

NISSUNA UMANA INVESTIGAZIONE SI PUO DIMANDARE VERA SCIENZA
S'ESSA NON PASSA PER LE MATEMATICHE DIMOSTRAZIONI
LEONARDO DA VINCI

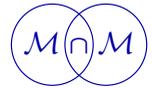
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We consider spin systems between a finite number N of “species” or “phases” partitioning a cubic lattice \mathbb{Z}^d . We suppose that interactions between points of the same phase are coercive while those between points of different phases (or possibly between points of an additional “weak phase”) are of lower order. Following a discrete-to-continuum approach, we characterize the limit as a continuum energy defined on N -tuples of sets (corresponding to the N strong phases) composed of a surface part, taking into account homogenization at the interface of each strong phase, and a bulk part that describes the combined effect of lower-order terms, weak interactions between phases, and possible oscillations in the weak phase.

1. Introduction

In this paper, we consider lattice spin energies mixing strong ferromagnetic interactions and weak (possibly antiferromagnetic) pair interactions. The geometry that we have in mind is a periodic system of interactions such as that whose periodicity cell is represented in [Figure 1](#). In that picture, the strong interactions between nodes of the lattice (circles) are represented by solid lines and weak ones by dashed lines. In this particular case, we have two three-periodic systems of “strong sites”, i.e., sites connected by strong interactions, and isolated “weak sites” (pictured as white circles). Note that we may also have one or more infinite systems of connected weak interactions as in [Figure 2](#). In a discrete environment, the topological requirements governing the interactions between the strong and weak phases characteristic of continuum high-contrast models are substituted with assumptions on long-range interactions. In particular, contrary to the continuum case, for discrete systems with second-neighbor (or longer-range) interactions, we may have a limit multiphase system even in dimension 1 (see the examples in [Section 6](#)).

This paper is part of a general study of spin systems by means of variational techniques through the computation of continuum approximate energies, for which

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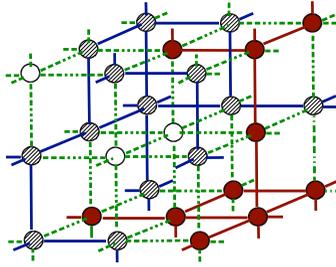


Figure 1. Picture of a double-porosity system.

homogenization results have been proved in the ferromagnetic case (i.e, when all interactions are strong) [Caffarelli and de la Llave 2005; Braides and Piatnitski 2013], and a general discrete-to-continuum theory of representation and optimization has been developed (see the survey [Braides 2014a]). In particular, a discrete-to-continuum compactness result and an integral representation of the limit by means of surface energies defined on sets of finite perimeter have been proved [Alicandro and Gelli 2016]. In that result, the coercivity of energies is obtained by assuming that nearest neighbors are always connected through a chain of strong interactions. Double-porosity systems can be interpreted as energies for which this condition does not hold but is satisfied separately on (finitely many) infinite connected components.

We are going to consider energies defined on functions parametrized on the cubic lattice \mathbb{Z}^d of the form

$$F_\varepsilon(u) = \sum_{(\alpha, \beta) \in \varepsilon \mathcal{N}_1 \cap (\Omega \times \Omega)} \varepsilon^{d-1} a_{\alpha\beta}^\varepsilon (u_\alpha - u_\beta)^2 + \sum_{(\alpha, \beta) \in \varepsilon \mathcal{N}_0 \cap (\Omega \times \Omega)} \varepsilon^d a_{\alpha\beta}^\varepsilon (u_\alpha - u_\beta)^2 + \sum_{\alpha \in \Omega \cap \varepsilon \mathbb{Z}^d} \varepsilon^d g(u_\alpha), \quad (1)$$

where Ω is a regular open subset of \mathbb{R}^d and $u_\alpha \in \{-1, +1\}$ denote the values of a spin function. For explanatory purposes, in this formula and the rest of the

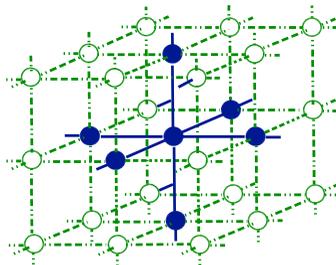


Figure 2. A double-porosity system with an infinite connected weak component.

introduction, we use a simplified notation with respect to the rest of the paper, defining $u = \{u_\alpha\}$ on the nodes of $\Omega \cap \varepsilon \mathbb{Z}^d$ (instead of, equivalently, on the nodes of $(1/\varepsilon)\Omega \cap \mathbb{Z}^d$). We denote by \mathcal{N}_1 the set of pairs of nodes in $\mathbb{Z}^d \times \mathbb{Z}^d$ between which we have strong interactions and by \mathcal{N}_0 the set of pairs in $\mathbb{Z}^d \times \mathbb{Z}^d$ between which we have weak interactions. The difference between these two types of interactions in the energy is the scaling factor: ε^{d-1} for strong interactions and ε^d for weak interaction. We suppose that all coefficients are obtained by scaling fixed coefficients on \mathbb{Z}^d , i.e.,

$$a_{\alpha\beta}^\varepsilon = a_{\alpha/\varepsilon, \beta/\varepsilon} \quad \text{if } \alpha, \beta \in \varepsilon \mathbb{Z}^d, \quad (2)$$

and a_{jk} are periodic of some integer period T . Moreover, we assume that the coefficients of the strong interactions are strictly positive, i.e., $a_{jk} > 0$ if $(j, k) \in \mathcal{N}_1$. The “forcing” term containing g and depending only on the point values u_α is of lower order with respect to strong interactions but of the same order as the weak interactions.

We suppose that there are N infinite connected components of the graph of points linked by strong interactions, which we denote by C_1, \dots, C_N . Note that weak interactions in \mathcal{N}_0 are due either to the existence of “weak sites” or to weak bonds between different “strong components” and, if we have more than one strong graph, the interactions in \mathcal{N}_0 are present also in the absence of a weak component. We will describe the asymptotic behavior of energies (1) using the notation and techniques of Γ -convergence (see, e.g., [Braides 2002; 2006]).

If we consider only the strong interactions restricted to each strong connected component C_j , we obtain energies

$$F_\varepsilon^j(u) = \sum_{(\alpha, \beta) \in \varepsilon \mathcal{N}_1^j \cap (\Omega \times \Omega)} \varepsilon^{d-1} a_{\alpha\beta}^\varepsilon (u_\alpha - u_\beta)^2, \quad (3)$$

where \mathcal{N}_1^j is the restriction to $C_j \times C_j$ of the set \mathcal{N}_1 . This is a discrete analog of an energy on a *perforated domain*, the perforation being $\mathbb{Z}^d \setminus C_j$.

We prove an extension lemma that allows us to define for each $j \in \{1, \dots, N\}$ a *discrete-to-continuum convergence* of (the restriction to C_j of) a sequence of functions u^ε to a function $u^j \in \text{BV}(\Omega; \{\pm 1\})$, which is compact under an equi-boundedness assumption for the energies $F_\varepsilon^j(u^\varepsilon)$. Thanks to this lemma, such energies behave as ferromagnetic energies with positive coefficients on the whole of \mathbb{Z}^d , which can be *homogenized* thanks to [Braides and Piatnitski 2013]; i.e., their Γ -limit with respect to the convergence $u^\varepsilon \rightarrow u^j$ exists and is of the form

$$F^j(u^j) = \int_{S(u^j) \cap \Omega} f_{\text{hom}}^j(v_{u^j}) d\mathcal{H}^{d-1} \quad (4)$$

where $S(u^j)$ is the set of jump points of u^j , which can also be interpreted as the interface between $\{u^j = 1\}$ and $\{u^j = -1\}$.

