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CIRCULAR DOMAINS**

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## GLOBAL ANALYTIC HYPOELLIPTICITY OF $\square_b$ ON CIRCULAR DOMAINS

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Let  $D$  be a smoothly bounded pseudoconvex domain in  $\mathbb{C}^n$ ,  $n \geq 2$ , with real analytic boundary. In this paper we show that  $\square_b$  is globally analytic hypoelliptic if  $D$  is either circular satisfying  $\sum_{j=1}^n z_j \frac{\partial r}{\partial z_j}(z) \neq 0$  near the boundary  $bD$ , where  $r(z)$  is a defining function for  $D$ , or Reinhardt.

### I. Introduction.

Let  $D$  be a smoothly bounded pseudoconvex domain in  $\mathbb{C}^n$ ,  $n \geq 2$ , with real analytic boundary, and let  $\mathbb{C}^n$  be equipped with the standard Euclidean metric. We consider the real analytic regularity problem of the  $\square_b$ -equation on the boundary. Namely, given any  $f \in C_{p,q}^\omega(bD)$ ,  $0 \leq p \leq n-1$  and  $1 \leq q \leq n-1$ , let  $u = N_b f \in L_{p,q}^2(bD)$  be the solution to the following equation,

$$(1.1) \quad \square_b u = \left( \bar{\partial}_b \bar{\partial}_b^* + \bar{\partial}_b^* \bar{\partial}_b \right) N_b f = f.$$

Then we ask: is  $u = N_b f \in C_{p,q}^\omega(bD)$ ? For the definitions of these notations the reader is referred to Section II.

The existence of the solution  $u = N_b f$  is an immediate consequence of the closedness of the range of  $\square_b$  which was proved by M.C.Shaw [17] and Boas and M.C.Shaw [1], and independently by Kohn [15]. Since  $u = N_b f$  is the canonical solution to the equation (1.1), it is unique. It also follows from Proposition 2.7. Next the real analyticity of the boundary  $bD$  implies that  $u = N_b f$  is smooth, i.e.,  $u \in C_{p,q}^\infty(bD)$ . For instance see Kohn [14][16]. Therefore, the main concern here is about the real analytic regularity of the solution  $u$ . The only result we know so far is that the answer is affirmative when  $D$  is of strict pseudoconvexity which is due to Tartakoff [18][19][20] and Treves [21] for  $n \geq 3$  and to Geller [13] for  $n = 2$ .

The purpose of this article is to prove the following main results which presumably yield the first positive result to this problem on weakly pseudoconvex domains.

**Theorem 1.2.** *Let  $D$  be a smoothly bounded pseudoconvex domain with real analytic boundary  $bD$  in  $\mathbb{C}^n$ ,  $n \geq 2$ . Suppose that  $D$  is circular and that  $\sum_{j=1}^n z_j \frac{\partial r}{\partial z_j}(z) \neq 0$  near  $bD$ , where  $r(z)$  is the defining function for  $D$ . Then for any  $f \in C_{p,q}^\omega(bD)$ ,  $0 \leq p \leq n-1$  and  $1 \leq q \leq n-1$ , the solution  $u = N_b f$  to the  $\square_b$ -equation is also in  $C_{p,q}^\omega(bD)$ .*

Here a domain  $D$  is called circular if  $z \in D$  implies

$$e^{i\theta} \cdot z = (e^{i\theta} z_1, \dots, e^{i\theta} z_n) \in D$$

for any  $\theta \in \mathbb{R}$ .  $D$  is called Reinhardt if  $z \in D$  implies  $(e^{i\theta_1} z_1, \dots, e^{i\theta_n} z_n) \in D$  for any  $\theta_1, \dots, \theta_n \in \mathbb{R}$ , and  $D$  is called complete Reinhardt if  $z \in D$  implies  $(\lambda_1 z_1, \dots, \lambda_n z_n) \in D$  for any  $\lambda_i \in \mathbb{C}$  with  $|\lambda_i| \leq 1$ ,  $i = 1, \dots, n$ . Then we also prove

**Theorem 1.3.** *Let  $D$  be a smoothly bounded Reinhardt pseudoconvex domain in  $\mathbb{C}^n$ ,  $n \geq 2$ , with real analytic boundary. Then the same assertion as in the Theorem 1.2 holds.*

Hence, in particular,  $\square_b$  is globally analytically hypoelliptic on any complete Reinhardt domains with real analytic boundary which provides a large class of examples. Next we have the following immediate corollary.

