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Grove and Shiohama used the critical point theory of a distance function to prove the diameter sphere theorem. In light of the angular distribution of minimizing geodesics, we examine and develop the techniques in its proof to make some diameter sphere theorems and study complete noncompact manifolds, using a generalized Toponogov comparison theorem.

1. Introduction

Let M be a compact Riemannian n -manifold with distance $d(\cdot, \cdot)$ induced from its Riemannian metric. Let $\text{diam}(M) = \max\{d(x, y) \mid x, y \in M\}$ denote its diameter. Grove and Shiohama [1977] have proved that if the sectional curvature of M is greater than or equal to 1 and $\text{diam}(M) > \pi/2$, then M is homeomorphic to an n -sphere, using the critical point theory of a distance function. From this point of view, the unit sphere has nice properties as a reference surface. We examine those properties to make some other diameter sphere theorems and show some conditions under which M is diffeomorphic to an n -plane. In order to do this, we introduce the angular distribution of minimizing geodesic segments and the reference map from M into a reference surface. The angular distribution measures how the minimizing geodesics are distributed in M . The reference map will be used to compare the geometry on M with the geometry on a reference surface \tilde{M} through the generalized Toponogov comparison theorem.

In Section 2, we define the angular distribution of minimizing geodesic segments connecting two points and the reference map $\Phi_{p,q}$ for q in (M, p) with a base point at p into a reference surface (\tilde{M}, \tilde{p}) of revolution with vertex \tilde{p} . We propose a domain $D(\tilde{p}, \tilde{q}) \subset \tilde{M}$ such that the generalized Toponogov comparison theorem is valid if $\Phi_{p,q}(M) \subset D(\tilde{p}, \tilde{q})$. Using this terminology we state some theorems.

In Section 3, we summarize some properties of geodesics in a surface of revolution and present the generalized Toponogov comparison theorem of the form used in

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this note. In Section 4, we show some properties of the domain $D(\tilde{p}, \tilde{q})$ and give proofs of the theorems stated in Section 2. In Section 5, we study the case that \tilde{M} is a κ -plane M_κ — which is, by definition, a complete simply connected Riemannian surface with constant Gaussian curvature κ . We have some sphere theorems depending on the relation among the angular distribution of minimizing geodesic segments, the distance between two points, and the Gaussian curvature of a model surface. In Section 6, we discuss the case of noncompact manifolds referred to a κ -plane with $\kappa < 0$.

Klingenberg [1963] was first interested in radial sectional curvature. Some roles of critical point theory have been introduced in [Abresch and Meyer 1997]. A general introduction to the techniques used in this note is found in [Cheeger and Ebin 1975]. There are some generalized Toponogov comparison theorems for radial curvature. But the version used in this note was first proved in [Itokawa et al. 2001; 2003] and developed in [Kondo and Tanaka 2010; Innami et al. 2013a]. As its application, some diameter sphere theorems have been proved in [Kondo 2007; Kondo and Ohta 2007; Lee 2005; Innami et al. 2013b]. The geometry of geodesics on surfaces of revolution has been developed in [Belegradek et al. 2012; Sinclair and Tanaka 2007; Tanaka 1992].

2. Definitions and statements

Let M be a complete Riemannian manifold. We introduce a function $\alpha_p(x)$ that measures the angular distribution of minimizing geodesic segments from x to p . For $p \in M$ let $d_p(x) = d(p, x)$ for all $x \in M$. Let $T_x M$ denote the tangent space of M at x . Let $A_p(x)$ be the set of tangent vectors $T(x, p)^*(0)$ at $x \neq p$ of all minimizing geodesic segments $T(x, p)$ from x to p . The geodesics are supposed to be parameterized by arclength. Let $\beta_x(v) = \min\{\angle(v, w) \mid w \in A_p(x)\}$ for $v \in T_x M$ and

$$\alpha_p(x) = \max\{\beta_x(v) \mid v \in T_x M\}.$$

Obviously, $\alpha_p(x) \leq \pi$ for all $x \in M$, $x \neq p$. If x is not a cut point of p , then $\alpha_p(x) = \pi$. We call $\alpha_p(x)$ the *angular distribution* of $A_p(x)$ in the unit sphere $S_x M$ in $T_x M$. We call $x \in M$ a *critical point* of d_p if $\alpha_p(x) \leq \pi/2$. If $p, q \in M$ satisfy $d(p, q) = \text{diam}(M)$, then q is a critical point of d_p , and p is a critical point of d_q .

The distribution of critical points of d_p depends on the topological and metric structure of M . The diameter sphere theorem is based on the following lemma due to Grove and Shiohama [1977].

Lemma 2.1 (basic lemma). *Let M be a complete Riemannian manifold and $p \in M$. If there exists no critical point of d_p in $M \setminus \{p\}$, then M is diffeomorphic to the Euclidean space \mathbb{E}^n . If there exists only one critical point $q \in M \setminus \{p\}$ of d_p and*

if $\alpha_p(q) < \pi/2$ or $d_p(q) = \max\{d_p(x) \mid x \in M\}$, then M is homeomorphic to an n -sphere.

In this note, using the angular distribution, we propose some conditions under which the assumption of Lemma 2.1 is satisfied. In order to do this we use the generalized Toponogov comparison theorem for radial curvature proved in [Itokawa et al. 2003; Innami et al. 2013a; Kondo and Tanaka 2010].

Let (\tilde{M}, \tilde{p}) be a surface of revolution homeomorphic to a sphere or a plane with a geodesic polar coordinate system (r, θ) around \tilde{p} . Its metric is of class C^2 and given by

$$ds^2 = dr^2 + m(r)^2 d\theta^2,$$

where $m(r) > 0$, $0 < r < \ell \leq \infty$, $\theta \in S^1$, and $m : [0, \ell) \rightarrow \mathbb{R}$ satisfies the Jacobi equation

$$m'' + \tilde{K}m = 0, \quad m(0) = 0, \quad m'(0) = 1,$$

and if $\ell < \infty$,

$$m(\ell) = 0, \quad m'(\ell) = -1.$$

The function \tilde{K} is called the *radial curvature function* of \tilde{M} .

Let (M, p) be a complete Riemannian manifold with a base point at p . A *radial plane* $\Pi \subset T_x M$ at a point $x \in M$ is a plane containing a vector tangent to a minimizing geodesic segment emanating from p . A *radial sectional curvature* $K_M(\Pi)$ is a sectional curvature with respect to a radial plane Π . We say that (M, p) is *referred* to (\tilde{M}, \tilde{p}) if every radial sectional curvature at $x \in M$ is bounded below by $\tilde{K}(d(p, x))$, namely, $K_M(\Pi) \geq \tilde{K}(d(p, x))$.

Let (M, p) be referred to (\tilde{M}, \tilde{p}) . If $\ell < \infty$, we then have $d_p(x) \leq \ell$ for all $x \in M$, equality holding if and only if M is isometric to the warped product $S^{n-1} \times_m [0, \ell]$, where $n = \dim M$ and S^{n-1} is a sphere; see [Itokawa et al. 2001]. From this fact, we may assume that $\max\{d_p(x) \mid x \in M\} < \ell$ if $\ell < \infty$, because our purpose is to study some conditions on M being homeomorphic to a sphere. Thus, we have the point $\tilde{q} = (d(p, q), 0) \in \tilde{M}$ for any point $q \in M$.