Taking into account separately the restrictions of u^ε to all of the components C_j , we define a *vector-valued* limit function $u = (u^1, \dots, u^N)$ and a convergence $u^\varepsilon \rightarrow u$ and consider the Γ -limit of the whole energy with respect to that convergence. The combination of the weak interactions and the forcing term gives rise to a term of the form

$$\int_{\Omega} \varphi(u) dx$$

depending on the values of all components of u . In the case that $\bigcup_{j=1}^N C_j$ is all of \mathbb{Z}^d , the function $\varphi(z^1, \dots, z^N)$ is simply computed as the average of the T -periodic function

$$i \mapsto \sum_{k \in \mathbb{Z}^d} a_{ik} (u_i - u_k)^2 + g(u_i)$$

where u takes the value z^j on C_j . Note that with this condition only (weak) interactions between different C_j are taken into account. Note moreover that the restriction of the last term g to εC_j is continuously converging to

$$K_j \int_{\Omega} g(u^j) dx,$$

where $K_j = T^{-d} \#\{i \in C_j : i \in \{0, \dots, T\}^d\}$ is the percentage of sites in C_j . In general, φ is obtained by optimizing the combined effect of weak pair interactions and g on the free sites in the complement of all C_j .

Such different interactions can be summed up to describe the Γ -limit of F_ε that finally takes the form

$$F_{\text{hom}}(u) = \int_{S(u) \cap \Omega} f_{\text{hom}}(u^+, u^-, \nu_u) d\mathcal{H}^{d-1} + \int_{\Omega} \varphi(u) dx, \quad (5)$$

where $f_{\text{hom}}(u^+, u^-, \nu) = \frac{1}{2} \sum_{j=1}^N f_{\text{hom}}^j(\nu) |u_j^+ - u_j^-|$.

We note that the presence of two terms of different dimensions in the limit highlights the combination of bulk homogenization effects due to periodic oscillations besides the optimization of the interfacial structure. The effect of those oscillations on the variational motions of such systems (in the sense of [Ambrosio et al. 2008; Braides 2014b]) is addressed in [Braides and Solci 2015]. With respect to [Braides et al. 2015], we remark that the case of spin systems allows a very easy proof of an extension lemma from connected discrete sets and at the same time permits us to highlight the possibility to include a weak phase with antiferromagnetic interactions, optimized by microscopic oscillations.

Discrete problems modeling high-contrast media in the case of elastic energies have recently been considered in [Braides et al. 2015], but double-porosity homogenization in a continuum framework is a long-standing issue. The interest in double-porosity systems came at first from geophysics. The notion of double porosity, or double permeability, is borne from studies carried out on naturally fractured porous rocks such as oil fields. The benefits of describing oil flow and stock capacity in these kinds of soils justified theoretical studies undertaken during the 1960s. The double-porosity model was first introduced by [Barenblatt et al. 1960], and it has been used since in a wide range of engineering specialties. The first rigorous mathematical result on the subject was obtained in [Arbogast et al. 1990], where a linear parabolic equation with asymptotically degenerating coefficients was considered. This result was subsequently generalized in [Panasenکو 1991; Bourgeat et al. 1996; 1998; 1999; Sandrakov 1999a; 1999b; Pankratov and Piatnitski 2002; Marchenko and Khruslov 2006] also for nonperiodic domains and various rates of contrast. On the physical level of rigor, double-porosity models were studied in [Panfilov 2000]. Linear double-porosity models with thin fissures were considered in [Pankratov and Rybalko 2003; Amaziane et al. 2009b]. The singular double-porosity model was considered in [Bourgeat et al. 2003]. The works [Bourgeat et al. 1999; Marchenko and Khruslov 2006; Pankratov and Rybalko 2003; Amaziane et al. 2009b] are carried out in the framework of Khruslov's mesoscopic energy characteristic methods. In addition, note that the double-porosity model was also obtained using the two-scale convergence method in [Hornung 1997]. Elliptic and parabolic nonlinear double-porosity models, including homogenization in variable Sobolev spaces, were also obtained in [Pankratov et al. 2003; Amaziane et al. 2006; 2009a; Choquet and Pankratov 2010]. Finally, the double-porosity models of multiphase flows, including the nonequilibrium ones, were also obtained in [Choquet 2004; Yeh 2006; Amaziane and Pankratov 2016; Konyukhov and Pankratov 2015] (see also [Hornung 1997] and the references therein). A reformulation in terms of Γ -convergence can be found in [Braides et al. 2004] with related results for nonconvex integrands. An approach using Γ -convergence and a two-scale formulation at the same time is given in [Cherdantsev and Cherednichenko 2012]. Double-porosity models for interfacial energies on the continuum were previously examined in [Solci 2009; 2012; Braides and Solci 2013].

The results in the present paper may be regarded as a geometrically simplified model of continuum ones (but with more freedom in the lattice interactions), but the same framework may also be useful for other discrete models actually developed in mechanics. Among them are pantographic systems made of beams and used for modeling of some metamaterials [Seppecher et al. 2011] and investigations of two- and three-dimensional lattices in order to develop models used in nano- and micromechanics.

The plan of the paper is the following. In [Section 2](#), we introduce the geometric setting, identifying the “strong” and possibly “weak” phases of the lattice network, and define the microscopic energy. In [Section 3](#), we prove a compactness theorem and a homogenization result for each separate strong phase. The resulting energies will provide the interfacial energy part of the limit. In [Section 4](#), we define the interaction term between the strong phases by proving an asymptotic formula. The main convergence result is stated and proved in [Section 5](#), where the compactness theorem in [Section 3](#) applied to each strong phase is used to define a multiphase limit. Finally in [Section 6](#), some simple examples are provided, which in particular also exhibit nontrivial limits in dimensions 1 and 2.

2. Notation

The numbers d, m, T , and N are positive integers. We introduce a T -periodic *label function* $J : \mathbb{Z}^d \rightarrow \{0, 1, \dots, N\}$ and the corresponding sets of sites

$$A_j = \{k \in \mathbb{Z}^d : J(k) = j\}, \quad j = 0, \dots, N.$$

Sites interact through possibly long- (but finite-)range interactions, whose range is defined through a system $P^j = \{P_k^j\}$ of finite subsets $P_k^j \subset \mathbb{Z}^d$ for $j = 0, \dots, N$ and $k \in A_j$. We suppose

- (*T-periodicity*) $P_{k+m}^j = P_k^j$ for all $m \in T\mathbb{Z}^d$ and
- (*symmetry*) if $k \in A_j$ for $j = 1, \dots, N$ (*hard components*) and $i \in P_k^j$, then $k+i \in A_j$ and $-i \in P_{k+i}^j$, and $0 \in P_k^j$.

We say that two points $k, k' \in A_j$ are P^j -*connected* in A_j if there exists a path $\{k_n\}_{n=0, \dots, K}$ such that $k_n \in A_j$, $k_0 = k$, $k_K = k'$, and $k_n - k_{n-1} \in P_{k_{n-1}}^j$.

We suppose

- (*connectedness*) there exists a unique infinite P^j -connected component of each A_j for $j = 1, \dots, N$, which we denote by C_j .

Clearly, the connectedness assumption is not a modeling restriction upon introducing more labeling parameters if the number of infinite connected components is finite. Note that we do not make any assumptions on A_0 and P^0 . In particular, if $k \in A_j$ for $j = 0, \dots, N$ and $i \in P_k^0$, then $k+i$ may belong to any $A_{j'}$ with $j' \neq j$.

We consider the following sets of bonds between sites in \mathbb{Z}^d : for $j = 1, \dots, N$

$$N_j = \{(k, k') : k, k' \in A_j, k' - k \in P_k^j \setminus \{0\}\}$$

and for $j = 0$

$$N_0 = \{(k, k') : k' - k \in P_k^0 \setminus \{0\}, J(k)J(k') = 0 \text{ or } J(k) \neq J(k')\}.$$

Note that the set N_0 takes into account interactions not only among points of the set A_0 but also among pairs of points in different A_j . More refined notation could be introduced by defining a range of interactions P^{ij} and the corresponding sets N_{ij} , in which case the sets N_j would correspond to N_{jj} for $j = 1, \dots, N$ and N_0 to the union of the remaining sets. However, for simplicity of presentation, we limit our notation to a single index.

