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**CONVERGENCE TOPOLOGIES FOR MEASURES AND THE
EXISTENCE OF TRANSITION PROBABILITIES**

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1. Introduction. A recent approach to measure theory is the introduction of measures as functionals on spaces of continuous functions [2]. To the probabilist, however, the measures are of primary concern, with the functions occurring as integrands playing a secondary role as random variables. We are thus motivated to reverse the modern procedure. We shall introduce various topologies into spaces of measures and shall in each case investigate the dual space consisting of all continuous linear functionals on the measures. From this point of view the continuous functions form only one of many possible dual spaces to a space of measures.

The study of the dual spaces yields a necessary and sufficient continuity condition for the existence of transition probabilities in a stochastic semigroup, thus solving a problem posed by W. Feller.

We introduce topologies through the convergence of nets [5], an elegant device for analysis. The spaces of measures considered are vector spaces and usually vector lattices [1]. We admit any topology for which the vector operations are continuous, but do not require that the lattice operations be continuous.

Let \mathfrak{A} be a Boolean algebra of sets in an abstract space X . Wherever \mathfrak{A} is required to be a σ -algebra, it shall be denoted by \mathfrak{A}_σ . A *partition* ρ of X is a finite collection $\{E_k\}$ of sets in \mathfrak{A} which form a disjoint covering of X . The partitions of X form a lattice [1] if we define $\rho < \rho'$ whenever ρ' is a refinement of ρ . In this way the partitions ρ will be used extensively as directed indices for nets.

For each x in X define the *unit point mass* H_x by

$$(1.2) \quad H_x(E) = \begin{cases} 0 & \text{if } x \text{ is not in } E. \\ 1 & \text{if } x \text{ is in } E. \end{cases}$$

Such H_x will belong to all spaces of measures considered below. A *discrete measure* is any finite linear combination of point masses. We shall use the symbol E to denote the characteristic function of a set E , since the context will serve to distinguish between the set and its characteristic function. Thus,

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$$(1.2) \quad E(x) = H_x(E).$$

A *step function* is any finite linear combination of characteristic functions of sets in \mathfrak{A} . For each step function f there exists a partition $\rho = \{E_k\}$ such that

$$(1.3) \quad f(x) = \sum_{\rho} a_k E_k(x).$$

If f is any real-valued function on X , $f(E)$ will denote the set of all $f(x)$ for x in E . Bars will be used to denote the diameter of a set of numbers. Thus,

$$(1.4) \quad |f(E)| = \sup f(E) - \inf f(E).$$

2. The topology of simple convergence. Let S consist of all finitely additive functions on \mathfrak{A} . That is, F belongs to S if

$$(2.1) \quad -\infty < F(E) < \infty \quad \text{for all } E \text{ in } \mathfrak{A}, \text{ and}$$

$$(2.2) \quad F(A + E) = F(A) + F(E) \quad \text{for } A \text{ and } E \text{ disjoint.}$$

S is a vector space with the obvious definitions of addition and scalar multiplication.

Let $\{F_{\alpha}\}$ be a net in S . We induce a topology in S by defining: F_{α} converges simply to F if $\lim_{\alpha} F_{\alpha}(E) = F(E)$ for each E in \mathfrak{A} .

THEOREM 1. *The discrete measures are dense in S . In particular,*

$$(2.3) \quad F = \int_X H_x dF(x),$$

where the latter integral is defined to be $\lim_{\rho} \sum_{\rho} F(E_k) H_{x_k}$ with $\rho = \{E_k\}$ and x_k in E_k . S^* , the dual space of S , consists of all step functions (1.3). With the topology of stepwise convergence in S^* , defined below, $S^{**} = S$.

Proof. For ρ fine enough to partition E and its complement E' , $\sum_{\rho} F(E_k) H_{x_k}(E) = F(E)$. Hence, (2.3).

