Pacific Journal of Mathematics

THE SPLITTING OF EXTENSIONS OF SL(3, 3) BY THE VECTOR SPACE F_3^3 .

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Vol. 63, No. 2

April 1976

THE SPLITTING OF EXTENSIONS OF SL(3, 3) BY THE VECTOR SPACE F_3^3

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We give two proofs that $H^{2}(SL(3, 3), F_{3}^{*}) = 0$. This result has appeared in a paper by Sah, [6], but our methods are relatively elementary, i.e., we require only elementary homological algebra and do a group-theoretic analysis of an extension of SL(3, 3) by F_{3}^{*} to show that the extension splits. The starting point is to notice that the vector space is a free module for $F_{3}(\langle x \rangle)$, where x has Jordan canonical form $\begin{pmatrix} 1 & 1 & 0\\ 0 & 1 & 1\\ 0 & 0 & 1 \end{pmatrix}$. We then can exploit the vanishing of $H^{4}(\langle x \rangle, F_{3}^{*}) i=$ 1, 2.

For elementary linear algebra, we refer to [2] and for cohomology of groups, we refer to [1], [4], [5] or [6]. Group theoretic notation is standard and follows [3]. Let V be a 3-dimensional F_3 -vector space and let SL(3, 3) be the associated special linear group. Let v_1, v_2, v_3 be a basis for V. Define, for $i, j \in \{1, 2, 3\}, i \neq j$, and $t \in F_3$, $x_{ij}(t) \in SL(3, 3)$ by

$$x_{ij}(t){:}\; v_k \longmapsto egin{cases} v_k & k
eq i \ v_i + t v_j, \ k = i \ . \end{cases}$$

Inspection of the Jordan canonical form shows that all $x_{ij}(t)$, $t \neq 0$, are conjugate in $GL(3, 3) = \{\pm I\} \times SL(3, 3)$, hence in SL(3, 3).

Set G = SL(3, 3). We let

$$(*) 1 \longrightarrow V \longrightarrow G^* \xrightarrow{\pi} G \longrightarrow 1$$

be an arbitrary extension of G by V with the above action. We will show (*) is split. We use the convention that $u^* \in G^*$ is a representative (arbitrary, unless otherwise specified) for $u \in G$.

The alternate proof of splitting (given later) is much neater than the first version. The methods are quite different, however, and it seems worthwhile to give two proofs.

LEMMA 1. Let $x = x_{12}(1)x_{23}(1)x_{13}(-1)$. Then $C_G(x) = \langle x, x_{13}(1) \rangle$. If $t \in G$ is an involution which inverts x, then t centralizes $x_{13}(1)$.

Proof. The first statement is elementary linear algebra. Namely, x has a cyclic vector in V, so that any transformation which commutes with x is a polynomial in x. Since x has minimal polynomial of

degree 3, its full commuting algebra is all matrices of the shape

$$egin{pmatrix} a & b & c \ 0 & a & b \ 0 & 0 & a \end{pmatrix}$$
 , a, b, $c \in F_3$.

The first statement is now clear. As for the second, it suffices to display an element t with the required properties, e.g.

	$/^{-1}$	$^{-1}$	0/	
t =	0	1	0 0	.
	\ 0	0	-1/	

The lemma is proven.

LEMMA 2. $x_{12}(1)x_{23}(1)x_{13}(-1)$ and all its conjugates are represented in G^{*} by elements of order 3. Any two such representatives are conjugate by an element of V.

Proof. The Jordan canonical form for $x = x_{12}(1)x_{23}(1)x_{13}(-1)$ indicates that V is a free $F_3\langle x \rangle$ -module. So $H^i(\langle x \rangle, V) = 0$ for $i \ge 1$. Both statements follow.

LEMMA 3. Each $x_{ij}(t)$ is represented in G^* by an element of order 3, which commutes with an involution of G^* .

Proof. We may assume
$$i = 1, j = 3, t = 1$$
. Let $x = x_{12}(1)x_{23}(1)x_{13}(-1)$,

and let $x^* \in G^*$ represent x, $|x^*|=3$. Again by Lemma 2, a Frattinilike argument shows that $N_G(\langle x \rangle)^* = V \cdot N_{G^*}(\langle x^* \rangle)$. Choose $y \in N_{G^*}(\langle x^* \rangle)$ with $y^{\pi} = x_{13}(1)$. Then $C_{G^*}(x^*) = \langle x^*, y, v_3 \rangle$ is abelian. Let $t \in N_{G^*}(\langle x^* \rangle)$ be an involution inverting x^* . Then by Lemma 1, t^{π} centralizes $x_{13}(1)$ and inverts v_3 . By Fittings theorem.

$$C_{{\scriptscriptstyle G}*}\!(x^*) = \langle y_{\scriptscriptstyle 1}
angle imes \langle x, \, v_{\scriptscriptstyle 3}
angle$$

where $\langle y_1 \rangle = C_{G^*}(\langle x^*, t \rangle)$. Clearly $|y_1| = 3$ and $1 \neq y_1^{\pi} \in \langle x_{13}(1) \rangle$. This proves the lemma.

