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**TOPOLOGICAL AND PHYSICAL LINK THEORY
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ALEXANDER COWARD AND JOEL HASS

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Physical knots and links are one-dimensional submanifolds of \mathbb{R}^3 with fixed length and thickness. We show that isotopy classes in this category can differ from those of classical knot and link theory. In particular we exhibit a Gordian split link, a two-component link that is split in the classical theory but cannot be split with a physical isotopy.

1. Introduction

The theory of knots and links studies one-dimensional submanifolds of \mathbb{R}^3 . These are often described as loops of string, or rope, with their ends glued together. Real ropes however are not one-dimensional, but have a positive thickness and a finite length. Indeed, most physical applications of knot theory are related more closely to the theory of knots of fixed thickness and length than to classical knot theory. For example, biologists are interested in knotted curves of fixed thickness and length when studying properties of DNA [Cantarella et al. 1998] and protein molecules [Liang and Mislou 1994]. In these applications the thickness of the curve modeling the molecule plays an essential role in determining the possible configurations.

In this paper we show that the equivalence class of a link in \mathbb{R}^3 under an isotopy that preserves thickness and length can be distinct from the classical equivalence class under isotopy. We thus show for the first time that the theory of physically realistic curves of fixed thickness and length in \mathbb{R}^3 is distinct from the classical theory of knots and links.

The two most fundamental problems concerning physical knots and links are to show the existence of a *Gordian unknot* and a *Gordian split link*. A Gordian unknot is a loop of fixed thickness and length whose core is unknotted, but which cannot be deformed to a round circle by an isotopy fixing its length and thickness. A Gordian split link is a pair of loops of fixed thickness whose core curves can be split, or isotoped so that its two components are separated by a plane, but cannot be split by an isotopy fixing each component's length and thickness. In this paper we establish the existence of such a link.

MSC2010: 53A04, 57M25.

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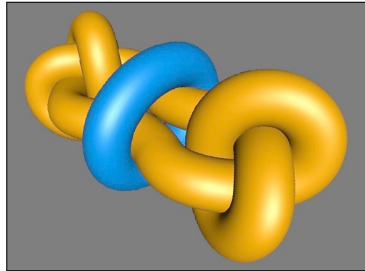


Figure 1. A Gordian split link.

Theorem 1.1. *A Gordian split link exists.*

The proof of Theorem 1.1 is by explicit construction of a link, illustrated in Figure 1, that can be topologically but not physically split.

There has been extensive investigation into the properties of shortest representatives of physical knots, called *tight* [Cantarella et al. 1998] or *ideal* knots [Katritch et al. 1997], and into the possible existence of Gordian unknots [Buck and Simon 1997; Cantarella et al. 1998; Diao et al. 1999; Gonzalez and Maddocks 1999; Katritch et al. 1997]. A candidate Gordian unknot was suggested by Freedman, He and Wang [Freedman et al. 1994], who studied energies associated to curves in \mathbb{R}^3 and associated gradient flows [He 2002]. This curve was studied numerically by Pierański [1998], who developed a computer program called SONO (Shrink On No Overlaps) to numerically shorten a curve of fixed thickness while avoiding overlaps. The program unexpectedly succeeded in unraveling the Freedman–He–Wang example. However there are more complicated examples that do fail to unravel under SONO and hence give numerical evidence for the existence of Gordian unknots. Extensive tables of physical knots of minimal length in various isotopy classes have been experimentally derived [Ashton et al. 2011]. A proof of the existence of Gordian unknots or Gordian split links based on a rigorous analysis of such algorithms is plausible but has not yet been found. In related work, Nabutovsky [1995] showed that n -dimensional spheres of fixed thickness in \mathbb{R}^{n+1} can be knotted for dimensions $n \geq 5$. Cantarella and Johnston [1998] showed that the theory of polygonal knots of fixed edge lengths is distinct from classical knot theory.

We now give precise definitions. We say that a knot or link L in \mathbb{R}^3 is r -thick if it is differentiable and its open radius- r normal disk bundle is embedded. This means that the collection of flat, radius- r two-disks intersecting L perpendicularly at their centers have mutually disjoint interiors. An isotopy of a knot or link maintaining r -thickness throughout is called an r -thick isotopy. By rescaling we may take $r = 1$ and take *thick* to mean 1-thick. A *physical isotopy* is a thick isotopy of a knot or link that preserves the length of each component. This reflects the real world properties of links composed of nonstretchable rope of fixed radius.

