Riesz transforms  $R_j$  from (1-4)–(1-5) with  $\Sigma := \partial\Omega$  extends to a bounded linear operator on  $L^2(\partial\Omega)$ , in the form of the principal value Riesz transform  $R_j^{\text{PV}}$  from (1-1) with  $\Sigma := \partial\Omega$ . In particular, we now have

$$R_j 1 = R_j^{\text{PV}} 1 \quad \text{in } L^2(\partial\Omega). \quad (6-48)$$

Next observe that, since  $v \odot v = -1$  at  $\sigma$ -a.e. point on  $\partial\Omega$  and  $x - y = \sum_{j=1}^n (x_j - y_j) e_j$  for every  $x, y \in \mathbb{R}^n$ , from (5-2), (1-1) and (6-48) we obtain

$$\mathcal{C}^{\text{PV}} v = - \sum_{j=1}^n (R_j^{\text{PV}} 1) e_j = \sum_{j=1}^n (R_j 1) e_j \quad \text{at } \sigma\text{-a.e. point on } \partial\Omega, \quad (6-49)$$

which, on account of (5-5), further yields

$$\frac{1}{4} v = \mathcal{C}^{\text{PV}} (\mathcal{C}^{\text{PV}} v) = -\mathcal{C}^{\text{PV}} \left( \sum_{j=1}^n (R_j 1) e_j \right) \quad \text{at } \sigma\text{-a.e. point on } \partial\Omega. \quad (6-50)$$

With this in hand, it readily follows from Theorem 5.6 that if condition (1-14) holds then  $v \in \mathcal{C}^\alpha(\partial\Omega)$ . Having established this, Theorem 2.2 applies and gives that  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$ .  $\square$

This concludes the proof of Theorem 1.1, and we now turn to the proof of Theorem 1.3.

*Proof of Theorem 1.3.* This is a direct consequence of Proposition 2.12 and Corollary 1.2 upon observing that  $\mathcal{C}^{\text{PV}} = i R_1^{\text{PV}} + R_2^{\text{PV}}$ , where  $R_j^{\text{PV}}$ ,  $j = 1, 2$ , are the two principal value Riesz transforms in the plane.  $\square$

We finally present the proof of Theorem 1.6.

*Proof of Theorem 1.6.* Let

$$k|_{S^{n-1}} = \sum_{l=0}^{\infty} Y_l \quad (6-51)$$

be the decomposition of  $k|_{S^{n-1}} \in L^2(S^{n-1})$  in surface spherical harmonics. That is,  $\{Y_l\}_{l \in \mathbb{N}_0}$  are mutually orthogonal functions in  $L^2(S^{n-1})$  with the property that for each  $l \in \mathbb{N}_0$  the function

$$P_l(x) := \begin{cases} |x|^l Y_l(x/|x|) & \text{if } x \in \mathbb{R}^n \setminus \{0\}, \\ 0 & \text{if } x = 0, \end{cases} \quad (6-52)$$

is a homogeneous harmonic polynomial of degree  $l$  in  $\mathbb{R}^n$ . In particular,

$$\Delta_{S^{n-1}} Y_l = -l(l+n-2) Y_l \quad \text{on } S^{n-1} \text{ for all } l \in \mathbb{N}_0. \quad (6-53)$$

See, for example, [Stein 1970, pp. 68–70] for a discussion. Then, for each  $l \in \mathbb{N}_0$ , we may write

$$\begin{aligned} [-l(l+n-2)]^{m_l} \|Y_l\|_{L^2(S^{n-1})}^2 &= [-l(l+n-2)]^{m_l} \int_{S^{n-1}} k \bar{Y}_l d\omega \\ &= \int_{S^{n-1}} k \Delta_{S^{n-1}}^{m_l} \bar{Y}_l d\omega = \int_{S^{n-1}} (\Delta_{S^{n-1}}^{m_l} k) \bar{Y}_l d\omega, \end{aligned} \quad (6-54)$$

where the first equality uses (6-51), the second one is based on (6-53), and the third one follows via repeated integrations by parts. In turn, from (6-54) and the Cauchy–Schwarz inequality we obtain

$$\|Y_l\|_{L^2(S^{n-1})} \leq l^{-2m_l} \|\Delta_{S^{n-1}}^{m_l} k\|_{L^2(S^{n-1})} \quad \text{for all } l \in \mathbb{N}_0. \quad (6-55)$$

We continue by noting that the homogeneity of  $k$  together with (6-51) and (6-52) permit us to express

$$k(x) = \frac{k(x/|x|)}{|x|^{n-1}} = \sum_{l=0}^{\infty} \frac{Y_l(x/|x|)}{|x|^{n-1}} = \sum_{l=0}^{\infty} \frac{P_l(x/|x|)}{|x|^{n-1}} = \sum_{l=0}^{\infty} \frac{P_l(x)}{|x|^{n-1+l}} \quad (6-56)$$

for each  $x \in \mathbb{R}^n \setminus \{0\}$ . For each  $l \in \mathbb{N}_0$ , let  $\mathbb{T}_l$  and  $T_l$  be the integral operators defined analogously to (1-32) and (1-33) in which the kernel  $k(x - y)$  has been replaced by  $P_l(x - y)|x - y|^{-(n-1+l)}$ . Then, for each  $f \in \mathcal{C}^\alpha(\partial\Omega)$ , we may estimate

