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**REMARKS ON SIMPLE EXTENDED LIE ALGEBRAS**

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# REMARKS ON SIMPLE EXTENDED LIE ALGEBRAS

ARTHUR A. SAGLE

We continue the discussion of finite dimensional simple extended Lie algebras over an algebraically closed field  $F$  of characteristic zero with nondegenerate form  $(x, y) = \text{trace } R_x R_y$  where  $R_x$  (or  $R(x)$ ) denotes the mapping  $A \rightarrow A: a \rightarrow ax$ ; for brevity we call such an algebra a *simple el-algebra*. The main result of this paper is that those simple el-algebras which are not Lie or Malcev algebras probably cannot be analyzed by the usual desirable Lie-type methods.

First if we assume the simple el-algebra [3]  $A$  has a diagonalizable Cartan subalgebra [3] such that for any weight space  $A(N, \alpha)$  of  $N$  in  $A$  we have  $A(N, \alpha)^2 = 0$  or  $A(N, \alpha)^2 \subset A(N, \beta)$  for some weight  $\beta$  (which is a function of  $\alpha$ ), then  $A$  is a Lie or Malcev algebra. Thus if one attempts to remedy the situation that  $A(N, \alpha)^2$  is difficult to locate by the rather desirable above assumptions and tries to construct a multiplication table for a new simple el-algebra, then actually nothing new is obtained. Next we show that if the derivation algebra  $D(A)$  is used to analyze a simple el-algebra, using [1, page 54] or possibly Lie module theory, then again a difficult situation is encountered: If  $A$  is simple el-algebra, then  $A$  is not a simple Lie or Malcev algebra if and only if there exists a nonzero element  $a \in A$  such that for every derivation  $D \in D(A)$  we have  $aD = 0$ . The element  $a \in A$  reflects the structure of  $A$  and so it appears that the structure of  $A$  is not accurately reflected in its derivation algebra.

The proofs of the above results use the following lemma.

LEMMA 1.1. *If  $A$  is a simple el-algebra, then  $A$  is a Lie or 7-dimensional Malcev algebra if and only if  $u(x) = \text{trace } R_x$  is the zero linear functional.*

*Proof.* A linearization of the defining identities of an extended Lie algebra

$$xy = -yx \quad \text{and} \quad J(xy, x, y) = 0$$

where  $J(x, y, z) = xy \cdot z + yz \cdot x + zx \cdot y$  yields

$$(1.2) \quad J(wx, y, z) + J(yz, w, x) = J(wy, z, x) + J(zx, w, y)$$

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$$(1.3) \quad \begin{aligned} wJ(x, y, z) - xJ(y, z, w) + yJ(z, w, x) - zJ(w, x, y) \\ = 3[J(wx, y, z) + J(yz, w, x)] \end{aligned}$$

for all  $w, x, y, z \in A$ . From (1.2) we obtain by operating on  $w$  that

$$(1.4) \quad \begin{aligned} (xz, y) - (x, zy) &= \text{trace } R(xz)R(y) - \text{trace } R(x)R(zy) \\ &= \text{trace } R(xz \cdot y + x \cdot zy) \\ &= u(xz \cdot y + x \cdot zy) . \end{aligned}$$

Now if  $u(x) = 0$  for all  $x \in A$ , then from (1.4) we see  $(x, y)$  is a nondegenerate invariant form and from [3],  $A$  is a simple Lie or 7-dimensional Malcev algebra. Conversely, from the identities for these algebras [2] we see that  $u(x) = 0$  for all  $x \in A$ .

We continue the use of the notation in [3] for sets and algebraic operations.

**2. On the construction.** We shall first investigate the assumption that a simple el-algebra  $A$  has a diagonalizable Cartan subalgebra  $N$  [3]. That is,  $N$  is a nilpotent Lie subalgebra of  $A$  such that for all  $m, n \in N$ ,

$$R_{mn} = [R_m, R_n] \equiv R_m R_n - R_n R_m ;$$

furthermore, decomposing  $A$  into its weight spaces relative to  $R(N) = \{R_n : n \in N\}$  we have [1; 3]

$$A = A(N, 0) \oplus \sum_{\alpha \neq 0} A(N, \alpha)$$

where, since  $R(N)$  is diagonalizable,

$$A(N, \lambda) = \{x \in A : xR_n = \lambda(n)x\}$$

is the weight space of  $N$  corresponding to the weight  $\lambda$  and, since  $N$  is Cartan [3],

