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## **ROTATION SETS OF MAPS OF THE ANNULUS**

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## ROTATION SETS OF MAPS OF THE ANNULUS

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We study how the rotation interval of a point affects the rotation set of its  $\omega$ -limit set. Similarities between rotation set and topological entropy were found, suggesting a deeper relation between these two concepts.

Introduction. In 1913 Birkhoff proved the first important theorem about twist maps of the annulus, initially conjectured by Poincaré and known as "*Poincaré's last geometric theorem*". It roughly says that any area preserving homeomorphism of the annulus which rotates the boundary components in opposite directions has at least two fixed points.

In [6] John Franks, using an extension of Poincaré's definition of rotation number, proved that any chain transitive homeomorphism of the annulus that twists the boundaries in opposite directions has at least one fixed point; it follows from his work that if a homeomorphism of the annulus preserves area then either it has infinitely many periods or every point has the same rotation number.

In this paper we introduce the rotation set for an endomorphism of the annulus. Associated to each orbit we define a real sequence that measures the "wrapping" of the orbit around the inner boundary of the annulus. The limit of this sequence, if it exists, is called the *rotation number* of the orbit. If the limit does not exist, the set of all limit points of the referred sequence is a closed interval and designated *rotation interval* (see pg. 253). The rotation set is the union of all rotation intervals. It is a topologically invariant set that contains its supremum and infimum; however we don't know if it is always closed.

There are interesting similarities between properties of the rotation set and topological entropy. Katok in [11] proved that any  $C^{1+\epsilon}$  diffeomorphism, f, with positive entropy has an invariant hyperbolic set  $\Lambda$ where f is topologically conjugate to a shift. This implies that either every point in  $\Lambda$  has the same rotation number or there is some point without rotation number. Nevertheless the relation between positive entropy and existence of points without rotation number is not completely understood. 1. Definitions and notations. We review the definition of rotation number of a point in the annulus under an endomorphism of degree 1.

Notation is fixed as follows:

(a)  $A = (\mathbf{R} \times I) / \sim$ , where I = [0, 1]. For (s, t) and  $(s', t) \in \mathbf{R} \times I$  we have  $(s, t) \sim (s', t)$  iff  $s - s' \in \mathbf{Z}$ .

(b) f is an endomorphism of degree 1 and F a lift to  $\mathbf{R} \times I$ .

(c)  $p: \mathbf{R} \times I \to A$  is a covering map and  $x \in A, \overline{x} \in \mathbf{R} \times I$  with  $p(\overline{x}) = x$ .

(d)  $\overline{x}_1, \overline{x}_2$  are the projections of  $\overline{x}$  onto the first and second factors, respectively.  $F_i^n(\overline{x}) = (F^n(\overline{x}))_i$ , i = 1, 2.

DEFINITION. If the limit of  $((F_1^n(\overline{x}) - \overline{x}_1)/n)_{n\geq 1}$  exists, it is denoted  $\rho_f(x)$  (or  $\rho(x)$ ) and said the rotation number of x under f, (rotation number is well defined up to an integer).

**LEMMA** 1.1.  $((F_1^n(\overline{x}) - x_1)/n)_{n \ge 1}$  is uniformly bounded.

*Proof*. We note that  $\Phi_1(y) = F_1(y) - y_1$  is translation invariant i.e., for any  $y \in \mathbf{R} \times I$  we have  $\Phi_1(y + (1, 0)) = \Phi_1(y)$ .

Continuity of f assures the existence of

 $L = \max\{|\Phi_1(y)|, y \in \mathbf{R} \times I\} = \max\{|\Phi_1(y)|, y \in I^2\}.$ 

Consequently we have:

$$\frac{|F_1^n(\overline{x}) - \overline{x}_1|}{n} = \frac{\left|\sum_{j=0}^{n-1} \left[F_1(F^j(\overline{x})) - F_1^j(\overline{x})\right]\right|}{n}$$
$$\leq \frac{\sum_{j=0}^{n-1} |F_1(F^j(\overline{x})) - F_1^j(\overline{x})|}{n} \leq L.$$

**REMARK** 1.2. Denoting

 $\iota: \mathbf{R} \times I \to \mathbf{R} \times I$  $(x, y) \to (x, 0) \quad \text{then } F = \iota + \Phi,$ 

where  $\Phi$  is translation invariant. This leads to the Birkhoff sum

$$\frac{F_1^n(\overline{x})-\overline{x}_1}{n}=\frac{\sum_{j=0}^{n-1}\Phi_1(F^j(\overline{x}))}{n}.$$

It follows from Birkhoff's ergodic theorem that the subset of A consisting of points without rotation number has measure zero.