Theorem 1.1 is proved by an explicit construction of a two-component thick link L that is split but admits no physical isotopy splitting its components. To construct this link we begin by placing two points A and B at $(1, 0, 0)$ and $(-1, 0, 0)$. Let AB denote the straight line between these two points. The first component L_1 of L is any thick curve encircling AB in the xz -plane, disjoint from the open, radius-2 neighborhood of AB . The length of L_1 is at least $4\pi + 4 \approx 16.566$, and this length can be realized by taking L_1 to be the boundary of the radius-2 neighborhood of AB in the xz -plane. To construct the other component, join the two points A and B by an arc α satisfying the following three conditions:

- (1) The union of α with AB forms a nontrivial knot contained in the half-space $y \geq 0$.
- (2) The arc α meets the xz -plane only at its endpoints and is perpendicular to the xz -plane at these points.
- (3) The union of L_1 , α and the reflection of α across the xz -plane forms a thick link.

The union of α and its reflection in the xz -plane is the second component L_2 of the thick link L . Figure 1 shows an example of such a link.

Theorem 1.1 follows immediately from the following result, which gives an explicit lower bound on the length required for L_1 , the unknotted component of L , if L can be split by a physical isotopy.

Theorem 1.2. *If there is a physical isotopy of $L = L_1 \sqcup L_2$ that splits its two components, then the length of L_1 must be at least $4\pi + 6 \approx 18.566$.*

Since the link L can be constructed with the length of the unknotted component L_1 equal to $4\pi + 4$, this result implies Theorem 1.1.

The paper is arranged as follows. In Section 2 we give a lower bound on the boundary length of a disk of nonpositive curvature containing three disjoint disks of radius 1. In Section 3 we show that if a family of disks spanning L_1 gives a homotopy from a disk in the xz -plane to a disk disjoint from L_2 and each disk in the homotopy intersects a neighborhood of L_2 in at most two components containing points of L_2 , then L_2 is unknotted. In Section 4 we bring these results together to prove Theorem 1.2. We conclude with a short list of open problems.

2. An isoperimetric inequality

To prove Theorem 1.2, we show that if the unknotted component L_1 has length less than $4\pi + 6$, then there are severe restrictions on how the other component can pass through a natural spanning disc for L_1 . This spanning disc, to be defined in Section 4, is a cone with cone angle at least 2π , and hence a CAT(0) space. We are therefore led to finding a lower bound on the length of a curve in a CAT(0) surface

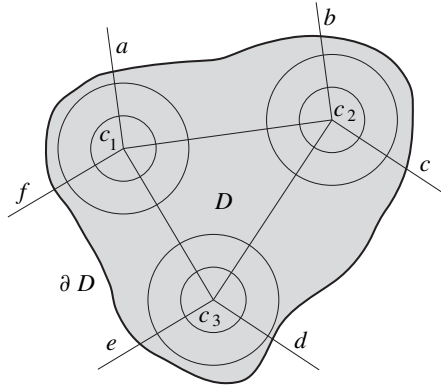


Figure 2. The boundary of this disk has length at least $6 + 4\pi$.

that bounds a disk enclosing three or more nonoverlapping subdisks of radius 1, as in Figure 2. This next result is based on an argument for flat metrics given in [Cantarella et al. 2002].

Proposition 2.1. *Let P be a complete CAT(0) surface and let D_1, D_2, D_3 be three subdisks of P with disjoint interiors and radius 1. Let $D \subset P$ be a disk containing D_1, D_2, D_3 such that ∂D has distance at least 1 to any of D_1, D_2, D_3 . Then the length of ∂D is at least $4\pi + 6$.*

Proof. Let T be the triangle with vertices at the center points c_1, c_2, c_3 of the disks D_1, D_2, D_3 . Each edge of T has length at least 2. Let a, b, c, d, e, f denote perpendicular rays from the sides of T at its vertices, as in Figure 2. The curve ∂D intersects each of a, b, c, d, e, f in at least one point. We pick one such point for each, ordered cyclically around ∂D , and refer to the intervening arcs of ∂D as the parts of ∂D between them. Since the edge of T between c_1 and c_2 is perpendicular to a and to b , it realizes the minimal distance of any path between them. Thus the length of the part of ∂D between a and b is at least 2. We can argue similarly for the length of ∂D between c and d , and between e and f . Thus these three parts of ∂D have total length at least 6.

The sum of the interior angles of T is at most π , so the sum of the three angles between f and a , between b and c , and between d and e is at least 2π . Radial projection projects the remaining parts of ∂D onto three circular arcs with total angle at least 2π . In a CAT(0) space, radius-decreasing radial projection onto a circle of constant radius is length-decreasing. Since a circle of radius 2 has length at least 4π , it follows that the length of ∂D is at least $6 + 4\pi$. \square

Remark. A similar argument shows that a curve enclosing two disks has length at least $4\pi + 4$ and that the length of a curve enclosing $n > 3$ disks is at least $4\pi + 2n$ if the centers of the disks form the vertices of a convex polygon.