Let $\Phi_{p,q}$ denote the reference map from M to the east side \tilde{M}^+ of the meridian containing $T(\tilde{p}, \tilde{q})$ in \tilde{M} , namely $\tilde{M}^+ = \{(r, \theta) \mid 0 \leq r, 0 \leq \theta \leq \pi\}$. By definition, for a point $x \in M$,

$$d(\tilde{p}, \Phi_{p,q}(x)) = d(p, x) \quad \text{and} \quad d(\tilde{q}, \Phi_{p,q}(x)) = d(q, x).$$

It is not certain whether or not every point $x \in M$ has a reference point and every geodesic triangle $\Delta(pqx)$, $q, x \in M$, admits the corresponding geodesic triangle $\Delta(\tilde{p}\tilde{q}\tilde{x})$, $\tilde{q}, \tilde{x} \in \tilde{M}$. This question has been answered affirmatively under a certain condition in [Innami et al. 2013a]. However, we use only a quarter of \tilde{M} in the critical point theory. More precisely, as the image space of the reference map $\Phi_{p,q}$,

we define a special domain $D(\tilde{p}, \tilde{q})$ in \tilde{M}^+ for $\tilde{q} = (r_0, 0) \in \tilde{M}$, $0 < r_0 < \ell$. For $\theta \in [0, \pi/2]$ let

$$\lambda_{\tilde{q}}(\theta) = \sup \left\{ r > 0 \mid \angle \left(v_s, -\frac{\partial}{\partial r} \right) > \frac{\pi}{2}, v_s \in A_{\tilde{q}}(z_s), \right. \\ \left. \angle \left(w_s, -\frac{\partial}{\partial r} \right) < \frac{\pi}{2}, w_s \in A_{z_s}(\tilde{q}), 0 \leq s < r \right\}$$

where $z_s = (s, \theta)$, and set

$$D(\tilde{p}, \tilde{q}) = \{(r, \theta) \in \tilde{M} \mid 0 \leq r < \lambda_{\tilde{q}}(\theta), 0 \leq \theta < \pi/2\} \cup \{\tilde{p}, \tilde{q}\}.$$

Obviously, $D(\tilde{p}, \tilde{q}) \supset T(\tilde{p}, \tilde{q})$, since $\angle(\tilde{p}z\tilde{q}) = \pi$ for all $z \in T(\tilde{p}, \tilde{q}) \setminus \{\tilde{p}, \tilde{q}\}$. Moreover, as will be shown in Lemma 4.1, there exists no cut point of \tilde{q} in $D(\tilde{p}, \tilde{q})$. Hence, if $\Phi_{p,q}(M) \subset D(\tilde{p}, \tilde{q})$, then the generalized Toponogov comparison theorem is valid for all geodesic triangles $\Delta(pqx)$ and for all $x \in M$.

We define a dominant triangle for M with respect to p and q . Let $z \in \tilde{M}$ and T a minimizing geodesic segment with $z \in T$. For an angle ω let $S = S(z, T, \omega)$ denote the geodesic such that the angle of S with T at z is ω . We make a trilateral with three geodesic segments:

$$S_0 = T(\tilde{p}, \tilde{q}), \quad S_1 = S(\tilde{p}, T(\tilde{p}, \tilde{q}), \alpha_q(p)), \quad S_2 = S(\tilde{q}, T(\tilde{p}, \tilde{q}), \alpha_p(q)).$$

We call the domain D_M bounded by S_0 , S_1 and S_2 a *dominant domain* for M if it exists. The dominant domain D_M becomes a triangle if S_1 and S_2 intersect. Otherwise, it may not become a triangle. If S_0 , S_1 and S_2 make a triangle, we call it the *dominant triangle* for M , and it is denoted by $\Delta_M = \Delta(T(\tilde{p}, \tilde{q}), \alpha_q(p), \alpha_p(q))$.

For a triangle Δ , the triangle domain bounded by Δ in \tilde{M}^+ is also denoted by Δ . If the dominant triangle Δ_M exists and the generalized Toponogov comparison theorem is valid for (M, p) referred to (\tilde{M}, \tilde{p}) , then $\Phi_{p,q}(M) \subset \Delta_M$ because of the Alexandrov convexity. The vertex of the dominant triangle Δ_M other than \tilde{p} and \tilde{q} is denoted by $z(\Delta_M)$.

Theorem 2.2. *Let (M, p) be a complete Riemannian manifold referred to (\tilde{M}, \tilde{p}) . Assume that there exists a point q in M such that the dominant triangle $\Delta_M = \Delta(T(\tilde{p}, \tilde{q}), \alpha_q(p), \alpha_p(q))$ for M can be made from p and q . If $z(\Delta_M) \in D(\tilde{p}, \tilde{q})$, then M is topologically an n -sphere.*

We have a generalization of the diameter sphere theorem if we impose a certain condition on \tilde{M} ; see Lemma 4.3. We say that \tilde{M} is *without conjugate points in a half* if any point $z \in \text{Int}(\tilde{M}^+)$ has no point conjugate to z along any geodesic segment from z contained in $\text{Int}(\tilde{M}^+)$. Here $\text{Int}(\tilde{M}^+)$ is the interior of \tilde{M}^+ . Any point in $\text{Int}(\tilde{M}^+)$ has no cut point in $\text{Int}(\tilde{M}^+)$ if and only if \tilde{M} is without conjugate points in a half. Tanaka [1992] proved that \tilde{M} is without conjugate points in a half if \tilde{M} is a von Mangoldt surface of revolution.

We say that \tilde{M} is *without meridian focal points in a quarter* if there exists no focal point of the meridian $\{(r, 0) \mid 0 \leq r \leq \ell\}$ in a quarter $\{(r, \theta) \mid 0 \leq r < \ell, 0 < \theta < \pi/2\}$ of \tilde{M} . If \tilde{M} is without conjugate points in a half, then it is without meridian focal points in a quarter; see Proposition 3.1. If \tilde{M} is without meridian focal points in a quarter, then it is without conjugate points in a quarter; see Proposition 3.2.

If \tilde{M} is without meridian focal points in a quarter and $m'(r(\tilde{q})) < 0$, then $\Delta(T(\tilde{p}, \tilde{q}), \pi/2, \pi/2) \subset D(\tilde{p}, \tilde{q})$; see Lemma 4.3. Kondo and Ohta [2007] have proved the following corollary, assuming that \tilde{M} is a von Mangoldt surface of revolution.

Corollary 2.3. *Let (\tilde{M}, \tilde{p}) be a reference surface homeomorphic to a sphere such that \tilde{M} is without meridian focal points in a quarter. Let (M, p) be a complete Riemannian manifold referred to (\tilde{M}, \tilde{p}) . If there exists a point $q \in M$ such that q and p are critical points of d_p and d_q , respectively, and if $m'(d_p(q)) < 0$, then M is homeomorphic to an n -sphere.*

When $\ell = \infty$, let $\tilde{\gamma}(t) = (t, 0)$ for $t \in [0, \infty)$. For $\theta \in [0, \pi]$, let $\lambda_{\tilde{\gamma}}(\theta)$ denote the supremum of those $r > 0$ such that there exists a unique coray from (s, θ) , $0 < s < r$, to $\tilde{\gamma}$ whose initial tangent vector v satisfies $\angle(v, -\partial/\partial r) > \pi/2$. Using this function $\lambda_{\tilde{\gamma}}(\theta)$, we define a special domain $D(\tilde{\gamma})$ in a reference surface of revolution \tilde{M} . Namely, we set

$$D(\tilde{\gamma}) = \{(r, \theta) \in \tilde{M} \mid 0 \leq r < \lambda_{\tilde{\gamma}}(\theta), 0 \leq \theta \leq \pi\}.$$

Obviously, $\lambda_{\tilde{\gamma}}(0) = \infty$. Let $\rho_{\tilde{p}}(\tilde{\gamma}) = \sup\{\theta_0 \mid \lambda_{\tilde{\gamma}}(\theta) = \infty \text{ for } \theta \in [0, \theta_0)\}$. When \tilde{M} is a κ -plane with $\kappa \leq 0$, we have $\rho_{\tilde{p}}(\tilde{\gamma}) = 0$ if $\kappa < 0$ and $\rho_{\tilde{p}}(\tilde{\gamma}) = \pi/2$ if $\kappa = 0$. If \tilde{M} is a paraboloid of revolution, then $\rho_{\tilde{p}}(\tilde{\gamma}) = \pi$.

