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**GLOBAL WELL-POSEDNESS FOR THE
3D ROTATING NAVIER–STOKES EQUATIONS
WITH HIGHLY OSCILLATING INITIAL DATA**

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We prove the global well-posedness for the 3D rotating Navier–Stokes equations in the critical functional framework. This result allows us to construct global solutions for a class of highly oscillating initial data.

1. Introduction

In this paper, we study the 3D rotating Navier–Stokes equations

$$(1-1) \quad \begin{cases} u_t - \nu \Delta u + \Omega e_3 \times u + u \cdot \nabla u + \nabla p = 0, \\ \operatorname{div} u = 0, \\ u(0, x) = u_0(x), \end{cases}$$

where ν denotes the viscosity coefficient of the fluid, Ω the speed of rotation, e_3 the unit vector in the x_3 direction and $\Omega e_3 \times u$ the Coriolis force. We refer to [Chemin et al. 2006; Majda 2003; Pedlosky 1987] for its background in geophysical fluid dynamics. If the Coriolis force is neglected, the equations (1-1) become the classical 3D incompressible Navier–Stokes equations

$$(1-2) \quad \begin{cases} u_t - \nu \Delta u + u \cdot \nabla u + \nabla p = 0, \\ \operatorname{div} u = 0, \\ u(0, x) = u_0(x). \end{cases}$$

The global existence of a weak solution of (1-1) can be proved by the classical compactness method, since we still have the energy estimate

$$\|u(t)\|_{L^2}^2 + 2 \int_0^t \|\nabla u(s)\|_{L^2}^2 ds \leq \|u_0\|_{L^2}^2.$$

As in 3D Navier–Stokes equations, the uniqueness and regularity of weak solutions are also open problems. Recently, Giga et al. [2006; 2007; 2008] studied the local

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existence of a mild solution for a class of nondecaying initial data which includes a class of almost periodic functions, as well as global existence for small data. On the other hand, when the speed Ω of rotation is fast enough, the global existence of smooth solution was proved in [Babin et al. 1997; 1999; Chemin et al. 2000; 2006].

For the 3D Navier–Stokes equations, Fujita and Kato [1964; Kato 1984] proved the local well-posedness for large initial data and the global well-posedness for small initial data in the homogeneous Sobolev space $\dot{H}^{\frac{1}{2}}$ and the Lebesgue space L^3 , respectively. These spaces are all the critical ones, which are relevant to the scaling of the Navier–Stokes equations: if (u, p) solves (1-2), then

$$(1-3) \quad (u_\lambda(t, x), p_\lambda(t, x)) := (\lambda u(\lambda^2 t, \lambda x), \lambda^2 p(\lambda^2 t, \lambda x))$$

is also a solution of (1-2). The so-called *critical space* is the one such that the associated norm is invariant under the scaling of (1-3). Recently, Cannone [1997] (see also [Cannone 1995; 2004; Cannone et al. 1994]) generalized it to Besov spaces with negative index of regularity. More precisely, he showed that if the initial data satisfies

$$\|u_0\|_{\dot{B}_{p,\infty}^{-1+\frac{3}{p}}} \leq c, \quad p > 3$$

for some small constant c , then the Navier–Stokes equations (1-2) are globally well-posed. Let us emphasize that this result allows us to construct global solutions for highly oscillating initial data which may have a large norm in $\dot{H}^{\frac{1}{2}}$ or L^3 . A typical example is

$$u_0(x) = \sin \frac{x_3}{\varepsilon} (-\partial_2 \phi(x), \partial_1 \phi(x), 0)$$

where $\phi \in \mathcal{S}(\mathbb{R}^3)$ and $\varepsilon > 0$ is small enough. We refer to [Chemin and Gallagher 2006; Chemin and Zhang 2007; Chen et al. 2010a] for some relevant results. A natural question is then to prove a theorem of this type for the rotating Navier–Stokes equations.

We know that Kato’s method heavily relies on the uniform boundedness of the Stokes semigroup in L^p and global $L^p - L^q$ estimates, but the Stokes–Coriolis semigroup is not uniformly bounded in L^p for $p \neq 2$; see Theorems 5 and 6 in [Dragičević et al. 2006]. Standard techniques allow us to prove these estimates only locally for the Stokes–Coriolis semigroup, hence one can obtain the local existence of mild solution in L^3 by Kato’s method. Whether one can extend this solution to a global one for small data in L^3 is a very interesting problem.

Very recently, based on the global $L^p - L^q$ estimates with $q \leq 2 \leq p$ and $L^q - H^{\frac{1}{2}}$ estimates with $q > 3$ for the Stokes–Coriolis semigroup, Hieber and Shibata [2010] proved the following global result for small data in $H^{\frac{1}{2}}$.

Theorem 1.1. *Let $q > 3$. Then there exists $c > 0$ independent of Ω such that for any $u_0 \in H_\sigma^{\frac{1}{2}}$ with $\|u_0\|_{H_\sigma^{\frac{1}{2}}} \leq c$, the equations (1-1) admit a unique mild solution $u \in C([0, \infty), H_\sigma^{\frac{1}{2}})$ satisfying*

$$(1-4) \quad u \in C((0, \infty), L^q) \quad \text{and} \quad \lim_{t \rightarrow 0^+} \sup_{0 < s < t} s^{\frac{1}{2} - \frac{3}{2q}} \|u(s, \cdot)\|_{L^q} = 0,$$

$$\nabla u \in C((0, \infty), L^2) \quad \text{and} \quad \lim_{t \rightarrow 0^+} \sup_{0 < s < t} s^{\frac{1}{4}} \|\nabla u(s, \cdot)\|_{L^2} = 0.$$

Here $H_\sigma^{\frac{1}{2}}$ denotes the closure of the set $\{u \in C_c^\infty(\mathbb{R}^3)^3, \operatorname{div} u = 0\}$ in the norm of $\|\cdot\|_{H_\sigma^{\frac{1}{2}}}$.

The goal of this paper is to prove the global existence of a solution of (1-1) for a class of highly oscillating initial velocity. Thus we need to solve the system (1-1) for the initial data in a critical functional framework whose regularity index is negative, for example, $\dot{B}_{p,q}^{-1+\frac{3}{p}}$ for $p > 3$. However, Cannone’s proof [1997] doesn’t work for our case, since it also relies on the global $L^p - L^q$ estimates for the Stokes semigroup. Indeed, for the Stokes–Coriolis semigroup $\mathcal{G}(t)$, one has

$$\|\mathcal{G}(t)u_0\|_{L^p} \leq C_{p,\Omega} t^2 \|u_0\|_{L^p}, \quad \text{if } p \neq 2;$$

see Proposition 2.2 in [Hieber and Shibata 2010]. Then we can infer from the definition of the Besov space that

$$\|\mathcal{G}(t)u_0\|_{\dot{B}_{p,q}^{-1+\frac{3}{p}}} \leq C t^2 \|u_0\|_{\dot{B}_{p,q}^{-1+\frac{3}{p}}}.$$

This means that even if the initial data u_0 is small in $\dot{B}_{p,q}^{-1+\frac{3}{p}}$, the linear part of the solution, $\|\mathcal{G}(t)u_0\|_{\dot{B}_{p,q}^{-1+\frac{3}{p}}}$, may become large after some time $t_0 > 0$.

