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A UNIQUENESS THEOREM FOR THE MINIMAL SURFACE **EQUATION**

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In 1991, Collin and Krust proved that if u satisfies the minimal surface equation in a strip with linear Dirichlet data on two sides, then u must be a helicoid. In this paper, we give a simpler proof of this result and generalize it.

1. Introduction.

Let $\Omega_{\alpha} \subset \mathbb{R}^2$ be a sector domain with angle $0 < \alpha < \pi$. Consider the minimal surface equation

where $Tu = \frac{\nabla u}{\sqrt{1+|\nabla u|^2}}$ and ∇u is the gradient of u. In 1965, Nitsche [7] announced the following results:

- Given a continuous function f on $\partial\Omega_{\alpha}$, there always exists a solution u (1) which satisfies the minimal surface equation in Ω_{α} with Dirichlet data f on $\partial\Omega_{\alpha}$;
- (2) If u satisfies the minimal surface equation with vanishing boundary value in Ω_{α} , then $u \equiv 0$.

Nitsche thus raised the following question: Let $\Omega \subset \Omega_{\alpha}$ and let f be an arbitrary continuous function on $\partial\Omega$. If the Dirichlet problem

$$
\begin{cases} \text{div}\,Tu = 0 & \text{in }\Omega, \\ u = f & \text{on }\partial\Omega \end{cases}
$$

has a solution, is it unique?

We notice that similar questions for higher dimensions are raised in $[6]$. Results in this direction were obtained by Miklyukov [5] and Hwang [4] independently, in which the following result was established:

Theorem 1. Let $\Omega \subset \mathbb{R}^2$ be an unbounded domain and let $u, v \in C^2(\Omega) \cap$ $C^0(\overline{\Omega})$. For every $R > 0$, set $B_R = \{x \in \mathbb{R}^2 \mid |x| < R\}$ and $\Gamma_R = \partial(\Omega \cap B_R) \cap$ ∂B_R . Denote $|\Gamma_R|$ as the length of Γ_R . And suppose that

$$
\begin{cases}\n(i) & \text{div } Tu = \text{div } Tv & \text{in } \Omega, \\
(ii) & u = v & \text{on } \partial\Omega, \\
(iii) & \max_{\Omega \cap B_R} |u - v| = O\left(\sqrt{\int_{R_0}^R \frac{1}{|\Gamma_r|} dr}\right) & \text{as } R \to \infty, \text{ for some positive constant } R_0.\n\end{cases}
$$

Then $u \equiv v$ in Ω .

A stronger version of Theorem 1 was discovered by Collin and Krust [2] independently, which is the following:

Theorem 1^{*}. Let $\Omega, u, v, B_R, \Gamma_r$ and $|\Gamma_r|$ as in Theorem 1. And suppose $_{that}$

$$
\begin{cases}\n(i) & \text{div } Tu = \text{div } Tv & \text{in } \Omega, \\
(ii) & u = v & \text{on } \partial\Omega, \\
(iii) & \max_{\Omega \cap B_R} |u - v| = o\left(\int_{R_0}^R \frac{1}{|\Gamma_r|} dr\right) & \text{as } R \to \infty, \text{ for some} \\
 & \text{positive constant } R_0.\n\end{cases}
$$

Then $u \equiv v$ in Ω .

In fact, for any unbounded domain Ω , we have $|\Gamma_R| = O(R)$, and condition (iii) in Theorem 1^{*} becomes

$$
\max_{\Omega \cap B_R} |u - v| = o(\log R) \quad \text{as } R \to \infty.
$$

In the special case when Ω is a strip, then $|\Gamma_R| \leq$ constant, and condition (iii) becomes $\max_{\Omega \cap B_R} |u - v| = o(R)$.

On the other hand, in a strip domain Ω , Collin [1] showed that there exist two different solutions for the minimal surface equation such that $u = v$ on $\partial\Omega$ and max_{$\Omega \cap B_R$} $|u - v| = O(R)$ as $R \to \infty$. So condition (iii) is necessary.

This counterexample also answers Nitsche's question in the negative.

In contrast, the following result is also given in $[2]$.

Theorem 2. Let $\Omega = (0,1) \times \mathbb{R}$ be a strip. Suppose that

$$
\begin{cases}\n\text{div } Tu = 0 & \text{in } \Omega, \\
u(0, y) = ay + b, \\
u(1, y) = cy + d\n\end{cases}
$$

where a, b, c, d are constant. Then u must be a helicoid.

The following inequality was discovered by Miklyukov $[5, p. 265]$, Hwang [4, p. 342] and Collin and Krust $[2, p. 452]$:

$$
(Tu - Tv) \cdot (\nabla u - \nabla v) \ge \frac{\sqrt{1 + |\nabla u|^2} + \sqrt{1 + |\nabla v|^2}}{2} |Tu - Tv|^2
$$

$$
\geq |Tu-Tv|^2.
$$

Using this inequality, Miklyukov $[5]$ and Hwang $[4]$ proved Theorem 1 independently, and Collin and Krust [2] proved Theorem 1^{*} also based on this inequality.