Let Γ_p denote the set of all rays from p in (M, p) . Let

$$\eta_p(v) = \min\{\angle(v, \dot{\gamma}(0)) \mid \gamma \in \Gamma_p\}$$

for any $v \in T_p M$, and set

$$\zeta_p = \max\{\eta_p(v) \mid v \in T_p M\}.$$

Obviously, $\zeta_p \leq \pi$ for all $p \in M$. We call ζ_p the *angular distribution of rays* from p . We call $\tilde{M}^+(\theta_0) = \{(r, \theta) \mid 0 \leq r < \ell, 0 \leq \theta \leq \theta_0\}$ a *sector* of \tilde{M} for $\theta_0 \in [0, \pi]$.

Theorem 2.4. *Let (M, p) be a complete noncompact Riemannian n -manifold referred to (\tilde{M}, \tilde{p}) such that $\rho_{\tilde{p}}(\tilde{\gamma}) > 0$. Assume that the sector $\text{Int}(\tilde{M}^+(\rho_{\tilde{p}}(\tilde{\gamma})))$ is without conjugate points. If $\zeta_p < \rho_{\tilde{p}}(\tilde{\gamma})$, then M is diffeomorphic to an n -plane.*

Since $\rho_{\tilde{p}}(\tilde{\gamma}) = 0$ for M_κ with $\kappa < 0$, the theorem shows an advantage of using a surface of revolution as a reference surface.

3. Preliminaries

Let (\tilde{M}, \tilde{p}) be a surface of revolution with vertex \tilde{p} and let $\gamma : (-\infty, \infty) \rightarrow \tilde{M}$ be a geodesic with unit speed. We write $\gamma(s) = (r(s), \theta(s))$ for all $s \in (-\infty, \infty)$. Let $\{E_1(s) = \dot{\gamma}(s), E_2(s)\}$ denote a set of parallel orthonormal vector fields along γ . Since the vector field $Y(s) = \partial/\partial\theta$ along γ is generated from a variation through geodesics $\gamma_u(s) = (r(s), \theta(s) + u)$, it is a Jacobi vector field along γ . If $\varphi(s)$ denotes the angle of $Y(s)$ with $\dot{\gamma}(s)$, we then have $\langle E_1(s), Y(s) \rangle = m(r(s)) \cos \varphi(s) = v$ which is called the Clairaut relation. Note that $-m(r(0)) \leq v \leq m(r(0))$. The orthogonal complement of $Y(s)$ to $\dot{\gamma}(s)$ is $\sqrt{m(r(s))^2 - v^2} E_2(s)$. Therefore,

$$y(s) = \sqrt{m(r(s))^2 - v^2}$$

satisfies the Jacobi equation,

$$y''(s) + \tilde{K}(r(s))y(s) = 0.$$

If $C(\gamma) = \{s \mid r'(s) = 0\}$, then the number of elements of $C(\gamma)$ is 1 or ∞ . The Sturm separation theorem states that if $C(\gamma) = \{s_0\}$, then for every $s < s_0$ there exists at most one point $\gamma(s_1)$, $s_1 > s_0$, conjugate to $\gamma(s)$. The Clairaut relation states that if $\dots < s_{-1} < s_0 < s_1 < \dots$ are the solutions of the equation $y(s) = 0$, then γ is tangent to the parallel circle $r = r(s_i)$ with $m(r(s_i)) = v$ and $\gamma(s_i)$ are conjugate to one another for $i \in \mathbb{Z}$. From the Sturm separation theorem, if $\bar{y}(s)$ is the length of a perpendicular Jacobi vector field along γ such that $\bar{y}(t_0) = 0$, $s_0 < t_0 < s_1$, then the zeros of $\bar{y}(s)$ appear in each interval (s_i, s_{i+1}) once for every $i \in \mathbb{Z}$.

Proposition 3.1. *Let (\tilde{M}, \tilde{p}) be a surface of revolution with vertex \tilde{p} . If \tilde{M} is without conjugate points in a half, then \tilde{M} is without meridian focal points in a quarter.*

Proof. Suppose that \tilde{M} is not without meridian focal points in a quarter. Then there exists a geodesic $\gamma : [0, a] \rightarrow \text{Int}(\tilde{M}^+)$ normal to the meridian $\theta = \pi/2$ such that $\theta(\gamma(a)) = \pi/2$ and $\gamma(0)$ is a focal point of $\theta = \pi/2$ along γ . Since \tilde{M} is a surface of revolution, \tilde{M} is symmetric with respect to $\theta = \pi/2$. From this symmetry, if $\gamma_e : [0, \infty) \rightarrow \tilde{M}$ denotes the extension of γ , we see that $\gamma_e(2a) \in \text{Int}(\tilde{M}^+)$ is a point conjugate to $\gamma_e(0)$. Namely, \tilde{M} is not without conjugate points in a half. \square

Proposition 3.2. *Let (\tilde{M}, \tilde{p}) be a surface of revolution with vertex \tilde{p} . Assume that \tilde{M} is without meridian focal points in a quarter. Then, \tilde{M} is without conjugate points in a quarter. In particular, there exists a unique geodesic segment in $\tilde{M}^+(\pi/2)$ connecting any two points in $\tilde{M}^+(\pi/2)$.*

Proof. Suppose that there exists a geodesic segment $\omega : [0, L] \rightarrow \tilde{M}^+(\pi/2)$ such that $\omega(L)$ is the first point conjugate to $\omega(0)$ along ω . Then, $r(s) = r(\omega(s))$, $s \in [0, L]$, is not monotone because \tilde{M} is a surface of revolution without meridian focal points in a quarter. Assume that $r'(s_0) = 0$ at s_0 with $0 < s_0 < L$.

The complete extension of ω is denoted by the same symbol and its parametrization is changed by $\bar{\omega}(s) = \omega(s + s_0)$, $s \in (-\infty, \infty)$. By the symmetry of \tilde{M} with respect to the meridian through $\bar{\omega}(0)$, $\bar{\omega}(s_0)$ is a point conjugate to $\bar{\omega}(s_0 - L)$. From the Sturm separation theorem, there exists a number $L_1 > 0$ such that $s_0 - L < -L_1 < 0$ and $\bar{\omega}(L_1)$ is a point conjugate to $\bar{\omega}(-L_1)$ along $\bar{\omega}$. Then, $\bar{\omega}(L_1)$ is a focal point of the meridian through $\bar{\omega}(0)$ along $\bar{\omega}$ and $|\theta(\bar{\omega}(0)) - \theta(\bar{\omega}(L_1))| < \pi/2$. This contradicts that \tilde{M} is without meridian focal points in a quarter.