$$N = A(N, 0) .$$

Since we are using a fixed Cartan subalgebra we use the notation  $A_\sigma$  or  $A(\sigma)$  for  $A(N, \sigma)$  and the convention  $A(\sigma) = 0$  if  $\sigma$  is not a weight of  $N$  in  $A$ . From [3] we have the identities

$$(2.1) \quad A_\alpha A_\beta \subset A_{\alpha+\beta} \quad \text{if } \alpha \neq \beta$$

$$(2.2) \quad \begin{aligned} J(A_\alpha, A_\beta, A_\gamma) &= 0 \quad \text{if } \alpha \neq \beta \neq \gamma \neq \alpha \\ \text{and } J(A_\alpha, A_\beta, N) &= 0 \quad \text{if } \alpha \neq \beta . \end{aligned}$$

Let  $K$  denote the kernel of the linear functional  $u : x \rightarrow \text{trace } R_x$ , then we have

$$(2.3) \quad (\alpha + \beta)(n)(x, y) = (\alpha - \beta)(n)u(xy) \\ \text{if } n \in N, x \in A_\alpha, y \in A_\beta$$

$$(2.4) \quad (A_\alpha, A_\beta) = 0 \quad \text{if } \alpha \neq 0 \text{ and } \beta \neq 0 \text{ and } \alpha \neq -\beta$$

$$(2.5) \quad A_\alpha A_\beta \subset K \quad \text{if } \alpha \neq 0 \text{ and } \beta \neq 0 \text{ and } \alpha \neq \beta.$$

For (2.3), let  $n \in N$ , then  $xn = \alpha(n)x$ ,  $yn = \beta(n)y$  and using (1.4) we have

$$(\alpha(n) + \beta(n))(x, y) = (xn, y) - (x, ny) \\ = u(xn \cdot y + x \cdot ny) = (\alpha(n) - \beta(n))u(xy).$$

For (2.4) and (2.5), let  $x \in A_\alpha$ ,  $y \in A_\beta$  and first assume  $\alpha \neq 0$  and  $\beta \neq 0$ ,  $\pm \alpha$ . If  $xy = 0$  for all  $x, y$  as above, then the results follow from (2.3). So assume  $0 \neq xy \in A(\alpha)A(\beta) \subset A(\alpha + \beta)$ , then  $\alpha + \beta$  is a weight of  $N$  in  $A$ . Let  $z \in A(\alpha + \beta)$ , then since  $\alpha \neq \alpha + \beta \neq \beta \neq \alpha$  we use (2.2) to obtain  $J(x, y, z) \in J(A(\alpha), A(\beta), A(\alpha + \beta)) = 0$ . Therefore

$$zR(xy) = zx \cdot y + yz \cdot x \in A(2\alpha + \beta)A(\beta) \\ + A(\alpha + 2\beta)A(\alpha) \subset A(2(\alpha + \beta)).$$

Using this result and (2.1) we see that for any weight  $\gamma$ ,

$$A(\gamma)R(xy) \subset A(\gamma + (\alpha + \beta)) \neq A(\gamma)$$

and therefore the matrix for  $R(xy)$  has zeros on its diagonal so that  $u(xy) = \text{trace } R(xy) = 0$ . Next we relax the assumptions on  $\beta$ , use the above result and (2.3) to see that (2.4) and (2.5) now follow.

Now we shall start using the hypothesis that if  $\alpha$  is any weight of  $N$  in  $A$ , then  $A_\alpha^2 = 0$  or there exists a weight  $\pi(\alpha)$  such that  $A_\alpha^2 \subset A_{\pi(\alpha)}$ . Thus we are assuming that if  $A_\alpha^2 \neq 0$ , then there exists a weight  $\pi(\alpha)$  such that for each  $x, y \in A_\alpha$ ,  $xy \in A_{\pi(\alpha)}$ ; that is,  $\pi$  is a function of the weight and not a function of the particular elements used in forming the products. Using this assumption we shall show that for any weight  $\alpha$ ,  $A_\alpha \subset K$  (=kernel of  $u$ ) and therefore by Lemma 1.1 conclude that  $A$  is Lie or Malcev.

