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Let X and Y be Banach spaces and T, respectively S, be a bounded linear transformation mapping X into Y, respectively Y into X. It is well-known that a nonzero complex number λ belongs to the spectrum of ST precisely when λ belongs to the spectrum of TS. The main result of §2 shows that for $\lambda \neq 0$ the states of the operators $ST - \lambda I_x$, $TS - \lambda I_r$ agree.

Sufficient conditions are obtained for this same result to hold when T and S are unbounded closed linear transformations from X into Y and Y into X respectively. Section 4 compares spectral decompositions of ST and TS when these sufficient conditions are satisfied.

Throughout this paper D(A) and R(A) will denote the domain and range of A. The resolvent of A will be denoted $\rho(A)$, the spectrum $\sigma(A)$, the point spectrum p(A) and the approximate point spectrum a(A). [X, Y] will denote the set of all bounded linear transformations, defined on the Banach space X into the Banach space Y. Any other notation used will agree with that of [3]. When no confusion will arise the identity operator will be denoted by I regardless of the space. The following preliminary result can be easily varified.

PROPOSITION 1.1. If $T: D(T) \subset X \rightarrow Y$, $S: D(S) \subset Y \rightarrow X$ and $\lambda \neq 0$, then $\lambda \in p(TS)$ if and only if $\lambda \in p(ST)$.

2. Continuous transformations.

PROPOSITION 2.1. If $\lambda \neq 0$ then $\overline{R(ST - \lambda I)} = X$ precisely when $\overline{R(TS - \lambda I)} = Y$.

Proof. $\overline{R(ST - \lambda I)} \neq X$ implies that there exists an $x' \in X'$, $x' \neq 0$ such that $x'((ST - \lambda I)(x)) = 0$ for all $x \in X$. Consequently for all $x \in X$, $0 = (ST - \lambda I)'(x'(x)) = (T'S' - \lambda I)(x'(x))$ and $\lambda \in p(T'S')$. By Proposition 1.1, $\lambda \in p(S'T')$ so $y' \in Y'$, $y' \neq 0$ exists with the property that for each $y \in Y$, $0 = (S'T' - \lambda I)(y'(y)) = y'((TS - \lambda I)(y))$. Thus $\overline{R(TS - \lambda I)} \neq Y$.

The following is a construction of a "generalized" Banach space in the manner of that of Berberian [2].

Denote by glim a fixed "generalized Banach limit" defined for all

bounded sequences of complex numbers and having properties: ([1] - page 34)

(i) $\operatorname{glim}(\lambda_n + \mu_n) = \operatorname{glim} \lambda_n + \operatorname{glim} \mu_n;$

(ii) glim $(\lambda \lambda_n) = \lambda$ glim λ_n ;

(iii) glim $\lambda_n = \lim \lambda_n$ if $\{\lambda_n\}$ converges;

(iv) glim $\lambda_n \geq 0$ whenever $\lambda_n \geq 0$ for each n.

For a Banach space X, denote by $\mathscr{B}(X)$ the set of all sequences $\{x_n\}$ of elements of X for which $\sup ||x_n|| < \infty$. If for $s = \{x_n\}$ and $t = \{y_n\}$ in $\mathscr{B}(X)$ and complex λ we define $s + t = \{x_n + y_n\}$, $\lambda s = \{\lambda x_n\}$ and $||s||_1 = \operatorname{glim} ||x_n||$ it is clear that $\mathscr{B}(X)$ is a prenormed space. If $\mathscr{N}(X) = \{s \in \mathscr{B}(X): ||s||_1 = 0\}$ then $\mathscr{P}(X) = \mathscr{B}(X)/\mathscr{N}(X)$ is a normed vector space whose completion will be denoted by $\mathscr{K}(X)$. Since $x \mapsto \{x\} + \mathscr{N}(X)$ is an isomorphism of X into a closed linear subspace X' of the Banach space $\mathscr{K}(X)$, X can be identified with this subspace and X' is called the generalized extension of X.