Each ϕ in S^* defines a function f on X through

$$(2.4) \quad f(x) = \phi(H_x) \quad \text{for all } x \text{ in } X.$$

Suppose f were not a step function. Then, for each partition ρ we could choose x_{ρ} and y_{ρ} in some set E_k in ρ such that $f(x_{\rho}) \neq f(y_{\rho})$. Define

$$(2.5) \quad G_\rho = \frac{1}{f(x_\rho) - f(y_\rho)} (H_{x_\rho} - H_{y_\rho}).$$

Then, $\phi(G_\rho) = 1$ for all ρ . But, for all $\rho \geq \{E, E'\}$, $G_\rho(E) = 0$. Hence, G_ρ converges simply to 0. Since ϕ is continuous, $\lim_\rho \phi(G_\rho) = 0$, a contradiction. So f must be of the form (1.3). Then, of course,

$$(2.6) \quad \phi(F) = \sum_\rho a_k F(E_k) = \int f \, dF.$$

A sequence of step functions f_n converges step-wise to a step function f , if there exists a partition ρ such that eventually

$$(2.7) \quad f_n(x) = \sum_\rho a_{nk} E_k(x),$$

and

$$(2.8) \quad f(x) = \sum_\rho \lim_n a_{nk} E_k(x).$$

In this topology, every linear functional on S^* is continuous. Since every linear functional on S^* defines an additive function on \mathfrak{A} with a unique linear extension to S^* , $S = S^{**}$.

3. The topology of bounded convergence. The functions in S that are bounded form the space B . The condition (2.1) is strengthened to

$$(3.1) \quad -M < F(E) < M \quad \text{for all } E.$$

The usual topology for B is the topology of uniform convergence, that is, the topology induced by the norm

$$(3.2) \quad \|F\| = \sup_E F(E) - F(E') = \lim_\rho \sum_\rho |F(E_k)|.$$

With this norm B is a Banach space [1]. The norm topology is defective in that there may exist bounded (that is, continuous) linear functionals on B which have no representation as integrable functions on X , and B is not reflexive.

These defects are removed by introducing the topology of bounded convergence: F_α converges boundedly to F if $\lim F_\alpha(E) = F(E)$ for each E in \mathfrak{A} , and $|F_\alpha(E)| < M$ for all $\alpha \geq \alpha_0$ and all E in \mathfrak{A} .

THEOREM 2. *In the topology of bounded convergence the discrete measures are dense in B . In particular,*

$$(3.3) \quad F = \int_x H_x \, dF(x),$$

defined as in (2.3). The dual space B^* consists of uniform limits of

step functions (1.3). That is, to every continuous linear functional ϕ there corresponds biuniquely a function f on X such that f is a uniform limit of step functions and, for all F in B ,

$$(3.4) \quad \phi(F) = \int_X f(x) dF(x).$$

With the topology of uniform convergence on B^* , $B^{**} = B$.

Proof. By Theorem 1, (3.3) holds for simple convergence. Since $|\sum_{\rho} F(E_k) H_{x_k}(E)| \leq \sum_{\rho} |F(E_k)| \leq \|F\|$, the convergence is bounded for F in B .

For ϕ in B^* let f be defined by (2.4). Now, suppose f were not a uniform limit of step functions. Then there would exist some $\varepsilon > 0$ such that for each partition ρ we could choose x_{ρ} and y_{ρ} in some set E_k belonging to ρ such that $|f(x_{\rho}) - f(y_{\rho})| > \varepsilon$. Define

$$(3.5) \quad F_{\rho} = H_{x_{\rho}} - H_{y_{\rho}}.$$

Then, F_{ρ} converges boundedly to 0, since $\|F_{\rho}\| = 2$ for all ρ and $F_{\rho}(E) = 0$ for $\rho \geq \{E, E'\}$. Since ϕ is continuous, $\lim \phi(F_{\rho}) = 0$. But, since ϕ is linear, $\phi(F_{\rho}) = f(x_{\rho}) - f(y_{\rho})$. Hence, $|\phi(F_{\rho})| > \varepsilon$, a contradiction. So f is a uniform limit of step functions. The existence of (3.4) follows from (3.3) and the continuity of ϕ . Since step functions are bounded, f is bounded.

