

Pacific Journal of Mathematics

TRANSLATION INVARIANT CLOSED * DERIVATIONS

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If G is a locally compact group and δ is a left invariant closed* derivation in $C_0(G)$, then δ generates a C^* dynamics of $C_0(G)$. If G is a Lie group, $C_c^\infty(G)$ is a core for δ . Similar results are obtained for coset spaces.

1. Introduction. This paper is a study of translation invariant closed* derivations in C_0 of locally compact groups and their coset spaces. Our starting point is a theorem of S. Sakai [8, Proposition 1.17]: *A nonzero translation invariant closed* derivation in $C(S^1)$ has domain $C^1(S^1)$ and is a constant multiple of the derivative.* Our object is to generalize this result first to Lie groups and their homogeneous spaces, and then to locally compact groups and certain coset spaces. Theorems A and B, stated below, are the main results.

DEFINITIONS. Let G be a locally compact Hausdorff space. A linear map δ in $C_0(G)$ is a **derivation* if its domain $\mathcal{D}(\delta)$ is a dense conjugate-closed subalgebra of $C_0(G)$, $\delta(\bar{f}) = \overline{\delta(f)}$, and $\delta(fg) = f\delta(g) + \delta(f)g$ ($f, g \in \mathcal{D}(\delta)$). The derivation δ is *closed* if its graph is closed. Now let G be a locally compact group and let H be a closed subgroup. Left translations in G/H and in $C_0(G/H)$ are defined by $\iota_s(tH) = stH$ and $\iota_s f = f \circ \iota_{s^{-1}}$ ($s, t \in G, f \in C_0(G/H)$). We say that a closed* derivation δ in $C_0(G/H)$ is *G-invariant* or *translation invariant* if $\iota_s \circ \delta \circ \iota_{s^{-1}} = \delta$ for all $s \in G$. A closed* derivation in $C_0(G)$ is *left invariant* if it is invariant under left translations by elements of G .

NOTATION. If F is a class of continuous functions on a locally compact space, F_c will denote the elements of F with compact support and $F_{s.a.}$ will denote the real valued elements of F .

THEOREM A. *Let G be a Lie group and H a closed subgroup. Suppose that δ is a G -invariant closed* derivation in $C_0(G/H)$. Then*

(i) $C_c^\infty(G/H) \subseteq \mathcal{D}(\delta)$ and there is a G -invariant vector field X on G/H such that $\delta(f) = X(f)$ for all $f \in C_c^\infty(G/H)$.

(ii) $C_c^\infty(G/H)$ is a core for δ .

(iii) The C^* dynamics (strongly continuous one-parameter group of* automorphisms) of $C_0(G/H)$ corresponding to the complete vector field X has generator δ .

The point of this is that δ is not assumed at the outset to have anything to do with the differential structure of G/H ; but G -invariance implies that δ arises from a uniquely determined G -invariant vector field. In particular, the differential structure of a Lie group G can be recovered from the left invariant closed $*$ derivations in $C_0(G)$.

Theorem A is proved in § 2.

THEOREM B. *Let G be a locally compact group, and let δ be a left invariant closed $*$ derivation in $C_0(G)$. Then δ is the generator of a C^* dynamics of $C_0(G)$.*

This result is derived from Theorem A, using the structure theorem which gives certain locally compact groups as projective limits of Lie groups. The proof is in § 3. (Theorem B in turn implies the special case of Theorem A where H is the identity subgroup.) Some further generalizations to coset spaces are also presented in § 3.

The Lie algebra of a locally compact group is discussed in § 4.

We now recall some facts about a closed $*$ derivation δ in a commutative C^* algebra $C_0(X)$. [1, 4, 8]

The algebra $\mathcal{D}(\delta)$, with the graph norm $\| \cdot \|_\delta = \| \cdot \|_\infty + \| \delta(\cdot) \|_\infty$ is a Silov algebra with structure space X . $\mathcal{D}(\delta)$ has a C^1 functional calculus and $\delta(f \circ g) = (f' \circ g)\delta(g)$ for $f \in C^1(\mathbf{R})$ and $g \in \mathcal{D}(\delta)_{s.a.}$.¹ The derivation δ is local; that is, if $f, g \in \mathcal{D}(\delta)$ agree near $x \in X$, then $\delta(f)(x) = \delta(g)(x)$. The minimum closed primary ideal in $\mathcal{D}(\delta)$ at $x \in X$ is $\{f \in \mathcal{D}(\delta): f(x) = \delta(f)(x) = 0\}$.

