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TAKAŜI KUSANO AND MANABU NAITO

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Takaŝi Kusano and Manabu Naito

Lovelady has recently proved the following oscillation theorem.

THEOREM. Let  $n \ge 4$  be even and  $q: [a, \infty) \to (0, \infty)$  be continuous. If  $\int_{0}^{\infty} t^{n-2}q(t)dt < \infty$  and the second order equation

$$rac{d^2 z}{dt^2} + \Bigl(rac{1}{(n-3)!} \, \int_t^\infty {(s-t)^{n-3} q(s) ds}\, \Bigr) z = 0$$

is oscillatory, then the nth order equation

$$x^{(n)} + q(t)x = 0$$

is oscillatory.

In this paper the above theorem will be extended to a class of differential equations of the form

$$rac{1}{p_n(t)} rac{d}{dt} rac{1}{p_{n-1}(t)} rac{d}{dt} \cdots rac{d}{dt} rac{1}{p_1(t)} rac{d}{dt} rac{x}{p_0(t)} + q(t)x = 0$$

Let  $n \ge 4$  be an even number, let  $p_i$ ,  $0 \le i \le n$ , and q be positive continuous functions on  $[a, \infty)$ , and consider the linear differential equation

$$(1)$$
  $L_n x + q(t) x = 0$  ,

where  $L_n$  denotes the general disconjugate operator

$$(2) L_n = \frac{1}{p_n(t)} \frac{d}{dt} \frac{1}{p_{n-1}(t)} \frac{d}{dt} \cdots \frac{d}{dt} \frac{1}{p_1(t)} \frac{d}{dt} \frac{d}{p_0(t)}$$

We introduce the notation:

$$egin{aligned} D^{\scriptscriptstyle 0}(x;\,p_{\scriptscriptstyle 0})(t) &= rac{x(t)}{p_{\scriptscriptstyle 0}(t)} \;, \ (\,3\,) & D^{\scriptstyle j}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{\scriptstyle j})(t) = rac{1}{p_{\scriptstyle j}(t)}rac{d}{dt}\,D^{j_{-1}}\!(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{\scriptstyle j-1})(t)\;, \ & 1 \leq j \leq n \end{aligned}$$

The differential operator  $L_n$  defined by (2) can then be rewritten as

$$L_n = D^n(\cdot; p_0, \cdots, p_n)$$
.

The domain  $\mathscr{D}(L_n)$  of  $L_n$  is defined to be the set of all functions  $x: [a, \infty) \to R$  such that  $D^j(x; p_0, \dots, p_j)(t), 0 \leq j \leq n$ , exist and are continuous on  $[a, \infty)$ . By a solution of equation (1) we mean a func-

tion  $x \in \mathscr{D}(L_n)$  which satisfies (1) on  $[a, \infty)$ . A nontrivial solution of (1) is called oscillatory if the set of its zeros is unbounded, and it is called nonoscillatory otherwise. Equation (1) itself is said to be oscillatory if all of its nontrivial solutions are oscillatory.

The study of the oscillatory behavior of higher-order ordinary differential equations goes back to Kneser [12] and has received a great deal of attention up to the present. For typical results on the subject we refer to the papers [1, 2, 4-6, 8, 10, 11, 13, 14, 16, 18].

In what follows we are primarily interested in the situation in which equation (1) is oscillatory. We have been motivated by the observation that there are very few effective criteria for equation (1) with general  $L_n$  to be oscillatory, though equation (1) and its nonlinear analogue have been the object of intensive investigations in recent years. The desired oscillation criterion is established in §2. It generalizes an interesting oscillation theorem of Lovelady [15] for the particular equation  $x^{(n)} + q(t)x = 0$ .

1. Preliminaries. We begin by formulating preparatory results which are needed in proving the main theorem in the next section.