**Corollary 1.4.** *Let  $D$  be a smoothly bounded pseudoconvex domain with real analytic boundary in  $\mathbb{C}^n$ ,  $n \geq 2$ . Suppose that either  $D$  is Reinhardt or  $D$  is circular with  $\sum_{j=1}^n z_j \frac{\partial r}{\partial z_j}(z) \neq 0$  near  $bD$ , where  $r(z)$  is the defining function for  $D$ . Then we have*

- (i) *The Szegő projection  $S$  defined on  $bD$  preserves the real analyticity globally, and*
- (ii) *The canonical solution  $w$  to the  $\bar{\partial}_b$ -equation, i.e.,  $\bar{\partial}_b w = \alpha$ , is in  $C_{p,q-1}^\omega(bD)$  if the given  $\alpha$  is in  $C_{p,q}^\omega(bD)$  and satisfies  $\bar{\partial}_b \alpha = 0$ .*

Here the Szegő projection  $S$  is defined to be the orthogonal projection from  $L^2(bD)$  onto the closed subspace, denoted by  $H^2(bD)$ , of square-integrable  $CR$ -functions defined on the boundary, and by canonical solution  $w$  we mean the solution with minimum  $L^2$ -norm. We remark that statement (i) has been proved by the author before in [5] via a more direct argument, and a special case of (ii), i.e.,  $n = 2$ , is verified by Derridj and Tartakoff in [11].

Now if we combine the above theorems and the main result, i.e., the Theorem B, obtained by the author in Chen [6], then we can conclude the following theorem.

**Theorem 1.5.** *Let  $D \subseteq \mathbb{C}^n$ ,  $n \geq 3$ , be a smoothly bounded pseudoconvex domain with real analytic boundary. Then the Szegő projection  $S$  associated with  $D$  preserves the real analyticity globally whenever  $D$  is defined by*

(i)  $D = \left\{ (z_1, \dots, z_n) \in \mathbb{C}^n \mid |f(z_1)|^2 + H(|z_2|^2, \dots, |z_n|^2) < 1 \right\}$ , where  $f(z_1)$  is holomorphic in  $z_1$  and  $H(x_2, \dots, x_n)$  is a polynomial with positive coefficient and  $H(0, \dots, 0) = 0$ , or

(ii)  $D = \left\{ (z_1, \dots, z_n) \in \mathbb{C}^n \mid |f(z_1)|^2 + |g(z_2)|^2 + \sum_{j=3}^n h_j(|z_j|^2) < 1 \right\}$ , where  $f(z_1)$  and  $g(z_2)$  are holomorphic in one variable  $z_1$  or  $z_2$  respectively, and  $h_j(x)$  is a polynomial with positive coefficients satisfying  $h_j(0) = 0$ ,  $h'_j(0) > 0$  for  $3 \leq j \leq n$ .

The real analytic regularity of the Bergman projection  $P$ , which is defined to be the orthogonal projection from  $L^2(D)$  onto the closed subspace  $H^2(D)$  of square-integrable holomorphic functions defined on  $D$ , on the domains (i) and (ii) defined in Theorem 1.5 has been established in Chen [6].

We should point out that in general the analytic pseudolocality of the Szegő projection  $S$  is false. Counterexamples have been discovered by Christ and Geller [7]. However, so far there is no counterexample to the globally real analytic regularity of  $S$ . Meanwhile, a number of positive results of the local analytic hypoellipticity for  $\square_b$  have been established on some model pseudoconvex hypersurface by Derridj and Tartakoff. For instance, see [8][9][10].

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## II. Proofs of the Theorems 1.2 and 1.3.

Let  $D$  be a smoothly bounded pseudoconvex domain with real analytic boundary in  $\mathbb{C}^n$ ,  $n \geq 2$ , and let  $\mathbb{C}^n$  be equipped with the standard Euclidean metric. Since we assume that the domain  $D$  is circular, we can choose a real analytic defining function  $r(z)$  for  $D$  such that  $r(z) = r(e^{i\theta} \cdot z)$  and that  $|\nabla r(z)| = 1$  for  $z \in bD$ . Let  $z_0 \in bD$  be a boundary point. We may assume that  $\frac{\partial r}{\partial z_n}(z_0) \neq 0$ . Hence a local basis for  $T^{1,0}(bD)$  near  $z_0$  can be chosen to be

$$L_j = \frac{\partial r}{\partial z_n} \frac{\partial}{\partial z_j} - \frac{\partial r}{\partial z_j} \frac{\partial}{\partial z_n} \text{ for } 1 \leq j \leq n-1.$$