LEMMA 1.1. *Let X be a locally compact Hausdorff space and let δ be a closed $*$ derivation in $C_0(X)$. Then $\mathcal{D}(\delta)_c$ is dense in $\mathcal{D}(\delta)$ in the graph norm.*

Proof. Let $X \cup \{\infty\}$ be the one point compactification of X . Define a closed $*$ derivation δ_1 in $C(X \cup \{\infty\})$ “extending” δ by taking $\mathcal{D}(\delta_1) = \mathcal{D}(\delta) \oplus \mathbf{C}1$ and setting $\delta_1 = \delta \oplus 0$. Then $\mathcal{D}(\delta) = \{f \in \mathcal{D}(\delta_1): f(\infty) = \delta_1(f)(\infty) = 0\}$. But this is the minimum closed ideal at ∞ in $\mathcal{D}(\delta_1)$, and is therefore the closure in $\mathcal{D}(\delta_1)$ of the ideal of functions vanishing in a neighborhood of ∞ . [3, Theorem 36.1]. That is, $\mathcal{D}(\delta)_c$ is dense in $\mathcal{D}(\delta)$. \square

DEFINITION. A closed subset $E \subseteq X$ is called a *restriction set* for δ if whenever $f \in \mathcal{D}(\delta)$ and $f|_E = 0$, it follows that $\delta(f)|_E = 0$.

¹ One must require $f(0) = 0$, unless X is compact.

If E is a restriction set, the formula $\delta_E(f|_E) = \delta(f)|_E$ defines a * derivation in $C_0(E)$ with domain $\{f|_E: f \in \mathcal{D}(\delta)\}$.

LEMMA 1.2. *If V is open and closed in X , then V is a restriction set for δ , and δ_V is closed.*

Proof. That V is a restriction set follows from the fact that δ is local. The characteristic function 1_V of V is locally in $\mathcal{D}(\delta)$, since $\mathcal{D}(\delta)$ is Silov regular. (We say that a function g is locally in $\mathcal{D}(\delta)$ if for each $x \in X$ there is an $f \in \mathcal{D}(\delta)$ such that $f = g$ in a neighborhood of x .) If $f \in \mathcal{D}(\delta)_c$, then $f1_V \in \mathcal{D}(\delta)$, because a Silov algebra contains each function of compact support which is locally in the algebra. Given $f \in \mathcal{D}(\delta)$, let $\langle f_n \rangle$ be a sequence in $\mathcal{D}(\delta)_c$ such that $\|f_n - f\|_\delta \rightarrow 0$ (Lemma 1.1); then $\|f_n1_V - f1_V\|_\infty \rightarrow 0$, and $\delta(f_n1_V) = \delta(f_n)1_V \rightarrow \delta(f)1_V$ uniformly. Since δ is closed, $f1_V \in \mathcal{D}(\delta)$. It now follows that any $g \in \mathcal{D}(\delta_V)$ can be extended *isometrically* to a function g_1 in $\mathcal{D}(\delta)$ by setting $g_1(x) = 0$ for $x \in X \setminus V$. This implies that δ_V is closed. \square

Acknowledgments. I would like to thank Jonathan Rosenberg and Antony Wassermann for helpful discussions. After this paper was completed I learned that H. Nakazato had independently proved Theorem B for compact groups. I am grateful to Professor Nakazato for sending me his preprint [7].

2. The proof of Theorem A. Let the dimensions of G and H be d and $d - c$ respectively. Let $\pi: G \rightarrow G/H$ be the canonical map, and let η be a C^∞ section of π defined in a neighborhood of H in G/H .

For each $g \in \mathcal{D}(\delta)$, the map $s \mapsto \iota_s g$ is continuous from G to $(\mathcal{D}(\delta), \|\cdot\|_\delta)$. Therefore for $f \in C_c(G)$, $f * g = \int_G f(s) \iota_s(g) ds$ is an element of $\mathcal{D}(\delta)$, and

$$\begin{aligned} \delta(f * g)(tH) &= \int_G f(s) \delta(\iota_s(g))(tH) ds \\ &= \int_G f(s) \iota_s(\delta(g))(tH) ds \\ &= f * \delta(g)(tH). \end{aligned}$$

(The integrations are with respect to a fixed left Haar measure on G .) If $f \in C_c^\infty(G)$, then $f * g \in \mathcal{D}(\delta) \cap C^\infty(G/H)$.

We want to produce a co-ordinate system on a neighborhood of H in G/H such that the co-ordinate functions extend to elements of $\mathcal{D}(\delta) \cap C^\infty(G/H)$. In the special case that $H = \{1\}$, this can be

done very easily. Let $\{x_i: 1 \leq i \leq d\}$ be elements of $C_c^\infty(G)$ which form a local co-ordinate system near 1. Because $\mathcal{D}(\delta)$ is Silov regular, G has a right approximate identity $\langle f_n \rangle$ for convolution, with each f_n an element of $\mathcal{D}(\delta)$. For large n , $\{x_i * f_n: 1 \leq i \leq d\}$ is a co-ordinate system in a neighborhood of 1, and each $x_i * f_n$ is an element of $\mathcal{D}(\delta) \cap C_c^\infty(G)$. The proof in the following paragraphs for H arbitrary follows the same basic line, although it is somewhat more convoluted.

