

Quasiflats with holes in reductive groups

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We give a new proof of a theorem of Kleiner–Leeb: that any quasi-isometrically embedded Euclidean space in a product of symmetric spaces and Euclidean buildings is contained in a metric neighborhood of finitely many flats, as long as the rank of the Euclidean space is not less than the rank of the target. A bound on the size of the neighborhood and on the number of flats is determined by the size of the quasi-isometry constants.

Without using asymptotic cones, our proof focuses on the intrinsic geometry of symmetric spaces and Euclidean buildings by extending the proof of Eskin–Farb’s quasiflat with holes theorem for symmetric spaces with no Euclidean factors.

[20F65](#); [20G30](#), [22E40](#)

1 Introduction

We will give a new proof and a generalization of the following result:

Theorem 1.1 (Kleiner–Leeb) *Let \mathbb{E}^m be m -dimensional Euclidean space, and suppose $\varphi: \mathbb{E}^m \rightarrow X$ is a (κ, C) quasi-isometric embedding, where X is a product of symmetric spaces and Euclidean buildings and m equals the rank of X . Then there exist finitely many flats $F_1, F_2, \dots, F_M \subseteq X$ such that*

$$\varphi(\mathbb{E}^m) \subseteq \text{Nbhd}_N \left(\bigcup_{i=1}^M F_i \right),$$

where $M = M(\kappa, X)$ and $N = N(\kappa, C, X)$.

[Theorem 1.1](#) was proved by Kleiner and Leeb in [\[5\]](#). It can be used to give a new proof of a conjecture of Margulis from the 1970s (also proved in [\[5\]](#)) that any self-quasi-isometry of X as above is a bounded distance from an isometry when all factors correspond to higher rank simple groups. For an indication as to how [Theorem 1.1](#) can be used to give a proof of this fact, see [\[3\]](#) where Eskin–Farb give a proof of [Theorem 1.1](#) and Margulis’ conjecture in the case when X is a symmetric space.

Our proof of [Theorem 1.1](#) does not use asymptotic cones as the proof of Kleiner–Leeb does. Rather, we adapt results of Eskin–Farb who used large-scale homology to characterize quasiflats in symmetric spaces without Euclidean factors in a way that allowed for the absence of large regions in the domain of a quasiflat (a “quasiflat with holes”). Thus, we provide a marriage between the quasiflats theorems of Kleiner–Leeb and Eskin–Farb: a quasiflats theorem that allows for products of symmetric spaces and Euclidean buildings in the target of a quasiflat, and for holes in the domain; see [Theorem 1.2](#) below. [Theorem 1.1](#) occurs as a special case.

Allowing for holes in our quasiflats leads to applications for the study of the large-scale geometry of non-cocompact S -arithmetic lattices; see Wortman [\[9; 10\]](#).

Bibliographic note The full theorem of Kleiner–Leeb is more general than [Theorem 1.1](#) as it allows for generalized Euclidean buildings in the target of φ . However, [Theorem 1.1](#) does include all of the standard Euclidean buildings that are naturally acted on by reductive groups over local fields.

Quasiflats with holes For constants $\kappa \geq 1$ and $C \geq 0$, a (κ, C) *quasi-isometric embedding* of a metric space X into a metric space Y is a function $\varphi: X \rightarrow Y$ such that for any $x_1, x_2 \in X$:

$$\frac{1}{\kappa}d(x_1, x_2) - C \leq d(\varphi(x_1), \varphi(x_2)) \leq \kappa d(x_1, x_2) + C.$$

For a subset of Euclidean space $\Omega \subseteq \mathbb{E}^m$, we let

$$\Omega_{(\varepsilon, \rho)} = \{x \in \Omega \mid B_y(\varepsilon d(x, y)) \cap \Omega \neq \emptyset \text{ for all } y \in \mathbb{E}^m - B_x(\rho)\},$$

where we use the notation $B_z(r)$ to refer to the ball of radius r centered at z . Hence, $\Omega_{(\varepsilon, \rho)}$ is the set of all points $x \in \Omega$ which can serve as an observation point from which all points in \mathbb{E}^m (that are a sufficient distance from x) have a distance from Ω that is proportional to their distance from x .

A special case to keep in mind is that if $\Omega = \mathbb{E}^m$, then $\Omega_{(\varepsilon, \rho)} = \mathbb{E}^m$ for any $\varepsilon \geq 0$ and $\rho \geq 0$.

A *quasiflat with holes* is the image of $\Omega_{(\varepsilon, \rho)}$ under a quasi-isometric embedding $\phi: \Omega \rightarrow X$.

