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REDUCING THE ORDER OF THE LAGRANGEAN FOR A CLASSICAL FIELD IN CURVED SPACE-TIME

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We show how the Lagrangean L can be replaced by another, L^* , having the same extremals, but having only first order derivatives and being in fact a first degree polynomial in these derivatives.

1. Introduction. Whittaker [4] showed how to reduce the order and degree of a Lagrangean to 1 in the case of one-dimensional "space-time". As he points out, this leads instantly to Hamilton's canonical formalism. Rodrigues [3] showed how to do this without using coordinates in the configuration space. "Reducing the order" is not an adequate description of the construction since when the order is 1 (as it usually is) it still takes some work to make it of the first degree.

In [1] we treated the case of true (several dimensional) space-time. However, we took it to be \mathbb{R}^4 , and we used coordinates in the field space.

Such a theorem is not usable when several coordinate systems must be used in space-time M. This is because the L^* doing the desired things is not unique.

Our construction of L^* here depends on the choice of an affine connection Γ and a volume element ω in M. The result is not independent of the Γ and ω chosen, but it is independent of coordinates.

2. π -manifolds. In this paper, a suitable order N of differentiability is assumed.

Let *M* be a manifold which we will call *space-time*. Let *P* be another manifold. We will call it a π -manifold if there is defined on it a *regular* map $\pi: P \to M$.

If P and Q are two π -manifolds, let F(P, Q) be the class of all maps f of open sets in P into Q for which

(2.1)
$$\pi(f(p)) = \pi(p)$$

whenever f(p) is defined. Let p be a point of P and let $f, g \in F(P, Q)$. Say $f \equiv g$ at p if f and g agree up to the Nth order at p. Let $J^{N}(P, Q)$ be the set of equivalence classes. An element C of $J^{N}(P, Q)$ may be represented by a pair (p, f) where C is an equivalence at p and $f \in C$. Define $\pi(C) = \pi(p) = \pi(f(p))$. Then $J^{N}(P, Q)$ is also a π -space.

Let $X^1, \ldots, x^m, y^1, \ldots, y^n$ be coordinates in P and Q respectively. Then $(y^i)_{\lambda \cdots \nu}$ shall be the function defined in $J^N(P, Q)$ be saying that

(2.2)
$$(y^i)_{\lambda\cdots\nu}(C) = \frac{\partial^k (y^i \circ f)}{\partial x^{\lambda}\cdots\partial x^{\nu}}(p).$$

Here k must not exceed N.

A particularly useful kind of coordinates x^1, \ldots, x^m are coordinates exponential at a point p. For this one must select an affine connection Γ for P. Let $T^1(P)_p$ be the tangent space to P at p. Select a *linear* coordinate system in $T^1(P)p$ and transfer these to P using the exponential map defined by Γ (see [2].)

3. Lagrangeans. In classical mechanics, a Lagrangean is a function defined on $\mathbf{R} \times T^1(Q)$, the latter being the tangent bundle of configuration space. Now $\mathbf{R} \times T^1(Q)$ is naturally isomorphic with $J^1(M, M \times Q)$ where $M = \mathbf{R}$, and $M \times Q$ has the projection on M. Since we want to use 2.1 we define Lagrangeans in this *milieu*.

Let *M* be a manifold of dimension *m*. Let *S* be a π -manifold. If coordinates t^1, \ldots, t^m are chosen for *M*, then $t^1 \circ \pi, \ldots, t^m \circ \pi$ are (independent, by the regularity of π) variables in *S*. We will abbreviate them to t^1, \ldots, t^m .

A Lagrangean (of order at most N) is an m-form Λ defined on $J^{N}(M, S)$ such that in terms of coordinates t^{1}, \ldots, t^{m} in M,

(3.1)
$$\Lambda = L dt^1 \wedge \cdots \wedge dt^m.$$

Let the class of these Lagrangeans be called $\mathscr{L}^{N}(S)$.

3.2. THEOREM. Let M and S be as above. Let Γ be an affine connection for M. Let ω be a volume element for M. Let K be the cotangent bundle of $J^{N}(M, S)$. Then Γ , ω define a mapping

(3.3)
$$\mathscr{L}^{N}(S) \to \mathscr{L}^{1}(K), \quad \Lambda \to \Lambda^{*}.$$

This mapping is linear and 1:1

3.4. L^* is a polynomial of the first degree in the derivatives (necessarily only of the first order), and

3.5. Λ^* has the same extremals as Λ .

The precise (and natural) meaning of 3.5 is given in §5 below, together with the proof of 3.2.

Property 3.4 is useful for the following construction.

