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**EIGENVALUE ESTIMATE AND COMPACTNESS  
FOR CLOSED  $f$ -MINIMAL SURFACES**

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## EIGENVALUE ESTIMATE AND COMPACTNESS FOR CLOSED $f$ -MINIMAL SURFACES

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**Let  $\Omega$  be a bounded domain with convex boundary in a complete noncompact Riemannian manifold with Bakry–Émery Ricci curvature bounded below by a positive constant. We prove a lower bound on the first eigenvalue of the weighted Laplacian for closed embedded  $f$ -minimal hypersurfaces contained in  $\Omega$ . Using this estimate, we prove a compactness theorem for the space of closed embedded  $f$ -minimal surfaces with uniform upper bounds on genus and diameter in a complete 3-manifold with Bakry–Émery Ricci curvature bounded below by a positive constant and admitting an exhaustion by bounded domains with convex boundary.**

### 1. Introduction

A hypersurface  $\Sigma$  immersed in a Riemannian manifold  $(M, \bar{g})$  is said to be  $f$ -minimal if its mean curvature  $H$  satisfies, for any  $p \in \Sigma$ ,

$$H = \langle \bar{\nabla} f, \nu \rangle,$$

where  $\nu$  is the unit normal at  $p \in \Sigma$ ,  $f$  is a smooth function defined on  $M$ , and  $\bar{\nabla} f$  denotes the gradient of  $f$  on  $M$ . When  $f$  is a constant function, an  $f$ -minimal hypersurface is just a minimal hypersurface. One nontrivial class of  $f$ -minimal hypersurfaces is that of self-shrinkers. Recall that a self-shrinker (for the mean curvature flow in the Euclidean space  $(\mathbb{R}^{n+1}, g_{\text{can}})$ ) is a hypersurface immersed in  $(\mathbb{R}^{n+1}, g_{\text{can}})$  satisfying

$$H = \frac{1}{2} \langle x, \nu \rangle,$$

where  $x$  is the position vector in  $\mathbb{R}^{n+1}$ . Hence a self-shrinker is an  $f$ -minimal hypersurface  $\Sigma$  with  $f = |x|^2/4$  (see more information on self-shrinkers in [Colding and Minicozzi 2012a] and references therein).

In the study of  $f$ -minimal hypersurfaces, it is convenient to consider the ambient space as a smooth metric measure space  $(M, \bar{g}, e^{-f} d\mu)$ , where  $d\mu$  is the volume

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form of  $\bar{g}$ . For  $(M, \bar{g}, e^{-f} d\mu)$ , an important and natural tensor is the Bakry–Émery Ricci curvature  $\bar{\text{Ric}}_f := \bar{\text{Ric}} + \bar{\nabla}^2 f$ . There are many interesting examples of smooth metric measure spaces  $(M, \bar{g}, e^{-f} d\mu)$  with  $\bar{\text{Ric}}_f \geq k$ , for a positive constant  $k$ . A nontrivial class of examples is the shrinking gradient Ricci solitons. It is known that, after a normalization, a shrinking gradient Ricci soliton  $(M, \bar{g}, f)$  satisfies the equation  $\bar{\text{Ric}} + \bar{\nabla}^2 f = \bar{g}/2$  or, equivalently,  $\bar{\text{Ric}}_f = \frac{1}{2}$ . We refer to [Cao 2010], a survey of this topic where some compact and noncompact examples are explained. Even though the asymptotic growth of the potential function  $f$  of a noncompact shrinking gradient Ricci soliton is the same as that of a Gaussian shrinking soliton [Cao and Zhou 2010], both the geometry and topology can be quite different from known examples. We may consider  $f$ -minimal hypersurfaces in a shrinking gradient Ricci soliton. For instance, a self-shrinker in  $\mathbb{R}^{n+1}$  can be viewed as an  $f$ -minimal hypersurface in the Gaussian shrinking soliton  $(\mathbb{R}^{n+1}, g_{\text{can}}, |x|^2/4)$ .

There are other examples of  $f$ -minimal hypersurfaces. Let  $M$  be the hyperbolic space  $\mathbb{H}^{n+1}(-1)$ . Let  $r$  denote the distance function from a fixed point  $p \in M$  and  $f(x) = nar^2(x)$ , where  $a > 0$  is a constant. Then  $\bar{\text{Ric}}_f \geq n(2a-1)$ , and the geodesic sphere of radius  $r$  centered at  $p$  in  $\mathbb{H}^{n+1}(-1)$  is an  $f$ -minimal hypersurface if it satisfies  $2ar = \coth r$ .

An  $f$ -minimal hypersurface  $\Sigma$  has two aspects to view. One is that  $\Sigma$  is  $f$ -minimal if and only if  $\Sigma$  is a critical point of the weighted volume functional  $e^{-f} d\sigma$ , where  $d\sigma$  is the volume element of  $\Sigma$ . Another one is that  $\Sigma$  is  $f$ -minimal if and only if  $\Sigma$  is minimal in the new conformal metric  $\tilde{g} = e^{-2f/n} \bar{g}$  (see Section 2).  $f$ -minimal hypersurfaces, even more general stationary hypersurfaces for parametric elliptic functionals, have been studied before. See, for instance, the work of White [1987] and Colding and Minicozzi [2002].

In this paper, we will first estimate the lower bound on the first eigenvalue of the weighted Laplacian  $\Delta_f = \Delta - \langle \nabla f, \nabla \cdot \rangle$  for closed (i.e., compact and without boundary) embedded  $f$ -minimal hypersurfaces in a complete metric measure space  $(M, \bar{g}, e^{-f} d\mu)$ . Subsequently using the eigenvalue estimate, we study compactness for the space of closed embedded  $f$ -minimal surfaces in a complete noncompact 3-manifold. To explain our result, we give some background.

Choi and Wang [1983] estimated the lower bound for the first eigenvalue of closed minimal hypersurfaces in a complete Riemannian manifold with Ricci curvature bounded below by a positive constant and proved the following:

**Theorem 1.** *If  $M$  is a simply connected complete Riemannian manifold with Ricci curvature bounded below by a constant  $k > 0$  and  $\Sigma$  is a closed embedded minimal hypersurface, then the first eigenvalue of the Laplacian  $\Delta$  on  $\Sigma$  is at least  $k/2$ .*

Later, using a covering argument, Choi and Schoen [1985] proved that the assumption that  $M$  is simply connected is not needed. Recently Ma and Du [2010]

extended Theorem 1 to the first eigenvalue of the weighted Laplacian  $\Delta_f$  on a closed embedded  $f$ -minimal hypersurface in a simply connected compact manifold with positive Bakry–Émery Ricci curvature  $\overline{\text{Ric}}_f$ . Very recently Li and Wei [2012] also used the covering argument to delete the assumption that the ambient space is simply connected in the result of Ma and Du.

The Bonnet–Myers theorem says that a complete manifold with Ricci curvature bounded below by a positive constant must be compact. But the corresponding result is not true for complete manifolds with Bakry–Émery Ricci curvature  $\overline{\text{Ric}}_f$  bounded below by a positive constant. One example is the Gaussian shrinking soliton  $(\mathbb{R}^{n+1}, g_{\text{can}}, e^{-|x|^2/4} d\mu)$ , with  $\overline{\text{Ric}}_f = \frac{1}{2}$ . Hence the theorems of Ma and Du and Li and Wei cannot be applied to self-shrinkers.

For self-shrinkers, Ding and Xin [2013] recently obtained a lower bound on the first eigenvalue  $\lambda_1(\mathcal{L})$  of the weighted Laplacian  $\mathcal{L} = \Delta - \langle x, \nabla \cdot \rangle / 2$  (i.e.,  $\Delta_f$ ) on a closed  $n$ -dimensional embedded self-shrinker in the Euclidean space  $\mathbb{R}^{n+1}$ , that is,  $\lambda_1(\mathcal{L}) \geq \frac{1}{4}$ .