We will show that $\{d(f * g)(H): f \in C_c^\infty(G)_{s.a.}, g \in \mathcal{D}(\delta)_{s.a.}\}$ spans the cotangent space $T_H^*(G/H)$. If not, there is a tangent vector $w_1 \in T_H(G/H)$ such that $w_1(f * g) = 0$ for all $f \in C_c^\infty(G)_{s.a.}$ and $g \in \mathcal{D}(\delta)_{s.a.}$. Let $w_i (1 \leq i \leq c)$ be a basis of $T_H(G/H)$ and let $v_i = d\eta(w_i)$. Choose a basis $\{v_i: c+1 \leq i \leq d\}$ of $T_1(H) \subseteq T_1(G)$. Then $\{v_i: 1 \leq i \leq d\}$ is a basis of $T_1(G)$. Let X_i be a *right* invariant vector field on G such that $X_i(1) = v_i$ ($1 \leq i \leq d$). There is a positive constant a such that the map

$$\phi^{-1}: (r_1, \dots, r_d) \longmapsto \exp(r_1 X_1) \cdots \exp(r_d X_d)$$

is a diffeomorphism of the cube $\{r \in \mathbf{R}^d: |r_i| < 4a \ (1 \leq i \leq d)\}$ onto a neighborhood U of 1 in G , and the map

$$(r_{c+1}, \dots, r_d) \longmapsto \exp(r_{c+1} X_{c+1}) \cdots \exp(r_d X_d)$$

is a diffeomorphism of the cube $\{r \in \mathbf{R}^{d-c}: |r_i| < 4a \ (c+1 \leq i \leq d)\}$ onto the neighborhood $U \cap H$ of 1 in H . Let $\{x_i: 1 \leq i \leq d\}$ be the co-ordinate functions of the co-ordinate system (U, ϕ) . Let $e: \mathbf{R} \rightarrow \mathbf{R}$ be a C^∞ function satisfying $0 \leq e \leq 1$, $e|_{[-a, a]} = 1$, and $\text{supp}(e) \subseteq]-2a, 2a[$. Define

$$F(s) = \begin{cases} \prod_{i=1}^d e(x_i(s)) & (s \in U) \\ 0 & (s \notin U) \end{cases}.$$

Let V be a symmetric neighborhood of 1 in G satisfying

- (1) $\phi^{-1}([-2a, 2a]^d) \cdot V \subseteq \phi^{-1}([-3a, 3a]^d)$
- (2) $\phi^{-1}([-3a, 3a]^d) \cdot V \subseteq U$, and
- (3) $|x_1(s)| < a/2$ for $s \in (H \cap \phi^{-1}([-3a, 3a]^d)) \cdot V$.

(Point (3) is possible since $x_1|_{H \cap U} = 0$.) Let $g \in \mathcal{D}(\delta)$ satisfy $g(H) > 0$, $g \geq 0$, and $\text{supp}(g) \subseteq \pi(V)$.

We next observe that $X_1(F)(s)g(\pi(s^{-1})) = 0$ for all $s \in G$. Of course $X_1(F)(s) = 0$ for $s \notin U$. Suppose that for some $s \in U$, $X_1(F)(s)g(\pi(s^{-1})) \neq 0$. Since $X_1(F)(s) = e'(x_1(s)) \prod_{i=2}^d e(x_i(s))$, we must have $|x_i(s)| \leq 2a$ ($2 \leq i \leq d$), and

$$(4) \quad a \leq |x_1(s)| \leq 2a.$$

Because $g(\pi(s^{-1})) \neq 0$, $\pi(s^{-1}) \in \pi(V)$. Thus $\exists h \in H$ and $\exists w \in V$ such that $s^{-1}h = w$. Since $s \in \phi^{-1}([-2a, 2a]^d)$, $h = sw$ is an element of $H \cap \phi^{-1}([-3a, 3a]^d)$, according to (1). Therefore $s = hw^{-1}$ is an element of $(H \cap \phi^{-1}([-3a, 3a]^d)) \cdot V$, and (3) implies $|x_1(s)| < a/2$. This contradicts (4).