We consider interaction energy densities associated with positive numbers $a_{kk'}$ for $k, k' \in \mathbb{Z}^d$ and the forcing term g . We suppose that for all $k, k' \in \mathbb{Z}^d$

- (*coerciveness on the hard phase*) there exists $c > 0$ such that $a_{kk'} \geq c > 0$ if $k \in C_j$ and $k' - k \in P_k^j$ for $j \geq 1$,
- (*T-periodicity*) $a_{k+m, k'+m} = a_{kk'}$ for all $m \in T\mathbb{Z}^d$,
- (*symmetry*) $a_{k'k} = a_{kk'}$, and
- (*T-periodicity of the forcing term*) $g(k+m, 1) = g(k, 1)$ and $g(k+m, -1) = g(k, -1)$ for all $m \in T\mathbb{Z}^d$.

Note that we do not suppose that the $a_{kk'}$ are positive for weak interactions. They can be negative as well, thus favoring oscillations in the weak phase.

Given Ω , a bounded regular open subset of \mathbb{R}^d , for $u : (1/\varepsilon)\Omega \cap \mathbb{Z}^d \rightarrow \{+1, -1\}$, we define the energies

$$F_\varepsilon(u) = F_\varepsilon\left(u, \frac{1}{\varepsilon}\Omega\right) = \sum_{j=1}^N \sum_{(k, k') \in \mathcal{N}_j^\varepsilon(\Omega)} \varepsilon^{d-1} a_{kk'} (u_k - u_{k'})^2 + \sum_{(k, k') \in \mathcal{N}_0^\varepsilon(\Omega)} \varepsilon^d a_{kk'} (u_k - u_{k'})^2 + \sum_{k \in \mathbb{Z}^\varepsilon(\Omega)} \varepsilon^d g(k, u_k), \quad (6)$$

where

$$\mathcal{N}_j^\varepsilon(\Omega) = N_j \cap \frac{1}{\varepsilon}(\Omega \times \Omega), \quad j = 0, \dots, N, \quad \mathbb{Z}^\varepsilon(\Omega) = \mathbb{Z}^d \cap \frac{1}{\varepsilon}\Omega. \quad (7)$$

The first sum in the energy takes into account all interactions between points in A_j (*hard phases*), which are supposed to scale differently than those between points in A_0 (*soft phase*) or between points in different phases. The latter are contained in the second sum. The third sum is a zero-order term taking into account all types of phases with the same scaling.

Note that the first sum may also take into account points in $A_j \setminus C_j$, which form “islands” of the hard phase P^j -disconnected from the corresponding infinite component. Furthermore, in this energy, we may have sites that do not interact at all with hard phases.

Remark 2.1 (choice of the parameter space). The energy is defined on discrete functions parametrized on $(1/\varepsilon)\Omega \cap \mathbb{Z}^d$. The choice of this notation, rather than interpreting u as defined on $\Omega \cap \varepsilon\mathbb{Z}^d$, allows a much easier notation for the coefficients, which in this way are ε -independent rather than obtained by scaling as in (2).

3. Homogenization of perforated discrete domains

In this section, we separately consider the interactions in each infinite connected component of the hard phases introduced above. To that end, we fix one of the indices j , with $j > 0$, dropping it in the notation of this section (in particular, we use the symbol C in place of C_j , etc.), and define the energies

$$\mathcal{F}_\varepsilon(u) = \mathcal{F}_\varepsilon\left(u, \frac{1}{\varepsilon}\Omega\right) = \sum_{(k,k') \in N_C^\varepsilon(\Omega)} \varepsilon^{d-1} a_{kk'} (u_k - u_{k'})^2, \quad (8)$$

where

$$N_C^\varepsilon(\Omega) = \left\{ (k, k') \in (C \times C) \cap \frac{1}{\varepsilon}(\Omega \times \Omega) : k' - k \in P_k, k \neq k' \right\}. \quad (9)$$

We also introduce the notation $C^\varepsilon(\Omega) = C \cap (1/\varepsilon)\Omega$.

Definition 3.1. We define the *piecewise-constant interpolation* of a function $u : \mathbb{Z}^d \cap (1/\varepsilon)\Omega \rightarrow \mathbb{R}^m$, $k \mapsto u_k$, as

$$u(x) = u_{\lfloor x/\varepsilon \rfloor},$$

where $\lfloor y \rfloor = (\lfloor y_1 \rfloor, \dots, \lfloor y_d \rfloor)$ and $\lfloor s \rfloor$ stands for the integer part of s . The *convergence* of a sequence (u^ε) of discrete functions is understood as the $L^1_{\text{loc}}(\Omega)$ convergence of these piecewise-constant interpolations. Note that, since we consider local convergence in Ω , the value of $u(x)$ close to the boundary is not involved in the convergence process.

We prove an extension and compactness lemma with respect to the convergence of piecewise-constant interpolations.

Lemma 3.2 (extension and compactness). *Let C be a T -periodic subset of \mathbb{Z}^d P -connected in the notation of the previous section, and let $u^\varepsilon : \mathbb{Z}^d \cap (1/\varepsilon)\Omega \rightarrow \{+1, -1\}$ be a sequence such that*

$$\sup_\varepsilon \varepsilon^{d-1} \#\{(k, k') \in N_C^\varepsilon(\Omega) : u_k^\varepsilon \neq u_{k'}^\varepsilon\} < +\infty. \quad (10)$$

Then there exists a sequence $\tilde{u}^\varepsilon : \mathbb{Z}^d \cap (1/\varepsilon)\Omega \rightarrow \mathbb{R}^m$ such that $\tilde{u}_k^\varepsilon = u_k^\varepsilon$ if $k \in C^\varepsilon(\Omega)$ and $\text{dist}(k, \partial(1/\varepsilon)\Omega) > c = c(P)$ with \tilde{u}^ε converging to some $u \in \text{BV}_{\text{loc}}(\Omega; \{+1, -1\})$ up to subsequences.

Proof. For a fixed $M \in \mathbb{N}$ and $j \in \mathbb{Z}^d$, we consider the discrete cubes of side length M

$$Q_M(j) := jM + \{0, M-1\}^d.$$

For each j , we also define the cube

$$Q'_{3M}(j) = \bigcup_{\|i-j\|_\infty \leq 1} Q_M(i),$$

which is a discrete cube centered at $Q_M(j)$ and with side length $3M$.

For all ε , we consider the family

$$\mathcal{Q}_M^\varepsilon := \left\{ Q_M(j) : j \in \mathbb{Z}^d, Q'_{3M}(j) \subset \frac{1}{\varepsilon} \Omega \right\}.$$

We suppose that M is large enough such that, if $k, k' \in Q_M(j) \cap C$, then there exists a P -path connecting k and k' contained in $Q'_{3M}(j)$. The existence of such M follows easily from the connectedness hypotheses. Indeed, we may take M as the length of the longest shortest P -path connecting two points in C with distance not greater than $2\sqrt{d}$ (in particular belonging to neighboring periodicity cubes) and construct such a P -path by concatenating a family of those shortest paths.

We define the set of indices

$$\mathcal{S}_\varepsilon = \{j \in \mathbb{Z}^d : Q_M(j) \in \mathcal{Q}_M^\varepsilon \text{ and } u^\varepsilon \text{ is not constant on } C \cap Q_M(j)\}.$$

By our choice of M , if $j \in \mathcal{S}_\varepsilon$, then there exist $k, k' \in Q'_{3M}(j) \cap C$ with $k' - k \in P$ such that $u_k^\varepsilon \neq u_{k'}^\varepsilon$. Let

$$K := \sup_\varepsilon \varepsilon^{d-1} \#\{(k, k') \in N_C^\varepsilon(\Omega) : u_k^\varepsilon \neq u_{k'}^\varepsilon\}.$$

Then we deduce that

$$\#\mathcal{S}_\varepsilon \leq 3^d K \frac{1}{\varepsilon^{d-1}} \quad (11)$$

(the factor 3^d comes from the fact that $k, k' \in Q'_{3M}(j)$ for 3^d possible j).