We will discuss a lower bound for the first eigenvalue of  $\Delta_f$  of a closed embedded  $f$ -minimal hypersurface in the case that the ambient space is complete and noncompact. Precisely, we prove the following:

**Theorem 2.** *Let  $(M^{n+1}, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with Bakry–Émery Ricci curvature  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Sigma$  be a closed embedded  $f$ -minimal hypersurface in  $M$ . If there is a bounded domain  $D$  in  $M$  with convex boundary  $\partial D$  so that  $\Sigma$  is contained in  $D$ , then the first eigenvalue  $\lambda_1(\Delta_f)$  of the weighted Laplacian  $\Delta_f$  on  $\Sigma$  satisfies*

$$(1) \quad \lambda_1(\Delta_f) \geq \frac{k}{2}.$$

Here and below the boundary  $\partial D$  is called convex if, for any  $p \in \partial D$ , the second fundamental form  $A$  of  $\partial D$  at  $p$  is nonnegative with respect to the outer unit normal of  $\partial D$ .

A closed self-shrinker  $\Sigma^n$  in  $\mathbb{R}^{n+1}$  satisfies the assumption of Theorem 2 since there always exists a ball  $D$  of  $\mathbb{R}^{n+1}$  containing  $\Sigma$ . Therefore Theorem 2 implies the result of Ding and Xin for self-shrinkers mentioned before. Also we give a different and hence alternative proof of their result.

**Remark.** If  $M$  is a Cartan–Hadamard manifold, all geodesic balls are convex. If  $M$  is a complete noncompact Riemannian manifold with nonnegative sectional curvature, the work of Cheeger and Gromoll [1972] asserts that  $M$  admits an exhaustion by convex domains.

Choi and Wang [1983] used the lower bound estimate of the first eigenvalue in Theorem 1 to obtain an upper bound on the area of a simply connected closed

embedded minimal surface  $\Sigma$  in a 3-manifold, depending on the genus  $g$  of  $\Sigma$  and the positive lower bound  $k$  of Ricci curvature of  $M$ . Further the lower bound on the first eigenvalue and the upper bound on the area were used in [Choi and Schoen 1985] to prove a smooth compactness theorem for the space of closed embedded minimal surfaces of genus  $g$  in a closed 3-manifold  $M^3$  with positive Ricci curvature. Very recently Li and Wei [2012] proved a compactness theorem for closed embedded  $f$ -minimal surfaces in a compact 3-manifold with Bakry–Émery Ricci curvature  $\overline{\text{Ric}}_f \geq k$ , for a constant  $k > 0$ .

On the other hand, Ding and Xin [2013] recently applied the lower bound estimate of the first eigenvalue of the weighted Laplacian on a self-shrinker to prove a compactness theorem for closed self-shrinkers in  $\mathbb{R}^3$  with uniform bounds on genus and diameter. As was mentioned before, a self-shrinker in  $\mathbb{R}^3$  is an  $f$ -minimal surface in a complete noncompact  $\mathbb{R}^3$  with  $\overline{\text{Ric}}_f \geq \frac{1}{2}$ . Motivated by this example, we consider compactness for  $f$ -minimal surfaces in a complete noncompact manifold. We prove:

**Theorem 3.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Assume that  $M$  admits an exhaustion by bounded domains with convex boundary. Then the space, denoted by  $S_{D,g}$ , of closed embedded  $f$ -minimal surfaces in  $M$  with genus at most  $g$  and diameter at most  $D$  is compact in the  $C^m$  topology, for any  $m \geq 2$ . Namely any sequence in  $S_{D,g}$  has a subsequence that converges in the  $C^m$  topology on compact subsets to a surface in  $S_{D,g}$ , for any  $m \geq 2$ .*

Theorem 3 implies especially the compactness theorem of Ding and Xin for self-shrinkers. We also prove the following compactness theorem, which implies Theorem 3.

**Theorem 4.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Given a bounded domain  $\Omega \subset M$ , let  $S$  be the space of closed embedded  $f$ -minimal surfaces in  $M$  with genus at most  $g$  and contained in the closure  $\bar{\Omega}$ . If there is a bounded domain  $U \subset M$  with convex boundary so that  $\bar{\Omega} \subset U$ , then  $S$  is compact in the  $C^m$  topology, for any  $m \geq 2$ . Namely any sequence in  $S$  has a subsequence that converges in the  $C^m$  topology on compact subsets to a surface in  $S$ , for any  $m \geq 2$ .*

If  $M$  admits an exhaustion by bounded domains with convex boundary, such  $U$  as in Theorem 4 always exists. Also the assumption that  $f$ -minimal surfaces are contained in the closure of a bounded domain  $\Omega$  in Theorem 4 is equivalent to there being a uniform upper bound on the extrinsic diameter of  $f$ -minimal surfaces (see remark on page 361).

We mention that, for self-shrinkers in  $\mathbb{R}^3$ , Colding and Minicozzi [2012b] proved a smooth compactness theorem for complete embedded self-shrinkers with uniform

upper bound on genus and uniform scale-invariant area growth. In [Cheng et al. 2012], we generalized their result to the complete embedded  $f$ -minimal surfaces in a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , for a constant  $k > 0$ .

Theorems 3 and 4 have some immediate corollaries. First they imply the corresponding compactness theorems for embedded closed  $f$ -minimal surfaces of fixed topological type and bounded diameter; see Theorems 7 and 8. Second, by using an argument as in [Choi and Schoen 1985], we have the following uniform curvature estimates:

**Corollary of Theorem 3.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Assume that  $M$  admits an exhaustion by bounded domains with convex boundary. Then, for any integer  $g$  and a positive constant  $D$ , there exists a constant  $C$  depending only on  $M$ ,  $g$  and  $D$  such that if  $\Sigma$  is a closed embedded  $f$ -minimal surface of genus  $g$  and diameter at most  $D$  in  $M$ , the norm  $|A|$  of the second fundamental form of  $\Sigma$  satisfies*

$$\max_{x \in \Sigma} |A| \leq C.$$

**Corollary of Theorem 4.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Omega$  be a bounded domain whose closure is contained in a bounded domain  $U$  with convex boundary. Then, for any integer  $g$ , there exists a constant  $C$  depending only on  $U$ ,  $g$  such that if  $\Sigma$  is a closed embedded  $f$ -minimal surface of genus  $g$  contained in  $\overline{\Omega}$ , the norm  $|A|$  of the second fundamental form of  $\Sigma$  satisfies*

$$\max_{x \in \Sigma} |A| \leq C.$$

An argument similar to the proof of Theorem 2 also works for the case where the ambient space is a compact manifold with convex boundary. Hence we have the following estimate:

**Theorem 5.** *Let  $(M^{n+1}, \bar{g})$  be a simply connected compact manifold with convex boundary  $\partial M$  and  $f$  a nonconstant smooth function on  $M$ . Assume that  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. If  $\Sigma$  is a closed  $f$ -minimal hypersurface embedded in  $M$  and does not intersect the boundary  $\partial M$ , then the first eigenvalue of the weighted Laplacian on  $\Sigma$  satisfies*

$$(2) \quad \lambda_1(\Delta_f) \geq \frac{k}{2}.$$

Here we give a remark: the assumption in Theorem 5 that  $f$  is a nonconstant smooth function on  $M$  is necessary. The reason is that under the assumption

$\overline{\text{Ric}} \geq k > 0$ , any closed minimal hypersurface  $\Sigma$  must intersect the convex boundary  $\partial M$  by a standard argument similar to the one in Frankel’s intersection theorem.

The rest of this paper is organized as follows: In Section 2, some definitions and notation are given. In Section 3, we give some facts which will be used later. In Section 4, we prove Theorems 2 and 5. In Section 6, we prove Theorems 3 and 4. For completeness, we give in an appendix the proof of the known Reilly formula for a weighted metric measure space.

### 2. Definitions and notation

In general, a smooth metric measure space, denoted by  $(N, g, e^{-w} d\text{vol})$ , is a Riemannian manifold  $(N, g)$  together with a weighted volume form  $e^{-w} d\text{vol}$  on  $N$ , where  $w$  is a smooth function on  $N$  and  $d\text{vol}$  the volume element induced by the Riemannian metric  $g$ . The associated weighted Laplacian  $\Delta_w$  is defined by

$$\Delta_w u := \Delta u - \langle \nabla w, \nabla u \rangle,$$

where  $\Delta$  and  $\nabla$  are the Laplacian and gradient on  $(N, g)$ , respectively.

