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HITTING TIMES FOR TRANSIENT STABLE PROCESSES

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In this paper we explicitly find the asymptotic behavior, for large t, of the probability that a transient d-dimensional stable process first (last) hits a bounded Borel set during the time interval (t, ∞) .

Assume that X(t) is a stable process on R^d (d-dimensional Euclidean space) having exponent $\alpha < d$ and normalized so that the paths are right continuous with left-hand limits at every point. Assume further that $[X(t)-X(0)]t^{-1/\alpha}$ is distributed like X(1)-X(0), and moreover, that X(1)-X(0) has a genuinely d-dimensional distribution on R^d . [In particular, every symmetric stable process on R^d with 0 mean (when it exists) satisfies these conditions.]

From these assumptions it follows that X(t) - X(0) has a bounded, continuous density, f(t, x), which satisfies the well-known scaling property

(1.1)
$$f(t,x) = t^{-d/\alpha} f(1, t^{-1/\alpha}x).$$

For a Borel (more generally, analytic) set $B \subset \mathbb{R}^d$, let

$$V_B = \inf\{t > 0: X(t) \in B\}$$

denote the first hitting time of B. As usual we set $V_{\scriptscriptstyle B}=\infty$ if

$$X(t) \notin B$$

for all t > 0. Our main purpose in this note is to establish the following.

THEOREM 1. Let B be a bounded Borel (or analytic) subset of R^d . Then under the above assumptions on X(t),

$$(1.2) \quad \lim_{t\to\infty} t^{(d/\alpha)-1} P_x(t < V_B < \infty) = P_x(V_B = \infty) C(B) \left\lceil \frac{d}{\alpha} - 1 \right\rceil^{-1} f(1,0) ,$$

where C(B) is the natural capacity of B.

Previously, (by using a different method) Joffe [2] established this result for symmetric processes with $(d/2) < \alpha < 1$ when B has a non-empty interior, and Spitzer [4] (Lemma, p. 114) established this result for arbitrary compact B in the case of 3-dimensional Brownian motion. In the case of recurrent stable processes the analogue of Theorem 1 can be found in [3].

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It is interesting to compare Theorem 1 with the following, much easier

THEOREM 2. Let

$$T_{B} = \inf\{t \geq 0 : X(s) \notin B, \ all \ s > t\}$$

be the last hitting time of B. Then under the same conditions as Theorem 1.

(1.3)
$$\lim_{t\to\infty} t^{(d/\alpha)-1} P_x(T_B > t) = C(B) \left[\frac{d}{\alpha} - 1 \right]^{-1} f(1,0) .$$

2 Proofs.

Proof of Theorem 1. A first passage decomposition yields

$$\begin{array}{ll} (2.1) & P_x(t < V_B < \infty) = \int_{\mathbb{R}^d} \!\! P_x(V_B > t, \, X\!(t) \in \! dy) P_y(V_B < \infty) \\ & = \int_{\mathbb{R}^d} \!\! \left[f(t,y-x) - \int_0^t \!\! \int_{\overline{B}} \!\! H_B(x,ds,dz) f(t-s,y-z) \right] \!\! P_y(V_B < \infty) dy, \end{array}$$

where here and in the following,

$$H_B(x, ds, dz) = P_x(V_B \in ds, X(s) \in dz)$$
,

and \bar{B} is the closure of B. But it is a known fact ([1] Prop. 18.4) that there is a measure, $e_B(dy)$, with support contained in \bar{B} (the capacitary measure of B) and finite total mass C(B) (the capacity of B), such that

$$(2.2) P_y(V_B < \infty) = \int_{\overline{B}} g(u-y)e_B(du) ,$$

where

$$g(x) = \int_0^\infty f(t, x) dt$$

is the potential kernel density for the process X(t). Setting

$$R(t, x) = \int_{t}^{\infty} f(s, x) ds$$

and using the fact that

we obtain from (2.1) that

$$(2.4) P_x(t < V_B < \infty)$$

$$\int_{\overline{B}} \Big[R(t, y - x) - \int_{\overline{B}} \int_0^t H_B(x, ds, dz) R(t - s, y - z) \Big] e_B(dy) .$$

From the scaling property (1.1) and the fact that f(1, x) is continuous, we see that $\lim_{t\to\infty} t^{d/\alpha} f(t, x) = f(1, 0)$, uniformly in x on compacts, and thus

(2.5)
$$\lim_{t\to\infty} t^{(d/\alpha)-1}R(t,x) = f(1,0)\left[\frac{d}{\alpha}-1\right]^{-1},$$

uniformly in x on compacts. Set

$$R(t) = t^{-(d/\alpha)+1} \left[\frac{d}{\alpha} - 1 \right]^{-1}.$$

Then from (2.5),

(2.6)
$$\lim_{t\to\infty} \int_{\overline{B}} \frac{R(t, y-x)}{R(t)} e_B(dy) = f(1, 0)C(B) ,$$

and

$$(2.7) \quad \lim_{T \to \infty} \lim_{t \to \infty} \int_0^T \left[\int_{\bar{B}} \int_{\bar{B}} H_B(x, ds, dz) R(t - s, y - z) e_B(dy) \right] R(t)^{-1} \\ = \lim_{T \to \infty} \int_0^T H_B(x, ds, \bar{B}) C(B) f(1, 0) = P_x(V_B < \infty) C(B) f(1, 0) .$$

From (2.4), we see that in order to complete the proof it suffices to show

$$(2.8) \quad \lim_{T\to\infty} \limsup_{t\to\infty} R(t)^{-1} \int_T^t \!\! \int_{\overline{B}} \!\! \int_{\overline{B}} \!\! H_{\scriptscriptstyle B}(x,\,ds,\,dz) R(t-s,\,y-z) e_{\scriptscriptstyle B}(dy) = 0 \; .$$