For $T \in [X, Y]$ define $\mathscr{B}(T): \mathscr{B}(X) \to \mathscr{B}(Y)$ as $\mathscr{B}(T): s = \{x_n\} \mapsto \{Tx_n\}$. T is bounded so $\mathscr{B}(T)$ is bounded and $||\mathscr{B}(T)||_1 = ||T||$. Moreover, $\mathscr{B}(T): \mathscr{N}(X) \to \mathscr{N}(Y)$ so $\mathscr{B}(T)$ may be extended to $\mathscr{P}(X)$ and consequently to X' to obtain a unique extension $T' \in [X', Y']$ of T with ||T'|| = ||T||.

For T_1 , $T_2 \in [X, Y]$ and $S \in [Y, X]$ the following properties can be verified directly:

(i) $(T_1 + T_2)' = T_1' + T_2';$

(ii)
$$(\lambda T_1)' = \lambda T_1';$$

(iii) $(ST_1)' = S'T_1'$.

The next proposition gives the results which necessitated the preceding construction. For the Hilbert space analogue of this proposition, see Berberian [2], Theorem 1.

PROPOSITION 2.2. Let $A \in [X, X]$ then a(A) = a(A') = p(A).

Proof. $\lambda \in a(A')$ implies that for each $\varepsilon > 0$ an $s \in X'$ exists with $||(A' - \lambda I)s|| < \varepsilon ||s||$. Since $\mathscr{P}(x)$ is dense in X', it may be assumed that $s = \{x_n\} \in \mathscr{P}(X)$. Thus $||(A' - \lambda I)s|| = \text{glim} ||(A - \lambda I)x_n|| < \varepsilon \text{glim} ||x_n||$ so $0 > \text{glim} [\varepsilon ||x_n|| - ||(A - \lambda I)x_n||]$. By property (iv) of glim it must be true that for at least one $n, 0 < \varepsilon ||x_n|| - ||(A - \lambda I)x_n||$ and hence for some $x_n \in X$, $||(A - \lambda I)x_n|| < \varepsilon ||x_n||$, which implies $\lambda \in a(A)$.

To complete the proof of this proposition, if suffices to show that $a(A) \subset p(A')$. For $\lambda \in a(A)$, a sequence $\{x_n\}$ in X exists with $||x_n|| = 1$ for all n and $||(A - \lambda I)x_n|| \rightarrow 0$. $\{x_n\}$ is bounded in norm so $s = \{x_n\} \in X'$, ||s|| = 1 and $||(A' - \lambda I)s|| = \text{glim} ||(A - \lambda I)x_n|| = 0$. Hence $\lambda \in p(A')$. Considering $T \in [X, Y]$ and $S \in [Y, X]$ we obtain:

COROLLARY 2.1. If $\lambda \neq 0$ then $\lambda \in a(TS)$ if and only if $\lambda \in a(ST)$.

Proof. By Proposition 2.2, $\lambda \in a(TS)$ implies $\lambda \in p((TS)') = p(T'S')$. Hence by Proposition 1.1, $\lambda \in p(S'T') = a(ST)$.

The preceding corollary together with the result of Propositions 1.1 and 2.1 prove the following theorem. The classification of states of a linear operator may be found in [5].

THEOREM 2.1. If $T \in [X, Y]$, $S \in [Y, X]$ and $\lambda \neq 0$, then the states of $TS - \lambda I$ and $ST - \lambda I$ agree.

Proof. To show that one of the operators cannot be in state I_s while the other is in state II_s , a theorem of Goldberg [4], Theorem II 4.4, is used which in our case states:

(i) T has a bounded inverse if and only if $R(T^*) = X^*$.

(ii) T^* has a bounded inverse if and only if R(T) = Y.

3. Closed transformations. Let T be a closed linear transformation with D(T) and R(T) both contained in the Banach space X. Suppose further that $\rho(T) \neq \phi$, that $\alpha \in \rho(T)$ is fixed and $A \in [X, X]$ is defined by $A = (T - \alpha I)^{-1}$. The following theorems are due to Taylor [6].