The second-order operator  $\Delta_w$  is a self-adjoint operator on the space of square integrable functions on  $N$  with respect to the measure  $e^{-w} d\text{vol}$ . For a closed manifold  $N$ , the first eigenvalue of  $\Delta_w$ , denoted by  $\lambda_1(\Delta_w)$ , is the lowest nonzero real number  $\lambda_1$  satisfying

$$\Delta_w u = -\lambda_1 u, \quad \text{on } N.$$

It is well known that the definition of  $\lambda_1(\Delta_w)$  is equivalent to

$$\lambda_1(\Delta_w) = \inf_{\substack{\int_N u e^{-w} d\text{vol} = 0 \\ u \neq 0}} \frac{\int_N |\nabla u|^2 e^{-w} d\text{vol}}{\int_N u^2 e^{-w} d\text{vol}}.$$

The  $\infty$ -Bakry–Émery Ricci curvature tensor  $\text{Ric}_w$  (for simplicity, Bakry–Émery Ricci curvature) on  $(N, g, e^{-w} d\text{vol})$  is defined by

$$\text{Ric}_w := \text{Ric} + \nabla^2 w,$$

where  $\text{Ric}$  denotes the Ricci curvature of  $(N, g)$  and  $\nabla^2 w$  is the Hessian of  $w$  on  $N$ . If  $w$  is constant,  $\Delta_w$  and  $\text{Ric}_w$  are the Laplacian  $\Delta$  and Ricci curvature  $\text{Ric}$  on  $N$ , respectively.

Now let  $(M^{n+1}, \bar{g})$  be an  $(n + 1)$ -dimensional Riemannian manifold. Assume that  $f$  is a smooth function on  $M$  so that  $(M^{n+1}, \bar{g}, e^{-f} d\mu)$  is a smooth metric measure space, where  $d\mu$  is the volume element induced by  $\bar{g}$ .

Let  $i : \Sigma^n \rightarrow M^{n+1}$  be an  $n$ -dimensional smooth immersion. Then

$$i : (\Sigma^n, i^* \bar{g}) \rightarrow (M^{n+1}, \bar{g})$$



is an isometric immersion with the induced metric  $i^*\bar{g}$ . For simplicity, we still denote  $i^*\bar{g}$  by  $\bar{g}$  whenever there is no confusion. Let  $d\sigma$  denote the volume element of  $(\Sigma, \bar{g})$ . Then the function  $f$  induces a weighted measure  $e^{-f}d\sigma$  on  $\Sigma$ . Thus we have an induced smooth metric measure space  $(\Sigma^n, \bar{g}, e^{-f}d\sigma)$ .

In this paper, unless otherwise specified, we denote by a bar all quantities on  $(M, \bar{g})$ , for instance by  $\bar{\nabla}$  and  $\bar{\text{Ric}}$ , the Levi-Civita connection and the Ricci curvature tensor of  $(M, \bar{g})$ , respectively. Also we denote, for example, by  $\nabla$ ,  $\text{Ric}$ ,  $\Delta$  and  $\Delta_f$ , the Levi-Civita connection, the Ricci curvature tensor, the Laplacian, and the weighted Laplacian on  $(\Sigma, \bar{g})$ , respectively. Let  $p \in \Sigma$  and  $\nu$  a unit normal at  $p$ . The second fundamental form  $A$ , the mean curvature  $H$ , and the mean curvature vector  $\mathbf{H}$  of hypersurface  $(\Sigma, \bar{g})$  are defined, respectively, by

$$A : T_p\Sigma \rightarrow T_p\Sigma, \quad A(X) := \bar{\nabla}_X\nu, \quad X \in T_p\Sigma,$$

$$H := \text{tr } A = - \sum_{i=1}^n \langle \bar{\nabla}_{e_i}e_i, \nu \rangle, \quad \mathbf{H} := -H\nu.$$

Define the weighted mean curvature vector  $\mathbf{H}_f$  and the weighted mean curvature  $H_f$  of  $(\Sigma, \bar{g})$  by

$$\mathbf{H}_f := \mathbf{H} - (\bar{\nabla}f)^\perp \quad \text{and} \quad H_f = -\mathbf{H}_f\nu,$$

where  $\perp$  denotes the projection to the normal bundle of  $\Sigma$ . It follows that

$$H_f = H - \langle \bar{\nabla}f, \nu \rangle.$$

**Definition.** A hypersurface  $\Sigma$  immersed in  $(M^{n+1}, \bar{g}, e^{-f}d\mu)$  with the induced metric  $\bar{g}$  is called  $f$ -minimal if its weighted mean curvature  $H_f$  vanishes identically or, equivalently, if it satisfies

$$(3) \quad H = \langle \bar{\nabla}f, \nu \rangle.$$

**Definition.** The weighted volume of  $(\Sigma, \bar{g})$  is defined by

$$(4) \quad V_f(\Sigma) := \int_{\Sigma} e^{-f}d\sigma.$$

It is well known that  $\Sigma$  is  $f$ -minimal if and only if  $\Sigma$  is a critical point of the weighted volume functional. Namely it holds that

**Proposition 1.** *If  $T$  is a compactly supported normal variational vector field on  $\Sigma$  (i.e.,  $T = T^\perp$ ), then the first variation formula of the weighted volume of  $(\Sigma, \bar{g})$  is given by*

$$(5) \quad \frac{d}{dt}V_f(\Sigma_t) \Big|_{t=0} = - \int_{\Sigma} \langle T, \mathbf{H}_f \rangle_{\bar{g}} e^{-f}d\sigma.$$

On the other hand, an  $f$ -minimal hypersurface can be viewed as a minimal hypersurface under a conformal metric. More precisely, define the new metric  $\tilde{g} = e^{-2f/n}\bar{g}$  on  $M$ , which is conformal to  $\bar{g}$ . Then the immersion  $i : \Sigma \rightarrow M$  induces a metric  $i^*\tilde{g}$  on  $\Sigma$  from  $(M, \tilde{g})$ . In the following,  $i^*\tilde{g}$  is still denoted by  $\tilde{g}$  for simplicity of notation. The volume of  $(\Sigma, \tilde{g})$  is

$$(6) \quad \tilde{V}(\Sigma) := \int_{\Sigma} d\tilde{\sigma} = \int_{\Sigma} e^{-f} d\sigma = V_f(\Sigma).$$

Hence Proposition 1 and (6) imply that

$$(7) \quad \int_{\Sigma} \langle T, \tilde{H} \rangle_{\tilde{g}} d\tilde{\sigma} = \int_{\Sigma} \langle T, H_f \rangle_{\tilde{g}} e^{-f} d\sigma,$$

where  $d\tilde{\sigma} = e^{-f} d\sigma$  and  $\tilde{H}$  denote the volume element and the mean curvature vector of  $\Sigma$  with respect to the conformal metric  $\tilde{g}$ , respectively.

Equation (7) implies that  $\tilde{H} = e^{2f/n}H_f$ . Therefore  $(\Sigma, \tilde{g})$  is  $f$ -minimal in  $(M, \tilde{g})$  if and only if  $(\Sigma, \bar{g})$  is minimal in  $(M, \bar{g})$ .

In this paper, for a closed hypersurface, we choose  $\nu$  to be the outer unit normal.

### 3. Some facts on the weighted Laplacian and $f$ -minimal hypersurfaces

In this section, we give some known results which will be used later in this paper. Recall that Reilly [1977] proved an integral version of the Bochner formula for compact domains of a Riemannian manifold, which is called the Reilly formula. Ma and Du [2010] obtained a Reilly formula for metric measure spaces, which is the following proposition. We include its proof in an appendix for the sake of completeness.