Let  $\Gamma_a$  be the set of all limit points of  $((F_1^n(\overline{a}) - \overline{a}_1)/n)_{n \ge 1}$ , where  $a \in A$ . Then for all  $n \in \mathbb{Z}$ ,  $\Gamma_a = \Gamma_{f^n(a)}$ .

LEMMA 1.3.  $\Gamma_a$  is a closed interval.

*Proof.* Assume that  $\Gamma_a$  is not an interval, and its complement contains  $I_0 = (\alpha_1, \alpha_2)$ , where  $\alpha_1, \alpha_2 \in \Gamma_a$ . Set  $\delta = \alpha_2 - \alpha_1 > 0$ . Let d be the usual metric in **R** and

$$L = \max\{|\Phi_1(y)|, y \in \mathbf{R} \times I\}.$$

There exists  $i_0$  such that for  $i > i_0$ 

$$d\left(\frac{F_1^i(\overline{a})-\overline{a}_1}{i},\Gamma_a\right)<\frac{\delta}{8}\quad\text{and}\quad\frac{2L}{i_0}<\frac{\delta}{8}.$$

We choose  $n > i_0$  so that:

$$\frac{F_1^n(\overline{a})-\overline{a}_1}{n} < \alpha_1 + \frac{\delta}{8} \quad \text{and} \quad \frac{F_1^{n+1}(\overline{a})-\overline{a}_1}{n+1} > \alpha_2 - \frac{\delta}{8}.$$

Hence the distance between these terms is bigger than  $3\delta/4$ .

On the other hand:

$$d\left(\frac{F_{1}^{n}(\overline{a}) - \overline{a}_{1}}{n}, \frac{F_{1}^{n+1}(\overline{a}) - \overline{a}_{1}}{n+1}\right)$$

$$= \frac{|nF_{1}^{n+1}(\overline{a}) - n\overline{a}_{1} - (n+1)F_{1}^{n}(\overline{a}) + (n+1)\overline{a}_{1}|}{n(n+1)}$$

$$\leq \frac{|F_{1}^{n+1}(\overline{a}) - F_{1}^{n}(\overline{a})|}{n+1} + \frac{|F_{1}^{n}(\overline{a}) - \overline{a}_{1}|}{(n+1)n} \leq \frac{L}{n+1} + \frac{L}{n+1} < \frac{\delta}{8}. \quad \Box$$

**DEFINITION.**  $\Gamma_a$  is the rotation interval associated with a.

If  $\Lambda$  is an *f*-invariant subset of *A*, the rotation set of *f* restricted to  $\Lambda$ ,  $R(f|_{\Lambda})$ , is the union  $\bigcup_{\alpha \in \Lambda} \Gamma_a$ . If  $\Lambda = A$ ,  $R(f|_{\Lambda})$  is called the **rotation set** of *f* and denoted by R(f).

Problem. Is R(f) closed? (see Proposition 2.1, cf. [10]). (If R(f) is finite then every point has rotation number.)

DEFINITION. The rotation function  $\rho: A \to \mathbf{R}$  is defined by:

$$\forall x \in A \quad \rho(x) = \limsup \frac{F_1^n(\overline{x}) - \overline{x}_1}{n}$$

It is easy to see that: (cf. [14])

- (i)  $\rho$  is measurable.
- (ii)  $\rho$  is continuous in a dense subset of A.

(iii)  $\rho$  is Lebesgue measurable and  $\int_{A} \rho = \lim_{n \to \infty} \int (F_1^n(\overline{x}) - \overline{x}_1)/n \, dx$ .

(iv) For  $\eta > 0$ , there exists a closed set F such that  $m(F) > m(A) - \eta$ and  $\rho$  is continuous in F (m is the Lebesgue measure). 2. Homeomorphisms of the annulus. The rotation number of a point is defined using the asymptotic average of the angular component of the forward orbit of a point. The  $\omega$ -limit set is defined using the forward asymptotic behavior of a point. One would expect that if a point x has rotation number  $\alpha$  then the rotation set of  $\omega(x)$  is reduced to  $\alpha$ . However this is not the case. There are examples (cf. pg. 262-263) of points with rotation number whose rotation set of the  $\omega$ -limit set is nontrivial.

In this section we study the relationship between the rotation interval of a point and the rotation of its  $\omega$ -limit set.

Let  $\beta(x, \delta)$  be the ball of center x and radius  $\delta$ .

**PROPOSITION 2.1.** Let  $\Lambda$  be a compact f-invariant subset of A.  $R(f|_{\Lambda})$  contains its supremum and infimum.