3. Sweepouts of solid tori

The following proposition gives a generalization of the fact that a 1-bridge knot is unknotted. It considers a generic 1-parameter family of disks, possibly singular, whose interiors sweep across a region containing a solid torus and concludes that if each disk meets the solid torus in at most two components that cross its core, then the solid torus is unknotted. To simplify the argument we restrict to a setting where T and c have a reflectional symmetry. Roughly speaking, this allows us to argue that if a family of arcs forms a partial spanning disk that fills in half of a curve, then the entire curve bounds a disk formed from reflection of this partial spanning disk and is thus unknotted.

Proposition 3.1. *Let T be a solid torus in \mathbb{R}^3 with core c , such that both T and c are symmetric under reflection r in the xz -plane. Suppose there is a homotopy of the disc $g_t : D \rightarrow \mathbb{R}^3$, $t \in [-1, 1]$, with the following properties:*

- (1) *The curve $g_t(\partial D)$ is disjoint from T for all $t \in [-1, 1]$.*
- (2) *The family of disks $g_t(D)$ is symmetric under reflection r in the xz -plane; i.e., $g_0(D)$ is contained in the xz -plane and $g_{-t} = r \circ g_t$.*
- (3) *The preimage $g_0^{-1}(T)$ has two components, each containing a single point of $g_0^{-1}(c)$.*
- (4) *The disk $g_1(D)$ is disjoint from c .*
- (5) *For all $t \in [-1, 1]$ the preimage $g_t^{-1}(T) \subset D$ has at most two components that contain a point of $g_t^{-1}(c)$.*
- (6) *The map g_t is generic with respect to the pair (T, c) .*

Then c is unknotted.

Assumption (6) means that g_t is transverse to c with the exception of a finite number of times t at which a birth or death of a pair of points of $g_t^{-1}(c)$ occurs and that g_t is transverse to ∂T at these times. Additionally, g_t is transverse to ∂T except for a finite number of times at which $g_t^{-1}(\partial T)$ consists of finitely many simple closed curves and a single component that is either a bouquet of finitely many circles (at a general saddle-type singularity) or a point (at a birth or death singularity).

Proof of Proposition 3.1. To show that c is unknotted, we will form a spanning disk E for c that is traced by a continuous family of arcs in \mathbb{R}^3 , each arc having endpoints on c and interior disjoint from c . These arcs are of two types. The first type will lie on $g_t(D)$ and vary continuously with t except at finitely many times t when it jumps from one arc on $g_t(D)$ to another; the second type will interpolate continuously between the arcs just before and just after these jumps.

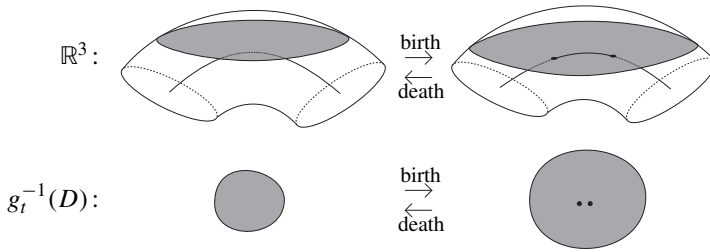


Figure 3. A birth or death adds or removes two points of $g_t^{-1}(c)$ from a component of $g_t^{-1}(T)$.

For a map $g : D \rightarrow \mathbb{R}^3$ we call a point of $g^{-1}(c) \subset D$ a *dot* and a component of $g^{-1}(T)$ that contains at least one point of $g^{-1}(c)$ a *dotted component*. Thus $g_0^{-1}(T)$ contains two dotted components, each with a single dot. A birth or death changes the number of points of $g_t^{-1}(c)$ in a component of $g_t^{-1}(T)$ by two, oppositely oriented, as illustrated in Figure 3.

At time $t = 0$, the preimage $g_0^{-1}(c) \subset D$ consists of a pair of points, one in each dotted component. Let α_0 be an arc joining these two points in D , with interior disjoint from $g_0^{-1}(c) \subset D$. As t increases, we take α_t to vary continuously through arcs in D , joining dots in distinct dotted components with interiors disjoint from the dots. There is no obstruction to this while the collection of dots in D is changing by an isotopy. As long as the number of dotted components does not drop, there are two possible obstructions to the extension of α_t as t increases:

- (1) Part of the arc α_t may run between two dots that come together and disappear in a death singularity.
- (2) One of the endpoints of α_t may disappear in a death singularity.

