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**EISENSTEIN-SERIES ON REAL, COMPLEX, AND
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The real, complex, and quaternionic half-spaces are introduced in certain analogy with the Siegel half-space. The modified symplectic group acts on the attached half-space in the usual way. At first properties of these half-spaces considered as symmetric spaces are derived. Then a fundamental domain with respect to the modified modular group, which consists of integral modified symplectic matrices, is constructed. The behavior of convergence of the corresponding Eisenstein-series is determined carefully. The Fourier-coefficients of the Eisenstein-series are calculated explicitly, whenever the degree is sufficiently small.

Introduction. The present paper deals with half-spaces, which are built in analogy with the Siegel half-space, and the corresponding non-analytic Eisenstein-series. The roots can be traced back to C. L. Siegel's paper "Die Modulgruppe in einer einfachen involutorischen Algebra" [30]. A special case of these investigations is considered and continued by the examination of the Riemannian geometry as well as the attached Eisenstein-series.

To be more precise, throughout this paper let \mathbf{F} stand for \mathbf{R} , \mathbf{C} or \mathbf{H} , where \mathbf{H} is the skew-field of real Hamiltonian quaternions. Just as in [16] let $r = r(\mathbf{F}) = \dim_{\mathbf{R}} \mathbf{F}$ and denote the standard basis of \mathbf{F} over \mathbf{R} by $1 = e_1, \dots, e_r$. Given $a = \sum_{j=1}^r a_j e_j \in \mathbf{F}$, $a_j \in \mathbf{R}$, put $\text{Re}(a) := a_1$ and let $a \mapsto \bar{a} = 2 \text{Re}(a) - a$ denote the canonical conjugation in \mathbf{F} . Then $A^{(n)}$, resp. $A \in \text{Mat}(n; \mathbf{F})$, means that A is an $n \times n$ matrix with entries in \mathbf{F} and A' denotes the transpose of A . The letter I is reserved for the identity matrix and 0 for the zero matrix of appropriate size. $\text{GL}(n; \mathbf{F})$ stands for the group of units in the ring $\text{Mat}(n; \mathbf{F})$.

The half-space $\mathcal{H}(n; \mathbf{F})$ consists of all $Z \in \text{Mat}(n; \mathbf{F})$ such that $Z + \bar{Z}'$ becomes a positive definite Hermitian matrix. Thus $i\mathcal{H}(n; \mathbf{C})$ equals the Hermitian half-space, which was investigated by H. Braun [3]. But the remaining cases are related, because $\mathcal{H}(n; \mathbf{H})$ can always be embedded into the Hermitian half-space of degree $2n$.

The attached modified symplectic group $\text{MSp}(n; \mathbf{F})$ consists of the automorphs of the symmetric matrix $Q = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}$, $I = I^{(n)}$, having the

signature (n, n) and acts on $\mathscr{H}(n; \mathbf{F})$ in the usual way. The real modified symplectic group was already investigated by C. L. Siegel [28], M. Koecher [14], III, §1, and H. Maaß [23] in different contexts. Considering the symplectic group

$$(0.1) \quad \mathrm{Sp}(n; \mathbf{F}) = \{M \in \mathrm{Mat}(2n; \mathbf{F}); \overline{M}'JM = J\},$$

$$J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}, \quad I = I^{(n)},$$

as in [16], one has

$$(0.2) \quad \begin{pmatrix} e_2 I & 0 \\ 0 & I \end{pmatrix} \mathrm{MSp}(n; \mathbf{C}) \begin{pmatrix} e_2 I & 0 \\ 0 & I \end{pmatrix}^{-1} = \mathrm{Sp}(n; \mathbf{C}).$$

$\mathrm{MSp}(n; \mathbf{F})$ is obviously conjugate to the indefinite unitary group $U^n(2n, \mathbf{F})$ in [34], p. 377, and to $O(n, n)$, $U(n, n)$, resp. $\mathrm{Sp}(n, n)$, if $\mathbf{F} = \mathbf{R}, \mathbf{C}$, resp. \mathbf{H} , in Helgason's notation (cf. [8], p. 340).

Nevertheless the notion of modified symplectic group may be justified by the connection with C. L. Siegel's paper [30]. Consider $\mathbf{F} = \mathbf{R}, \mathbf{H}$ and an arbitrary \mathbf{R} -involution ι of $\mathrm{Mat}(n; \mathbf{F})$. According to [1], X, Theorem 11, there exists $F \in \mathrm{GL}(n; \mathbf{F})$ such that $\overline{F}' = \pm F$ and

$$\iota(X) = F\overline{X}'F^{-1} \quad \text{for } X \in \mathrm{Mat}(n; \mathbf{F}).$$

In this general situation C. L. Siegel [30] defined the symplectic group Σ . In our notation we gain

$$(0.3) \quad \Sigma = \begin{cases} \begin{pmatrix} F & 0 \\ 0 & I \end{pmatrix} \mathrm{Sp}(n; \mathbf{F}) \begin{pmatrix} F & 0 \\ 0 & I \end{pmatrix}^{-1} & \text{if } \overline{F}' = F, \\ \begin{pmatrix} F & 0 \\ 0 & I \end{pmatrix} \mathrm{MSp}(n; \mathbf{F}) \begin{pmatrix} F & 0 \\ 0 & I \end{pmatrix}^{-1} & \text{if } \overline{F}' = -F. \end{cases}$$

The special case $\mathbf{F} = \mathbf{H}$, $n = 1$, $F = (e_3)$ was recently treated by E. Kähler [10].

The Riemannian geometry and the description of the geodesics can be pointed out along the lines of Siegel's classical work [29], where the case $\mathbf{F} = \mathbf{C}$ is due to H. Klingenberg [12]. If dZ denotes the matrix of differentials, then

$$ds^2 = \frac{1}{2} \mathrm{trace}(Y^{-1}dZY^{-1}\overline{dZ}' + dZY^{-1}\overline{dZ}'Y^{-1}), \quad Y := \frac{1}{2}(Z + \overline{Z}'),$$

proves to be a positive definite quadratic differential form. The modified symplectic transformations become isometries. Thus $\mathscr{H}(n; \mathbf{F})$ endowed with ds^2 turns out to be a Riemannian globally symmetric space of the noncompact type, which is irreducible except for

$\mathbf{F} = \mathbf{R}$, $n = 1, 2$ and which fails to be Hermitian, whenever $\mathbf{F} = \mathbf{R}$, $n \neq 2$, resp. $\mathbf{F} = \mathbf{H}$, $n \geq 1$.

$\mathcal{H}(1; \mathbf{C})$ equals the right half-plane in \mathbf{C} . Moreover $\mathcal{H}(1; \mathbf{H})$ becomes a model of the four-dimensional hyperbolic space, which was recently treated by E. Kähler [10]. Kähler's paper was the starting point of these investigations. The present paper arose from the attempt of combining Kähler's approach with the investigations of Eisenstein-series on the three-dimensional hyperbolic space by J. Elstrodt, F. Grunewald and J. Mennicke [6] as well as with Siegel's methods. Therefore this paper can also be understood as an extension of [6].

Choosing a special order for $\mathbf{F} = \mathbf{R}, \mathbf{C}, \mathbf{H}$, namely \mathbf{Z} , the Gaussian integers and the quaternions of Hurwitz, the modified modular group is defined to consist of all integral modified symplectic matrices. By means of the Euclidean algorithm a simple set of generators of the modified modular group can be determined. Following the classical procedure as in the case of the Siegel half-space, a fundamental domain is obtained, which has a cusp only at infinity.

The last two paragraphs deal with the corresponding non-analytic Eisenstein-series. Let Γ_n denote the modified modular group and Γ_n^∞ the subgroup of all matrices, whose C -block equals 0. Given $Z \in \mathcal{H}(n; \mathbf{F})$ and $M \in \Gamma_n$ set $Y_M = \frac{1}{2}(M\langle Z \rangle + \overline{M}\langle \overline{Z} \rangle')$. Then the Eisenstein-series is given by

$$E_n^{\mathbf{F}}(Z, s) = \sum_{M: \Gamma_n^\infty \backslash \Gamma_n} (\det Y_M)^s, \quad Z \in \mathcal{H}(n; \mathbf{F}),$$

and converges locally uniformly in Z and s . The abscissa of absolute convergence equals $\operatorname{Re}(s) = \frac{1}{n} \cdot d$, where d denotes the dimension of the real vector space of all skew-Hermitian matrices. One can define a modified Siegel ϕ -operator and obtains the same result, namely

$$E_n^{\mathbf{F}}(\cdot, s) |_{s\phi} = E_{n-1}^{\mathbf{F}}(\cdot, s),$$

as known from the classical case.

The investigations of $E_n^{\mathbf{R}}(\cdot, s)$ by H. Maaß [23] are extended and partially strengthened. The Eisenstein-series $E_n^{\mathbf{C}}(\cdot, s)$ were also examined by G. Shimura [27]. But one has to distinguish carefully between $E_n^{\mathbf{H}}(\cdot, s)$ and the analytic Eisenstein-series on the half-space of quaternions in [16], since the domains of definition are completely different.

Moreover coincidences between different classes of symmetric spaces for “small” values of n (cf. [8], p. 351–353) correspond to identities between the associated Eisenstein-series. Therefore Eisenstein-series on the upper half-plane in \mathbf{C} as well as Eisenstein-series for $\mathrm{GL}(4; \mathbf{Z})$ (cf. [31]) come to light.

Finally the Fourier-expansions of Eisenstein-series are investigated. Just as in the case of the Siegel half-space, one cannot expect explicit formulas for arbitrary degree. But if the degree is sufficiently “small”, the explicit description of the Fourier-coefficients succeeds. As one can expect from the upper half-plane (cf. [19], [20]), resp. the three-dimensional hyperbolic space (cf. [6]), resp. from Eisenstein-series for $\mathrm{GL}(n; \mathbf{Z})$ (cf. [31]), the Fourier-coefficients involve the modified Bessel function and certain weighted divisor sums.

Although a great deal of work can be done along the lines of classical patterns, one has to be cautious with the analogy. On several occasions the cases $\mathbf{F} = \mathbf{R}$ or $\mathbf{F} = \mathbf{H}$ or even $n = 1$ have to be treated in a different way. Thus an explicit description might be useful.

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1. Real, complex, and quaternionic half-space. Considering the symmetric matrix

$$Q := \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}, \quad I = I^{(n)},$$

we define

$$\mathrm{MSp}(n; \mathbf{F}) := \{M \in \mathrm{Mat}(2n; \mathbf{F}); \overline{M}' Q M = Q\}$$

and call $\mathrm{MSp}(n; \mathbf{F})$ the *modified symplectic group of degree n over \mathbf{F}* . Given $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \mathrm{MSp}(n; \mathbf{F})$ we always assume $A, B, C, D \in \mathrm{Mat}(n; \mathbf{F})$. Clearly $M \in \mathrm{MSp}(n; \mathbf{F})$ is equivalent to $\overline{M}' \in \mathrm{MSp}(n; \mathbf{F})$ as well as to

$$(1.1) \quad A\overline{B}' + B\overline{A}' = C\overline{D}' + D\overline{C}' = 0, \quad A\overline{D}' + B\overline{C}' = I.$$

In this case one has

$$(1.2) \quad M^{-1} = Q\overline{M}'Q = \begin{pmatrix} \overline{D}' & \overline{B}' \\ \overline{C}' & \overline{A}' \end{pmatrix}.$$

The definition contains one trivial case, namely

$$(1.3) \quad \mathbf{MSp}(1; \mathbf{R}) = \left\{ \begin{pmatrix} a & 0 \\ 0 & a^{-1} \end{pmatrix}; 0 \neq a \in \mathbf{R} \right\} \\ \cup \left\{ \begin{pmatrix} 0 & b \\ b^{-1} & 0 \end{pmatrix}; 0 \neq b \in \mathbf{R} \right\}.$$

Again in the general situation we want to describe special elements. Therefore we need the real vector space

$$\text{Alt}(n; \mathbf{F}) := \{X \in \text{Mat}(n; \mathbf{F}); \overline{X}' = -X\}$$

of all skew-Hermitian matrices, which has the dimension $\frac{1}{2}n(n+1) - n$. Then the matrices

$$(1.4) \quad Q = \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix}, \quad \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}, \quad S \in \text{Alt}(n; \mathbf{F}), \\ \begin{pmatrix} \overline{U}' & 0 \\ 0 & U^{-1} \end{pmatrix}, \quad U \in \text{GL}(n; \mathbf{F}),$$

belong to $\mathbf{MSp}(n; \mathbf{F})$ in view of (1.1).

Moreover consider the subgroup

$$\mathbf{MSp}(n; \mathbf{F})_\infty := \left\{ M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \mathbf{MSp}(n; \mathbf{F}); C = 0 \right\}.$$

Then (1.1) immediately yields

$$(1.5) \quad \mathbf{MSp}(n; \mathbf{F})_\infty = \left\{ \begin{pmatrix} \overline{U}' & 0 \\ 0 & U^{-1} \end{pmatrix} \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}; \right. \\ \left. U \in \text{GL}(n; \mathbf{F}), S \in \text{Alt}(n; \mathbf{F}) \right\}.$$

Given $0 < j < n$ we define the usual embedding

$$\mathbf{MSp}(j; \mathbf{F}) \times \mathbf{MSp}(n-j; \mathbf{F}) \rightarrow \mathbf{MSp}(n; \mathbf{F}), \quad (M_1, M_2) \mapsto M_1 \times M_2, \\ (1.6) \quad \begin{pmatrix} A_1 & B_1 \\ C_1 & D_1 \end{pmatrix} \times \begin{pmatrix} A_2 & B_2 \\ C_2 & D_2 \end{pmatrix} := \begin{pmatrix} A_1 & 0 & B_1 & 0 \\ 0 & A_2 & 0 & B_2 \\ C_1 & 0 & D_1 & 0 \\ 0 & C_2 & 0 & D_2 \end{pmatrix}$$

(cf. [16], p. 44). If $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \mathbf{MSp}(n; \mathbf{F})$ with $\text{rank } C = j$, one can proceed as in the classical situation (cf. [4], 3.12, [16], II.1.4) in order to obtain $K, L \in \mathbf{MSp}(n; \mathbf{F})_\infty$ such that

$$(1.7) \quad M = K(Q^{(2j)} \times I)L,$$

where $j = 0, n$ can be interpreted unmistakably.

LEMMA 1.1. (a) *The group $\text{MSp}(n; \mathbf{F})$ is generated by the matrices*

$$\begin{aligned} Q^{(2)} \times I, \quad & \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}, \quad S \in \text{Alt}(n; \mathbf{F}), \\ & \begin{pmatrix} \bar{U}' & 0 \\ 0 & U^{-1} \end{pmatrix}, \quad U \in \text{GL}(n; \mathbf{F}). \end{aligned}$$

(b) *Let $\mathbf{F} = \mathbf{R}$, n odd, or $\mathbf{F} = \mathbf{C}, \mathbf{H}$, $n \geq 1$. Then $\text{MSp}(n; \mathbf{F})$ is also generated by the matrices (1.4).*

Proof. (a) Apply (1.7).