We prove the second part. If there exist two geodesic segments connecting the same endpoints in $\tilde{M}^+(\pi/2)$, then they may bound a biangle domain in $\tilde{M}^+(\pi/2)$. There exists a minimizing geodesic segment in the biangle domain such that the endpoints are conjugate to each other. This contradicts the first part. \square

Lemma 3.3. *Let (\tilde{M}, \tilde{p}) be a surface of revolution with vertex \tilde{p} . If \tilde{M} is without meridian focal points in a quarter, then $\text{Int}(\tilde{M}^+)$ is foliated by geodesics perpendicular to the meridian $\theta = \pi/2$. In particular, if \tilde{M} is compact, then those geodesics cross the meridian $\theta = 0$ at points between the focal points along the meridian $\theta = 0$.*

Proof. Let $z \in \text{Int}(\tilde{M}^+)$. Since \tilde{M} is without meridian focal points in a quarter, there exists a unique foot w of z on $\theta = \pi/2$, namely $z \in X = \theta^{-1}(\pi/2)$ and $d(z, w) = d(z, X)$. This proves the first part of the lemma.

If \tilde{M} is compact, then $\tilde{q} = (\ell, 0)$ is the unique point conjugate to $\tilde{p} = (0, 0)$. Hence, there exist focal points to $\theta = \pi/2$ along $\theta = 0$ from \tilde{p} and \tilde{q} . Let $(a, 0)$ and $(b, 0)$ be focal points of $\theta = \pi/2$ along $\theta = 0$ from \tilde{p} and $(\ell, 0)$, respectively. We then have $a \leq b$. In fact, if $a > b$, then the geodesics normal to $\theta = \pi/2$ from points near \tilde{p} and $(\ell, 0)$ meet in $\text{Int}(\tilde{M}^+)$, contradicting the first part. If $a = b$, then all geodesics normal to $\theta = \pi/2$ pass through $(a, 0)$. If $a < b$, then they pass the interval $([a, b], 0)$, keeping their order. \square

We review the generalized Toponogov comparison theorem. Let (M, p) be a complete Riemannian manifold referred to (\tilde{M}, \tilde{p}) . Let $q \in M, q \neq p$. For a point $x \in M$, let $\gamma : [0, a] \rightarrow M$ denote a minimizing geodesic segment such that $\gamma(0) = q$ and $\gamma(a) = x$. As was seen in [Itokawa et al. 2003], if $\Phi_{p,q}(\gamma(s)), s \in [0, a]$, do not intersect the cut locus $\text{Cut}(\tilde{q})$ of \tilde{q} in \tilde{M} , then the generalized Toponogov comparison theorem for the base angles is valid. Namely, we have

$$(1) \quad \angle(\tilde{p}\tilde{q}\tilde{x}) \leq \angle(pqx) \quad \text{and} \quad \angle(\tilde{p}\tilde{x}\tilde{q}) \leq \angle(pxq).$$

Let $\alpha : [0, b] \rightarrow M$ be a minimizing geodesic segment such that $\alpha(0) = p$ and $\alpha(b) = x$. As was seen in [Innami et al. 2013a], the generalized Toponogov comparison theorem for the angle at p is valid, under the condition that if $\Phi_{p,q}(\alpha(s)), s \in [0, b]$, intersects $\text{Cut}(\tilde{q})$ at $s = s_0$, then for any minimizing geodesic segment $T(\tilde{q}, \Phi_{p,q}(\alpha(s_0)))$, there exists a minimizing geodesic segment from q to $\alpha(s_0)$

satisfying (1). Namely, we then have

$$\angle(\tilde{q}\tilde{p}\tilde{x}) \leq \angle(qpx).$$

For $p, q, x \in M$, the minimum angle $\angle^i(pqx)$ and maximum one $\angle^s(pqx)$ are defined by

$$\begin{aligned} \angle^i(pqx) &= \min\{\angle(v, w) \mid v \in A_p(q), w \in A_x(q)\}, \\ \angle^s(pqx) &= \max\{\angle(v, w) \mid v \in A_p(q), w \in A_x(q)\}. \end{aligned}$$

It should be noted that there may not exist any triangle $\Delta(pqx)$ with three angles $\angle^s(pqx)$, $\angle^s(pxq)$, and $\angle^s(qpx)$.

In this note, we use the generalized Toponogov comparison theorem of the following form, which is a conclusion of the argument in [Itokawa et al. 2003].

Theorem 3.4. *Let (M, p) be a complete Riemannian manifold referred to a surface of revolution (\tilde{M}, \tilde{p}) . Let $q \in M, q \neq p$. If there exists a star-shaped domain D around \tilde{q} contained in the dominant domain D_M such that $\Phi_{p,q}(M) \subset D$, then for all $x \in M$,*

$$\angle(\tilde{p}\tilde{q}\tilde{x}) \leq \angle^i(pqx), \quad \angle(\tilde{p}\tilde{x}\tilde{q}) \leq \angle^i(pxq), \quad \angle(\tilde{q}\tilde{p}\tilde{x}) \leq \angle^i(qpx).$$

We say that a domain $D \subset \tilde{M}^+$ is star-shaped around \tilde{q} in \tilde{M} if there exists a unique minimizing geodesic segment from \tilde{q} to any point $z \in D$ contained in D .

4. Dominant domains

Let (\tilde{M}, \tilde{p}) be a surface of revolution homeomorphic to a sphere or a plane with a geodesic polar coordinate system (r, θ) around \tilde{p} . Let $\tilde{q} = (r_0, 0) \in \tilde{M}, 0 < r_0 < \ell$.

Lemma 4.1. *Let $D(\tilde{p}, \tilde{q})$ be the subset defined before. Then, there is no cut point of \tilde{q} in $D(\tilde{p}, \tilde{q})$, and $D(\tilde{p}, \tilde{q})$ is star-shaped around \tilde{p} and \tilde{q} .*

Proof. Let $z \in D(\tilde{p}, \tilde{q})$ and let $\gamma : [0, a] \rightarrow \tilde{M}, a = d(\tilde{q}, z)$, a minimizing geodesic segment such that $\gamma(0) = \tilde{q}, \gamma(a) = z, \angle(\dot{\gamma}(0), -\partial/\partial r) < \pi/2$, and $\angle(\dot{\gamma}(a), -\partial/\partial r) < \pi/2$. If $r(s) = r(\gamma(s)), s \in [0, a]$, then $r'(0) < 0$ and $r'(a) < 0$.

We prove that $\gamma(a)$ is not conjugate to $\gamma(0)$ along it. In order to prove this, it is enough to prove that $r(s)$ is monotone decreasing in $s \in [0, a]$, since \tilde{M} is a surface of revolution. If $r'(s) \geq 0$ for some $s \in [0, a]$, then, from $r'(a) < 0$, there exist at least two parameters s_1 and s_2 such that $0 < s_1 < s_2 < a$ and $r'(s_1) = r'(s_2) = 0$. This implies that $\gamma(s_2)$ is a point conjugate to $\gamma(s_1)$ along γ , contradicting the fact that $\gamma([0, a])$ is minimizing.

Next, we prove that z is joined to \tilde{q} by a unique minimizing geodesic. Suppose for indirect proof that $\gamma_1 : [0, a] \rightarrow \tilde{M}$ is another minimizing geodesic segment satisfying

the same condition as γ . Set $\varphi(s) = \angle(\dot{\gamma}(s), \partial/\partial\theta)$ and $\varphi_1(s) = \angle(\dot{\gamma}_1(s), \partial/\partial\theta)$ for $s \in [0, a]$. Without loss of generality, $0 > \varphi(0) > \varphi_1(0) > -\pi/2$, so

$$m(r(0)) \cos \varphi(0) > m(r(0)) \cos \varphi_1(0).$$

From this, the Clairaut relation states that

$$m(r(a)) \cos \varphi(a) > m(r(a)) \cos \varphi_1(a).$$

Therefore, we have $0 > \varphi(a) > \varphi_1(a) > -\pi/2$. On the other hand, since z is the first meeting point of γ and γ_1 , the relation between $\varphi(a)$ and $\varphi_1(a)$ must be $\varphi(a) < \varphi_1(a)$, a contradiction. This implies that z is not a cut point of \tilde{q} .