*Proof*. We start by noticing that Lemma 1.1 assures the existence of the infimum and supremum of  $R(f|_{\Lambda})$ . Let  $\alpha = \inf R(f|_{\Lambda})$ . We assume that  $\alpha \notin R(f|_{\Lambda})$ . Then the following holds:

(1)  $d(\alpha, \Gamma_x) = \varepsilon_x > 0$ , for all  $x \in \Lambda$ .

(2)  $\forall x \in \Lambda \exists n_x \in \mathbb{Z}^+$  and  $\delta_x > 0$  such that

$$\frac{F_1^{n_x}(\overline{x})-\overline{x}_1}{n_x}-\alpha>\frac{\varepsilon_x}{2}\quad\text{and}\quad\frac{F_1^{n_x}(\overline{y})-\overline{y}_1}{n_x}-\alpha>\frac{\varepsilon_x}{2},\qquad\forall y\in\beta(x,\delta_x).$$

By compactness of  $\Lambda \exists x_1, \ldots, x_k \in \Lambda$  such that  $\Lambda \subset \bigcup_{j=1}^k \beta(x_j, \delta_j)$ where  $\delta_j = \delta_{x_j}$ .

Setting  $\varepsilon_0 = \min{\{\varepsilon_1, \ldots, \varepsilon_k\}}$  and  $n^* = \max{\{n_1, \ldots, n_k\}}$  (for simpler notation we denote  $\varepsilon_j$  for  $\varepsilon_{x_j}$  and  $n_j$  for  $n_{x_j}$ ), we choose  $n_0 > n^*$  such that  $n^*L/n_0 < \varepsilon_0/8$ , where  $L = \max{\{|F_1(y) - y_1|, y \in \mathbb{R} \times I\}}$ .

*Claim.*  $\forall n \geq n_0$  and  $x \in \Lambda$ 

$$\frac{F_1^n(\overline{x})-\overline{x}_1}{n}-\alpha>\frac{\varepsilon_0}{4}.$$

(This contradicts the infimum assumption for  $\alpha$ .)

*Proof of the claim.* Let  $n > n_0$  and  $x \in \Lambda$ . Then  $x \in \beta(x_{i_1}, \delta_{i_1})$  for some  $i_1 \leq k$ . Condition (2) above can be written as follows

$$F_1^{n_{i_1}}(\overline{x}) - \overline{x}_1 - n_{i_1}\alpha > n_{i_1}\frac{\varepsilon_0}{2}$$

Since  $f^{n_{i_1}}(x) \in \Lambda$  one has

$$F_1^{n_{i_1}+n_{i_2}}(\overline{x}) - F_1^{n_{i_1}}(\overline{x}) - n_{i_2}\alpha > n_{i_2}\frac{\varepsilon_0}{2}$$

for some  $i_2 \leq k$ . Adding both inequalities, one gets

$$F_1^{n_{i_1}+n_{i_2}}(\overline{x})-\overline{x}_1-(n_{i_1}+n_{i_2})\alpha>(n_{i_1}+n_{i_2})\cdot\frac{\varepsilon_0}{2}.$$

This procedure is repeated until

$$s = n_{i_1} + \cdots + n_{i_p} < n \le n_{i_1} + \cdots + n_{i_{(p+1)}}$$

The following calculations are rather straightforward

$$F_1^s(\overline{x}) - \overline{x}_1 - s\alpha > s\frac{\varepsilon_0}{2}$$

Setting n' = n - s it follows that  $n' \le n^*$ . Hence

$$\frac{F_1^n(\overline{x}) - \overline{x}_1}{n} = \frac{F_1^n(\overline{x}) - F_1^s(\overline{x})}{n} + \frac{F_1^s(\overline{x}) - \overline{x}_1}{s} \cdot \frac{s}{n}$$
$$= \frac{F_1^n(\overline{x}) - F_1^s(\overline{x})}{n} + \frac{F_1^s(\overline{x}) - \overline{x}_1}{s} - \frac{F_1^s(\overline{x}) - \overline{x}_1}{s} \cdot \frac{n'}{n}$$

Since

$$\left|\frac{F_1^n(\overline{x}) - F_1^s(\overline{x})}{n}\right| \le \frac{n'L}{n} \le \frac{n^*L}{n} \le \frac{\varepsilon_0}{8}$$

and

$$\left|\frac{F_1^s(\overline{x}) - \overline{x}_1}{s} \cdot \frac{n'}{n}\right| \le \frac{n'L}{n} < \frac{\varepsilon_0}{8}$$

one has

$$\frac{F_1^n(\overline{x}) - \overline{x}_1}{n} - \alpha > \frac{F_1^s(\overline{x}) - \overline{x}_1}{s} - \alpha - \frac{\varepsilon_0}{8} - \frac{\varepsilon_0}{8} > \frac{\varepsilon_0}{2} - \frac{\varepsilon_0}{4} = \frac{\varepsilon_0}{4}.$$

REMARK. If  $\Lambda$  is some  $\omega$ -limit set this proposition basically implies that  $R(f|_{\Lambda}) \subset [\inf R(f|_{\Lambda}), \sup R(f|_{\Lambda})]$ . In the known examples where the inclusion is strict, there exists some point without rotation number. Does equality hold if we assume that every point has rotation number?