Before stating our main result, recall that for a metric space X , the *rank* of X (or $\text{rank}(X)$ for short) is the maximal dimension of a flat in X . Now we have the following generalization of [Theorem 1.1](#):

Theorem 1.2 (Quasiflats with holes) *Let $\varphi: \Omega \rightarrow X$ be a (κ, C) quasi-isometric embedding where X is a product of symmetric spaces and Euclidean buildings, $\Omega \subseteq \mathbb{E}^m$, and $m \geq \text{rank}(X)$. There are constants $M = M(\kappa, X)$ and $\varepsilon_0 = \varepsilon_0(\kappa, X)$, such that if $\varepsilon < \varepsilon_0$, then there exist flats $F_1, F_2, \dots, F_M \subseteq X$ such that*

$$\varphi(\Omega_{(\varepsilon, \rho)}) \subseteq \text{Nbhd}_N \left(\bigcup_{i=1}^M F_i \right),$$

where $N = N(\kappa, C, \rho, X)$.

Quasirank We remark that by comparing the volume of the domain and image of a function φ satisfying the hypotheses of [Theorem 1.2](#), it is clear that no quasi-isometric embeddings exist of a Euclidean space into X when the dimension of the Euclidean space is greater than the rank of X . This observation is not new and follows very easily from the pre-existing quasiflats theorems. However, we choose to state our theorem in this more general manner since the proof given below does not depend on the dimension of the Euclidean space once its dimension at least equals the rank of X , and our proof will run more smoothly if we allow for dimensions larger than the rank of X .

Applications for quasiflats One would like to characterize quasiflats as a starting point for understanding quasi-isometries of a lattice as Mostow did for cocompact lattices. (See Morse [\[6\]](#), Mostow [\[7\]](#), Pansu [\[8\]](#), Kleiner–Leeb [\[5\]](#), Eskin–Farb [\[3\]](#), Eskin [\[2\]](#), Wortman [\[9; 10\]](#) for the details of this brief sketch.)

The basic example of a quasiflats theorem is the Morse–Mostow Lemma which states that a quasi-isometric embedding of \mathbb{R} into a rank one symmetric space has its image contained in a metric neighborhood of a unique geodesic.

For general symmetric spaces and Euclidean buildings X , it is not the case that a quasi-isometrically embedded Euclidean space is necessarily contained in the neighborhood of a single flat. (Recall that a *flat* is an isometrically embedded Euclidean space.) If, however, the dimension of a quasi-isometrically embedded Euclidean space is equal to the dimension of a maximal flat in X , then its image will be contained in a neighborhood of finitely many flats.

Quasiflats can be used in the study of quasi-isometries of cocompact lattices as follows. First, we may assume that any self-quasi-isometry of a cocompact lattice in a semisimple Lie group is a quasi-isometry of its orbit in an appropriate product of symmetric spaces and Euclidean buildings, X . Second, since any flat in X is necessarily contained in a metric neighborhood of the cocompact lattice orbit, we can restrict the quasi-isometry

to any flat and examine its image. The space X has a boundary at infinity which is defined in terms of the asymptotic behavior of flats, so in determining the images of flats we are finding a map on the boundary of X . Finally—as long as X contains no factors that are real hyperbolic spaces, complex hyperbolic spaces, or trees—one can deduce from the properties of the boundary map that the quasi-isometry is a finite distance from an isometry.

The story is different for non-cocompact lattices. Generic flats in X will not be contained in a neighborhood of a non-cocompact lattice orbit. Hence, we cannot apply the same proof technique.

However, the generic flat will have a substantial portion of its volume contained in a neighborhood of a non-cocompact lattice orbit. With an eye towards this feature, Eskin–Farb provided a foundational tool for studying quasi-isometries of non-cocompact lattices in real semisimple Lie groups by defining and characterizing quasiflats with holes in symmetric spaces.

Using quasiflats with holes in symmetric spaces, Eskin developed a boundary map in the non-cocompact lattice case for real groups en route to proving that any quasi-isometry of a higher rank arithmetic group is a finite distance from a commensurator.

By allowing for Euclidean building factors in the image of a quasiflat with holes, we will be able to use this same approach to analyze quasi-isometries of non-cocompact lattices in semisimple Lie groups over arbitrary local fields.

Outline Our proof of [Theorem 1.2](#) in the case that X is a Euclidean building is self-contained aside from results of Eskin–Farb on the large-scale homology of pinched sets in Euclidean space and some consequences of those results. Hopefully, the reader who is interested in only the case when X is a building can read through our proof without having to consider symmetric spaces.

In the general case, when X is a nontrivial product of a symmetric space and a Euclidean building, we rely heavily on the results of Eskin–Farb for symmetric spaces. Our approach is to project the quasiflat with holes into the building factor X_p , and into the symmetric space factor X_∞ . By projecting the quasiflat with holes to X_p , we can apply arguments below that were created expressly for buildings while ignoring the symmetric space factor. Conversely, by projecting the quasiflat with holes to X_∞ , we can directly apply most of the content of [\[3\]](#) to analyze the image. After examining the image in each factor, we piece together the information obtained in the full space X to obtain our result.

Thus, in our approach to proving [Theorem 1.2](#), we will try to avoid dealing with the product space X . We do this since arguments for symmetric spaces and Euclidean

buildings (although extremely similar in spirit) have to be dealt with using different tools.