**Proposition 2.** *Let  $\Omega$  be a compact Riemannian manifold with boundary  $\partial\Omega$  and  $(\Omega, \bar{g}, e^{-f} d\mu)$  a smooth metric measure space. Then*

$$(8) \quad \int_{\Omega} (\bar{\Delta}_f u)^2 e^{-f} = \int_{\Omega} |\bar{\nabla}^2 u|^2 e^{-f} + \int_{\Omega} \bar{\text{Ric}}_f(\bar{\nabla} u, \bar{\nabla} u) e^{-f} \\ + 2 \int_{\partial\Omega} u_{\nu} (\Delta_f u) e^{-f} + \int_{\partial\Omega} A(\nabla u, \nabla u) e^{-f} + \int_{\partial\Omega} u_{\nu}^2 H_f e^{-f},$$

where  $\nu$  is the outward pointing unit normal to  $\partial\Omega$  and  $A$  is the second fundamental form of  $\partial\Omega$  with respect to the normal  $\nu$ , the quantities with bars denote the ones on  $(\Omega, \bar{g})$  (for instance,  $\bar{\text{Ric}}_f$  denotes the Bakry–Émery Ricci curvature on  $(\Omega, \bar{g})$ ), and  $\Delta_f$  and  $H_f$  denote the weighted Laplacian on  $\partial\Omega$  and the weighted mean curvature of  $\partial\Omega$ , respectively.

A Riemannian manifold with Bakry–Émery Ricci curvature bounded below by a positive constant has some properties similar to a Riemannian manifold with Ricci

curvature bounded below by a positive constant. We refer to [Wei and Wylie 2009; Munteanu and Wang 2014; 2012] and the references therein.

**Proposition 3** [Morgan 2005] (see also [Wei and Wylie 2009, Corollary 5.1]). *If a complete smooth metric measure space  $(N, g, e^{-\omega} d\mu)$  has  $\text{Ric}_w \geq k$ , where  $k$  is a positive constant, then  $N$  has finite weighted volume and finite fundamental group.*

For  $f$ -minimal hypersurfaces, the following intersection theorem holds.

**Proposition 4** [Wei and Wylie 2009, Theorem 7.4]. *Any two closed  $f$ -minimal hypersurfaces immersed in a complete smooth metric measure space  $(M, \bar{g}, e^{-f} d\mu)$  with  $\bar{\text{Ric}}_f > 0$  must intersect. Thus a closed  $f$ -minimal hypersurface in  $M$  must be connected.*

In [Cheng and Zhou 2013] it was proved that the weighted volume of a self-shrinker  $\Sigma^n$  immersed in  $\mathbb{R}^m$  being finite implies it is properly immersed. This result extends to  $f$ -minimal submanifolds:

**Proposition 5** [Cheng et al. 2012]. *Let  $\Sigma^n$  be an  $n$ -dimensional complete  $f$ -minimal submanifold immersed in an  $m$ -dimensional Riemannian manifold  $M^m$ ,  $n < m$ . If  $\Sigma$  has finite weighted volume, then  $\Sigma$  is properly immersed in  $M$ .*

An  $f$ -minimal hypersurface is an  $f$ -minimal submanifold with codimension 1. See more properties of  $f$ -minimal submanifolds in [Cheng et al. 2012].

#### 4. Lower bound for $\lambda_1(\Delta_f)$

In this section, we apply the Reilly formula for metric measure spaces to prove Theorems 2 and 5.

*Proof of Theorem 2.* Since  $\bar{\text{Ric}}_f \geq k$ , where  $k > 0$  is constant, Proposition 3 implies that  $M$  has finite fundamental group. We first assume that  $M$  is simply connected. Since  $\Sigma$  is connected (Proposition 4) and embedded in  $M$ ,  $\Sigma$  is orientable and divides  $M$  into two components (see its proof in [Choi and Schoen 1985]). Thus  $\Sigma$  divides  $D$  into two bounded components  $\Omega_1$  and  $\Omega_2$ . That is  $D \setminus \Sigma = \Omega_1 \cup \Omega_2$  with  $\partial\Omega_1 = \Sigma$  and  $\partial\Omega_2 = \partial D \cup \Sigma$ .

For simplicity, we denote by  $\lambda_1$  the first eigenvalue  $\lambda_1(\Delta_f)$  of the weighted Laplacian  $\Delta_f$  on  $\Sigma$ . Let  $h$  be a corresponding eigenfunction so that on  $\Sigma$

$$\Delta_f h + \lambda_1 h = 0 \quad \text{with} \quad \int_{\Sigma} h^2 e^{-f} = 1.$$

Consider the solution of the Dirichlet problem on  $\Omega_1$  so that

$$(9) \quad \begin{cases} \bar{\Delta}_f u = 0 & \text{in } \Omega_1, \\ u = h & \text{on } \partial\Omega_1 = \Sigma. \end{cases}$$

Substitute  $\Omega_1$  for  $\Omega$  and put the solution  $u$  of (9) in Proposition 2. Then the

assumption on  $\overline{\text{Ric}}_f$  implies that

$$0 \geq k \int_{\Omega_1} |\overline{\nabla}u|^2 e^{-f} - 2\lambda_1 \int_{\Sigma} u_\nu h e^{-f} + \int_{\Sigma} A(\nabla h, \nabla h) e^{-f},$$

where  $\nu$  is the outer unit normal of  $\Sigma$  with respect to  $\Omega_1$ . By Stokes' theorem and (9),

$$\int_{\Sigma} u_\nu h e^{-f} = \int_{\Omega_1} (|\overline{\nabla}u|^2 + u \overline{\Delta}_f u) e^{-f} = \int_{\Omega_1} |\overline{\nabla}u|^2 e^{-f}.$$

Thus

$$0 \geq (k - 2\lambda_1) \int_{\Omega_1} |\overline{\nabla}u|^2 e^{-f} + \int_{\Sigma} A(\nabla h, \nabla h) e^{-f}.$$

If  $\int_{\Sigma} A(\nabla h, \nabla h) e^{-f} \geq 0$ , by  $u \not\equiv C$ , we have

$$\lambda_1 \geq \frac{k}{2}.$$

If  $\int_{\Sigma} A(\nabla h, \nabla h) e^{-f} < 0$ , we consider the compact domain  $\Omega_2$  with the boundary  $\partial\Omega_2 = \Sigma \cup \partial D$ . Let  $u$  be the solution of the mixed problem

$$(10) \quad \begin{cases} \overline{\Delta}_f u = 0 & \text{in } \Omega_2, \\ u = h & \text{on } \Sigma, \\ u_{\tilde{\nu}} = 0 & \text{on } \partial D, \end{cases}$$

where  $\tilde{\nu}$  denotes the outer unit normal of  $\partial D$  with respect to  $\Omega_2$ .

Substituting  $\Omega_2$  for  $\Omega$  and putting the solution  $u$  of (10) in Proposition 2, we have

$$0 \geq \int_{\Omega_2} |\overline{\nabla}^2 u|^2 e^{-f} + k \int_{\Omega_2} |\overline{\nabla}u|^2 e^{-f} - 2\lambda_1 \int_{\Sigma} h u_{\tilde{\nu}} e^{-f} + \int_{\Sigma} \tilde{A}(\nabla h, \nabla h) e^{-f} + \int_{\partial D} \tilde{A}(\nabla u, \nabla u) e^{-f},$$

where  $\tilde{\nu}$  denotes the outer unit normal of  $\Sigma$  with respect to  $\Omega_2$  and  $\tilde{A}$  denotes the second fundamental form of  $\Sigma$  with respect to the normal  $\tilde{\nu}$ .

On the other hand, Stokes' theorem and (10) imply

$$\int_{\Omega_2} |\overline{\nabla}u|^2 e^{-f} = \int_{\partial\Omega_2} u u_{\tilde{\nu}} e^{-f} = \int_{\Sigma} h u_{\tilde{\nu}} e^{-f}.$$

Thus we have

$$(11) \quad 0 \geq (k - 2\lambda_1) \int_{\Omega_2} |\overline{\nabla}u|^2 e^{-f} + \int_{\Sigma} \tilde{A}(\nabla h, \nabla h) e^{-f} + \int_{\partial D} \tilde{A}(\nabla u, \nabla u) e^{-f}.$$

Since  $\partial D$  is assumed convex, the last term on the right side of (11) is nonnegative. Observe that the orientations of  $\Sigma$  are opposite for  $\Omega_1$  and  $\Omega_2$ . Namely  $\tilde{\nu} = -\nu$ .

Then  $\tilde{A}(\nabla u, \nabla u) = -A(\nabla u, \nabla u)$  on  $\Sigma$ . This implies that the second term on the right side of (11) is nonnegative. Thus

$$0 \geq (k - 2\lambda_1) \int_{\Omega_2} |\bar{\nabla} u|^2 e^{-f}.$$

Since  $u$  is not a constant function, we conclude that  $k - 2\lambda_1 \leq 0$ . Again we have

$$\lambda_1 \geq \frac{k}{2}.$$

Therefore we obtain that  $\lambda_1(\Delta_f) \geq k/2$  if  $M$  is simply connected.