Let  $i_k \in \{1, \dots, n-1\}$ ,  $1 \leq k \leq n-1$ , and  $t, s \in [a, \infty)$ . Generalizing upon notation introduced by Willett [19], we define

$$(4) \qquad I_0 = 1,$$

$$(4) \qquad I_k(t, s; p_{i_k}, \dots, p_{i_1}) = \int_s^t p_{i_k}(u) I_{k-1}(u, s; p_{i_{k-1}}, \dots, p_{i_1}) du.$$

It is easy to verify that for  $1 \leq k \leq n-1$ 

$$(5) I_k(t, s; p_{i_k}, \cdots, p_{i_1}) = (-1)^k I_k(s, t; p_{i_1}, \cdots, p_{i_k}),$$

(6) 
$$I_k(t, s; p_{i_k}, \dots, p_{i_1}) = \int_s^t p_{i_1}(u) I_{k-1}(t, u; p_{i_k}, \dots, p_{i_2}) du$$
.

For convenience of notation we put

$$(7)$$
  $J_i(t, s) = p_0(t)I_i(t, s; p_1, \cdots, p_i)$ ,  $J_i(t) = J_i(t, a)$ ,

$$(8) K_i(t, s) = p_n(t)I_i(t, s; p_{n-1}, \cdots, p_{n-i}), K_i(t) = K_i(t, a).$$

LEMMA 1. If  $x \in \mathscr{D}(L_n)$ , then for  $t, s \in [a, \infty)$  and  $0 \leq i < k \leq n-1$ 

$$(9) \qquad D^{i}(x; p_{0}, \cdots, p_{i})(t) - D^{i}(x; p_{0}, \cdots, p_{i})(s) \\ = \sum_{j=i+1}^{k} (-1)^{j-i} D^{j}(x; p_{0}, \cdots, p_{j})(s) I_{j-i}(s, t; p_{j}, \cdots, p_{i+1}) \\ + (-1)^{k-i+1} \int_{t}^{s} I_{k-i}(u, t; p_{k}, \cdots, p_{i+1}) p_{k+1}(u) \\ \times D^{k+1}(x; p_{0}, \cdots, p_{k+1})(u) du .$$

This lemma is a generalization of Taylor's formula with remainder encountered in calculus. The proof is immediate.

LEMMA 2. If there exists an eventually positive function  $y \in \mathscr{D}(L_n)$  satisfying

$$(10) L_n y + q(t) y \leq 0$$

for all large t, then equation (1) has an eventually positive solution.

This lemma exhibits an important relationship between the differential equation (1) and the differential inequality (10). For the proof see Čanturija [3].

In what follows we assume that

(11) 
$$\int_a^\infty p_i(t)dt = \infty$$
 for  $1 \leq i \leq n-1$ .

The operator  $L_n$  satisfying condition (11) is said to be in canonical form. It is known that any operator  $L_n$  of the form (2) can always be represented in canonical form in an essentially unique way (see Trench [17]).

LEMMA 3. Suppose (11) holds. If  $x \in \mathscr{D}(L_n)$  satisfies  $x(t)L_nx(t) < 0$ on  $[t_0, \infty)$ , then there exist an odd integer  $l, 1 \leq l \leq n-1$ , and a  $t_1 > t_0$  such that

(12) 
$$x(t)D^{j}(x; p_{0}, \cdots, p_{j})(t) > 0$$
 on  $[t_{1}, \infty)$  for  $0 \leq j \leq l$ ,

This lemma generalizes a well-known lemma of Kiguradze [9] and can be proved similarly.

2. Main Result. The best oscillation theorem known to date for equation (1) is the following theorem due to Trench [18].

THEOREM A. Suppose (11) holds. If (14)  $\int_{i-1}^{\infty} J_{i-1}(t)K_{n-i-1}(t)q(t)dt = \infty$  for  $i = 1, 3, \dots, n-1$ ,

then equation (1) is oscillatory.

A question naturally arises as to what will happen when condition (14) is violated. In fact, Theorem A cannot cover an important class of Euler's equations of the form

$$(15)$$
  $rac{d^m}{dt^m}t^{lpha+m}rac{d^mx}{dt^m}+ct^{lpha-m}x=0$  ,  $t\ge 1$  ,

where  $\alpha$  and c > 0 are constants with  $\alpha + m \leq 1$ , since in this case the integrals appearing in (14) converge.