Conversely, the integral (3.4) exists for any uniform limit of step functions f and thus defines a linear functional ϕ on B . For, given any $\varepsilon > 0$ there exists a partition ρ_{ε} such that $|f(A_k)| < \varepsilon$ for all A_k in ρ_{ε} . Hence, $\sum_{\rho} |f(E_k)| |F(E_k)| \leq \sum_{\rho} \varepsilon |F(E_k)| \leq \varepsilon \|F\|$ for all $\rho \geq \rho_{\varepsilon}$. Moreover, the functional ϕ defined by (3.4) is continuous. For, let F_{α} converge boundedly to 0. Now,

$$(3.6) \quad \int f dF_{\alpha} = \int (f - f_{\rho}) dF_{\alpha} + \int f_{\rho} dF_{\alpha}$$

where $f_{\rho} = \sum_{\rho} a_k E_k$ and $|f(x) - f_{\rho}(x)| < \varepsilon$ for all x . Hence,

$$(3.7) \quad \left| \int f dF_{\alpha} \right| \leq \varepsilon \|F_{\alpha}\| + \left| \sum_{\rho} a_k F_{\alpha}(E_k) \right|$$

and

$$(3.8) \quad \overline{\lim}_{\alpha} \left| \int f dF_{\alpha} \right| \leq \varepsilon \overline{\lim}_{\alpha} \|F_{\alpha}\| \leq 2M\varepsilon.$$

So, $\lim_{\alpha} \phi(F_{\alpha}) = 0$.

For f in B^* define

$$(3.9) \quad \|f\| = \sup_x |f(x)|.$$

Then B^* is a Banach space and the norm topology is equivalent to the topology of uniform convergence. With this topology a continuous linear functional on B^* is a bounded linear functional. A bounded linear functional ϕ on B^* defines, a fortiori, a bounded additive set function on \mathfrak{A} . Since \mathfrak{A} is fundamental in B^* , the correspondence between ϕ and F is biunique. Hence, $B^{**} = B$.

For *positive* measures bounded convergence is equivalent to simple convergence, and hence to weak convergence over B^* . To show that bounded convergence in B is, in general, stronger than weak convergence over B^* we prove the following.

THEOREM 3. *There may exist a net $\{F_\alpha\}$ in B such that $\lim_\alpha \int f dF_\alpha = 0$ for every f in B^* , but F_α does not converge boundedly.*

Proof. Let X consist of all real-valued functions $x(t)$ on $(-\infty, \infty)$. Let \mathfrak{A}_σ be the σ -algebra in X generated by sets of the form

$$(3.10) \quad I_t = \{x \mid x(t) \in I\}$$

where I is any interval. Let $\{E_\alpha\}$ be the class of all E in \mathfrak{A}_σ which contain the zero function 0 . The indexing set $\{\alpha\}$ is directed by defining $\alpha < \alpha'$ whenever $E_{\alpha'} \subset E_\alpha$. For each real s define x_s by

$$(3.11) \quad x_s(t) = \begin{cases} 0 & \text{for } t \neq s. \\ 1 & \text{for } t = s. \end{cases}$$

Then each E_α contains all but a countable set of x_s . Hence, we may choose x_{s_α} in E_α . Also, choose a_α such that $\lim_\alpha a_\alpha = \infty$. Finally, define

$$(3.12) \quad F_\alpha = a_\alpha(H_{x_{s_\alpha}} - H_0).$$

Then, $\|F_\alpha\| = 2|a_\alpha|$. So $\lim_\alpha \|F_\alpha\| = \infty$. For f in B^* , $\int f dH_0$ exists. Therefore, $\lim_\alpha \int f(E_\alpha) = 0$. Hence, $|f(x_s) - f(0)| > 1/n$ for only countably many values of s , and thus $f(x_s) \neq f(0)$ for only countably many values of s . Therefore, $f(x_{s_\alpha}) = f(0)$ eventually. Since $\int f dF_\alpha = a_\alpha[f(x_{s_\alpha}) - f(0)]$, $\int f dF_\alpha = 0$ eventually. A fortiori, $\lim_\alpha \int f dF_\alpha = 0$.