THEOREM 3.1. Suppose μ and λ are complex numbers satisfying $(\lambda - \alpha)\mu = 1$:

(i) If $x \in X$ and $(\mu I - A)x = y$ then $(T - \lambda I)(\mu x - y) = \mu^{-1}y$;

(ii) If $x \in D(T)$ and $(T - \lambda I)x = y$ then $(\mu I - A)x = \mu Ay$. Furthermore, $\mu I - A$ is 1-1 precisely when $T - \lambda I$ is 1-1 and on the common domain of their inverses $(\mu I - A)^{-1} = \mu^{-2}[\mu I + (T - \lambda I)^{-1}]$ and $(T - \lambda I)^{-1} = \mu(\mu I - A)^{-1}A = \mu A(\mu I - A)^{-1}$.

THEOREM 3.2. Let λ and μ satisfy $(\lambda - \alpha)\mu = 1$. Then λ belongs to $\rho(T)$ if and only if μ belongs to $\rho(A)$.

The following lemma follows from the closed graph theorem and will be needed often in our development:

LEMMA 3.1. If $P: D(P) \subset Y \rightarrow Z$ is a closed linear transformation and $Q \in [X, Y]$ where X, Y, Z are Banach spaces, then PQ is closed and if $R(Q) \subset D(P)$ then $PQ \in [X, Z]$.

For T closed with D(T) and R(T) both in X and $0 \neq \alpha \in \rho(T)$ we define $A = (T - \alpha I)^{-1}$ and $B = T(T - \alpha I)^{-1}(T - \alpha I^{-1})$. (By Lemma 3.1, $B \in [X, X]$.) The next three propositions give the substance for a method of referring a pair of closed operators to a pair which are continuous and everywhere defined.

PROPOSITION 3.1. Consider T, A, and B as defined above and $0 \neq \alpha \in \rho(T)$. For $0 \neq \lambda \neq \alpha$, let $\nu = (\lambda/(\lambda - \alpha)^2)$, $\mu = (1/(\lambda - \alpha))$. Then $R(B - \nu I) \subset R(T - \lambda I)$.

Proof. Suppose $y = (B - \nu I)x$. Then $y + \nu x = (T - \alpha I)^{-1}[x + \alpha(T - \alpha I)^{-1}x] \in D(T - \alpha I) = D(T - \lambda I)$ and $(T - \lambda I)(y + \nu x) + (\lambda - \alpha)(y + \nu x) = x + \alpha(T - \alpha I)^{-1}x$; so $-1/\alpha[(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] = \mu x - Ax$. If Theorem 3.1, part (i), is applied, we obtain that $1/\alpha[(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] \in R(T - \lambda I)$ so that

(1)
$$(T - \lambda I) \Big\{ \mu x + \frac{1}{\alpha} [(T - \lambda I)(y + \nu x) + (\lambda - \alpha)y] \\ + \frac{1}{\mu \alpha} (y + \nu x) \Big\} = \frac{-1}{\alpha \nu \mu} y \in R(T - \lambda I) .$$

PROPOSITION 3.2. If $\lambda \neq 0$ is such that for some $0 \neq \alpha \in \rho(T)$, $\alpha^2/\lambda \in \rho(T)$ also, then $R(T - \lambda I) \subset R(B - \nu I)$.

Proof. We may assume, without loss of generality, that $\lambda \neq \alpha$, for if $0 \neq \alpha \in \rho(T)$ there exists some a > 0 with $0 \notin \{\mu \mid \mid \mu - \lambda \mid < a\} \subset \rho(T)$ and $\lambda = \alpha + (a/2)e^{i\theta}$, where θ is the argument of α , will satisfy our hypothesis.