$$\begin{aligned} \sum_{l=0}^{\infty} \|\mathbb{T}_l f\|_{\mathcal{C}^\alpha(\bar{\Omega})} &\leq \sum_{l=0}^{\infty} C^l 2^{l^2} \|P_l\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &= \sum_{l=0}^{\infty} C^l 2^{l^2} \|Y_l\|_{L^2(S^{n-1})} \|f\|_{\mathcal{C}^\alpha(\partial\Omega)} \\ &\leq \left( \sum_{l=0}^{\infty} C^l 2^{l^2} l^{-2m_l} \|\Delta_{S^{n-1}}^{m_l} k\|_{L^2(S^{n-1})} \right) \|f\|_{\mathcal{C}^\alpha(\partial\Omega)}, \end{aligned} \quad (6-57)$$

by invoking (1-19) and (6-55), and keeping in mind that  $P|_{S^{n-1}} = Y_l$  (see (6-52)). Since for  $l$  large we have  $C^l 2^{l^2} \leq 4^{l^2}$ , it follows from (1-31) that the series in the curly bracket in (6-57) is convergent to some finite constant  $M$ . Based on this and (6-56), we may then conclude that  $\|\mathbb{T}f\|_{\mathcal{C}^\alpha(\bar{\Omega})} \leq \sum_{l=0}^{\infty} \|\mathbb{T}_l f\|_{\mathcal{C}^\alpha(\bar{\Omega})} \leq M \|f\|_{\mathcal{C}^\alpha(\partial\Omega)}$ . This proves the boundedness of the first operator in (1-34), and the second operator in (1-34) is treated similarly (making use of (1-20)).  $\square$

**Remark 6.1.** We claim that (1-31) is satisfied whenever the kernel  $k$  is of the form  $P(x)/|x|^{n-1+l_o}$  for some homogeneous polynomial  $P$  of degree  $l_o \in 2\mathbb{N} - 1$  in  $\mathbb{R}^n$ . Indeed, writing  $P(x)/|x|^{n-1+l_o} = P(x/|x|)/|x|^{n-1}$  and invoking (6-29), there is no loss of generality in assuming that  $P$  is also harmonic to begin with. Granted this, it follows that  $k|_{S^{n-1}} = P|_{S^{n-1}}$  is a surface spherical harmonic of degree  $l_o$ ; hence—see [Stein 1970, §3.1.4, p. 70]— $\Delta_{S^{n-1}}(k|_{S^{n-1}}) = -l_o(l_o + n - 2)(k|_{S^{n-1}})$ . Choosing  $m_l := l^2$  for each  $l \in \mathbb{N}_0$  and iterating this formula then shows that the series in (1-31) is dominated by

$$\sum_{l=0}^{\infty} 4^{l^2} l^{-2l^2} [l_o(l_o + n - 2)]^{l^2} \|k\|_{L^2(S^{n-1})} < +\infty. \quad (6-58)$$

## 7. Further results

We start by recalling some definitions. First, given a compact Ahlfors regular set  $\Sigma \subset \mathbb{R}^n$ , introduce  $\sigma := \mathcal{H}^{n-1}|_{\Sigma}$  and define the John–Nirenberg space of functions of bounded mean oscillations on  $\Sigma$  as

$$\text{BMO}(\Sigma) := \{f \in L^1(\Sigma, \sigma) : f^{\#, p} \in L^\infty(\Sigma, \sigma)\}, \quad (7-1)$$

where  $p \in [1, \infty)$  is a fixed parameter and

$$f^{\#, p}(x) := \sup_{r>0} \left( \frac{1}{\sigma(\Sigma \cap B(x, r))} \int_{\Sigma \cap B(x, r)} |f(y) - f_{\Delta(x, r)}|^p d\sigma(y) \right)^{\frac{1}{p}}, \quad (7-2)$$

with  $f_{\Delta(x, r)}$  the mean value of  $f$  on  $\Sigma \cap B(x, r)$ . As is well known, various choices of  $p$  give the same space. Keeping this in mind, we define the seminorm

$$[f]_{\text{BMO}(\Sigma)} := \|f^{\#, p}\|_{L^\infty(\Sigma, \sigma)}. \quad (7-3)$$

We then define the Sarason space  $\text{VMO}(\Sigma)$  of functions of vanishing mean oscillations on  $\Sigma$  as the closure in  $\text{BMO}(\Sigma)$  of  $\mathcal{C}^0(\Sigma)$ , the space of continuous functions on  $\Sigma$ . Alternatively, given any  $\alpha \in (0, 1)$ , the space  $\text{VMO}(\Sigma)$  may be described (see [Hofmann et al. 2010, Proposition 2.15, p. 2602]) as the closure in  $\text{BMO}(\Sigma)$  of  $\mathcal{C}^\alpha(\Sigma)$ . Hence, in the present context,

$$\bigcup_{0 \leq \alpha < 1} \mathcal{C}^\alpha(\Sigma) \hookrightarrow \text{VMO}(\Sigma) \hookrightarrow \text{BMO}(\Sigma) \hookrightarrow \bigcap_{0 < p < \infty} L^p(\Sigma, \sigma). \quad (7-4)$$

**Proposition 7.1.** *If  $\Omega \subseteq \mathbb{R}^n$  is a UR domain with compact boundary then the principal value Cauchy–Clifford operator  $\mathcal{C}^{\text{PV}}$  from (5-2) is bounded both on  $\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$  and on  $\text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Moreover,  $(\mathcal{C}^{\text{PV}})^2 = \frac{1}{4}I$  both on  $\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$  and on  $\text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Hence, in particular,  $\mathcal{C}^{\text{PV}}$  is an isomorphism when acting on either of these spaces.*