Let g be as above and define

$$f(s) = \begin{cases} F(s)x_1(s) & (s \in U) \\ 0 & (s \notin U) \end{cases}.$$

Then $f \in C_c^\infty(G)$. We will show that $w_1(f * g) \neq 0$. In fact,

$$\begin{aligned} w_1(f * g) &= v_1((f * g) \circ \pi) \\ &= v_1(f * (g \circ \pi)) \\ &= X_1(f * (g \circ \pi))(1) \\ &= X_1(f) * (g \circ \pi)(1). \end{aligned}$$

The last equality comes from the right invariance of X_1 . Continuing,

$$\begin{aligned} w_1(f * g) &= \int_U X_1(f)(s)g(\pi(s^{-1}))ds \\ &= \int_U x_1(s)X_1(F)(s)g(\pi(s^{-1}))ds + \int_U F(s)g(\pi(s^{-1}))ds. \end{aligned}$$

In the last line, the first integrand is zero, as was noted in the previous paragraph. The second integral is positive. Thus $w_1(f * g) \neq 0$, and this contradiction shows that $\{dy(H): y \in C_c^\infty(G/H) \cap \mathcal{D}(\delta)_{s.a.}\}$ exhausts $T_H^*(G/H)$. Therefore there exist functions $y_i (1 \leq i \leq c)$ in $C_c^\infty(G/H) \cap \mathcal{D}(\delta)_{s.a.}$ and a neighborhood U_0 of H such that $(U_0, \{y_i\})$ is a co-ordinate system.

Let $C^\infty(y_j)$ denote $\{g \circ y_j: g \in C^\infty(\mathbf{R})\}$.² Because of the C^1 functional calculus in $\mathcal{D}(\delta)$, $C^\infty(y_j) \subseteq \mathcal{D}(\delta)$ and $\delta(g \circ y_j) = (g' \circ y_j)\delta(y_j)$ ($g \in C^\infty(\mathbf{R})$). For $s \in U_0$, this is $\delta(g \circ y_j)(s) = \partial/\partial y_j(g \circ y_j)(s)\delta(y_j)(s)$. It follows that for f in the algebra A generated by $\{C^\infty(y_j): 1 \leq j \leq c\}$, and for $s \in U_0$, $\delta(f)(s) = X(f)(s)$, where X is the C^0 vector field on U_0 ,

$$X(s) = \sum_{j=1}^c \delta(y_j)(s) \frac{\partial}{\partial y_j}.$$

Now let W be a compact neighborhood of H contained in U_0 , such that $\{(y_1(w), \dots, y_c(w)): w \in W\}$ is a cube in \mathbf{R}^c . If f is a C^∞ function with support in $\text{int}(W)$, then there is a sequence $\langle f_n \rangle$ in A , each f_n also having support in $\text{int}(W)$, such that $f_n(w) \rightarrow f(w)$ and $\delta(f_n)(w) = X(f_n)(w) \rightarrow X(f)(w)$ uniformly for $w \in W$. Because

² One should require $g(0) = 0$.

all functions are supported in W , $\langle f_n \rangle$ and $\langle \delta(f_n) \rangle$ are uniformly convergent on G/H , and since δ is closed, it follows that $f \in \mathcal{D}(\delta)$. By translation invariance of $\mathcal{D}(\delta)$ every C^∞ function is *locally* in $\mathcal{D}(\delta)$ and therefore $C_c^\infty(G/H) \subseteq \mathcal{D}(\delta)$. There is a vector field X on G/H such that $\delta(f) = X(f)$ ($f \in C_c^\infty(G/H)$), and because of the G -invariance of δ , X is also G -invariant. This proves the first assertion.

Now let $g \in \mathcal{D}(\delta)_c$ and let $\langle f_n \rangle$ be a left approximate identity for convolution in G , with each $f_n \in C_c^\infty(G)$. Then $f_n * g \in C_c^\infty(G/H)$, $f_n * g \rightarrow g$ uniformly and $\delta(f_n * g) = f_n * \delta(g) \rightarrow \delta(g)$ uniformly. Thus $C_c^\infty(G/H)$ is dense in $\mathcal{D}(\delta)_c$, with respect to $\| \cdot \|_\delta$. Since $\mathcal{D}(\delta)_c$ is in turn dense in $\mathcal{D}(\delta)$, by Lemma 1.1, $C_c^\infty(G/H)$ is a core for δ .