LEMMA 4. If t is an involution of G^* , $C_{G^*}(t)$ has a Sylow 3subgroup isomorphic to $Z_3 \times Z_3$.

Proof. Since G has one class of involutions, so does G^* . So, we apply Lemma 3 to see that t centralizes an element of order 3

outside V. Since $|C_{\nu}(t)| = 3$ and $C_{\sigma}(t^{\pi}) \cong \operatorname{GL}(2, 3)$, we are done by the Frattini argument namely, $\langle t \rangle \in \operatorname{Syl}_2(V \langle t \rangle)$ and $V \langle t \rangle \triangleleft H$, where H is the preimage in G^* of $C_{\sigma}(t^{\pi})$.

In what follows, let $R = N_{G^*}(\langle v_3 \rangle)$ and $Q = 0_3(R)$. Then

$$egin{aligned} R^{\pi} &= egin{pmatrix} \left(egin{aligned} && a \ A && b \ 0 && 0 && c \ \end{pmatrix}
ight| A \in \mathrm{GL}(2,\ 3),\ a,\ b \in F_3,\ c &= (\det A)^{-1} \ \end{pmatrix} \ Q^{\pi} &= egin{pmatrix} \left(egin{pmatrix} 1 && 0 && a \ 0 && 1 && b \ 0 && 0 && 1 \ \end{pmatrix}
ight| a,\ b \in F_3 \ . \end{aligned}$$

Let

$$h = egin{pmatrix} -1 & 0 & 0 \ 0 & -1 & 0 \ 0 & 0 & 1 \end{pmatrix}$$

and let—denote images under $R \to R/\langle v_s \rangle$. Let $h^* \in R$ be an involution representing h.

LEMMA 5. \overline{Q} is inverted by h^* . Also, \overline{Q} is elementary abelian and Q is extra special of order 3^5 , exponent 3, with center $\langle v_3 \rangle$.

Proof. The first statement is clear since h inverts Q^{π} and $\langle v_1, v_2 \rangle$. Therefore, \overline{Q} is abelian. From Lemma 3, we get that \overline{Q} is elementary and the action of members of Q^{π} on V implies that Q is extra special. Since Q^{π} is generated by elements of order 3, by Lemma 3 again, Q has exponent 3.

We now require a technical result for studying automorphisms of Q. Since automorphisms commute with commutation, we have a homorphism (which is actually onto) Aut $(Q) \rightarrow \text{Sp}_0(4, 3)$, the group of similitudes of a nondegenerate alternating bilinear form from F_3^{t} to F_3 (a similitude preserves the form up to a scalar multiple; we have $|\text{Sp}_0(4, 3): \text{Sp}(4, 3) = |F_3^{\times}| = 2$, where Sp (4, 3) is the symplectic group, i.e. the group preserving the form).

LEMMA 6. Let M be a 4-dimensional F_s -vector space supporting a nondegenerate alternating form (,) and let $\text{Sp}_0(4, 3)$, Sp(4, 3) be the associated group of similitudes, resp. symplectic group. Let I be a maximal totally isotropic subspace and let K be its (global) stabilizer in $\text{Sp}_0(4, 3)$. Then

(i) dim I = 2

(ii) If J is a maximal totally isotropic subspace complementing

I in M we may choose a basis a_1, b_1 for I, a_2, b_2 for J so that $(a_i, b_j) = \delta_{ij}$ and $(a_i, a_j) = (b_i, b_j) = 0$. With respect to the basis $\{a_1, a_2, b_1, b_2\}$ for V, elements of K have the shape

$$\begin{pmatrix} A & B \\ 0 & c^{t}A^{-1} \end{pmatrix}$$
,

 $A \in GL(2, 3)$, B a symmetric 2×2 matrix, $c \in F_s^{\times}$; c = 1 if and only if the matrix lies in Sp(4, 3). In this notation, $0_s(K)$ consists of those matrices with $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and if L is the set of matrices with B = 0, L complements $0_s(K)$ in K.

(iii) If $Y \in Syl_3(L)$, $0_3(K)$ is a free F_3Y - module.

(iv) Any subgroup of K meeting $0_s(K)$ trivially stabilizes a maximal totally isotropic subspace which complements I, and is in fact conjugate to a subgroup of L.

Proof. Statements (i) and (ii) are straightforward. To prove (iii), we may assume $Y = \langle y \rangle$,

$$y = egin{pmatrix} 1 & 1 & 0 & 0 \ 0 & 1 & 0 & 0 \ 0 & 0 & 1 & 0 \ 0 & 0 & -1 & 1 \end{pmatrix}$$

Take

$$k(lpha,\ eta,\ \gamma) = egin{pmatrix} 1 & 0 & lpha & eta \ 0 & 1 & eta & \gamma \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$
 ,

a typical element of $0_{\mathfrak{s}}(K)$. A matrix calculation show that $y^{-1}k(\alpha, \beta, \gamma)y = k(\alpha - 2\beta + \gamma, \beta - \gamma, \gamma)$. To show $0_{\mathfrak{s}}(K)$ is a free Y-module, it suffices, since $0_{\mathfrak{s}}(K) \cong \mathbb{Z}_{\mathfrak{s}} \times \mathbb{Z}_{\mathfrak{s}} \times \mathbb{Z}_{\mathfrak{s}}$, to find a triple (α, β, γ) such that the three elements $y^{-i}k(\alpha, \beta, \gamma)y^i$, i = 0, 1, 2 are linearly independent. Any (α, β, γ) with $\beta \neq 0$ does the trick.