(b) If $\mathbf{F} = \mathbf{C}, \mathbf{H}$, compute

$$Q^{(2)} \times I = \left(\begin{pmatrix} I & S \\ 0 & I \end{pmatrix} \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \right)^2 \begin{pmatrix} I & S \\ 0 & I \end{pmatrix} \begin{pmatrix} \bar{U}' & 0 \\ 0 & U^{-1} \end{pmatrix},$$

where $S = \begin{pmatrix} e_2 & 0 \\ 0 & 0 \end{pmatrix} \in \text{Alt}(n; \mathbf{F})$, $U = \begin{pmatrix} e_2 & 0 \\ 0 & I \end{pmatrix} \in \text{GL}(n; \mathbf{F})$. If $\mathbf{F} = \mathbf{R}$, $n = 1$ use (1.3). In the case $\mathbf{F} = \mathbf{R}$, $n = 2m + 1$, $m \geq 1$, compute

$$Q^{(2)} \times I = \left(\begin{pmatrix} I & S \\ 0 & I \end{pmatrix} \begin{pmatrix} 0 & I \\ I & 0 \end{pmatrix} \right)^3 \begin{pmatrix} U' & 0 \\ 0 & U^{-1} \end{pmatrix},$$

where $S = \begin{pmatrix} 0 & 0 \\ 0 & J \end{pmatrix} \in \text{Alt}(n; \mathbf{R})$, $U = \begin{pmatrix} 1 & 0 \\ 0 & J \end{pmatrix} \in \text{GL}(n; \mathbf{R})$, $J = J^{(2m)}$. \square

The case $\mathbf{F} = \mathbf{R}$ has to be treated in a different way. Note that $\text{Sp}(n; \mathbf{R}) \subset \text{SL}(2n; \mathbf{R})$, whereas (1.5) and (1.7) yield the surprising formula

$$(1.8) \quad \det M = (-1)^j, \quad j = \text{rank } C,$$

whenever $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{MSp}(n; \mathbf{R})$. Thus $\text{MSp}(n; \mathbf{R}) \cap \text{SL}(2n; \mathbf{R})$ becomes a normal subgroup of $\text{MSp}(n; \mathbf{R})$ of index 2. If n is even, this subgroup is generated by the matrices (1.4).

Combining (0.2) and (0.3) with Siegel's procedure [30], it becomes obvious how the attached half-space has to be defined. Consider the real vector space

$$\text{Sym}(n; \mathbf{F}) := \{X \in \text{Mat}(n; \mathbf{F}); \bar{X}' = X\}$$

of the dimension $n + \frac{1}{2}rn(n-1)$ as well as the open subset $\text{Pos}(n; \mathbf{F})$ consisting of all positive definite matrices in $\text{Sym}(n; \mathbf{F})$. Then set

$$\begin{aligned} \mathcal{H}(n; \mathbf{F}) &= \text{Alt}(n; \mathbf{F}) + \text{Pos}(n; \mathbf{F}) \\ &= \{Z \in \text{Mat}(n; \mathbf{F}); Z + \bar{Z}' \in \text{Pos}(n; \mathbf{F})\}. \end{aligned}$$

We always assume that each $Z \in \mathcal{H}(n; \mathbf{F})$ is given in the form

$$Z = X + Y, \quad X \in \text{Alt}(n; \mathbf{F}), \quad Y \in \text{Pos}(n; \mathbf{F}).$$

DEFINITION. $\mathcal{H}(n; \mathbf{F})$ is called the *real, complex, resp. quaternionic half-space of degree n* , whenever $\mathbf{F} = \mathbf{R}, \mathbf{C}$, resp. \mathbf{H} .

The definition especially yields

$$\mathcal{H}(1; \mathbf{R}) = \mathbf{R}^+ = \{y \in \mathbf{R}; y > 0\},$$

$$\mathcal{H}(1; \mathbf{H}) = \left\{ z = \sum_{j=1}^4 z_j e_j; z_j \in \mathbf{R}, z_1 > 0 \right\}.$$

Note that in the cases $\mathbf{F} = \mathbf{R}, \mathbf{H}$ there is a decisive difference between $\mathcal{H}(n; \mathbf{F})$ and the half-space $H(n; \mathbf{F})$ defined in [16], p. 46. But there are also close relations, namely

$$(1.9) \quad H(n; \mathbf{C}) = i \cdot \mathcal{H}(n; \mathbf{C}) = \text{Sym}(n; \mathbf{C}) + i \text{Pos}(n; \mathbf{C}).$$

Given $a = \sum_{j=1}^4 a_j e_j \in \mathbf{H}$ define

$$\check{a} = \begin{pmatrix} a_1 e_1 + a_2 e_2 & a_3 e_1 + a_4 e_2 \\ -a_3 e_1 + a_4 e_2 & a_1 e_1 - a_2 e_2 \end{pmatrix} \in \text{Mat}(2; \mathbf{C})$$

and $\check{A} = (\check{a}_{kl}) \in \text{Mat}(2n; \mathbf{C})$ for $A = (a_{kl}) \in \text{Mat}(n; \mathbf{H})$ (cf. [16], p. 14,15, 46). Then (1.9) leads to

$$(1.10) \quad i\check{Z} = i\check{X} + i\check{Y} \in H(2n; \mathbf{C}), \text{ whenever } Z = X + Y \in \mathcal{H}(n; \mathbf{H}).$$

Note that i and e_2 may be identified for $\mathbf{F} = \mathbf{C}$. Furthermore (0.2) implies

$$(1.11) \quad \begin{pmatrix} iI & 0 \\ 0 & I \end{pmatrix} \{ \check{M}; M \in \text{MSp}(n; \mathbf{H}) \} \begin{pmatrix} iI & 0 \\ 0 & I \end{pmatrix}^{-1} \subset \text{Sp}(2n; \mathbf{C}),$$

where $I = I^{(2n)}$. Moreover we have the obvious relations

$$(1.12) \quad \mathcal{H}(n; \mathbf{R}) \subset \mathcal{H}(n; \mathbf{C}) \subset \mathcal{H}(n; \mathbf{H}),$$

$$\text{MSp}(n; \mathbf{R}) \subset \text{MSp}(n; \mathbf{C}) \subset \text{MSp}(n; \mathbf{H}).$$

We need the abbreviation $A[B] := \overline{B}^t A B$, whenever A is an $n \times n$ and B an $n \times m$ matrix, as well as $|\det A| := |\det \check{A}|^{1/2}$, whenever $A \in \text{Mat}(n; \mathbf{H})$ (cf. [16], p. 15, I.3.4, I.3.5).

PROPOSITION 1.2. *The half-space $\mathcal{H}(n; \mathbf{F})$ is an open convex subset of $\text{Mat}(n; \mathbf{F})$, which is contained in $\text{GL}(n; \mathbf{F})$. Given $Z = X + Y \in \mathcal{H}(n; \mathbf{F})$, one has*

$$|\det Z|^2 = \det Y \cdot \det(Y + Y^{-1}[X]).$$

Proof.

$$\begin{aligned} |\det Z|^2 &= |\det Z| |\det \bar{Z}'| = \det Y \cdot |\det(X + Y)| \cdot |\det(-Y^{-1}X + I)| \\ &= \det Y \cdot \det(Y - XY^{-1}X). \end{aligned}$$

The remaining parts are obvious. □

Next we consider the action of the modified symplectic group on the attached half-space.

THEOREM 1.3. *Let $L, M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{MSp}(n; \mathbf{F})$ and $Z = X + Y \in \mathcal{H}(n; \mathbf{F})$. Then the following hold:*

- (a) $M\langle Z \rangle := CZ + D \in \text{GL}(n; \mathbf{F})$.
- (b) $M\langle Z \rangle := (AZ + B)(CZ + D)^{-1} = X_M + Y_M \in \mathcal{H}(n; \mathbf{F})$.
- (c) $Y_M = Y[M\langle Z \rangle^{-1}]$, $Y_M^{-1} = Y^{-1}[\overline{X' \bar{C}'} + \bar{D}'] + Y[\bar{C}']$.
- (d) $(LM)\langle Z \rangle = L\langle M\langle Z \rangle \rangle \cdot M\langle Z \rangle$.

The group $\text{MSp}(n; \mathbf{F})$ acts transitively on $\mathcal{H}(n; \mathbf{F})$. Two transformations $Z \mapsto M\langle Z \rangle$ and $Z \mapsto L\langle Z \rangle$ coincide if and only if

$$L = \rho M, \quad \text{where } \rho \in \text{center } \mathbf{F}, |\rho| = 1.$$

Proof. (a) Apply (1.5), (1.7) and Proposition 1.2.

(b), (c) According to (a) we obtain $X_M \in \text{Alt}(n; \mathbf{F})$, $Y_M \in \text{Sym}(n; \mathbf{F})$ satisfying $M\langle Z \rangle = X_M + Y_M \in \text{Mat}(n; \mathbf{F})$. Thus we gain

$$2Y_M = M\langle Z \rangle + \overline{M\langle Z \rangle}' = 2Y[(M\langle Z \rangle)^{-1}]$$

in view of (1.1). Hence $Y_M \in \text{Pos}(n; \mathbf{F})$ follows. The remaining parts can be derived by easy calculations. □

Clearly the definition yields

$$(1.13) \quad Z \in \mathcal{H}(n; \mathbf{F}) \Rightarrow \bar{Z}' \in \mathcal{H}(n; \mathbf{F}).$$

In the cases $\mathbf{F} = \mathbf{C}$, $n \geq 2$, and $\mathbf{F} = \mathbf{H}$, $n = 2$, additionally

$$Z \in \mathcal{H}(n; \mathbf{F}) \Rightarrow Z' \in \mathcal{H}(n; \mathbf{F})$$

holds. Now we are going to describe the combination of (1.13) with the action of $\text{MSp}(n; \mathbf{F})$ on $\mathcal{H}(n; \mathbf{F})$. Given $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{MSp}(n; \mathbf{F})$ one easily verifies

$$\tilde{M} := M \left[\begin{pmatrix} I & 0 \\ 0 & -I \end{pmatrix} \right] = \begin{pmatrix} A & -B \\ -C & D \end{pmatrix} \in \text{MSp}(n; \mathbf{F}).$$

Then a calculation using (1.1) and Theorem 1.3 implies

PROPOSITION 1.4. *Given $Z, W \in \mathcal{H}(n; \mathbf{F})$ and $M \in \text{MSp}(n; \mathbf{F})$, one has*

- (a) $\overline{M\langle Z' \rangle} = \tilde{M}\langle Z \rangle.$
- (b) $M\langle Z \rangle + \overline{M\langle W' \rangle} = \overline{M\{W'\}}^{-1}(Z + \overline{W'})(M\{Z\})^{-1}.$
- (c) $M\langle Z \rangle - M\langle W \rangle = \overline{\tilde{M}\{W'\}}^{-1}(Z - W)(M\{Z\})^{-1}$
 $= \overline{\tilde{M}\{Z'\}}^{-1}(Z - W)(M\{W\})^{-1}.$

Following C. L. Siegel [30] we obtain a bijection between the half-space and the set of positive definite modified symplectic matrices. Put

$$\mathcal{P}(n; \mathbf{F}) := \text{MSp}(n; \mathbf{F}) \cap \text{Pos}(2n; \mathbf{F}).$$

THEOREM 1.5. *The map*

$$\kappa: \mathcal{H}(n; \mathbf{F}) \rightarrow \mathcal{P}(n; \mathbf{F}), \quad Z = X + Y \mapsto \begin{pmatrix} Y^{-1} & 0 \\ 0 & Y \end{pmatrix} \left[\begin{pmatrix} I & -X \\ 0 & I \end{pmatrix} \right],$$

is bijective and satisfies

$$(*) \quad \kappa(M\langle Z \rangle) = \kappa(Z)[M^{-1}]$$

for all $M \in \text{MSp}(n; \mathbf{F})$ and $Z \in \mathcal{H}(n; \mathbf{F})$.

Proof. $\kappa(Z) \in \mathcal{P}(n; \mathbf{F})$ follows from (1.1). The surjectivity of κ is obtained by the method of completing squares (cf. [16], I.3.2). Since κ is obviously injective, the first part is proved.

In order to demonstrate (*) we may confine ourselves to $\mathbf{F} = \mathbf{H}$ and to the generators (1.4) of $\text{MSp}(n; \mathbf{H})$. An explicit calculation using Theorem 1.3 completes the proof. □

There also exists a bounded domain, which is birationally equivalent to the half-space. Consider the generalized unit disc

$$\mathcal{D}(n; \mathbf{F}) := \{W \in \text{Mat}(n; \mathbf{F}); I - \overline{W'}W \in \text{Pos}(n; \mathbf{F})\}.$$

The generalized Cayley transformation yields that the maps

$$\begin{aligned} \mathcal{H}(n; \mathbf{F}) &\rightarrow \mathcal{D}(n; \mathbf{F}), & Z &\mapsto (Z - I)(Z + I)^{-1}, \\ \mathcal{D}(n; \mathbf{F}) &\rightarrow \mathcal{H}(n; \mathbf{F}), & W &\mapsto (W + I)(-W + I)^{-1}, \end{aligned}$$

are bijective and inverse to each other.

As a consequence one obtains a good description of the stabilizer

$$\text{Stab}(Z) := \{M \in \text{MSp}(n; \mathbf{F}); M\langle Z \rangle = Z\}, \quad Z \in \mathcal{H}(n; \mathbf{F}).$$

We need the unitary group

$$\mathcal{U}(n; \mathbf{F}) := \{U \in \text{Mat}(n; \mathbf{F}); \bar{U}'U = U\bar{U}' = I\}.$$

Then an explicit calculation yields

PROPOSITION 1.6.

$$\begin{aligned} \text{Stab}(I) &= \text{MSp}(n; \mathbf{F}) \cap \mathcal{U}(2n; \mathbf{F}) \\ &= \left\{ \begin{pmatrix} A & B \\ B & A \end{pmatrix}; A, B \in \text{Mat}(n; \mathbf{F}), A\bar{B}' + B\bar{A}' = 0, A\bar{A}' + B\bar{B}' = I \right\} \\ &= \left\{ \frac{1}{2} \begin{pmatrix} I & I \\ -I & I \end{pmatrix} \begin{pmatrix} U & 0 \\ 0 & V \end{pmatrix} \begin{pmatrix} I & -I \\ I & I \end{pmatrix}; U, V \in \mathcal{U}(n; \mathbf{F}) \right\}. \end{aligned}$$

REMARK 1.7. Consider the three-dimensional hyperbolic space

$$\mathcal{H} = \left\{ z = \sum_{j=1}^3 z_j e_j; z_j \in \mathbf{R}, z_3 > 0 \right\}$$

investigated in [6]. Clearly \mathcal{H} becomes a real submanifold of

$$e_3 \cdot \mathcal{H}(1; \mathbf{H}) = \left\{ z = \sum_{j=1}^4 z_j e_j; z_j \in \mathbf{R}, z_3 > 0 \right\}.$$

In view of (0.3) one easily verifies that the group

$$\Sigma = \begin{pmatrix} e_3 & 0 \\ 0 & 1 \end{pmatrix} \text{MSp}(1; \mathbf{H}) \begin{pmatrix} e_3 & 0 \\ 0 & 1 \end{pmatrix}^{-1}$$

contains $\text{SL}(2; \mathbf{C})$ as a subgroup. Now one can show that

$$\{M \in \Sigma; M\langle \mathcal{H} \rangle = \mathcal{H}\} = \text{SL}(2; \mathbf{C}) \cup (e_3 I) \cdot \text{SL}(2; \mathbf{C}).$$

The right-hand side proves to be a group by virtue of $(e_3 I) \cdot M \cdot (e_3 I)^{-1} = \bar{M}$ for $M \in \text{Mat}(2; \mathbf{C})$. Moreover, note that $z = z_1 e_1 + z_2 e_2 + z_3 e_3 \in \mathcal{H}$ implies

$$(e_3 I)\langle z \rangle = z_1 e_1 - z_2 e_2 + z_3 e_3.$$

2. The half-space as a symmetric space. One can proceed in the same way, as C. L. Siegel [29] did in the classical situation, in order to turn the half-space into a symmetric space.