X , being G -invariant, is a complete vector field on G/H . Let $\{X_t: t \in \mathbf{R}\}$ denote the group of diffeomorphisms of G/H generated by X , and let $\alpha_t(f) = f \circ X_t$ ($f \in C_0(G/H)$, $t \in \mathbf{R}$). Let δ_1 be the infinitesimal generator of the C^* dynamics $\{\alpha_t\}$. Then $C_c^\infty(G/H) \subseteq \mathcal{D}(\delta_1)$ and $\delta_1(f) = X(f) = \delta(f)$ ($f \in C_c^\infty(G/H)$). Moreover, it follows from the invariance of X that $l_s \circ \alpha_t \circ l_{s^{-1}} = \alpha_t$ ($t \in \mathbf{R}$, $s \in G$) and hence that δ_1 is G -invariant. But then $C_c^\infty(G/H)$ is also a core for δ_1 , and since δ and δ_1 agree on $C_c^\infty(G/H)$, $\delta = \delta_1$. \square

3. Theorem B and generalizations. Before giving the proof of Theorem B, we note that this theorem contains the case of Theorem A where $H = \{1\}$. Let G be a Lie group and δ a left invariant closed $*$ -derivation in $C_0(G)$. If we know that δ generates a C^* dynamics $\{\alpha_t\}$, we can easily obtain the remaining conclusions of Theorem A. Let us see that $\mathcal{D}(\delta) \supseteq C_c^\infty(G)$. Let $\{X_t\}$ be the group of homeomorphisms of G such that $\alpha_t(f) = f \circ X_t$ ($f \in C_0(G)$, $t \in \mathbf{R}$), and let $\theta_t = X_t(1)$. Because of the left invariance of δ , $\angle_s \circ \alpha_t \circ \angle_{s^{-1}} = \alpha_t$ and $\angle_s \circ X_t \circ \angle_{s^{-1}} = X_t$ ($s \in G$, $t \in \mathbf{R}$). It follows that $X_t(s) = s\theta_t$, $\{\theta_t\}$ is a continuous one-parameter subgroup, and $\alpha_t(f)(s) = f(s\theta_t)$ ($s \in G$, $t \in \mathbf{R}$, $f \in C_0(G)$). Now the fact that $\{\theta_t\}$ is C^∞ implies that $\mathcal{D}(\delta) \supseteq C_c^\infty(G)$.

Proof of Theorem B. Suppose first that G is the projective limit of Lie groups: Let $\{G_a: a \in \mathbf{B}\}$ be an inverse limit system of Lie groups with homomorphisms $\phi_{ab}: G_b \rightarrow G_a$ ($b > a$) such that $G = \varprojlim G_a$. Let $\phi_a: G \rightarrow G_a$ be the natural projection; we are supposing that the kernel N_a of ϕ_a is compact. Thus if $K \subseteq G_a$ is compact, then $\phi_a^{-1}(K)$ is compact in G . Let $\phi_a^0(f) = f \circ \phi_a$ ($f \in C_0(G_a)$); then ϕ_a^0 is a $*$ -isomorphism of $C_0(G_a)$ into $C_0(G)$ which carries $C_c(G_a)$ into $C_c(G)$. Let $A_a = \phi_a^0(C_0(G_a))$, and let $A = \bigcup_{a \in \mathbf{B}} A_a$.

Each A_a is both left and right translation invariant, since

$$r_s(f \circ \phi_a) = (r_{\phi_a(s)} f) \circ \phi_a,$$

and

$$\ell_s(f \circ \phi_a) = (\ell_{\phi_a(s)} f) \circ \phi_a \quad (f \in C_0(G_a)) .$$

A function $f \in C_0(G)$ is in A_a if and only if $\ell_n(f) = f$ for all $n \in N_a$. If $f \in \mathcal{D}(\delta) \cap A_a$, then $\delta(f)$ is also in A_a , since $\ell_n(\delta(f)) = \delta(\ell_n(f)) = \delta(f)$ ($n \in N_a$). We next observe that $\mathcal{D}(\delta) \cap A_a$ is dense in A_a . Let dn denote normalized Haar measure on the compact group N_a . Given $g_0 \in A_a$ and $\varepsilon > 0$, choose $g_1 \in \mathcal{D}(\delta)$ such that $\|g_0 - g_1\| < \varepsilon$. Define $g_2 = \int_{N_a} \ell_n(g_1) dn$. Then $g_2 \in \mathcal{D}(\delta) \cap A_a$, and

$$g_0 - g_2 = \int_{N_a} \ell_n(g_0 - g_1) dn .$$

Therefore $\|g_0 - g_2\|_\infty \leq \int_{N_a} \|\ell_n(g_0 - g_1)\| dn < \varepsilon$.