It seems that the method of proof of Theorem 1^{*} can not be used to prove Theorem 2, and so Collin and Krust [2] resorted to the theory of Gauss maps instead.

In this paper, we will point out that the method of proof of Theorem 1 and Theorem 1^{*} could be use to give a simpler proof of Theorem 2. Moreover, we shall generalize Theorem 1^{*} and Theorem 2 to get the more general results as stated in Theorem 3 and Theorem 4. And we will make a remark after Theorem 3 to point out why Collin and Krust [2] could get a better result then Miklyukov $[5]$ and Hwang $[4]$.

2. A new proof for Theorem 2 and its generalization.

Without loss of generality, we may rephrase Theorem 2 in the following form:

Theorem 2^{*}. Let $\Omega = (b, a) \times \mathbb{R}$ be a strip domain in \mathbb{R}^2 where a, b are two constants with $-\frac{\pi}{2} < b < a < \frac{\pi}{2}$, and let $u \in C^0(\overline{\Omega}) \cap C^2(\Omega)$. Suppose that

$$
\begin{cases} \text{div}\,Tu = 0 & \text{in }\ \Omega, \\ u = y\tan x & \text{on }\ \partial\Omega. \end{cases}
$$

Then $u \equiv y \tan x$ in Ω ; in other words, u must be a helicoid.

Proof. For any $y > 0$, let

$$
\Omega_y = (b, a) \times (-y, y),
$$

\n
$$
\Gamma_y = \{(b, a) \times \{y\} \} \cup \{(b, a) \times \{-y\}\}\
$$

 $\quad \text{and, set}$

$$
g(y) = \int_{\Gamma} (u - v)(Tu - Tv) \cdot \nu \, ds
$$

=
$$
\oint_{\partial \Omega_y} (u - v)(Tu - Tv) \cdot \nu \, ds
$$

=
$$
\int \int_{\Omega_y} (\nabla u - \nabla v) \cdot (Tu - Tv)
$$

where $v \equiv y \tan x$ and ν is the unit outward normal of Γ_y and $\partial \Omega_y$. Since $(\nabla u - \nabla v) \cdot (Tu - Tv) \geq 0$, Fubini's Theorem yields that the derivative $g'(y)$

exists for almost all $y > 0$ and

$$
g'(y) = \int_{\Gamma_y} (\nabla u - \nabla v) \cdot (Tu - Tv)
$$

whenever $g'(y)$ exists. Thus, in view of (2), for these y,

$$
g'(y) \ge \int_{\Gamma_y} \frac{\sqrt{1+|\nabla u|^2} + \sqrt{1+|\nabla v|^2}}{2} |Tu - Tv|^2
$$

$$
\ge \left(\min_{\Gamma_y} \frac{\sqrt{1+|\nabla v|^2}}{2}\right) \int_{\Gamma_y} |Tu - Tv|^2,
$$

in which, as $v_x = y \sec^2 x$, we have

$$
\frac{\sqrt{1+|\nabla v|^2}}{2} \ge \frac{y\sec^2 x}{2} \ge \frac{y}{2}.
$$

Furthermore, by means of Schwarz's inequality,

$$
|\Gamma_y| \int_{\Gamma_y} |Tu - Tv|^2 \ge \left(\int_{\Gamma_y} |Tu - Tv| \right)^2,
$$

and $|\Gamma_y| = 2(a - b)$ (in virtue of the special geometry of Ω), thus

$$
\int_{\Gamma_y} |Tu - Tv|^2 \geq \frac{1}{2(a - b)} \left(\int_{\Gamma_y} |Tu - Tv| \right)^2.
$$

Hence, for any y where $g'(y)$ exists,

(3)
$$
g'(y) \ge \frac{y}{4(a-b)} \left(\int_{\Gamma_y} |Tu - Tv| \right)^2
$$

$$
\ge \frac{y}{4(a-b)} \left(\frac{1}{\pi} \int_{\Gamma_y} \tan^{-1}(u-v) (Tu - Tv) \cdot \nu \right)^2
$$

Now, for all $y > 0$, set

$$
h(y) = \int_{\Gamma_y} \tan^{-1}(u - v)(Tu - Tv) \cdot \nu
$$

=
$$
\int \int_{\Omega_y} \frac{(\nabla u - \nabla v) \cdot (Tu - Tv)}{1 + (u - v)^2}.
$$

We note that $h \geq 0$ and $h(y)$ increases as y increases. Thus, if $h \equiv 0$, it is easy to see that Theorem 2* holds. Hence we may assume that $h \neq 0$ and

that there exist two positive constants y_1 and c_1 such that $h(y) \geq c_1$ for all $y\geq y_1.$