We next prove that $\gamma([0, a]) \subset D(\tilde{p}, \tilde{q})$. If $z = (r_0, \theta)$, then we define $z_t = (t, \theta)$ for $t \in [0, r_0]$. We set

$$t_0 = \sup\{s \mid T(z_t, \tilde{q}) \subset D(\tilde{p}, \tilde{q}) \text{ for all } t \in [0, s]\}.$$

From the first variation formula, we see there exists a number $\varepsilon > 0$ such that there exists a unique minimizing geodesic segment $T(z_t, \tilde{q})$ and $z_t \in D(\tilde{p}, \tilde{q})$ for every $t \in [0, \varepsilon]$. As seen above, $T(z_t, \tilde{q}) \subset D(\tilde{p}, \tilde{q})$ for all $t \in [0, \varepsilon]$; hence $t_0 > 0$. If $T(z_{t_0}, \tilde{q})$ is tangent to the parallel circle at \tilde{q} , then $t_0 = \lambda_{\tilde{q}}(\theta)$, contradicting $r_0 < \lambda_{\tilde{q}}(\theta)$. This is not the case. Otherwise, from the facts seen above, there exists a neighborhood of $T(z_{t_0}, \tilde{q})$ contained in $D(\tilde{p}, \tilde{q})$. This implies that $t_0 = r_0$. \square

This lemma makes it possible to use the generalized Toponogov comparison theorem if $\Phi_{p,q}(M) \subset D(\tilde{p}, \tilde{q})$.

Lemma 4.2. *Let (M, p) be a complete Riemannian manifold referred to (\tilde{M}, \tilde{p}) . Assume that there exists a point q in M such that the dominant triangle $\Delta_M = \Delta(T(\tilde{p}, \tilde{q}), \alpha_q(p), \alpha_p(q))$ for M can be made from p and q . If $z(\Delta_M) \in D(\tilde{p}, \tilde{q})$, then $\Phi_{p,q}(M) \subset \Delta_M \subset D(\tilde{p}, \tilde{q})$. In particular, the generalized Toponogov comparison theorem by $\Phi_{p,q}$ for (M, p) referred to (\tilde{M}, \tilde{p}) is valid.*

Proof. From Lemma 4.1, $D(\tilde{p}, \tilde{q})$ is star-shaped around \tilde{p} and \tilde{q} . Therefore, the triangle domain Δ_M satisfies $\Delta_M \subset D(\tilde{p}, \tilde{q})$.

We prove that $\Phi_{p,q}(M) \subset \Delta_M$. For a sufficiently small $\varepsilon > 0$, the generalized Toponogov comparison theorem is valid for all triangles $\Delta(pqx)$ if

$$d(p, x) + d(q, x) < d(p, q) + \varepsilon;$$

see [Itokawa et al. 2003; Innami et al. 2013a; Kondo and Tanaka 2010]. Let $\tilde{x} = \Phi_{p,q}(x)$. Since $\angle(\tilde{p}\tilde{q}\tilde{x}) \leq \angle(pqx) \leq \alpha_p(q)$ and $\angle(\tilde{q}\tilde{p}\tilde{x}) \leq \angle(qpx) \leq \alpha_q(p)$, we have $\tilde{x} \in \Delta_M$.

Let $x \in M$ be any point and $\gamma : [0, a] \rightarrow M$, a minimizing geodesic segment such that $\gamma(0) = q$ and $\gamma(a) = x$. We define

$$t_0 = \sup\{t \mid \Phi_{p,q}(\gamma(s)) \text{ is defined and } \Phi_{p,q}(\gamma(s)) \in \Delta_M \text{ for } s \in [0, t]\}.$$

As is seen above, we have $t_0 > 0$. Suppose for indirect proof that $t_0 < a$. Then $\tilde{y} = \Phi_{p,q}(\gamma(t_0))$ is defined and $\tilde{y} \in T(\tilde{q}, z(\Delta_M))$ or $\tilde{y} \in T(\tilde{p}, z(\Delta_M))$. Let \tilde{U} be an open set such that $\Delta_M \setminus T(\tilde{p}, \tilde{q}) \subset \tilde{U} \subset D(\tilde{p}, \tilde{q})$. Since \tilde{y} is not a cut point of \tilde{q} , there exists a number t_1 with $t_1 > t_0$, such that the points $\Phi_{p,q}(\gamma(s))$ exist in \tilde{U} for all $s \in [t_0, t_1]$ and $\tilde{x}_1 = \Phi_{p,q}(\gamma(t_1)) \notin \Delta_M$. In fact, we find those reference points because of the method in [Itokawa et al. 2003]. Therefore, we have either $\angle(\tilde{p}\tilde{q}\tilde{x}_1) > \alpha_p(q)$ or $\angle(\tilde{q}\tilde{p}\tilde{x}_1) > \alpha_q(p)$.

On the other hand, since there is no cut point of \tilde{q} in \tilde{U} , the generalized Toponogov comparison theorem is valid in $\Phi_{p,q}^{-1}(\tilde{U})$. Hence,

$$\angle(\tilde{p}\tilde{q}\tilde{x}_1) \leq \angle(pq\gamma(t_1)) \leq \alpha_p(q), \quad \angle(\tilde{q}\tilde{p}\tilde{x}_1) \leq \angle(qp\gamma(t_1)) \leq \alpha_q(p),$$

a contradiction. Therefore, $t_0 = a$ and $\tilde{x} \in \Delta_M$. □

Proof of Theorem 2.2. Since $z(\Delta_M) \in D(\tilde{p}, \tilde{q})$, we have both $\alpha_p(q) < \pi/2$ and $\alpha_q(p) < \pi/2$. In particular, q is a critical point of d_p . In order to apply Lemma 2.1, we have only to prove that there exists no critical point in $M \setminus \{p, q\}$. Let $x \in M$. From Lemma 4.2, the generalized Toponogov comparison theorem by $\Phi_{p,q}$ for (M, p) referred to (\tilde{M}, \tilde{p}) is valid. Hence, we have $\pi/2 < \angle(\tilde{p}\tilde{x}\tilde{q}) \leq \angle(pxq)$ since $\tilde{x} = \Phi_{p,q}(x) \in D(\tilde{p}, \tilde{q})$. Consequently, $\alpha_p(x) > \pi/2$, so x is not a critical point of d_p . □

A special case of the next lemma has been proved in [Kondo and Ohta 2007].

Lemma 4.3. *Let (\tilde{M}, \tilde{p}) be a reference surface without meridian focal points in a quarter and $\tilde{q} = (r_0, 0)$. If $m'(r_0) < 0$, then $\Delta = \Delta(T(\tilde{p}, \tilde{q}), \pi/2, \pi/2) \subset D(\tilde{p}, \tilde{q})$.*

Proof. We first prove that the domain Ω —bounded by the minimizing geodesic segment $T(\tilde{p}, \tilde{q})$, the parallel circle $r = r_0 = r(\tilde{q})$, and the meridian $\theta = \pi/2$ —is foliated by geodesic segments which are either tangent to $r = r_0$ or perpendicular to the meridian $\theta = \pi/2$ and cross the meridian $\theta = 0$.