*Proof.* To begin with, observe that in the present setting (5-21) ensures that  $\mathcal{C}^{\text{PV}}$  is well-defined on  $\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Now fix  $f \in \text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$  and pick some  $x_0 \in \partial\Omega$  and  $r > 0$ . For each  $R > 0$ , let us agree to abbreviate  $\Delta_R := \partial\Omega \cap B(x_0, R)$ . Denote by  $v$  the geometric measure-theoretic outward unit normal to  $\Omega$  and, with  $\sigma := \mathcal{H}^{n-1}|_{\partial\Omega}$ , introduce

$$A(x_0, r) := \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_0 - y| \geq 2r}} \frac{x_0 - y}{|x_0 - y|^n} \odot v(y) \odot (f(y) - f_{\Delta_{2r}}) d\sigma(y) \pm \frac{1}{2} f_{\Delta_{2r}}, \quad (7-5)$$

where the sign is chosen to be plus if  $\Omega$  is bounded and minus if  $\Omega$  is unbounded, and where  $f_{\Delta_{2r}}$  stands for the integral average of  $f$  over  $\Delta_{2r}$ . For  $x \in \Delta_r$ , use (5-21) to split

$$\begin{aligned} \mathcal{C}^{\text{PV}} f(x) &= \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \setminus B(x, \varepsilon) \\ |x_0 - y| < 2r}} \frac{x - y}{|x - y|^n} \odot v(y) \odot (f(y) - f_{\Delta_{2r}}) d\sigma(y) \\ &\quad + \frac{1}{\omega_{n-1}} \int_{\substack{y \in \partial\Omega \\ |x_0 - y| \geq 2r}} \left( \frac{x - y}{|x - y|^n} - \frac{x_0 - y}{|x_0 - y|^n} \right) \odot v(y) \odot (f(y) - f_{\Delta_{2r}}) d\sigma(y) + A(x_0, r), \end{aligned} \quad (7-6)$$

then employ this representation (and Minkowski's inequality) in order to estimate

$$\left( \frac{1}{\sigma(\Delta_r)} \int_{\Delta_r} |\mathcal{C}^{\text{PV}} f(x) - A(x_0, r)|^2 d\sigma(x) \right)^{\frac{1}{2}} \leq c(I + II), \quad (7-7)$$

where  $c \in (0, \infty)$  depends only on  $\Omega$  and

$$\begin{aligned} I &:= \left( \frac{1}{\sigma(\Delta_r)} \int_{\partial\Omega} |\mathcal{C}^{\text{PV}}((f - f_{\Delta_{2r}})\mathbf{1}_{\Delta_{2r}})|^2 d\sigma \right)^{\frac{1}{2}}, \\ II &:= r^{-n-1/(2)} \int_{\substack{y \in \partial\Omega \\ |x_0 - y| \geq 2r}} \left( \int_{\Delta_r} \left| \frac{x-y}{|x-y|^n} - \frac{x_0-y}{|x_0-y|^n} \right|^2 d\sigma(x) \right)^{\frac{1}{2}} |f(y) - f_{\Delta_{2r}}| d\sigma(y). \end{aligned}$$

Now, the boundedness of  $\mathcal{C}^{\text{PV}}$  on  $L^2(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n$  from [Proposition 5.1](#) gives (bearing in mind that  $\sigma$  is doubling)

$$I \leq c \left( \frac{1}{\sigma(\Delta_{2r})} \int_{\Delta_{2r}} |f - f_{\Delta_{2r}}|^2 d\sigma \right)^{\frac{1}{2}} \leq c[f]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n}, \quad (7-8)$$

which suits our purposes. Next, we write

$$\begin{aligned} II &\leq c \int_{\substack{y \in \partial\Omega \\ |x_0 - y| \geq 2r}} \frac{r}{|x_0 - y|^n} |f(y) - f_{\Delta_{2r}}| d\sigma(y) \\ &\leq c \sum_{j=1}^{\infty} \int_{\Delta_{2^{j+1}r} \setminus \Delta_{2^j r}} \frac{r}{(2^j r)^n} |f(y) - f_{\Delta_{2r}}| d\sigma(y) \\ &\leq c \sum_{j=1}^{\infty} \frac{1}{2^j} \int_{\Delta_{2^{j+1}r}} |f - f_{\Delta_{2r}}| d\sigma \\ &\leq c \sum_{j=1}^{\infty} \frac{1}{2^j} \int_{\Delta_{2^{j+1}r}} \left[ |f - f_{\Delta_{2^{j+1}r}}| + \sum_{k=1}^j |f_{\Delta_{2^{k+1}r}} - f_{\Delta_{2^k r}}| \right] d\sigma \\ &\leq c \sum_{j=1}^{\infty} \frac{1}{2^j} (1+j) f^{\#, 1}(x_0) \leq c f^{\#, 1}(x_0) \leq c[f]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n}. \end{aligned} \quad (7-9)$$

Above, the first inequality follows from the mean value theorem, while the second inequality is a consequence of writing the integral over  $\partial\Omega \setminus \Delta_{2r}$  as the telescopic sum over  $\Delta_{2^{j+1}r} \setminus \Delta_{2^j r}$ ,  $j \in \mathbb{N}$ , and the fact that  $|x_0 - y| \geq 2^j r$  for  $y \in \Delta_{2^{j+1}r} \setminus \Delta_{2^j r}$ . The third inequality is a result of enlarging the domain of integration from  $\Delta_{2^{j+1}r} \setminus \Delta_{2^j r}$  to  $\Delta_{2^{j+1}r}$  and using  $\sigma(\Delta_{2^{j+1}r}) \approx (2^j r)^{n-1}$ . The fourth inequality follows from the triangle inequality after writing

$$f - f_{\Delta_{2r}} = f - f_{\Delta_{2^{j+1}r}} + \sum_{k=1}^j (f_{\Delta_{2^{k+1}r}} - f_{\Delta_{2^k r}}). \quad (7-10)$$