An answer to this question is given in the following theorem, which reduces the oscillation of equation (1) to the oscillation of a certain set of second order linear differential equations.

THEOREM B. Suppose  $n \ge 4$ , (11) holds, and the integrals in (14) converge. Define

(16) 
$$q_{i}(t) = p_{i+1}(t) \int_{t}^{\infty} J_{i-1}(u, t) K_{n-i-2}(u, t) q(u) du ,$$
$$i = 1, 3, \dots, n-3 ;$$

(17) 
$$q_{n-1}(t) = p_{n-2}(t) \int_{t}^{\infty} J_{n-3}(u, t) K_{0}(u, t) q(u) du .$$

Then equation (1) is oscillatory if the second order equations

$$(18) \qquad \quad rac{d}{dt} \, rac{1}{p_i(t)} rac{dz}{dt} + q_i(t) z = 0 \;, \qquad i = 1, \, 3, \, \cdots, \, n-1 \;,$$

are oscillatory.

*Proof.* Suppose x(t) is a nonoscillatory solution of (1). We may suppose x(t) is eventually positive. Let  $t_0 \ge a$  be such that x(t) > 0 for  $t \ge t_0$ . Lemma 3 implies that there exists an odd integer l,  $1 \le l \le n - 1$ , such that (12) and (13) hold for  $t \ge t_1$ , provided  $t_1 > t_0$  is sufficiently large.

Suppose  $1 \leq l \leq n-3$ . Then, from Lemma 1 applied to x(t) with i = l+1, k = n-1 and  $s \geq t \geq t_1$  it follows that

$$egin{aligned} D^{l+1}&(x;\,p_0,\,\cdots,\,p_{l+1})(t) - D^{l+1}&(x;\,p_0,\,\cdots,\,p_{l+1})(s) \ &= \sum_{j=l+2}^{n-1} (-1)^{j-l-1} D^j&(x;\,p_0,\,\cdots,\,p_j)(s) I_{j-l-1}&(s,\,t;\,p_j,\,\cdots,\,p_{l+2}) \ &+ (-1)^{n-l-1} \int_t^s I_{n-l-2}&(u,\,t;\,p_{n-1},\,\cdots,\,p_{l+2}) p_n(u) D^n&(x;\,p_0,\,\cdots,\,p_n)(u) du \;. \end{aligned}$$

Using (12) and (13) in the above and letting  $s \rightarrow \infty$ , we have

(19) 
$$-D^{l+1}(x; p_0, \cdots, p_{l+1})(t) \\ \ge \int_t^\infty p_n(u) I_{n-l-2}(u, t; p_{n-1}, \cdots, p_{l+2}) q(u) x(u) du$$

for  $t \ge t_1$ . If  $l \ge 3$ , then using Lemma 1 again (with i = 0, k = l - 2,  $s = t_1$  and  $t \ge t_1$ ) and (5), we get

$$\begin{split} D^{\scriptscriptstyle 0}(x;\,p_{\scriptscriptstyle 0})(t)\,&=\,D^{\scriptscriptstyle 0}(x;\,p_{\scriptscriptstyle 0})(t_{\scriptscriptstyle 1})\\ &=\,\sum_{j=1}^{l-2}\,(-1)^{j}D^{j}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{j})(t_{\scriptscriptstyle 1})I_{j}(t_{\scriptscriptstyle 1},\,t;\,p_{j},\,\cdots,\,p_{\scriptscriptstyle 1})\\ &+\,(-1)^{l-1}\,\int_{t}^{t_{\scriptscriptstyle 1}}\,I_{l-2}(u,\,t;\,p_{l-2},\,\cdots,\,p_{\scriptscriptstyle 1})p_{l-1}(u)D^{l-1}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{l-1})(u)du\\ &=\,\sum_{j=1}^{l-2}\,D^{j}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{j})(t_{\scriptscriptstyle 1})I_{j}(t,\,t_{\scriptscriptstyle 1};\,p_{\scriptscriptstyle 1},\,\cdots,\,p_{j})\\ &+\,\int_{t}^{t_{\scriptscriptstyle 1}}\,I_{l-2}(u,\,t;\,p_{l-2},\,\cdots,\,p_{\scriptscriptstyle 1})p_{l-1}(u)D^{l-1}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{l-1})(u)du \;. \end{split}$$