To accomplish this, decompose \int_{T}^{t} as $\int_{T}^{t/2} + \int_{t/2}^{t-T} + \int_{t-T}^{t}$. Since

$$\sup_{x} f(1, x) = K < \infty ,$$

it follows from the scaling property that $R(t, x) \leq KR(t)$ for all t > 0. Setting A = KC(B), we obtain

$$\int_{T}^{t/2} \le A \int_{T}^{t/2} P_x(V_{\scriptscriptstyle B} \in ds) R(t-s) \le A R(t/2) P_x(T < V_{\scriptscriptstyle B} < \infty)$$
 ,

and thus

$$\lim_{r} \lim_{t} \sup_{t} R(t)^{-1} \int_{r}^{t/2} = 0.$$

Next observe that

$$\int_{t/2}^{t-T} \le A \int_{t/2}^{t-T} P_x(V_{\scriptscriptstyle B} \in ds) R(t-s) \le A R(T) P_x(t/2 < V_{\scriptscriptstyle B} < \infty)$$
 .

By (2.4) this last term is dominated by $A^2R(T)R(t/2)$, and thus

$$\lim_{T} \lim\sup_{t} R(t)^{-1} \int_{t/2}^{t-T} = 0$$
 .

Finally, from (2.2) we see that

$$\int_{t-T}^t \leq \int_{t-T}^t \int_{\overline{B}} H_{\scriptscriptstyle B}(x,\,ds,\,dz) \int_{\overline{B}} g(y\,-z) e_{\scriptscriptstyle B}(dy) \leq \int_{t-T}^t P_{\scriptscriptstyle x}(V_{\scriptscriptstyle B}\!\in\!ds) \;.$$

But

$$P_x(t-T < V_B \le t) = \int_{\mathbb{R}^d} P_x(V_B > t-T, X(t-T) \in dy) P_y(V_B \le T)$$

 $\le \int_{\mathbb{R}^d} f(t-T, y-x) P_y(V_B \le T) dy \le K(t-T)^{-d/\alpha} \int_{\mathbb{R}^d} P_y(V_B \le T) dy$.

Since the paths X(t) are bounded a.s. on [0, T], we see that for each T there is a sphere $S_T \supset \overline{B}$, such that $P_y(X(t) \in S_T) \ge 1/2$ for all $t \le T$ and $y \in \overline{B}$. But then

$$egin{aligned} |S_{T}| &= \int_{\mathbb{R}^d} P_x(X(T) \in S_T) dx \geqq \int_{\mathbb{R}^d} dx \int_0^T \!\! \int_{\overline{B}} H_B(x,ds,dy) P_y(X(T-s) \in S_T) \ &\geqq rac{1}{2} \int_{\mathbb{R}^d} P_x(V_B \leqq T) dx \;. \end{aligned}$$

Thus

$$\lim_{t\to\infty}R(t)^{-1}\int_{t=T}^t=0.$$

This completes the proof.

Proof of Theorem 2. Clearly

$$P_x(T_B>t)=\int_{\mathbb{R}^d}f(t,y-x)P_y(V_B<\infty)dy$$
 .

Using (2.2) and (2.3) we see that

$$P_x(T_{\scriptscriptstyle B}>t)=\int_{\overline{\scriptscriptstyle B}}R(\mathsf{t},y-x)e_{\scriptscriptstyle B}(dy)$$
 ,

from which the theorem follows.

REMARK. When $d/2 < \alpha < d$, it is possible to establish Theorem 1 by a much simpler argument. Set

$$egin{align} Q_{\!\scriptscriptstyle B}^\lambda(x) &= \int_{\scriptscriptstyle 0}^\infty \! e^{-\lambda t} P_x(t < V_{\scriptscriptstyle B} < \infty) dt \;, \ &H_{\scriptscriptstyle B}^\lambda(x,\, dy) &= \int_{\scriptscriptstyle 0}^\infty \! e^{-\lambda t} P_x(V_{\scriptscriptstyle B} \! \in \! dt,\, x(t) \! \in \! dy) \end{split}$$

and

$$R^{\lambda}(x) = \int_0^{\infty} R(t, x) e^{-\lambda t} dt$$
.

Then from (2.4) we obtain

$$(2.9) \qquad Q_{\scriptscriptstyle B}^{\scriptscriptstyle \lambda}(x) = \int_{\scriptscriptstyle \overline{B}} \biggl[R^{\scriptscriptstyle \lambda}(y-x) - \int_{\scriptscriptstyle \overline{B}} H_{\scriptscriptstyle B}^{\scriptscriptstyle \lambda}(x,\,dz) R^{\scriptscriptstyle \lambda}(y-z) \biggr] e_{\scriptscriptstyle B}(dy) \; .$$

It follows from (2.5) that uniformly in x on compacts,

$$\lim_{\lambda\downarrow0}R^{\lambda}\!(x)\lambda^{2-d/lpha}=f(1,\,0)\!\Big[rac{d}{lpha}-1\Big]^{\!-1}\!arGamma(2-d/lpha)$$
 .

Consequently, from (2.9), we see that

$$\lim_{\lambda \downarrow 0} Q_B^{\lambda}(x) \lambda^{2-d/lpha} = f(1,0) C(B) P_x(V_B = \infty) \left[rac{d}{lpha} - 1
ight]^{-1} \Gamma(2-d/lpha)$$
 .

An appeal to Karamata's theorem, and the fact that $P_x(t < V_B < \infty)$ is monotone in t, then yields (1.2).

The above argument breaks down when $\alpha < d/2$ since

$$\lim_{\lambda\downarrow0}R^{\lambda}\!(x)<\infty$$
 ,

and the more complicated proof given previously is needed.

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