The fifth inequality is a consequence of the fact that, for each  $k$ , we have

$$\begin{aligned} |f_{\Delta_{2^{k+1}r}} - f_{\Delta_{2^kr}}| &= \left| \int_{\Delta_{2^kr}} (f - f_{\Delta_{2^{k+1}r}}) d\sigma \right| \\ &\leq c \int_{\Delta_{2^{k+1}r}} |f - f_{\Delta_{2^{k+1}r}}| d\sigma \leq c f^{\#,1}(x_0). \end{aligned} \quad (7-11)$$

The sixth inequality is a consequence of  $\sum_{j=1}^{\infty} 2^{-j}(1+j) < +\infty$  and, finally, the last inequality is seen from (7-3).

From (7-7)–(7-9) we eventually obtain  $\|(\mathcal{C}^{\text{PV}} f)^{\#,2}\|_{L^{\infty}(\partial\Omega, \sigma) \otimes \mathcal{C}\ell_n} \leq c[f]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n}$ ; hence,

$$[\mathcal{C}^{\text{PV}} f]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \leq c[f]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n}, \quad (7-12)$$

from which we conclude that the operator

$$\mathcal{C}^{\text{PV}} : \text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n \longrightarrow \text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n \quad (7-13)$$

is well-defined and bounded. Next, that

$$\mathcal{C}^{\text{PV}} : \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n \longrightarrow \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n \quad (7-14)$$

is also well-defined and bounded follows from (7-13), the characterization of  $\text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$  as the closure in  $\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$  of  $\mathcal{C}^{\alpha}(\partial\Omega) \otimes \mathcal{C}\ell_n$  for each  $\alpha \in (0, 1)$ , and Theorem 5.6.

Finally, the claims in the last part of the statement of the proposition are direct consequences of what we have proved so far, (7-4), and (5-5).  $\square$

When  $\Omega \subseteq \mathbb{R}^n$  is a UR domain with compact boundary, it follows from (1-13) and (3-8) in Theorem 3.1 that  $R_j$  maps  $\mathcal{C}^{\alpha}(\partial\Omega)$  into  $\text{BMO}(\partial\Omega)$  for each  $j \in \{1, \dots, n\}$ . Hence, in this case,  $R_j 1 \in \text{BMO}(\partial\Omega)$  for each  $j \in \{1, \dots, n\}$ . Remarkably, the proximity of the BMO functions  $R_j 1$ ,  $1 \leq j \leq n$ , to the space  $\text{VMO}(\partial\Omega)$  controls how close the outward unit normal  $\nu$  to  $\Omega$  is to being in  $\text{VMO}(\partial\Omega)$ . Specifically, we have the following result:

**Theorem 7.2.** *Let  $\Omega \subseteq \mathbb{R}^n$  be a UR domain with compact boundary and denote by  $\nu$  the geometric measure-theoretic outward unit normal to  $\Omega$ . Also, let  $\|\mathcal{C}^{\text{PV}}\|_{*}$  stand for the operator norm of the Cauchy–Clifford singular integral operator acting on the space  $\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n$ . Then, with distances considered in  $\text{BMO}(\partial\Omega)$ , one has*

$$\text{dist}(\nu, \text{VMO}(\partial\Omega)) \leq 4\|\mathcal{C}^{\text{PV}}\|_{*} \left( \sum_{j=1}^n \text{dist}(R_j 1, \text{VMO}(\partial\Omega))^2 \right)^{\frac{1}{2}}, \quad (7-15)$$

$$\left( \sum_{j=1}^n \text{dist}(R_j 1, \text{VMO}(\partial\Omega))^2 \right)^{\frac{1}{2}} \leq \|\mathcal{C}^{\text{PV}}\|_{*} \text{dist}(\nu, \text{VMO}(\partial\Omega)). \quad (7-16)$$

*Proof.* On the one hand, based on (6-50), Proposition 7.1 and the fact that each  $R_j^{\text{PV}}$  agrees with  $R_j$  on  $L^2(\partial\Omega)$ , we may estimate

$$\begin{aligned}
 \text{dist}(\nu, \text{VMO}(\partial\Omega)) &= \inf_{\eta \in \text{VMO}(\partial\Omega)} [\nu - \eta]_{\text{BMO}(\partial\Omega)} \\
 &= \inf_{\eta \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} [\nu - \eta]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= \inf_{\eta \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} 4 \left[ \mathcal{C}^{\text{PV}} \left( \sum_{j=1}^n (R_j^{\text{PV}} 1) e_j + \mathcal{C}^{\text{PV}} \eta \right) \right]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &\leq 4 \|\mathcal{C}^{\text{PV}}\|_* \inf_{\eta \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \left[ \sum_{j=1}^n (R_j 1) e_j + \mathcal{C}^{\text{PV}} \eta \right]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= 4 \|\mathcal{C}^{\text{PV}}\|_* \inf_{\xi \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \left[ \sum_{j=1}^n (R_j 1) e_j - \xi \right]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= 4 \|\mathcal{C}^{\text{PV}}\|_* \inf_{\xi \in \text{VMO}(\partial\Omega)} \left[ \sum_{j=1}^n (R_j 1) e_j - \xi \right]_{\text{BMO}(\partial\Omega)} \\
 &= 4 \|\mathcal{C}^{\text{PV}}\|_* \left( \sum_{j=1}^n \text{dist}(R_j 1, \text{VMO}(\partial\Omega))^2 \right)^{\frac{1}{2}}, \tag{7-17}
 \end{aligned}$$