Thus in view of (12) we obtain

(20) 
$$D^{0}(x; p_{0})(t) \geq \int_{t_{1}}^{t} I_{l-2}(t, u; p_{1}, \cdots, p_{l-2}) p_{l-1}(u) D^{l-1}(x; p_{0}, \cdots, p_{l-1})(u) du$$

for  $t \ge t_1$ . Combining (19) with (20) yields

$$\begin{split} &-D^{l+1}(x;\,p_{0},\,\cdots,\,p_{l+1})(t)\\ &\geqq \int_{t}^{\infty} p_{n}(u)I_{n-l-2}(u,\,t;\,p_{n-1},\,\cdots,\,p_{l+2})q(u)p_{0}(u)\\ &\qquad \times \int_{t_{1}}^{u}I_{l-2}(u,\,v;\,p_{1},\,\cdots,\,p_{l-2})p_{l-1}(v)D^{l-1}(x;\,p_{0},\,\cdots,\,p_{l-1})(v)dvdu\\ &\geqq \int_{t}^{\infty} p_{n}(u)I_{n-l-2}(u,\,t;\,p_{n-1},\,\cdots,\,p_{l+2})q(u)p_{0}(u)\\ &\qquad \times \int_{t}^{u}I_{l-2}(u,\,v;\,p_{1},\,\cdots,\,p_{l-2})p_{l-1}(v)D^{l-1}(x;\,p_{0},\,\cdots,\,p_{l-1})(v)dvdu \end{split}$$

for  $t \ge t_1$ . Since  $D^{l-1}(x; p_0, \cdots, p_{l-1})$  is increasing, we conclude from the above that

$$\begin{array}{l} -D^{l+1}(x;\,p_{0},\,\cdots,\,p_{l+1})(t)\\ \geqq D^{l-1}(x;\,p_{0},\,\cdots,\,p_{l-1})(t)\int_{t}^{\infty}\,p_{n}(u)I_{n-l-2}(u,\,t;\,p_{n-1},\,\cdots,\,p_{l+2})\\ (21) \qquad \qquad \times q(u)p_{0}(u)\int_{t}^{u}I_{l-2}(u,\,v;\,p_{1},\,\cdots,\,p_{l-2})p_{l-1}(v)dvdu\\ = D^{l-1}(x;\,p_{0},\,\cdots,\,p_{l-1})(t)\int_{t}^{\infty}\,p_{n}(u)I_{n-l-2}(u,\,t;\,p_{n-1},\,\cdots,\,p_{l+2})\\ \qquad \qquad \times q(u)p_{0}(u)I_{l-1}(u,\,t;\,p_{1},\,\cdots,\,p_{l-1})du ,\end{array}$$

where we have used formula (6). Let y(t) be given by

$$y(t) = D^{l-1}(x; p_0, \cdots, p_{l-1})(t)$$
 .

Note that y(t) > 0 and in view of (21)

(22) 
$$-D^{l+1}(x; p_0, \cdots, p_{l+1})(t) \ge y(t) \int_t^\infty K_{n-l-2}(u, t) J_{l-1}(u, t) q(u) du$$

for  $3 \leq l < n-1$  and  $t \geq t_1$ . That (22) is true for l = 1 follows immediately from (19). Since  $dy(t)/dt = p_l(t)D^l(x; p_0, \dots, p_l)(t)$ , we have

$$rac{d}{dt} rac{1}{p_l(t)} rac{dy(t)}{dt} = p_{l+1}(t) D^{l+1}(x;\,p_{\scriptscriptstyle 0},\,\cdots,\,p_{l+1})(t)$$
 ,

which together with (22) implies

$$rac{d}{dt}rac{1}{p_l(t)}rac{dy(t)}{dt}+q_l(t)y(t)\leq 0$$
 ,

where  $q_i(t)$  is defined by (16). Now from Lemma 2 it follows that the equation

$$rac{d}{dt} rac{1}{p_l(t)} rac{dz}{dt} + q_l(t) z = 0$$

has a nonoscillatory solution. But this is impossible by hypothesis. Finally, suppose l = n - 1. Integrating (1), we have

(23) 
$$D^{n-1}(x; p_0, \cdots, p_{n-1})(t) \ge \int_t^\infty p_n(u)q(u)x(u)du$$
,  $t \ge t_1$ .