Put  $X(z) = \sum_{j=1}^n \frac{\partial r}{\partial \bar{z}_j} \frac{\partial}{\partial z_j} - \sum_{j=1}^n \frac{\partial r}{\partial z_j} \frac{\partial}{\partial \bar{z}_j}$ . We see that

$$L_1, \dots, L_{n-1}, \bar{L}_1, \dots, \bar{L}_{n-1}$$

and  $X(z)$  form a local basis for the complexified tangent space  $\mathbb{C}T(bD)$ , and  $X(z)$  is perpendicular to  $T^{1,0}(bD) \oplus T^{0,1}(bD)$ . Let  $w_1, \dots, w_{n-1}$  be  $(1, 0)$ -form dual to  $L_1, \dots, L_{n-1}$  respectively. Put  $\eta = 2(\partial r - \bar{\partial} r)$ . Then it is not hard to see that  $w_1, \dots, w_{n-1}, \bar{w}_1, \dots, \bar{w}_{n-1}$  and  $\eta$  form a local basis for the complexified cotangent space  $\mathbb{C}T^*(bD)$ , and  $\eta$  is dual to  $X(z)$  and perpendicular to  $T^{*1,0}(bD) \oplus T^{*0,1}(bD)$ .

Now for any  $\theta \in \mathbb{R}$ , define

$$\begin{aligned} \Lambda_\theta : \bar{D} &\rightarrow \bar{D} \\ z &\mapsto e^{i\theta} \cdot z = (e^{i\theta} z_1, \dots, e^{i\theta} z_n). \end{aligned}$$

Put  $\zeta = e^{i\theta} \cdot z$ , then we obtain by direct computation  $\frac{\partial r}{\partial z_k}(z) = e^{i\theta} \frac{\partial r}{\partial \zeta_k}(\zeta)$ ,  $\Lambda_{\theta^*} \left( \frac{\partial}{\partial z_k} \right) = e^{i\theta} \frac{\partial}{\partial \zeta_k}$  and  $\Lambda_\theta^*(d\zeta_k) = e^{i\theta} dz_k$  for  $1 \leq k \leq n$ . It follows that we have

$$(2.1) \quad \Lambda_{\theta^*}(X(z)) = X(\zeta),$$

$$(2.2) \quad \Lambda_{\theta^*}(L_j(z)) = e^{i2\theta} L_j(\zeta), \quad \Lambda_{\theta^*}(\bar{L}_j(z)) = e^{-i2\theta} \bar{L}_j(\zeta), \quad \text{for } 1 \leq j \leq n-1,$$

$$(2.3) \quad \Lambda_\theta^*(\bar{\partial} r(\zeta)) = \bar{\partial} r(z), \quad \Lambda_\theta^*(\partial r(\zeta)) = \partial r(z).$$

This implies that  $\Lambda_\theta^* w_i$  is again a  $(1, 0)$ -form in  $\mathbb{C}T^*(bD)$ .

Next we recall the definition of  $\bar{\partial}_b$  briefly here. let  $f \in C_{p,q}^\infty(bD)$ , where  $C_{p,q}^\infty(bD)$  denotes the space of tangential  $(p, q)$ -forms defined on the boundary with smooth coefficients. Namely, any  $f$  in  $C_{p,q}^\infty(bD)$  can be expressed in the form

$$f = \sum'_{\substack{|I|=p \\ |J|=q}} f_{IJ} w_I \wedge \bar{w}_J,$$

where  $I = (i_1, \dots, i_p)$  and  $J = (j_1, \dots, j_q)$  are strictly increasing multiindices of length  $p$  and  $q$  respectively, and  $w_I = w_{i_1} \wedge \dots \wedge w_{i_p}$  and  $\bar{w}_J = \bar{w}_{j_1} \wedge \dots \wedge \bar{w}_{j_q}$ , and the prime indicates that the summation is carried over only the strictly increasing multiindices. Then consider  $f$  as a  $(p, q)$ -form in some open neighbourhood  $U$  of the boundary, and apply  $\bar{\partial}$  to  $f$ . We get

$$\bar{\partial} f = F + r(z)G + \bar{\partial} r \wedge H,$$

where  $F$  is a  $(p, q+1)$ -form involving only the  $w_i$ 's and  $\bar{w}_j$ 's, and  $G$  is a  $(p, q+1)$ -form, and  $H$  is a  $(p, q)$ -form. Then the tangential Cauchy-Riemann operator  $\bar{\partial}_b$  is defined to be

$$\bar{\partial}_b f = \pi_{p,q+1} \left( \bar{\partial} f \right) = F \Big|_{bD},$$

where  $\pi_{p,q+1}$  maps  $\bar{\partial}f$  to the restriction of  $F$  on the boundary. For the details the reader is referred to Folland and Kohn [12].