Let x^1, \ldots, x^n (plus those t^1, \ldots, t^m) be coordinates in S. $\Lambda^* = L^* dt^1$ $\wedge \cdots \wedge dt^m$ and by 3.4, L^* is a sum of a term -H depending only on the x^i and t^{λ} , and a sum of terms like $a(x^i)_{\lambda}$. Thus Λ^* is a sum of $-H dt^1 \wedge \cdots \wedge dt^m$ and of terms like $a(x^i)_{\lambda} dt^1 \wedge \cdots \wedge dt^m$. This latter term is congruent modulo $dx^i - (x^i)_{\lambda} dt^{\lambda}$ to $a dt^1 \wedge \cdots \wedge dx^i \wedge \cdots dt^m$, dx^i being in the λ th place. Thus Λ^* is congruent to an *m*-form involving only the x^i and t^{λ} , that is, an *m*-form on *S*.

4. A vector field U_{Γ} on $J^{N}(M, S)$.

4.1. THEOREM. Let Γ be an affine connection for M. Using Γ one can construct a vector field U_{Γ} on $J^{N}(M, S)$. Let $A \in J^{N}(M, S)$ and let t^{1}, \ldots, t^{m} be exponential coordinates at $\pi(A)$ in M. Use t^{1}, \ldots, t^{m} together with some further coordinates x^{1}, \ldots, x^{n} as coordinates in S. Then at A,

(4.2)
$$U_{\Gamma} = (x^{i})_{\lambda} \frac{\partial}{\partial (x^{i})_{\lambda}} + 2(x^{i})_{\lambda \mu} \frac{\partial}{\partial (x^{i})_{\lambda \mu}} + \dots + N(x^{i})_{\lambda \dots \nu} \frac{\partial}{\partial (x^{i})_{\lambda \dots \nu}}.$$

A sum is intended in 4.2. For example, by

$$(x^i)_{\lambda\cdots\mu}\frac{\partial}{\partial(x^i)_{\lambda\cdots\mu}}$$

where there are k indices, we mean the sum over all sets of k indices such that $1 \le \lambda \le \cdots \le \mu \le m$.

We now prove 4.1. Let A = (a, f) be a point of $J^{N}(M, S)$. Express f in terms of t^{1}, \ldots, t^{m} :

$$f=\varphi(t^1,\ldots,t^m).$$

For sufficiently small real s and $|t^{\lambda}|$, f_s can be defined by

$$f_s = \varphi(e^s t^1, \dots, e^s t^m).$$

Define the "moving" point A_s in $J^N(M, S)$ as (a, f_s) . We define U_{Γ} at A to be the tangent to the curve $s \to A_s$ for s = 0.

We must show that its $(x^i)_{\lambda\cdots\mu}$ component is correctly represented in 4.2. Now

$$(x^{i})_{\lambda\cdots\mu}(A_{s}) = \frac{\partial^{k}}{\partial t^{\lambda}\cdots\partial t^{\mu}} [x^{i}\circ f_{s}]\Big|_{t=0}$$
$$= e^{ks} \frac{\partial^{k}}{\partial t^{\lambda}\cdots\partial t^{\mu}} [x^{i}\circ f]\Big|_{t=0} = e^{ks} (x^{i})_{\lambda\cdots\mu}(A).$$

Then we take d/ds of this for s = 0, obtaining

$$k(x^i)_{\lambda\cdots\mu}$$

as 4.2 asserts. The construction of A_s is clearly independent of the coordinates.

4.3. COROLLARY. Let K be the cotangent bundle $T_1(J)$ of $J = J^N(M, S)$. Then Γ defines a real-valued function on K whose expression in terms of coordinates is

(4.4)
$$p_i^{\lambda}\overline{(x^i)_{\lambda}} + 2p_i^{\lambda\mu}\overline{(x^i)_{\lambda\mu}} + \cdots + Np_i^{\lambda\cdots\nu}\overline{(x^i)_{\lambda\cdots\nu}}.$$

Here $p_i^{\lambda \cdots \mu}$ is the "momentum" coordinate dual to the configuration coordinate $(x^i)_{\lambda \cdots \mu}$ in J.

To prove 4.3, we need only show that 4.4 is independent of the coordinate representation. A point *B* is a pair (A, g) where *A* is a point of *J* as before, and *g* is a map from a neighborhood of *A* into **R**, where g(A) = 0. The value of $p_i^{\lambda \cdots \mu}$ at *B* is

$$\frac{\partial g}{\partial (x^i)_{\lambda\cdots\mu}}\Big|_A.$$

The value of $(x^i)_{\lambda\cdots\mu}$ at B is just $(x^i)_{\lambda\cdots\mu}(A)$. Here the latter is defined in J, and the former is the coordinate defined in $T_1(J)$ as obtained from the latter and the projection ρ

(4.5)
$$T_1(J) = K$$
$$\downarrow$$
$$J = J^N(M, S)$$

Hence the value of 4.4 at B is $U_{\Gamma}[g]$, the result of applying the operator U_{Γ} to g, and is thus independent of coordinates.