Given $Z, W \in \text{Mat}(n; \mathbf{F})$, $Z = (z_{kl})$, $z_{kl} = \sum_{j=1}^r z_{kl}^{(j)} e_j$, $z_{kl}^{(j)} \in \mathbf{R}$, set $\tau(Z, W) := \frac{1}{2} \text{trace}(Z\overline{W}' + W\overline{Z}')$ and let dZ denote the matrix of differentials

$$dZ = \left(\sum_{j=1}^r dz_{kl}^{(j)} e_j \right)_{1 \leq k, l \leq n}.$$

Now consider the quadratic differential form

$$ds^2 := \tau(Y^{-1}dZY^{-1}, dZ),$$

whenever $Z = X + Y \in \mathcal{H}(n; \mathbf{F})$. The case $\mathbf{F} = \mathbf{C}$ of the following assertion is due to H. Braun [3].

LEMMA 2.1. *The quadratic differential form ds^2 is positive definite in $\mathcal{H}(n; \mathbf{F})$ and invariant under the maps $Z \mapsto M\langle Z \rangle$, $M \in \text{MSp}(n; \mathbf{F})$, as well as $Z \mapsto \overline{Z}'$.*

Proof. $\tau(A, B) = \tau(\overline{A}', \overline{B}')$ yields the invariance under $Z \mapsto \overline{Z}'$. Let $M \in \text{MSp}(n; \mathbf{F})$, $Z \in \mathcal{H}(n; \mathbf{F})$ and set $Z_1 = M\langle Z \rangle$. Then (1.1) and Proposition 1.4 lead to

$$dZ_1 = \overline{\tilde{M}\{\overline{Z}'\}'}^{-1} dZ(M\{Z\})^{-1}.$$

Next $Y_1 = (M\{Z\})Y^{-1}\overline{M\{Z\}'} = (\tilde{M}\{\overline{Z}'\})Y^{-1}\overline{\tilde{M}\{\overline{Z}'\}'}$ follows from Theorem 1.3 and Proposition 1.4. Finally, the use of [16], IV.1.1, yields

$$\tau(Y_1^{-1}dZ_1Y_1^{-1}, dZ_1) = \tau(Y^{-1}dZY^{-1}, dZ).$$

ds^2 is obviously positive definite in the point $Z = I$. Since $\text{MSp}(n; \mathbf{F})$ acts transitively, the assertion follows. □

In Helgason's notation [8] we obtain

THEOREM 2.2. *$\mathcal{H}(n; \mathbf{F})$ endowed with the metric ds^2 is a Riemannian globally symmetric space of the noncompact type, which is irreducible except for the cases $\mathbf{F} = \mathbf{R}$, $n = 1, 2$.*

Proof. The map $Z \mapsto Q\langle Z \rangle = Z^{-1}$ becomes an involutive isometry, which possesses I as an isolated fixed point.

With the aid of Proposition 1.6 we determine the associated Lie algebras, namely

$$\begin{aligned} \text{Lie MSp}(n; \mathbf{F}) &= \{M \in \text{Mat}(2n; \mathbf{F}); \overline{M}'Q + QM = 0\} \\ &= \left\{ \begin{pmatrix} A & B \\ C & -A' \end{pmatrix}; A \in \text{Mat}(n; \mathbf{F}), B, C \in \text{Alt}(n; \mathbf{F}) \right\}, \end{aligned}$$

$$\text{Lie Stab}(I) = \text{Lie MSp}(n; \mathbf{F}) \cap \text{Alt}(2n; \mathbf{F}).$$

Now one easily checks

$$\begin{aligned} \begin{pmatrix} I & I \\ -I & I \end{pmatrix} \text{Lie MSp}(n; \mathbf{F}) \begin{pmatrix} I & I \\ -I & I \end{pmatrix}^{-1} &= \begin{cases} \mathfrak{so}(n, n) & \text{if } \mathbf{F} = \mathbf{R}, \\ \mathfrak{u}(n, n) & \text{if } \mathbf{F} = \mathbf{C}, \end{cases} \\ \begin{pmatrix} I & I \\ -I & I \end{pmatrix} \text{Lie Stab}(I) \begin{pmatrix} I & I \\ -I & I \end{pmatrix}^{-1} &= \begin{cases} \mathfrak{so}(n) \times \mathfrak{so}(n) & \text{if } \mathbf{F} = \mathbf{R}, \\ \mathfrak{u}(n) \times \mathfrak{u}(n) & \text{if } \mathbf{F} = \mathbf{C}, \end{cases} \end{aligned}$$

(cf. [8], p. 341). In the case $\mathbf{F} = \mathbf{H}$ a similar map yields an isomorphism between $\text{Lie MSp}(n; \mathbf{H})$ and $\mathfrak{sp}(n, n)$ as well as between $\text{Lie Stab}(I)$ and $\mathfrak{sp}(n) \times \mathfrak{sp}(n)$. Now the assertion follows from Helgason's classification (cf. [8], IX, §4). \square

REMARK 2.3. (a) $\mathcal{H}(n; \mathbf{F})$ corresponds to BDI for $\mathbf{F} = \mathbf{R}$, to AIII for $\mathbf{F} = \mathbf{C}$ and to CII for $\mathbf{F} = \mathbf{H}$ in Helgason's classification (cf. [8], p. 354), where in every case $p = q = n$. Note that the spaces $\mathcal{H}(n; \mathbf{R})$, $n \neq 2$, and $\mathcal{H}(n; \mathbf{H})$, $n \geq 1$, fail to be Hermitian (cf. [8], p. 354).

(b) In view of [8], p. 353, (x), the space $\mathcal{H}(2; \mathbf{R})$ is isomorphic to the direct product of two copies of the upper half-plane $\mathcal{H} = \{z = x + iy \in \mathbf{C}; y > 0\}$ in \mathbf{C} . Each $Z \in \mathcal{H}(2; \mathbf{R})$ is uniquely representable as

$$Z = xJ + Y = \begin{pmatrix} y_1 & y + x \\ y - x & y_2 \end{pmatrix}.$$

Now define the map

$$\chi_2: \mathcal{H}(2; \mathbf{R}) \rightarrow \mathcal{H} \times \mathcal{H}, \quad Z \mapsto (x + i\sqrt{\det Y}, \frac{1}{y_1}(-y + i\sqrt{\det Y})).$$

Clearly χ_2 becomes a bijection. If $\chi_2(Z) = (z, w)$ and $U \in \text{GL}(2; \mathbf{R})$ one easily verifies

$$\begin{aligned} \chi_2(Z + J) &= (z + 1, w), \\ \chi_2(U'ZU) &= \begin{cases} (\det U \cdot z, U^{-1}\langle w \rangle) & \text{if } \det U > 0, \\ (\det U \cdot \bar{z}, U^{-1}\langle \bar{w} \rangle) & \text{if } \det U < 0, \end{cases} \\ \chi_2(Z^{-1}) &= \left(-\frac{1}{z}, -\frac{1}{w}\right), \\ \chi_2((Q \times I)\langle Z \rangle) &= (w, z), \quad \text{where } Q = Q^{(2)}, \quad I = I^{(2)}. \end{aligned}$$

(c) In view of [8], p. 352, (iv), the space $\mathcal{H}(3; \mathbf{R})$ is isomorphic to the space $\text{SPos}(4; \mathbf{R}) = \text{Pos}(4; \mathbf{R}) \cap \text{SL}(4; \mathbf{R})$ (cf. [32]). Given $x = (x_1, x_2, x_3)' \in \mathbf{R}^3$ we define

$$\text{ad } x = \begin{pmatrix} 0 & -x_3 & x_2 \\ x_3 & 0 & -x_1 \\ -x_2 & x_1 & 0 \end{pmatrix} \in \text{Alt}(3; \mathbf{R}),$$

which comes from the vector product (cf. [15], p. 205). Now set

$$\chi_3: \mathcal{H}(3; \mathbf{R}) \rightarrow \text{SPos}(4; \mathbf{R}),$$

$$\text{ad } x + Y \mapsto (\det Y)^{-1/2} \begin{pmatrix} Y & 0 \\ 0 & \det Y \end{pmatrix} \left[\begin{pmatrix} I & x \\ 0 & 1 \end{pmatrix} \right].$$

Given $s \in \mathbf{R}^3$, $U \in \text{GL}(3; \mathbf{R})$ one easily verifies

$$\chi_3(Z + \text{ad } s) = \chi_3(Z) \left[\begin{pmatrix} I & s \\ 0 & 1 \end{pmatrix} \right],$$

$$\chi_3(U'ZU) = \chi_3(Z)[U^*], \quad \text{where } U^* = |\det U|^{-1/2} \begin{pmatrix} U & 0 \\ 0 & \det U \end{pmatrix},$$

$$\chi_3(Z^{-1}) = (\chi_3(Z))^{-1}.$$

Now we are going to describe the associated invariant volume element and the Laplace-Beltrami-operator, which was determined by H. Maaß [21] in the case of the Siegel half-space. Therefore define the vector

$$d\mathfrak{z} = (dz_{11}^{(1)}, \dots, dz_{11}^{(r)}, dz_{21}^{(1)}, \dots, dz_{21}^{(r)}, dz_{22}^{(1)}, \dots, dz_{nn}^{(r)})'$$

of the length rn^2 . Given $Y \in \text{Pos}(n; \mathbf{F})$ there exists $S_Y \in \text{Pos}(rn^2; \mathbf{R})$ satisfying

$$(2.1) \quad ds^2 = \tau(Y^{-1}dZY^{-1}, dZ) = S_Y[d\mathfrak{z}]$$

in view of Lemma 2.1.

PROPOSITION 2.4. *The volume element*

$$dv = (\det Y)^{-rn} \prod_{k=1}^n \prod_{l=1}^n \prod_{j=1}^r dz_{kl}^{(j)}$$

of $\mathcal{H}(n; \mathbf{F})$ is invariant under the modified symplectic transformations $Z \mapsto M\langle Z \rangle$, $M \in \text{MSp}(n; \mathbf{F})$, as well as $Z \mapsto \bar{Z}'$.

Proof. Define $d := \det S_Y$; then $dv = d^{1/2} \prod_{k,l,j} dz_{kl}^{(j)}$ has the desired invariance property due to Lemma 2.1. One calculates $d = (\det Y)^{-2rn}$. \square

We compute the effect of differential operators on determinants.

PROPOSITION 2.5. *Let $Y \in \text{Pos}(n; \mathbf{F})$, $Y^{-1} = (\tilde{y}_{kl})$ and $s \in \mathbf{C}$. Given $1 \leq k, l \leq n$, $1 \leq j \leq r$, one has*

$$\frac{\partial}{\partial z_{kl}^{(j)}} (\det Y)^s = s (\det Y)^s \tilde{y}_{kl}^{(j)}.$$

Proof. Due to the method of completing squares (cf. [16], I.3.2), we may confine ourselves to the case $n = 2$. Then an explicit calculation completes the proof. □

In order to get an explicit description of the Laplace-Beltrami-operator, let $\partial/\partial Z$ denote the matrix differential operator

$$\frac{\partial}{\partial Z} = \left(\sum_{j=1}^r \frac{\partial}{\partial z_{kl}^{(j)}} e_j \right)_{1 \leq k, l \leq n}.$$

THEOREM 2.6. *The Laplace-Beltrami-operator Δ is invariant under the maps $Z \mapsto M\langle Z \rangle$, $M \in \text{MSp}(n; \mathbf{F})$, as well as $Z \mapsto \bar{Z}$ and is given by*

$$\Delta = \tau \left(Y \frac{\partial}{\partial Z} Y, \frac{\partial}{\partial Z} \right) - \left(\frac{1}{2} r(n+1) - 1 \right) \tau \left(Y, \frac{\partial}{\partial Z} \right).$$

Proof. The invariance follows from Lemma 2.1 and [8], X.2.1. Using (2.1) an elementary but lengthy calculation yields $(S_Y)^{-1} = S_{Y^{-1}}$. Then the definition of Δ leads to

$$\Delta = \sum_{\substack{1 \leq j, k, l, m \leq n \\ 1 \leq \nu, \mu \leq r}} (\det Y)^m \frac{\partial}{\partial z_{kl}^{(\nu)}} \text{Re}(y_{jk} e_\nu y_{lm} \bar{e}_\mu) (\det Y)^{-m} \frac{\partial}{\partial z_{jm}^{(\mu)}}.$$

Now one can use Proposition 2.5 and another lengthy calculation shows that Δ has the form given above. □

Theorem 2.6 combined with Proposition 2.5 yields

COROLLARY 2.7. *Let $Z \in \mathcal{H}(n; \mathbf{F})$, $M \in \text{MSp}(n; \mathbf{F})$ and $s \in \mathbf{C}$. Then one has*

$$\Delta(\det Y_M)^s = ns \left(s + 1 - \frac{1}{2} r(n+1) \right) (\det Y_M)^s.$$

REMARK 2.8. One can proceed in the same way as C. L. Siegel [29], resp. H. Klingen [12], in order to derive normal forms for pairs of points under modified symplectic transformations. As a result one

obtains that the geodesics in $\mathcal{H}(n; \mathbf{F})$ are given by the images of the curves

$$Z(u) = \begin{pmatrix} e^{up_1} & & 0 \\ & \ddots & \\ 0 & & e^{up_n} \end{pmatrix}$$

under the transformations $Z \mapsto M\langle Z \rangle$, $M \in \text{MSp}(n; \mathbf{F})$. Here p_1, \dots, p_n satisfy $0 \leq p_1 \leq \dots \leq p_n$ as well as $\sum_{k=1}^n p_k^2 = 1$ and u runs through the interval $[0, \rho]$, where ρ denotes the geodesic distance of the points. On the other hand the geodesics in $\mathcal{H}(n; \mathbf{F})$ coincide with the solutions of the differential equation

$$\ddot{Z} = \dot{Z}Y^{-1}\dot{Z}.$$

Thus in the relations

$$\mathcal{H}(n; \mathbf{R}) \subset \mathcal{H}(n; \mathbf{C}) \subset \mathcal{H}(n; \mathbf{H})$$

every half-space becomes a totally geodesic submanifold of the following one.