Second, if  $M$  is not simply connected, we consider its universal covering  $\hat{M}$ , which is a finite  $|\pi_1|$ -fold covering.  $\hat{M}$  is simply connected and the covering map  $\pi : \hat{M} \rightarrow M$  is a locally isometry.

Take  $\hat{f} = f \circ \pi$ . Obviously  $\hat{M}$  has  $\text{Ric}_{\hat{f}} \geq k$ , and the lift  $\hat{\Sigma}$  of  $\Sigma$  is also  $\hat{f}$ -minimal, embedded and closed. By Proposition 4,  $\hat{\Sigma}$  must be connected. Since  $\hat{M}$  is simply connected, the closed embedded connected  $\hat{\Sigma}$  must be orientable and thus divides  $\hat{M}$  into two components. Moreover the connectedness of  $\hat{\Sigma}$  implies that the lift  $\hat{D}$  of  $D$  is also a connected domain. Also  $\partial\hat{D} = \hat{\partial D}$  is smooth and convex. Hence the assertion obtained for the simply connected ambient space can be applied here. Thus the first eigenvalue of the weighted Laplacian  $\hat{\Delta}_{\hat{f}}$  on  $\hat{\Sigma}$  satisfies  $\lambda_1(\hat{\Delta}_{\hat{f}}) \geq k/2$ .

Observing the lift of the first eigenfunction of  $\Sigma$  is also an eigenfunction of  $\hat{M}$ , we have

$$\lambda_1(\Delta_f) \geq \lambda_1(\hat{\Delta}_{\hat{f}}) \geq \frac{k}{2}. \quad \square$$

**Remark.** In Theorem 2, the boundary  $\partial D$  is not necessarily smooth.  $\partial D$  can be assumed to be  $C^1$ , which is sufficient for the existence of the solution of the mixed problem (10).

Theorem 5 holds by the same argument as that of Theorem 2.

### 5. Upper bound on area and total curvature of $f$ -minimal surfaces

In this section, we study surfaces in a 3-manifold. First we estimate the corresponding upper bounds on the area and weighted area of an embedded closed  $f$ -minimal surface by applying the first eigenvalue estimate in Section 4. Next we discuss the upper bound on the total curvature. We begin with a result of Yang and Yau [1980]:

**Proposition 6.** *Let  $\Sigma^2$  be a closed orientable Riemannian surface with genus  $g$ . Then the first eigenvalue  $\lambda_1(\Delta)$  of the Laplacian  $\Delta$  on  $\Sigma$  satisfies*

$$\lambda_1(\Delta) \text{Area}(\Sigma) \leq 8\pi(1 + g).$$

Using Theorem 2 and Proposition 6, we obtain the following area estimates for closed embedded  $f$ -minimal surfaces if the ambient space is simply connected.

**Proposition 7.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a simply connected complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Sigma^2 \subset M$  be a closed embedded  $f$ -minimal surface with genus  $g$ . If  $\Sigma$  is contained in a bounded domain  $D$  with convex boundary  $\partial D$ , then its area and weighted area satisfy*

$$(12) \quad \text{Area}(\Sigma) \leq \frac{16\pi(1+g)}{k} e^{\text{osc}_\Sigma f}$$

and

$$(13) \quad \text{Area}_f(\Sigma) \leq \frac{16\pi(1+g)}{k} e^{-\inf_\Sigma f},$$

where  $\text{osc}_\Sigma f = \sup_\Sigma f - \inf_\Sigma f$ .

*Proof.* Consider the conformal metric  $\tilde{g} = e^{-f} \bar{g}$  on  $M$ . Let  $\lambda_1(\tilde{\Delta})$  be the first eigenvalue of the Laplacian  $\tilde{\Delta}$  on  $(\Sigma, \tilde{g})$ , which satisfies

$$\lambda_1(\tilde{\Delta}) = \inf_{\substack{\int_\Sigma u d\tilde{\sigma}=0 \\ u \neq 0}} \frac{\int_\Sigma |\tilde{\nabla} u|_{\tilde{g}}^2 d\tilde{\sigma}}{\int_\Sigma u^2 d\tilde{\sigma}},$$

where  $\tilde{\Delta}$ ,  $\tilde{\nabla}$  and  $d\tilde{\sigma}$  are the Laplacian, gradient and area element of  $\Sigma$  with respect to the metric  $\tilde{g}$ , respectively.

On the other hand, the first eigenvalue of the weighted Laplacian  $\lambda_1(\Delta_f)$  on  $(\Sigma, \bar{g})$  satisfies

$$\lambda_1(\Delta_f) = \inf_{\substack{\int_\Sigma u e^{-f} d\sigma=0 \\ u \neq 0}} \frac{\int_\Sigma |\nabla u|_{\bar{g}}^2 e^{-f} d\sigma}{\int_\Sigma u^2 e^{-f} d\sigma}.$$

Since  $\tilde{\nabla} u = e^f \nabla u$ ,  $d\tilde{\sigma} = e^{-f} d\sigma$  and  $\tilde{g} = e^{-f} \bar{g}$ ,

$$\begin{aligned} \lambda_1(\tilde{\Delta}) &= \inf_{\substack{\int_\Sigma u e^{-f} d\sigma=0 \\ u \neq 0}} \frac{\int_\Sigma |\nabla u|_{\bar{g}}^2 d\sigma}{\int_\Sigma u^2 e^{-f} d\sigma} \\ &\geq \inf_{\substack{\int_\Sigma u e^{-f} d\sigma=0 \\ u \neq 0}} \frac{\int_\Sigma |\nabla u|_{\bar{g}}^2 e^{-f + \inf_\Sigma(f)} d\sigma}{\int_\Sigma u^2 e^{-f} d\sigma} \\ &= e^{\inf_\Sigma f} \lambda_1(\Delta_f). \end{aligned}$$

By this inequality, Theorem 2 and Proposition 6, we have the estimate

$$(14) \quad \text{Area}(\Sigma, \tilde{g}) \leq \frac{16\pi(1+g)}{k} e^{-\inf_\Sigma(f)}.$$

Since  $\text{Area}_f(\Sigma) = \int_{\Sigma} e^{-f} d\sigma = \text{Area}(\Sigma, \tilde{g})$ ,

$$\text{Area}_f(\Sigma) \leq \frac{16\pi(1+g)}{k} e^{-\inf_{\Sigma}(f)},$$

which is (13). Thus

$$\text{Area}(\Sigma) \leq \frac{16\pi(1+g)}{k} e^{\sup_{\Sigma}(f)-\inf_{\Sigma}(f)} = \frac{16\pi(1+g)}{k} e^{\text{osc}_{\Sigma}(f)}.$$

That is, (12) holds. □

Now, suppose that  $M$  is not simply connected. We use a covering argument as in [Choi and Schoen 1985].

**Proposition 8.** *Let  $(M^3, \tilde{g}, e^{-f} d\mu)$  be a complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Sigma^2$  be a closed embedded  $f$ -minimal surface. If  $\Sigma$  is contained in a bounded domain  $D$  of  $M$  with convex boundary  $\partial D$ , then*

$$(15) \quad \text{Area}_f(\Sigma) \leq \frac{16\pi}{k} \left( \frac{2}{|\pi_1|} - \frac{1}{2}\chi(\Sigma) \right) e^{-\inf_{\Sigma} f}$$

and

$$(16) \quad \text{Area}(\Sigma) \leq \frac{16\pi}{k} \left( \frac{2}{|\pi_1|} - \frac{1}{2}\chi(\Sigma) \right) e^{\text{osc}_{\Sigma} f},$$

where  $|\pi_1|$  is the order of the fundamental group of  $M$ , and  $\chi(\Sigma)$  is the Euler characteristic of  $\Sigma$ .