COROLLARY 2.2. If  $R(f|\omega(a)) = \{\alpha\}$  then a has rotation number and it equals  $\alpha$ .

*Proof.* Applying the proof of 2.1 to  $\Lambda = \omega(a)$  we have that  $\Gamma_a \subset [\inf R(f|\omega(a)), \sup R(f|\omega(a))].$ 

The corollary below is an easy consequence of a theorem by J. Franks which says that every point of an orientation preserving homeomorphism of the annulus with finitely many periods has rotation number. Furthermore if  $\Lambda$  is a compact, invariant and chain transitive subset of the annulus then  $R(f|_{\Lambda})$  is constant. COROLLARY 2.3. If f is a homeomorphism of A with finitely many periods then  $R(f|\omega(a)) = \rho(a)$ , for every  $\alpha \in A$ .

*Proof*. If f is orientation preserving, the result follows from Franks' theorem. Otherwise  $f^2$  is orientation preserving. The proof follows from the next two lemmas since  $R(f^2|\omega_{f^2}(a)) = \rho_{f^2}(a)$ .

**LEMMA.** The point  $a \in A$  has rotation number under f iff it has rotation number under  $f^2$ . If  $\rho_f(a)$  exists then  $\rho_f(a) = \rho_{f^2}(a)/2$ .

Proof.

$$\frac{F_1^{2n+1}(\overline{a}) - \overline{a}_1}{2n+1} - \frac{F_1^{2n}(\overline{a}) - \overline{a}_1}{2n} \bigg|$$
  

$$\leq \bigg| \frac{F_1^{2n+1}(\overline{a}) - F_1^{2n}(\overline{a})}{2n+1} \bigg| + \bigg| \frac{F_1^{2n}(\overline{a}) - \overline{a}_1}{2n} \bigg| \frac{1}{2n+1} \bigg|$$
  

$$\leq \frac{L+L}{2n+1}, \quad \text{where } L = \max\{|F_1(y) - y_1|, y \in \mathbb{R} \times I\}.$$

It follows that if  $\rho_{f^2}(a)$  exists, so does  $\rho_f(a)$  and  $\rho_f(a) = \rho_{f^2}(a)/2$ .  $\Box$ 

LEMMA.  $R(f^2|\omega_{f^2}(a)) = 2 \cdot R(f|\omega_f(a)).$ 

*Proof*. Let  $\alpha \in R(f^2|\omega_{f^2}(a))$ . Choose  $(n_i)_i$  and  $x \in \omega_{f^2}(a)$  such that

$$\alpha = \lim_{i} \frac{F_1^{2n_i}(\overline{x})}{n_i} = 2\lim_{i} \frac{F_1^{2n_i}(\overline{x})}{2n_i}.$$

Since  $\lim_i F_1^{2n_i}(\overline{x})/2n_i \in R(f|\omega_f(a))$  we have proved that

$$R(f^2|\omega_{f^2}(a)) \subset 2 \cdot R(f|\omega_f(a)).$$

Now we show the other inclusion. Fix  $\alpha \in R(f|\omega_f(a))$  and choose  $(n_i)_i$  and  $x \in \omega_f(a)$  such that  $\alpha = \lim_i F_1^{n_i}(\overline{x})/n_i$ . Assume  $(n_i)_i$  has some subsequence constituted by even integers. Then  $x \in \omega_{f^2}(a)$ . Therefore  $2\alpha \in R(f^2|\omega_{f^2}(a))$ . If such sequence does not exist then

$$f(x) \in \omega_{f^2}(a)$$
 and  $\alpha = \lim_i \frac{F_1^{1+n_i}(\overline{x})}{1+n_i}$ .

Therefore  $2\alpha \in R(f^2|\omega_{f^2}(a))$ .

3. Properties of entropy and the rotation set. Both topological entropy and the rotation set *measure* the dynamics of an endomorphism. In this section we point out some similarities between these two concepts. We shall use the definition of entropy as presented by Bowen in [4].

Notation. h(f) denotes the topological entropy of f.

We state below, without proof, some well known results concerning topological entropy [1]. We then state and prove the corresponding properties of the rotation set.