For $x \in D(T)$, $BTx = x + \alpha Ax + \alpha Bx$. Consequently, if $(T - \lambda I)x = y$, then $(y - \alpha)Bx = x + \alpha Ax - By$. Theorem 3.1, part (ii), implies $(\mu I - A)x = \mu Ay$ so $(\lambda - \alpha)Bx = \lambda \mu x - \alpha \mu Ay - By$. Thus

$$(B-
u I)(x+\mu y) = -rac{lpha
u}{\lambda}Ay -
u \mu y \ = -rac{lpha
u}{\lambda} \Big[A - rac{1}{(lpha^2/\lambda - lpha)}I \Big] y \; .$$

By hypothesis, $\alpha^2/\lambda \in \rho(T)$, so Theorem 3.2 may be used to obtain

$$rac{1}{(lpha^2/\lambda-lpha)}\in
ho(A)$$

and

$$-rac{lpha
u}{\lambda} y = \left[A - rac{\lambda}{(lpha^2 - lpha \lambda)} I
ight]^{-1} (B -
u I) (x + \mu y) \, .$$

Since $\left[A - \frac{\lambda}{(\alpha^2 - \alpha\lambda)}I\right]^{-1}$ and $B - \nu I$ commute,

$$(2) \quad -\frac{\alpha\nu}{\lambda}y = (B-\nu I) \Big[A - \frac{1}{(\alpha^2/\lambda - \alpha)} I \Big]^{-1} (x + \mu y) \in R(B-\nu I) \ .$$

The following proposition follows easily by considering equations (1) and (2), together with the result of Theorem 3.2.

PROPOSITION 3.3. Suppose $\lambda \neq 0$ and for some $\alpha \neq 0$ in $\rho(T)$, $\alpha^2/\lambda \in \rho(T)$ also. Then $T - \lambda I$ is 1-1 precisely when $B - \nu I$ is 1-1.

The following theorem is an immediate consequence of the Propositions 3.1, 3.2, 3.3, and the closed graph theorem.

THEOREM 3.3. Let T be a closed linear operator with D(T) and R(T) both contained in the Banach space X. Suppose $\lambda \neq 0$ is a complex number with the property that for some $\alpha \in \rho(T)$, $\alpha^2/\lambda \in \rho(T)$ also, then the state of $T - \lambda I$ is the same as the state of $B - \nu I$.

For the remainder of this section, we consider a pair of closed linear transformations, $T: D(T) \subset X \to Y$ and $S: D(S) \subset Y \to X$, with the property that ST and TS are both closed on their respective domains. We assume moreover that $\rho(TS) \cap \rho(ST) \neq \varphi$ and for $\alpha \in \rho(TS) \cap \rho(ST)$ fixed we define:

$$A(ST)=(ST-lpha I)^{\scriptscriptstyle -1}$$
 , $A(TS)=(TS-lpha I)^{\scriptscriptstyle -1}$

and

$$B(ST) = ST(ST - \alpha I)^{-1}(ST - \alpha I)^{-1}$$

 $B(TS) = TS(TS - \alpha I)^{-1}(TS - \alpha I)^{-1}$.

When $x \in D(T)$, TA(ST)x = A(TS)Tx; thus B(ST) and B(TS) may be rewritten:

$$egin{aligned} B(ST) &= S(TS - lpha I)^{-1} T(ST - lpha I)^{-1} = SA(TS) TA(ST) \ B(TS) &= T(ST - lpha I)^{-1} S(TS - lpha I)^{-1} = TA(ST) SA(TS) \ . \end{aligned}$$

Since $R(A(ST)) \subset D(T)$ and $R(A(TS)) \subset D(S)$, Lemma 3.1 shows that $TA(ST) \in [X, Y]$ and $SA(TS) \in [Y, X]$. By Theorem 2.1, whenever $\nu \neq 0$, the state of $B(TS) - \nu I$ is the same as the state of $B(ST) - \nu I$, which gives the main result in this section:

THEOREM 3.4. If $\lambda \neq 0$ is such that for some $\alpha \in \rho(ST) \cap \rho(TS)$, $\alpha^2/\lambda \in \rho(ST) \cap \rho(TS)$ also, the state of $ST - \lambda I$ is the same as the state of $TS - \lambda I$.

It is conjectured that the hypothesis of Theorem 3.4 can be

weakened to simply requiring that $\rho(ST) \cap \rho(TS) \neq \{0\}$. A different method of proof would likely be needed, however.