A modification of the above example shows that the lattice operations [1] need not be continuous. Let \mathfrak{A} be the algebra generated by

sets of the form (3.10). Then, H_{x_n} converges boundedly to H_0 , where x_n is defined by (3.11). However, $H_{x_n} \wedge H_0 = 0$ which does not converge to $H_0 = H_0 \wedge H_0$.

If our algebra of sets is also a σ -algebra \mathfrak{A}_σ , we may consider the space of *countably* additive set functions on \mathfrak{A}_σ . With the topology of bounded convergence, this space L is dense in B because of (3.3). The proof of theorem 2 shows that $L^* = B^*$. However, L is reflexive only with respect to the pseudo-topology on L^* induced by the bounded convergence of sequences: f_n converges to f if $\lim_n f_n(x) = f(x)$ for each x in X , and $\|f_n\| < M$ for all n . That $L^{**} = L$ follows from the Lebesgue bounded convergence theorem [4].

4. The topology of regular convergence. Let X be a normal Hausdorff space and \mathfrak{A}_σ be the Borel sets in X . Let R be the space of bounded, regular, signed measures on \mathfrak{A}_σ . That is, F is in R if

$$(4.1) \quad F\left(\bigcup_n E_n\right) = \sum_n F(E_n)$$

for every sequence $\{E_n\}$ of disjoint sets in \mathfrak{A}_σ ,

$$(4.2) \quad |F(E)| < M$$

for all E in \mathfrak{A}_σ , and if $\{A_\alpha\}$ is the class of all open sets containing E and $|F|$ is the total variation of F [1], then

$$(4.3) \quad \inf_\alpha |F|(A_\alpha - E) = 0.$$

With norm (3.2) R is a Banach space and with the natural ordering a Banach lattice [1]. Since every F in R is the difference of two positive measures in R , we may define convergence for positive measures, a net of signed measures being convergent if it is the difference of two positive convergent nets.

A net $\{F_\alpha\}$ of positive measures in R converges *regularly* to F in R if

$$(4.4) \quad F(\text{bdy } E) = 0 \quad \text{implies} \quad \lim_\alpha F_\alpha(E) = F(E),$$

where $\text{bdy } E$ is the boundary of E . Since $\text{bdy } X$ is empty, (4.4) implies that eventually

$$(4.5) \quad \|F_\alpha\| < M.$$

This type of convergence, under more restrictive conditions, has been considered by de La Vallée Pousin [6].

THEOREM 4. *For a net of positive measures in R the following*

conditions are equivalent:

- (i) F_α converges regularly to F .
- (ii) For every bounded, measurable function f on X continuous almost everywhere relative to F , $\int f dF_\alpha$ converges to $\int f dF$.
- (iii) For every bounded, continuous function f on X , $\int f dF_\alpha$ converges to $\int f dF$.
- (iv) $F_\alpha(X)$ converges to $F(X)$ and, for every closed set E , $\lim_\alpha F_\alpha(E) \leq F(E)$.

The dual space R^* of R consists of all bounded, continuous functions f on X with the functionals defined by (3.4). Thus, for positive measures regular convergence is equivalent to weak convergence over R^* .

Proof. Given (i) and f bounded, measurable, and continuous almost everywhere relative to F , consider the sets $A_t = f^{-1}(t)$. Since F is additive and bounded, and the sets A_t are disjoint, $F(A_t) \neq 0$ for at most countably many values of t . Hence, for arbitrary $\epsilon > 0$ we can partition the range of f by means of $t_1 < t_2 < \dots < t_n$ so that $t_{k+1} - t_k < \epsilon$ and $F(A_{t_k}) = 0$. Let $E_k = A_{t_k} + f^{-1}(t_k, t_{k+1})$. Then $\text{bdy } E_k \subseteq A_{t_k} + A_{t_{k+1}} + D$ where D consists of discontinuities of f . Hence, $F(\text{bdy } E_k) = 0$. By (i), $\lim_\alpha F_\alpha(E_k) = F(E_k)$.