P1. Topological entropy and the rotation set are both topological invariants.

*Proof*. We show that  $R(\psi f \psi^{-1}) = R(f)$ , where  $\psi$  is some homeomorphism of A.

Set  $\Psi = \iota + \eta$ , where  $\Psi$  is a lift of  $\psi$  and  $\iota(x, y) = (x, 0)$  for any  $(x, y) \in \mathbf{R} \times I$ , (note that  $\eta$  is translation invariant in the following sense:  $\eta(x + 1, y) = \eta(x, y), \forall (x, y) \in \mathbf{R} \times I$ ).

For  $\alpha \in R(f)$  we choose  $x \in A$  and  $(n_i)_i$  such that

$$\alpha = \lim_{i} \frac{F_1^{n_i}(\overline{x})}{n_i}.$$

Denoting  $\overline{y} = \Psi(\overline{x})$  one has:

$$\alpha = \lim_{i} \frac{F_1^{n_i}(\Psi^{-1}(\overline{y}))}{n_i} = \lim_{i} \frac{F_1^{n_i}(\Psi^{-1}(\overline{y})) + \eta_1(F_1^{n_i}(\Psi^{-1}(\overline{y})))}{n_i}$$
$$= \lim_{i} \frac{\Psi_1 F^{n_i}(\Psi^{-1}(\overline{y}))}{n_i} \in R(\psi f \psi^{-1}).$$

Since  $\psi$  is a homeomorphism the proof is completed.

In fact the rotation set is invariant under semi-conjugacy i.e. given f and g, homeomorphisms of A we say that f is semi-conjugate to g if there exists  $\psi$ , continuous and onto so that the following diagram commutes:

$$\begin{array}{ccc} A & \xrightarrow{f} & A \\ \psi & & \psi \\ A & \xrightarrow{g} & A \end{array}$$

Under this assumption R(f) = R(g). The proof is similar to the previous one. However M. Rees in [13] gave an example where topological entropy is not invariant under semi-conjugacy.

P2. If  $\{f^n\}_n$  is an equicontinuous family then h(f) = 0 and R(f) is constant.

*Proof*. Since  $\{f^n\}_n$  is equicontinuous  $\exists \delta > 0$  such that  $\forall n \in \mathbb{N}$ 

$$|F_1^n(\overline{x}) - F_1^n(\overline{y})| < 1$$
 if  $|\overline{x} - \overline{y}| < \delta$ .

This implies that  $\Gamma_x = \Gamma_y$  when  $|x - y| < \delta$ . Since A is compact it can be covered by finitely many open balls  $(\beta_i)_{i=1,\dots,k}$  with radius  $\delta/2$ . The set of points without rotation number has zero measure and therefore the result follows.

P3.  $h(f^k) = |k|h(f), k \in \mathbb{Z}, \quad R(f^k) = kR(f), k \in \mathbb{Z}.$ 

(The proof follows directly from the definition, see Lemma 2.4.)

REMARK 3.1. (a) There exists a homeomorphism of A with infinite entropy. Set  $A = \{(r, \theta) : 1 \le r \le 2 \text{ and } 0 \le \theta \le 2\pi\}$ ,  $Q_n$  a small square with edge  $\le 1/4n(n+1)$ . Let

$$A_n = \left\{ (r, \theta) : 1 + \frac{1}{n+1} \le r \le 1 + \frac{1}{n} \right\} \subset Q_n$$

and f a horseshoe map as seen below.

f is extended to a homeomorphism of  $A_n$  agreeing with the identity on the boundary, also denoted by f.



Defining  $g: A \to A$  by  $g|_{A_n} = f^n$ , it follows that  $h(g) \ge h(f^n) = n \log 2$  hence  $h(g) = \infty$ . Consequently for any *p*-manifold *M*, there exists a homeomorphism of  $M^p$  with infinite entropy that can be constructed by considering generalized horseshoe maps defined as above in *p*-cylinders conveniently embedded in  $M^p$ .

P4. If the nonwandering set of f is finite then h(f) = 0 and R(f) is finite.

*Proof*. If f has finitely many periodic points then the result follows from Corollary 2.3.

P5. If  $\{f^n\}_n$  is an equicontinuous family and g a homeomorphism of A that commutes with f then  $h(f \circ g) = h(f) + h(g)$  and  $R(f \circ g) = R(f) + R(g)$ .