Define δ_a in $C_0(G_a)$ by $\mathcal{D}(\delta_a) = (\phi_a^0)^{-1}(\mathcal{D}(\delta) \cap A_a)$, $\delta_a = (\phi_a^0)^{-1} \delta \phi_a^0$. Then δ_a is a densely defined * derivation in $C_0(G_a)$, and it is straightforward to check that δ_a is closed and left invariant. Since G_a is a Lie group, δ_a generates a C^* dynamics of $C_0(G_a)$ (Theorem A). Let $\psi_t^a = \phi_a^0 \exp(t\delta_a)(\phi_a^0)^{-1}$ be the corresponding C^* dynamics of A_a . If $b > a$ in \mathbf{A} , then $N_b \subseteq N_a$, and $A_a \subseteq A_b$. We observe that $\psi_t^b|_{A_a} = \psi_t^a$. For $s \in G$ and $t \in \mathbf{R}$,

$$\begin{aligned} \ell_s \psi_t^b \ell_s^{-1} &= \ell_s \phi_b^0 \exp(t\delta_b)(\phi_b^0)^{-1} \ell_s^{-1} \\ &= \phi_b^0 \ell_{\phi_b(s)} \exp(t\delta_b) \ell_{\phi_b(s)}^{(s-1)} (\phi_b^0)^{-1} \\ &= \phi_b^0 \exp(t\delta_b)(\phi_b^0)^{-1} \\ &= \psi_t^b . \end{aligned}$$

For $f \in A_a$ and $n \in N_a$,

$$\psi_t^b(f) = \ell_n \psi_t^b \ell_n^{-1}(f) = \ell_n \psi_t^a(f) .$$

Therefore ψ_t^b maps A_a into A_a . Now both $\{\psi_t^a\}$ and $\{\psi_t^b|_{A_a}\}$ have generator $\delta|_{\mathcal{D}(\delta) \cap A_a}$, so $\psi_t^b|_{A_a} = \psi_t^a$. We define a group of * automorphisms of $A = \bigcup_{a \in \mathbf{B}} A_a$ by $\psi_t(f) = \psi_t^a(f)$ if $f \in A_a$; $\{\psi_t\}$ is strongly continuous on A . A is a conjugate-closed subalgebra of $C_0(G)$. If $s \neq 1$, there is a kernel N_s such that $s \notin N_s$, and there is an $f \in A_s$ such that $f(s) \neq f(1)$. So A separates points of G and is dense in $C_0(G)$. Each ψ_t extends uniquely to a * automorphism of $C_0(G)$ and $\{\psi_t\}$ is a C^* dynamics of $C_0(G)$. Let δ_1 be the generator of $\{\psi_t\}$.

We show that $\delta = \delta_1$. First it is evident that $\mathcal{D}(\delta_1) \cap A = \mathcal{D}(\delta) \cap A$ and $\delta_1(f) = \delta(f)$ ($f \in \mathcal{D}(\delta) \cap A$). Since $\ell_s \psi_t \ell_s^{-1} = \psi_t$ ($t \in \mathbf{R}$, $s \in G$), δ_1 is left invariant. Given $g \in \mathcal{D}(\delta)$ and $\varepsilon > 0$, there is a neighborhood U of 1 in G such that $\|\ell_s(g) - g\|_s < \varepsilon$ for all $s \in U$, and there is an $a \in \mathbf{B}$ such that $N_a \subseteq U$. Let $g_1 = \int_{N_a} \ell_n(g) dn$ (with

dn denoting normalized Haar measure on N_a). Then $g_1 \in \mathcal{D}(\delta) \cap A_a$, and $\|g - g_1\|_s < \varepsilon$. Thus $A \cap \mathcal{D}(\delta)$ is a core for δ . Similarly $A \cap \mathcal{D}(\delta_1) = A \cap \mathcal{D}(\delta)$ is a core for δ_1 . Since δ and δ_1 agree on $A \cap \mathcal{D}(\delta)$, $\delta = \delta_1$. This completes the proof in the case that G is the projective limit of Lie groups.

Now let G be any locally compact group, with identity component G_0 . Let G_1 be the pre-image in G of a compact-open subgroup of G/G_0 [6, Theorem 2.3]. Thus G_1 is an open (and closed) subgroup, and according to Lemma 1.2, G_1 is a restriction set for δ and δ_{G_1} is closed. It is clear that δ_{G_1} is G_1 -invariant. Since G_1/G_0 is compact, G_1 is the projective limit of Lie groups [6, Theorem 4.6]. By the first part of the proof, δ_{G_1} generates a C^* dynamics $\{\alpha_t\}$ of $C_0(G_1)$. There is a continuous one-parameter subgroup $\{\theta_t\}$ of G_0 such that $\alpha_t(f) = r_{\theta_t}(f)$ ($f \in C_0(G_1)$, $t \in \mathbf{R}$). (See the remarks at the beginning of this section.) We define a C^* dynamics $\{\psi_t\}$ of $C_0(G)$ by the formula