3. The modified modular group. We proceed in the same way as in [16]. Thus we obtain integral elements by the choice of a special order $\mathcal{O} = \mathcal{O}(\mathbf{F})$, namely

$$\mathcal{O}(\mathbf{R}) = \mathbf{Z}, \quad \mathcal{O}(\mathbf{C}) = \mathbf{Z}e_1 = \mathbf{Z}e_2, \quad \mathcal{O}(\mathbf{H}) = \mathbf{Z}e_0 + \mathbf{Z}e_1 + \mathbf{Z}e_2 + \mathbf{Z}e_3,$$

where $e_0 = \frac{1}{2}(e_1 + e_2 + e_3 + e_4)$. Here $\mathcal{O}(\mathbf{C})$ of course denotes the Gaussian integers and $\mathcal{O}(\mathbf{H})$ the quaternions of Hurwitz (cf. [9] or [5], §91). Then the set of integral modified symplectic matrices

$$\Gamma(n; \mathcal{O}) := \text{MSp}(n; \mathbf{F}) \cap \text{Mat}(2n; \mathcal{O})$$

becomes a subgroup of $\text{MSp}(n; \mathbf{F})$, which acts discontinuously on the half-space $\mathcal{H}(n; \mathbf{F})$.

DEFINITION. $\Gamma(n; \mathcal{O})$ is called the *modified modular group of degree n* .

Clearly, we include the trivial case

$$(3.1) \quad \Gamma(1; \mathbf{Z}) = \{\pm I, \pm Q\}$$

in view of (1.3). In the case $\mathbf{F} = \mathbf{C}$ (0.2) implies that

$$(3.2) \quad \begin{pmatrix} e_2 I & 0 \\ 0 & I \end{pmatrix} \Gamma(n; \mathbf{Z}e_1 + \mathbf{Z}e_2) \begin{pmatrix} e_2 I & 0 \\ 0 & I \end{pmatrix}^{-1}$$

equals the Hermitian modular group with respect to the Gaussian number field (cf. [3]).

Let $\text{Alt}(n; \mathcal{O})$ denote the lattice of all integral skew-Hermitian $n \times n$ matrices. $\text{GL}(n; \mathcal{O})$ stands for the group of units in the ring $\text{Mat}(n; \mathcal{O})$. Thus (1.5) yields

$$(3.3) \quad \Gamma(n; \mathcal{O})_\infty := \text{MSp}(n; \mathbf{F})_\infty \cap \text{Mat}(2n; \mathcal{O}) \\ = \left\{ \begin{pmatrix} \overline{U}' & \overline{U}'S \\ 0 & U^{-1} \end{pmatrix}; U \in \text{GL}(n; \mathcal{O}), S \in \text{Alt}(n; \mathcal{O}) \right\}.$$

Set $N(a) := a\bar{a} \in \mathbf{R}$ for $a \in \mathbf{F}$. Hence one easily verifies the property:

$$(3.4) \quad \text{Given } a \in \text{Alt}(1; \mathbf{F}) \text{ then } g \in \text{Alt}(1; \mathcal{O}) \text{ exists such that} \\ N(a - g) < 1.$$

Hence the Euclidean algorithm is valid in \mathcal{O} as well as in $\text{Alt}(1; \mathcal{O})$. Thus we can derive a result of L. Kronecker [18]—often cited as Witt's Theorem [33]—on the generators of the modified modular group. The proofs in [16], II.2.2 and II.2.3, can be adapted by the use of (1.1) and (3.4) in order to obtain

THEOREM 3.1. *The modified modular group $\Gamma(n; \mathcal{O})$ is generated by the matrices*

$$Q^{(2)} \times I, \quad \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}, \quad S \in \text{Alt}(n; \mathcal{O}), \quad \begin{pmatrix} \overline{U}' & 0 \\ 0 & U^{-1} \end{pmatrix}, \quad U \in \text{GL}(n; \mathcal{O}).$$

The same arguments that were applied in the proof of Lemma 1.1b yield that $\Gamma(n; \mathcal{O})$ can also be generated by the matrices

$$Q, \quad \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}, \quad S \in \text{Alt}(n; \mathcal{O}), \quad \begin{pmatrix} \overline{U}' & 0 \\ 0 & U^{-1} \end{pmatrix}, \quad U \in \text{GL}(n; \mathcal{O}),$$

except for the case $\mathcal{O} = \mathbf{Z}$, n even.

Combining this with (1.8) it becomes clear that the group Δ_n^* considered by H. Maaß in [23] equals $\Gamma(n; \mathbf{Z})$, whenever n is odd, and $\Gamma(n; \mathbf{Z}) \cap \text{SL}(2n; \mathbf{Z})$, whenever n is even.

Now we are going to determine a suitable fundamental domain. Therefore let $\mathcal{E}(n; \mathcal{O})$ denote the fundamental parallelotope of the lattice $\text{Alt}(n; \mathcal{O})$ in $\text{Alt}(n; \mathbf{F})$, which consists of the matrices $X = (x_{kl}) \in \text{Alt}(n; \mathbf{F})$ such that

$$x_{kl} = \sum_{j=1}^r x_{kl}^{(j)} e_j, \quad -\frac{1}{2} \leq x_{kl}^{(j)} \leq \frac{1}{2}, \quad 1 \leq k \leq l \leq n, \quad 1 \leq j \leq r,$$

where $x_{kl}^{(1)} \geq 0$ in the case $\mathbf{F} = \mathbf{H}$. Moreover, $\mathcal{R}(n; \mathbf{F})$ stands for the set of reduced matrices in $\text{Pos}(n; \mathbf{F})$ (cf. [16], p. 29). Now let $\mathcal{F}(n; \mathcal{O})$ consist of all matrices $Z = X + Y \in \mathcal{R}(n; \mathbf{F})$, which satisfy

(i) $X \in \mathcal{E}(n; \mathcal{O})$,

(ii) $Y \in \mathcal{R}(n; \mathbf{F})$,

(iii) $|\det M\{Z\}| \geq 1$, i.e. $\det Y_M \leq \det Y$, for all $M \in \Gamma(n; \mathcal{O})$.

Clearly, one has

(3.5) $\mathcal{F}(1; \mathbf{Z}) = \{y \in \mathbf{R}; y \geq 1\}$,

(3.6) $i\mathcal{F}(n; \mathbf{Z}e_1 + \mathbf{Z}e_2) = \mathcal{F}(n; \mathbf{C})$,

where $\mathcal{F}(n; \mathbf{C})$ denotes the fundamental domain in [3] resp. [16], p. 58.

At first we derive some properties of the domain $\mathcal{F}(n; \mathcal{O})$.

PROPOSITION 3.2. *There exists a constant $\rho = \rho(n; \mathbf{F})$ such that $Y \geq \rho I$ holds for all $Z = X + Y \in \mathcal{F}(n; \mathcal{O})$.*

Proof. $1 \leq |\det(Q^{(2)} \times I)\{Z\}|^2 = N(z_{11}) = y_{11}^2 + N(x_{11})$ holds in view of (iii). The definition of $\mathcal{E}(n; \mathcal{O})$ yields $N(x_{11}) \leq \frac{3}{4}$, hence $y_{11} \geq \frac{1}{2}$. Now [16], I.4.7 and I.5.1, combined with (ii) imply $Y \geq \frac{1}{2}\beta I$, where β only depends on n . □

Let dv again denote the invariant volume element (cf. Proposition 2.4). One can apply nearly the same arguments, which were used for the proof of [16], II.3.2, II.3.9, in order to obtain

LEMMA 3.3. (a) $\lambda I \in \mathcal{F}(n; \mathcal{O})$ for all $\lambda \geq 1$.

(b) Given $Z = X + Y \in \mathcal{F}(n; \mathcal{O})$, then $Z_\lambda := X + \lambda Y \in \mathcal{F}(n; \mathcal{O})$ holds for $\lambda \geq 1$.

(c) $\mathcal{F}(n; \mathcal{O})$ is arcwise connected.

(d) $\text{vol}(\mathcal{F}(n; \mathcal{O})) := \int_{\mathcal{F}(n; \mathcal{O})} dv < \infty$ except for $n = 1, \mathcal{O} = \mathbf{Z}$.

Hence the domain $\mathcal{F}(n; \mathcal{O})$ fails to be compact. Given $\alpha > 0$ the subset $\mathcal{E}(n; \mathbf{F})[\alpha]$ of $\text{Pos}(n; \mathbf{F})$ consists of the matrices

$$\begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix} \left[\begin{pmatrix} 1 & & b_{kl} \\ & \ddots & \\ 0 & & 1 \end{pmatrix} \right],$$

where $0 < d_j < \alpha d_{j+1}$ for $1 \leq j < n$ and $N(b_{kl}) < \alpha^2$ for $1 \leq k < l \leq n$ (cf. [16], p. 33). Then we define the Siegel set

$$\mathcal{F}(n; \mathbf{F})[\alpha] := \{Z \in \mathcal{R}(n; \mathbf{F}); N(x_{kl}) < \alpha^2, Y \in \mathcal{E}(n; \mathbf{F})[\alpha], 1 < \alpha y_{11}\},$$

confer [7], p. 90, in the case of the Siegel half-space. Recall the definition of κ from Theorem 1.5 and consider the matrices

$$V_0 = \begin{pmatrix} 0 & & 1 \\ & \ddots & \\ 1 & & 0 \end{pmatrix} \in \mathrm{GL}(n; \mathcal{O}) \quad \text{and} \quad W_0 = \begin{pmatrix} V_0 & 0 \\ 0 & I \end{pmatrix} \in \mathrm{GL}(2n; \mathcal{O}).$$

LEMMA 3.4. (a) *There exists $\alpha = \alpha(n; \mathbf{F}) > 0$ such that*

$$\mathcal{F}(n; \mathcal{O}) \subset \mathcal{S}(n; \mathbf{F})[\alpha].$$

(b) *Given a compact subset \mathcal{E} in $\mathcal{H}(n; \mathbf{F})$, there exists $\beta = \beta(\mathcal{E}) > 0$ satisfying*

$$\mathcal{E} \subset \mathcal{S}(n; \mathbf{F})[\beta].$$

(c) *Given $\gamma > 0$ one can find $\delta > 0$ such that*

$$\kappa(\mathcal{S}(n; \mathbf{F})[\gamma])[W_0] \subset \mathcal{E}(2n; \mathbf{F})[\delta].$$

(d) *Let $\gamma > 0$, then there are only finitely many $M \in \Gamma(n; \mathcal{O})$ satisfying*

$$M\langle \mathcal{S}(n; \mathbf{F})[\gamma] \rangle \cap \mathcal{S}(n; \mathbf{F})[\gamma] \neq \emptyset.$$

Proof. (a) and (b) The proof is settled in analogy with [16], II. 3.6, where Proposition 3.2 is applied.

(c) Proceed in the same way as in [16], II.3.7.

(d) The assertion follows from part (c) combined with [16], I.4.10. \square

We take the definition of a fundamental domain from [16], p. 6.

THEOREM 3.5. *$\mathcal{F}(n; \mathcal{O})$ is a fundamental domain of $\mathcal{H}(n; \mathbf{F})$ with respect to the action of $\Gamma(n; \mathcal{O})$ except for $\mathbf{F} = \mathbf{H}$, $n = 1$. The domain $\mathcal{F}(n; \mathcal{O})$ is arcwise connected and closed in $\mathrm{Mat}(n; \mathbf{F})$. Moreover $\mathrm{vol}(\mathcal{F}(n; \mathcal{O})) < \infty$ holds except for $\mathbf{F} = \mathbf{R}$, $n = 1$.*

Proof. Given $Z \in \mathcal{H}(n; \mathbf{F})$ we can show in the same way as in [16], II.3.3, that there exists $M \in \Gamma(n; \mathcal{O})$ satisfying

$$\det Y_K \leq \det Y_M \quad \text{for all } K \in \Gamma(n; \mathcal{O}).$$

We may replace M by KM , where $K \in \Gamma(n; \mathcal{O})_\infty$, in order to map Z into $\mathcal{F}(n; \mathcal{O})$ by a modified modular transformation.

In view of the definition $\mathcal{F}(n; \mathcal{O})$ is relatively closed in $\mathcal{H}(n; \mathbf{F})$. Now $\mathcal{F}(n; \mathcal{O})$ proves to be closed in $\mathrm{Mat}(n; \mathbf{F})$ according to Proposition 3.2. By virtue of

$$\bigcup_M M\langle \mathcal{F}(n; \mathcal{O}) \rangle = \mathcal{H}(n; \mathbf{F}),$$

where M runs through $\Gamma(n; \mathcal{O})$, clearly $\mathcal{F}(n; \mathcal{O})$ contains interior points.

Let $M \in \Gamma(n; \mathcal{O})$ and $Z \in \mathcal{F}(n; \mathcal{O})$ such that Z and $W := M\langle Z \rangle$ are interior points of $\mathcal{F}(n; \mathcal{O})$. We obtain $(M\langle Z \rangle)^{-1} = M^{-1}\langle W \rangle$ from Theorem 1.3. Thus $|\det M\langle Z \rangle| = |\det M^{-1}\langle W \rangle| = 1$ follows. Since Z and W are interior points, we conclude $C = 0$. Then (3.3) implies

$$W = Z[U] + S$$

for appropriate $U \in \text{GL}(n; \mathcal{O})$ and $S \in \text{Alt}(n; \mathcal{O})$. Since Y is an interior point of $\mathcal{R}(n; \mathbf{F})$, whenever $Z = X + Y$, we conclude $U = \varepsilon I$, where ε is a unit in \mathcal{O} and belongs to the center of \mathbf{F} , if $n > 1$. Finally we obtain $S = 0$, because X lies in the open kernel of $\mathcal{E}(n; \mathcal{O})$.

The remaining assertions follow from Lemma 3.3 and 3.4. □

In the case $\mathbf{F} = \mathbf{H}$, $n = 1$ we observe that the matrices $M = \varepsilon I^{(2)}$, where $\varepsilon \in \mathcal{E} = \{g \in \mathcal{O}; N(g) = 1\}$, induce the identity map on $\text{Pos}(1; \mathbf{H}) = \mathbf{R}^+$. Using [16], I.1.3, and the considerations above, we obtain a fundamental domain \mathcal{F}^* of $\mathcal{H}(1; \mathbf{H})$ with respect to the action of $\Gamma(1; \mathcal{O})$, where

$$\mathcal{F}^* = \left\{ z = x + y \in \mathcal{F}(1; \mathcal{O}); x = \sum_{j=2}^4 x_j e_j, x_2 \geq x_3 \geq 0, x_2 \geq |x_4| \right\}.$$

But we can simplify the condition (iii) and gain

COROLLARY 3.6. *A fundamental domain of $\mathcal{H}(1; \mathbf{H})$ with respect to the action of $\Gamma(1; \mathcal{O})$ is given by*

$$\mathcal{F}^* = \left\{ z = \sum_{j=1}^4 z_j e_j \in \mathbf{H}; z_1 > 0, \frac{1}{2} \geq z_2 \geq z_3 \geq 0, z_2 \geq |z_4|, N(z) \geq 1 \right\}.$$

Moreover, besides the obvious cases $n = 1$, $\mathbf{F} = \mathbf{R}, \mathbf{C}$ (cf. (3.5), (3.6)) the domain $\mathcal{F}(2; \mathbf{Z})$ can be described easily.