yielding (7-15). On the other hand, from (6-49) and Proposition 7.1 we deduce — once again by bearing in mind that each  $R_j^{\text{PV}}$  agrees with  $R_j$  on  $L^2(\partial\Omega)$  — that

$$\begin{aligned}
 \left( \sum_{j=1}^n \text{dist}(R_j 1, \text{VMO}(\partial\Omega))^2 \right)^{\frac{1}{2}} &= \inf_{\xi \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \left[ \sum_{j=1}^n (R_j 1) e_j - \xi \right]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= \inf_{\xi \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \left[ \sum_{j=1}^n (R_j^{\text{PV}} 1) e_j - \xi \right]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= \inf_{\xi \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} [\mathcal{C}^{\text{PV}} \nu - \xi]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= \inf_{\eta \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} [\mathcal{C}^{\text{PV}} (\nu - \eta)]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &\leq \|\mathcal{C}^{\text{PV}}\|_* \inf_{\eta \in \text{VMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} [\nu - \eta]_{\text{BMO}(\partial\Omega) \otimes \mathcal{C}\ell_n} \\
 &= \|\mathcal{C}^{\text{PV}}\|_* \inf_{\eta \in \text{VMO}(\partial\Omega)} [\nu - \eta]_{\text{BMO}(\partial\Omega)} \\
 &= \|\mathcal{C}^{\text{PV}}\|_* \text{dist}(\nu, \text{VMO}(\partial\Omega)), \tag{7-18}
 \end{aligned}$$

finishing the justification of (7-16).  $\square$

Having established Theorem 7.2, we are now in a position to present the proof of Theorem 1.4.

*Proof of Theorem 1.4.* For the left-to-right implication in (1-28), first observe that  $\Omega$  is a UR domain (see Definition 2.7). As such, Theorem 7.2 applies and (7-16) gives  $R_j 1 \in \text{VMO}(\partial\Omega)$  for each  $j \in \{1, \dots, n\}$ .

For the right-to-left implication in (1-28), use (1-11) and the background assumptions on  $\Omega$  to conclude that  $\Omega$  is a UR domain, then invoke (7-15) from Theorem 7.2 to conclude that  $v \in \text{VMO}(\partial\Omega)$ .  $\square$

Moving on, we record the following definition:

**Definition 7.3.** Let  $\Omega \subset \mathbb{R}^n$  be an open set with compact boundary. Then  $\Omega$  is said to satisfy a *John condition* if there exist  $\theta \in (0, 1)$  and  $R \in (0, \infty)$ , called the John constants of  $\Omega$ , with the following significance: for every  $p \in \partial\Omega$  and  $r \in (0, R)$  one can find  $p_r \in B(p, r) \cap \Omega$  such that  $B(p_r, \theta r) \subset \Omega$  and with the property that, for each  $x \in B(p, r) \cap \partial\Omega$ , there exists a rectifiable path  $\gamma_x : [0, 1] \rightarrow \bar{\Omega}$  whose length is at most  $\theta^{-1}r$  and

$$\gamma_x(0) = x, \quad \gamma_x(1) = p_r \quad \text{and} \quad \text{dist}(\gamma_x(t), \partial\Omega) > \theta|\gamma_x(t) - x| \quad \text{for all } t \in (0, 1]. \quad (7-19)$$

Furthermore,  $\Omega$  is said to satisfy a *two-sided John condition* if both  $\Omega$  and  $\mathbb{R}^n \setminus \bar{\Omega}$  satisfy a John condition.

The above definition appears in [Hofmann et al. 2010], where it was noted that any NTA domain (in the sense of D. Jerison and C. Kenig [1982]) with compact boundary satisfies a John condition.

Next, we recall the concept of  $\delta$ -Reifenberg flat domain, following [Kenig and Toro 1999; 2003]. As a preamble, the reader is reminded that the Pompeiu–Hausdorff distance between two sets  $A, B \subseteq \mathbb{R}^n$  is given by

$$D[A, B] := \max\{\sup\{\text{dist}(a, B) : a \in A\}, \sup\{\text{dist}(b, A) : b \in B\}\}. \quad (7-20)$$

**Definition 7.4.** Let  $\Sigma \subset \mathbb{R}^n$  be a compact set and let  $\delta \in (0, 1/(4\sqrt{2}))$ . Call  $\Sigma$  a  *$\delta$ -Reifenberg flat set* if there exists  $R > 0$  such that, for every  $x \in \Sigma$  and every  $r \in (0, R]$ , there exists an  $(n-1)$ -dimensional plane  $L(x, r)$  which contains  $x$  and is such that

$$D[\Sigma \cap B(x, r), L(x, r) \cap B(x, r)] \leq \delta r. \quad (7-21)$$

**Definition 7.5.** Say that a bounded open set  $\Omega \subset \mathbb{R}^n$  has the *separation property* if there exists  $R > 0$  such that, for every  $x \in \partial\Omega$  and  $r \in (0, R]$ , there exists an  $(n-1)$ -dimensional plane  $\mathcal{L}(x, r)$  containing  $x$  and a choice of unit normal vector to  $\mathcal{L}(x, r)$  — call it  $\vec{n}_{x,r}$  — satisfying

$$\begin{aligned} \{y + t\vec{n}_{x,r} \in B(x, r) : y \in \mathcal{L}(x, r), t < -\frac{1}{4}r\} &\subset \Omega, \\ \{y + t\vec{n}_{x,r} \in B(x, r) : y \in \mathcal{L}(x, r), t > \frac{1}{4}r\} &\subset \mathbb{R}^n \setminus \Omega. \end{aligned} \quad (7-22)$$

Moreover, if  $\Omega$  is unbounded, it is also required that  $\partial\Omega$  divides  $\mathbb{R}^n$  into two distinct connected components and that  $\mathbb{R}^n \setminus \Omega$  has a nonempty interior.