In the remainder of this section we consider conditions on the transformations S and T which will ensure that the hypotheses of Theorem 3.4 are fulfilled. We first need the following propositions:

PROPOSITION 3.4. If T, S, TS, and ST are closed and $\lambda \neq 0$ is such that $\lambda \in \sigma(TS) \cap \rho(ST)$, then whenever $\alpha \in \rho(TS) \cap \rho(ST)$,

$$\frac{lpha^2}{\lambda} \in \sigma(ST)$$
 .

Proof. Since $\lambda \in \rho(ST)$, $ST - \lambda I$ is 1-1; so by Theorem 3.4, $TS - \lambda I$ is also 1-1, and $\lambda \in \sigma(TS)$ implies $\overline{R(TS - \lambda I)} \neq Y$. For $0 \neq \alpha \in \rho(TS)$ and $\nu = \lambda/(\lambda - \alpha)^2$ we have by Proposition 3.1

$$R(B(TS) - \nu I) \subset R(TS - \lambda I)$$

and consequently

$$\overline{R(B(TS)-
uI)}
eq Y$$
.

By Theorem 3.3 $R(B(ST) - \nu I) \neq X$. If $\alpha^2/\lambda \in \rho(ST)$, then

$$R(ST - \lambda I) \subset R(B(ST) - \nu I)$$
,

 \mathbf{so}

$$\overline{R(ST)-\lambda I)}
eq X$$
 .

This clearly contradicts our assumption of $\lambda \in \rho(ST)$.

PROPOSITION 3.5. If T, S, TS, and ST are closed and ρ_1 , respectively ρ_2 , are connected components of $\rho(ST)$, respectively $\rho(TS)$, then $(\rho_1 - \rho_2) \cup (\rho_2 - \rho_1) \subset \{0\}.$

Proof. It suffices to show that both $\rho_1 \cap \partial \rho_2 \subset \{0\}$, where $\partial \rho_2$ denotes the boundary of ρ_2 , and $\rho_2 \cap \partial \rho_1 \subset \{0\}$.

To prove the former, suppose $0 \neq \lambda \in \rho_1 \cap \partial \rho_2$. Then $\lambda \in \sigma(TS)$ and there is an open set N with $\lambda \in N \subset \rho_1$. We may therefore construct a sequence $\lambda_n \in \rho_1 \cap \rho_2$ for all n with the property that λ_n converges to λ . By Proposition 3.4 $\mu^2/\lambda \in \sigma(ST)$ whenever $\mu \in \rho(ST) \cap \rho(TS)$. In particular $(\lambda_n)^2/\lambda \in \sigma(ST)$ for all n. This is clearly impossible since $(\lambda_n)^2/\lambda$ converges to λ and eventually $(\lambda_n)^2/\lambda \in N$.

The next two propositions give sufficient conditions for the hypothesis of Theorem 3.4 to be fulfilled.

PROPOSITION 3.6. If T, S, TS, and ST are closed and such that there exists a neighborhood of zero intersected with an open half plane about the origin which is a subset of $\rho(ST) \cap \rho(TS)$ then the state of $TS - \lambda I$ is the same as the state of $ST - \lambda I$ whenever $\mu \neq 0$.

Proof. Suppose $D = \{\mu \mid | \mu | < r\} \subset U$ is contained in $\rho(ST) \cap \rho(TS)$, where U denotes the open upper half plane.

Given $\lambda \neq 0$, choose α satisfying

(i) $0 < |\alpha| < \min\{r, |\lambda|\};$

- (ii) argument of α , arg α , is as follows:
 - (a) $\pi/4$ if arg $\lambda = 0$;
 - (b) $\operatorname{arg} \lambda$ if $0 < \operatorname{arg} \lambda < \pi$;
 - (c) $3\pi/4$ if $\arg \lambda = \pi$;
 - (d) $\pi/2 + \arg \lambda/4$ if $\pi < \arg \lambda < 2\pi$.

By direct calculation, it can be shown that both α and α^2/λ belong to $D \subset \rho(ST) \cap \rho(TS)$ and consequently by Theorem 3.4, the states of $TS - \lambda I$ and $ST - \lambda I$ agree. It is clear, by the method in which α was chosen, that our assumption of U being the open upper half plane involves no loss of generality. Any other open half plane about the origin would simply introduce a change in $\arg \alpha$.