We define

$$\tilde{u}^\varepsilon = \begin{cases} \text{constant value of } u^\varepsilon \text{ on } Q_M(j) \cap C & \text{on } Q_M(j) \text{ if } Q_M(j) \in \mathcal{Q}_M^\varepsilon \text{ and } j \notin \mathcal{S}_\varepsilon, \\ u^\varepsilon & \text{elsewhere.} \end{cases}$$

This will be the required extension. However, we will prove the convergence of \tilde{u}^ε as a consequence of the convergence of the functions

$$v^\varepsilon = \begin{cases} \tilde{u}^\varepsilon & \text{on } Q_M(j) \text{ if } Q_M(j) \in \mathcal{Q}_M^\varepsilon \text{ and } j \notin \mathcal{S}_\varepsilon, \\ 1 & \text{elsewhere.} \end{cases}$$

By (11), we have that for fixed $\Omega' \Subset \Omega$

$$\|v^\varepsilon - \tilde{u}^\varepsilon\|_{L^1(\Omega')} = O(\varepsilon)$$

(recall that we identify the function with its scaled interpolations in $L^1(\Omega)$).

If the value of v^ε differs on two neighboring $Q_M(j)$ and $Q_M(j')$ with $\|j - j'\|_1 = 1$, then upon taking a suitable larger M , we may also suppose that there exist

$k, k' \in (Q'_{3M}(j) \cup Q'_{3M}(j)) \cap C$ with $k - k' \in P$ and $u_k^\varepsilon \neq u_{k'}^\varepsilon$. Arguing as for (11), we deduce that the number of such j is $O(\varepsilon^{1-d})$ so that

$$\mathcal{H}^{d-1}(\partial\{v^\varepsilon = 1\} \cap \Omega') = O(1),$$

which implies the compactness of the family (v^ε) in $BV_{\text{loc}}(\Omega)$. \square

The compactness theorem above proves that the domain of the limit is functions $u \in BV(\Omega, \{+1, -1\})$, which can be identified with the *sets of finite perimeter* $E = \{u = 1\}$. In this case, the set of discontinuity points $S(u)$ coincides, up to sets of \mathcal{H}^{n-1} -measure 0, with the *reduced boundary* $\partial^*\{u = 1\}$, whose *inner normal* we denote by ν [Braides 1998].

Theorem 3.3 (homogenization on discrete perforated domains). *The energies \mathcal{F}_ε defined in (8) Γ -converge with respect to the $L^1_{\text{loc}}(\Omega)$ topology to the energy*

$$\bar{\mathcal{F}}_{\text{hom}}(u) = \int_{\Omega \cap \partial^*\{u=1\}} f_{\text{hom}}(\nu) d\mathcal{H}^{d-1}, \quad (12)$$

defined on $u \in BV(\Omega, \{+1, -1\})$, where the energy density f_{hom} satisfies

$$f_{\text{hom}}(\nu) = \lim_{T \rightarrow +\infty} \frac{1}{T^{d-1}} \inf \left\{ \sum_{(k,k') \in \tilde{N}_C(Q_T^\nu)} a_{kk'} (u_k - u_{k'})^2 : u_k = \text{sign}\langle k, \nu \rangle \text{ if } k \notin Q_T^\nu \right\}, \quad (13)$$

where

$$\text{sign } x = \begin{cases} 1 & \text{if } x > 0, \\ -1 & \text{if } x \leq 0, \end{cases} \quad (14)$$

Q_T^ν is a cube centered at 0 and with one side orthogonal to ν , $Q_T^\nu = T Q^\nu$, and $\tilde{N}_C(Q_T^\nu)$ denotes all pairs in $(k, k') \in N_C^1(\mathbb{R}^d)$ such that either $k \in Q_T^\nu$ or $k' \in Q_T^\nu$.

Proof. In [Braides and Piatnitski 2013], this theorem is proved under the additional assumption that the energies \mathcal{F}_ε are equicoercive with respect to the weak BV-convergence. This assumption can be substituted with Lemma 3.2. Indeed, if u^ε is a sequence converging to u in $L^1_{\text{loc}}(\Omega)$ and with equibounded energies, then by Lemma 3.2, we may find a sequence \tilde{u}^ε coinciding with u^ε on $C^\varepsilon(\Omega')$ for every fixed $\Omega' \Subset \Omega$ and ε sufficiently small and converging to some \tilde{u} in $BV(\Omega; \{\pm 1\})$. Since $\tilde{u}^\varepsilon = u^\varepsilon$ on $C^\varepsilon(\Omega')$, we have that $\tilde{u} = u$ and $\mathcal{F}_\varepsilon(\tilde{u}^\varepsilon, (1/\varepsilon)\Omega') = \mathcal{F}_\varepsilon(u^\varepsilon, (1/\varepsilon)\Omega')$. Then we can give a lower estimate on each Ω' fixed using the proof of [Braides and Piatnitski 2013] and hence on Ω by internal approximation. Note that neither the proof of the existence of the limit in (13) therein nor the construction of the recovery sequences depends on the coerciveness assumption, so the proof is complete. \square

4. Definition of the interaction term

The homogenization result in [Theorem 3.3](#) will describe the contribution of the hard phases to the limiting behavior of energies F_ε . We now characterize their interactions with the soft phase.

For all positive integers M and $z_1, \dots, z_N \in \{+1, -1\}$, we define the minimum problem

$$\varphi_M(z_1, \dots, z_N) = \frac{1}{M^d} \min \left\{ \sum_{(k,k') \in N_0(Q_M)} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M)} g(k, v_k) : v \in \mathcal{V}_M \right\},$$

where

$$Q_M = \left[-\frac{M}{2}, \frac{M}{2} \right)^d, \quad N_0(Q_M) = N_0 \cap (Q_M \times Q_M), \quad Z(Q_M) = \mathbb{Z}^d \cap Q_M \quad (15)$$

and the minimum is taken over the set $\mathcal{V}_M = \mathcal{V}_M(z_1, \dots, z_N)$ of all v constant on each connected component of $A_j \cap Q_M$ and $v = z_j$ on C_j for $j = 1, \dots, N$.

Proposition 4.1. *The limit φ of φ_M as $M \rightarrow +\infty$ exists.*

Proof. We first show that

$$\varphi_{KM} \geq \varphi_M \quad \text{for all } K \in \mathbb{N}. \quad (16)$$

To that end, let \bar{v} be a minimizer for $\varphi_{KM}(z_1, \dots, z_N)$. Then we have

$$\begin{aligned} & K^d M^d \varphi_{KM}(z_1, \dots, z_N) \\ &= \sum_{(k,k') \in N_0(Q_{KM})} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 + \sum_{k \in Z(Q_{KM})} g(k, \bar{v}_k) \\ &= \sum_{l \in \mathbb{Z}^d \cap Q_K} \left(\sum_{(k,k') \in N_0(Q_M + lM)} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 + \sum_{k \in Z(Q_M + lM)} g(k, \bar{v}_k) \right) \\ &\quad + \sum_{(k,k') \in N_0(Q_{KM}) \setminus \bigcup_l N_0(Q_M + lM)} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 \\ &\geq \sum_{l \in \mathbb{Z}^d \cap Q_K} \left(\sum_{(k,k') \in N_0(Q_M + lM)} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 + \sum_{k \in Z(Q_M + lM)} g(k, \bar{v}_k) \right). \end{aligned}$$

Let $\bar{l} \in \mathbb{Z}^d \cap Q_K$ minimize the expression in parentheses. Then we deduce

$$K^d M^d \varphi_{KM}(z_1, \dots, z_N) \geq K^d \left(\sum_{(k,k') \in N_0(Q_M + \bar{l}M)} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 + \sum_{k \in Z(Q_M + \bar{l}M)} g(k, \bar{v}_k) \right),$$

from which (16) follows by taking $v_k = \bar{v}_{k - \bar{l}M}$ in the computation of $\varphi_M(z_1, \dots, z_N)$.