Fortunately, we have the following important observation: if u is an element of L^p with $\operatorname{supp} \hat{u} \in \{\xi : |\xi| \gtrsim \lambda\}$, then

$$\|\mathcal{G}(t)u\|_{L^p} \leq C_{p,\Omega} e^{-t\lambda^2} \|u\|_{L^p}$$

for any $p \in [1, \infty]$ and $t \in [0, \infty]$, while for any $u \in L^2$,

$$\|\mathcal{G}(t)u\|_{L^2} \leq \|u\|_{L^2}.$$

This motivates us to introduce the hybrid-Besov spaces $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$ (see Definition 2.2). Roughly speaking, if $u \in \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$, the low frequency part of u belongs to $\dot{H}^{\frac{1}{2}}$ and the high frequency part belongs to $\dot{B}_{p,\infty}^{-1+\frac{3}{p}}$. So, $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$ is still a critical space. A remarkable property of $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$ is that if $p > 3$, then

$$\|u_0(x)\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq C \varepsilon^{1-\frac{3}{p}},$$

for $u_0(x) = \sin(x_1/\varepsilon)\phi(x)$, with $\phi(x) \in \mathcal{S}(\mathbb{R}^3)$; see [Proposition 2.4](#). That is, the highly oscillating function is still small in the norm of $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$.

Definition 1.2. Let $1 \leq p \leq \infty$, we denote by E_p the space of functions such that

$$E_p = \{u : \operatorname{div} u = 0, \|u\|_{E_p} < +\infty\},$$

where

$$\|u\|_{E_p} := \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1})} + \|u\|_{\tilde{L}^1(\mathbb{R}^+; \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1})}.$$

Definition 1.3. We denote by $C_*([0, \infty); \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1})$ the set of functions u such that u is continuous from $(0, \infty)$ to $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$, but weakly continuous at $t = 0$; i.e.,

$$\lim_{t \rightarrow 0^+} \sup_{0 < s < t} \langle u(s, \cdot), g(\cdot) \rangle = 0 \quad \text{for all } g \in \mathcal{S} \text{ with } \|g\|_{\dot{\mathcal{B}}_{2,p}^{-\frac{1}{2}, 1-\frac{3}{p}}} \leq 1.$$

Our main results are stated as follows.

Theorem 1.4. Let $p \in [2, 4]$. There exists a positive constant c independent of Ω such that if $\|u_0\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq c$, then there exists a unique solution $u \in E_p$ of [\(1-1\)](#) such that

$$u \in C_*([0, \infty); \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}).$$

Remark 1.5. Due to the inclusion map

$$H^{\frac{1}{2}} \subseteq \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1} \quad \text{for } p \geq 2,$$

[Theorem 1.4](#) is an improvement on [Theorem 1.1](#). The importance of this is that it allows us to construct global solutions of [\(1-1\)](#) for a class of highly oscillating initial velocity u_0 , for example,

$$(1-5) \quad u_0(x) = \sin\left(\frac{x_3}{\varepsilon}\right)(-\partial_2\phi(x), \partial_1\phi(x), 0)$$

where $\phi \in \mathcal{S}(\mathbb{R}^3)$ and $\varepsilon > 0$ is small enough. This type of data is large in the Sobolev norm; however, it is small in the norms of Besov spaces with negative regularity index.

Remark 1.6. As shown in Section 4.2 of [\[Cannone 2004\]](#), for the classical Navier–Stokes equations [\(1-2\)](#), there exists the following “highly oscillating” initial data: $u_0(x) \in \mathcal{S}'(\mathbb{R}^3)$ is such that $\hat{u}_0(\xi) = 0$ if $|\xi| \leq 1/\varepsilon$. Then

$$(1-6) \quad \|u_0\|_{\dot{H}^{1/2}} \leq \varepsilon^{1/2} \|u_0\|_{\dot{H}^1}.$$

We point out that examples like [\(1-5\)](#) are not included in such initial data. In fact, if $\operatorname{supp} \hat{\phi}(\xi) \subset \{|\xi| \leq 1/2\varepsilon\}$, then the above estimate is satisfied, while if $\hat{\phi}(\xi)$ has no support, it is not sure that [\(1-6\)](#) holds, which implies the norm of $\|u_0\|_{\dot{H}^{1/2}}$ may

not be small enough.

Remark 1.7. The inhomogeneous part of the solution has more regularity:

$$u - \mathcal{G}(t)u_0 \in C(\mathbb{R}^+; \dot{B}_{2,\infty}^{\frac{1}{2}}),$$

which can be proved by following the proof of [Proposition 4.1](#).

If u_0 lies in $\dot{H}^{\frac{1}{2}}$, we can obtain the following global well-posedness result.

Theorem 1.8. *Let $p \in [2, 4]$. There exists a positive constant c independent of Ω such that, if u_0 belongs to $\dot{H}^{\frac{1}{2}}$ with $\|u_0\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq c$, then there exists a unique global solution of [\(1-1\)](#) in $C(\mathbb{R}^+, \dot{H}^{\frac{1}{2}})$.*

Remark 1.9. Since we only impose the smallness condition of the initial data in the norm of $\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}$, this allows us to obtain the global well-posedness of [\(1-1\)](#) for a class of highly oscillating initial velocity u_0 . Moreover, the uniqueness holds in the class $C(\mathbb{R}^+, \dot{H}^{\frac{1}{2}})$; i.e., it is unconditional.

The structure of this paper is as follows. In [Section 2](#), we recall some basic facts about Littlewood–Paley theory and the functional spaces. In [Section 3](#), we recall some results concerning the Stokes–Coriolis semigroup’s regularizing effect. [Section 4](#) is devoted to the important bilinear estimates. In [Section 5](#), we prove [Theorem 1.4](#) and [Theorem 1.8](#).

2. Littlewood–Paley theory and the function spaces

First of all, we introduce the Littlewood–Paley decomposition. Choose two radial functions $\varphi, \chi \in \mathcal{S}(\mathbb{R}^3)$ supported in $\mathcal{C} = \{\xi \in \mathbb{R}^3, \frac{3}{4} \leq |\xi| \leq \frac{8}{3}\}$, $\mathcal{B} = \{\xi \in \mathbb{R}^3, |\xi| \leq \frac{4}{3}\}$, respectively, such that

$$\sum_{j \in \mathbb{Z}} \varphi(2^{-j} \xi) = 1 \quad \text{for all } \xi \neq 0.$$

For $f \in \mathcal{S}'(\mathbb{R}^3)$, the frequency localization operators Δ_j and S_j ($j \in \mathbb{Z}$) are defined by

$$\Delta_j f = \varphi(2^{-j} D) f, \quad S_j f = \chi(2^{-j} D) f, \quad D = \frac{\nabla_x}{i}.$$

Moreover, we have

$$S_j f = \sum_{k=-\infty}^{j-1} \Delta_k f \quad \text{in } \mathcal{L}'(\mathbb{R}^3).$$

Here we denote by $\mathcal{L}'(\mathbb{R}^3)$ the dual space of

$$\mathcal{L}(\mathbb{R}^3) = \{f \in \mathcal{S}(\mathbb{R}^3) : D^\alpha \hat{f}(0) = 0 \text{ for all multiindices } \alpha \in (\mathbb{N} \cup 0)^3\}.$$

With our choice of φ , it is easy to verify that

$$(2-1) \quad \Delta_j \Delta_k f = 0 \quad \text{if } |j - k| \geq 2 \quad \text{and} \quad \Delta_j (S_{k-1} f \Delta_k f) = 0 \quad \text{if } |j - k| \geq 5.$$

In the sequel, we will constantly use Bony's decomposition [1981]:

$$(2-2) \quad fg = T_f g + T_g f + R(f, g),$$

with

$$T_f g = \sum_{j \in \mathbb{Z}} S_{j-1} f \Delta_j g, \quad R(f, g) = \sum_{j \in \mathbb{Z}} \Delta_j f \tilde{\Delta}_j g, \quad \tilde{\Delta}_j g = \sum_{|j' - j| \leq 1} \Delta_{j'} g.$$

Definition 2.1 (homogeneous Besov space). Let $s \in \mathbb{R}$, $1 \leq p, q \leq +\infty$. The homogeneous Besov space $\dot{B}_{p,q}^s$ is defined by

$$\dot{B}_{p,q}^s := \{f \in \mathcal{L}'(\mathbb{R}^3) : \|f\|_{\dot{B}_{p,q}^s} < +\infty\},$$

where

$$\|f\|_{\dot{B}_{p,q}^s} := \|2^{ks} \|\Delta_k f\|_{L^p}\|_{l^q}.$$

If $p = q = 2$, $\dot{B}_{2,2}^s$ is equivalent to the homogeneous Sobolev space \dot{H}^s .