Let $r_1 < r_0$ satisfy $m(r_1) = m(r_0)$ and $m(r) > m(r_0)$ for all $r \in (r_1, r_0)$. Since $m'(r_0) < 0$, there exists at least one r_1 . The Clairaut relation states that the strip between parallels $r = r_1$ and $r = r_0$ is foliated by the geodesic segments $T_\tau(t)$, $0 \leq t \leq t_0$, where $T_\tau(0) = (r_0, \tau)$, $\dot{T}_\tau(0) = -(1/m(r_0))\partial/\partial\theta$, and $r(T_\tau(t)) \in (r_1, r_0)$ for all $t \in (0, t_0)$. Hence the subset Ω_1 of Ω bounded by $T(\tilde{p}, \tilde{q})$, $r = r_0$, and $T_{\pi/2}$ is foliated by geodesic segments T_τ which are tangent to $r = r_0$.

Let $S_\sigma(t)$, $\sigma \in (0, r_0)$, denote the geodesic segments such that $S_\sigma(0) = (\sigma, \pi/2)$ and $\dot{S}_\sigma(0) = -(1/m(\sigma))\partial/\partial\theta$. Since there exists no point focal to $\theta = \pi/2$ in the sector $\{(r, \theta) \mid \theta \in (0, \pi/2)\}$, those geodesic segments give a foliation of the subset Ω_2 of Ω , bounded by $T(\tilde{p}, \tilde{q})$, $T_{\pi/2}$, and $\theta = \pi/2$; see Lemma 3.3. Since $\Omega = \Omega_1 \cup \Omega_2$, the first claim is proved.

Let $\gamma : [0, L] \rightarrow \tilde{M}$ denote the geodesic segment which is the edge of Δ opposite to \tilde{p} . Hence, we have $\gamma(0) = \tilde{q}$, $\dot{\gamma}(0) = (1/m(r_0))\partial/\partial\theta$, and $\theta(\gamma(L)) = \pi/2$. Let

$z = (r, \pi/2)$ for $r \in (0, r(\gamma(L)))$. From Proposition 3.2, there exists a unique minimizing geodesic segment $\omega : [0, L_1] \rightarrow \tilde{M}$ from \tilde{q} to z in Δ .

We have only to prove that the r -coordinate of ω is monotone decreasing. We have $\angle(\dot{\omega}(0), -\partial/\partial r) < \pi/2$ and $\angle(\dot{\omega}(L_1), -\partial/\partial r) > \pi/2$ because of the foliation given in the first part. Therefore, if it is not monotone, then there exist two parameters s_1 and s_2 such that ω is tangent to the parallel circles at s_1 and s_2 , since then $\omega(s_2)$ is a point conjugate to $\omega(s_1)$, contradicting the fact that ω is minimizing.

Since the r -coordinate of any geodesic segment from \tilde{q} in Δ is monotone decreasing, $\Delta(T(\tilde{p}, \tilde{q}), \pi/2, \pi/2) \subset D(\tilde{p}, \tilde{q})$. □

Proof of Corollary 2.3. This corollary follows from Proposition 3.1, Lemma 4.3 and Theorem 2.2, since $\Delta_M \subset \Delta(T(\tilde{p}, \tilde{q}), \pi/2, \pi/2) \subset D(\tilde{p}, \tilde{q})$. □

We need two lemmas to prove Theorem 2.4. For $z \in D(\tilde{\gamma})$, let $z_t \in T(\tilde{p}, z)$ be the point such that $r(z_t) = t$.

Lemma 4.4. *Let (\tilde{M}, \tilde{p}) be a surface of revolution with vertex \tilde{p} such that $\ell = \infty$ and let $\tilde{\gamma} : [0, \infty) \rightarrow \tilde{M}$ be a ray such that $\tilde{\gamma}(t) = (t, 0)$ for all $t \geq 0$. Let $z \in D(\tilde{\gamma})$. Then, there exists a number $R_0 > 0$ such that the angles of $T(z_t, \tilde{\gamma}(s))$ with $-\partial/\partial r$ at z_t are greater than $\pi/2$ for all $z_t \in T(\tilde{p}, z)$ and $s > R_0$.*

Proof. For any $s > 0$, let $\psi(s)$ be the supremum of the angles of $T(z_t, \tilde{\gamma}(s))$ with $-\partial/\partial r$ at z_t for all $z_t \in T(\tilde{p}, z)$. Then $\psi(s)$ is monotone and increasing in $s \in (0, \infty)$, since (\tilde{M}, \tilde{p}) is a surface of revolution homeomorphic to a plane. Since $T(z_t, \tilde{\gamma}(s))$ converges to the corays from z_t to $\tilde{\gamma}$, $\psi(s)$ converges to a real number greater than $\pi/2$ as $s \rightarrow \infty$. □

Lemma 4.5. *Let (M, p) be a complete noncompact Riemannian n -manifold referred to (\tilde{M}, \tilde{p}) . Let $\gamma : [0, \infty) \rightarrow M$ be a ray such that $\gamma(0) = p$. Then, for any points $x \in M$ and $z \in \tilde{M}$, there exists a sequence of parameters s_j such that $s_j \rightarrow \infty$ and the angles of $T(\gamma(s_j), x)$ with $-\dot{\gamma}(s_j)$ and $T(\tilde{\gamma}(s_j), z)$ with $-\dot{\tilde{\gamma}}(s_j)$ converge to zero as $j \rightarrow \infty$.*

Proof. This follows from the following inequality and the first variation formula.

$$|2s - d(\gamma(s), x) - d(\tilde{\gamma}(s), z)| \leq d(\gamma(0), x) + d(\tilde{\gamma}(0), z).$$

In fact, if this lemma is not true, then the left hand side of the inequality goes to ∞ as $s \rightarrow \infty$. □

Proof of Theorem 2.4. From Lemma 2.1, we have only to prove that there exists no critical point of d_p in $M \setminus \{p\}$. Let $x \in M \setminus \{p\}$ and $\alpha : [0, a] \rightarrow M$ a minimizing geodesic segment such that $\alpha(0) = p$ and $\alpha(a) = x$. From the assumption, there exists a ray $\gamma : [0, \infty) \rightarrow M$ from p such that $\angle(\dot{\gamma}(0), \dot{\alpha}(0)) \leq \zeta_p$. Let $z = (d(p, x), \xi)$, where $\zeta_p < \xi < \rho_{\tilde{p}}(\tilde{\gamma})$. For this point z , let $R_0 > 0$ denote the number given in Lemma 4.4. Furthermore, for this x and z , there exists a number $s_0 > R_0$

satisfying the property in Lemma 4.5. If Δ is the triangle domain bounded by $T(\tilde{p}, \tilde{\gamma}(s_0)) \cup T(\tilde{\gamma}(s_0), z) \cup T(\tilde{p}, z)$, as is seen in the proof of Lemma 4.1, then $\Delta \subset D(\tilde{p}, \tilde{\gamma}(s_0))$.

We have to prove that $\Phi_{p, \gamma(s_0)}(x) \in \Delta$. Since \tilde{p} is not a cut point of $\tilde{\gamma}(s_0)$, there exists a number $\varepsilon > 0$ such that if $0 \leq t < \varepsilon$, then $y_t = \Phi_{p, \gamma(s_0)}(\alpha(t)) \in \Delta$. In fact, $r(y_t) = t$ and $\angle(\tilde{\gamma}(s_0)\tilde{p}y_t) \leq \angle(\gamma(s_0)px) < \xi$, since the generalized Toponogov comparison theorem is valid in some neighborhood of $\gamma([0, s_0])$. Set

$$t_0 = \sup\{t \in (0, a) \mid y_t \in \Delta\}.$$

As seen before, $t_0 > 0$ and $\alpha(t_0) \in \Delta$. If $t_0 \neq a$, we find a number $\varepsilon_1 > 0$ such that $y_t \in \Delta$ for all $t \in (t_0, t_0 + \varepsilon_1)$, since the sector $\text{Int}(\tilde{M}^+(\rho_{\tilde{p}}(\tilde{\gamma})))$ is without conjugate points and, hence, the generalized Toponogov comparison theorem is valid. This contradicts the choice of t_0 . Thus, we have $y_a = \Phi_{p, \gamma(s_0)}(x) \in \Delta$.