In contrast, birth singularities do not pose a problem for the extension of the family of arcs past the time at which they occur.

Let t_1 be the time of the first death singularity. To avoid the two problems above we pick a small $\varepsilon > 0$ and at time $t'_1 = t_1 - \varepsilon$ we jump from $\alpha_{t'_1}^- := \alpha_{t'_1}$ to a different arc $\alpha_{t'_1}^+$ that also joins points of $g_{t'_1}^{-1}(c)$ in distinct dotted components but that avoids a neighborhood of the death singularity. We will show how to construct $\alpha_{t'_1}^+$ so that this jump can be filled in appropriately for the construction of the disk E . We will then extend the family of arcs α_t for $t > t'_1$ by starting with $\alpha_{t'_1}^+$ and continuing past t_1 until just before the next death singularity occurs at some time $t_2 > t_1$. In the first case we show that the arc α_t can be replaced with one that avoids a neighborhood of the death singularity. In the second case we show that α_t can be replaced with an arc having an endpoint that avoids the death singularity.

For a continuous map $g : D \rightarrow \mathbb{R}^3$, we say that two arcs in the disk D joining points of $g^{-1}(c)$ in distinct dotted components of $g^{-1}(T)$ are *g-equivalent* if their

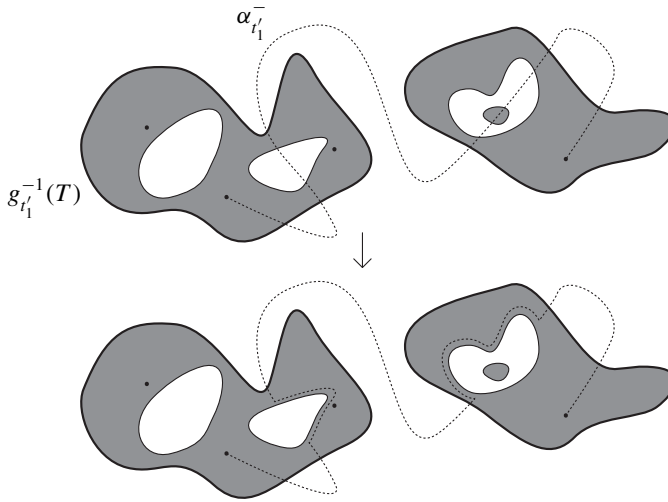


Figure 4. Removing intersections of $\alpha_{t_1}^-$ with secondary boundary components of $g_{t_1}^{-1}(T)$.

images under g are homotopic through arcs in \mathbb{R}^3 whose interiors are disjoint from c and whose endpoints lie on c . Our goal is then to construct the arc $\alpha_{t_1}^+$ so that it is g_{t_1} -equivalent to $\alpha_{t_1}^-$.

When g_t is transverse to ∂T the dotted components of $g_t^{-1}(T)$ form planar subsurfaces of D , each a disk with holes. A boundary curve of a dotted component that has dots on both of its sides in D is called *primary*, and boundary components with all dots on one side are called *secondary*.

If $\alpha_{t_1}^-$ leaves a dotted component X through a secondary boundary component b , it must reenter X through b , since b is separating in D . Let β be a subarc of $\alpha_{t_1}^-$ running between two successive intersections of $\alpha_{t_1}^-$ with b and with interior outside of X . Then β runs through either a dotless disc or a dotless annulus in D . We can then homotope β into b rel endpoints without crossing any dots. Push β a little further into the interior of X . Repeating this process we can homotope $\alpha_{t_1}^-$ rel endpoints without crossing dots and so that it crosses only primary boundary components. See Figure 4. We abuse notation somewhat and continue to refer to this arc as $\alpha_{t_1}^-$.

Our next goal is to arrange for $\alpha_{t_1}^-$ to pass through each primary boundary component exactly once. We will achieve this with the following lemma.

Lemma 3.2. *Suppose T is an embedded solid torus in \mathbb{R}^3 with core c , and suppose $g : D \rightarrow \mathbb{R}^3$ is a continuous map of a disc into \mathbb{R}^3 for which $g^{-1}(T)$ has two dotted components, each with image having algebraic intersection number ± 1 with c . Let α be an arc in D , joining dots in distinct dotted components of $g^{-1}(T)$, and with*

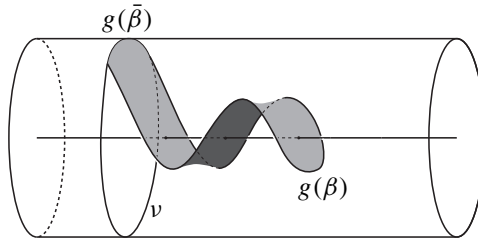


Figure 5. Two ways to homotope $g(\beta)$ onto ∂T .

interior disjoint from $g^{-1}(c)$. Let $\beta \subset g^{-1}(T)$ be a subarc of α that starts and ends on the same primary boundary component b of $g^{-1}(T)$. Then there is an arc $\beta' \subset b$ with the same endpoints as β and with the property that replacing β with β' in α yields an arc α' that is g -equivalent to α .