Definition 2.2 (hybrid-Besov space). Let $s, \sigma \in \mathbb{R}$, $1 \leq p \leq +\infty$. The hybrid-Besov space $\dot{\mathcal{B}}_{2,p}^{s,\sigma}$ is defined by

$$\dot{\mathcal{B}}_{2,p}^{s,\sigma} := \{f \in \mathcal{L}'(\mathbb{R}^3) : \|f\|_{\dot{\mathcal{B}}_{2,p}^{s,\sigma}} < +\infty\},$$

where

$$\|f\|_{\dot{\mathcal{B}}_{2,p}^{s,\sigma}} := \sup_{2^k \leq \Omega} 2^{ks} \|\Delta_k f\|_{L^2} + \sup_{2^k > \Omega} 2^{k\sigma} \|\Delta_k f\|_{L^p}.$$

The norm of the space $\tilde{L}_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma})$ is defined by

$$\|f\|_{\tilde{L}_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma})} := \sup_{2^k \leq \Omega} 2^{ks} \|\Delta_k f\|_{L_T^r L^2} + \sup_{2^k > \Omega} 2^{k\sigma} \|\Delta_k f\|_{L_T^r L^p}.$$

It is easy to check that $L_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma}) \subseteq \tilde{L}_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma})$, where the norm of $L_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma})$ is defined by

$$\|f\|_{L_T^r(\dot{\mathcal{B}}_{2,p}^{s,\sigma})} := \|\|f(t)\|_{\dot{\mathcal{B}}_{2,p}^{s,\sigma}}\|_{L_T^r}.$$

Bernstein's lemma will be repeatedly used throughout this paper:

Lemma 2.3 [Chemin 1995]. Let $1 \leq p \leq q \leq +\infty$. Then for any $\beta, \gamma \in (\mathbb{N} \cup \{0\})^3$, there exists a constant C independent of f, j such that, for any $f \in L^p$,

$$\text{supp } \hat{f} \subseteq \{|\xi| \leq A_0 2^j\} \Rightarrow \|\partial^\gamma f\|_{L^q} \leq C 2^{j|\gamma| + jn(\frac{1}{p} - \frac{1}{q})} \|f\|_{L^p},$$

$$\text{supp } \hat{f} \subseteq \{A_1 2^j \leq |\xi| \leq A_2 2^j\} \Rightarrow \|f\|_{L^p} \leq C 2^{-j|\gamma|} \sup_{|\beta|=|\gamma|} \|\partial^\beta f\|_{L^p}.$$

Proposition 2.4. Let $\phi \in \mathcal{S}(\mathbb{R}^3)$ and $p > 3$. If $\phi_\varepsilon(x) := e^{i\frac{x_1}{\varepsilon}} \phi(x)$, then, for any $0 < \varepsilon \leq \Omega^{-1}$,

$$\|\phi_\varepsilon\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq C\varepsilon^{1-\frac{3}{p}},$$

where C is a constant independent of ε .

Proof. Let $j_0 \in \mathbb{N}$ be such that $\Omega \leq 2^{j_0} \sim \varepsilon^{-1}$. By Lemma 2.3, we have

$$\sup_{j \geq j_0} 2^{(\frac{3}{p}-1)j} \|\Delta_j \phi_\varepsilon\|_{L^p} \leq C 2^{(\frac{3}{p}-1)j_0} \leq C \varepsilon^{1-\frac{3}{p}}.$$

Noting that $e^{i\frac{x_1}{\varepsilon}} = (-i\varepsilon \partial_1)^N e^{i\frac{x_1}{\varepsilon}}$ for any $N \in \mathbb{N}$, we get, by integration by parts,

$$\Delta_j \phi_\varepsilon(x) = (i\varepsilon)^N 2^{3j} \int_{\mathbb{R}^3} e^{i\frac{y_1}{\varepsilon}} \partial_{y_1}^N (h(2^j(x-y))\phi(y)) dy, \quad h(x) := (\mathcal{F}^{-1}\varphi)(x).$$

By the Leibnitz formula, we have

$$|\Delta_j \phi_\varepsilon(x)| \leq C\varepsilon^N 2^{3j} \sum_{k=0}^N 2^{kj} \int_{\mathbb{R}^3} |(\partial_{y_1}^k h)(2^j(x-y))| |\partial_{y_1}^{N-k} \phi(y)| dy,$$

from which, along with Young's inequality, we infer that, for $j \geq 0$,

$$\|\Delta_j \phi_\varepsilon\|_{L^q} \leq C\varepsilon^N \sum_{k=0}^N 2^{kj} 2^{3j} \|(\partial_{y_1}^k h)(2^j y)\|_{L^1} \|\partial_{y_1}^{N-k} \phi(y)\|_{L^q} \leq C\varepsilon^N 2^{jN},$$

and for $j \leq 0$,

$$\|\Delta_j \phi_\varepsilon\|_{L^q} \leq C\varepsilon^N \sum_{k=0}^N 2^{kj} 2^{3j} \|(\partial_{y_1}^k h)(2^j y)\|_{L^q} \|\partial_{y_1}^{N-k} \phi(y)\|_{L^1} \leq C\varepsilon^N 2^{(1-\frac{1}{q})3j}.$$

Thus we have

$$\begin{aligned} \sup_{\Omega < 2^j < 2^{j_0}} 2^{(\frac{3}{p}-1)j} \|\Delta_j \phi_\varepsilon\|_{L^p} &\leq C\varepsilon^N 2^{(N-1+\frac{3}{p})j_0} \leq C\varepsilon^{1-\frac{3}{p}}, \\ \sup_{2^j \leq \Omega} 2^{\frac{j}{2}} \|\Delta_j \phi_\varepsilon\|_{L^2} &\leq C\Omega^{\frac{1}{2}} \varepsilon^N \leq C\varepsilon^{N-\frac{1}{2}}. \end{aligned}$$

Summing up the above estimates yields that

$$\|\phi_\varepsilon\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq C\varepsilon^{1-\frac{3}{p}}.$$

The proof of Proposition 2.4 is completed. \square

3. Regularizing effect of the Stokes–Coriolis semigroup

We consider the linear system

$$(3-1) \quad \begin{cases} u_t - v\Delta u + \Omega e_3 \times u + \nabla p = 0, \\ \operatorname{div} u = 0, \\ u(0, x) = u_0(x). \end{cases}$$

From [Giga et al. 2005; Hieber and Shibata 2010, Proposition 2.1], we know that

$$(3-2) \quad \hat{u}(t, \xi) = \cos\left(\Omega \frac{\xi_3}{|\xi|} t\right) e^{-v|\xi|^2 t} I \hat{u}_0(\xi) + \sin\left(\Omega \frac{\xi_3}{|\xi|} t\right) e^{-v|\xi|^2 t} R(\xi) \hat{u}_0(\xi),$$

for $t \geq 0$ and $\xi \in \mathbb{R}^3$, where I is the identity matrix and

$$R(\xi) = \begin{pmatrix} 0 & \xi_3/|\xi| & -\xi_2/|\xi| \\ -\xi_3/|\xi| & 0 & \xi_1/|\xi| \\ \xi_2/|\xi| & -\xi_1/|\xi| & 0 \end{pmatrix}.$$

The Stokes–Coriolis semigroup is explicitly represented by

$$(3-3) \quad \mathcal{G}(t)f = [\cos(\Omega R_3 t)I + \sin(\Omega R_3 t)R]e^{vt\Delta}f, \quad \text{for } t \geq 0, f \in L_\sigma^p,$$

where $\widehat{R_3 f}(\xi) := (\xi_3/|\xi|)\hat{f}(\xi)$ for $\xi \neq 0$.