**Definition 7.6.** Let  $\Omega \subset \mathbb{R}^n$  be a bounded open set and  $\delta \in (0, \delta_n)$ . Call  $\Omega$  a  *$\delta$ -Reifenberg flat domain* if  $\Omega$  has the separation property and  $\partial\Omega$  is a  $\delta$ -Reifenberg flat set.

The notion of *Reifenberg flat domain with vanishing constant* is introduced in a similar fashion, this time allowing the constant  $\delta$  appearing in (7-21) to depend on  $r$ , say  $\delta = \delta(r)$ , and demanding that  $\lim_{r \rightarrow 0^+} \delta(r) = 0$ .

As our next result shows, under appropriate background assumptions (of a “large” geometry nature) the proximity of the vector-valued function  $(R_1 1, R_2 1, \dots, R_n 1)$  to the space  $\text{VMO}(\partial\Omega)$ , measured in  $\text{BMO}(\partial\Omega)$ , can be used to quantify Reifenberg flatness.

**Theorem 7.7.** Assume  $\Omega \subseteq \mathbb{R}^n$  is an open set with a compact Ahlfors regular boundary, satisfying a two-sided John condition (hence,  $\Omega$  is a UR domain, which further entails that  $R_j 1 \in \text{BMO}(\partial\Omega)$  for each  $j$ ). If, with distances considered in  $\text{BMO}(\partial\Omega)$ ,

$$\sum_{j=1}^n \text{dist}(R_j 1, \text{VMO}(\partial\Omega)) < \varepsilon, \quad (7-23)$$

then  $\Omega$  is a  $\delta$ -Reifenberg flat domain for  $\delta = C_o \cdot \varepsilon$ , where  $C_o \in (0, \infty)$  depends only on the Ahlfors regularity and John constants of  $\Omega$ .

As a consequence, if  $R_j 1 \in \text{VMO}(\partial\Omega)$  for every  $j \in \{1, \dots, n\}$  then actually  $\Omega$  is a Reifenberg flat domain with vanishing constant.

*Proof.* It is known that if  $\Omega \subseteq \mathbb{R}^n$  is an open set with a compact Ahlfors regular boundary, satisfying a two-sided John condition, and such that

$$\text{dist}(v, \text{VMO}(\partial\Omega)) < \varepsilon \quad (7-24)$$

(with the distance considered in  $\text{BMO}(\partial\Omega)$ ), then  $\Omega$  is a  $\delta$ -Reifenberg flat domain for the choice  $\delta = C_o \cdot \varepsilon$ , where the constant  $C_o \in (0, \infty)$  is as in the statement of the theorem. See [Hofmann et al. 2010, Definition 4.7, p. 2690 and Corollary 4.20, p. 2710] in this regard. Granted this, the desired conclusion follows by invoking [Theorem 7.2](#), since our assumptions on  $\Omega$  guarantee that this is a UR domain (see [\(1-29\)](#)).  $\square$

In this last part of this section we discuss a (partial) extension of [Theorem 1.1](#) in the context of Besov spaces. We begin by defining this scale and recalling some of its most basic properties.

**Definition 7.8.** Assume that  $\Sigma \subset \mathbb{R}^n$  is an Ahlfors regular set and let  $\sigma := \mathcal{H}^{n-1}|_\Sigma$ . Then, given  $1 \leq p \leq \infty$  and  $0 < s < 1$ , define the Besov space

$$B_s^{p,p}(\Sigma) := \{f \in L^p(\Sigma, \sigma) : \|f\|_{B_s^{p,p}(\Sigma)} < +\infty\}, \quad (7-25)$$

where

$$\|f\|_{B_s^{p,p}(\Sigma)} := \|f\|_{L^p(\Sigma, \sigma)} + \left( \int_{\Sigma} \int_{\Sigma} \frac{|f(x) - f(y)|^p}{|x - y|^{n-1+sp}} d\sigma(x) d\sigma(y) \right)^{\frac{1}{p}}, \quad (7-26)$$

with the convention that

$$B_s^{\infty,\infty}(\Sigma) := \mathscr{C}^s(\Sigma) \quad \text{and} \quad \|f\|_{B_s^{\infty,\infty}(\Sigma)} := \|f\|_{\mathscr{C}^s(\Sigma)}. \quad (7-27)$$

Finally, denote by  $B_{s,\text{loc}}^{p,p}(\Sigma)$  the space of functions whose truncations by smooth and compactly supported functions belong to  $B_s^{p,p}(\Sigma)$ .