Now the above argument shows  $\Lambda_\theta^*$  maps the tangential component to the tangential component and maps the normal component to the normal component. Therefore, if  $f \in C_{p,q}^\infty(bD)$  with  $1 \leq q \leq n-2$  we obtain

$$\begin{aligned}
\bar{\partial}(\Lambda_\theta^* f(\zeta)) &= \pi_{p,q+1} \circ \bar{\partial} \circ \Lambda_\theta^* f \\
&= \pi_{p,q+1} \circ \Lambda_\theta^* \circ \bar{\partial} f \\
&= \pi_{p,q+1} \circ \Lambda_\theta^* \left( F + r(\zeta) G + \bar{\partial} r \wedge H \right) \\
&= \pi_{p,q+1} \circ \left( \Lambda_\theta^* F + r(z) \Lambda_\theta^* G + \bar{\partial} r \wedge \Lambda_\theta^* H \right) \\
&= \Lambda_\theta^* F \Big|_{bD} \\
&= \Lambda_\theta^* \circ \pi_{p,q+1} \left( F + r(\zeta) G + \bar{\partial} r \wedge H \right) \\
&= \Lambda_\theta^* \circ \pi_{p,q+1} \circ \bar{\partial} f \\
&= \Lambda_\theta^* \left( \bar{\partial}_b f \right).
\end{aligned}$$

Hence we have proved the following lemma.

**Lemma 2.4.**  $\bar{\partial}_b \Lambda_\theta^* f = \Lambda_\theta^* \bar{\partial}_b f$  for any  $f \in C_{p,q}^\infty(bD)$  with  $1 \leq q \leq n-1$ .

In general,  $\bar{\partial}_b \circ h^* \neq h^* \circ \bar{\partial}_b$  if  $h$  is just smooth  $CR$ -mapping. Denote by  $L_{p,q}^2(bD)$  the space of tangential  $(p,q)$ -forms with square-integrable coefficients. Then we have

**Lemma 2.5.** For any  $u$  in  $L_{p,q}^2(bD)$ , we have  $(\Lambda_\theta^* u, v) = (u, \Lambda_{-\theta}^* v)$  for any  $\theta \in \mathbb{R}$ .

*Proof.* Put  $\zeta = e^{i\theta} \cdot z$ , and express  $u$  and  $v$  in terms of the Euclidean coordinates, we get

$$u(\zeta) = \sum_{\substack{|I|=p \\ |J|=q}}' u_{IJ}(\zeta) d\zeta_I \wedge d\bar{\zeta}_J \text{ and } v(z) = \sum_{\substack{|I|=p \\ |J|=q}}' v_{IJ}(z) dz_I \wedge d\bar{z}_J.$$

Let  $d\sigma$  be the surface element defined on  $bD$ . We see that  $d\sigma$  is invariant under rotation, i.e.,  $\Lambda_\theta^* d\sigma_\zeta = d\sigma_z$ . For instance, see Chen [5]. Hence if we

set  $z = e^{-\theta} \cdot \zeta$ , we obtain

$$\begin{aligned}
(\Lambda_\theta^* u, v) &= \left( \sum' u_{IJ} (e^{i\theta} \cdot z) e^{i(p-q)\theta} dz_I \wedge d\bar{z}_J, \sum' v_{IJ}(z) dz_I \wedge d\bar{z}_J \right) \\
&= \sum' \int_{bD} u_{IJ} (e^{i\theta} \cdot z) e^{i(p-q)\theta} \overline{v_{IJ}(z)} d\sigma_z \\
&= \sum' \int_{bD} u_{IJ} (\zeta) \cdot \overline{e^{-i(p-q)\theta} v_{IJ} (e^{-i\theta} \cdot \zeta)} d\sigma_\zeta \\
&= (u, \Lambda_{-\theta}^* v) .
\end{aligned}$$

This completes the proof of the lemma.  $\square$

**Lemma 2.6.**  $\bar{\partial}_b^* \Lambda_\theta^* \alpha = \Lambda_\theta^* \bar{\partial}_b^* \alpha$  for any  $\alpha \in C_{p,q}^\infty(bD)$  with  $1 \leq q \leq n-1$ , where  $\bar{\partial}_b^*$  is the  $L^2$ -adjoint of  $\bar{\partial}_b$ .