First for  $\alpha = 0$  we have  $A_0^2 = A_0N = 0$ . So assume  $\alpha \neq 0$ . If  $xy = 0$  for all  $x, y \in A_\alpha$ , then using (2.1) we see that for any  $x \in A_\alpha$ ,  $u(x) = \text{trace } R_x = 0$  and therefore  $A_\alpha \subset K$ . So next we consider  $0 \neq A_\alpha^2 \subset A_{\pi(\alpha)}$  where  $\alpha \neq 0$ .

LEMMA 2.6. *If  $\alpha \neq 0$  and  $0 \neq A_\alpha^2 \subset A_{\pi(\alpha)}$ , then  $\pi(\alpha) \neq 0$ .*

COROLLARY 2.7.  $N = \sum_{\alpha \neq 0} A(\alpha)A(-\alpha) \subset K$ .

Suppose Lemma 2.6 has been proven, then to prove the corollary we first note  $\sum_{\alpha \neq 0} A(\alpha)A(-\alpha) \subset A(0) = N$ . Next set  $B = \sum_{\alpha \neq 0} A(\alpha)(-\alpha) \oplus \sum_{\alpha \neq 0} A(\alpha)$ ; we shall show  $B$  is an ideal of  $A$ . For any weight  $\beta \neq 0$ ,

$$BA(\beta) \subset (\sum_{\alpha \neq 0} A(\alpha)A(-\alpha))A(\beta) + A(\beta)^2 + A(\beta)A(-\beta) + \sum_{\alpha \neq 0, \pm\beta} A(\alpha + \beta).$$

Then using  $A(\beta)^2 = 0$  or  $A(\beta)^2 \subset A(\pi(\beta))$ , where from Lemma 2.6  $\pi(\beta) \neq 0$ , we see that  $BA(\beta) \subset B$ . For  $\beta = 0$  we note that

$$(\sum_{\alpha \neq 0} A(\alpha)A(-\alpha))A(0) \subset A(0)N = 0$$

and use (2.1) to obtain  $BA(0) \subset B$ . Thus  $BA \subset B$  so that  $B$  is an ideal of  $A$  and since  $A$  is simple,  $B = 0$  or  $B = A$ . If  $B = 0$ , then  $A_\alpha = 0$  for each  $\alpha \neq 0$  and  $A = A_0 = N$  so that  $A^2 = A_0N = 0$ , a contradiction. Thus  $B = A$  and from this  $N = \sum_{\alpha \neq 0} A(\alpha)A(-\alpha) \subset K$ , using (2.5).

For Lemma 2.6 assume  $\pi(\alpha) = 0$  and let  $x, y \in A_\alpha$ , then  $xy \in A_\alpha^2 \subset A_0 = N$ . We shall show for any weight  $\beta$  that  $\beta(xy) = 0$ , then for any  $z \in A_\beta$  we have  $z(xy) = zR(xy) = \beta(xy)z = 0$ . Therefore  $(xy)F$  is an ideal of  $A$  which must be zero and so  $A_\alpha^2 = 0$ , a contradiction. For  $x, y \in A_\alpha$  we have from the defining identity

$$0 = J(xy, x, y) = (xy \cdot x)y + (y \cdot xy)x$$

which implies, since  $xy \in N$ ,  $2\alpha(xy)xy = 0$ . From this and the fact that  $\alpha$  is a linear functional on  $N$  we have  $2\alpha(xy)^2 = 0$  and so  $\alpha(xy) = 0$ . Thus for  $\beta = 0, \alpha$  we have  $\beta(xy) = 0$  so we now assume  $\beta \neq 0, \alpha$  and let  $z \in A_\beta, n \in N$ , then using (2.1) and (2.2) we obtain

$$J(zx, y, n) + J(yn, z, x) = \alpha(n)J(y, z, x) = -\alpha(n)\beta(xy)z + \alpha(n)(yz \cdot x + zx \cdot y)$$

and

$$J(zn, x, y) + J(xy, z, n) = \beta(n)J(z, x, y) = -\beta(n)\beta(xy)z + \beta(n)(yz \cdot x + zx \cdot y).$$

We combine these equations by using (1.2) to obtain

$$\alpha(n)(-\beta(xy)z + zx \cdot y + yz \cdot x) = \beta(n)(-\beta(xy)z + zx \cdot y + yz \cdot x).$$

From this equality we obtain, since  $\beta(n) \neq \alpha(n)$  for some  $n$ , that

$$\beta(xy)z = zx \cdot y + yz \cdot x \in A(2\alpha + \beta).$$

But since  $\beta(xy)z \in A(\beta)$  we have

$$\beta(xy)z \in A(\beta) \cap A(2\alpha + \beta) = 0.$$

Thus if  $z \neq 0$ ,  $\beta(xy) = 0$  and this proves the lemma.