Proposition 3.1 (smoothing effect of the Stokes–Coriolis semigroup). *Let \mathcal{C} be a ring centered at 0 in \mathbb{R}^3 . Then there exist positive constants c and C depending only on v such that if $\operatorname{supp} \hat{u} \subset \lambda \mathcal{C}$, then we have:*

(i) *for any $\lambda > 0$,*

$$(3-4) \quad \|\mathcal{G}(t)u\|_{L^2} \leq Ce^{-c\lambda^2 t} \|u\|_{L^2};$$

(ii) *if $\lambda \gtrsim \Omega$, then, for any $1 \leq p \leq \infty$,*

$$(3-5) \quad \|\mathcal{G}(t)u\|_{L^p} \leq Ce^{-c\lambda^2 t} \|u\|_{L^p}.$$

Proof. (i) Thanks to (3-2) and the Plancherel theorem, we get

$$\|\mathcal{G}(t)u\|_{L^2} = \|\hat{\mathcal{G}}(t, \xi)\hat{u}(\xi)\|_{L^2} \leq C \|e^{-v|\xi|^2 t} \hat{u}(\xi)\|_2 \leq Ce^{-v\lambda^2 t} \|u\|_2,$$

where we have used the support property of $\hat{u}(\xi)$.

(ii) Let $\phi \in \mathcal{D}(\mathbb{R}^3 \setminus \{0\})$, which equals 1 near the ring \mathcal{C} . Set

$$g(t, x) := (2\pi)^{-3} \int_{\mathbb{R}^3} e^{ix \cdot \xi} \phi(\lambda^{-1}\xi) \hat{\mathcal{G}}(t, \xi) d\xi.$$

To prove (3-5), it suffices to show

$$(3-6) \quad \|g(x, t)\|_{L^1} \leq Ce^{-c\lambda^2 t}.$$

Thanks to (3-3), we infer that

$$(3-7) \quad \int_{|x| \leq \lambda^{-1}} |g(x, t)| dx \leq C \int_{|x| \leq \lambda^{-1}} \int_{\mathbb{R}^3} |\phi(\lambda^{-1}\xi)| |\hat{\mathcal{G}}(t, \xi)| d\xi dx \leq C e^{-c\lambda^2 t}.$$

Set $L := x \cdot \nabla_{\xi} / (i|x|^2)$. Noting that $L(e^{ix \cdot \xi}) = e^{ix \cdot \xi}$, we get, using integration by parts,

$$g(x, t) = \int_{\mathbb{R}^3} L^N(e^{ix \cdot \xi}) \phi(\lambda^{-1}\xi) \hat{\mathcal{G}}(t, \xi) d\xi = \int_{\mathbb{R}^3} e^{ix \cdot \xi} (L^*)^N(\phi(\lambda^{-1}\xi) \hat{\mathcal{G}}(t, \xi)) d\xi,$$

where $N \in \mathbb{N}$ is chosen later. Using the Leibnitz formula, it is easy to verify that

$$|\partial^\gamma(e^{\pm i\Omega \frac{\xi_3}{|\xi|} t})| \leq C |\xi|^{-|\gamma|} (1 + \Omega t)^{|\gamma|}, \quad |\partial^\gamma(e^{-\nu|\xi|^2 t})| \leq C |\xi|^{-|\gamma|} e^{-\frac{\nu}{2}|\xi|^2 t}.$$

Thus we obtain

$$\begin{aligned} & |(L^*)^N(\phi(\lambda^{-1}\xi) \hat{\mathcal{G}}(t, \xi))| \\ & \leq C |x|^{-N} \sum_{\substack{|\alpha_1|+|\alpha_2| \\ +|\alpha_3|=|\alpha| \\ |\alpha|\leq N}} \lambda^{-N+\alpha} |(\nabla^{N-\alpha} \phi)(\lambda^{-1}\xi) \partial^{\alpha_1}(e^{\pm i\Omega \frac{\xi_3}{|\xi|} t}) \partial^{\alpha_2}(e^{-\nu|\xi|^2 t}) \partial^{\alpha_3}(I + R(\xi))| \\ & \leq C |\lambda x|^{-N} \sum_{\substack{|\alpha_1|+|\alpha_2| \\ +|\alpha_3|=|\alpha| \\ |\alpha|\leq N}} \lambda^\alpha |(\nabla^{N-\alpha} \phi)(\lambda^{-1}\xi)| |\xi|^{-|\alpha_1|-|\alpha_2|-|\alpha_3|} e^{-\frac{\nu}{2}|\xi|^2 t} (1 + \Omega t)^{|\alpha_1|}. \end{aligned}$$

Taking $N = 4$, for any $\xi \in \{\xi : A^{-1}\lambda \leq |\xi| \leq A\lambda\}$ and for some constant A depending on the ring \mathcal{C} and $\lambda \gtrsim \Omega$,

$$|(L^*)^4(\phi(\lambda^{-1}\xi) \hat{\mathcal{G}}(t, \xi))| \leq C |\lambda x|^{-4} e^{-\frac{\nu}{4}|\xi|^2 t},$$

which implies that

$$\int_{|x| \geq \frac{1}{\lambda}} |g(x, t)| dx \leq C e^{-c\lambda^2 t} \lambda^3 \int_{|x| \geq \frac{1}{\lambda}} |\lambda x|^{-4} dx \leq C e^{-c\lambda^2 t},$$

which, together with (3-7), gives (3-6). Then the inequality (3-5) is proved. \square

The following proposition is a direct consequence of Proposition 3.1.