Note that if S, T, ST, and TS are closed operators in a Hilbert space with both ST and TS self-adjoint, the hypotheses of Proposition 3.6 hold.

PROPOSITION 3.7. Let T, S, TS, and ST be closed and such that there exists a half plane entirely contained in $\rho(ST) \cap \rho(TS)$. Then the state of $ST - \lambda I$ is the same as the state of $TS - \lambda I$ whenever $\lambda \neq 0$.

Proof. Suppose that U is a half plane contained in $\rho(ST) \cap \rho(TS)$. We may assume, without loss of generality, that

$$U = \{\mu \mid IM(\mu) > R\}$$
 where $R > 1$.

For $\lambda \neq 0$ we choose α as follows:

(i) If $\arg \lambda = 0$, then $\arg \alpha = \pi/4$ and $|\alpha| = \max \{\alpha R, |\lambda|\};$

(ii) If $\arg \lambda = \pi$, then $\arg \alpha = 3\pi/4$ and $|\alpha| = \max \{\alpha R, |\lambda|\}$;

(iii) If $0 < \arg \lambda < \pi$, then $\arg \alpha = \arg \lambda$ and

$$| \alpha | = \max \left\{ | \lambda |, \frac{lpha R}{\sin (rg \lambda)}
ight\};$$

(iv) If $\pi < \arg \lambda < 2\pi$, then $\arg \alpha = \arg \lambda - \pi$ and

$$| lpha | = \max \left\{ | \lambda |, \frac{R}{\sin (rg \lambda - \pi)}
ight\}$$

It can be demonstrated in a straight forward manner that both α and α^2/λ are in $\rho(ST) \cap \rho(TS)$ in each case.

4. Spectral decompositions. The notation in the following discussion is full explained in [5].

THEOREM 4.1. If D is a bounded Cauchy domain satisfying

 $\partial D \subset \rho(ST) \cap \rho(TS)$

then there exists a pair of closed subspaces (X_1, X_2) of X and (Y_1, Y_2) of Y such that

(i) (X_1, X_2) completely reduces ST;

(ii) (Y_1, Y_2) completely reduces TS;

(iii) $(ST)_1 = ST \mid X_1$ and $(TS)_1 = TS \mid Y_1$ are continuous with domains X_1 , Y_1 respectively;

(iv) $T: X_i \to Y_i, S: Y_i \to X_i, i = 1, 2.$

Proof. Let

$$\sigma_{\scriptscriptstyle 1} = D \cap \sigma_{\scriptscriptstyle e}(ST)$$
 , $\sigma_{\scriptscriptstyle 2} = D \cap \sigma_{\scriptscriptstyle e}(TS)$,

where σ_{e} denotes the extended spectrum of the transformation. σ_{1} and σ_{2} are bounded spectral sets for ST and TS respectively. Let $\tau_{1} = \sigma_{e}(ST) - \sigma_{1}$ and $\tau_{2} = \sigma_{e}(TS) - \sigma_{2}$ be their complementary spectral sets.

If $E(\sigma_1)$, $E(\sigma_2)$, $E(\tau_1)$, and $E(\tau_2)$ are the projections associated with these spectral sets with ranges X_1 , Y_1 , X_2 , and Y_2 respectively, it is well-known, see [5], that statements (i), (ii), and (iii) are satisfied.

For $x \in X$, $E(\sigma_1)x \in X_1$ and

$$egin{aligned} TE(\sigma_{\scriptscriptstyle 1})x &= \ Tigg[-rac{1}{2\pi i}\int_{\scriptscriptstyle +\partial D}(ST-\lambda I)^{\scriptscriptstyle -1}d\lambdaigg]x \ &= igg[-rac{1}{2\pi i}\int_{\scriptscriptstyle +\partial D}T(ST-\lambda I)^{\scriptscriptstyle -1}d\lambdaigg]x \ &= igg[-rac{1}{2\pi i}\int_{\scriptscriptstyle +\partial D}(TS-\lambda I)^{\scriptscriptstyle -1}d\lambdaigg]Tx \ &= E(\sigma_{\scriptscriptstyle 2})Tx \;. \end{aligned}$$

so $T: X_1 \to Y_1$.