Consider  $\Sigma$  as in [Definition 7.8](#) and suppose  $1 \leq p_0, p_1 \leq \infty$  and  $s_0, s_1 \in (0, 1)$  are such that

$$\frac{1}{p_1} - \frac{s_1}{n-1} = \frac{1}{p_0} - \frac{s_0}{n-1} \quad \text{and} \quad s_0 \geq s_1. \quad (7-28)$$

Then [Jonsson and Wallin 1984, Proposition 5, p. 213] gives that

$$B_{s_0}^{p_0, p_0}(\Sigma) \hookrightarrow B_{s_1}^{p_1, p_1}(\Sigma) \quad \text{continuously.} \quad (7-29)$$

In particular,

$$B_s^{p, p}(\Sigma) \hookrightarrow \mathcal{C}^\alpha(\Sigma) \quad \text{if } p \in [1, \infty], s \in (0, 1) \text{ with } sp > n - 1, \alpha := s - \frac{n-1}{p}. \quad (7-30)$$

In turn, from (7-25)–(7-26) and (7-30) one may easily deduce that

$$B_s^{p, p}(\Sigma) \text{ is an algebra if } p \in [1, \infty] \text{ and } s \in (0, 1) \text{ satisfy } sp > n - 1, \quad (7-31)$$

and

$$f/g \in B_s^{p, p}(\Sigma) \text{ whenever } f, g \in B_s^{p, p}(\Sigma) \text{ and } |g| \geq c > 0 \text{ } \sigma\text{-a.e. on } \Sigma. \quad (7-32)$$

Another useful simple property is that, given any  $p \in [1, \infty]$  and  $s \in (0, 1)$ , if  $F : \mathbb{R} \rightarrow \mathbb{R}$  is a bounded Lipschitz function then

$$F \circ f \in B_{s, \text{loc}}^{p, p}(\Sigma) \quad \text{for every } f \in B_s^{p, p}(\Sigma). \quad (7-33)$$

Finally, we note that in the case when  $\Sigma$  is the graph of a Lipschitz function  $\varphi : \mathbb{R}^{n-1} \rightarrow \mathbb{R}$ , from [Mitrea and Mitrea 2013, Proposition 2.9, p. 33] and real interpolation we obtain that, for each  $p \in (1, \infty)$  and  $s \in (0, 1)$ ,

$$f \in B_s^{p, p}(\Sigma) \iff f(\cdot, \varphi(\cdot)) \in B_s^{p, p}(\mathbb{R}^{n-1}). \quad (7-34)$$

**Proposition 7.9.** *Assume  $\Omega \subset \mathbb{R}^n$  is a Lebesgue measurable set whose boundary is compact, Ahlfors regular, and satisfies (2-16). Then*

$$\mathcal{C}^{\text{PV}} : B_s^{p, p}(\partial\Omega) \otimes \mathcal{C}\ell_n \longrightarrow B_s^{p, p}(\partial\Omega) \otimes \mathcal{C}\ell_n \quad (7-35)$$

is well-defined and bounded for each  $p \in [1, \infty]$  and  $s \in (0, 1)$ .

*Proof.* One way to see this is via real interpolation (see [Han et al. 2008, §8.1] for a version suiting the current setting) between the boundedness result proved in Theorem 5.6 (corresponding to (7-35) when  $p = \infty$ ; see (7-27)), and the fact that the operator  $\mathcal{C}^{\text{PV}}$  in (7-35) with  $p = 1$  is also bounded (which follows from the atomic/molecular theory for the Besov scale on spaces of homogeneous type from [Han and Yang 2003]).  $\square$

In order to present the extension of Theorem 1.1 mentioned earlier to the scale of Besov spaces, we make the following definition:

**Definition 7.10.** Given  $p \in [1, \infty]$  and  $s \in (0, 1)$ , call a nonempty, open, proper subset  $\Omega$  of  $\mathbb{R}^n$  a  $B_{s+1}^{p, p}$ -domain provided it may be locally identified<sup>5</sup> near boundary points with the upper graph of a real-valued function  $\varphi$  defined in  $\mathbb{R}^{n-1}$  with the property that  $\partial_j \varphi \in B_s^{p, p}(\mathbb{R}^{n-1})$  for each  $j \in \{1, \dots, n-1\}$ .

The stage has been set for stating and proving the following result:

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<sup>5</sup>In the sense described in Definition 2.1.

**Theorem 7.11.** Assume  $\Omega \subseteq \mathbb{R}^n$  is an Ahlfors regular domain with a compact boundary, satisfying  $\partial\Omega = \partial(\bar{\Omega})$ . Then, for each  $s \in (0, 1)$  and  $p \in [1, \infty]$  with the property that  $sp > n - 1$ , the following claims are equivalent:

- (a)  $\Omega$  is a  $B_{s+1}^{p,p}$  domain.
- (b) The distributional Riesz transforms associated with  $\partial\Omega$  satisfy

$$R_j 1 \in B_s^{p,p}(\partial\Omega) \quad \text{for each } j \in \{1, \dots, n\}. \quad (7-36)$$

*Proof.* Consider the implication (b)  $\Rightarrow$  (a). The starting point is the observation that (7-36) and (7-30) imply (1-14) for  $\alpha := s - (n - 1)/p \in (0, 1)$ . As such, Theorem 1.1 applies and gives that  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$ . Hence, locally, the outward unit normal  $v$  to  $\Omega$  has components  $(v_j)_{1 \leq j \leq n}$  of the form

$$v_j(x', \varphi(x')) = \begin{cases} \frac{\partial_j \varphi(x')}{\sqrt{1 + |\nabla \varphi(x')|^2}} & \text{if } 1 \leq j \leq n - 1, \\ -\frac{1}{\sqrt{1 + |\nabla \varphi(x')|^2}} & \text{if } j = n, \end{cases} \quad (7-37)$$

where  $\varphi \in \mathcal{C}^{1+\alpha}(\mathbb{R}^{n-1})$  is a real-valued function whose upper graph locally describes  $\Omega$ . Without loss of generality it may be assumed that  $\varphi$  has compact support.