4.6. COROLLARY. Let J and K be as in 4.3. Let $P = J^1(M, K)$. Then Γ defines a real-valued function on P whose value at C = (c, h) is

(4.7)
$$\overline{p_i^{\lambda}} Z_{\lambda}^i + \overline{p_i^{\lambda\mu}} Z_{\lambda\mu}^i + \cdots + \overline{p_i^{\lambda\cdots\nu}} Z_{\lambda\cdots\nu}^i$$

where $Z^{i}_{\lambda \dots u}$ is the sum of all

(4.8) $\left(\overline{(x^i)_{\lambda\cdots\hat{\sigma}\cdots\mu}}\right)_{\sigma}.$

Several explanations are needed.

4.81. In forming the sum $Z_{\lambda \cdots \mu}^{i}$ we select each index appearing in $\lambda \cdots \mu$, form 4.8, and add the results. $\hat{\sigma}$ means delete ' σ ' from the string $\lambda \cdots \mu$.

4.82. The $p_i^{\overline{\lambda}\cdots\mu}$ is $p_i^{\overline{\lambda}\cdots\mu}\circ\xi$ where ξ is the projection of $P = J^1(M, K)$ $\rightarrow K$. Hence, for an element C = (c, h) of P, wherein h maps a neighborhood of $c \in M$ into K,

(4.83)
$$\overline{p_{i}^{\lambda\cdots\mu}}(C) = p_{i}^{\lambda\cdots\mu}(h(c))$$

which is

$$\frac{\partial g}{\partial (x^i)_{\lambda\cdots\mu}}\bigg|_{A}$$

if $h(c) = (A, g), A \in K$.

4.84. The bar on the $(x^i)_{\lambda \cdots \mu}$ means that (see 4.5)

$$\overline{(x^i)_{\lambda\cdots\mu}}=(x^i)_{\lambda\cdots\mu}\circ\rho.$$

For any real variable z (and thus for $(x^i)_{\lambda \dots}$) on K, 2.2 with N = 1 gives sense to z_{σ} for $1 \le \sigma \le m$.

To begin the proof of 4.6, we evaluate at C = (c, h) of P. By 2.2, the answer is

$$\frac{\partial}{\partial t^{\sigma}} \Big[\overline{(x^i)_{\lambda \cdots \mu}} \circ h \Big] \Big|_c.$$

Let us write ∂_{σ} for $\partial/\partial t^{\sigma}$. So

$$Z^{i}_{\lambda\cdots\mu} = \sum \partial_{\sigma} \big[(x^{i})_{\lambda\cdots\hat{\sigma}\cdots\mu} \circ \rho \circ h \big].$$

We need a somewhat more abstract version of 2.2. Let $\pi_1(C) = p$, $\pi_2(C) = h$ in 2.2. Replace x^{λ} by t^{λ} and y^i by x^i , since that is the notation for the present instance. Then 2.2 says

$$(x^{\prime})_{\lambda\cdots\mu} = \left\{\partial_{\lambda}\cdots\partial_{\mu}(x^{\prime}\circ\pi_{2})\right\}\circ\pi_{1}.$$

Accordingly,

$$Z^{i}_{\lambda\cdots\mu} = \sum \partial_{\sigma} \Big[\Big\{ \partial_{\lambda\cdots\hat{\sigma}\cdots\mu} \Big(x^{i} \circ \pi_{2} \Big) \Big\} \circ \pi_{1} \circ \rho \circ h \Big] \Big|_{c}.$$

We assert that $\pi_1 \circ \rho \circ h$ is the identity map. First of all π_1 is the map π for the π -space J. Then ρ (4.5) is a π -space morphism, for that is the way in which K is made into a π -space. So $\pi_1 \circ \rho = \pi$. But h has to satisfy 2.1, so $\pi \circ h = \pi$. But the π for M itself is the identity (on some neighborhood). Therefore

$$Z^{i}_{\lambda\cdots\mu} = \sum \partial_{\sigma} \big\{ \partial_{\lambda\cdots\hat{\sigma}\cdots\mu} \big(x^{i} \circ \pi_{2} \big) \big\} = k \partial_{\lambda\cdots\mu} \big(x^{i} \circ \pi_{2} \big)$$

where k is the length of the string $\lambda \cdots \mu$ with nothing deleted. So

$$Z^{i}_{\lambda\cdots\mu} = k\left\{\partial_{\lambda\cdots\mu}\left(x^{i}\circ\pi_{2}\right)\right\}\circ\pi_{1}\circ\rho\circ h\Big|_{c} = k(x^{i})_{\lambda\cdots\mu}(A)$$

since h(c) = (A, g). Combine this with 4.83 and obtain that this Z term contributes

$$k(x^i)_{\lambda\cdots\mu}(A)rac{\partial g}{\partial (x^i)_{\lambda\cdots\mu}}$$

to the sum 4.7. This sum is evidently $U_{\Gamma}[g]$ evaluated at A. Thus 4.7 is independent of the coordinates. Thus it defines the function for which 4.6 holds.