EXAMPLE 3.7. The fundamental domain $\mathcal{F}(2; \mathbf{Z})$ consists of the matrices

$$Z = \begin{pmatrix} y_1 & y + x \\ y - x & y_2 \end{pmatrix} \in \text{Mat}(2; \mathbf{R}),$$

where

$$1 \leq y_1 \leq y_2, \quad 0 \leq 2y \leq y_1, \quad -\frac{1}{2} \leq x \leq \frac{1}{2},$$

$$\det Z = y_1 y_2 - y^2 + x^2 \geq 1.$$

REMARK 3.8. Let us replace $\Gamma(n; \mathbf{Z})$ by $\Gamma^*(n; \mathbf{Z}) := \Gamma(n; \mathbf{Z}) \cap \mathrm{SL}(2n; \mathbf{Z})$. In the corresponding fundamental domain $\mathcal{F}^*(n; \mathbf{Z})$ the condition (iii) is only valid for $M \in \Gamma^*(n; \mathbf{Z})$. However $\mathcal{F}^*(n; \mathbf{Z})$ possesses more than one cusp. As an example observe that

$$\mathcal{F}^*(1; \mathbf{Z}) = \mathcal{H}(1; \mathbf{R}) = \mathbf{R}^+,$$

$$\mathcal{F}^*(2; \mathbf{Z}) = \left\{ Z = \begin{pmatrix} y_1 & y+x \\ y-x & y_2 \end{pmatrix} \in \mathcal{H}(2; \mathbf{R}); \right. \\ \left. \begin{array}{l} 0 \leq 2y \leq y_1 \leq y_2, -\frac{1}{2} \leq x \leq \frac{1}{2}, \\ \det Z \geq 1 \end{array} \right\}.$$

In general the diagonal matrix $[\frac{1}{\lambda}, \lambda, \dots, \lambda]$ belongs to $\mathcal{F}^*(n; \mathbf{Z})$, whenever $\lambda \geq 1$.

In this special case we can compute the volume of the fundamental domain explicitly.

PROPOSITION 3.9. $\mathrm{vol}(\mathcal{F}(2; \mathbf{Z})) = \pi^2/9$.

Proof. In view of Example 3.7 and Remark 3.8 one has

$$\mathrm{vol}(\mathcal{F}(2; \mathbf{Z})) = \frac{1}{4} \int_{\mathcal{D}} d\nu,$$

where

$$\mathcal{D} = \left\{ Z = \begin{pmatrix} y_1 & y+x \\ y-x & y_2 \end{pmatrix} \in \mathcal{H}(2; \mathbf{R}); \right. \\ \left. 0 \leq |2y| \leq y_1 \leq y_2, |x| \leq \frac{1}{2}, \det Z \geq 1 \right\}.$$

Remark 2.3 yields

$$\chi_2(\mathcal{D}) = \mathcal{F} \times \mathcal{F}, \quad \mathcal{F} = \{x + iy \in \mathbf{C}; y > 0, |x| \leq \frac{1}{2}, |z| \geq 1\}.$$

Change of variables leads to

$$\mathrm{vol}(\mathcal{F}(2; \mathbf{Z})) = \left(\int_{\mathcal{F}} y^{-2} dx dy \right)^2 = \frac{\pi^2}{9}. \quad \square$$

4. Eisenstein-series. We are going to define non-analytic Eisenstein-series in analogy with the classical case, cf. [19], [20]. Special attention is devoted to the behavior of convergence, which is investigated after the model of Eisenstein-series on the Siegel half-space.

DEFINITION. Given $\varepsilon > 0$ the set

$$\mathcal{V}_\varepsilon(n; \mathbf{F}) := \{Z = X + Y \in \mathcal{H}(n; \mathbf{F}); Y \geq \varepsilon I, \varepsilon^{-2}I \geq \overline{X}'X\}$$

is called a *vertical strip of height ε* .

Using (1.9), (1.10), (1.12) as well as the definition of a vertical strip $\mathcal{V}_\varepsilon(n; \mathbf{F})$ in $H(n; \mathbf{F})$ (cf. [16], p. 148), we obtain

$$(4.1) \quad \mathcal{V}_\varepsilon(n; \mathbf{R}) \subset \mathcal{V}_\varepsilon(n; \mathbf{C}) \subset \mathcal{V}_\varepsilon(n; \mathbf{H}),$$

$$(4.2) \quad i\mathcal{V}_\varepsilon(n; \mathbf{C}) = \mathcal{V}_\varepsilon(n; \mathbf{C}),$$

$$(4.3) \quad \{i\check{Z}; Z \in \mathcal{V}_\varepsilon(n; \mathbf{H})\} \subset \mathcal{V}_\varepsilon(2n; \mathbf{C}).$$

PROPOSITION 4.1. *Given $\varepsilon > 0$ there exists $c = c(n; \varepsilon) > 0$ such that*

$$|\det M\{Z\}| \geq c |\det M\{I\}|$$

holds for all $Z \in \mathcal{V}_\varepsilon(n; \mathbf{F})$ and $M \in \text{MSp}(n; \mathbf{F})$.

Proof. In view of (4.1) and (1.12) we may restrict to the case $\mathbf{F} = \mathbf{H}$. Now apply (4.3), (1.11) and [16], V.2.5. □

Analogous arguments using [16], V.2.7, and Theorem 1.3 yield

PROPOSITION 4.2. *Given a compact subset \mathcal{C} in $\mathcal{H}(n; \mathbf{F})$ there exists a constant $c = c(\mathcal{C})$ such that all $Z = X + Y, W = U + V \in \mathcal{C}$ and $M \in \text{MSp}(n; \mathbf{F})$ satisfy*

$$\det Y_M \leq c \cdot \det V_M.$$

We use the abbreviations

$$\Gamma_n := \Gamma(n; \mathcal{O}) \quad \text{and} \quad \Gamma_n^\infty := \Gamma(n; \mathcal{O})_\infty.$$

LEMMA 4.3. *Let $\varepsilon \in \mathbf{R}, \varepsilon > 0$ and $k \in \mathbf{R}, k > r(n + 1) - 2$. Then the series*

$$\sum_{M: \Gamma_n^\infty \setminus \Gamma_n} |\det M\{Z\}|^{-k}$$

converges uniformly for $Z \in \mathcal{V}_\varepsilon(n; \mathbf{F})$.

Proof. In view of (3.3) the definition does not depend on the choice of the representatives. Hence let \mathcal{R} denote a fixed set of representatives. According to Proposition 4.1 the series is uniformly majorized by

$$\sum_{M \in \mathcal{R}} |\det M\{I\}|^{-k}.$$

Observe that $|\det M\{I\}|^{-2} = \det Y$, whenever $M\langle I \rangle = X + Y$. Let dv denote the invariant volume element quoted in Proposition 2.4. Moreover set

$$\mathcal{E} = \{Z = X + Y \in \mathcal{F}(n; \mathcal{O}); \det Y \leq c\}$$

for sufficiently large $c > 1$. Then \mathcal{E} becomes a compact subset with positive volume. Hence the series is majorized by

$$G_k := \sum_{M \in \mathcal{R}} \int_{M\langle \mathcal{E} \rangle} (\det Y)^{k/2} dv$$

in view of Proposition 4.2. Let l denote the number of neighbors of $\mathcal{F}(n; \mathcal{O})$ and set $\mathcal{U} = \bigcup_{M \in \mathcal{R}} M\langle \mathcal{E} \rangle$. Thus we obtain

$$G_k \leq l \int_{\mathcal{U}} (\det Y)^{k/2} dv.$$

Now \mathcal{U} is contained in a fundamental domain of $\mathcal{H}(n; \mathbf{F})$ with respect to the action of $\Gamma(n; \mathcal{O})_\infty$. Every $Z = X + Y \in \mathcal{U}$ satisfies $\det Y \leq c$ in virtue of $\mathcal{E} \subset \mathcal{F}(n; \mathcal{O})$. According to (3.3) it suffices to check the convergence of the integral

$$\int_{\substack{X \in \mathcal{E}(n; \mathcal{O}), Y \in \mathcal{H}(n; \mathbf{F}) \\ \det Y \leq c}} (\det Y)^{k/2} dv.$$

In view of $dv = 2^{rn(n-1)/2} (\det Y)^{-rn} dX dY$ it suffices to estimate the integral

$$\int_{Y \in \mathcal{H}(n; \mathbf{F}), \det Y \leq c} (\det Y)^{k/2 - rn} dY.$$

According to [16], I.5.10, this integral exists, whenever $k > r(n + 1) - 2$. □

Thus we can easily derive

THEOREM 4.4. *The series*

$$E_n^{\mathbf{F}}(Z, s) := \sum_{M: \Gamma_n^\infty \setminus \Gamma_n} (\det Y_M)^s$$

converges absolutely and uniformly, whenever Z belongs to a compact subset of $\mathcal{H}(n; \mathbf{F})$ and $s \in \mathbf{C}$ satisfies $\operatorname{Re}(s) \geq k$, $k > \frac{1}{2}r(n + 1) - 1$. Given $Z \in \mathcal{H}(n; \mathbf{F})$ the function

$$\left\{ s \in \mathbf{C}; \operatorname{Re}(s) > \frac{1}{2}r(n + 1) - 1 \right\} \rightarrow \mathbf{C}, \quad s \mapsto E_n^{\mathbf{F}}(Z, s),$$

becomes holomorphic. Let $s \in \mathbf{C}$, $\operatorname{Re}(s) > \frac{1}{2}r(n+1) - 1$, be fixed. Then

$$(4.4) \quad E_n^{\mathbf{F}}(M\langle Z \rangle, s) = E_n^{\mathbf{F}}(\overline{Z}', s) = E_n^{\mathbf{F}}(Z, s)$$

holds for all $Z \in \mathcal{H}(n; \mathbf{F})$ and $M \in \Gamma(n; \mathcal{O})$. Given $\varepsilon > 0$ there exists $c > 0$ such that

$$(4.5) \quad |E_n^{\mathbf{F}}(Z, s)| \leq c(\det Y)^{\operatorname{Re}(s)}$$

holds for all $Z \in \mathcal{H}(n; \mathbf{F})$ satisfying $Y \geq \varepsilon I$.

Proof. The definition does not depend on the choice of the representatives in view of (3.3). Using $\det Y_M = (\det Y) \cdot |\det M\{Z\}|^{-2}$ the properties of convergence follow from the previous lemma.

The uniform convergence implies that the function $s \mapsto E_n^{\mathbf{F}}(Z, s)$ becomes holomorphic. If K then also KM , where $M \in \Gamma(n; \mathcal{O})$, resp. \check{K} (cf. Proposition 1.4), run through sets of representatives of $\Gamma_n^\infty \backslash \Gamma_n$. Hence (4.4) follows by a rearrangement. In order to prove (4.5), we may assume $Z \in \mathcal{V}_{\varepsilon}^{\mathcal{O}}(n; \mathbf{F})$ in virtue of $E_n^{\mathbf{F}}(Z + S, s) = E_n^{\mathbf{F}}(Z, s)$ for $S \in \operatorname{Alt}(n; \mathcal{O})$. Then Lemma 4.3 completes the proof. \square

DEFINITION. $E_n^{\mathbf{F}}(Z, s)$ is called *Eisenstein-series in Z and s* .

In virtue of (3.1) the case $\mathbf{F} = \mathbf{R}$, $n = 1$ becomes trivial, namely

$$(4.6) \quad E_1^{\mathbf{R}}(y, s) = y^s + y^{-s}, \quad \text{whenever } y \in \mathcal{H}(1; \mathbf{R}) = \mathbf{R}^+.$$

Consider the classical non-analytic Eisenstein-series

$$(4.7) \quad E(z, s) = \frac{1}{2} \sum_{(c,d) \in \mathbf{Z}^2 \text{ coprime}} \left(\frac{y}{|cz + d|^2} \right)^s,$$

where $s \in \mathbf{C}$, $\operatorname{Re}(s) > 1$, $z = x + iy \in \mathbf{C}$, $y > 0$ (cf. [19], [20]). Then (3.2) and [16], II.2.6, imply

$$(4.8) \quad E_1^{\mathbf{C}}(z, s) = E(iz, s), \quad z \in \mathcal{H}(1; \mathbf{C}).$$

Consider the Laplace-Beltrami-operator Δ in Theorem 2.6. Corollary 2.7 immediately leads to

COROLLARY 4.5. *The Eisenstein-series is an eigenfunction of the Laplace-Beltrami-operator. More precisely, if $s \in \mathbf{C}$, $\operatorname{Re}(s) > \frac{1}{2}r(n+1) - 1$, then*

$$\Delta E_n^{\mathbf{F}}(Z, s) = ns(s - \frac{1}{2}r(n+1) + 1)E_n^{\mathbf{F}}(Z, s).$$

According to the classical procedure by H. Braun [2], we can show that the abscissa of absolute convergence is given by $\text{Re}(s) = \frac{1}{2}r(n + 1) - 1$ except for the trivial case (4.6), of course. Therefore some preliminaries are necessary.

A matrix $G \in \text{Mat}(n, m; \mathcal{O})$, where $m \geq n$ (resp. $n \geq m$), is called *primitive* if there exists $U \in \text{GL}(m; \mathcal{O})$ such that $U = \begin{pmatrix} G \\ * \end{pmatrix}$ (resp. $U \in \text{GL}(n; \mathcal{O})$ such that $U = (G, *)$). Clearly if $m \geq n$

$$(4.9) \quad G \text{ is primitive if and only if } H \in \text{Mat}(m, n; \mathcal{O}) \text{ exists such that } GH = I.$$

In the cases $\mathcal{O} = \mathbf{Z}, \mathbf{Z}e_1 + \mathbf{Z}e_2$ the matrix G proves to be primitive if and only if the n -rowed subdeterminants of G are coprime.

Given $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{MSp}(n; \mathbf{F})$ then (C, D) is called the second row of M .

PROPOSITION 4.6. *The second rows of the matrices in $\Gamma(n; \mathcal{O})$ coincide with the primitive pairs $(C, D) \in \text{Mat}(n, 2n; \mathcal{O})$ satisfying $C\bar{D}' + D\bar{C}' = 0$.*

Proof. If M belongs to $\Gamma(n; \mathcal{O})$, apply (1.1) and use $\Gamma(n; \mathcal{O}) \subset \text{GL}(2n; \mathcal{O})$. Conversely, let such a pair (C, D) be given. According to (4.9) $F, G \in \text{Mat}(n; \mathcal{O})$ exist such that $CF + DG = I$. Now set

$$M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}, \quad A := \bar{G}' - \bar{F}'GC, \quad B := \bar{F}' - \bar{F}'GD$$

and verify $M \in \Gamma(n; \mathcal{O})$. □

Next we consider $\Gamma(1; \mathcal{O}(\mathbf{H}))$ and compute the number of d 's, whenever an odd c is given.