Proposition 3.2. *Let $s, \sigma \in \mathbb{R}$, and $(p, q) \in [1, \infty]$. Then, for any $u \in \dot{\mathcal{B}}_{2,p}^{s-\frac{2}{q}, \sigma-\frac{2}{q}}$, we have*

$$(3-8) \quad \|\mathcal{G}(t)u\|_{\tilde{L}_T^q(\dot{\mathcal{B}}_{2,p}^{s,\sigma})} \leq C \|u\|_{\dot{\mathcal{B}}_{2,p}^{s-\frac{2}{q}, \sigma-\frac{2}{q}}},$$

and for any $f \in \tilde{L}_T^1(\dot{\mathcal{B}}_{2,p}^{s,\sigma})$, we have

$$(3-9) \quad \left\| \int_0^t \mathcal{G}(t-\tau) f(\tau) d\tau \right\|_{\tilde{L}_T^q(\dot{\mathcal{B}}_{2,p}^{s+\frac{2}{q}, \sigma+\frac{2}{q}})} \leq C \|f(t)\|_{\tilde{L}_T^1(\dot{\mathcal{B}}_{2,p}^{s,\sigma})}.$$

Proof. Here we only prove (3-9). For any $2^j \geq \Omega$, we get by Proposition 3.1 that

$$\left\| \Delta_j \int_0^t \mathcal{G}(t-\tau) f(\tau) d\tau \right\|_{L^p} \leq C \int_0^t e^{-c(t-\tau)2^{2j}} \|\Delta_j f(\tau)\|_{L^p} d\tau,$$

from which, along with Young's inequality, it follows that

$$(3-10) \quad \begin{aligned} \left\| \Delta_j \int_0^t \mathcal{G}(t-\tau) f(\tau) d\tau \right\|_{L_T^q L^p} &\leq C \|e^{-ct2^{2j}}\|_{L_T^q} \|\Delta_j f(\tau)\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{2}{q}j} \|\Delta_j f(\tau)\|_{L_T^1 L^p}. \end{aligned}$$

Similarly, we also have

$$\begin{aligned} \left\| \Delta_j \int_0^t \mathcal{G}(t-\tau) f(\tau) d\tau \right\|_{L_T^q L^2} &\leq C \|e^{-ct2^{2j}}\|_{L_T^q} \|\Delta_j f(\tau)\|_{L_T^1 L^2} \\ &\leq C 2^{-\frac{2}{q}j} \|\Delta_j f(\tau)\|_{L_T^1 L^2}. \end{aligned}$$

Then the inequality (3-9) follows from (3-10) and (3-11). \square

4. Bilinear estimates

We study the continuity of the inhomogeneous term in the space $E_{p,T}$ whose norm is defined by

$$\|u\|_{E_{p,T}} := \|u\|_{\tilde{L}^\infty(0,T; \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1})} + \|u\|_{\tilde{L}^1(0,T; \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1})}.$$

We define

$$B(u, v) := \int_0^t \mathcal{G}(t-\tau) \mathbb{P} \nabla \cdot (u \otimes v) d\tau,$$

where \mathbb{P} denotes the Helmholtz projection which is bounded in the L^p space for $1 < p < \infty$.

Proposition 4.1. *Let $p \in [2, 4]$. Assume that $u, v \in E_{p,T}$. There exists a constant C independent of Ω, u, v such that, for any $T > 0$,*

$$(4-1) \quad \|B(u, v)\|_{E_{p,T}} \leq C \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

Proof. Thanks to Proposition 3.2, it suffices to show that

$$(4-2) \quad \|uv\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{3}{2}, \frac{3}{p}}} \leq C \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

From Bony's decomposition (2-2) and (2-1), we have

$$\begin{aligned} \Delta_j(uv) &= \sum_{|k-j| \leq 4} \Delta_j(S_{k-1}u \Delta_k v) + \sum_{|k-j| \leq 4} \Delta_j(S_{k-1}v \Delta_k u) + \sum_{k \geq j-2} \Delta_j(\Delta_k u \tilde{\Delta}_k v) \\ &=: I_j + II_j + III_j. \end{aligned}$$

Set $J_j := \{(k', k) : |k - j| \leq 4, k' \leq k - 2\}$. Then for $2^j > \Omega$,

$$\begin{aligned} \|I_j\|_{L_T^1 L^p} &\leq \sum_{J_j} \|\Delta_j(\Delta_{k'} u \Delta_k v)\|_{L_T^1 L^p} \\ &\leq \left(\sum_{J_{j,11}} + \sum_{J_{j,1h}} + \sum_{J_{j,hh}} \right) \|\Delta_j(\Delta_{k'} u \Delta_k v)\|_{L_T^1 L^p} := I_{j,1} + I_{j,2} + I_{j,3}, \end{aligned}$$

where

$$J_{j,11} = \{(k', k) \in J_j : 2^{k'} \leq \Omega, 2^k \leq \Omega\},$$

$$J_{j,1h} = \{(k', k) \in J_j : 2^{k'} \leq \Omega, 2^k > \Omega\},$$

$$J_{j,hh} = \{(k', k) \in J_j : 2^{k'} > \Omega, 2^k > \Omega\}.$$

We get by using [Lemma 2.3](#) that

$$\begin{aligned} I_{j,1} &\leq C \sum_{(k', k) \in J_{j,11}} \|\Delta_{k'} u\|_{L_T^\infty L^\infty} 2^{k(\frac{3}{2} - \frac{3}{p})} \|\Delta_k v\|_{L_T^1 L^2} \\ &\leq C \sum_{(k', k) \in J_{j,11}} 2^{\frac{k'}{2}} \|\Delta_{k'} u\|_{L_T^\infty L^2} 2^{k'} \|\Delta_k v\|_{L_T^1 L^2} 2^{k(\frac{3}{2} - \frac{3}{p})} \\ &\leq C \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_2^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_2^{\frac{5}{2}, \frac{3}{p}+1}} \sum_{(k', k) \in J_{j,11}} 2^{(k'-k)} 2^{-\frac{3}{p}k} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_2^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_2^{\frac{5}{2}, \frac{3}{p}+1}}, \end{aligned}$$

where we used in the last inequality the fact that

$$\sum_{(k', k) \in J_{j,11}} 2^{(k'-k)} 2^{-\frac{3}{p}k} \leq \sum_{k' \leq k-2} 2^{(k'-k)} \sum_{|k-j| \leq 4} 2^{-\frac{3}{p}k} \leq C 2^{-\frac{3}{p}j},$$

with C independent of j . Similarly, we have

$$\begin{aligned} I_{j,2} &\leq \sum_{(k', k) \in J_{j,1h}} \|\Delta_{k'} u\|_{L_T^\infty L^\infty} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C \sum_{(k', k) \in J_{j,1h}} 2^{\frac{k'}{2}} \|\Delta_{k'} u\|_{L_T^\infty L^2} 2^{k'} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_2^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_2^{\frac{5}{2}, \frac{3}{p}+1}} \end{aligned}$$

and

$$\begin{aligned} I_{j,3} &\leq \sum_{(k',k) \in J_{j,hh}} \|\Delta_{k'} u\|_{L_T^\infty L^\infty} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C \sum_{(k',k) \in J_{j,hh}} 2^{k'(\frac{3}{p}-1)} \|\Delta_{k'} u\|_{L_T^\infty L^p} 2^{k'} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}}. \end{aligned}$$

On the other hand, for $2^j \leq \Omega$, we have

$$\begin{aligned} \|I_j\|_{L_T^1 L^2} &\leq \sum_{J_j} \|\Delta_j (\Delta_{k'} u \Delta_k v)\|_{L_T^1 L^2} \\ &\leq \left(\sum_{J_{j,II}} + \sum_{J_{j,Ih}} + \sum_{J_{j,hh}} \right) \|\Delta_j (\Delta_{k'} u \Delta_k v)\|_{L_T^1 L^2} := I_{j,4} + I_{j,5} + I_{j,6}. \end{aligned}$$