*Proof.* Let  $\hat{M}$  be the universal covering manifold of  $M$ . By Proposition 3, the covering is a finite  $|\pi_1|$ -fold covering. Let  $\hat{\Sigma}$  be the lifting of  $\Sigma$ . In the proof of Theorem 2, we have shown that  $\hat{\Sigma}$  is orientable and satisfies the assumption of Theorem 2. Hence Theorem 2 implies that the first eigenvalue of the weighted Laplacian of  $\hat{\Sigma}$  satisfies  $\lambda_1(\hat{\Delta}_{\hat{f}}) \geq k/2$ , where  $\hat{f}$  is the lift of  $f$ . By Proposition 7, we conclude that

$$\text{Area}(\hat{\Sigma}) \leq \frac{16\pi}{k} \left( 2 - \frac{1}{2}\chi(\hat{\Sigma}) \right) e^{\text{osc}_{\hat{\Sigma}}(\hat{f})}$$

and

$$\text{Area}_{\hat{f}}(\hat{\Sigma}) = \int_{\hat{\Sigma}} e^{-\hat{f}} d\sigma \leq \frac{16\pi}{k} \left( 2 - \frac{1}{2}\chi(\hat{\Sigma}) \right) e^{-\inf_{\hat{\Sigma}}(\hat{f})}.$$

Thus (15) and (16) follow from the equalities

$$\chi(\hat{\Sigma}) = |\pi_1| \cdot \chi(\Sigma), \quad \inf_{\hat{\Sigma}}(\hat{f}) = \inf_{\Sigma}(f), \quad \text{osc}_{\hat{\Sigma}}(\hat{f}) = \text{osc}_{\Sigma}(f),$$

$$\text{Area}(\hat{\Sigma}) = |\pi_1| \cdot \text{Area}(\Sigma) \quad \text{and} \quad \text{Area}_{\hat{f}}(\hat{\Sigma}) = |\pi_1| \cdot \text{Area}_f(\Sigma). \quad \square$$

In the following, we will give the upper bound for the total curvature of  $f$ -minimal surfaces. Here the term the *total curvature* of  $\Sigma$  means  $\int_{\Sigma} |A|^2 d\sigma$  not  $\int_{\Sigma} K d\sigma$ .

**Proposition 9.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Sigma^2 \subset M$  be a closed embedded  $f$ -minimal surface with genus  $g$ . If  $\Sigma$  is contained in a bounded domain  $D$  of  $M$  with convex boundary  $\partial D$ , then  $\Sigma$  satisfies*

$$(17) \quad \int_{\Sigma} |A|^2 d\sigma \leq C,$$

where  $A$  is the second fundamental form of  $(\Sigma, \bar{g})$  and  $C$  is a constant depending on the genus  $g$  of  $\Sigma$ , the order  $|\pi_1|$  of the fundamental group of  $M$ , the maximum  $\sup_{\Sigma} \bar{K}$  of the sectional curvature of  $M$  on  $\Sigma$ , the lower bound  $k$  of the Bakry–Émery Ricci curvature of  $M$ , the oscillation  $\text{osc}_{\Sigma}(f)$  and the maximum  $\sup_{\Sigma} |\bar{\nabla} f|$  on  $\Sigma$ .

*Proof.* By the Gauss equation and Gauss–Bonnet formula,

$$\begin{aligned} \int_{\Sigma} |A|^2 d\sigma &= \int_{\Sigma} H^2 - 2 \int_{\Sigma} (K - \bar{K}) = \int_{\Sigma} \langle \bar{\nabla} f, \mathbf{n} \rangle^2 - 4\pi \chi(\Sigma) + 2 \int_{\Sigma} \bar{K} \\ &\leq (\sup_{\Sigma} |\bar{\nabla} f|)^2 \text{Area}(\Sigma) + 8\pi(g - 1) + 2(\sup_{\Sigma} \bar{K}) \text{Area}(\Sigma). \end{aligned}$$

Using (16), we have the conclusion of the theorem. □

To prove the compactness theorem in Section 6, we need the following total curvature estimate for  $(\Sigma, \tilde{g})$ , which is a minimal surface in  $(M, \tilde{g})$ .

**Proposition 10.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Let  $\Sigma^2 \subset M$  be a closed embedded  $f$ -minimal surface with genus  $g$ . If  $\Sigma$  is contained in a bounded domain  $D$  of  $M$  with convex boundary  $\partial \Omega$ , then  $\Sigma$  satisfies*

$$(18) \quad \int_{\Sigma} |\tilde{A}|_{\tilde{g}}^2 d\tilde{\sigma} \leq C,$$

where  $\tilde{A}$  is the second fundamental form of  $(\Sigma, \tilde{g})$  with respect to the conformal metric  $\tilde{g} = e^{-f} \bar{g}$  of  $M$  and  $C$  is a constant depending on the genus  $g$  of  $\Sigma$ , the order  $|\pi_1|$  of the fundamental group of  $M$ , the maximum  $\sup_{\Sigma} \tilde{K}$  of the sectional curvature of  $(M, \tilde{g})$  on  $\Sigma$ , the lower bound  $k$  of the Bakry–Émery Ricci curvature of  $M$  and the oscillation  $\text{osc}_{\Sigma}(f)$  on  $\Sigma$ .

*Proof.* By the Gauss equation and the Gauss–Bonnet formula, we have

$$\begin{aligned} \int_{\Sigma} |\tilde{A}|_{\tilde{g}}^2 d\tilde{\sigma} &= \int_{\Sigma} \tilde{H}^2 - 2 \int_{\Sigma} (\tilde{K}^{\Sigma} - \tilde{K}^M) d\tilde{\sigma} = -4\pi \chi(\Sigma) + 2 \int_{\Sigma} \tilde{K} d\tilde{\sigma} \\ &\leq 8\pi(g - 1) + 2(\sup_{\Sigma} \tilde{K}) \text{Area}((\Sigma, \tilde{g})) \\ &= 8\pi(g - 1) + 2(\sup_{\Sigma} \tilde{K}) \text{Area}_f(\Sigma). \end{aligned}$$



We have used  $\tilde{H} = e^f H_f = 0$  and  $\text{Area}((\Sigma, \tilde{g})) = \text{Area}_f(\Sigma)$ . Now (18) follows from (15).  $\square$

### 6. Compactness of compact $f$ -minimal surfaces

We will prove some compactness theorems for closed embedded  $f$ -minimal surfaces in a 3-manifold. We have two ways to prove Theorem 4.

The first proof roughly follows the one in [Colding and Minicozzi 2011] (cf. [Choi and Schoen 1985]) with some modifications. The modifications can be made because we have the assumptions that  $f$ -minimal surfaces are contained in the closure of a bounded domain  $\Omega$  of  $M$  and  $\bar{\Omega}$  is contained in a bounded domain  $U$  with convex boundary. The second proof will need a compactness theorem of complete embedded  $f$ -minimal surfaces that was proved in [Cheng et al. 2012].

We prefer to give two proofs here since the first one is independent of the compactness theorem of complete embedded  $f$ -minimal surfaces. But the compactness theorem of complete embedded  $f$ -minimal surfaces needs a theorem about nonexistence of  $L_f$ -stable minimal surfaces (see [Cheng et al. 2012, Theorem 3]).

*First proof.* We first prove a singular compactness theorem, which is a variation of a result from [Choi and Schoen 1985] (compare [Colding and Minicozzi 2011, Proposition 7.14; Anderson 1985; White 1987]):

**Proposition 11.** *Let  $(M^3, \bar{g})$  be a 3-manifold. Assume that  $\Omega$  is a bounded domain in  $M$ . Let  $\Sigma_i$  be a sequence of closed embedded minimal surfaces contained in  $\bar{\Omega}$ , with genus  $g$ , and satisfying*

$$(19) \quad \text{Area}(\Sigma_i) \leq C_1$$

and

$$(20) \quad \int_{\Sigma_i} |A_{\Sigma_i}|^2 \leq C_2.$$

*Then there exists a finite set of points  $\mathcal{S} \subset \bar{\Omega}$  and a subsequence, still denoted by  $\Sigma_i$ , that converges uniformly in the  $C^m$  topology ( $m \geq 2$ ) on compact subsets of  $M \setminus \mathcal{S}$  to a complete minimal surface  $\Sigma \subset \bar{\Omega}$  (possibly with multiplicity).*

*The subsequence also converges to  $\Sigma$  in extrinsic Hausdorff distance.  $\Sigma$  is smooth, embedded in  $M$ , has genus at most  $g$  and satisfies (19) and (20).*

*Proof.* We may use the same argument as that of [Colding and Minicozzi 2011, Proposition 7.14]. Moreover  $\Sigma_i \subset \bar{\Omega}$  implies that the singular set  $S \subset \bar{\Omega}$  and the smooth surface  $\Sigma \subset \bar{\Omega}$ . Here we omit the details of proof.  $\square$

We can apply Proposition 11 to the  $f$ -minimal surfaces which are minimal in the conformal metric.