Therefore, $\angle(\gamma(s_0)xp) \geq \angle(\tilde{\gamma}(s_0)y_a\tilde{p}) > \pi/2$, meaning that $\alpha_p(x) > \pi/2$. Thus, x is not a critical point of d_p . \square

5. The κ -plane as a reference surface for spheres

Let M_κ be the κ -plane, by definition isometric to the 2-sphere $S^2(1/\sqrt{\kappa})$ with radius $1/\sqrt{\kappa}$ if $\kappa > 0$, the Euclidean plane \mathbb{E}^2 if $\kappa = 0$, or the Poincaré disk with Gauss curvature κ if $\kappa < 0$. Notice that M_κ is without meridian focal points in a quarter. However, Lemma 4.3 is not applied if $\kappa \leq 0$, since no parameter r_0 exists such that $m'(r_0) < 0$. This means that the condition of being critical, namely $\alpha_p(q) \leq \pi/2$ and $\alpha_q(p) \leq \pi/2$, are not enough for a sphere theorem if the reference surface is M_κ , $\kappa \leq 0$. We need a restricted condition on $\alpha_p(q)$ and $\alpha_q(p)$ which depends on the distance $d(p, q)$ and κ .

Let M be a complete Riemannian n -manifold with sectional curvature bounded below by a constant κ . For points $p, q \in M$ we have points $\tilde{p}, \tilde{q} \in M_\kappa$ such that $d(p, q) = d(\tilde{p}, \tilde{q})$. When $\kappa > 0$, we assume that $d(p, q) < \pi/\sqrt{\kappa}$. Because, in general, $d(p, q) \leq \pi/\sqrt{\kappa}$, with equality holding if and only if M is isometric to the sphere with radius $1/\sqrt{\kappa}$.

Obviously, $D(\tilde{p}, \tilde{q}) = \{z \in M_\kappa \mid \angle(\tilde{p}z\tilde{q}) > \pi/2\}$. More precisely, $z \in D(\tilde{p}, \tilde{q})$ if and only if z satisfies the inequalities:

- (1) $\cos\sqrt{\kappa} d(\tilde{p}, \tilde{q}) < \cos\sqrt{\kappa} d(\tilde{p}, z) \cos\sqrt{\kappa} d(\tilde{q}, z)$ if $\kappa > 0$,
- (2) $d(\tilde{p}, \tilde{q})^2 > d(\tilde{p}, z)^2 + d(\tilde{q}, z)^2$ if $\kappa = 0$,
- (3) $\cosh\sqrt{-\kappa} d(\tilde{p}, \tilde{q}) > \cosh\sqrt{-\kappa} d(\tilde{p}, z) \cosh\sqrt{-\kappa} d(\tilde{q}, z)$ if $\kappa < 0$.

Example 5.1. In M_1 , if \tilde{p} and \tilde{q} satisfy $\pi > d(\tilde{p}, \tilde{q}) > \pi/2$ and $z \in M_1$ is a meeting point of the perpendiculars to $T(\tilde{p}, \tilde{q})$ at \tilde{p} and \tilde{q} , then the domain bounded by

the geodesic triangle $\Delta(\tilde{p}z\tilde{q})$ is contained in $D(\tilde{p}, \tilde{q})$. In $M_0 = \mathbb{E}^2$, by elementary geometry, we see that $D(\tilde{p}, \tilde{q})$ is the open disk with diameter $d(\tilde{p}, \tilde{q})$.

Corollary 5.2. *Let M be a complete Riemannian manifold with sectional curvature bounded below by κ . Assume that there exist two points p and q such that a dominant triangle $\Delta_M = \Delta(T(\tilde{p}, \tilde{q}), \alpha_q(p), \alpha_q(p))$ for M can be made from p and q . If its inner angle at $z(\Delta_M)$ is greater than $\pi/2$, then M is topologically an n -sphere.*

Proof. Since the dominant triangle Δ_M is contained in $D(\tilde{p}, \tilde{q})$, this proposition follows from Theorem 2.2. □

Let $\tilde{p}, \tilde{q} \in M_\kappa$ such that $\tilde{p} \neq \tilde{q}$. Let $E(\tilde{p}, \tilde{q}) = \{z \in M_\kappa \mid \angle(\tilde{p}z\tilde{q}) = \pi/2\}$. Namely, $E(\tilde{p}, \tilde{q}) = \partial D(\tilde{p}, \tilde{q})$. Set

$$\omega = \omega(\kappa, d(\tilde{p}, \tilde{q})) = \min\{\angle(z\tilde{p}\tilde{q}) + \angle(z\tilde{q}\tilde{p}) \mid z \in E(\tilde{p}, \tilde{q})\}.$$

Obviously, $\omega > 0$. From the Gauss–Bonnet formula, we have $\omega = \pi/2$ when $\kappa \geq 0$ and $\omega < \pi/2$ when $\kappa < 0$. If $\alpha_p(q) + \alpha_q(p) < \omega$, then there exists a dominant triangle for M .

Corollary 5.3. *Let M be a complete Riemannian n -manifold with sectional curvature bounded below by κ . If there exist two points $p, q \in M$ such that*

$$\alpha_p(q) + \alpha_q(p) < \omega(\kappa, d(p, q)),$$

then M is homeomorphic to an n -sphere.

Proof. From the assumption, there exists a dominant triangle Δ_M for M which is contained in $D(\tilde{p}, \tilde{q})$. This corollary follows from Theorem 2.2. □

Remark 5.4. Let \mathbb{E}^2 denote the Euclidean plane. Let G be the isometry group generated by two translations $\mu(x, y) = (x + a, y)$ and $\nu(x, y) = (x, y + b)$ where a and b are positive constants. The quotient space is a flat torus $T^2 = \mathbb{E}^2/G$. The equivalence class containing (x, y) is written with $[(x, y)]$. Let $p = [(a/2, b/2)]$ and $q = [(0, 0)]$. There exist four minimizing geodesic segments connecting p and q in T^2 . We then have $d(p, q) = \text{diam}(T^2)$ and $\alpha_p(q) + \alpha_q(p) = \pi/2$, meaning that Corollary 5.3 is optimal.

Let $\mathcal{C} = \mathcal{C}(p, q)$ be the set of all midpoints between p and q , namely

$$\mathcal{C} = \{x \in M \mid d(p, x) = d(x, q) = d(p, q)/2\}.$$

If $x \in \mathcal{C}$, then $T(p, x) \cup T(x, q)$ is the unique minimizing geodesic segment through x connecting p and q .

Corollary 5.5. *Let M be a complete Riemannian n -manifold of nonnegative sectional curvature and $p, q \in M$. If $d(x, \mathcal{C}(p, q)) < d(p, q)/2$ for all $x \in M \setminus \{p, q\}$, then M is topologically an n -sphere.*

Proof. We have only to prove that any point $x \in M \setminus \{p, q\}$ is not a critical point of the distance function d_p . We use the Euclidean plane \mathbb{E}^2 as a model space for the Toponogov comparison theorem. Let $\tilde{T} = T(\tilde{p}, \tilde{q})$ be a segment in \mathbb{E}^2 with length $d(p, q)$ and \tilde{m} the midpoint of \tilde{T} .