*Proof.* Let  $\beta$  be any tangential  $(p, q-1)$ -form, i.e.,  $\beta \in C_{p,q-1}^\infty(bD)$ . We have

$$\begin{aligned}
(\bar{\partial}_b^* \Lambda_\theta^* \alpha, \beta) &= (\Lambda_\theta^* \alpha, \bar{\partial}_b \beta) \\
&= (\alpha, \Lambda_{-\theta}^* \bar{\partial}_b \beta) \\
&= (\alpha, \bar{\partial}_b \Lambda_{-\theta}^* \beta) \\
&= (\bar{\partial}_b^* \alpha, \Lambda_{-\theta}^* \beta) \\
&= (\Lambda_\theta^* \bar{\partial}_b^* \alpha, \beta) .
\end{aligned}$$

This proves the lemma.  $\square$

Now denote by  $H_{p,q} = \left\{ u \in L_{p,q}^2(bD) \mid \square_b u = 0 \right\}$ . We have the following fact.

**Proposition 2.7.** (i)  $H_{p,q} = 0$  for  $1 \leq q \leq n-2$ , and  
(ii)  $H_{p,n-1} = \left\{ u \in L_{p,n-1}^2(bD) \mid u \in \text{Dom}(\bar{\partial}_b^*) \text{ and } \bar{\partial}_b^* u = 0 \right\}$ .

In general,  $H_{p,n-1} \neq 0$ . Now let  $f \in C_{p,q}^\infty(bD)$ ,  $f \perp H_{p,q}$ , for  $1 \leq q \leq n-1$  be given, and let  $u = N_b f \in C_{p,q}^\infty(bD)$  be the canonical solution to the  $\square_b$ -equation,

$$\square_b u = \square_b N_b f = f,$$

where  $N_b$  is the so-called boundary Neumann operator. Let  $T$  be the vector field generated by the rotation, namely,  $T$  is defined by

$$\begin{aligned}
T(z) &= \frac{1}{2} \pi_{z^*} \left( \frac{\partial}{\partial \theta} \Big|_{\theta=0} \right) \\
&= \frac{i}{2} \left( \sum_{j=1}^n z_j \frac{\partial}{\partial z_j} - \sum_{j=1}^n \bar{z}_j \frac{\partial}{\partial \bar{z}_j} \right),
\end{aligned}$$

where  $\pi_z$  is the mapping defined for any  $z \in bD$  by

$$\begin{aligned} \pi_z : S^1 &\rightarrow \bar{D} \\ e^{i\theta} &\mapsto e^{i\theta} \cdot z = (e^{i\theta} z_1, \dots, e^{i\theta} z_n). \end{aligned}$$

By our hypotheses stated in the Theorem 1.2,  $T(z)$  is tangential and pointing in the bad direction for any  $z \in bD$ .

From now on, we will assume that  $f$  has real analytic coefficients, namely,  $f \in C_{p,q}^\omega(bD)$  with  $1 \leq q \leq n-1$ , and that  $f \perp H_{p,n-1}$  if  $q = n-1$ . Write  $f$  as

$$f = \sum'_{I,J} f_{IJ}(z) \omega_I \wedge \bar{\omega}_J.$$

Define  $Tf$  by

$$Tf = \sum'_{I,J} Tf_{IJ}(z) \omega_I \wedge \bar{\omega}_J.$$

It is not hard to see that  $Tf$  is still a tangential  $(p, q)$ -form, i.e.,  $Tf \in C_{p,q}^\omega(bD)$ . Then we have the following key lemma.

**Lemma 2.8.**  $T^k u = T^k N_b f = N_b T^k f$  for any  $k \in \mathbb{N}$ .

*Proof.* Since, in general,  $H_{p,n-1} \neq 0$ , we need to check that if  $u \perp H_{p,n-1}$ , then  $\Lambda_\theta^* u \perp H_{p,n-1}$ . So, let  $w \in H_{p,n-1}$ . By Lemma 2.6 we have  $\Lambda_\theta^* w \in H_{p,n-1}$ . It follows that

$$(\Lambda_\theta^* u, w) = (u, \Lambda_{-\theta}^* w) = 0.$$

Hence  $\Lambda_\theta^* u \perp H_{p,n-1}$ . This proves our assertion.