**Lemma.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a smooth metric measure space. Assume that  $\Omega$  is a bounded domain in  $M$ . Let  $\Sigma_i \subset \bar{\Omega}$  be a sequence of closed embedded  $f$ -minimal surfaces of genus  $g$ . Suppose that  $\tilde{g} = e^{-f} \bar{g}$  on  $M$  and  $(\Sigma_i, \tilde{g})$  satisfy*

$$(21) \quad \text{Area}((\Sigma_i, \tilde{g})) = \text{Area}_f(\Sigma_i) \leq C_1$$

and

$$(22) \quad \int_{\Sigma_i} |\tilde{A}_{\Sigma_i}|_{\tilde{g}}^2 d\tilde{\sigma} \leq C_2,$$

where  $\tilde{A}_{\Sigma_i}$  and  $d\tilde{\sigma}$  denote the second fundamental form and the volume element of  $(\Sigma_i, \tilde{g})$ , respectively. Then there exists a finite set of points  $\mathcal{S} \subset \bar{\Omega}$  and a subsequence, still denoted by  $\Sigma_i$ , that converges uniformly in the  $C^m$  topology ( $m \geq 2$ ) on compact subsets of  $M \setminus \mathcal{S}$  to a complete  $f$ -minimal surface  $\Sigma \subset \bar{\Omega}$  (possibly with multiplicity).

The subsequence also converges to  $\Sigma$  in extrinsic Hausdorff distance.  $\Sigma$  is smooth, embedded in  $M$ , has genus at most  $g$ , and satisfies (21) and (22).

*Proof.* Since an  $f$ -minimal surface in the original metric  $\bar{g}$  is equivalent to it being minimal in the conformal metric  $\tilde{g}$ , we can apply Proposition 11 to get the conclusion of the lemma.  $\square$

*Proof of Theorem 4.* First assume  $M$  is simply connected. Since  $\Sigma_i \subset \bar{\Omega} \subset U$ , we see from Proposition 7 and Proposition 10 that

$$\text{Area}((\Sigma_i, \tilde{g})) = \text{Area}_f(\Sigma_i) \leq C_1$$

and

$$\int_{\Sigma_i} |\tilde{A}_{\Sigma_i}|_{\tilde{g}}^2 d\sigma_{\tilde{g}} \leq C_2,$$

where  $C_1$  and  $C_2$  depend on  $g$ ,  $\sup_{\Omega_j} f$ ,  $\sup_{\Omega_j} \tilde{K}$  and  $k$ .

By the lemma, there exists a finite set of points  $\mathcal{S} \subset \bar{\Omega}$  and a subsequence  $\Sigma_{i'}$  that converges uniformly in the  $C^m$  topology (any  $m \geq 2$ ) on compact subsets of  $M \setminus \mathcal{S}$  to a complete  $f$ -minimal surface  $\Sigma \subset \bar{\Omega}$  without boundary (possibly with multiplicity).  $\Sigma$  is smooth, embedded in  $M$  and has genus at most  $g$ . Equivalently, with respect to the conformal metric  $\tilde{g}$ , a subsequence  $\Sigma_{i'}$  of minimal surfaces converges uniformly in the  $C^m$  topology on compact subsets of  $M \setminus \mathcal{S}$  to a complete minimal surface  $\Sigma$ , where  $\Sigma \subset \bar{\Omega}$ .

Since complete embedded  $\Sigma \subset \bar{\Omega}$  satisfies (21), it must be properly embedded (Proposition 5), thus closed and orientable.

We need to prove that the convergence is smooth across the points  $\mathcal{S}$ . By Allard's regularity theorem, it suffices to prove that the convergence has multiplicity one. If the multiplicity is not one, by a proof similar to that of [Choi and Schoen 1985]

(see also [Colding and Minicozzi 2011, p. 249]), we can show that there is an  $i$  big enough and a  $\Sigma_i$  in the convergent subsequence, so that the first eigenvalue of the Laplacian  $\tilde{\Delta}^{\Sigma_i}$  on  $\Sigma_i$  with the conformal metric  $\tilde{g}$  satisfies  $\lambda_1(\tilde{\Delta}^{\Sigma_i}) < ke^{\inf_{\Omega} f} / 2$ . We have

$$\begin{aligned} \lambda_1(\tilde{\Delta}^{\Sigma_i}) &= \inf \left\{ \frac{\int_{\Sigma_i} |\tilde{\nabla}\phi|_{\tilde{g}}^2 d\tilde{\sigma}}{\int_{\Sigma_i} \phi^2 d\tilde{\sigma}}, \int_{\Sigma_i} \phi d\tilde{\sigma} = 0 \right\} \\ &= \inf \left\{ \frac{\int_{\Sigma_i} |\nabla\phi|^2 d\sigma}{\int_{\Sigma_i} \phi^2 e^{-f} d\sigma}, \int_{\Sigma_i} \phi e^{-f} d\sigma = 0 \right\} \\ &\geq \lambda_1(\Delta_f^{\Sigma_i}) e^{\inf_{\Omega} f}. \end{aligned}$$

By Theorem 2,  $\Sigma_i \subset \bar{\Omega} \subset U$  implies  $\lambda_1(\Delta_f^{\Sigma_i}) \geq k/2$ . Thus we have a contradiction.

When  $M$  is not simply connected, we use a covering argument. The assumption of  $\overline{\text{Ric}}_f \geq k$ , where  $k > 0$  is constant, implies that  $M$  has finite fundamental group  $\pi_1$  (Proposition 3). We consider the finite-fold universal covering  $\hat{M}$ . By the proof of Theorem 2, we know that the corresponding lifts of  $\Sigma_i, \bar{\Omega}$  and  $U$  satisfy  $\hat{\Sigma}_i \subset \hat{\Omega} \subset \hat{U}$ . Then Propositions 8 and 10 give uniform bounds on the area and total curvature in the conformal metric  $\hat{g}$  on  $\hat{M}$ . By the assertion on the simply connected ambient manifold before, we have the smooth convergence of a subsequence of  $\hat{\Sigma}_i$ . This implies the smooth convergence of a subsequence of  $\Sigma_i$ .  $\square$

*Second Proof.* In [Cheng et al. 2012], we proved the following:

**Theorem 6.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Given an integer  $g \geq 0$  and a constant  $V > 0$ , the space  $S_{g,V}$  of smooth complete embedded  $f$ -minimal surfaces  $\Sigma \subset M$  with*

- *genus at most  $g$ ,*
- *$\partial\Sigma = \emptyset$ , and*
- *$\int_{\Sigma} e^{-f} d\sigma \leq V$*

*is compact in the  $C^m$  topology, for any  $m \geq 2$ . Namely any sequence of  $S_{g,V}$  has a subsequence that converges in the  $C^m$  topology on compact subsets to a surface in  $S_{D,g}$ , for any  $m \geq 2$ .*

*Proof of Theorem 4.* Since a surface in  $S$  is contained in  $\bar{\Omega} \subset U$ , by Proposition 8, we have the uniform bound  $V$  of the weighted volume of closed embedded  $f$ -minimal surfaces in  $S$ . Hence Theorem 6 can be applied. Moreover  $\Sigma_i \subset \bar{\Omega}$  implies that the smooth limit surface  $\Sigma \subset \bar{\Omega}$ . Otherwise, since the subsequence  $\{\Sigma_i\}$  converges uniformly in the  $C^m$  topology ( $m \geq 2$ ) on any compact subset of  $M$  to  $\Sigma$ , there is

a surface  $\Sigma_i$  (with index  $i$  big enough) in the subsequence that would not satisfy  $\Sigma_i \subset \bar{\Omega}$ .