PROPOSITION 4.7. *Let $c \in \mathcal{O}(\mathbf{H})$ such that $N(c)$ is odd and set $l := \max\{m \in \mathbf{N}; \frac{1}{m}c \in \mathcal{O}\}$. Then there exist $l \cdot N(c)$ cosets $d + c\text{Alt}(1; \mathcal{O})$ such that $c\bar{d}' + d\bar{c}' = 0$.*

Proof. We can replace c by εc , $\varepsilon \in \mathcal{E} = \{g \in \mathcal{O}; N(g) = 1\}$, and may assume $c = \sum_{j=1}^4 c_j e_j$, $c_j \in \mathbf{Z}$. Thus $l = \text{g.c.d.}(c_1, c_2, c_3, c_4)$ holds. Let $q = N(c)$, then there are exactly lq^3 tuples $(d_1, d_2, d_3, d_4)'$ in $\mathbf{Z}^4 \text{ mod } q$ such that

$$c_1 d_1 + c_2 d_2 + c_3 d_3 + c_4 d_4 \equiv 0 \pmod{q}$$

holds. Hence there are lq^3 cosets $d_j + q\mathcal{O}$ such that $2\text{Re}(d_j \bar{c}) \equiv 0 \pmod{q}$. Observe that each coset $c\mathcal{O}$ decomposes into q^2 cosets $d + q\mathcal{O}$

(cf. [17]). After renumbering we therefore may assume that

$$\bigcup_{j=1}^{lq} (d_j + c\mathcal{O}) = \bigcup_{j=1}^{lq^3} (d_j + q\mathcal{O}).$$

Since q is odd, we can choose the representatives such that $\text{Re}(d_j \bar{c}) = 0$ holds for $1 \leq j \leq lq$. Hence $d_j + c\text{Alt}(1; \mathcal{O})$, $1 \leq j \leq lq$, are the cosets with the desired property. \square

Next it is necessary to compute an integral. The same arguments, which were used by H. Braun in [2], [3] resp. in [16], V.1.2, yield

LEMMA 4.8. *In the case $\mathbf{F} = \mathbf{R}$ let $n > 1$, $s \in \mathbf{C}$, $\text{Re}(s) > n - 3/2$. If $\mathbf{F} = \mathbf{C}, \mathbf{H}$, let $n \geq 1$, $s \in \mathbf{C}$, $\text{Re}(s) > rn - 1$. Given $Z = X + Y \in \mathcal{H}(n; \mathbf{F})$ the integral*

$$\eta_s(Z) := \int_{\text{Alt}(n; \mathbf{F})} |\det(Z + T)|^{-s} dT$$

exists and satisfies

$$(4.10) \quad \eta_s(Z) = (\det Y)^{r(n+1)/2-1-s} \eta_{s,n}^{\mathbf{F}},$$

where

$$\eta_{s,n}^{\mathbf{F}} = \pi^{rn(n+1)/4-n/2} \prod_{j=1}^n \frac{\Gamma(s + 1 - \frac{1}{2}r(n + j)) \Gamma(\frac{1}{2}(s + 1 - rj))}{\Gamma(s + 1 - rj) \Gamma(\frac{1}{2}(s + r - rj))}.$$

Note that in the case $\mathbf{F} = \mathbf{R}$, i.e. $r = 1$, several factors on the right-hand side can be reduced such that the reduced product even exists for $\text{Re}(s) > n - 3/2$. Here $\Gamma(s)$ denotes the gamma-function, since confusion with the modular group is not possible.

The existence of the integral implies the convergence of a series.

COROLLARY 4.9. *Let $k \in \mathbf{R}$ and $k > n - 3/2, n > 1$ for $\mathbf{F} = \mathbf{R}$ resp. $k > rn - 1, n \geq 1$ for $\mathbf{F} = \mathbf{C}, \mathbf{H}$. Given $\varepsilon > 0$ there exists $c > 0$ such that*

$$c^{-k} \eta_k(Z) \leq \sum_{T \in \text{Alt}(n; \mathcal{O})} |\det(Z + T)|^{-k} \leq c^k \eta_k(Z)$$

holds for all $Z = X + Y \in \mathcal{H}(n; \mathbf{F})$ satisfying $Y \geq \varepsilon I$.

Proof. The assertion follows from an estimation between $|\det(Z + T)|^{-k}$ and

$$\int_{\mathcal{H}(n; \mathcal{O})} |\det(Z + T + H)|^{-k} dH.$$

This estimation can be derived by (1.10), (1.11), (1.12) and [16], V.1.4. □

Now we follow H. Braun [2] in order to determine the abscissa of convergence of the Eisenstein-series. Hereby the result on real Eisenstein-series quoted by H. Maaß [23] can even be strengthened.

THEOREM 4.10. *Let $n > 1$ for $\mathbf{F} = \mathbf{R}$ and $n \geq 1$ for $\mathbf{F} = \mathbf{C}, \mathbf{H}$. Then the Eisenstein-series $E_n^{\mathbf{F}}(\mathbf{Z}, s)$ does not converge absolutely, whenever $\text{Re}(s) = \frac{1}{2}r(n + 1) - 1$.*

Proof. According to Proposition 4.2 it suffices to show that the series

$$E_n^{\mathbf{F}}(I, k) = \sum_{M: \Gamma_n^\infty \backslash \Gamma_n} |\det M\{I\}|^{-2k}, \quad k = \frac{1}{2}r(n + 1) - 1,$$

diverges. Therefore we take second rows (C, D) of matrices $M \in \Gamma(n; \mathcal{O})$ such that the cosets $\Gamma_n^\infty M \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}, S \in \text{Alt}(n; \mathcal{O})$, are mutually disjoint. In view of

$$\begin{aligned} E_n^{\mathbf{F}}(I, k) &\geq \sum_{M \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}} |\det M\{I\}|^{-2k} \\ &= \sum_{C, D, S} |\det C|^{-2k} |\det(I + C^{-1}D + S)|^{-2k} \end{aligned}$$

and Corollary 4.9 it suffices to estimate

$$E_k := \sum_{C, D} |\det C|^{-2k}.$$

In the case $\mathbf{F} = \mathbf{R}, n \geq 2$ choose

$$C = \begin{pmatrix} cI^{(2)} & 0 \\ G & I \end{pmatrix}, \quad D = \begin{pmatrix} dJ & -dJG' \\ 0 & 0 \end{pmatrix}, \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix},$$

where $c \in \mathbf{N}, d, 1 \leq d \leq c$, is relatively prime to c and G runs through a set of representatives of $\text{Mat}(n - 2, 2; \mathbf{Z})/c\text{Mat}(n - 2, 2; \mathbf{Z})$, which consists of c^{2n-4} elements. (C, D) has the desired property. If φ denotes Euler's φ -function, we obtain $k = \frac{1}{2}(n - 1)$ and

$$E_k = \sum_{c, d} c^{-2} = \sum_{c=1}^{\infty} \varphi(c) c^{-2}.$$

But this series diverges.

In the case $\mathbf{F} = \mathbf{C}$ apply [3], Theorem II.

In the case $\mathbf{F} = \mathbf{H}$ let c run through a system of representatives of

$$\mathcal{E} \setminus \{x \in \mathcal{O}; N(x) = p\},$$

where $\mathcal{E} = \{g \in \mathcal{O}; N(g) = 1\}$ and p runs through all odd primes. For every prime p we have $p + 1$ possibilities for c according to [9]. Given c choose d_1, \dots, d_p according to Proposition 4.7 and assume $d_p = 0$. Hence we may suppose $p \nmid N(d_j)$ for $1 \leq j < p$. Set $x = (c_2, \dots, c_n)'$ and let each c_j run through a set of representatives of $\mathcal{O}/\mathcal{O}c$, which consists of $N(c)^2 = p^2$ elements (cf. [17]). Now set

$$C = \begin{pmatrix} c & 0 \\ x & I \end{pmatrix}, \quad D = \begin{pmatrix} d & -d\bar{x}' \\ 0 & 0 \end{pmatrix}, \quad d = d_j, \quad 1 \leq j < p,$$

and observe that (C, D) has the desired property. Now we obtain $k = 2n + 1$ and

$$E_k = \sum_{p > 2 \text{ prime}} (p - 1)(p + 1)p^{-3}.$$

This series diverges. □

Just as in the case of Siegel modular forms we can define a modified ϕ -operator. Given a function $f: \mathcal{H}(n; \mathbf{F}) \rightarrow \mathbf{C}$ and $s \in \mathbf{C}$, we set

$$f|_s\phi: \mathcal{H}(n - 1; \mathbf{F}) \rightarrow \mathbf{C}, \quad Z \mapsto \lim_{\lambda \rightarrow \infty} \lambda^{-s} f \left(\begin{pmatrix} Z & 0 \\ 0 & \lambda \end{pmatrix} \right),$$

if this limit exists. $f|_s\phi$ has to be regarded as a constant, if $n = 1$. Then ϕ is called the modified Siegel ϕ -operator.

Finally we show that the modified Siegel ϕ -operator can be applied to Eisenstein-series just as in the classical case.

THEOREM 4.11. *Given $s \in \mathbf{C}$, $\text{Re}(s) > \frac{1}{2}r(n + 1) - 1$, then one has*

$$\begin{aligned} E_n^{\mathbf{F}}(\cdot, s)|_s\phi &= E_{n-1}^{\mathbf{F}}(\cdot, s) \quad \text{for } n \geq 2, \\ E_1^{\mathbf{F}}(\cdot, s)|_s\phi &= 1. \end{aligned}$$

Proof. According to Lemma 4.3 the limit may be distributed through the infinite series. The case $n = 1$ becomes clear in view of

$$\lim_{\lambda \rightarrow \infty} |M\{\lambda\}|^{-2} = \lim_{\lambda \rightarrow \infty} N(c\lambda + d)^{-1} = \begin{cases} N(d)^{-1} & \text{if } c = 0, \\ 0 & \text{if } c \neq 0. \end{cases}$$

Let $n \geq 2$ and let Γ_n^* denote the set of matrices $M \in \Gamma_n$ such that the elements $m_{2n,j}$, $1 \leq j < 2n$, vanish. Γ_n^* proves to be a subgroup and one easily verifies that the map

$$\Gamma_{n-1}^\infty \setminus \Gamma_{n-1} \rightarrow (\Gamma_n^* \cap \Gamma_n^\infty) \setminus \Gamma_n^*, \quad \Gamma_{n-1}^\infty M \mapsto (\Gamma_n^* \cap \Gamma_n^\infty)(M \times I^{(2)}),$$

becomes a bijection. Let $Z_\lambda := \begin{pmatrix} Z & 0 \\ 0 & \lambda \end{pmatrix}$. Given $M \in \Gamma_n^*$ then $|\det M\{Z_\lambda\}|$ does not depend on λ . Hence we obtain

$$\sum_{M: (\Gamma_n^* \cap \Gamma_n^\infty) \setminus \Gamma_n^*} (\det Y)^s |\det M\{Z_\lambda\}|^{-2s} = E_{n-1}^{\mathbf{F}}(Z, s).$$

Given $M \in \Gamma(n; \mathcal{O})$ such that $\Gamma_n^\infty M \cap \Gamma_n^* = \emptyset$ one checks that $\lim_{\lambda \rightarrow \infty} |M\{Z_\lambda\}| = \infty$ holds. \square

The isomorphisms χ_2 and χ_3 in Remark 2.3 between symmetric spaces correspond to identities between the associated Eisenstein-series. Therefore the Eisenstein-series (4.7) and Eisenstein-series for $GL(4; \mathbf{Z})$, which were investigated by A. Terras [31], appear. Note that the action of $\Gamma(3; \mathbf{Z})_\infty$ corresponds to the action of the parabolic subgroup $P_{3,1}$ of $GL(4; \mathbf{Z})$ via χ_3 . Consider the attached Eisenstein-series of the second type in [31]

$$E_{s,0}(Y) := \sum_{P: \text{Pr}(4,3,\mathbf{Z})/GL(3;\mathbf{Z})} (\det Y[P])^{-s},$$

where $Y \in \text{SPos}(4; \mathbf{R})$ and $\text{Pr}(4, 3, \mathbf{Z})$ denotes the set of primitive 4×3 matrices over \mathbf{Z} . Thus an explicit computation yields

LEMMA 4.12. (a) *Given*

$$Z = xJ + Y = \begin{pmatrix} y_1 & y + x \\ y - x & y_2 \end{pmatrix} \in \mathcal{H}(2; \mathbf{R})$$

and $s \in \mathbf{C}$ with $\text{Re}(s) > \frac{1}{2}$ one has

$$E_2^{\mathbf{R}}(Z, s) = E(x + i\sqrt{\det Y}, 2s) + E\left(\frac{1}{y_1}(-y + i\sqrt{\det Y}), 2s\right).$$

(b) *Given $Z \in \mathcal{H}(3; \mathbf{R})$ and $s \in \mathbf{C}$ with $\text{Re}(s) > 1$ one has*

$$E_3^{\mathbf{R}}(Z, s) = E_{2s,0}(\chi_3(Z)) + E_{2s,0}(\chi_3(Z)^{-1}).$$

5. Fourier-expansion of Eisenstein-series. The Fourier-expansion of non-analytic Eisenstein-series on the Siegel half-space was investigated by H. Maaß [22], §18. G. Shimura [27] dealt with the case $\mathbf{F} = \mathbf{C}$, if we regard (0.2) and (1.9). Some of the following results on real Eisenstein-series were already obtained by H. Maaß [23].

Throughout this paragraph let $s \in \mathbf{C}$ be fixed such that $\text{Re}(s) > \frac{1}{2}r(n+1) - 1$ holds. In order to describe the Fourier-development, we have to determine the dual lattice. Therefore set

$$\mathcal{O}^\#(\mathbf{F}) = \mathcal{O}(\mathbf{F}), \quad \mathbf{F} = \mathbf{R}, \mathbf{C},$$

$$\mathcal{O}^\#(\mathbf{H}) = \mathbf{Z}2e_1 + \mathbf{Z}(e_1 + e_2) + \mathbf{Z}(e_1 + e_3) + \mathbf{Z}(e_1 + e_4)$$

(cf. [16], p. 12). Using the definition of τ in §2 we derive

$$\begin{aligned} \text{Alt}^\tau(n; \mathcal{O}) &:= \{T \in \text{Alt}(n; \mathbf{F}); \tau(T, S) \in \mathbf{Z} \text{ for all } S \in \text{Alt}(n; \mathcal{O})\} \\ &= \{T = (t_{kl}) \in \text{Alt}(n; \mathbf{F}); t_{kk} \in \mathcal{O}, 2t_{kl} \in \mathcal{O}^\# \text{ for } k \neq l\}. \end{aligned}$$

Since the Eisenstein-series is invariant under the transformations $Z \mapsto Z + S, S \in \text{Alt}(n; \mathcal{O})$, we obtain

$$E_n^{\mathbf{F}}(Z, s) = \sum_{T \in \text{Alt}^\tau(n; \mathcal{O})} c(Y; T) e^{2\pi i \tau(X, T)}, \quad Z = X + Y \in \mathcal{X}(n; \mathbf{F}).$$

The use of $E_n^{\mathbf{F}}(Z[U], s) = E_n^{\mathbf{F}}(\overline{Z}, s) = E_n^{\mathbf{F}}(Z, s)$ according to (4.4) as well as the uniqueness of the Fourier-coefficients yield

$$c(Y[U]; T) = c(Y; T[\overline{U}']), \quad c(Y; T) = c(Y; -T)$$

for all $U \in \text{GL}(n; \mathcal{O})$.