On the other hand, application of Lemma 1 to the case where i = 0, k = n - 3,  $s = t_1$  and  $t \ge t_1$  shows that

$$\begin{split} D^{0}(x;\,p_{0})(t)\,&-\,D^{0}(x;\,p_{0})(t_{1})\\ &=\sum_{j=1}^{n-3}\,(-1)^{j}D^{j}(x;\,p_{0},\,\cdots,\,p_{j})(t_{1})I_{j}(t_{1},\,t;\,p_{j},\,\cdots,\,p_{1})\\ &+\,(-1)^{n-2}\int_{t}^{t_{1}}\,I_{n-3}(u,\,t;\,p_{n-3},\,\cdots,\,p_{1})p_{n-2}(u)D^{n-2}(x;\,p_{0},\,\cdots,\,p_{n-2})(u)du\\ &=\sum_{j=1}^{n-3}D^{j}(x;\,p_{0},\,\cdots,\,p_{j})(t_{1})I_{j}(t,\,t_{1};\,p_{1},\,\cdots,\,p_{j})\\ &+\,\int_{t_{1}}^{t}\,I_{n-3}(t,\,u;\,p_{1},\,\cdots,\,p_{n-3})p_{n-2}(u)D^{n-2}(x;\,p_{0},\,\cdots,\,p_{n-2})(u)du \;. \end{split}$$

This implies that

$$(24) \qquad D^{0}(x; p_{0})(t) \\ \ge \int_{t_{1}}^{t} I_{n-3}(t, u; p_{1}, \cdots, p_{n-3}) p_{n-2}(u) D^{n-2}(x; p_{0}, \cdots, p_{n-2})(u) du$$

for  $t \ge t_1$ . From (23) and (24) we obtain

$$egin{aligned} D^{n-1}(x;\,p_{_0},\,\cdots,\,p_{_{n-1}})(t)\ &&\geq \int_{t}^{\infty}\,p_n(u)q(u)p_0(u)\int_{t_1}^{u}I_{n-3}(u,\,v;\,p_{_1},\,\cdots,\,p_{_{n-3}})p_{_{n-2}}(v)\ && imes\,D^{n-2}(x;\,p_{_0},\,\cdots,\,p_{_{n-2}})(v)dvdu \end{aligned}$$

$$\geq \int_{t}^{\infty} p_{n}(u)q(u)p_{0}(u)\int_{t}^{u} I_{n-3}(u, v; p_{1}, \dots, p_{n-3})p_{n-2}(v) \\ \times D^{n-2}(x; p_{0}, \dots, p_{n-2})(v)dvdu \\ = \int_{t}^{\infty} \left(\int_{v}^{\infty} p_{n}(u)p_{0}(u)I_{n-3}(u, v; p_{1}, \dots, p_{n-3})q(u)du\right)p_{n-2}(v) \\ \times D^{n-2}(x; p_{0}, \dots, p_{n-2})(v)dv .$$

It follows that for  $t \ge t_1$ 

$$D^{n-1}(x; p_0, \cdots, p_{n-1})(t) \\ \ge \int_t^\infty \left( \int_v^\infty J_{n-3}(u, v) K_0(u, v) q(u) du \right) p_{n-2}(v) D^{n-2}(x; p_0, \cdots, p_{n-2})(v) dv \, .$$

Integrating the above inequality from  $t_1$  to t, we see that the positive function  $w(t) = D^{n-2}(x; p_0, \dots, p_{n-2})(t)$  satisfies