We get by using Lemma 2.3 that

$$\begin{aligned} I_{j,4} &\leq C \sum_{(k,k') \in J_{j,II}} 2^{\frac{k'}{2}} \|\Delta_{k'} u\|_{L_T^\infty L^2} 2^{k'} \|\Delta_k v\|_{L_T^1 L^2} \\ &\leq C 2^{-\frac{3j}{2}} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}}, \end{aligned}$$

and, noting that $p \leq 4$,

$$\begin{aligned} I_{j,5} &\leq C \sum_{(k,k') \in J_{j,Ih}} \|\Delta_{k'} u\|_{L_T^\infty L^{\frac{2p}{p-2}}} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C \sum_{(k,k') \in J_{j,Ih}} 2^{\frac{k'}{2}} \|\Delta_{k'} u\|_{L_T^\infty L^2} 2^{k'(\frac{3}{p}-\frac{1}{2})} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{3j}{2}} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}}, \end{aligned}$$

and

$$\begin{aligned} I_{j,6} &\leq C \sum_{(k,k') \in J_{j,hh}} \|\Delta_{k'} u\|_{L_T^\infty L^{\frac{2p}{p-2}}} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C \sum_{(k,k') \in J_{j,hh}} 2^{k'(\frac{3}{p}-1)} \|\Delta_{k'} u\|_{L_T^\infty L^p} 2^{k'(\frac{3}{p}-\frac{1}{2})} \|\Delta_k v\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{3j}{2}} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}}. \end{aligned}$$

Summing up the estimates for $I_{j,1}$ through $I_{j,6}$ yields that

$$(4.3) \quad \sup_{2^j > 1} 2^{j\frac{3}{p}} \|I_j\|_{L_T^1 L^p} + \sup_{2^j \leq 1} 2^{\frac{3j}{2}} \|I_j\|_{L_T^1 L^2} \leq C \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

By the same procedure as the one used to derive (4-3), we have

$$(4-4) \quad \sup_{2^j > 1} 2^{j\frac{3}{p}} \|II_j\|_{L_T^1 L^p} + \sup_{2^j \leq 1} 2^{\frac{3j}{2}} \|II_j\|_{L_T^1 L^2} \leq C \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

Set $K_j := \{(k, k') : k \geq j - 3, |k' - k| \leq 1\}$. Then we have

$$III_j = \left(\sum_{K_{j,1l}} + \sum_{K_{j,1h}} + \sum_{K_{j,hl}} + \sum_{K_{j,hh}} \right) \Delta_j (\Delta_k u \Delta_{k'} v) := III_{j,1} + III_{j,2} + III_{j,3} + III_{j,4},$$

where

$$K_{j,1l} = \{(k, k') \in K_j : 2^k \leq \Omega, 2^{k'} \leq \Omega\},$$

$$K_{j,1m} = \{(k, k') \in K_j : 2^k \leq \Omega, 2^{k'} > \Omega\},$$

$$K_{j,hm} = \{(k, k') \in K_j : 2^k > \Omega, 2^{k'} \leq \Omega\},$$

$$K_{j,hh} = \{(k, k') \in K_j : 2^k > \Omega, 2^{k'} > \Omega\}.$$

We get by Lemma 2.3 that

$$\begin{aligned} \|III_{j,1}\|_{L_T^1 L^p} &\leq C 2^{3j(1-\frac{1}{p})} \sum_{(k,k') \in K_{j,1l}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^1} \\ &\leq C 2^{3j(1-\frac{1}{p})} \sum_{(k,k') \in K_{j,1l}} 2^{\frac{k}{2}} \|\Delta_k u\|_{L_T^\infty L^2} 2^{-\frac{k}{2}} 2^{k'\frac{5}{2}} \|\Delta_{k'} v\|_{L_T^1 L^2} 2^{-k'\frac{5}{2}} \\ &\leq C 2^{3j(1-\frac{1}{p})} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}} \sum_{(k,k') \in K_{j,1l}} 2^{-\frac{k}{2}-\frac{5}{2}k'} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{\tilde{L}_T^\infty \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \|v\|_{\tilde{L}_T^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}} \sum_{k \geq j-3} 2^{-3(k-j)} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}, \end{aligned}$$

and

$$\|III_{j,1}\|_{L_T^1 L^2} \leq C 2^{\frac{3j}{2}} \sum_{(k,k') \in K_{j,1l}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^1} \leq C 2^{-\frac{3j}{2}} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

Similarly, we obtain

$$\begin{aligned} &\|III_{j,2} + III_{j,3}\|_{L_T^1 L^p} \\ &\leq C 2^{\frac{3j}{2}} \sum_{(k,k') \in K_{j,1h} \cup K_{j,hl}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^{\frac{2p}{2+p}}} \\ &\leq C 2^{\frac{3j}{2}} \left(\sum_{K_{j,1h}} \|\Delta_k u\|_{L_T^\infty L^2} \|\Delta_{k'} v\|_{L_T^1 L^p} + \sum_{K_{j,hl}} \|\Delta_k u\|_{L_T^1 L^p} \|\Delta_{k'} v\|_{L_T^\infty L^2} \right) \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}} \end{aligned}$$

and

$$\begin{aligned} \|III_{j,2} + III_{j,3}\|_{L_T^1 L^2} &\leq C 2^{\frac{3}{p}j} \sum_{(k,k') \in K_{j,lh} \cup K_{j,hl}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^{\frac{2p}{2+p}}} \\ &\leq C 2^{-\frac{3j}{2}} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}. \end{aligned}$$

Finally, due to $2 \leq p \leq 4$, we have

$$\begin{aligned} \|III_{j,4}\|_{L_T^1 L^p} &\leq C 2^{\frac{3}{p}j} \sum_{(k,k') \in K_{j,hh}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^{\frac{p}{2}}} \\ &\leq C 2^{\frac{3}{p}j} \sum_{(k,k') \in K_{j,hh}} \|\Delta_k u\|_{L_T^\infty L^p} \|\Delta_{k'} v\|_{L_T^1 L^p} \\ &\leq C 2^{-\frac{3}{p}j} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}, \end{aligned}$$

and

$$\|III_{j,4}\|_{L_T^1 L^2} \leq C 2^{3j(\frac{2}{p}-\frac{1}{2})} \sum_{(k,k') \in K_{j,hh}} \|\Delta_k u \Delta_{k'} v\|_{L_T^1 L^{\frac{p}{2}}} \leq C 2^{-\frac{3j}{2}} \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

Summing up the estimates of $III_{j,1} - III_{j,4}$, we obtain

$$(4-5) \quad \sup_{2^j > 1} 2^{\frac{3}{p}j} \|III_j\|_{L_T^1 L^p} + \sup_{2^j \leq 1} 2^{\frac{3j}{2}} \|III_j\|_{L_T^1 L^2} \leq C \|u\|_{E_{p,T}} \|v\|_{E_{p,T}}.$$

Then the inequality (4-2) can be deduced from (4-3)–(4-5). \square

In order to prove the uniqueness of the solution in $C(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})$, we establish the following new bilinear estimate in the weighted time-space Besov space introduced in [Chen et al. 2008; 2010b].

Proposition 4.2. *Assume that $u, v \in L_T^\infty(\dot{B}_{2,\infty}^{\frac{1}{2}})$. Then, for any $T > 0$, we have*

$$\|B(u, v)\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \leq C \|u\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \|\omega_{j,T} 2^{\frac{j}{2}} \|\Delta_j v\|_{L_T^\infty L^2}\|_{l^\infty},$$

where

$$\omega_{j,T} := \sup_{k \geq j} e_{k,T} 2^{\frac{1}{2}(j-k)}, \quad e_{j,T} := 1 - e^{-c2^{2j}T}.$$

Remark 4.3. The inequality $e_{j,T} \leq \omega_{j,T}$ (top of page 277) is important to the following estimates. On the other hand, due to the fact $\lim_{T \rightarrow 0} \omega_{j,T} = 0$, it can be proved that if $u \in C([0, T]; \dot{H}^{\frac{1}{2}})$, then, for any $\varepsilon > 0$, one has

$$\|\omega_{j,T} 2^{\frac{j}{2}} \|\Delta_j v\|_{L_T^\infty L^2}\|_{l^\infty} < \varepsilon \quad \text{if } T \text{ is small enough.}$$

This point is important in the proof of uniqueness.