Substituting this into (3), we obtain $g'(y) \ge \frac{c_1^2}{4(a-b)\pi^2}y$ for almost all $y \ge y_1$, which yields $g(y) - g(y_1) \ge \frac{c_1^2}{4(a-b)\pi^2}(y-y_1)^2$. Since $|u| = O(|y|)$ on $\partial\Omega$ as $|y| \to \infty$, by [7, p. 256], we have $|u| = O(|y|)$ in Ω as $|y| \to \infty$. Since for all $y > 0$, $g(y) = \int_{\Gamma_y} (u - v)(Tu - Tv) \cdot \nu$ and $|Tu - Tv| \le 2$, we have $g(y) = O(y)$ as $y \to \infty$, which gives a contradiction and completes our proof. П

By modifying the proof of Theorem 2^{*}, we can derive the following

Theorem 3. Let $\Omega \subseteq \mathbb{R}^2$ be an unbounded domain and let $u, v \in C^2(\Omega)$ $C^0(\overline{\Omega})$. Let B_R, Γ_R and $|\Gamma_R|$ be as in Theorem 1. Suppose that

$$
\begin{cases}\n(i) & \text{div } Tu = \text{div } Tv & \text{in } \Omega, \\
(ii) & u = v & \text{on } \partial\Omega, \\
(iii) & \max_{\Omega \cap B_R} |u - v| = o\left(\int_{R_0}^R \frac{1}{|\Gamma_R|} \min_{\Gamma_R} \sqrt{1 + |\nabla v|^2} \, dR\right) & \text{as } R \to \infty,\n\end{cases}
$$

where R_0 is a positive constant. Then we have $u \equiv v$ in Ω .

Remark.

- (a) Notice that condition (iii) depends on $|\nabla v|$ only, without assuming any condition on $|\nabla u|$.
- In Theorem 2^{*}, since div $Tu = 0$ in Ω and $u = y \tan x$ on $\partial \Omega$, by (b) [7, p. 256], we have $u = O(|y|)$ in Ω as $|y| \to \infty$. And so, condition (iii) of Theorem 3 holds.

Proof of Theorem 3. The proof is similar to that of Theorem 2^{*}. For every $R>0, \,{\rm let}$

$$
M(R) = \max_{\Omega \cap B_R} |u - v| = \max_{\Gamma_R} |u - v|,
$$

\n
$$
Q(R) = \min_{\Gamma_R} \frac{\sqrt{1 + |\nabla v|^2}}{2},
$$

\n
$$
g(R) = \int_{\Gamma_R} (u - v)(Tu - Tv) \cdot \nu = \int \int_{\Omega_R} (\nabla u - \nabla v) \cdot (Tu - Tv)
$$

 and

$$
h(R) = \int_{\Gamma_R} \tan^{-1}(u-v)(Tu-Tv) \cdot \nu.
$$

As in the proof of Theorem 2^{*}, we may assume that $h \neq 0$ and that there exist two positive constants R_1 and C_1 such that $R_1 > R_0$ and

(4)
$$
h(R) \geq C_1 \quad \text{for all } R \geq R_1.
$$

For almost all $R > 0$, we have

(5)
$$
g'(R) = \int_{\Gamma_R} (\nabla u - \nabla v) \cdot (Tu - Tv)
$$

$$
\geq \int_{\Gamma_R} Q(R) |Tu - Tv|^2
$$

$$
\geq Q(R) |\Gamma_R|^{-1} \left(\int_{\Gamma_R} |Tu - Tv| \right)^2.
$$

Thus $g'(R) \geq (\frac{\pi}{2})^2 C_1^2 |\Gamma_R|^{-1} Q(R)$, for almost all $R > R_1$. Hence, for every R and R_2 such that $R > R_2 \ge R_1$, we have

(6)
$$
g(R) - g(R_2) \ge \left(\frac{2C_1}{\pi}\right)^2 \int_{R_2}^R \frac{Q(r)}{|\Gamma_r|} dr.
$$

By (4), we have $M(R) > 0$ for all $R \ge R_1$, hence (5) yields, for almost all $R \geq R_1$,

$$
g'(R) \ge Q(R)|\Gamma_R|^{-1} \int |Tu - Tv|^2
$$

$$
\ge \frac{g^2(R)Q(R)}{M^2(R)|\Gamma_R|};
$$

and so, for every R and R_2 such that $R > R_2 \ge R_1$,

$$
-\frac{1}{g}\Big|_{R_2}^R \ge \int_{R_2}^R \frac{g'}{g^2} \ge \int_{R_2}^R \frac{Q(r)}{M^2(r)|\Gamma_r|} dr \ge \frac{1}{M^2(R)} \int_{R_2}^R \frac{Q(r)}{|\Gamma_r|} dr,
$$

and then

(7)
$$
\frac{1}{g(R_2)} \ge \frac{1}{M^2(R)} \int_{R_2}^R \frac{Q(r)}{|\Gamma_r|} dr.
$$