Proof. There is a homotopy of β in D rel endpoints to an arc $\bar{\beta}$ contained in b , possibly crossing dots. So $g(\beta)$ is homotopic rel endpoints in \mathbb{R}^3 to an arc $g(\bar{\beta})$ in $\partial T \cap g(D)$. This homotopy may pass outside T , as β slides over holes of the dotted component. However the boundaries of these holes are secondary, since there are precisely two dotted components, and therefore bound disks in \mathbb{R}^3 disjoint from c . It follows that they have image under g that is homotopically trivial on ∂T or they have images on ∂T that are nontrivial and bound disks in the exterior of T . In the latter case T is unknotted, and we are done. Thus we can assume that $g(\beta)$ and $g(\bar{\beta})$ are homotopic rel endpoints in T . The arc $g(\beta)$ is also homotopic rel endpoints in $T - c$, by radial projection away from c , to an arc ν on ∂T . See Figure 5, which for clarity shows only part of $g(D)$.

Now, $g(\bar{\beta})$ and ν are homotopic rel endpoints in T and so in ∂T they differ by a multiple of a meridian. Note that the curve $g(b)$ is a meridian, since it bounds a disk in T meeting c algebraically once. So $g(\beta)$ can be homotoped rel endpoints in the complement of c in T to ν , and then in turn to a curve formed by concatenating $g(\bar{\beta})$ with a multiple of $g(b)$. Take β' to be $\bar{\beta}$ followed by this multiple of b . \square

Now suppose that β is a subarc of $\alpha_{i_1}^-$ that enters and leaves a dotted component. Using Lemma 3.2 we can replace it with a g_{i_1} -equivalent arc β' that lies entirely on $g_{i_1}^{-1}(\partial T)$, and then perturb β' slightly so that it is disjoint from $g_{i_1}^{-1}(T)$, as illustrated in Figure 6. In this way we replace $\alpha_{i_1}^-$ with a g_{i_1} -equivalent arc that has fewer intersections with dotted components, and by repeating we may remove all subarcs of $\alpha_{i_1}^-$ that enter and leave a dotted component. We continue to refer to the resulting arc as $\alpha_{i_1}^-$. Note that $\alpha_{i_1}^-$ may now intersect itself.

We have found an arc g_{i_1} -equivalent to the original arc $\alpha_{i_1}^-$ that starts at a dot in one dotted component, exits that dotted component, then enters the second dotted component and finally ends at a dot. The following lemma allows us to

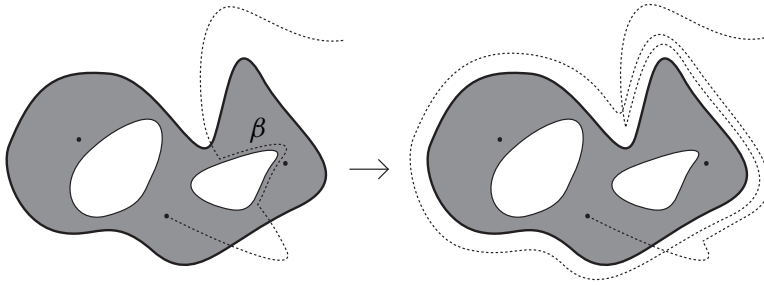


Figure 6. Removing an arc in D that starts and ends on the same primary boundary component of $g^{-1}(T)$.

find a $g_{t'_1}$ -equivalent arc that replaces a subarc running from a primary boundary component to a dot, with any other arc running from the same point to a dot and not leaving $g_{t'_1}^{-1}(T)$.

We define an arc in a solid torus T with core c to be *core-to-boundary* if it has one endpoint on ∂T , the other endpoint on c , and interior disjoint from c .