We remark that for $L \geq L'$ we have

$$L^d \varphi_L \geq (L')^d \varphi_{L'} - \max|g|(L^d - (L')^d). \quad (17)$$

Hence, fixing n , L , and M with $L \geq M2^n$ and taking $L' = \lfloor L/(M2^n) \rfloor M2^n$ in (17), we have, using (16) with $K = \lfloor L/(M2^n) \rfloor 2^n$

$$\begin{aligned} \varphi_L &\geq \frac{1}{L^d} \left(\left\lfloor \frac{L}{M2^n} \right\rfloor M2^n \right)^d \varphi_{\lfloor L/(M2^n) \rfloor M2^n} - \max|g| \left(1 - \left(\left\lfloor \frac{L}{M2^n} \right\rfloor \frac{M2^n}{L} \right)^d \right) \\ &\geq \left(\left\lfloor \frac{L}{M2^n} \right\rfloor \frac{M2^n}{L} \right)^d \varphi_M - \max|g| \left(1 - \left(\left\lfloor \frac{L}{M2^n} \right\rfloor \frac{M2^n}{L} \right)^d \right). \end{aligned}$$

Letting $L \rightarrow +\infty$, we then obtain

$$\liminf_{L \rightarrow +\infty} \varphi_L \geq \varphi_M$$

and the conclusion follows by taking the upper limit in M . \square

Let R be defined by

$$R = \max\{|k - k'| : k, k' \in A_j \setminus C_j \text{ that are } P^j\text{-connected, } j = 1, \dots, N\}, \quad (18)$$

and for all M positive integer, set

$$D_M = \bigcup_{j=1}^N \bigcup \{P^j\text{-connected components } B \text{ of } A_j \setminus C_j \text{ not intersecting } Q_{M-R}\}.$$

For all $z_1, \dots, z_N \in \{+1, -1\}$, we define

$$\begin{aligned} \tilde{\varphi}_M(z_1, \dots, z_N) &= \frac{1}{M^d} \min \left\{ \sum_{(k,k') \in N_0(Q_M)} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M)} g(k, v_k) \right. \\ &\quad \left. : v \in \mathcal{V}_M, v_k = 1 \text{ if } k \in D_M \right\}. \quad (19) \end{aligned}$$

Proposition 4.2. *There is a positive constant c independent of M such that*

$$\tilde{\varphi}_M \geq \varphi_M \geq \tilde{\varphi}_M - \frac{c}{M}. \quad (20)$$

Proof. The first inequality is trivial. To prove the second, let \bar{v} be a minimizer for $\varphi_M(z_1, \dots, z_N)$ and define v by

$$v_k = \begin{cases} 1 & \text{if } k \in D_M \\ \bar{v}_k & \text{otherwise.} \end{cases}$$

Using v as a test function for $\tilde{\varphi}_M(z_1, \dots, z_N)$, we obtain

$$\begin{aligned}
M^d \tilde{\varphi}_M(z_1, \dots, z_N) &\leq \sum_{(k,k') \in N_0(Q_M), k, k' \notin D_M} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M) \setminus D_M} g(k, v_k) \\
&\quad + 2 \sum_{(k,k') \in N_0(Q_M), k \in D_M} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M) \cap D_M} g(k, v_k) \\
&\leq \sum_{(k,k') \in N_0(Q_M), k, k' \notin D_M} a_{kk'} (\bar{v}_k - \bar{v}_{k'})^2 + \sum_{k \in Z(Q_M) \setminus D_M} g(k, \bar{v}_k) \\
&\quad + \sum_{(k,k') \in N_0(Q_M), k \in D_M} a_{kk'} + \sum_{k \in Z(Q_M) \cap D_M} g(k, 1) \\
&\leq M^d \varphi_M(z_1, \dots, z_N) + \#D_M \#P_0 \max a_{ij} + \#D_M 2 \max |g|.
\end{aligned}$$

As $\#D_M \leq 2^d M^{d-1} R$, the result follows with $c = 2^d R(\#P_0 \max a_{ij} + 2 \max |g|)$. \square

5. Statement of the convergence result

We now have all the ingredients to characterize the asymptotic behavior of F_ε defined in (6).

Definition 5.1 (multiphase discrete-to-continuum convergence). We define the *convergence*

$$u^\varepsilon \rightarrow (u^1, \dots, u^N) \quad (21)$$

as the $L^1_{\text{loc}}(\Omega; \mathbb{R}^m)$ convergence $\tilde{u}_j^\varepsilon \rightarrow u^j$ of the extensions of the restrictions of u^ε to C_j as in Lemma 3.2, which is a compact convergence as ensured by that lemma.

The total contribution of the hard phases will be given separately by the contribution on the infinite connected components and the finite ones. The first one is obtained by independently computing the limit relative to the energy restricted to each component

$$\mathfrak{F}_\varepsilon^j(u) = \sum_{(k,k') \in N_j^\varepsilon(\Omega)} \varepsilon^{d-1} a_{kk'} (v_k - v_{k'})^2, \quad (22)$$

where

$$N_j^\varepsilon(\Omega) = N_{C_j}^\varepsilon(\Omega) = \left\{ (k, k') \in (C_j \times C_j) \cap \frac{1}{\varepsilon}(\Omega \times \Omega) : k - k' \in P_k^j, k \neq k' \right\}, \quad (23)$$

which is characterized by Theorem 3.3 as

$$\mathfrak{F}_{\text{hom}}^j(u) = \int_{\Omega \cap \partial^* \{u=1\}} f_{\text{hom}}^j(v) d\mathcal{H}^{d-1}. \quad (24)$$

In Section 4, we introduced the energy density φ , which describes the interactions between the hard phases. Taking all contributions into account, we may state the following convergence result.

Theorem 5.2 (double-porosity homogenization). *Let Ω be a Lipschitz bounded open set, and let F_ε be defined by (6) with the notation of Section 2. Then the Γ -limit of F_ε with respect to the convergence (21) exists, and it equals*

$$F_{\text{hom}}(u^1, \dots, u^N) = \sum_{j=1}^N \int_{\Omega \cap \partial^* \{u^j=1\}} f_{\text{hom}}^j(v) d\mathcal{H}^{d-1} + \int_{\Omega} \varphi(u^1, \dots, u^N) dx \quad (25)$$

on functions $u = (u^1, \dots, u^N) \in (\text{BV}(\Omega; \{1, -1\}))^N$, where φ is defined in Proposition 4.1 and f_{hom}^j are defined by (24).

Note that there is no contribution of the finite connected components of A_j .

Remark 5.3 (nonhomogeneous lower-order term). In our hypotheses, the lower-order term g depends on the fast variable k , which is integrated out in the limit. We may easily include a measurable dependence on the slow variable εk by assuming $g = g(x, k, z)$ is a Carathéodory function (this covers in particular the case $g = g(x, z)$) and substitute the last sum in (6) by

$$\sum_{k \in Z^\varepsilon(\Omega)} \varepsilon^d g(\varepsilon k, k, u_k).$$

Correspondingly, in Theorem 5.2, the integrand in the last term in (25) must be substituted by $\varphi(x, u^1, \dots, u^N)$, where the definition of this last function is the same but taking $g(x, k, z)$ in place of $g(k, z)$ so that x simply acts as a parameter.

The proof of Theorem 5.2 will be subdivided into a lower and an upper bound.