*Proof*. For 
$$\alpha \in R(f \circ g)$$
,  $\exists x \in A$  and  $(n_i)_i$  such that  
 $\alpha = \lim_i \frac{(F \circ G)_1^{n_i}(\overline{x})}{n_i} = \lim_i \frac{F_1^{n_i}(G^{n_i}(\overline{x}))}{n_i}$ 

and as setting several times before,  $F = i + \Phi$ , one gets

$$\alpha = \lim_{i} \frac{F_{1}^{n_{i}}(G^{n_{i}}(\overline{x}))}{n_{i}} = \lim_{i} \left( \frac{G_{1}^{n_{i}}(\overline{x})}{n_{i}} + \frac{F_{1}^{n_{i}}(G^{n_{i}}(\overline{x})) - G_{1}^{n_{i}}(\overline{x})}{n_{i}} \right)$$
$$= \lim_{i} \frac{G_{1}^{n_{i}}(\overline{x})}{n_{i}} + \lim_{i} \frac{\sum_{j=0}^{n_{i}-1} \Phi_{1} \circ F^{j} \circ G^{n_{i}}(\overline{x})}{n_{i}}.$$

Let  $x_0$  be a limit point of  $\{g^{n_i}(x)\}$  (assume  $g^{n_i}(x) \to x_0$ ) and  $L = \max\{|\Phi_1(y)|, y \in \mathbb{R} \times I\}.$ 

The equicontinuity of  $\{F^n\}_n$  and continuity of  $\Phi$  assures the existence, for  $\varepsilon > 0$ , of  $n_0$  such that

$$|\Phi_1 F^j G^{n_i}(\overline{x}) - \Phi_1 F^j(\overline{x}_0)| < \varepsilon, \qquad \forall n_i \ge n_0.$$

Therefore

$$\frac{\sum_{j=0}^{n_i-1} \left[ \Phi_1 \circ F^j \circ G^{n_i}(\overline{x}) - \Phi_1 \circ F^j(\overline{x}_0) \right] \right|}{n_i}$$

$$\leq \frac{\left| \sum_{j=0}^{n_0-1} \left[ \Phi_1 \circ F^j \circ G^{n_i}(\overline{x}) - \Phi_1 \circ F^j(\overline{x}_0) \right] \right|}{n_i}$$

$$+ \frac{\left| \sum_{j=n_0}^{n_i-1} \left[ \Phi_1 \circ F^j \circ G^{n_i}(\overline{x}) - \Phi_1 \circ F^j(\overline{x}_0) \right] \right|}{n_i}$$

$$\leq \frac{2Ln_0}{n_i} + \frac{n_i - n_0}{n_i} \varepsilon \leq 2\varepsilon \quad \text{if } n_i \text{ is suitably large.}$$

This leads to the equality

$$\lim_{i} \frac{\sum_{j=0}^{n_{i}-1} \Phi_{1} \circ F^{j} \circ G^{n_{i}}(\overline{x})}{n_{i}} = \lim_{i} \frac{\sum_{j=0}^{n_{i}-1} \Phi_{1} \circ F^{j}(\overline{x}_{0})}{n_{i}} = \lim_{i} \frac{F_{1}^{n_{i}}(\overline{x}_{0})}{n_{i}}.$$

Plugging this back into the expression for  $\alpha$ , one gets

$$\alpha = \lim_{i} \frac{G_1^{n_i}(\overline{x})}{n_i} + \lim_{i} \frac{F_1^{n_i}(\overline{x}_0)}{n_i} \in R(g) + R(f).$$

This shows that  $R(f \circ g) \subseteq R(f) + R(g)$ .

Now we prove the other inclusion. Fix  $\alpha \in R(g) + R(f)$ . Then  $\alpha = \beta + \delta$  with  $\beta \in R(g)$  and  $\delta \in R(f)$ . Since  $\beta \in R(g)$  there exists  $x \in A$  and  $(n_i)_i$  so that

$$\beta = \lim \frac{G_1^{n_i}(\overline{x})}{n_i}.$$

Let y be a limit point  $\{g^{n_i}(\overline{x})\}$  (we assume that  $g^{n_i}(x) \xrightarrow{i} y$ ). The equicontinuity of  $\{F^n\}$  and P2 assures that R(f) is constant. Then

$$\delta = \lim_{i} \frac{F_1^{n_i}(\overline{y}) - \overline{y}_1}{n_i} = \lim_{i} \frac{\sum_{j=0}^{n_i-1} \Phi_1 \circ F^j(\overline{y})}{n_i}$$

Using, once more, the equicontinuity of  $\{F^n\}_n$  we have that

$$\lim_{i} \frac{\sum_{j=0}^{n_i-1} \Phi_1 \circ F^j(\overline{y})}{n_i} = \lim_{i} \frac{\sum_{j=0}^{n_i-1} \Phi_1 \circ F^j \circ G^{n_i}(\overline{x})}{n_i}.$$

Plugging this back into the expression for  $\alpha$  we get:

$$\alpha = \lim_{i} \left( \frac{G_1^{n_i}(\overline{x})}{n_i} + \frac{\sum_{j=0}^{n_i=1} \Phi_1 \circ F^j \circ G^{n_i}(\overline{x})}{n_i} \right)$$
$$= \lim_{i} \frac{F_1^{n_i}(G^{n_i}(\overline{x}))}{n_i} \in R(f \circ g).$$

Notice that P5 requires equicontinuity; just consider any homeomorphism f with non-trivial rotation set and  $g = f^{-1}$ .