Lemma 3.3. *Let T be a solid torus with core c . Let γ and γ' be core-to-boundary arcs in T with $\gamma \cap \partial T = \gamma' \cap \partial T$. Then γ and γ' can be joined by a homotopy of core-to-boundary arcs, keeping the endpoint on ∂T fixed.*

Proof. We can lift γ and γ' to the universal cover of T , which is homeomorphic to $(\text{disk}) \times \mathbb{R}$, so that their common endpoint on ∂T lifts to the same point x while c lifts to $\{0\} \times \mathbb{R}$. Each lift can be homotoped, keeping x fixed and moving points only along the \mathbb{R} -factor, to the slice $(\text{disk}) \times \{\text{point}\}$ containing x . Further, the resulting arcs are homotopic rel endpoints in $(\text{disk}) \times \{\text{point}\}$ via arcs that miss $\{0\} \times \{\text{point}\}$ in their interior. Therefore the lifts of γ and γ' are homotopic through arcs joining x to $\{0\} \times \mathbb{R}$ and with interiors disjoint from $\{0\} \times \mathbb{R}$. The projection of this homotopy to T gives a homotopy joining γ and γ' through core-to-boundary arcs in T . □

Now suppose that a death singularity takes place in a dotted component containing a segment of $\alpha_{t'_1}^-$. Let γ_1 be the segment of $\alpha_{t'_1}^-$, running from a dot to the primary boundary component. Choose an arc γ'_1 in the same dotted component that runs from a dot to the point where γ_1 exits the dotted component, so that γ'_1 is disjoint from a neighborhood containing the two dying dots. This is possible because the number of dots in each dotted component is odd. By Lemma 3.3, $\alpha_{t'_1}^-$ is $g_{t'_1}$ -equivalent to the arc formed by replacing γ_1 by γ'_1 . We take $\alpha_{t'_1}^+$ to be the arc, $g_{t'_1}$ -equivalent to $\alpha_{t'_1}^-$, which is obtained from $\alpha_{t'_1}^-$ after making all these changes. See Figure 7. See also Figure 8 for an example, illustrated in \mathbb{R}^3 , of how Lemma 3.3 may be applied.

We have constructed a family of arcs α_t in D that varies continuously until time $t'_1 = t_1 - \varepsilon$. It then jumps from $\alpha_{t'_1}^-$ to the $g_{t'_1}$ -equivalent arc $\alpha_{t'_1}^+$. The arc $\alpha_{t'_1}^+$ was

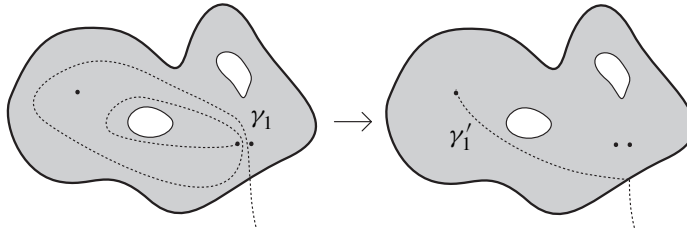


Figure 7. Changing $\alpha_{t_1}^-$ so that it avoids a death singularity.

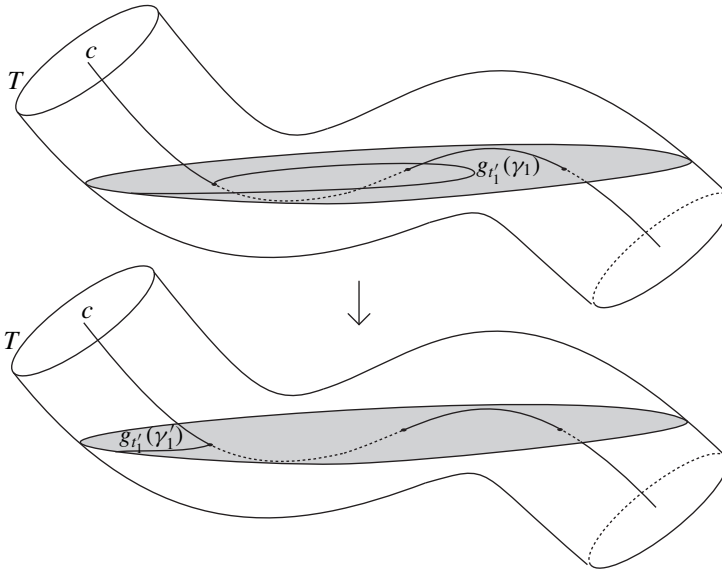


Figure 8. Illustrating Lemma 3.3, where an arc can be homotoped to a new arc through arcs in the complement of c .

chosen to avoid a neighborhood of the death singularity at time t_1 , so we can extend the family of arcs α_t past time $t = t_1$ until just before the next death singularity at time $t = t_2$. We then repeat this process.

Eventually, at time $t = t_l \in (0, 1)$ the two dotted components must merge along $g_{t_l}^{-1}(\partial T)$. At this time $g_{t_l}^{-1}(\partial T)$ consists of a collection of finitely many simple closed curves and one bouquet of finitely many circles embedded in D . The arc α_{t_l} begins and ends at a dot, and may run in and out of the single dotted component.