Proof. First we note that $e_{j,T} \leq \omega_{j,T}$ for any $j \in \mathbb{Z}$ and that

$$(4-6) \quad \omega_{j,T} \leq 2^{\frac{1}{2}(j-j')} \omega_{j',T} \quad \text{if } j' \leq j, \quad \omega_{j,T} \leq 2\omega_{j',T} \quad \text{if } j \leq j'.$$

We get by Proposition 3.1 that

$$\begin{aligned} (4-7) \quad \|B(u, v)\|_{\dot{B}_{2,\infty}^{\frac{1}{2}}} &\leq \sup_{j \in \mathbb{Z}} 2^{\frac{j}{2}} \int_0^t \|\mathcal{G}(t-\tau) \Delta_j \mathbb{P} \nabla \cdot (u \otimes v)\|_{L^2} d\tau \\ &\leq \sup_{j \in \mathbb{Z}} 2^{\frac{3j}{2}} \|e^{-c2^{2j}t}\|_{L_T^1} \|\Delta_j(u \otimes v)\|_{L_T^\infty L^2} \\ &\leq C \sup_{j \in \mathbb{Z}} 2^{-\frac{j}{2}} e_{j,T} \|\Delta_j(uv)\|_{L_T^\infty L^2}. \end{aligned}$$

We use Bony's decomposition to estimate $\|\Delta_j(uv)\|_{L_T^\infty L^2}$. Since $e_{j,T} \leq \omega_{j,T}$ and thanks to (4-6), we have

$$\begin{aligned} (4-8) \quad \sum_{|k-j| \leq 4} \|\Delta_j(S_{k-1}u \Delta_k v)\|_{L_T^\infty L^2} &\leq C \|u\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \sum_{|k-j| \leq 4} 2^k \|\Delta_k v\|_{L_T^\infty L^2} \\ &\leq C \omega_{j,T}^{-1} 2^{\frac{j}{2}} \|u\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \|\omega_{k,T} 2^{\frac{k}{2}} \|\Delta_k v\|_{L_T^\infty L^2}\|_{l^\infty}, \end{aligned}$$

and, again by the same properties of $\omega_{j,T}$,

$$\begin{aligned} \|S_{k-1}v\|_{L^\infty} &\leq \sum_{k' \leq k-2} \|\Delta_{k'}v\|_{L^2} 2^{\frac{3}{2}k'} \leq \|\omega_{k',T} 2^{\frac{k'}{2}} \|\Delta_{k'}v\|_{L_T^\infty L^2}\|_{l^\infty} \sum_{k' \leq k-2} 2^{k'} \omega_{k',T}^{-1} \\ &\leq 2^k \omega_{k,T}^{-1} \|\omega_{k',T} 2^{\frac{k'}{2}} \|\Delta_{k'}v\|_{L_T^\infty L^2}\|_{l^\infty}, \end{aligned}$$

which implies that

$$\begin{aligned} (4-9) \quad \sum_{|k-j| \leq 4} \|\Delta_j(S_{k-1}v \Delta_k u)\|_{L_T^\infty L^2} &\leq 2^{\frac{k}{2}} \omega_{k,T}^{-1} \|u\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \|\omega_{k',T} 2^{\frac{k'}{2}} \|\Delta_{k'}v\|_{L_T^\infty L^2}\|_{l^\infty}, \end{aligned}$$

and for the remainder term,

$$\begin{aligned} (4-10) \quad \sum_{k \geq j-2} \|\Delta_j(\Delta_k u \tilde{\Delta}_k v)\|_{L_T^\infty L^2} &\leq \sum_{k \geq j-2} 2^{\frac{3}{2}j} \|\Delta_j(\Delta_k u \tilde{\Delta}_k v)\|_{L_T^\infty L^1} \\ &\leq C \sum_{k \geq j-2} 2^{\frac{3}{2}j} \|\Delta_k u\|_{L_T^\infty L^2} \|\tilde{\Delta}_k v\|_{L_T^\infty L^2} \\ &\leq C \omega_{j,T}^{-1} 2^{\frac{j}{2}} \|u\|_{L_T^\infty \dot{B}_{2,\infty}^{\frac{1}{2}}} \|\omega_{k,T} 2^{\frac{k}{2}} \|\Delta_k v\|_{L_T^\infty L^2}\|_{l^\infty}. \end{aligned}$$

Substituting (4-8)–(4-10) into (4-7) concludes the proof. \square

5. Proofs of Theorem 1.4 and Theorem 1.8

The proof of [Theorem 1.4](#) is based on the following classical lemma.

Lemma 5.1 [Cannone 1995]. *Let X be an abstract Banach space and $B : X \times X \rightarrow X$ a bilinear operator, $\|\cdot\|$ being the X -norm, such that for any $x_1 \in X$ and $x_2 \in X$, we have*

$$\|B(x_1, x_2)\| \leq \eta \|x_1\| \|x_2\|.$$

Then for any $y \in X$ such that

$$4\eta \|y\| < 1,$$

the equation

$$x = y + B(x, x)$$

has a solution x in X . Moreover, this solution x is the only one such that

$$\|x\| \leq \frac{1 - \sqrt{1 - 4\eta \|y\|}}{2\eta}.$$

Proof of Theorem 1.4. Using the Stokes–Coriolis semigroup, we rewrite the system [\(1-1\)](#) as the integral form

$$(5-1) \quad u(x, t) = \mathcal{G}(t)u_0 - \int_0^t \mathcal{G}(t-\tau) \mathbb{P} \nabla \cdot (u \otimes u) d\tau := \mathcal{G}(t)u_0 + B(u, u).$$

Thanks to [Proposition 3.2](#), we have

$$\|\mathcal{G}(t)u_0\|_{E_p} \leq C \|u_0\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq Cc.$$

Obviously, $B(u, v)$ is bilinear, and we get by [Proposition 4.1](#) that

$$\|B(u, v)\|_{E_p} \leq C \|u\|_{E_p} \|v\|_{E_p}.$$

Taking c such that $4C^2c < \frac{3}{4}$, [Lemma 5.1](#) ensures that the equation

$$u = \mathcal{G}(t)u_0 + B(u, u)$$

has a unique solution in the ball $\{u \in E_p : \|u\|_{E_p} \leq \frac{1}{4C}\}$. \square

Now we prove [Theorem 1.8](#).

Proof of Theorem 1.8. We introduce a Banach space F_p whose norm is defined by

$$\|u\|_{F_p} := \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})} + \|u\|_{E_p}.$$

Step 1: existence in F_p . We define the map

$$\mathcal{T}u := \mathcal{G}(t)u_0 + B(u, u).$$

Next we prove that, if c is small enough, the map \mathcal{T} has a unique fixed point in the ball

$$B_A := \{u \in F_p : \|u\|_{E_p} \leq Ac, \|u\|_{F_p} \leq A\|u_0\|_{\dot{H}^{\frac{1}{2}}}\},$$

for some $A > 0$ to be determined later. From [Proposition 3.2](#) and [Proposition 4.1](#), we infer that

$$(5-2) \quad \|\mathcal{T}u\|_{E_p} \leq C\|u_0\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} + C\|u\|_{E_p}^2.$$