Now by combining Lemma 2.4 and 2.6, we obtain

$$\begin{aligned} \square_b \Lambda_\theta^* N_b f &= \Lambda_\theta^* \square_b N_b f \\ &= \Lambda_\theta^* f \\ &= \square_b N_b \Lambda_\theta^* f. \end{aligned}$$

Therefore, by Proposition 2.7 and our assertion we conclude that

$$(2.9) \quad \Lambda_\theta^* N_b f = N_b \Lambda_\theta^* f \text{ for any } \theta \in \mathbb{R}.$$

So now one can argue as we did in Chen [2] to get  $TN_b f = N_b Tf$ . Inductively we have  $T^k N_b f = N_b T^k f$ . This completes the proof of the lemma.  $\square$

Lemma 2.8 enables us to estimate the derivatives of the solution  $u = N_b f$  in the bad direction as follows,

$$\|T^k u\| = \|T^k N_b f\| = \|N_b T^k f\| \leq C_0 \|f\|_k \leq CC^k k!,$$



for some constant  $C > 0$  and any  $k \in \mathbb{N}$ , where  $\|\cdot\|_k$  is the Sobolev  $k$ -norm.

Therefore, what we need to estimate is the mixed derivatives of  $u$ , namely, the differentiations involving  $L_i$ 's,  $\bar{L}_i$ 's and  $T$ . For dealing with the  $\bar{\partial}$ -Neumann problem we can avail ourselves of the so-called basic estimate to achieve this goal. However, for the  $\bar{\partial}_b$ -Neumann problem, in general, the energy norm  $Q_b$  does not control the barred terms. But if we add the differentiation in  $T$ -direction to the right hand side, then we do have the following estimate,

$$(2.10) \quad \|u\| + \sum_{j=1}^{n-1} \|L_j u\| + \sum_{j=1}^{n-1} \|\bar{L}_j u\| \leq C \left( \|\bar{\partial}_b u\| + \|\bar{\partial}_b^* u\| + \|Tu\| \right),$$

for any  $u \in C_{p,q}^\omega(bD)$  with support in some open neighbourhood of  $z_0$ . The estimate (2.10) is essentially proved in [12]. Since we know how to control the  $T$ -derivatives of the solution  $u = N_b f$ , then a standard argument can be used to obtain the estimates of all the other mixed derivatives. For the details the reader is referred to Chen [2][3][4]. This completes the proof of Theorem 1.2.

A similar argument can be applied to prove the Theorem 1.3. Let  $D$  be a smoothly bounded Reinhardt pseudoconvex domain with real analytic boundary in  $\mathbb{C}$ ,  $n \geq 2$ . Let  $z_0 \in bD$  be a boundary point. First one can choose a direction, say  $z_n$ , such that  $\left(z_n \frac{\partial r}{\partial z_n}\right)(z_0) \neq 0$ , where  $r(z)$  is the defining function for  $D$ . Next we simply consider the rotation in  $z_n$ -direction, namely, for each  $\theta \in \mathbb{R}$ , define

$$\begin{aligned} \Lambda_\theta : \bar{D} &\rightarrow \bar{D} \\ z &\mapsto e^{i\theta} \cdot z = (z_1, \dots, z_{n-1}, e^{i\theta} z_n). \end{aligned}$$

Then by following the proof we present here for circular domains we can show without difficulty that  $\square_b$  is globally analytically hypoelliptic on any smoothly bounded Reinhardt pseudoconvex domain with real analytic boundary. Details can be found in Chen [3]. This also completes the proof of the Theorem 1.3.

Finally we make a concluding remark that the method we present here can be used to obtain the Sobolev  $H^s$ -regularity for  $\square_b$  on any smoothly bounded pseudoconvex domain which is either Reinhardt or circular with  $\sum_{j=1}^n z_j \frac{\partial r}{\partial z_j} \neq 0$  near  $bD$ , where  $r(z)$  is a smooth defining function for  $D$ . For instance, see Chen [4].

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**Added in proof:** M.Christ has recently proved the following, M.Christ, The Szegő projection need not preserve global analyticity, *Annals of Math.*, **143** (1996), 301-330.

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