It is convenient to decompose the Eisenstein-series into $n + 1$ partial series. Given $0 \leq j \leq n$ we set

$$E_{n,j}^{\mathbf{F}}(Z, s) = \sum_{\substack{M: \Gamma_n^\infty \setminus \Gamma_n \\ \text{rank } C = j}} (\det Y_M)^s.$$

The definition leads to the obvious relations

$$(5.1) \quad E_n^{\mathbf{F}}(Z, s) = \sum_{j=0}^n E_{n,j}^{\mathbf{F}}(Z, s),$$

$$(5.2) \quad E_{n,0}^{\mathbf{F}}(Z, s) = (\det Y)^s.$$

Set $\text{Pr}(n, m; \mathcal{O}) := \{G \in \text{Mat}(n, m; \mathcal{O}); G \text{ primitive}\}$. Following H. Maaß [22], §11, the same arguments yield

LEMMA 5.1. *Given $0 < j < n$ let P run through a set of representatives of $\text{Pr}(n, j; \mathcal{O})/\text{GL}(j; \mathcal{O})$. Each P is completed to a matrix $U = (P, *) \in \text{GL}(n; \mathcal{O})$ in exactly one way. Let M_1 run through the subset of representatives of $\Gamma_j^\infty \setminus \Gamma_j$, where $|\det C_1| \neq 0$. Then $(M_1 \times I) \begin{pmatrix} \overline{U} & 0 \\ 0 & U^{-1} \end{pmatrix}$ runs through the subset of representatives of $\Gamma_n^\infty \setminus \Gamma_n$, where $\text{rank } C = j$.*

Thus we easily compute

COROLLARY 5.2. *Given $0 < j < n$ one has*

$$E_{n,j}^{\mathbf{F}}(Z, s) = \sum_{P: \text{Pr}(n,j;\mathcal{O})/\text{GL}(j;\mathcal{O})} (\det Y)^s (\det Y[P])^{-s} E_{j,j}^{\mathbf{F}}(Z[P], s).$$

Given $S \in \text{Pos}(n; \mathbf{R})$, $0 < j < n$, and $\omega \in \mathbf{C}$ satisfying $\text{Re}(\omega) > \frac{1}{2}n$, we can define the Dirichlet-series

$$\zeta_j(S, \omega) := \sum_{P: \text{Pr}(n, j; \mathbf{Z})/\text{GL}(j; \mathbf{Z})} (\det S[P])^{-\omega}.$$

A related series was investigated by M. Koecher [13]. $\zeta_1(S, \omega)$ proves to be the quotient of the corresponding Epstein-zeta-function over the Riemann-zeta-function $2\zeta(2\omega)$. In view of (5.1), (5.2), (4.6) and Corollary 5.2 we gain

$$(5.3) \quad E_{n,1}^{\mathbf{R}}(Z, s) = (\det Y)^s \zeta_1(Y, 2s),$$

whenever $n \geq 2$.

In view of the corollary the problem is reduced to the investigation of $E_{n,n}^{\mathbf{F}}(Z, s)$. Set $\mathbf{F}_{\mathbf{Q}} = \mathbf{Q}e_1 + \dots + \mathbf{Q}e_r$. The matrices in $\text{Mat}(n; \mathbf{F}_{\mathbf{Q}})$ are called rational.

LEMMA 5.3. *Let $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$ run through the subset of representatives of $\Gamma_n^{\infty} \backslash \Gamma_n$, where $\text{rank } C = n$. Then each $R \in \text{Alt}(n; \mathbf{F}_{\mathbf{Q}})$ is represented in the form $R = C^{-1}D$ exactly once. Moreover*

$$\nu(R) = |\det C|$$

becomes well-defined and satisfies

$$\nu(R + S) = \nu(R) \quad \text{for } S \in \text{Alt}(n; \mathscr{O}).$$

If $\mathscr{O} = \mathbf{Z}$, $\mathbf{Z}e_1 + \mathbf{Z}e_2$, then $\nu(R)$ coincides with the absolute value of the product of the denominators of the reduced elementary divisors of R .

Proof. Given $R \in \text{Alt}(n; \mathbf{F}_{\mathbf{Q}})$ choose $U, V \in \text{GL}(n; \mathscr{O})$ such that

$$URV = [q_1, \dots, q_n], \quad q_j \in \mathbf{F}_{\mathbf{Q}}, \quad q_{j+1} \in \mathscr{O}q_j,$$

according to [16], I.2.3. Each q_j possesses a representation $q_j = c_j^{-1}d_j$, $c_j \neq 0$, $c_j, d_j \in \mathscr{O}$, where c_j and d_j are relatively left-prime. Define $C_0 = [c_1, \dots, c_n]$, $D_0 = [d_1, \dots, d_n]$, then (C_0, D_0) becomes primitive (cf. [16], I.1.11). Hence $(C, D) := (C_0U, D_0V^{-1})$ proves to be primitive and satisfies $\text{rank } C = n$ as well as

$$C^{-1}D = U^{-1}[q_1, \dots, q_n]V^{-1} = R.$$

Now (C, D) turns out to be the second row of a matrix in $\Gamma(n; \mathscr{O})$ according to Proposition 4.6. If $\mathscr{O} = \mathbf{Z}$, $\mathbf{Z}e_1 + \mathbf{Z}e_2$, moreover $|\det C|$ equals the absolute value of the product of the denominators of the reduced elementary divisors of R .

Clearly, the representation $R = C^{-1}D$ and $|\det C|$ do not depend on the choice of the representative in the coset $\Gamma_n^\infty M$ in view of (3.3). Now suppose that $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix}$ and $M_1 = \begin{pmatrix} A_1 & B_1 \\ C_1 & D_1 \end{pmatrix}$ belong to $\Gamma(n; \mathscr{O})$ and fulfill $\text{rank } C = \text{rank } C_1 = n$ as well as $C^{-1}D = C_1^{-1}D_1 = R$. Then $\overline{R}' = -R$ yields $C\overline{D}'_1 + D\overline{C}'_1 = 0$. Hence (1.2) implies $MM_1^{-1} \in \Gamma_n^\infty$, i.e. $\Gamma_n^\infty M = \Gamma_n^\infty M_1$. Replacing M by $M \begin{pmatrix} I & S \\ 0 & I \end{pmatrix}$, $S \in \text{Alt}(n; \mathscr{O})$, yields $\nu(R + S) = \nu(R)$. \square

In the case $\mathscr{O} = \mathbf{Z}$ we obtain information about the elementary divisor normal form of the C -block in a matrix $M \in \Gamma(n; \mathbf{Z})$.

COROLLARY 5.4. *Given $M = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \Gamma(n; \mathbf{Z})$ then the elementary divisor matrix of C has the form*

$$\begin{aligned} [c_1, c_1, c_2, c_2, \dots, c_m, c_m, 0, \dots, 0], & \quad \text{if } \text{rank } C = 2m, \\ [1, c_1, c_1, c_2, c_2, \dots, c_m, c_m, 0, \dots, 0], & \quad \text{if } \text{rank } C = 2m + 1, \end{aligned}$$

where $c_1, \dots, c_m \in \mathbf{N}$ such that $c_j \mid c_{j+1}$.

Proof. We may assume $\text{rank } C = n$. Then a combination of [25], Theorem IV.1, with Lemma 5.3 yields the assertion. \square

Replacing M by a product of M and Q a corresponding result is true for each other block of the matrix $M \in \Gamma(n; \mathbf{Z})$.

Furthermore, Lemma 5.3 immediately yields

$$(5.4) \quad E_{n,n}^{\mathbf{F}}(\mathbf{Z}, s) = (\det Y)^s \sum_{R \in \text{Alt}(n; \mathbf{F}_{\mathbf{Q}})} \nu(R)^{-2s} |\det(\mathbf{Z} + R)|^{-2s}.$$

In view of $\nu(R + S) = \nu(R)$ for $S \in \text{Alt}(n; \mathscr{O})$, the partial series $E_{n,j}^{\mathbf{F}}(\mathbf{Z}, s)$ possesses a Fourier-expansion, too. Let $R \bmod 1$ indicate that R runs through a set of representatives of $\text{Alt}(n; \mathbf{F}_{\mathbf{Q}})/\text{Alt}(n; \mathscr{O})$. Given $T \in \text{Alt}^t(n; \mathscr{O})$ and $Y \in \text{Pos}(n; \mathbf{F})$, we define

$$\begin{aligned} \alpha_s(T) &:= \sum_{R \bmod 1} \nu(R)^{-2s} e^{2\pi i \tau(R, T)}, \\ \beta_s(Y; T) &:= \int_{\text{Alt}(n; \mathbf{F})} |\det(Y + X)|^{-2s} e^{-2\pi i \tau(X, T)} dX. \end{aligned}$$

Given $U \in \text{GL}(n; \mathscr{O})$ we immediately obtain

$$(5.5) \quad \begin{aligned} \alpha_s(T[U]) &= \alpha_s(-T) = \alpha_s(T), \\ \beta_s(Y; T[U]) &= \beta_s(Y[\overline{U}']; T), \quad \beta_s(Y; T) = \beta_s(Y; -T). \end{aligned}$$

Hence Lemma 5.3 and the definition of the Fourier-coefficients imply

LEMMA 5.5.

$$E_{n,n}^{\mathbf{F}}(Z, s) = (\text{vol } \mathcal{E}(n; \mathcal{O}))^{-1} \sum_{T \in \text{Alt}^r(n; \mathcal{O})} (\det Y)^s \alpha_s(T) \beta_s(Y; T) e^{2\pi i \tau(X, T)}.$$

Combining this result with (5.1) and Corollary 5.2, we gain

COROLLARY 5.6.

$$E_n^{\mathbf{F}}(Z, s) = (\det Y)^s + (\det Y)^s \times \sum_{j=1}^n c_j^{-1} \sum_P \sum_{T \in \text{Alt}^r(j; \mathcal{O})} \alpha_s(T) \beta_s(Y[P]; T) e^{2\pi i \tau(X, T[\overline{P}])},$$

where $c_j = \text{vol } \mathcal{E}(j; \mathcal{O})$ and $P: \text{Pr}(n, j; \mathcal{O})/\text{GL}(j; \mathcal{O})$.

As a consequence we observe that in the Fourier-expansion of $E_{n,j}^{\mathbf{F}}(Z, s)$ all the coefficients of matrices $T \in \text{Alt}^r(n; \mathcal{O})$ vanish, whenever $\text{rank } T > j$.

Lemma 4.8 yields

$$(5.6) \quad \beta_s(Y; 0) = (\det Y)^{r(n+1)/2-1-2s} \eta_{2s,n}^{\mathbf{F}}.$$

REMARK 5.7. It is possible to reduce the computation of $\beta_s(Y; T)$ to the case $|\det T| \neq 0$ by aid of (5.5). Therefore let

$$T = \begin{pmatrix} T_1 & 0 \\ 0 & 0 \end{pmatrix} \in \text{Alt}^r(n; \mathcal{O}), \quad Y = \begin{pmatrix} Y_1 & * \\ * & * \end{pmatrix} \in \text{Pos}(n; \mathbf{F}),$$

$$T_1 = T_1^{(m)}, \quad Y_1 = Y_1^{(m)}.$$

Then one obtains

$$\begin{aligned} \beta_s(Y; T) &= \beta_{s-r(n-m)/2}(Y_1; T_1) (\det Y)^{r(n+1)/2-2s} \\ &\cdot (\det Y_1)^{2s+1+r(m-1-2n)/2} \eta_{2s,n-m}^{\mathbf{F}} \pi^{rm(n-m)/2} \\ &\cdot \prod_{j=1}^{n-m} \frac{\Gamma(2s+1-\frac{1}{2}r(n+j))}{\Gamma(2s+1-\frac{1}{2}r(n-m+j))}. \end{aligned}$$

In general the evaluation of the integral $\beta_s(Y; T)$ leads to generalized confluent hypergeometric functions, where the case $\mathbf{F} = \mathbf{C}$ was treated by G. Shimura [26]. On the other hand it might be possible to investigate $\alpha_s(T)$ in analogy with Y. Kitaoka’s procedure [11] in the case of the Siegel half-space. But it seems to be plausible that the Fourier-coefficients of the Eisenstein-series can only be expressed by well-known functions, whenever the degree n is “sufficiently small”.

Therefore let us consider the case $n = 1$. Now $\mathbf{F} = \mathbf{R}$ becomes trivial in view of (4.6). Dealing with $\mathbf{F} = \mathbf{C}$ we observe the connection (4.8) with the classical Eisenstein-series and obtain the Fourier-expansion from [19], p. 46, or [20].

In order to deal with the case $\mathbf{F} = \mathbf{H}$, it is more convenient to introduce the subring $\Lambda := \mathbf{Z}e_1 + \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4$ of $\mathcal{O}(\mathbf{H})$. Given $0 \neq c \in \Lambda$ define the greatest rational divisor of c in Λ by

$$\rho(c) := \max\{l \in \mathbf{N}; l^{-1}c \in \Lambda\}$$

and set $\rho(0) := 0$. Note that $\text{Alt}(1; \mathcal{O}) = \text{Alt}^\tau(1; \mathcal{O}) = \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4 \subset \Lambda$.