On the other hand, we get by [Proposition 3.1](#) that

$$\begin{aligned} (5-3) \quad & \|B(u, u)\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})} \\ & \leq \left\| \int_0^t \mathcal{G}(t-\tau) \mathbb{P} \nabla \cdot (u \otimes u)(\tau) d\tau \right\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})} \\ & \leq C \left(\sum_{j \in \mathbb{Z}} 2^j \left(\sup_{t \in \mathbb{R}^+} \int_0^t \|\mathcal{G}(t-\tau) \Delta_j \mathbb{P} \nabla \cdot (u \otimes u)(\tau)\|_{L^2} d\tau \right)^2 \right)^{\frac{1}{2}} \\ & \leq C \left\| 2^{\frac{3}{2}j} \sup_{t \in \mathbb{R}^+} \int_0^t e^{-\tilde{c}2^{2j}t} \|\Delta_j(u \otimes u)\|_{L^2} d\tau \right\|_{l^2}. \end{aligned}$$

In the following, we denote by $\{c_j\}_{j \in \mathbb{Z}}$ a sequence in l^2 with norm $\|\{c_j\}\|_{l^2(\mathbb{Z})} \leq 1$. We get by [Lemma 2.3](#) that

$$\begin{aligned} (5-4) \quad & \sup_{t \in \mathbb{R}^+} \int_0^t e^{-\tilde{c}2^{2j}t} \|\Delta_j(T_u u)\|_{L^2} d\tau \\ & \leq \|e^{-\tilde{c}2^{2j}t}\|_{L^1(\mathbb{R}^+)} \sum_{|k-j| \leq 4} \|\Delta_j(S_{k-1}u \Delta_k u)\|_{L^\infty(\mathbb{R}^+; L^2)} \\ & \leq C 2^{-2j} \|S_{k-1}u\|_{L^\infty(\mathbb{R}^+; L^\infty)} \sum_{|k-j| \leq 4} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\ & \leq C \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1})} 2^k 2^{-2j} \sum_{|k-j| \leq 4} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\ & \leq C 2^{-\frac{3}{2}j} \|u\|_{E_p} \sum_{|k-j| \leq 4} 2^{\frac{(k-j)}{2}} 2^{\frac{k}{2}} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\ & \leq C 2^{-\frac{3}{2}j} c_j \|u\|_{E_p} \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})}. \end{aligned}$$

The remainder term of uv is estimated by

$$\begin{aligned}
 (5-5) \quad & \sup_{t \in \mathbb{R}^+} \int_0^t e^{-\tilde{c}2^{2j}t} \|\Delta_j R(u, u)\|_{L^2} d\tau \\
 & \leq \|e^{-\tilde{c}2^{2j}t}\|_{L^\infty(\mathbb{R}^+)} \sum_{k \geq j-2} \|\Delta_j(\Delta_k u \tilde{\Delta}_k u)\|_{L^1(\mathbb{R}^+; L^2)} \\
 & \leq C \sum_{k \geq j-2} \|\tilde{\Delta}_k u\|_{L^1(\mathbb{R}^+; L^\infty)} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\
 & \leq C \|u\|_{\tilde{L}^1 \dot{\mathcal{B}}_{2,p}^{\frac{5}{2}, \frac{3}{p}+1}} \sum_{k \geq j-2} 2^{-k} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\
 & \leq C \|u\|_{E_p} \sum_{k \geq j-2} 2^{-\frac{3}{2}k} 2^{\frac{1}{2}k} \|\Delta_k u\|_{L^\infty(\mathbb{R}^+; L^2)} \\
 & \leq C 2^{-\frac{3}{2}j} c_j \|u\|_{E_p} \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})}.
 \end{aligned}$$

Combining (5-4)–(5-5) with (5-3) yields that

$$\|B(u, u)\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})} \leq C \|u\|_{E_p} \|u\|_{\tilde{L}^\infty(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})}.$$

It is easy to verify that

$$\|\mathcal{G}(t)u_0\|_{\tilde{L}_T^\infty \dot{H}^{\frac{1}{2}}} \leq C \|u_0\|_{\dot{H}^{\frac{1}{2}}}.$$

Consequently by (5-2) and the estimate

$$\|u_0\|_{\dot{\mathcal{B}}_{2,p}^{\frac{1}{2}, \frac{3}{p}-1}} \leq C \|u_0\|_{\dot{H}^{\frac{1}{2}}}$$

(which follows from Lemma 2.3 and the definition of the Besov space), we obtain

$$(5-6) \quad \|\mathcal{T}u\|_{F_p} \leq C \|u_0\|_{\dot{H}^{\frac{1}{2}}} + C \|u\|_{E_p} \|u\|_{F_p}.$$

Taking $A = 2C$ and $c > 0$ such that $2C^2c \leq \frac{1}{2}$, it follows from (5-2) and (5-6) that the map \mathcal{T} is a map from B_A to B_A . Similarly, it can be proved that \mathcal{T} is also a contraction in B_A . Thus, the Banach fixed point theorem ensures that the map \mathcal{T} has a unique fixed point in B_A .

Step 2: uniqueness in $C(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})$. Let u_1 and u_2 be two solutions of (1-1) in $\overline{C(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})}$ with the same initial data u_0 . We consider

$$\begin{aligned}
 u_1 - u_2 &= B(u_1 - \mathcal{G}(t)u_0, u_1 - u_2) + B(\mathcal{G}(t)u_0, u_1 - u_2) \\
 &\quad + B(u_1 - u_2, u_2 - \mathcal{G}(t)u_0) + B(u_1 - u_2, \mathcal{G}(t)u_0).
 \end{aligned}$$

Then we get by [Proposition 4.2](#) that

$$(5-7) \quad \begin{aligned} & \sup_{t \in [0, T]} \| (u_1 - u_2)(t) \|_{\dot{B}_{2,\infty}^{\frac{1}{2}}} \\ & \leq C \sup_{t \in [0, T]} \| (u_1 - u_2)(t) \|_{\dot{B}_{2,\infty}^{\frac{1}{2}}} \left(\| \omega_{j,T} 2^{\frac{j}{2}} \|_{L^\infty} \| \Delta_j u_0 \|_2 \|_{l^\infty} \right. \\ & \quad \left. + \sup_{t \in [0, T]} \| u_1(t) - \mathcal{G}(t)u_0 \|_{\dot{H}^{\frac{1}{2}}} + \sup_{t \in [0, T]} \| u_2(t) - \mathcal{G}(t)u_0 \|_{\dot{H}^{\frac{1}{2}}} \right), \end{aligned}$$

where we used the fact $\omega_{j,T} \leq 1$ so that

$$\| \omega_{j,T} 2^{\frac{j}{2}} \|_{L_T^\infty L^2} \|_{l^\infty} \leq \sup_{t \in [0, T]} \| u(t) \|_{\dot{H}^{\frac{1}{2}}}.$$

Noticing that $\omega_{j,0} = 0$ and $u_0 \in \dot{H}^{\frac{1}{2}}$, we have

$$\| \omega_{j,T} 2^{\frac{j}{2}} \|_{\Delta_j u_0} \|_2 \|_{l^\infty} \leq \frac{1}{3C},$$

for T small enough. On the other hand, since $u_1, u_2 \in C(\mathbb{R}^+; \dot{H}^{\frac{1}{2}})$, we also have

$$\sup_{t \in [0, T]} \| u_1 - \mathcal{G}(t)u_0 \|_{\dot{H}^{\frac{1}{2}}} + \sup_{t \in [0, T]} \| u_2 - \mathcal{G}(t)u_0 \|_{\dot{H}^{\frac{1}{2}}} \leq \frac{1}{3C},$$

for T small enough. Then (5-7) ensures that $u_1(t) = u_2(t)$ for T small enough. Then, by a standard continuity argument, we conclude that $u_1 = u_2$ on $[0, \infty)$. \square

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