Now, since $M(R) > 0$ for all $R \ge R_1$, $M(R)$ is an increasing function of R and, in view of condition (iii),

$$
(M(R))^{-1} \int_{R_1}^R \frac{Q(r)}{|\Gamma_r|} dr \to \infty \quad \text{as } R \to \infty,
$$

and also

$$
\int_{R_1}^R \frac{Q(r)}{|\Gamma_r|} dr \to \infty \quad \text{as } R \to \infty;
$$

hence we can choose a constant $R_3 > R_1$ such that

$$
(M(R))^{-1} \int_{R_1}^R \frac{Q(r)}{|\Gamma_r|} \ge \sqrt{2}\pi C_1^{-1}, \quad \text{for every } R \ge R_3,
$$

and a constant R_4 , $R_4 > R_3$, which depends on R_3 , such that

$$
\int_{R_1}^{R_4} \frac{Q(r)}{|\Gamma_r|} dr = 2 \int_{R_1}^{R_3} \frac{Q(r)}{|\Gamma_r|} dr.
$$

With this choice of R_3 and R_4 , we have

$$
1 \geq \frac{g(R_3) - g(R_1)}{g(R_3)}
$$

\n
$$
\geq \left[\left(\frac{2C_1}{\pi} \right)^2 \int_{R_1}^{R_3} \frac{Q(r)}{|\Gamma_r|} \right] \left[(M^2(R_4))^{-1} \int_{R_3}^{R_4} \frac{Q(r)}{|\Gamma_r|} \right] \qquad \text{(by (6), (7))}
$$

\n
$$
= \left[\left(\frac{2C_1}{\pi} \right)^2 (M^2(R_4))^{-1} \right] \frac{1}{4} \left(\int_{R_1}^{R_4} \frac{Q(r)}{|\Gamma_r|} \right)^2 \qquad \text{(by the choice of } R_3, R_4)
$$

\n
$$
\geq \frac{C_1^2}{\pi^2} (2\pi^2) C_1^{-2} \qquad \text{(again by the choice of } R_3 \text{ and } R_4)
$$

\n
$$
\geq 2,
$$

which is desired contradiction.

Remark. The above proof is to show (6) , which is the lower bound of $g(R)$, and (7), which is the upper bound of $g(R)$. And from (6) and (7), we get contradiction and so prove the theorem. Miklyukov [5] and Hwang [4] only observed the upper bound of $q(R)$, and so could not derive the better result as in Collin and Krust [2].

Let Ω be a domain in \mathbb{R}^2 . Consider the following equation in divergence form

$$
\operatorname{div} A(x, u, \nabla u) = f(x, u, \nabla u),
$$

where

$$
A = (A_1, A_2), A_i: \Omega \times \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R}, \quad i = 1, 2,
$$

$$
f: \Omega \times \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R},
$$

and

$$
A_i \in C^0\left(\overline{\Omega} \times \mathbb{R} \times \mathbb{R}^2\right) \cap C^1(\Omega \times \mathbb{R} \times \mathbb{R}^2), \quad i = 1, 2, f \in C^0(\Omega \times \mathbb{R} \times \mathbb{R}^2).
$$

We rewrite $A(x, u, \nabla u)$ briefly as Au.

Suppose that Au satisfies the following structural condition:

(8)
\n
$$
\begin{cases}\n(Au - Av) \cdot (\nabla u - \nabla v) \ge |Au - Av|^2 Q(R), \\
\text{where } R = \sqrt{x^2 + y^2} \text{ and } Q(R) \text{ is a positive function,} \\
(\nabla u - \nabla v) \cdot (Au - Av) = 0, \quad \text{if } \nabla u = \nabla v.\n\end{cases}
$$

 \Box

Now we have the following result:

Theorem 4. Let $\partial\Omega = \Sigma^{\alpha} + \Sigma^{\beta}$ be a decomposition of $\partial\Omega$ such that $\Sigma^{\beta} \in C^1$. Let $u, v \in C^2(\Omega) \cap C^1(\Omega \cup \Sigma^{\beta}) \cap C^0(\overline{\Omega})$ and let $M(R) = \max_{\Omega \cap B_R} (u - v, 0)$. Suppose that

Then, if $\partial\Omega = \Sigma^{\beta}$, we have either $u(x) \equiv v(x) + a$ positive constant or else $u(x) \leq v(x)$. Otherwise, $u(x) \equiv v(x)$.

The proof of Theorem 4 is exactly the same as that of Theorem 3. The interested readers may consult [4].

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