Proof of the lower bound. Let $u^\varepsilon \rightarrow (u^1, \dots, u^N)$ be such that $F_\varepsilon(u^\varepsilon) \leq c < +\infty$. Fixing $M \in \mathbb{N}$, we introduce the notation

$$\begin{aligned} J_M^\varepsilon &= \left\{ z \in \mathbb{Z}^d : Q_M + zM \subset \frac{1}{\varepsilon} \Omega \right\}, \\ R^\varepsilon &= \mathcal{N}_0^\varepsilon(\Omega) \setminus \bigcup_{z \in J_M^\varepsilon} \mathcal{N}_0^\varepsilon(Q_M + zM), \\ S^\varepsilon &= Z^\varepsilon(\Omega) \setminus \bigcup_{z \in J_M^\varepsilon} Z(Q_M + zM) \end{aligned}$$

and write

$$F_\varepsilon(u^\varepsilon) = \sum_{j=1}^N \text{I}_j^\varepsilon + \text{II}^\varepsilon + \text{III}^\varepsilon + \text{IV}^\varepsilon + \text{V}^\varepsilon,$$

where

$$\text{I}_j^\varepsilon = \mathcal{F}_\varepsilon^j(u),$$

$$\begin{aligned}
\text{II}^\varepsilon &= \sum_{j=1}^N \sum_{(k,k') \in \mathcal{N}_j^\varepsilon(\Omega) \setminus (C_j \times C_j)} \varepsilon^{d-1} a_{kk'} (v_k - v_{k'})^2, \\
\text{III}^\varepsilon &= \sum_{z \in J_M^\varepsilon} \varepsilon^d \left(\sum_{(k,k') \in \mathcal{N}_0^\varepsilon(Q_M + zM)} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M + zM)} g(k, v_k) \right), \\
\text{IV}^\varepsilon &= \sum_{(k,k') \in R^\varepsilon} \varepsilon^d a_{kk'} (v_k - v_{k'})^2, \\
\text{V}^\varepsilon &= \sum_{k \in S^\varepsilon} \varepsilon^d g(k, v_k).
\end{aligned}$$

Note that

$$\begin{aligned}
\text{II}^\varepsilon &\geq 0, \\
\text{IV}^\varepsilon &\geq -c/M + o(1), \\
\text{V}^\varepsilon &\geq -\max |g| \left(\left| \Omega \setminus \varepsilon^d \bigcup_{z \in J_M^\varepsilon} (Q_M + zM) \right| + o(1) \right),
\end{aligned} \tag{26}$$

where we have taken into account that the interactions in IV^ε may be negative and

$$\liminf_{\varepsilon \rightarrow 0} \sum_{j=1}^N \text{I}_j^\varepsilon \geq \sum_{j=1}^N \liminf_{\varepsilon \rightarrow 0} \text{I}_j^\varepsilon \geq \sum_{j=1}^N \int_{\Omega \cap \partial^* \{u^j=1\}} f_{\text{hom}}^j(v) d\mathcal{H}^{d-1}. \tag{27}$$

It remains to estimate III^ε . To that end, we introduce the set of indices

$$\Lambda_M^\varepsilon = \{z \in J_M^\varepsilon : u^\varepsilon \text{ constant on every connected component of } A_j \cap (Q_{3M} + zM), \\ j = 1, \dots, N\}.$$

Note that

$$\#(J_M^\varepsilon \setminus \Lambda_M^\varepsilon) \leq \frac{cM}{\varepsilon^{d-1}}. \tag{28}$$

We then write

$$\begin{aligned}
\text{III}^\varepsilon &= \sum_{z \in \Lambda_M^\varepsilon} \varepsilon^d \left(\sum_{(k,k') \in \mathcal{N}_0^\varepsilon(Q_M + zM)} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M + zM)} g(k, v_k) \right) \\
&\quad + \sum_{z \in J_M^\varepsilon \setminus \Lambda_M^\varepsilon} \varepsilon^d \left(\sum_{(k,k') \in \mathcal{N}_0^\varepsilon(Q_M + zM)} a_{kk'} (v_k - v_{k'})^2 + \sum_{k \in Z(Q_M + zM)} g(k, v_k) \right) \\
&\geq \sum_{z \in \Lambda_M^\varepsilon} \varepsilon^d M^d \varphi_M(u_1^\varepsilon, \dots, u_N^\varepsilon) - c\varepsilon^d M^d \max(|g| + |a_{kk'}|) \#(J_M^\varepsilon \setminus \Lambda_M^\varepsilon),
\end{aligned}$$

where u_j^ε is the constant value taken by u^ε on $(Q_M + zM) \cap C_j$. Here we suppose M is large enough so that the connected component of C_j containing $(Q_M + zM) \cap C_j$

is connected in $Q_{3M} + zM$. We set

$$U^\varepsilon = \sum_{z \in \Lambda_M^\varepsilon} (u_1^\varepsilon, \dots, u_N^\varepsilon) \chi_{Q_M + zM}$$

and $\varphi_M(0, \dots, 0) = 0$. Note that $U^\varepsilon \rightarrow U := (u^1, \dots, u^N)$ in $L^1(\Omega)^N$ so that

$$\liminf_{\varepsilon \rightarrow 0} \text{III}^\varepsilon \geq \liminf_{\varepsilon \rightarrow 0} \left(\int_{\Omega} \varphi_M(U^\varepsilon) dx - \varepsilon \max |g| c_M M^d \right) = \int_{\Omega} \varphi_M(U) dx \quad (29)$$

by the Lebesgue dominated convergence theorem and the estimate (28).

Summing up the inequalities (26), (27), and (29), we get

$$\liminf_{\varepsilon \rightarrow 0} F_\varepsilon(u^\varepsilon) \geq \sum_{j=1}^N \int_{\Omega \cap \partial^* \{u^j=1\}} f_{\text{hom}}^j(v) d\mathcal{H}^{d-1} + \int_{\Omega} \varphi_M(U) dx. \quad (30)$$

The lower-bound inequality then follows by taking the limit as $M \rightarrow +\infty$, using Proposition 4.1 and the Lebesgue dominated convergence theorem. \square

Proof of the upper bound. We fix $U = (u^1, \dots, u^N) \in \text{BV}(\Omega; \{1, -1\})^N$. For every $j = 1, \dots, N$, we choose $u^{j,\varepsilon} \rightarrow u^j$ a recovery sequence for $\mathcal{F}_{\text{hom}}^j(u^j)$. We tacitly extend all functions defined on $Z^\varepsilon(\Omega)$ to all of \mathbb{Z}^d with the value $+1$ outside $Z^\varepsilon(\Omega)$. This does not affect the value of the energies but allows us to rigorously define some sets of indices z in the sequel.

We fix $M \in \mathbb{N}$ large enough. As in Section 4, we introduce the sets of indices

$$\tilde{J}_M^\varepsilon = \left\{ z \in \mathbb{Z}^d : (Q_M + zM) \cap \frac{1}{\varepsilon} \Omega \neq \emptyset \right\},$$

$$\Lambda_M^{j,\varepsilon} = \{ z \in J_M^\varepsilon : u^\varepsilon \text{ constant on every connected component of } A_j \cap (Q_{3M} + zM) \}$$

and give the estimate

$$\sum_{j=1}^N \#(\tilde{J}_M^\varepsilon \setminus \Lambda_M^{j,\varepsilon}) \leq \frac{cM}{\varepsilon^{d-1}}. \quad (31)$$

Note that, if $z \in \bigcap_{j=1}^N \Lambda_M^{j,\varepsilon}$, then $u^{j,\varepsilon} =: u^{j,\varepsilon,z}$ is constant on $C_j \cap (Q_M + zM)$ for $j = 1, \dots, N$. Let $v^{\varepsilon,z}$ be a minimizer for $\tilde{\varphi}_M(u^{1,\varepsilon,z}, \dots, u^{N,\varepsilon,z})$.