$$\psi_t(f) = r_{\theta_t}(f) \quad (f \in C_0(G)).$$

If δ_1 is the generator of $\{\psi_t\}$, then G_1 is also a restriction set for δ_1 and $(\delta_1)_{G_1} = \delta_{G_1}$, since $\psi_t(f)|_{G_1} = \alpha_t(f|_{G_1})$ ($f \in C_0(G)$). By translation invariance of δ and δ_1 , a function is locally in $\mathcal{D}(\delta)$ if and only if it is locally in $\mathcal{D}(\delta_1)$. Hence $\mathcal{D}(\delta)_e = \mathcal{D}(\delta_1)_e$. Again by translation invariance, δ and δ_1 agree on $\mathcal{D}(\delta)_e$, and Lemma 1.1 implies that $\delta = \delta_1$. \square

COROLLARY 3.1. *Let δ be a left invariant closed $*$ derivation in $C_0(G)$, where G is a locally compact group. The identity component of G is a restriction set for δ .*

Proof. This follows immediately from the existence of a one-parameter subgroup $\{\theta_t\}$ of G such that

$$\delta(f)(s) = \left. \frac{d}{dt} \right|_{t=0} f(s\theta_t) \quad (s \in G, f \in \mathcal{D}(\delta)).$$

We next consider generalizations of Theorem B to coset spaces.

THEOREM 3.2. *Let G be a locally compact group. Suppose that there is an inverse limit system $\{G_a\}$ of Lie groups such that $G = \varprojlim G_a$ and each projection $G \rightarrow G_a$ has compact kernel. Let H be a closed subgroup of G and let δ be a G -invariant closed $*$ derivation in $C_0(G/H)$. Then δ is the generator of a C^* dynamics of $C_0(G/H)$. \square*

The first part of the proof of Theorem B can be modified to prove this result. Theorem 3.2 applies in particular if G is compact

or connected. We have not obtained the analogous result for arbitrary G , but we do have the result for another special class of groups:

THEOREM 3.3. *Let G be a locally compact group which can be covered by countably many translates of an arbitrary neighborhood of the identity. Let H be a closed subgroup and let δ be a G -invariant closed * derivation in $C_0(G/H)$. Then δ generates a C^* dynamics of $C_0(G/H)$.*

Proof. Let G_1 be an open subgroup of G which is the projection limit of Lie groups. Each G_1 -orbit M in G/H is open and closed, and is therefore a restriction set for δ . The derivation δ_M is closed and evidently G_1 -invariant.

G_1 inherits the property of being covered by countably many translates of an arbitrary neighborhood of the identity. Because of this, there is a homeomorphism of M onto a coset space of G_1 which respects the G_1 actions. It now follows from Theorem 3.2 that δ_M generates a C^* dynamics $\{\alpha_t^M\}$ of $C_0(M)$.

Define $\alpha_t: C_0(G/H) \rightarrow C_0(G/H)$ by

$$\alpha_t(f)|_M = \alpha_t^M(f|_M),$$

for each G_1 -orbit M . Then $\{\alpha_t\}$ is a C^* dynamics of $C_0(G/H)$. Let δ_1 be the generator of $\{\alpha_t\}$. For each G_1 -orbit M , $(\delta_1)_M = \delta_M$. It follows that $\mathcal{D}(\delta_1)_c = \mathcal{D}(\delta)_c$ and $\delta_1(f) = \delta(f)$ for $f \in \mathcal{D}(\delta)_c$. Now Lemma 1.1 implies that $\delta = \delta_1$. \square

4. The Lie algebra of a locally compact group. The Lie algebra of a connected locally compact group G was defined by Lashof in [5] to be the projective limit of the Lie algebras of Lie groups forming a projective limit system for G . The Lie algebra of an arbitrary locally compact group is defined to be the same as the Lie algebra of its connected component. Bruhat [2] identified the Lie algebra of G with a closed subspace of the dual of the algebra $\mathcal{D}(G)$ of regular functions on G .

For the remainder of this section let G be a connected locally compact group. We show that the set $L(G)$ of left invariant closed * derivations in $C_0(G)$ has a natural Lie algebra structure and can be identified with the Lie algebra of G .

Let $\{G_a: a \in B\}$ be an inverse limit system of Lie groups such that $G = \varprojlim G_a$. We adopt the notation of the proof of Theorem B. The algebra $\mathcal{D}(G)$ is defined to be $\bigcup_{a \in B} \phi_a^0(C_c^\infty(G_a))$. $\mathcal{D}(G)$ is independent if the choice of the inverse limit system $\{G_a\}$. [2]

- PROPOSITION. (i) $\mathcal{D}(G)$ is a core for each element of $L(G)$.
(ii) Each element of $L(G)$ maps $\mathcal{D}(G)$ into $\mathcal{D}(G)$.
(iii) Each $*$ derivation in $C_0(G)$ with domain $\mathcal{D}(G)$ is closable.