Consider  $C^0(A, A)$  the set of all continuous functions of A with the metric  $d_0$  defined by  $d_0(f, g) = \sup\{|F(\overline{x}) - G(\overline{x})|, \overline{x} \in I^2\}$  and  $\mathfrak{P}(\mathbb{R})$  the set of all compact subsets of  $\mathbb{R}$  with the Hausdorff metric D:

$$D(X, Y) = \max\{\max\{(\min d(\alpha, \beta), \beta \in Y), \alpha \in X\}, \\ \max\{(\min d(\alpha, \beta), \alpha \in X), \beta \in Y\}\}, \quad X, Y \in \mathfrak{P}(\mathbb{R}).$$

(d denotes the euclidean metric in  $\mathbf{R}$ ).

Let  $C^*(A, A)$  be the set of all continuous functions on A with the  $d_*$  metric.  $\forall f, g \in C^*(A, A) \ d_*(f, g) = \sup\{|\varphi(F^j(\overline{x})) - \psi(G^j(\overline{x}))| : \overline{x} \in I^2, j \in \mathbb{N}\}$ , where F and G denote lifts of f and g, respectively, such that  $F = i + \varphi$  and  $G = i + \psi$  (cf. pg. 252).

Now let  $h : C^0(A, A) \to \mathbb{R}$  be the entropy function and  $\mathfrak{R} : C^*(A, A) \to \mathfrak{P}(\mathbb{R})$  be so that  $\forall f \in C^*(A, A) \ \mathfrak{R}(f) = \text{closure of } R(f)$ .

**P6.** The function h is discontinuous at f if f has finite entropy and some periodic point; the function  $\Re$  is uniformly continuous.

*Proof.* We first prove that h is discontinuous at f if h(f) is finite and f has some periodic point p. Without loss of generality assume p a fixed point, for  $\varepsilon$  small enough choose  $\delta > 0$  with  $f(\beta(p, \delta)) \subset$  $\beta(p, \varepsilon) \subset A$  and select  $\varepsilon_1 < \min\{\varepsilon, \delta\}$ . We now define a homeomorphism g on A, which is an extension of a horseshoe map in  $\beta(p, \varepsilon_1)$ that agrees with the identity elsewhere—see Remark 3.1 and the picture below.



Let  $\alpha : A \to [0, 1]$  be a bump function with value 1 in  $\beta(p, \varepsilon_1)$  and 0 outside  $\beta(p, \delta)$ . We define  $\overline{f}_n = \alpha g^n + (1 - \alpha)f$ . It follows that  $d_0(f, \overline{f}_n) < 2\varepsilon$ , and  $h(\overline{f}_n) \ge n \log 2$  since  $h(g^n) \ge n \log 2$ .

We now prove that  $\mathfrak{R}$  is uniformly continuous. Fix  $\varepsilon > 0$  and  $\alpha \in \mathfrak{R}(f)$ , and choose  $(n_i)_i$  and  $x \in A$  so that:

$$\min_{\beta \in \mathfrak{R}(g)} d(\alpha, \beta) \leq \min_{\beta \in \mathfrak{R}(g)} \left| \frac{F_1^{n_i}(\overline{x})}{n_i} - \beta \right| + \varepsilon.$$

We have that  $\{G_1^{n_i}(\overline{x})/n_i\}$  has some subsequence that converges to some number  $\mu$ . Therefore we choose  $n_0$  s.t.

$$\begin{split} \min_{\boldsymbol{\beta}\in\mathfrak{R}(g)} d(\alpha, \boldsymbol{\beta}) &\leq \left| \frac{F_1^{n_0}(\overline{x})}{n_0} - \mu \right| + \varepsilon \\ &\leq \left| \frac{F_1^{n_0}(\overline{x})}{n_0} - \frac{G_1^{n_0}(\overline{x})}{n_0} \right| + 2\varepsilon \\ &= \frac{\left| \sum_{j=0}^{n_0-1} \left[ \Phi_1 \circ F^j(\overline{x}) - \Psi_1 \circ G^j(\overline{x}_0) \right] \right|}{n_0} + 2\varepsilon \\ &\leq d_*(f, g) + 2\varepsilon. \end{split}$$

Consequently we have  $D(\mathfrak{R}(f), \mathfrak{R}(g)) \leq d_*(f, g)$ .