Thus far we have considered for  $\alpha \neq 0$ : (1)  $A_\alpha^2 = 0$  which implies  $A_\alpha \subset K$ ; (2)  $A_\alpha^2 \neq 0$  which implies  $\pi(\alpha) \neq 0$  and consequently  $N = A_0 = \sum_{\alpha \neq 0} A(\alpha)A(-\alpha) \subset K$ . So we next investigate (2) more closely and note that it suffices to consider  $0 \neq A_\alpha^2 \subset A_{\pi(\alpha)}$  where  $\pi(\alpha) = \alpha$ . For if  $\pi(\alpha) \neq \alpha$ , then using (2.1) we see that the matrix of  $R_x$  for any  $x \in A_\alpha$  has zeros on its diagonal and therefore  $u(x) = 0$  so that  $A_\alpha \subset K$  which is what we eventually want to show for any weight  $\alpha$ .

Thus we are considering  $0 \neq A_\alpha^2 \subset A_\alpha$ . Since  $(x, y)$  is nondegenerate and  $A_\alpha^2 \neq 0$ , there exists a weight  $\beta$  so that

$$(A_\alpha^2, A_\beta) \neq 0.$$

But since  $A_\alpha^2 \subset A_\alpha$  this means  $(A_\alpha, A_\beta) \neq 0$  and from (2.4) and the assumption that  $\alpha \neq 0$  we conclude  $\beta = 0$  or  $\beta = -\alpha$ . We shall consider these two cases and show that the situation  $0 \neq A_\alpha^2 \subset A_\alpha$  actually does not exist so that we may conclude that for any weight  $\alpha$ ,  $A_\alpha \subset K$ .

Case  $\beta = 0$ . Let  $x, y \in A_\alpha$ ,  $n \in A_0$  and  $xy \in A_\alpha$ , then using  $(A_\alpha, A_\alpha) = 0$  (from (2.3)) we have

$$\begin{aligned} (xy, n) &= (xy, n) - (x, yn) \\ &= u(xy \cdot n + x \cdot yn) \\ &= u(\alpha(n)xy + \alpha(n)xy) \\ (2.8) \qquad &= 2\alpha(n)u(xy). \end{aligned}$$

However from (2.3) and  $xy \in A_\alpha$  we have

$$\begin{aligned} \alpha(n)(xy, n) &= (\alpha + 0)(n)(xy, n) \\ &= (\alpha - 0)(n)u(xy \cdot n) \\ (2.9) \qquad &= \alpha(n)^2 u(xy). \end{aligned}$$

From (2.8) we also have  $\alpha(n)(xy, n) = 2\alpha(n)^2 u(xy)$  and therefore from

$$(2.9) \qquad \alpha(n)^2 u(xy) = 0 \quad \text{for all } n \in N, x, y \in A_\alpha.$$

Now there exists  $x, y \in A_\alpha$  so that  $u(xy) \neq 0$ , otherwise from (2.8) we would have  $(A_\alpha^2, A_0) = 0$ , contrary to our assumption for case  $\beta = 0$ . But from the previous equation this implies  $\alpha(n) = 0$  for all  $n \in N$ , contradicting the assumption  $\alpha \neq 0$ . Thus case  $\beta = 0$  does not exist.

Case  $\beta = -\alpha$ . That is,  $\alpha \neq 0$ ,  $A_\alpha^2 \subset A_\alpha$  and  $(A_\alpha^2, A_\beta) \neq 0$  with  $\beta = -\alpha$ ; in particular we are assuming  $-\alpha$  is a weight. We shall show in this case that the dimension of  $A_\alpha$  is one and therefore  $A_\alpha^2 = 0$ , a contradiction; thus case  $\beta = -\alpha$  does not exist. So assume the dimension of  $A_\alpha$  is greater than one and let  $x, y \in A_\alpha$ ,  $z \in A_{-\alpha}$  and  $n \in N$ , then using  $xy \in A_\alpha$  and (2.2) we have

$$J(ny, z, x) + J(zx, n, y) = -\alpha(n)J(y, z, x)$$

and 
$$J(nz, x, y) + J(xy, n, z) = \alpha(n)J(z, x, y) .$$

Applying (1.2) to these equations we have, since  $\alpha \neq 0$ ,

$$\begin{aligned} 0 = J(y, z, x) &= yz \cdot x + zx \cdot y + xy \cdot z \\ &= xy \cdot z - \alpha(yz)x - \alpha(zx)y . \end{aligned}$$