Let $\rho = \{E_k\}$ and $f_\rho = \sum_\rho t_k E_k$. Then

$$\begin{aligned}
 (4.6) \quad \left| \int f dF_\alpha - \int f dF \right| &\leq \left| \int (f - f_\rho) dF_\alpha \right| \\
 &+ \left| \int f_\rho dF_\alpha - \int f_\rho dF \right| + \left| \int (f_\rho - f) dF \right| \\
 &\leq \epsilon \|F_\alpha\| + \left| \sum_\rho t_k [F_\alpha(E_k) - F(E_k)] \right| + \epsilon \|F\|.
 \end{aligned}$$

Hence,

$$(4.7) \quad \lim_\alpha \left| \int f dF_\alpha - \int f dF \right| \leq 2M\epsilon.$$

Since ϵ is arbitrary,

$$(4.8) \quad \lim_\alpha \int f dF_\alpha = \int f dF.$$

Since a continuous function is, a fortiori, continuous almost everywhere as well as measurable, (ii) implies (iii).

Given (iii), the convergence of $F_\alpha(X)$ to $F(X)$ follows if we take $f(x) = 1$ in (iii). Given a closed set E , let A be any open set containing

E. By Urysohn's lemma [7], there exists a continuous function g such that $E \leq g \leq A$. Hence $F_\alpha(E) \leq \int g dF_\alpha$ and $\int g dF \leq F(A)$. Thus, (iii) gives $\lim_\alpha F_\alpha(E) \leq F(A)$. (iv) follows from (4.3).

Given (iv), let E be any set with $F(\text{bdy } E) = 0$. Let $\bar{E} = E \cup \text{bdy } E$, a closed set. Then $F_\alpha(E) \leq F_\alpha(\bar{E})$, so $\lim F_\alpha(E) \leq \lim F_\alpha(\bar{E}) \leq F(\bar{E})$ by (iv). But $F(\bar{E}) = F(E)$ since $F(\text{bdy } E) = 0$. Hence

$$(4.9) \quad \lim_\alpha F_\alpha(E) \leq F(E).$$

Similarly (4.9) holds for the complement E' , since $\text{bdy } E' = \text{bdy } E$. Thus

$$(4.10) \quad \lim_\alpha F_\alpha(X - E) \leq F(X - E).$$

Since $F_\alpha(X)$ converges to $F(X)$ by (iv), (4.10) gives

$$(4.11) \quad F(X) - \lim_\alpha F_\alpha(E) \leq F(X) - F(E).$$

Hence

$$(4.12) \quad F(E) \leq \lim_\alpha F_\alpha(E).$$

Thus, (i) follows from (4.9) and (4.12).

Since (i) implies (iii), every bounded, continuous function f on X defines a continuous linear functional ϕ on R of the form (3.4). We need only prove conversely that every ϕ is of this form.

Since H_x is regular and simple convergence implies regular convergence for positive measures, we have (3.3). So discrete measures are dense in R . Hence, for ϕ in R^* we have (3.4) with f defined by (2.4). Moreover, f is continuous: If $\{x_\alpha\}$ is a net in X converging to x , then H_{x_α} converges regularly to H_x . Hence, $f(x_\alpha)$ converges to $f(x)$. Also, f is bounded: Otherwise there would exist a sequence $\{x_n\}$ such that $|f(x_n)| > 2^n$. We could then define $F_m = \sum_1^m (1/f(x_n)) H_{x_n}$. Let $F(E) = \lim F_m(E)$. Then F_m converges regularly to F in R . Hence, $\phi(F_m)$ converges to $\phi(F)$. But, $\phi(F_m) = m$ which diverges, a contradiction.