Let $x \in M \setminus \{p, q\}$. From the assumption, there exists a midpoint m between p and q such that $d(x, m) < d(p, q)/2$. Let $\Delta(\tilde{p}\tilde{q}\tilde{x})$ be the comparison triangle in \mathbb{E}^2 corresponding to $\Delta(pqx)$. Then it follows from the Alexandrov convexity that $d(x, m) \geq d(\tilde{x}, \tilde{m})$. Therefore, we have $d(\tilde{m}, \tilde{x}) < d(\tilde{p}, \tilde{q})/2$. Thus we have $\angle(\tilde{p}\tilde{x}\tilde{q}) > \pi/2$. From the Toponogov comparison theorem, we have $\angle(pqx) > \pi/2$. This implies that x is not a critical point of d_p . \square

Remark 5.6. Let T^2 , p , and q be as in Remark 5.4. Let $s = [(0, b/2)]$. We then have $d(s, x) = \text{diam}(T^2)/2$ for all $x \in \mathcal{C}(p, q)$. From this example, Corollary 5.5 is optimal.

6. Noncompact manifolds referred to M_κ

Let M be a complete noncompact Riemannian n -manifold with sectional curvature bounded below by $\kappa \leq 0$ and M_κ the κ -plane. Let γ be a ray in M with $\gamma(0) = p$. The Busemann function f_γ for γ is defined by

$$f_\gamma(x) = \lim_{t \rightarrow \infty} (t - d(x, \gamma(t))), \quad x \in M.$$

Let $B_\gamma(x)$ be the *open horoball* of a ray γ given by $\{y \in M \mid f_\gamma(y) > f_\gamma(x)\}$.

Let Γ_p denote the set of all rays from p in M . The *super* Busemann function f_p is given by $f_p(x) = \sup_{\gamma \in \Gamma_p} f_\gamma(x)$ for all $x \in M$.

Let $\tilde{\gamma}$ be a fixed ray in M_κ with $\tilde{\gamma}(0) = \tilde{p}$. We call $B_{\tilde{\gamma}}(z)$ a *horoball* of $\tilde{\gamma}$ determined by $z \in M_\kappa$. Since $\kappa \leq 0$, all horoballs are convex in M_κ , meaning that if $w_1, w_2 \in B_{\tilde{\gamma}}(z)$, then the unique minimizing geodesic segment $T(z_1, z_2)$ is contained in $B_{\tilde{\gamma}}(z)$.

Let $v(z)$ be the unit tangent vector at $z \in M_\kappa$ of the coray to $\tilde{\gamma}$ and $w(z)$ the unit tangent vector of geodesic segment from z to \tilde{p} at z , respectively. Set

$$D(\tilde{\gamma}) = \{z \in M_\kappa \mid \angle(v(z), w(z)) > \pi/2\}.$$

We have $D(\tilde{\gamma}) = \lim_{t \rightarrow \infty} B_{\tilde{\gamma}(t)}(t)$ if $\kappa = 0$. When $\kappa < 0$, the boundary $\partial D(\tilde{\gamma})$ of $D(\tilde{\gamma})$ is the trace of those points $z(t) \in M_\kappa$, $t \geq 0$, such that the straight line tangent to the horocircle $f_{\tilde{\gamma}}^{-1}(t)$ through $\tilde{\gamma}(t)$ at $z(t)$ passes through \tilde{p} .

Example 6.1. Let $M_{-1} = \{(x, y) \mid x^2 + y^2 < 1\}$ and

$$ds^2 = \frac{4(dx^2 + dy^2)}{(1 - x^2 - y^2)^2}$$

be the Poincaré disk model. Let $\tilde{p} = (0, 0)$ and $\tilde{\gamma}([0, \infty)) = \{(0, t) \mid 0 \leq t < 1\}$. If $x = r \cos \theta$, $y = r \sin \theta$, then $\partial D(\tilde{\gamma})$ is the trace of the curve given by the equation $r = \tan(\theta/2)$, $0 < \theta < \pi/2$. In fact, since any horocircle of $\tilde{\gamma}$ is a subarc of a circle with center $(u \cos \theta, 1)$ and radius $u \cos \theta$ and any geodesic from $(0, 0)$ is a subsegment of a straight line through $(0, 0)$ with slope $\tan \theta$, they meet at points satisfying

$$r = u - u \cos \theta, \quad 1 = u \sin \theta.$$

Hence, we have

$$r = \frac{1 - \cos \theta}{\sin \theta} = \frac{2 \sin^2(\theta/2)}{2 \sin(\theta/2) \cos(\theta/2)} = \frac{\sin(\theta/2)}{\cos(\theta/2)}.$$

Here we assume that $\kappa < 0$. As before, let $z(t) = \partial D(\tilde{\gamma}) \cap f_{\tilde{\gamma}}^{-1}(t)$ in M_κ . Let $\rho_{\tilde{p}}(t)$ be the angle of $\tilde{\gamma}$ with $T(\tilde{p}, z(t))$ at \tilde{p} for $t \geq 0$. Then $\rho_{\tilde{p}}(0) = \pi/2$ and $\lim_{t \rightarrow \infty} \rho_{\tilde{p}}(t) = 0$. Moreover, $\rho_{\tilde{p}}(t)$ is monotone decreasing in $t \geq 0$.

Let $\tilde{\gamma}$ be a fixed ray in (M_κ, \tilde{p}) with $\tilde{\gamma}(0) = \tilde{p}$. Let Ψ_p be the reference map from M to M_κ^+ . By definition, we have, for all points $x \in M$,

$$d(\tilde{p}, \Psi_p(x)) = d(p, x), \quad f_{\tilde{\gamma}}(\Psi_p(x)) = f_p(x).$$

Corollary 6.2. *Let M be a complete noncompact Riemannian n -manifold with sectional curvature bounded below by κ . If there exists a point $p \in M$ such that $\Psi_p(M \setminus \{p\}) \subset D(\tilde{\gamma})$, then M is diffeomorphic to the Euclidean space \mathbb{E}^n .*

Proof. From the definition of $D(\tilde{\gamma})$, there exists no critical point of d_p in $M \setminus \{p\}$. Lemma 2.1 proves this corollary. □

Proposition 6.3. *Let M denote a complete noncompact Riemannian n -manifold with sectional curvature bounded below by $\kappa < 0$. Assume that $\zeta_p < \pi/2$. Then p is a minimum point of f_p in M . If t_0 satisfies $\rho_{\tilde{p}}(t_0) = \zeta_p$, then there exists no critical point of d_p in $f_p^{-1}((0, t_0))$.*

Proof. Since $\zeta_p < \pi/2$, it follows that $f_p(p) = 0$ is a minimum of f_p in M . Let $x \in M$ be such that $0 < f_p(x) < t_0$. Let v be the initial tangent vector of a minimizing geodesic segment from p to x . From the definition of ζ_p , there exists $\gamma \in \Gamma_p$ such that $\angle(v, \dot{\gamma}(0)) \leq \zeta_p$. From the definition of f_p , we have $f_\gamma(x) \leq f_p(x) < t_0$ and, hence, from the Toponogov comparison theorem,

$$\rho_{\tilde{p}}(f_\gamma(x)) > \rho_{\tilde{p}}(t_0) = \zeta_p \geq \angle(v, \dot{\gamma}(0)) \geq \angle(\tilde{v}, \dot{\tilde{\gamma}})$$

where \tilde{v} is the initial tangent vector of the minimizing geodesic segment from \tilde{p} to $\Psi_\gamma(x)$ in M_κ . This inequality shows $\Psi_\gamma(x) \in D(\tilde{\gamma})$. □

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
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