P7. Set  $S = \{f \in \text{Diff}(A): f \text{ has some point without rotation number}\}$  and  $T = \{f \in \text{Diff}(A): h(f) > 0\}$ . Both sets have nonempty interior in the  $C^1$  topology.

*Proof.* Denote  $A = \{(r, \theta) : 1 \le r \le 2\}$  and  $Q \subset A$  a small square with edge = 1/4, consider a horseshoe map that contracts linearly in the vertical direction by a factor  $\delta < 1/2$  and expands in the horizontal direction by a factor  $1/\delta$  (see picture below). We can extend it to a diffeomorphism, f, of A (for details see [5]).



There exists an invariant hyperbolic set  $\Lambda \subset Q$  where f is topologically conjugate to a shift  $\sigma$  in two symbols.



To each  $x \in \Lambda$  we associate an infinite sequence  $(\ldots, a_{-1}, a_0, a_1, \ldots)$ —the itinerary of x—so that:

> $a_j = s$  iff  $f^j(x) \in H_s$  $a_{-j} = s$  iff  $f^{-j}(x) \in V_s$  (see [5] for details).

Now  $\sigma(..., a_{-1}, a_0, a_1, ...) = (..., b_{-1}, b_0, b_1, ...)$  where  $b_i = a_{i+1}$ . We choose  $x \in \Lambda$ .

If 
$$a_1 = 0$$
 then  $|F_1(\overline{x}) - \overline{x}_1| \le 1/4$ .  
If  $a_1 = 1$  then  $|F_1(\overline{x}) - \overline{x}_1 - 1| \le 1/4$  (see picture below).

Therefore, in general we obtain  $|F_1^n(\overline{x}) - \overline{x}_1 - k_n| \le 1/4$ , where  $k_n$  is the number of 1's that appear in  $\{a_1, \ldots, a_n\}$ .

It follows that

$$\lim_n \frac{F_1^n(\overline{x}) - \overline{x}_1}{n} = \lim_n \frac{k_n}{n}.$$



In order to find a point without rotation number simply choose a sequence  $(\ldots, a_{-1}, a_0, a_1, \ldots)$  such that  $k_n/n$  does not converge.

More precisely we define a sequence of 0's and 1's with longer and longer blocks of only 0's or only 1's so that the sequence  $(k_n/n)_n$  oscillates between getting very close to 0 and very close to 1. The point x associated with this itinerary does not have rotation number and the result follows from the stability of a hyperbolic set. The above proof also shows that T has nonempty interior.

4. Some connections between entropy and rotation set. If f is a  $C^{1+\varepsilon}$  diffeomorphism of A with positive entropy, Katok's theorem [11] implies that there exists a hyperbolic invariant Cantor set  $\Lambda$  such that  $f|_{\Lambda}$  is topologically conjugate to a shift of n symbols. We note that either the rotation set of  $\Lambda$  reduces to one number or there exists some point without rotation number.

If  $R(f|_{\Lambda})$  is not one number then we can choose x, y in  $\Lambda$  with different rotation numbers  $\alpha, \beta$ .

To each point we associate a sequence of 0's and 1's

 $x \rightarrow (\dots, a_0, \dots)$  and  $y \rightarrow (\dots, b_0, \dots)$ .

We now construct a new sequence by taking longer and longer blocks from the sequences associated to x and y in such a way that  $(k_n/n)_n$ (see pg. 263 for the definition of  $k_n$ ) gets progressively and alternately closer to  $\alpha$  and  $\beta$ . The point corresponding to this sequence of 0's and 1's does not have rotation number.

DEFINITION. A diffeomorphism of A satisfies the Axiom A (see [4]) if it admits an Axiom A extension to  $S^2$ .

EXAMPLE. In picture 1 below we give an example of a flow whose time one mapping defines an Axiom A diffeomorphism of the annulus.



Each component of the boundary of A contains a source and a sink, and bounds a disk in  $S^2$ .

Picture 2 shows how the flow can be extended to  $S^2$ .



**THEOREM 4.1** (Bowen [3]). If f satisfies Axiom A and h(f) = 0 then the nonwandering set  $\Omega(f)$  is finite.

It follows easily that

COROLLARY 4.2. If f is Axiom A and h(f) = 0 then every point has rotation number and R(f) is constant.

*Proof*. By 4.1  $\Omega(f)$  is finite. Corollary 2.3 implies that every point has rotation number and R(f) is constant.

This leads to the following question: Does zero entropy imply that every point has rotation number?

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