5. Transition probabilities for stochastic semigroups. A system of stationary transition probabilities is a function $p(x, t, E)$ of three variables: x in the sample space X , t in $(0, \infty)$, and E in the σ -algebra \mathfrak{A}_σ in X such that

$$(5.1) \quad p(x, t, \cdot) \text{ is a probability measure on } \mathfrak{A}_\sigma \text{ for each } x \text{ and } t,$$

$$(5.2) \quad p(\cdot, t, E) \text{ is a measurable function on } X \text{ for each } t \text{ and } E,$$

and

$$(5.3) \quad p(y, s+t, E) = \int_x p(x, t, E) p(y, s, dx).$$

Such a system defines a family of operators $\{T_t\}$ on L through

$$(5.4) \quad FT_t(E) = \int_x p(x, t, E) dF(x)^1$$

with the readily verified properties:

$$(5.5) \quad T_t \text{ is a positive linear operator on } L.$$

$$(5.6) \quad \text{For } F > 0, \quad \|FT_t\| = \|F\|.$$

$$(5.7) \quad T_t T_s = T_{t+s}$$

We call any $\{T_t\}$ satisfying (5.5)–(5.7) a *stochastic semigroup*. These have been studied by W. Feller [3].

If we try to define Markov processes abstractly by means of stochastic semigroups, we encounter the following obstacle:

THEOREM 5. *There exist stochastic semigroups $\{T_t\}$ for which there are no transition probabilities satisfying (5.1)–(5.4).*

Proof. This simple, but striking, example is due to Feller. Let X be the real numbers and \mathfrak{A}_σ the Borel sets of X . For each F in L let $F = F_c + F_s$ be the Lebesgue decomposition [4] where F_c is absolutely continuous and F_s is singular. Define

$$(5.8) \quad T_t E = \{x \mid x - t \in E\}$$

for each E in \mathfrak{A}_σ , and

$$(5.9) \quad FT_t(E) = F_c(T_{-t}E) + F_s(T_tE).$$

Thus, continuous measures drift to the right and singular measures drift to the left as t increases. If transition probabilities exist for this process, (5.4) implies

$$(5.10) \quad p(x, t, E) = H_x T_t(E) = H_x(T_t E).$$

Hence,

$$(5.11) \quad FT_t(E) = \int_x H_x(T_t E) dF(x) = F(T_t E),$$

¹ We express operators on measures as right operators and their adjoints as left operators, using the same symbol for both.

which contradicts (5.9) if F is absolutely continuous.

The preceding example suggests that we examine the adjoint operators to $\{T_t\}$. We see then that a system of transition probabilities defines a semigroup of operators on L^* through

$$(5.12) \quad T_t f(y) = \int_x f(x) p(y, t, dx).$$

That $T_t f$ is a bounded, measurable function follows from the fact that f is a uniform limit of step functions f_n , so $T_t f$ is a uniform limit of $T_t f_n$, and $T_t f_n$ is bounded and measurable. Thus, L^* is invariant under $\{T_t\}$. The topological significance of this is given by the following.

THEOREM 6. *A linear operator T on B (or L) is continuous in the topology of bounded convergence if, and only if, the adjoint to T defines a bounded operator on the dual space B^* (resp. L^*).*

Proof. Let the adjoint to T be a bounded operator on B^* . Then, if F_α converges boundedly to F , we have $\lim_\alpha F_\alpha T E = F T E$ for all E , since $T E$ is in B^* . Thus, $F_\alpha T$ converges simply to $F T$. Since T is bounded, $\|F_\alpha T\| \leq \|F_\alpha\| \|T\|$, so $F_\alpha T$ converges boundedly to $F T$. Hence, T is continuous with respect to bounded convergence.