We now prove statement (iv). First (iii) implies that $H^i(Y, 0_{\mathfrak{s}}(K)) = 0$ for $i \ge 1$. Secondly, if $X \le K$, $X \cap 0_{\mathfrak{s}}(K) = 1$, then a Sylow 3-subgroup $X_{\mathfrak{s}}$ of X is conjugate to a subgroup of Y, and so $H^i(X_{\mathfrak{s}}, 0_{\mathfrak{s}}(K)) = 0$ for $i \ge 1$. Finally, we quote the injectiveness of the restriction $H^i(X, 0_{\mathfrak{s}}(K)) \to H^i(X_{\mathfrak{s}}, 0_{\mathfrak{s}}(K))$. A consequence is that X is conjugate in $0_{\mathfrak{s}}(K)X$ to $L \cap 0_{\mathfrak{s}}(K)X$, whence X stabilizes a maximal totally isotropic subspace complementing I.

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THEOREM. The extension (*) is split. Consequently, $H^2(SL(3, 3), F_3) = 0$.

Proof. Let $S \cong \operatorname{GL}(2, 3)$ complement $\langle v_3 \rangle$ in $C_{G^*}(h^*)$ (use Lemma 4 and Gaschütz' theorem). Easily, we see that S is faithful on Q and the map Aut $(Q) \to \operatorname{Sp}_0(4, 3)$ embeds S as a sugroup S_0 of K, where, in the notation of Lemma 6, $M = \overline{Q}, I = \overline{V}$. Also, $0_s(S) = 1$ implies $0_s(K) \cap S_0 = 1$. Hence, by Lemma 6 (iv), S_0 stabilizes a complement \overline{J} to \overline{V} in \overline{Q} , where \overline{J} is totally singular. Letting J be the preimage of \overline{J} in Q, J is elementary abelian. Since h^* inverts \overline{J} and centralizes v_s , we $J = \langle v_s \rangle \times [J, h^*]$. Then $[J, h^*]S$ complements V in R. Since $(|G: R^{\pi}|, 3) = 1$, Gaschütz theorem implies that G^* splits over V, as required.

An alternate proof was suggested by V. Landazuri in a conversation. We sketch the argument. Using Lemmas 2 and 3, we get

(i) every element of order 3 in G is represented in G^* by an element of order 3.

Let $y \in G^*$ represent $x_{ij}(1)$, |y| = 3. Since [V, y, y] = 1, a simple calculation shows

(ii) every element of the coset $Vx_{ij}(1)^* = Vy$ has order 3.

Now take $a, b \in U^*$, $a^{\pi} = x_{12}(1)$, $b^{\pi} = x_{12}(-1)x_{23}(1)$, |b| = 3 (using (i)). By (ii), |a| = |ab| = |ba| = 3. An elementary argument shows that, if ξ_1, ξ_2 are elements in any group such that $|\xi_1| = |\xi_2| = |\xi_1\xi_2| = 3$, then $\langle \xi_1\xi_2^{-1}, \xi_2^{-1}\xi_1 \rangle$ is a normal abelian subgroup of index 3 in $\langle \xi_1, \xi_2 \rangle$. Applying this to $\xi_1 = ab, \xi_2 = ba$ we see that $\langle a, b \rangle$ has a normal abelian subgroup $H = \langle [a^{-1}, b^{-1}], [a, b] \rangle$ of index 3. By (ii), H is elementary abelian. Therefore, $|\langle a, b \rangle| = 3^3$. It is easily seen that $\langle a^{\pi}, b^{\pi} \rangle = U$, and this means $\langle a, b \rangle \cap V = 1$. Our theorem now follows from Gaschütz' theorem.

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Received October 31, 1974.

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The *Pacific Journal of Mathematics* is issued monthly as of January 1966. Regular subscription rate: \$72.00 a year (6 Vols., 12 issues). Special rate: \$36.00 a year to individual members of supporting institutions.

Subscriptions, orders for back numbers, and changes of address should be sent to Pacific Journal of Mathematics, 103 Highland Boulevard, Berkeley, California, 94708.

PUBLISHED BY PACIFIC JOURNAL OF MATHEMATICS, A NON-PROFIT CORPORATION

Printed at Kokusai Bunken Insatsusha (International Academic Printing Co., Ltd.),

8-8, 3-chome, Takadanobaba, Shinjuku-ku, Tokyo 160, Japan.

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