Given $S \in \text{Pos}(n; \mathbf{R})$ and $s \in \mathbf{C}$ with $\text{Re}(s) > \frac{1}{2}n$, the Epstein-zeta-function associated with S is defined by

$$\zeta(S; s) := \sum_{0 \neq g \in \mathbf{Z}^n} (S[g])^{-s}.$$

Especially one has for $I = I^{(4)}$ and $s \in \mathbf{C}$ with $\text{Re}(s) > 2$

$$\zeta(I; s) = \sum_{0 \neq c \in \Lambda} N(c)^{-s} = 8(1 - 2^{2-2s})\zeta(s)\zeta(s - 1),$$

where ζ denotes the Riemann-zeta-function. Given $t, t^* \in \text{Alt}(1; \mathcal{O})$ the Fourier-expansion involves the function

$$\sigma_s(t, t^*) := \sum_{\substack{0 \neq c \in \Lambda \\ ct = t^*c}} N(c)^{-s}.$$

Clearly $\sigma_s(t, t^*) = 0$ unless $N(t) = N(t^*)$. The structure of $\sigma_s(t, t^*)$ is elucidated by

PROPOSITION 5.8. *Let $t, t^* \in \text{Alt}(1; \mathcal{O})$ with $N(t) = N(t^*) \neq 0$ and $s \in \mathbf{C}$ with $\text{Re}(s) > 1$. Then there exists $S \in \text{Pos}(2; \mathbf{Z})$ such that*

$$\sigma_s(t, t^*) = \zeta(S; s) \quad \text{and} \quad \det S = \frac{4N(t)}{[\text{gcd}(\rho(t + t^*), \rho(t - t^*))]^2}$$

Proof. Let

$$t = \sum_{j=2}^4 t_j e_j, \quad t^* = \sum_{j=2}^4 t_j^* e_j.$$

Then $c = \sum_{j=1}^4 c_j e_j$ satisfies $ct = t^*c$ if and only if $(c_1, c_2, c_3, c_4)'$ belongs to the kernel of the matrix

$$\begin{pmatrix} t_2 - t_2^* & 0 & t_4 + t_4^* & -t_3 - t_3^* \\ 0 & t_2 - t_2^* & t_3 - t_3^* & t_4 - t_4^* \\ t_4 - t_4^* & t_3 + t_3^* & -t_2 - t_2^* & 0 \\ -t_3 + t_3^* & t_4 + t_4^* & 0 & -t_2 - t_2^* \end{pmatrix},$$

which has the rank 2. Hence $\sigma_s(t, t) = \zeta(S; s)$ holds for an appropriate $S \in \text{Pos}(2; \mathbf{Z})$. If $t_2 \neq t_2^*$ the kernel over \mathbf{Q} is spanned by $a = (t_4 + t_4^*, t_3 - t_3^*, -t_2 + t_2^*, 0)'$ and $b = (t_3 + t_3^*, -t_4 + t_4^*, 0, t_2 - t_2^*)'$. Hence we have

$$\det S = \frac{\det(G'G)}{[\delta_2(G)]^2}, \quad G = (a, b) \in \text{Mat}(4, 2; \mathbf{Z}),$$

where $\delta_2(G)$ denotes the second determinantal divisor of G (cf. [25], p. 25). An elementary computation yields $\det(G'G) = 4(t_2 - t_2^*)^2 N(t)$ and $\delta_2(G) = (t_2 - t_2^*) \text{gcd}(\rho(t + t^*), \rho(t - t^*))$. In the case $t_2 = t_2^*$ analogous arguments complete the proof. \square

If K_s denotes the modified Bessel-function, the Fourier-expansion is given by

THEOREM 5.9.

$$E_1^{\mathbf{H}}(z, s) = \sum_{t \in \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4} c(y; t) e^{2\pi i \text{Re}(\bar{x}t)},$$

where $z = x + y \in \mathcal{H}(1; \mathbf{H})$ and with $I = I^{(4)}$

$$\begin{aligned} c(y; 0) &= y^s + \pi^{3/2} \frac{\Gamma(s - 3/2) \zeta(I; s - 1) \zeta(2s - 3)}{\Gamma(s) \zeta(I; s) \zeta(2s - 2)} y^{3-s}, \\ c(y; t) &= 2\pi^s \frac{\sum_{l|\rho(t)} l^{3-2s} \sum_{t^* \in \text{Alt}(1; \emptyset)} \sigma_{s-1}(t, t + 2lt^*)}{\Gamma(s) \zeta(I; s) \zeta(2s - 2)} \\ &\quad \cdot |t|^{s-3/2} y^{3/2} K_{s-3/2}(2\pi|t|y) \end{aligned}$$

for $0 \neq t \in \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4$.

Proof. At first (5.6) yields

$$\beta_s(y; 0) = \pi^{3/2} \frac{\Gamma(s - 3/2)}{\Gamma(s)} y^{3-2s}.$$

Given $0 \neq t \in \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4$ we use an orthogonal transformation and apply [24], p. 85, in the following calculation

$$\begin{aligned} \beta_s(y; t) &= \int_{\text{Alt}(1; \mathbf{H})} |y + x|^{-2s} e^{-2\pi i \text{Re}(\bar{x}t)} dx \\ &= y^{3-2s} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (1 + x_1^2 + x_2^2 + x_3^2)^{-s} e^{-2\pi i y |t| x_1} dx_1 dx_2 dx_3 \\ &= 2\pi^s \frac{1}{\Gamma(s)} y^{3/2-s} |t|^{s-3/2} K_{s-3/2}(2\pi|t|y). \end{aligned}$$

Next observe that the representatives of $\Gamma_1^\infty \backslash \Gamma_1$ may be chosen in $\text{Mat}(2; \Lambda)$. Given $0 \neq c \in \Lambda$ let $\mathcal{R}(c)$ denote a set of representatives of the cosets $d + c\text{Alt}(1; \mathcal{O})$, $d \in \Lambda$, satisfying $c\bar{d} + d\bar{c} = 0$. In analogy with Proposition 4.7 one can show that $\mathcal{R}(c)$ consists of $\rho(c)N(c)$ elements. Moreover we use the abbreviation

$$\gamma(c, t) := \sum_{d \in \mathcal{R}(c)} e^{2\pi i \text{Re}(c^{-1}d\bar{t})}$$

for $t \in \mathbf{Z}e_2 + \mathbf{Z}e_3 + \mathbf{Z}e_4$ and obtain

$$\begin{aligned} \alpha_s(t) &= \sum_{\omega \in \mathbf{Q}e_2 + \mathbf{Q}e_3 + \mathbf{Q}e_4 \bmod 1} \nu(\omega)^{-2s} e^{2\pi i \text{Re}(\omega t)} \\ &= \frac{1}{\zeta(I; s)} \sum_{0 \neq c \in \Lambda} N(c)^{-s} \gamma(c, t), \end{aligned}$$

where $I = I^{(4)}$. Especially we have

$$\alpha_s(0) = \frac{1}{\zeta(I; s)} \sum_{0 \neq c \in \Lambda} \rho(c)N(c)^{1-s} = \frac{\zeta(I; s-1)\zeta(2s-3)}{\zeta(I; s)\zeta(2s-2)}.$$

Now let $t \neq 0$. A standard argument (cf. [6], 4.5) shows that

$$(*) \quad \gamma(c, t) = \begin{cases} \rho(c)N(c) & \text{if } \text{Re}(c^{-1}d\bar{t}) \in \mathbf{Z} \text{ for all } d \in \mathcal{R}(c), \\ 0 & \text{otherwise.} \end{cases}$$

Given $c = c_2c_1$, where $c_1, c_2 \in \Lambda$, $N(c_2) = 2^m$, $m \in \mathbf{N}_0$, $N(c_1)$ odd, we gain

$$\gamma(c, t) = \gamma(c_2, t)\gamma(c_1, t).$$

Using the isomorphism between $\Lambda/l\Lambda$ and $\text{Mat}(2; \mathbf{Z}/l\mathbf{Z})$ for odd $l \in \mathbf{N}$ (cf. [9], Vorlesung 8, resp. [17]) and a direct computation for c_2 , one can show that $\text{Re}(c^{-1}d\bar{t}) \in \mathbf{Z}$ holds for all $d \in \mathcal{R}(c)$ if and only if

$$\rho(c)|\rho(t) \quad \text{and} \quad ctc^{-1} \in t + 2\rho(c)\text{Alt}(1; \mathcal{O}).$$

Thus we calculate

$$\begin{aligned} \alpha_s(t) &= \frac{1}{\zeta(I; s)} \sum_{l \in \mathbf{N}, l|\rho(t)} \sum_{t^* \in \text{Alt}(1; \mathcal{O})} l^{3-2s} \sum_{\substack{0 \neq c \in \Lambda, \rho(c)=1 \\ c \frac{1}{l}t = (\frac{1}{l}t + 2t^*)c}} N(c)^{1-s} \\ &= \frac{1}{\zeta(I; s)\zeta(2s-2)} \sum_{l|\rho(t)} l^{3-2s} \sum_{t^* \in \text{Alt}(1; \mathcal{O})} \sigma_{s-1}(t, t + 2lt^*). \end{aligned}$$

Hence the assertion follows from Lemma 5.5. □

Note that the sum over t^* in the formula above is finite.

In the case $\mathbf{F} = \mathbf{R}$ we are able to give the Fourier-expansions explicitly for $n = 2, 3$. Given $t \in \mathbf{N}$ and $s \in \mathbf{C}$ let

$$\sigma_s(t) := \sum_{l \in \mathbf{N}, l|t} l^s$$

denote the divisor sum. Then the application of Remark 2.3 and [19], p. 46, resp. [20] leads to

COROLLARY 5.10. *One has*

$$E_2^{\mathbf{R}}(Z, s) = \sum_{t \in \mathbf{Z}} c(Y; t) e^{2\pi i x t}, \quad Z = xJ + Y \in \mathcal{H}(2; \mathbf{R})$$

where

$$\begin{aligned} c(Y; 0) &= (\det Y)^s + (\det Y)^s \zeta_1(Y, 2s) \\ &\quad + \sqrt{\pi} \frac{\Gamma(2s - 1/2)}{\Gamma(2s)} \cdot \frac{\zeta(4s - 1)}{\zeta(4s)} (\det Y)^{1/2-s}, \end{aligned}$$

$$c(Y; t) = 2\pi^{2s} |t|^{2s-1/2} \frac{\sigma_{1-4s}(|t|)}{\Gamma(2s)\zeta(4s)} (\det Y)^{1/4} K_{2s-1/2}(2\pi|t|\sqrt{\det Y})$$

for $0 \neq t \in \mathbf{Z}$.

Note that the Fourier-coefficients $c(Y; t)$ for $t \neq 0$ only depend on $\det Y$ and s .

Let $n \geq 3$ and fix a set of representatives $P: \text{Pr}(n, 2; \mathbf{Z})/\text{GL}(2; \mathbf{Z})$. Then each $T \in \text{Alt}^\tau(n; \mathbf{Z})$ with $\text{rank } T = 2$ possesses a unique representation

$$T = \frac{1}{2} t J [P'], \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix},$$

where $0 \neq t \in \mathbf{Z}$ and where $\varepsilon(2T) = |t|$ is the greatest common divisor of the entries of $2T \in \text{Alt}(n; \mathbf{Z})$. Now observe that

$$t^2 \cdot \det(Y[P]) = 2\tau(T'YT, Y)$$

holds. Hence we can combine the Corollaries 5.2 and 5.10 in order to gain

$$\begin{aligned} (5.7) \quad E_{n,2}^{\mathbf{R}}(Z, s) &= \sqrt{\pi} \frac{\Gamma(2s - 1/2)}{\Gamma(2s)} \frac{\zeta(4s - 1)}{\zeta(4s)} (\det Y)^s \zeta_2 \left(Y, 2s - \frac{1}{2} \right) \\ &\quad + \sum_{\substack{T \in \text{Alt}^\tau(n; \mathbf{Z}) \\ \text{rank } T = 2}} 2\pi^{2s} \frac{\sigma_{4s-1}(\varepsilon(2T))}{\Gamma(2s)\zeta(4s)} (\det Y)^s (2\tau(T'YT, Y))^{\frac{1}{4}-s} \\ &\quad \cdot K_{2s-1/2}(2\pi\sqrt{2\tau(T'YT, Y)}). \end{aligned}$$

Now let $n = 3$. We compute

$$\beta_s(Y; 0) = (\det Y)^{1-2s} \pi^{3/2} \frac{\Gamma(2s - 3/2)}{\Gamma(2s)}$$

in view of (5.6) and Lemma 4.8. Let $0 \neq T \in \text{Alt}^\tau(3; \mathbf{Z})$ and $Y \in \text{Pos}(3; \mathbf{R})$. We choose $V \in \text{GL}(3; \mathbf{R})$ such that $Y = V'V$. Change of variables yields

$$\begin{aligned} \beta_s(Y; T) &= \int_{\text{Alt}(3; \mathbf{R})} (\det(Y + X))^{-2s} e^{-2\pi i \tau(X, T)} dX \\ &= (\det Y)^{-2s} \int_{\text{Alt}(3; \mathbf{R})} (\det(I + X[V^{-1}]))^{-2s} e^{-2\pi i \tau(X, T)} dX \\ &= (\det Y)^{1-2s} \int_{\text{Alt}(3; \mathbf{R})} (\det(I + X))^{-2s} e^{-2\pi i \tau(X, T[V'])} dX \\ &= (\det Y)^{1-2s} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (1 + x_1^2 + x_2^2 + x_3^2)^{-2s} e^{-2\pi i \omega x_1} dx_1 dx_2 dx_3 \end{aligned}$$

by the use of an orthogonal transformation, where

$$\omega = (2\tau(T[V'], T[V']))^{1/2} = (2\tau(T'YT, Y))^{1/2}.$$

The same calculations as in the proof of Theorem 5.9 show that

$$\begin{aligned} \beta_s(Y; T) &= 2\pi^{2s} \frac{1}{\Gamma(2s)} (2\tau(T'YT, Y))^{s-3/4} (\det Y)^{1-2s} \\ &\quad \cdot K_{2s-3/2}(2\pi\sqrt{2\tau(T'YT, Y)}). \end{aligned}$$

Given $0 \neq R \in \text{Alt}(3; \mathbf{Q})$ note that $\nu(R) = l^2$, where $l \in \mathbf{N}$, if and only if $R = l^{-1}T$, where $T \in \text{Alt}(3; \mathbf{Z})$ and $\varepsilon(T) = 1$. Denoting the number of elements of a set \mathcal{S} by $\#\mathcal{S}$, we calculate

$$\begin{aligned} \alpha_s(0) &= \sum_{R \bmod 1} \nu(R)^{-2s} \\ &= \sum_{l=1}^{\infty} l^{-4s} \cdot \#\{g \in \mathbf{Z}^3; 1 \leq g_j \leq l, \text{g.c.d. } g = 1\} \\ &= \frac{\zeta(4s - 3)}{\zeta(4s)}. \end{aligned}$$

Given $0 \neq T \in \text{Alt}^\tau(3; \mathbf{Z})$ we may restrict to the case

$$T = \frac{1}{2} \begin{pmatrix} 0 & t & 0 \\ -t & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad t = \varepsilon(2T),$$

in view of (5.5). Hence we calculate

$$\begin{aligned}\alpha_s(T) &= \sum_{R \bmod 1} \nu(R)^{-2s} e^{2\pi i t(R, T)} \\ &= \frac{1}{\zeta(4s)} \sum_{l=1}^{\infty} \sum_{j=1}^3 \sum_{q_j=1}^l l^{-4s} e^{2\pi i t q_1 / l} \\ &= \frac{1}{\zeta(4s)} \sigma_{3-4s}(t).\end{aligned}$$

A combination of (5.2), (5.3), (5.7) and Lemma 5.5 yields the final

COROLLARY 5.11.

$$E_3^{\mathbf{R}}(Z, s) = \sum_{T \in \text{Alt}^3(\mathbf{3}; \mathbf{Z})} c(Y; T) e^{2\pi i t(X, T)}, \quad Z = X + Y \in \mathcal{H}(3; \mathbf{R}),$$

where

$$\begin{aligned}c(Y; 0) &= (\det Y)^s + (\det Y)^s \zeta_1(Y, 2s) \\ &\quad + \sqrt{\pi} \frac{\Gamma(2s - 1/2)}{\Gamma(2s)} \frac{\zeta(4s - 1)}{\zeta(4s)} (\det Y)^s \zeta_2(Y, 2s - 1/2) \\ &\quad + \pi^{3/2} \frac{\Gamma(2s - 3/2)}{\Gamma(2s)} \frac{\zeta(4s - 3)}{\zeta(4s)} (\det Y)^{1-s}, \\ c(Y; T) &= 2\pi^{2s} \frac{\sigma_{4s-1}(\varepsilon(2T))}{\Gamma(2s)\zeta(4s)} (\det Y)^s (2\tau(T'YT, Y))^{1/4-s} \\ &\quad \times K_{2s-1/2}(2\pi\sqrt{2\tau(T'YT, Y)}) \\ &\quad + 2\pi^{2s} \frac{\sigma_{3-4s}(\varepsilon(2T))}{\Gamma(2s)\zeta(4s)} (\det Y)^{1-s} (2\tau(T'YT, Y))^{s-3/4} \\ &\quad \times K_{2s-3/2}(2\pi\sqrt{2\tau(T'YT, Y)})\end{aligned}$$

for $T \neq 0$.

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