We now look at the complementary components in D of the single dotted component of $g_{t_l}^{-1}(T)$. Each of these is either a disk or an annulus with ∂D as one boundary component. Any subarc β of α_{t_l} that runs out of a dotted component into a complementary component X eventually leaves X and reenters the dotted component. Since X is either a disk or an annulus having ∂D as one of its boundary

components, we can homotope β rel endpoints off X and into the dotted component without passing through any dots, since all dots lie within the single dotted component. In this way we can homotope α_{t_i} so that it lies entirely within the dotted component of $g_{t_i}^{-1}(T)$. This means that $g_{t_i}(\alpha_{t_i})$ now lies entirely within T . It is then straightforward to shrink $g_{t_i}(\alpha_{t_i})$ within T , keeping its interior disjoint from c and its endpoints on c , until it collapses to a point on c .

We now form a spanning disk E for c . Let $\beta_t = g_t \circ \alpha_t$, $t \in [0, t_i]$. Then β_t is a family of arcs in \mathbb{R}^3 whose endpoints lie on c and whose interiors are disjoint from c . These arcs vary continuously except at finitely many times t'_1, t'_2, \dots, t'_n just before death singularities. At these times the limiting arcs $\alpha_{t'_i}^-$ and $\alpha_{t'_i}^+$, as t approaches t'_i from below and above, are $g_{t'_i}$ -equivalent. Finally, α_{t_i} is homotopic to a point on c via arcs that start and end on c but have interiors disjoint from c . Therefore there is a family of arcs, with endpoints on c sweeping out a disk with interior in the complement of c , that represents a homotopy of β_0 to a point in c . Let \bar{E} denote the union of these arcs in \mathbb{R}^3 and take E to be the disk obtained by taking the union of \bar{E} with its reflection in the xz -plane. Note that the interior of E does not intersect c and that $\partial E \subseteq c$.

Let a be one of the two points of intersection of c with $g_0(D)$. Then ∂E intersects a in an odd number of points, one coming from β_0 and an additional even number coming from equal numbers of intersections of a with $\partial \bar{E}$ and its reflection. So ∂E is nontrivial in $\pi_1(c)$. By the Loop Theorem [Papakyriakopoulos 1957], c is the boundary of an embedded disc and therefore unknotted. □

4. Proof of Theorem 1.2

We now prove Theorem 1.2, showing that if L can be split via a physical isotopy then the length of L_1 must be at least $4\pi + 6$. Note that in this isotopy both components may move.

Assume there is a physical isotopy I_s , $s \in [0, 1]$, of \mathbb{R}^3 with I_0 the identity, I_1 taking L_1 and L_2 to opposite sides of a plane, and with the length of the unknotted component L_1 being less than $4\pi + 6$. We will derive a contradiction.

During the course of the isotopy I_s it is possible that the radius-one solid torus neighborhoods of the two link components bump against themselves or each other. We describe a slight modification of the isotopy that keeps the two components embedded and disjoint. Throughout the isotopy, tubular neighborhoods of any radius $r < 1$ give embedded disjoint solid torus neighborhoods of each of L_1 and L_2 . Take $r = 1 - \varepsilon'$ to be slightly less than 1 and then rescale the entire isotopy I_s by $1/(1 - \varepsilon')$. This restores the radius to 1 at the cost of slightly lengthening L_1 and L_2 . With ε' small, the length of L_1 remains below $4\pi + 6$. The rescaled physical isotopy is then $(1 + \varepsilon)$ -thick, with $\varepsilon = \varepsilon'/(1 - \varepsilon')$.

For a curve c in \mathbb{R}^3 , let $T(c)$ denote the radius-1 tubular neighborhood of c . Without loss of generality we can assume that the isotopy I_s preserves $T(L_1)$ and $T(L_2)$, so that $I_s(T(L_i)) = T(I_s(L_i))$ for $i = 1, 2$. We then let T_s denote the solid torus $T(I_s(L_2))$. For each $s \in [0, 1]$, let x_s be the center of mass of the embedded curve $I_s(L_1)$ and let $f_s : D \rightarrow \mathbb{R}^3$ parametrize the disk forming the cone over $I_s(L_1)$ with cone point x_s . Since the cone point is inside the convex hull, its cone angle is always at least 2π [Cantarella et al. 2002; Gage 1980; Gromov 1983]. The maps $f_s : D \rightarrow \mathbb{R}^3$ induce a family of metrics on the disk D , parametrized by s , in which each disc is flat except at the cone point and is therefore a subdisk of a complete CAT(0) surface obtained by extending the rays from the cone point to infinity.