By Proposition 5,  $\Sigma$  must be properly embedded. Thus  $\Sigma$  must be closed.  $\square$

To prove Theorem 3 we require a lemma.

**Lemma.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k > 0$ . If  $\Sigma$  is any closed  $f$ -minimal surface in  $M$  with genus at most  $g$  and diameter at most  $D$ , then  $\Sigma \subset \bar{B}_r(p)$  for some  $r > 0$  (independent of  $\Sigma$ ), where  $B_r(p)$  is a ball in  $M$  with radius  $r$  centered at  $p \in M$ .*

*Proof.* Fix a closed  $f$ -minimal surface  $\Sigma_0$ . Obviously  $\Sigma_0 \subset B_{r_0}(p)$  for some  $r_0 > 0$ . Proposition 4 says that  $\Sigma$  and  $\Sigma_0$  must intersect. Then, for  $x \in \Sigma$ ,

$$d(p, x) \leq d(p, x_0) + d(x_0, x) \leq r_0 + D, x_0 \in \Sigma_0.$$

Taking  $r = r_0 + D$ , we have  $\Sigma \subset \bar{B}_{r_0+D}$ .  $\square$

**Remark.** In the lemma and hence in Theorem 3,  $D$  is a bound on the intrinsic diameter of closed  $f$ -minimal surfaces or a bound on the extrinsic diameter of closed  $f$ -minimal surfaces. Also, by Proposition 4, the assumption that  $f$ -minimal surfaces are contained in the closure of a bounded domain  $\Omega$  in Theorem 4 is equivalent to that of a uniform upper bound on the extrinsic diameter of  $f$ -minimal surfaces.

*Proof of Theorem 3.* By the lemma immediately above, we may apply Theorem 4 to the space  $S_{D,g}$ . Next the closed embedded limit  $\Sigma$  must have diameter at most  $D$ . Otherwise, since the subsequence  $\{\Sigma_i\}$  converges uniformly in the  $C^m$  topology ( $m \geq 2$ ) on any compact subset of  $M$  to  $\Sigma$ , there is a surface  $\Sigma_i$  (with the index  $i$  big enough) in the subsequence that would have diameter greater than  $D$ . So  $\Sigma$  must be in  $S_{D,g}$ .  $\square$

As a corollary, Theorem 3 implies:

**Theorem 7.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Assume that  $M$  admits an exhaustion by bounded domains with convex boundary. Then the space of closed embedded  $f$ -minimal surface in  $M$  of fixed topological type and diameter at most  $D$  is compact in the  $C^m$  topology, for any  $m \geq 2$ .*

*Proof of Theorem 7.* By Theorem 3, it suffices to prove that the limit  $f$ -minimal surface of a convergent subsequence in the given space has the same topological type, which holds by the Gauss–Bonnet formula and smooth convergence.  $\square$

Similar to the proof of Theorem 7, Theorem 4 implies:

**Theorem 8.** *Let  $(M^3, \bar{g}, e^{-f} d\mu)$  be a complete noncompact smooth metric measure space with  $\overline{\text{Ric}}_f \geq k$ , where  $k$  is a positive constant. Assume that  $\Omega$  is a bounded domain and  $U$  is a bounded domain with convex boundary so that  $\bar{\Omega} \subset U$ . Then the space of closed embedded  $f$ -minimal surface in  $M$  of fixed topological type and contained in the closure  $\bar{\Omega}$  is compact in the  $C^m$  topology, for any  $m \geq 2$ .*

**Appendix: Proof of Proposition 2**

The Bochner formula implies that

$$\frac{1}{2} \bar{\Delta}_f |\bar{\nabla} u|^2 - \langle \bar{\nabla} u, \bar{\nabla}(\bar{\Delta}_f u) \rangle = |\bar{\nabla}^2 u|^2 + \overline{\text{Ric}}_f(\bar{\nabla} u, \bar{\nabla} u).$$

Integrating this equation on  $\Omega$  with respect to the weighted measure  $e^{-f} d\mu$ , we obtain

$$\int_{\Omega} (\frac{1}{2} \bar{\Delta}_f |\bar{\nabla} u|^2 - \langle \bar{\nabla} u, \bar{\nabla}(\bar{\Delta}_f u) \rangle) e^{-f} = \int_{\Omega} |\bar{\nabla}^2 u|^2 e^{-f} + \int_{\Omega} \overline{\text{Ric}}_f(\bar{\nabla} u, \bar{\nabla} u) e^{-f}.$$

On the other hand, by the divergence formula, we have

$$\begin{aligned} \frac{1}{2} \bar{\Delta}_f |\bar{\nabla} u|^2 - \langle \bar{\nabla} u, \bar{\nabla}(\bar{\Delta}_f u) \rangle \\ = \frac{1}{2} \text{div}(e^{-f} \bar{\nabla} |\bar{\nabla} u|^2) e^f - \text{div}(e^{-f} \bar{\Delta}_f(u) \bar{\nabla} u) e^f + (\bar{\Delta}_f u)^2. \end{aligned}$$

Integrating and applying Stokes' theorem, we have

$$\begin{aligned} (23) \quad \int_{\Omega} (\frac{1}{2} \bar{\Delta}_f |\bar{\nabla} u|^2 - \langle \bar{\nabla} u, \bar{\nabla}(\bar{\Delta}_f u) \rangle) e^{-f} \\ = \int_{\partial\Omega} (\frac{1}{2} |\bar{\nabla} u|_v^2 - (\bar{\Delta}_f u) u_v) e^{-f} + \int_{\Omega} (\bar{\Delta}_f u)^2 e^{-f}. \end{aligned}$$

Then

$$\begin{aligned} (24) \quad \frac{1}{2} |\bar{\nabla} u|_v^2 - (\bar{\Delta}_f u) u_v \\ = \langle \bar{\nabla}_v \bar{\nabla} u, \bar{\nabla} u \rangle - (\bar{\Delta}_f u) u_v = \langle \bar{\nabla}_{\bar{\nabla} u} \bar{\nabla} u, v \rangle - (\bar{\Delta}_f u) u_v \\ = \langle \bar{\nabla}_v \bar{\nabla} u, v \rangle u_v + \langle \bar{\nabla}_{\bar{\nabla} u} \bar{\nabla} u, v \rangle - (\bar{\Delta}_f u) u_v \\ = (\langle \bar{\nabla}_v \bar{\nabla} u, v \rangle - \bar{\Delta} u + \langle \bar{\nabla} f, \bar{\nabla} u \rangle) u_v + \langle \nabla u, \nabla u_v \rangle - \langle \bar{\nabla} u, \bar{\nabla}_{\nabla u} v \rangle \\ = (-\Delta u - H u_v + \langle \nabla f, \nabla u \rangle + \langle \bar{\nabla} f, v \rangle u_v) u_v + \langle \nabla u, \nabla u_v \rangle - \langle \nabla u, \bar{\nabla}_{\nabla u} v \rangle \\ = -(\Delta_f u + H_f u_v) u_v + \langle \nabla u, \nabla u_v \rangle - A(\nabla u, \nabla u), \end{aligned}$$

where  $H_f = H - \langle \bar{\nabla} f, \nu \rangle$ . By substituting (24) into (23), we obtain

$$\begin{aligned} & \int_{\Omega} \left( \frac{1}{2} \bar{\Delta} f |\bar{\nabla} u|^2 - \langle \bar{\nabla} u, \bar{\nabla} (\bar{\Delta} f u) \rangle \right) e^{-f} \\ &= - \int_{\partial \Omega} (\Delta_f u) u_\nu e^{-f} - \int_{\partial \Omega} H_f u_\nu^2 e^{-f} + \int_{\partial \Omega} (\langle \nabla u, \nabla u_\nu \rangle - A(\nabla u, \nabla u)) e^{-f} \\ & \quad + \int_{\Omega} (\bar{\Delta} f u)^2 e^{-f} \\ &= -2 \int_{\partial \Omega} (\Delta_f u) u_\nu e^{-f} - \int_{\partial \Omega} H_f u_\nu^2 e^{-f} - \int_{\partial \Omega} A(\nabla u, \nabla u) e^{-f} + \int_{\Omega} (\bar{\Delta} f u)^2 e^{-f}. \end{aligned}$$

This immediately implies (8).

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
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