Therefore since  $xy \cdot z \in A_0$  and  $x, y \in A_\alpha$  we have  $xy \cdot z = 0$  and  $\alpha(yz)x + \alpha(zx)y = 0$ . But since we have assumed the dimension of  $A_\alpha > 1$  and  $x, y$  are arbitrary in  $A_\alpha$  we have  $\alpha(zx) = 0$  for any  $z \in A_{-\alpha}$ ; for just choose  $0 \neq x$  arbitrary in  $A_\alpha$  and  $y$  to be linearly independent of  $x$ , then for any  $z \in A, \alpha(yz)x + \alpha(zx)y = 0$  which yields the result.

Next we shall show  $\beta(zx) = 0$  for any weight  $\beta$  of  $N$  and any  $z \in A(-\alpha), x \in A(\alpha)$ . If  $\beta = q\alpha$  where  $q$  is a rational number, the results follow. Next suppose  $\beta \neq q\alpha$  and let  $M = \sum_k A(\beta + k\alpha), k = 0, \pm 1, \pm 2, \dots$ . Using (2.1) and  $\beta \neq q\alpha$  we see that  $M$  is  $R_x - , R_z - ,$  and  $R(xz)$ -invariant and for any  $y = \sum_k y_k \in M$  where  $y_k \in A(\beta + k\alpha)$  we have

$$J(y, x, z) = \sum_k J(y_k, x, z) = 0 ,$$

using (2.2). Thus  $y([R_x, R_z] - R(xz)) = 0$ ; that is, on  $M$  we have  $R(xz) = [R_x, R_z]$  so that

$$(2.10) \quad \text{trace}_M R(xz) = 0 ,$$

where  $\text{trace}_M$  denotes the trace function restricted to  $M$ . However calculating the  $\text{trace}_M R(xz)$  from the matrix of  $R(xz)$  on  $M$  we see that

$$\begin{aligned} \text{trace}_M R(xz) &= \sum_k N_k(\beta + k\alpha)(xz), & N_k &= \dim A(\beta + k\alpha) \\ &= (\sum_k N_k)\beta(xz) + (\sum_k kN_k)\alpha(xz) \\ &\quad - (\sum_k N_k)\beta(xz), \text{ since } \alpha(xz) = 0 . \end{aligned}$$

This equation and (2.10) imply  $\beta(xz) = 0$ . Thus for any weight  $\beta$  and any  $y \in A_\beta$  we have  $yR(xz) = \beta(xz)y = 0$  which implies  $R(xz) = 0$  and therefore  $xz = 0$  i.e.  $A(\alpha)A(-\alpha) = 0$ . We use this fact to obtain a contradiction to  $(A^2(\alpha), A(-\alpha)) \neq 0$ . So let  $x, y \in A(\alpha), z \in A(-\alpha)$ , then using (1.4) we have

$$\begin{aligned} (xy, z) &= (x, yz) + u(xy \cdot z + x \cdot yz) \\ &= u(xy \cdot z), \text{ using } yz \in A(\alpha)A(-\alpha) = 0 \\ &= 0, \text{ using } xy \in A(\alpha) \text{ and } A(\alpha)A(-\alpha) = 0 . \end{aligned}$$

This contradiction shows case  $\beta = -\alpha$  does not exist and so from previous remarks we have for any weight  $\alpha, A_\alpha \subset K$  which proves

**THEOREM 2.11.** *Let  $A$  be a simple el-algebra satisfying the*

following conditions

- (1) there exists a Cartan subalgebra  $N$  of  $A$  so that  $R(N) = \{R_n; n \in N\}$  acts diagonally in  $A$
- (2) if  $A = \sum_{\alpha} A(N, \alpha)$  is the weight space decomposition of  $A$  relative to  $R(N)$  where  $N$  is the subalgebra of (1), then  $A(N, \alpha)^2 = 0$  or  $A(N, \alpha)^2 \subset A(N, \pi(\alpha))$  for some weight  $\pi(\alpha)$ .