(25) 
$$w(t) \ge w(t_1) + \int_{t_1}^t p_{n-1}(u) \int_u^\infty q_{n-1}(v) w(v) dv du$$

for  $t \ge t_1$ , where  $q_{n-1}(t)$  is given by (17). Denote the right hand side of (25) by y(t). By differentiation

$$rac{d}{dt} rac{1}{p_{n-1}(t)} \, rac{dy(t)}{dt} + q_{n-1}(t) w(t) = 0 \;, \qquad t \geqq t_1 \;,$$

and so

$$rac{d}{dt}\,rac{1}{p_{n-1}(t)}\,rac{dy(t)}{dt}+q_{n-1}(t)y(t)\leqq 0\;,\qquad t\geqq t_1\;.$$

Again by Lemma 2 we see that the equation

$$\frac{d}{dt}\frac{1}{p_{n-1}(t)}\frac{dz}{dt}+q_{n-1}(t)z=0$$

has a nonoscillatory solution, contradicting the hypothesis. This completes the proof in the case l = n - 1.

REMARK. According to a classical oscillation criterion of Hille [7] equations (18) are oscillatory if

(26) 
$$\liminf_{t\to\infty} \int_a^t p_i(s) ds \cdot \int_t^\infty q_i(s) ds > \frac{1}{4}, \quad i = 1, 3, \dots, n-1.$$

It is not difficult to see that, when specialized to the particular equation

(27) 
$$\frac{d^m}{dt^m} \frac{1}{p_m(t)} \frac{d^m x}{dt^m} + q(t)x = 0 ,$$

Theorem B yields the following result which contains the theorem of Lovelady stated at the beginning of this paper.

COROLLARY. Suppose that  $\int_{0}^{\infty} p_{m}(t)dt = \infty$ . Suppose moreover that:

(i) if m = 2, then the equation

(28) 
$$\frac{d^2z}{dt^2} + \left(p_m(t)\int_t^\infty (u-t)q(u)du\right)z = 0$$

is oscillatory;

(ii) if m > 2 is even, then the equations

(29) 
$$\frac{d^2z}{dt^2} + \left(\frac{1}{(m-1)! (m-3)!} \times \int_t^\infty \left(\int_t^u (u-v)^{m-1} (v-t)^{m-3} p_m(v) dv\right) q(u) du\right) z = 0,$$

(30) 
$$\frac{d^2z}{dt^2} + \left(\frac{p_m(t)}{(m-1)! (m-2)!} \int_t^\infty (u-t)^{2m-3} q(u) du\right) z = 0$$

## are oscillatory; and

(iii) if m > 2 is odd, then the equations (29) and

(31) 
$$\frac{d}{dt} \frac{1}{p_m(t)} \frac{dz}{dt} + \left(\frac{1}{(m-1)! (m-2)!} \int_t^\infty (u-t)^{2m-3} q(u) du\right) z = 0$$

are oscillatory. Then equation (27) is oscillatory.

EXAMPLE. Consider the Euler equation

$$(15)$$
  $rac{d^m}{dt^m}t^{lpha+m}rac{d^mx}{dt^m}+ct^{lpha-m}x=0$  ,  $t\geqq 1$  ,

where  $\alpha$  and c > 0 are real constants, and  $\alpha \leq -m + 1$ .

It is a matter of easy computation to find that the second order equations (28), (29), (30), and (31) associated with (15) reduce respectively to

$$\begin{aligned} \frac{d^2z}{dt^2} &+ \frac{c}{\alpha(\alpha-1)t^2} \, z = 0 , \\ \frac{d^2z}{dt^2} &+ \frac{c}{(m-1)! \, \alpha(\alpha-1) \cdots (\alpha-m+1)t^2} \, z = 0 , \\ \frac{d^2z}{dt^2} &+ \frac{(2m-3)! \, c}{(m-1)! \, (m-2)! \, (\alpha+m-2)(\alpha+m-3) \cdots (\alpha-m+1)t^2} z = 0 , \end{aligned}$$
and

$$\frac{d}{dt}t^{\alpha+m}\frac{dz}{dt} + \frac{(2m-3)!\ ct^{\alpha+m-2}}{(m-1)!\ (m-2)!\ (\alpha+m-2)(\alpha+m-3)\cdots(\alpha-m+1)}z = 0.$$