Proof. Let δ be an element of $L(G)$. By Theorem A the derivation δ_a induced by δ in $C_0(G_a)$ has domain containing $C_c^\infty(G_a)$ and maps $C_c^\infty(G_a)$ into itself. Therefore $\mathcal{D}(\delta) \supseteq \phi_a^0(C_c^\infty(G_a))$ and δ maps $\phi_a^0(C_c^\infty(G_a))$ into itself. This proves (ii). Now let $g \in \mathcal{D}(\delta)$ and $\varepsilon > 0$. By the proof of Theorem B, there is an $a \in \mathbf{B}$ and $g_1 \in \mathcal{D}(\delta) \cap A_a$ such that $\|g - g_1\|_s < \varepsilon$. Since $C_c^\infty(G_a)$ is a core for δ_a , it follows that there is a $g_2 \in \phi_a^0(C_c^\infty(G_a))$ such that $\|g_1 - g_2\|_s < \varepsilon$. Thus $\mathcal{D}(G)$ is a core for δ .

A $*$ derivation δ in $C_0(X)$ is said to be well behaved if it satisfies the following equivalent conditions: (a) $\|f \pm \delta(f)\| \geq \|f\|$ for all $f \in \mathcal{D}(\delta)_{s.a.}$, and (b) if $f \in \mathcal{D}(\delta)_{s.a.}$ attains its maximum at $s \in X$, then $\delta(f)(s) = 0$. A well behaved $*$ derivation is closable [8, Theorem 2.8].

Now let δ be a $*$ derivation in $C_0(G)$ with domain $\mathcal{D}(G)$. For each $a \in \mathbf{B}$, define $P_a: C_0(G) \rightarrow A_a$ by $P_a(f) = \int_{N_a} l_n(f) dn$. Since P_a is a conditional expectation, $P_a \circ \delta|_{\phi_a^0(C_c^\infty(G_a))} = \delta_a$ is a $*$ derivation in A_a . The $*$ derivation $(\phi_a^0)^{-1} \circ \delta_a \circ \phi_a^0$ in $C_0(G_a)$ with domain $C_c^\infty(G_a)$ is defined by a continuous vector field and is therefore well behaved (condition (b)). So δ_a is well behaved. Fix $a \in \mathbf{B}$ and $f \in \phi_a^0(C_c^\infty(G_a))_{s.a.}$; for all $b \geq a$, $\|f \pm P_b(\delta(f))\| \leq \|f\|$. Since $P_b(\delta(f)) \rightarrow \delta(f)$ uniformly, $\|f \pm \delta(f)\| \geq \|f\|$. Thus δ is well behaved and closable. \square

Given this result, we can define each Lie algebra operation on $L(G)$ by restricting the elements of $L(G)$ to $\mathcal{D}(G)$, performing the operation on the restrictions, and closing the resulting left invariant $*$ derivation on $\mathcal{D}(G)$.

It remains to identify $L(G)$ with the Lie algebra of G as defined in [5]. Let \mathfrak{g}_a be the Lie algebra of G_a ; $\{\mathfrak{g}_a: a \in \mathbf{B}\}$ forms an inverse limit system with homomorphisms $d\phi_{ab}: \mathfrak{g}_b \rightarrow \mathfrak{g}_a$ ($b > a$). Regard $L(G)$ as the set of left invariant $*$ derivations of $\mathcal{D}(G)$ and \mathfrak{g}_a as the set of left invariant $*$ derivations of $C_c^\infty(G_a)$. Then $\delta \rightarrow \{\delta_a: a \in \mathbf{B}\}$ is a Lie algebra isomorphism of $L(G)$ onto $\lim \mathfrak{g}_a$.

←

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Received June 9, 1980. Research partly supported by N.S.F.

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The *Pacific Journal of Mathematics* is issued monthly as of January 1966. Regular subscription rate: \$102.00 a year (6 Vols., 12 issues). Special rate: \$51.00 a year to individual members of supporting institutions.

Subscriptions, orders for numbers issued in the last three calendar years, and changes of address should be sent to Pacific Journal of Mathematics, P.O. Box 969, Carmel Valley, CA 93924, U.S.A. Old back numbers obtainable from Kraus Periodicals Co., Route 100, Millwood, NY 10546.

PUBLISHED BY PACIFIC JOURNAL OF MATHEMATICS, A NON-PROFIT CORPORATION

Printed at Kokusai Bunken Insatsusha (International Academic Printing Co., Ltd.).
8-8, 3-chome, Takadanobaba, Shinjuku-ku, Tokyo 160, Japan.

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