On the other hand, from the assumption (7-36), Proposition 7.9 and (6-50) we may conclude that

$$v \in B_s^{p,p}(\partial\Omega). \quad (7-38)$$

On account of this membership and (7-34), we obtain

$$v_j(\cdot, \varphi(\cdot)) \in B_s^{p,p}(\mathbb{R}^{n-1}) \quad \text{for each } j \in \{1, \dots, n\}. \quad (7-39)$$

Upon recalling (7-31)–(7-32), this further yields

$$\partial_j \varphi = \frac{v_j(\cdot, \varphi(\cdot))}{v_n(\cdot, \varphi(\cdot))} \in B_s^{p,p}(\mathbb{R}^{n-1}) \quad \text{for each } j \in \{1, \dots, n-1\}, \quad (7-40)$$

proving that  $\Omega$  is a  $B_{s+1}^{p,p}$  domain.

Concerning the implication (a)  $\Rightarrow$  (b), assume that  $\Omega$  is a  $B_{s+1}^{p,p}$  domain with  $s$  and  $p$  as before. From the definitions and (7-30) (used with  $\Sigma := \mathbb{R}^{n-1}$ ) it follows that  $\Omega$  is a domain of class  $\mathcal{C}^{1+\alpha}$  with  $\alpha := s - (n - 1)/p$ . Hence, in particular,  $\Omega$  is a Lipschitz domain. We claim that (7-38) holds. Thanks to (7-34), justifying this claim comes down to proving that (7-39) holds, where  $\varphi$  is a real-valued function defined in  $\mathbb{R}^{n-1}$  satisfying  $\partial_j \varphi \in B_s^{p,p}(\mathbb{R}^{n-1})$  for each  $j \in \{1, \dots, n-1\}$  and whose upper graph locally describes  $\Omega$  (again, without loss of generality it may be assumed that  $\varphi$  has compact support). To this end, consider the function  $F : \mathbb{R} \rightarrow \mathbb{R}$  given by  $F(t) := 1/\sqrt{1 + |t|}$  for each  $t \in \mathbb{R}$ , and note that  $F$  is both bounded and Lipschitz. Since, by (7-31),

$$|\nabla \varphi|^2 = \sum_{j=1}^{n-1} (\partial_j \varphi)(\partial_j \varphi) \in B_s^{p,p}(\mathbb{R}^{n-1}), \quad (7-41)$$

it follows from (7-33) that

$$v_n(\cdot, \varphi(\cdot)) = -F \circ |\nabla \varphi|^2 \in B_{s,\text{loc}}^{p,p}(\mathbb{R}^{n-1}). \quad (7-42)$$

Granted this, another reference to (7-31) gives that, for each  $j \in \{1, \dots, n-1\}$ ,

$$v_j(\cdot, \varphi(\cdot)) = \frac{\partial_j \varphi}{\sqrt{1 + |\nabla \varphi|^2}} = -\partial_j \varphi \cdot v_n(\cdot, \varphi(\cdot)) \in B_s^{p,p}(\mathbb{R}^{n-1}). \quad (7-43)$$

This finishes the proof of (7-39), hence completing the justification of (7-38). Having established this, bring in identity (6-49) in order to conclude, on account of Proposition 7.9, that

$$\sum_{j=1}^n (R_j 1) e_j = \sum_{j=1}^n (R_j^{\text{PV}} 1) e_j = -C^{\text{PV}} v \in B_s^{p,p}(\partial\Omega) \otimes \mathcal{C}\ell_n. \quad (7-44)$$

Since this readily implies (7-36), the implication (a)  $\Rightarrow$  (b) is established.  $\square$

Lastly, we remark that the limiting case  $s = 1$  of Theorem 7.11 also holds provided  $p \in (n-1, \infty)$  and the Besov space intervening in (7-36) is replaced by  $L_1^p(\partial\Omega)$ , the  $L^p$ -based Sobolev space of order 1 on  $\partial\Omega$  considered in [Hofmann et al. 2010] (in which scenario  $\Omega$  is an  $L_2^p$  domain, in a natural sense). The proof follows the same blueprint and makes use of the fact that  $C^{\text{PV}}$  is a bounded operator from  $L_1^p(\partial\Omega) \otimes \mathcal{C}\ell_n$  into itself (see [Mitrea et al. 2015; 2016] in this regard).

### Acknowledgments

D. Mitrea has been supported in part by the Simons Foundation grant # 200750, M. Mitrea has been supported in part by the Simons Foundation grant # 281566 and by a University of Missouri Research Leave grant, while Verdera has been supported in part by the grants 2014SGR475 (Generalitat de Catalunya) and MTM2013-44699 (Ministerio de Educación y Ciencia). The authors are also grateful to L. Escauriaza and M. Taylor for some useful correspondence on the subject of the paper.

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Received 24 Jan 2016. Revised 10 Feb 2016. Accepted 11 Mar 2016.

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Analysis & PDE (ISSN 1948-206X electronic, 2157-5045 printed) at Mathematical Sciences Publishers, 798 Evans Hall #3840, c/o University of California, Berkeley, CA 94720-3840, is published continuously online. Periodical rate postage paid at Berkeley, CA 94704, and additional mailing offices.

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Volume 9    No. 4    2016

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