We define

$$u_k^\varepsilon = \begin{cases} u_k^{j,\varepsilon} & \text{if } k \in C_j, j = 1, \dots, N, \\ v^{\varepsilon,z}(k - zM) & \text{if } k \in Q_M + zM \text{ and } z \in \bigcap_{j=1}^N \Lambda_M^{j,\varepsilon}, \\ 1 & \text{otherwise.} \end{cases}$$

We first estimate the energy on the strong connections. By the definition of $u^{j,\varepsilon}$, we have for all $j = 1, \dots, N$

$$\lim_{\varepsilon \rightarrow 0} \sum_{(k,k') \in \mathcal{N}_j^\varepsilon(\Omega) \cap (C_j \times C_j)} \varepsilon^{d-1} a_{kk'} (u_k^\varepsilon - u_{k'}^\varepsilon)^2 = \mathcal{F}_{\text{hom}}^j(u^j) \quad (32)$$

since $u^\varepsilon = u^{j,\varepsilon}$ on C_j . On the strong connections between points not in the infinite connected components C_j ,

$$\sum_{(k,k') \in \mathcal{N}_j^\varepsilon(\Omega) \setminus (C_j \times C_j)} \varepsilon^{d-1} a_{kk'} (u_k^\varepsilon - u_{k'}^\varepsilon)^2 = 0 \quad (33)$$

since u^ε is constant on every connected component of $A_j \setminus C_j$. Note that here we have used the condition that $v^{\varepsilon,z} = 1$ on D_M in the definition of $\tilde{\varphi}_M$.

We then examine the contribution due to the interaction between weak connections and the term g . We first look at the contributions on the cubes in the sets $\Lambda_M^{j,\varepsilon}$, where we can use the definition of $\tilde{\varphi}_M$: for every $z \in \bigcap_{j=1}^N \Lambda_M^{j,\varepsilon}$,

$$\sum_{(k,k') \in \mathcal{N}_0^\varepsilon(Q_M + zM)} a_{kk'} (u_k^\varepsilon - u_{k'}^\varepsilon)^2 + \sum_{k \in Z(Q_M + zM)} g(k, u_k^\varepsilon) = \tilde{\varphi}_M(u^{1,\varepsilon,z}, \dots, u^{N,\varepsilon,z}).$$

The contributions interior to all other cubes in \tilde{J}_M^ε sum up to

$$\begin{aligned} \sum_{z \notin \bigcap_{j=1}^N \Lambda_M^{j,\varepsilon}} \varepsilon^d \left(\sum_{(k,k') \in \mathcal{N}_0^\varepsilon(Q_M + zM)} a_{kk'} (u_k^\varepsilon - u_{k'}^\varepsilon)^2 + \sum_{k \in Z(Q_M + zM)} g(k, u_k^\varepsilon) \right) \\ \leq \varepsilon^d M^d (\#P_0 \max a_{il} + \max |g|) \sum_{j=1}^N \#(J_M^\varepsilon \setminus \Lambda_M^{j,\varepsilon}) \\ \leq \varepsilon M^d c'_M + o(1) \end{aligned} \quad (34)$$

by (31) and the fact that the boundary of Ω has zero measure. Finally, the contribution due to the weak connection across the boundary of neighboring cubes is given by

$$\begin{aligned} \sum_{z \neq z' \in \bigcap_{j=1}^N \Lambda_M^{j,\varepsilon}} \varepsilon^d \sum_{(k,k') \in \mathcal{N}_0^\varepsilon(\Omega), k \in Q_M + zM, k' \in Q_M + z'M} a_{kk'} (u_k^\varepsilon - u_{k'}^\varepsilon)^2 \\ \leq \varepsilon^d M^{d-1} \#J_M^\varepsilon \#P_0 \max a_{il} \leq \#P_0 \max a_{il} \frac{|\Omega|}{M}. \end{aligned}$$

From the inequalities above, we obtain

$$\limsup_{\varepsilon \rightarrow 0} F_\varepsilon(u^\varepsilon) \leq \sum_{j=1}^N \mathcal{F}_{\text{hom}}^j(u^j) + \int_{\Omega} \tilde{\varphi}_M(u^1, \dots, u^N) dx + \#P_0 \max a_{il} \frac{|\Omega|}{M}.$$

Letting $M \rightarrow +\infty$ and using Propositions 4.2 and 4.1 then gives the result. \square

6. Examples

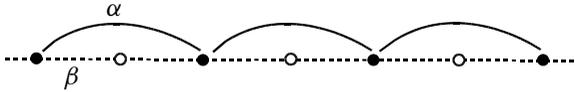
In the pictures in the following examples, weak connections are denoted by a dashed line and strong connections by a continuous line.

6.1. One-dimensional examples. In this section, we consider easy one-dimensional examples, highlighting the possibility of double-porosity behavior if long-range interactions are allowed, contrary to the continuum case. We use a slightly different notation than above, with the sums depending only on one index. The factor $\frac{1}{4}$ is just a normalization since $(u_i - u_j)^2$ is always a multiple of 4.

Example 6.1 (weak inclusions on alternating lattice). Consider a system of weak nearest-neighbor interactions and strong next-to-nearest-neighbor interactions on the even-odd lattice (see figure below); namely,

$$F_\varepsilon(u) = \frac{\beta}{4} \sum_{i=1}^{N_\varepsilon} \varepsilon(u_i - u_{i-1})^2 + \frac{\alpha}{4} \sum_{j=1}^{N_\varepsilon/2-1} (u_{2j+1} - u_{2j-1})^2 + \sum_{i=1}^{N_\varepsilon} \varepsilon g(u_i),$$

where we assume that $\Omega = [0, 1]$ and $N_\varepsilon = 1/\varepsilon \in 2\mathbb{N}$. In this case $N = 1$, $A_1 = C_1 = 1 + 2\mathbb{N}$, and $A_0 = 2\mathbb{N}$.

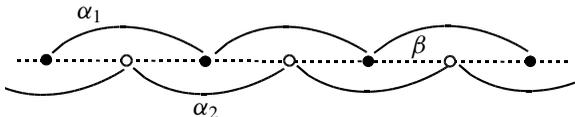


The Γ -limit is

$$\begin{aligned} F_{\text{hom}}(u) &= \alpha \#S(u) + \frac{1}{2} \int_0^1 g(u) \, dx + \frac{1}{2} \int_0^1 \min\{g(u), g(-u) + 2\beta\} \, dx \\ &= \alpha \#S(u) + \int_0^1 g(u) \, dx - \frac{1}{2} \int_0^1 \max\{0, g(u) - g(-u) - 2\beta\} \, dx. \end{aligned}$$

The last term favors states with the same value on A_0 and A_1 if the integrand is 0 and of opposite sign if the integrand is positive. Note that this is always the case if we have a strong-enough “antiferromagnetic” nearest-neighbor interaction, i.e., β is negative and $2|\beta| > |g(1) - g(-1)|$.

Example 6.2 (interacting sublattices). Consider a system of weak nearest-neighbor interactions and strong next-to-nearest-neighbor interactions:



Here

$$F_\varepsilon(u) = \frac{\beta}{4} \sum_{i=1}^{N_\varepsilon} \varepsilon(u_i - u_{i-1})^2 + \frac{\alpha_1}{4} \sum_{j=1}^{N_\varepsilon/2-1} (u_{2j+1} - u_{2j-1})^2 \\ + \frac{\alpha_2}{4} \sum_{j=0}^{N_\varepsilon/2-1} (u_{2j+2} - u_{2j})^2 + \sum_{i=1}^{N_\varepsilon} \varepsilon g(u_i),$$

where we assume that $N_\varepsilon = 1/\varepsilon \in 2\mathbb{N}$. In this case, $N = 2$, $A_1 = C_1 \stackrel{i=1}{=} 1 + 2\mathbb{N}$, $A_2 = C_2 = 2\mathbb{N}$, and $A_0 = \emptyset$.