Then  $A$  is a Lie or 7-dimensional Malcev algebra.

**3. On derivations.** Again let  $A$  be a simple el-algebra. To use the derivation algebra  $D(A)$  in the analysis of  $A$  we first locate the derivations of  $A$  as follows.

**THEOREM 3.1.** *Every derivation of  $A$  is inner, that is,  $D(A)$  is contained in the Lie transformation algebra  $L(A)$  which is the smallest Lie algebra containing  $R(A) = \{R_x; x \in A\}$  [4].*

*Proof.* Since  $A$  is simple it contains no nontrivial  $L(A)$ -invariant subspaces and so  $L(A)$  is irreducible in  $A$ . This implies  $L(A) = C \oplus L(A)'$  where  $C$  is the center of  $L(A)$  and  $L(A)' = [L(A), L(A)]$  is semi-simple [1; Th. 2.11]. Furthermore  $C = 0$  or  $C = FI$ ; for if  $S$  is a linear transformation in  $C$ , then since  $F$  is algebraically closed  $S$  has a characteristic root  $\lambda$  in  $F$ . Using the fact  $[R(A), S] = 0$  we see  $\{x \in A: xS = \lambda x\}$  is a nonzero ideal of  $A$  and therefore equals  $A$ . From this the results concerning  $C$  follow.

Now let  $D \in D(A)$ , then we have  $[R_x, D] = R(xD)$  for all  $x \in A$  and this together with the Jacobi identity imply  $[L(A)', D] \subset L(A)'$ . Thus the mapping

$$L(A)' \rightarrow L(A)': X' \mapsto [X', D] \quad \text{all } X' \in L(A)'$$

is a derivation of  $L(A)'$ . Since  $L(A)'$  is semi-simple every derivation of  $L(A)'$  is inner and therefore there exists  $D' \in L(A)'$  so that  $[X', D] = [X', D']$  all  $X' \in L(A)'$  [1; Th. 3.6]. But for any  $X = aI + X' \in L(A)$  where  $a \in F$  (if  $C \neq 0$ ) we have  $[X, D] = [X, D']$ . Thus if  $T = D - D'$  we have in particular that  $[R(A), T] = 0$ . Again since  $F$  is algebraically closed  $T$  has a characteristic root  $\mu$  and we see that  $\{x \in A: xT = \mu x\}$  is a nonzero ideal in  $A$ . This implies either  $T = 0$  in which case  $D = D'$  or  $T = \mu I$  in which case  $D = \mu I + D'$ . Now in this latter case we note  $D' \in L(A)'$  so that trace  $D' = 0$  and since  $(x, y) = \text{trace } R_x R_y$  is nondegenerate we have from  $[R_x, D] = R(xD)$  that  $(xD, y) + (x, yD) = 0$  so that  $D$  is skewsymmetric and also trace  $D = 0$ . From these facts on trace and  $D = \mu I + D'$  we conclude  $D = D' \in L(A)$  in both cases.

Even though we know all derivations of a simple el-algebra are inner, their exact form has not yet been determined. However the



following is not too difficult to prove: If  $A$  is a simple el-algebra, then  $A$  is a Lie algebra if and only if there exists an element  $x \in A$  so that  $R_x$  is a nonzero derivation of  $A$ . Next we have

**THEOREM 3.2.** *If  $A$  is a simple el-algebra, then  $A$  is not a Lie or 7-dimensional Malcev algebra if and only if there exists a nonzero element  $a \in A$  such that for every derivation  $D$  of  $A$  we have  $aD = 0$ .*

*Proof.* If  $A$  is a Lie or 7-dimensional Malcev algebra then the conclusion is well known [2]. Conversely, if  $A$  is not Lie or 7-dimensional Malcev, then since  $(x, y) = \text{trace } R_x R_y$  is nondegenerate we use Lemma 1.1 to obtain a nonzero element  $a \in A$  so that for all  $x \in A$ ,  $u(x) = (x, a)$ . But for any derivation  $D$  we have  $R(xD) = [R_x, D]$  and  $(xD, y) + (x, yD) = 0$  so that in particular we have for any  $x \in A$ ,  $(aD, x) = -(a, xD) = -u(xD) = -\text{trace } R(xD) = 0$ . Thus since  $(x, y)$  is nondegenerate  $aD = 0$ .

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