5. Proof of Theorem 3.2. Let Λ be given. Choose coordinates in M. Then 3.1 defines L, a function defined on $J^{N}(M, S)$. We have projections

$$J^{1}(M, K) = P$$

$$\xi \downarrow$$

$$K = T_{1}(J)$$

$$(5.1)$$

$$\rho \downarrow$$

$$J = J^{N}(M, S)$$

$$\downarrow$$

$$S$$

Hence L defines a function on $J^1(M, K)$, which we denote by L also, for simplicity. Using ξ , we can lift the function 4.4 up to a function φ on P. The function defined by 4.6 may be called ψ .

Let

(5.2)
$$\omega = \lambda \, dt^1 \wedge \cdots \wedge dt^m,$$

 $\lambda \neq 0$, be the volume element postulated in 3.2.

We define

$$L^* = L + \lambda(\psi - \varphi) = L - \lambda \varphi + \lambda \psi,$$

and

$$\Lambda^* = L^* dt^1 \wedge \cdots \wedge dt^m.$$

We consider assertion 3.4. 4.8 is a derivative of first order. The coefficients in 4.7 are mere coordinates, and the Z's are linear in the derivatives 4.8. Hence 3.4 holds.

To show 3.5 we mention first that L^* has the form

$$L^{*} = L + P_{i}^{\lambda} \Big[(\overline{(X^{i})})_{\lambda} - \overline{(x^{i})_{\lambda}} \Big]$$

+ $P_{i}^{\lambda\mu} \Big[(\overline{(x^{i})_{\lambda}})_{\mu} + (\overline{(x^{i})_{\mu}})_{\lambda} - 2\overline{(x^{i})_{\lambda\mu}} \Big]$
+ $P_{i}^{\lambda\mu\nu} \Big[(\overline{(x^{i})_{\mu\nu}})_{\lambda} + (\overline{(x^{i})_{\lambda\nu}})_{\mu} + (\overline{(x^{i})_{\lambda\mu}})_{\nu} - 3\overline{(x^{i})_{\lambda\mu\nu}} \Big] + \cdots,$

where P_i^{λ} , $P_i^{\lambda\mu}$,... are λ (see 5.2) times the p_i^{λ} , $p_i^{\lambda\mu}$,... lifted up to $J^1(M, K)$ by the projections 5.1. It follows from [1, 3.4] that L^* has the "same" extremals as *l*. The meaning of *same* is as follows. An extremal for L^* gives us expressions

(5.3) $x^i = f^i(t^1, \dots, t^m),$

(5.4)
$$(x^i)_{\lambda} = u^i_{\lambda}(t^1, \dots, t^m)$$

$$(x^{i})_{\lambda\mu} = u^{i}_{\lambda\mu}(t^{1}, \dots, t^{m})$$

$$\vdots$$

$$P^{i}_{\lambda} = g^{i}_{\lambda}(t^{1}, \dots, t^{m})$$

$$\vdots$$

If we abandon 5.4 and those following it, then 5.3 gives an extremal for L in the usual sense. It is shown in [1] that

$$u_{\lambda}^{i}=\frac{\partial f^{i}}{\partial t^{\lambda}},$$

and so forth.

6. Correction to [1].

(a) Delete 6.5. (Prop. 6.6. remains true, with the φ of 6.7.)

(b) Delete 6.9. (Better results are in the author's "The dynamic differential forms of the Klein-Gordon field and the conformal group", Jour. Geometry and Physics, Vol. 1, 1983.)

RICHARD ARENS

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Richard Arens, Reducing the order of the Lagrangean for a classical field in curved space-time
Shiferaw Berhanu, W. Wistar (William) Comfort and James Dolan Reid,
Counting subgroups and topological group topologies
Michael James Cambern, Isomorphisms of spaces of norm-continuous
functions
Gerald Arthur Edgar and Jun Feng Zhao, The ordering structure on
Banach spaces
Irving Leonard Glicksberg, An analogue of Liapounoff's convexity
theorem for Birnbaum-Orlicz spaces and the extreme points of their unit
balls
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respect to an elliptic integrand and with at most three boundary
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