Note that these are Euler equations of the second order. Consequently, we conclude that equation (15) is oscillatory provided c is so large that

(i) when 
$$m = 2$$
,  $c > (1/4)\alpha(\alpha - 1)$ ;

(ii) when m > 2 is even,

$$c > rac{1}{4} \max \left\{ (m-1)! \; lpha (lpha -1) \cdots (lpha -m+1), \ rac{(m-1)! \; (m-2)!}{(2m-3)!} \; (lpha +m-2) (lpha +m-3) \cdots (lpha -m+1) 
ight\};$$

(iii) when 
$$m > 2$$
 is odd,

$$c > rac{1}{4} \max \left\{ (m-1)! \ lpha (lpha -1) \cdots (lpha -m+1), \ rac{(m-1)! \ (m-2)!}{(2m-3)!} \ (lpha +m-1)^2 (lpha +m-2) (lpha +m-3) \cdots (lpha -m+1) 
ight\} \,.$$

Let us now turn to the case where  $\alpha > -m + 1$ . To examine this case we consider the fourth order equation

(32) 
$$rac{d^2}{dt^2} t^{lpha+2} rac{d^2 x}{dt^2} + c t^{lpha-2} x = 0 \;, \qquad t \ge 1 \;,$$

where we suppose that  $\alpha > -1$ . We observe that the differential operator  $(d^2/dt^2)t^{\alpha+2}(d^2/dt^2)$  can be represented in canonical form as follows:

(33) 
$$\frac{d}{dt} t^{\alpha+1} \frac{d}{dt} t^{-\alpha} \frac{d}{dt} t^{\alpha+1} \frac{d}{dt} \qquad (-1 < \alpha \leq 0) ,$$

$$(34) t^{\alpha}\frac{d}{dt} t^{1-\alpha}\frac{d}{dt} t^{\alpha}\frac{d}{dt} t^{1-\alpha}\frac{d}{dt} t^{\alpha} (0<\alpha<1) ,$$

(35) 
$$t^{\alpha} \frac{d^2}{dt^2} t^{2-\alpha} \frac{d^2}{dt^2} t^{\alpha} \qquad (\alpha \ge 1) \ .$$

Let  $0 < \alpha < 1$ , for example. Then in view of (34) equation (32) is equivalent to

(36) 
$$\frac{d}{dt} t^{1-\alpha} \frac{d}{dt} t^{\alpha} \frac{d}{dt} t^{1-\alpha} \frac{dy}{dt} + ct^{-\alpha-2}y = 0,$$

and, as easily cheked, the second order equations (18) associated with (36) reduce to the single equation

(37) 
$$\frac{d}{dt}t^{1-\alpha}\frac{dz}{dt} + \frac{c}{\alpha+1}t^{-\alpha-1}z = 0,$$

which is an Euler equation of the second order. From the remark following the proof of Theorem B equation (37) is oscillatory if

$$\liminf_{t o\infty}\int_{\scriptscriptstyle 1}^t s^{lpha-1}ds\cdot\int_t^\infty rac{c}{lpha+1}\,s^{-lpha-1}ds=rac{c}{lpha^2(lpha+1)}>rac{1}{4}\;.$$

Thus, in case  $0 < \alpha < 1$ , equation (32) is oscillatory if  $c > \alpha^2(\alpha + 1)/4$ . Similarly, it can be shown that (32) is oscillatory if  $c > \alpha^2(1 - \alpha)/4$ in case  $-1 < \alpha \leq 0$  and if  $c > \alpha(\alpha + 1)/4$  in case  $\alpha \geq 1$ . It follows that equation (32) is oscillatory for every  $\alpha$  provided c is sufficiently large.

The canonical representation of the operator  $(d^m/dt^m)t^{\alpha+m}(d^m/dt^m)$ with general m > 2 and  $\alpha > -m + 1$  is not known to us.

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Hiroshima University Hiroshima, Japan

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