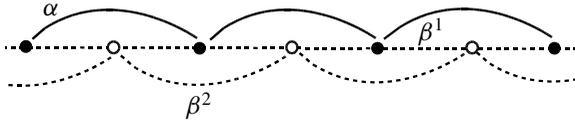
The Γ -limit is

$$F_{\text{hom}}(u^1, u^2) = \alpha_1 \#S(u^1) + \alpha_2 \#S(u^2) \\ + \frac{1}{2} \int_0^1 g(u^1) dx + \frac{1}{2} \int_0^1 g(u^2) dx + \frac{\beta}{4} \int_0^1 (u^2 - u^1)^2.$$

Note that, since $A_0 = \emptyset$, we have no optimization in the interacting term, which then is just the pointwise limit of the nearest-neighbor interactions. Note moreover that in the case $\beta = 0$ the interactions are completely decoupled.

Example 6.3 (interacting weak and strong sublattices). We consider the same pattern of interactions as in the previous example but with only strong connections on the odd lattice as in [Example 6.1](#) (see figure below), i.e., with

$$F_\varepsilon(u) = \frac{\beta^1}{4} \sum_{i=1}^{N_\varepsilon} \varepsilon(u_i - u_{i-1})^2 + \frac{\beta^2}{4} \sum_{j=0}^{N_\varepsilon/2-1} \varepsilon(u_{2j+2} - u_{2j})^2 \\ + \frac{\alpha}{4} \sum_{j=1}^{N_\varepsilon/2-1} (u_{2j+1} - u_{2j-1})^2 + \sum_{i=1}^{N_\varepsilon} \varepsilon g(u_i).$$



In this case, we have three possibilities:

- the minimizing values on the even lattice agree with those on the odd lattice (ferromagnetic overall behavior),
- the minimizing values on the even lattice disagree with those on the odd lattice (antiferromagnetic overall behavior), or
- the values on the even lattice alternate (antiferromagnetic behavior on the weak lattice).

The value of φ is obtained by optimizing over these three possibilities; i.e.,

$$\varphi(u) = \min \left\{ g(u), \frac{g(u) + g(-u)}{2} + \beta^1, \frac{3g(u) + g(-u)}{4} + \frac{\beta^1 + \beta^2}{2} \right\},$$

and we have

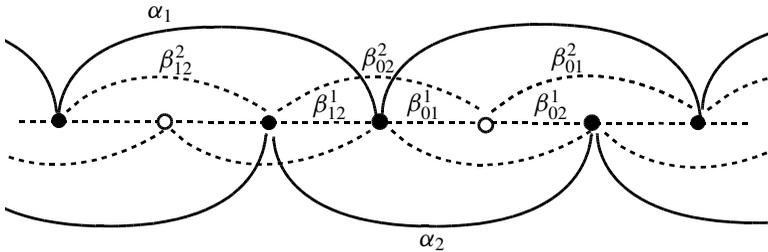
$$F_{\text{hom}}(u) = \alpha \#S(u) + \int_0^1 \varphi(u) dx.$$

Example 6.4 (third-neighbor hard phases). In the system described in the figure below, involving strong third-neighbor interactions, we have two strong components and a Γ -limit obtained by minimization of the nearest and next-to-nearest neighbors. Using the same notation of the previous examples for the coefficients, we can write the limit as

$$F_{\text{hom}}(u^1, u^2) = \alpha_1 \#S(u^1) + \alpha_2 \#S(u^2) + \int_0^1 \varphi(u^1, u^2) dx,$$

and

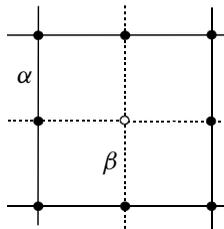
$$\begin{aligned} \varphi(u^1, u^2) = & \frac{1}{3}(g(u^1) + g(u^2)) + \frac{1}{4}\beta_{12}^2(u^2 - u^1)^2 \\ & + \frac{1}{3} \min\left\{\frac{1}{4}((\beta_{01}^1 + \beta_{01}^2)(v - u^1)^2 + (\beta_{02}^1 + \beta_{02}^2)(v - u^2)^2) + g(v) : v \in \{-1, 1\}\right\}. \end{aligned}$$



6.2. Higher-dimensional examples. In the following examples, we go back to the notation used in the statement of the main result. The normalization factor $\frac{1}{8}$ takes into account that each pair of nearest neighbors is accounted for twice.

Example 6.5 (a nearest-neighbor system with soft inclusions). Consider a nearest-neighbor system in two dimensions in which $A_0 = 2\mathbb{Z}^2$ and strong and weak interactions are given respectively by

$$\frac{1}{8}\alpha(u_k - u_{k'})^2, \quad \frac{1}{8}\varepsilon\beta(u_k - u_{k'})^2.$$



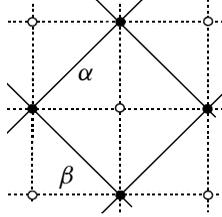
In this case,

$$F_{\text{hom}}(u) = \frac{1}{2}\alpha \int_{S(u) \cap \Omega} \|v_u\|_1 d\mathcal{H}^1 + \int_{\Omega} \varphi(u) dx,$$

where

$$\varphi(u) = \min \left\{ g(u), \frac{3g(u) + g(-u)}{4} + \beta \right\}.$$

Example 6.6 (a lattice with weak nearest-neighbor interactions). Consider strong interactions on a lattice of next-to-nearest neighbors as in the figure:



with weak nearest-neighbor interactions on the square lattice given respectively by

$$\frac{1}{8}\alpha(u_k - u_{k'})^2, \quad \frac{1}{8}\varepsilon\beta(u_k - u_{k'})^2,$$

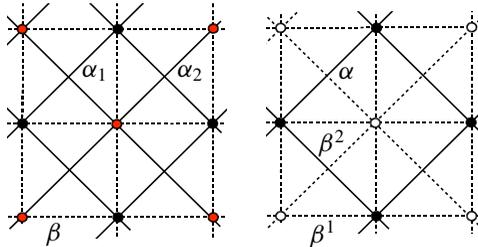
(the factor $\frac{1}{8}$ takes into account that each pair is accounted for twice). We only have one strong component, and with this choice of coefficients,

$$F_{\text{hom}}(u) = \alpha \int_{\Omega \cap \partial\{u=1\}} \|v\|_{\infty} d\mathcal{H}^1 + \int_{\Omega} \varphi(u) dx,$$

where

$$\varphi(u) = \min \{ g(u), \frac{1}{2}(g(u) + g(-u)) + \beta \}.$$

Example 6.7. We include just the pictorial description of two more two-dimensional systems with a limit with two parameters (below, left) and with one limit parameter but with the possibility of an oscillating behavior on the weak lattice (below, right), analogous to the one-dimensional Examples 6.2 and 6.3, respectively.



Example 6.8. We finally consider a three-dimensional two-periodic geometry, with one strong connected component pictured in Figure 3. Even in the absence of the

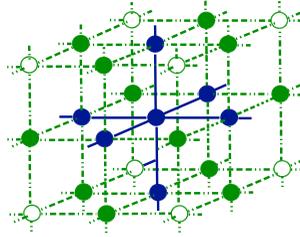


Figure 3. Oscillations in the infinite weak component.

forcing term g , we may have several competing microstructures in the determination of φ . In Figure 3, we have represented the uniform data $u = +1$ on the strong component with solid circles and a system of ferromagnetic connections between strong and weak sites (positive coefficients) and of antiferromagnetic connections between weak sites (a negative coefficient α). Correspondingly, the minimal states have the value $+1$ on weak sites connected with the strong component (represented by solid circles) and the value -1 on the other sites (represented by white circles). Note that in this case the contribution of the weak phase is a constant.

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