Similarly, if $x \in X$, $E(\tau_1)x \in X_2$ and

$$TE(\tau_1) = T(I - E(\sigma_1))x = Tx - TE(\sigma_1)x$$
$$= (I - E(\sigma_2))Tx = E(\tau_2)Tx .$$

So $T: X_2 \to Y_2$.

In a similar manner S: $Y_1 \rightarrow X_1$, S: $Y_2 \rightarrow X_2$ which completes the proof of the theorem.

THEOREM 4.2. If D is a bounded Cauchy domain with

 $\partial D \subset \rho(ST) \cap \rho(TS)$

and

$$\sigma_{\scriptscriptstyle 1} = D \cap \sigma_{\scriptscriptstyle e}(ST)$$
 , $\sigma_{\scriptscriptstyle 2} = D \cap \sigma_{\scriptscriptstyle e}(TS)$,

then

 $(\sigma_{\scriptscriptstyle 1}-\sigma_{\scriptscriptstyle 2})\cup(\sigma_{\scriptscriptstyle 2}-\sigma_{\scriptscriptstyle 1})\,{\subset}\,\{0\}$.

If in addition $0 \in D$, then

(i) the complementary spectral sets τ_1 and τ_2 are equal;

(ii) the state of $ST - \lambda I$ is the same as the state of $TS - \lambda I$, whenever $\lambda \neq 0$.

Proof. Using the notation of Theorem 4.1, let $T_i = T | X_i$, $S_i = S | Y_i$, i = 1, 2. Since $T_i, S_i, T_i S_i$, and $S_i T_i$, i = 1, 2, are restrictions of closed operators to closed subspaces, they are closed. Furthermore, $S_i T_i = (ST)_i$, $T_i S_i = (TS)_i$ for i = 1, 2.

By Theorem 4.1, $S_1T_1 \in [X_1, X_1]$ and $T_1S_1 \in [Y_1, Y_1]$ and therefore satisfy the hypotheses of Theorem 1.1. Thus for $\lambda \neq 0$, the state of $S_1T_1 - \lambda E(\sigma_1)$ agrees with the state of $T_1S_1 - \lambda E(\sigma_2)$.

When $0 \in D$ the sets $\sigma(S_2T_2) = \tau_1$ and $\sigma(T_2S_2) = \tau_2$ are bounded away from zero. Consequently by Proposition 3.6, the state of $S_2T_2 - \lambda E(\tau_1)$ agrees with the state of $T_2S_2 - \lambda E(\tau_2)$ whenever $\lambda \neq 0$.

It can be seen that the above is both necessary and sufficient for the state of $ST - \lambda I$ to be the same as the state of $TS - \lambda I$.

From the preceding theorems we obtain the final results:

THEOREM 4.3. Suppose $0 \in \rho(TS) \cap \sigma(ST)$ and a bounded Cauchy domain D exists satisfying:

(i) $\partial D \subset \rho(ST) \cap \rho(TS);$

(ii) $0 \in D$.

If $\sigma_1, \dots, \sigma_n$ is a spectral decomposition of $\sigma_e(ST)$ then $\sigma_0, \sigma_1, \dots, \sigma_n$ is a spectral decomposition of $\sigma_e(TS)$ where

$$\sigma_0 = \{0\}$$

whenever $0 \in \sigma(TS) \cap \rho(ST)$, and is empty otherwise.

Moreover, if $E_i(ST)$ and $E_i(TS)$ are the projections associated with these spectral sets with ranges X_i and Y_i respectively, then

$$T: X_i \longrightarrow Y_i ;$$

$$S: Y_i \longrightarrow X_i$$

where $i = 1, \dots, n$, and when $0 \in \sigma(TS) \cap \rho(ST)$,

 $S: Y_{\scriptscriptstyle 0} \longrightarrow \{0\}$.