Conversely, if T is continuous in the topology of bounded convergence, then T is bounded. To prove this we need only show that the function $u(x) = \|H_x T\|$ is bounded, since by (3.3), $F T = \int H_x T dF(x)$, so $\|F T\| \leq \sup_x u(x) \|F\|$. Suppose $u(x)$ were unbounded. Then, by Zorn's lemma, there is a maximal collection \mathfrak{M} of sets such that \mathfrak{M} has the finite intersection property and $u(x)$ is unbounded on every finite intersection of sets in \mathfrak{M} . Thus, for each partition ρ there exists a unique E_ρ belonging to both ρ and \mathfrak{M} . Choose x_ρ and y_ρ in E_ρ such that $\lim_\rho u(x_\rho) - u(y_\rho) = \infty$. Let $F_\rho = H_{x_\rho} - H_{y_\rho}$. Then F_ρ converges boundedly to 0. So $F_\rho T$ converges boundedly to 0. Hence, $\|F_\rho T\|$ is eventually bounded. But $u(x_\rho) - u(y_\rho) \leq \|F_\rho T\|$, a contradiction. So $u(x)$ must be bounded.

Now, the dual of a continuous operator always exists; that is, the dual space is invariant under the adjoint operator. For, if F_α converges to F , $F_\alpha T$ converges to $F T$, and so $F_\alpha T \phi$ converges to $F T \phi$ for each ϕ in the dual space. Thus, $T \phi$ is a continuous, linear functional. Hence, $T \phi$ is in the dual space.

The same proof holds for the space L . With an analogous argument, theorem 4 gives a similar result for the space R :

THEOREM 7. *A positive linear operator on R is continuous in the topology of regular convergence if, and only if, the adjoint defines a*

positive operator on the dual space R^* .

We can now remedy the defect given by Theorem 5. To (5.5)—(5.7) we add the condition

$$(5.13) \quad T_t \text{ is continuous in the topology of bounded convergence.}$$

THEOREM 8. *To every system of transition probabilities $p(x, t, E)$ there corresponds biuniquely a stochastic semigroup $\{T_t\}$ satisfying (5.13) such that (5.4) holds.*

Proof. We need only prove that (5.5)—(5.7) and (5.13) are sufficient, since the necessity of these conditions has already been discussed. Given $\{T_t\}$ we define

$$(5.14) \quad p(x, t, E) = H_x T_t E.$$

Condition (5.13) implies, by Theorem 6, that $T_t E$ is in L^* . Hence, (5.2). (5.1) follows from (5.5), (5.6), and (5.14). (5.3) is a direct result of (5.7), (5.14), and

$$(5.15) \quad FT_t E = \int_x H_x T_t E dF(x).$$

which results from $T_t E$ being in L^* . Finally, (5.4) follows from (5.14) and (5.15).

For the space R we have the following.

THEOREM 9. *Suppose (5.4) defines a stochastic semigroup of operators on R . Then the following conditions are equivalent:*

- (i) $p(x, t, E)$ is continuous at x if $p(x, t, \text{bdy } E) = 0$.
- (ii) T_t is continuous in the topology of regular convergence.
- (iii) If f is a bounded, continuous function, then so is $T_t f$.

Proof. The equivalence of (ii) and (iii) follows directly from Theorem 7.

Given (ii), let x_α converge to x in X . Then H_{x_α} converges regularly to H_x so $H_{x_\alpha} T_t$ converges regularly to $H_x T_t$. Thus, $H_{x_\alpha} T_t E$ converges to $H_x T_t E$ if $H_x T_t(\text{bdy } E) = 0$. This, through (5.14), gives (i).

Given (i), consider positive measures such that F_α converges regularly to F . Let $FT_t(\text{bdy } E) = 0$. Then (5.4) implies $p(x, t, \text{bdy } E) = 0$ except for x in D , where $F(D) = 0$. Let $f(x) = p(x, t, E)$. By (i), f is continuous almost everywhere relative to F . Thus, condition (ii) of

Theorem 4 applied to (5.4) gives $\lim_{\alpha} F_{\alpha} T_t E = F T_t E$. So $F_{\alpha} T$ converges regularly to $F T$. Hence, (ii).

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