Now perturb f_s , $s \in [0, 1]$, so that the family of maps f_s is generic, but leaving f_s unchanged for s in a small neighborhood of 0 and unchanged on ∂D for all s . By generic, we mean that

- (1) f_s is transverse to c except for a finite number of times s at which a birth or death of a pair of points of $f_s^{-1}(c)$ occurs;
- (2) f_s is transverse to ∂T at these times; and
- (3) f_s is transverse to ∂T except for a finite number of times when $f_s^{-1}(\partial T)$ consists of finitely many simple closed curves and a single component that is a bouquet of finitely many circles (in the case of a saddle-type singularity) or a single point (in the case of a birth or death singularity).

Genericity can be achieved by approximating the appropriate parts of f_s by PL maps and using general position. The perturbation can be made arbitrarily \mathcal{C}^0 -small, and we let f'_s denote the result of perturbing f_s in this manner.

Each component of $f_s'^{-1}(T_s)$ in D that contains a point of $f_s'^{-1}(I_s(L_2))$ contains a disc of radius 1 in D enclosing that point, measured in the induced metric. The distance in D of ∂D from each of these components is at least 1. Suppose for a contradiction that there are three components of $f_s'^{-1}(T_s)$ containing a point of $f_s'^{-1}(I_s(L_2))$ for some s and furthermore suppose that this is true no matter how small we made the perturbation of f_s that gave f'_s . Then $f_s'^{-1}(T_s)$ contains three disks of radius 1 with disjoint interiors, and with ∂D having distance at least 1 from each disk. This contradicts Proposition 2.1, since L_1 has length less than $4\pi + 6$. Hence, by taking the perturbation to obtain f'_s to be sufficiently small, we can arrange that for all s there are at most two components of $f_s'^{-1}(T_s)$ containing a point of $f_s'^{-1}(I_s(L_2))$.

We now define a family of disks $h_s : D \rightarrow \mathbb{R}^3$, $0 \leq s \leq 1$, by setting $h_s = I_s^{-1} \circ f'_s$. Extend h_s to $-1 \leq s \leq 0$ by reflecting through the xz -plane, setting $h_s = r \circ h_{-s}$ for $s < 0$. Each h_s maps ∂D to L_1 and for $s \in [-1, 1]$ the preimage $h_s^{-1}(T(L_2))$ has at most two components containing a point of $h_s^{-1}(L_2)$. Moreover $h_0(D)$ lies

in the xz -plane, and $h_1(D)$ and $h_{-1}(D)$ are disjoint from L_2 . The disks $h_s(D)$ now satisfy all the conditions of Proposition 3.1, implying that L_2 is unknotted. This contradiction proves Theorem 1.2. \square

5. Some open problems

The following related problems remain open.

- (1) Does there exist a Gordian unknot?
- (2) Can the methods of Theorem 1.2 be extended to produce a Gordian split link with two unknotted components?
- (3) In Theorem 1.2 the length of each component is fixed. One can formulate a problem where the sum of the component lengths is fixed but the individual components are allowed to stretch. Is there a Gordian split link in that setting?

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ALEXANDER COWARD
DEPARTMENT OF MATHEMATICS
UC BERKELEY
970 EVANS HALL #3840
BERKELEY, CA 94720
UNITED STATES
coward@math.berkeley.edu

JOEL HASS
MATHEMATICS DEPARTMENT
UNIVERSITY OF CALIFORNIA
DAVIS, CA 95616
UNITED STATES
hass@math.ucdavis.edu

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Los Angeles, CA 90095-1555
balmer@math.ucla.edu

Robert Finn
Department of Mathematics
Stanford University
Stanford, CA 94305-2125
finn@math.stanford.edu

Sorin Popa
Department of Mathematics
University of California
Los Angeles, CA 90095-1555
popa@math.ucla.edu

Vyjayanthi Chari
Department of Mathematics
University of California
Riverside, CA 92521-0135
chari@math.ucr.edu

Kefeng Liu
Department of Mathematics
University of California
Los Angeles, CA 90095-1555
liu@math.ucla.edu

Jie Qing
Department of Mathematics
University of California
Santa Cruz, CA 95064
qing@cats.ucsc.edu

Daryl Cooper
Department of Mathematics
University of California
Santa Barbara, CA 93106-3080
cooper@math.ucsb.edu

Jiang-Hua Lu
Department of Mathematics
The University of Hong Kong
Pokfulam Rd., Hong Kong
jhlu@maths.hku.hk

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Princeton University
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
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