Proof. First note that by Theorem 4.2,

$$(\sigma_{e}(ST) - \sigma_{e}(TS)) \cup (\sigma_{e}(TS) - \sigma_{e}(ST)) \subset \{0\}$$

and since $\sigma_{\epsilon}(ST)$ and $\sigma_{\epsilon}(TS)$ are both closed subsets of the complex plane, if $0 \in \sigma(TS) \cap \rho(ST)$ it must be an isolated point in $\sigma(TS)$. This demonstrates that the spectral decomposition $\sigma_1, \dots, \sigma_n$ of $\sigma_{\epsilon}(ST)$ gives rise to the spectral decomposition $\sigma_0, \sigma_1, \dots, \sigma_n$ of $\sigma_{\epsilon}(TS)$.

If $\infty \in \sigma_{\epsilon}(ST)$, i.e., if $ST \notin [X, X]$, assume that $\infty \in \sigma_n$. Then $\sigma_1, \dots, \sigma_{n-1}$ are bounded spectral sets for both ST and TS.

Let D_i be an admissible domain for σ_i , $i = 1, \dots, n-1$. Then

$$egin{aligned} E_i(ST) &= -rac{1}{2\pi i}\int_{+\partial D_i}(ST-\lambda I)^{-1}d\lambda\ E_i(TS) &= -rac{1}{2\pi i}\int_{+\partial D_i}(TS-\lambda I)^{-1}d\lambda \ . \end{aligned}$$

and

By Theorem 4.1

$$\frac{\partial f}{\partial x_i} = \frac{1}{2\pi i} \int_{+\partial D_i} (1 \partial f - x_i) dx_i$$

$$T: X_i \longrightarrow Y_i ,$$

$$S: Y_i \longrightarrow X_i ,$$

 $i = 1, \dots, n-1$, moreover T, S are continuous and everywhere defined on these subspaces.

Further, if $0 \in \sigma(TS) \cap \rho(ST)$ and D_0 is an admissible domain for σ_0 , let $y \in Y_0$. By Theorem 4.1, $y \in D(S)$ and

$$egin{aligned} Sy &= SE_{\scriptscriptstyle 0}(TS)y \ &= S\Big(-rac{1}{2\pi i}\int_{+lpha D_0}(TS-\lambda I)^{-1}d\lambda\Big)y \ &= \Big(-rac{1}{2\pi i}\int_{+lpha D_0}(ST-\lambda I)^{-1}d\lambda\Big)Sy \ &= 0 \;. \end{aligned}$$

To show that $T: X_n \to Y_n$, $S: Y_n \to X_n$ observe that

$$E_n(ST) = I - \sum_{i=1}^{n-1} E_i(ST)$$

and

$$E_n(TS) = I - \sum_{i=0}^{n-1} E_i(TS)$$

where $E_0(TS) = 0$ if $0 \in \rho(TS)$.

When $T \in [X, Y]$, $S \in [Y, X]$ we clearly have a bounded Cauchy domain

$$D = \{\mu \, | \, | \, \mu \, | < \max \, (|| \, ST \, ||, \, || \, TS \, ||) + 1 \}$$

which satisfies the conditions of Theorem 4.3. Hence:

COROLLARY 4.1. If $T \in [X, Y]$, $S \in [Y, X]$ and $0 \notin \rho(TS) \cap \sigma(ST)$ then a spectral decomposition $\sigma_1, \dots, \sigma_n$ of $\sigma(ST)$ gives a spectral decomposition $\sigma_0, \sigma_1, \dots, \sigma_n$ of $\sigma(TS)$ where

$$\sigma_{_0} = egin{cases} \{0\} & whenever & 0 \in \sigma(TS) \cap
ho(ST) \ \phi & otherwise \ . \end{cases}$$

Moreover, if $E_i(ST)$ and $E_i(TS)$ are the projections associated with the spectral sets with ranges X_i and Y_i respectively, then $T: X_i \to Y_i$, $S: Y_i \to X_i$, $i = 1, \dots, n$ and when $0 \in \sigma(TS) \cap \rho(ST)$, $S: Y_0 \to \{0\}$.

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