The approach of projecting to factors is taken from the work of Eskin–Farb as well. Their test case for their general theorem was when $X = \mathbb{H}^2 \times \mathbb{H}^2$, and they used the projection method to reduce most of the proof to arguments in the hyperbolic plane [4].

In [Section 2](#) we will show that certain subspaces in X which behave like rank one spaces cannot accommodate quasi-isometric embeddings of large Euclidean sets. This fact will be formulated more precisely in terms of homology.

Some of the nearly rank one spaces are then glued together to give a “degenerate space” in X which is a fattening of the singular directions in X with respect to a given basepoint. (Recall that a direction is singular if it is contained in more than one flat.) Using a Mayer–Vietoris sequence, it can be shown that the degenerate space cannot accommodate quasi-isometric embeddings of large Euclidean sets of large dimension. It is at this point where we apply our hypothesis that the dimension of \mathbb{E}^m equals, or exceeds, the rank of X .

In [Section 3](#) we begin to analyze the asymptotic behavior of quasiflats with holes. We define—following Eskin–Farb—what it means for a direction in a quasiflat with holes to limit on a point in the boundary at infinity of X .

The results of [Section 2](#) show that the image of a quasiflat with holes must have a substantial intersection with the complement of the degenerate space. (The complement of the degenerate space is the region of X for which limit points are defined.) We argue further to show that limit points exist.

Since the nondegenerate space behaves much like a rank one space itself, we can show that the image of a quasiflat with holes in the nondegenerate space cannot extend in too many directions (i.e. the number of limit points is bounded). We construct our bound by contrasting the polynomial growth of Euclidean space with the high cost of travelling out in different directions in a rank one space. It is from the finite set of limit points that the finite set of flats from the conclusion of [Theorem 1.2](#) is constructed.

[Section 4](#) contains a few lemmas to insure that all definitions depending on basepoints are well-defined up to a constant.

We conclude in [Section 5](#) with a proof of [Theorem 1.2](#). Results from [Sections 2, 3](#) and [4](#) are used in the proof.

Definitions Recall that a *polysimplex* is a product of simplices. Replacing simplices with polysimplices in the definition of a simplicial complex creates what is called a *polysimplicial complex*.

A *Euclidean building* X_p is a polysimplicial complex endowed with a metric d_p that satisfies the four properties below:

- (i) There is a family, $\{\mathcal{A}_\alpha\}$, of subcomplexes of X_p such that each \mathcal{A}_α is isometric to $\mathbb{E}^{\dim(X_p)}$ and $X_p = \bigcup_\alpha \mathcal{A}_\alpha$. Each \mathcal{A}_α is called an *apartment*.
- (ii) Any two polysimplices of maximal dimension (called *chambers*) are contained in some \mathcal{A}_α .
- (ii) If \mathcal{A}_α and \mathcal{A}_β are two apartments each containing the chambers c_1 and c_2 , then there is an isometric polysimplicial automorphism of X sending \mathcal{A}_α to \mathcal{A}_β , and fixing c_1 and c_2 pointwise.
- (iv) The group of isometric polysimplicial automorphisms of X_p acts transitively on the set of chambers.

Note that condition (iv) is nonstandard. Often one assumes the stronger condition that a building be *thick*. We desire to weaken the thickness condition to condition (iv) so that Euclidean space can naturally be given the structure of a Euclidean building.

Also notice that we do not assume X_p to be locally finite. Hence, we are including the buildings for, say, $\mathbf{GL}_n(\mathbb{C}(t))$ in our examination.

Along with the nonstandard definition of a Euclidean building given above, we also give the standard definition of a *symmetric space* as a Riemannian manifold X_∞ such that for every $p \in X_\infty$, there is an isometry g of X_∞ such that $g(p) = p$ and the derivative of g at p equals $-\text{Id}$.

Conventions Throughout this paper we will be examining products of symmetric spaces and Euclidean buildings. Since Euclidean space is a Euclidean building by our definition, we may assume that our symmetric spaces do not have Euclidean factors. This will allow us to more readily apply results from [3] where it is assumed that the symmetric spaces have no Euclidean factors.

We may also assume that our symmetric spaces do not have compact factors. Otherwise we could simply compose the quasi-isometry φ from [Theorem 1.2](#) with a projection map to eliminate the compact factors, then apply [Theorem 1.2](#), pull back the flats obtained to the entire symmetric space, and increase the size of N by the diameter of the compact factors.

Notation If a and b are positive numbers we write $a \ll b$ when there is a constant $\lambda = \lambda(X, \kappa) < 1$ such that $a < \lambda b$. If there are variables x_1, \dots, x_n and a constant $\eta = \eta(X, \kappa, x_1, \dots, x_n) < 1$ such that $a < \eta b$, then we write $a \ll_{(x_1, \dots, x_n)} b$. We will

use the notation $a = O(b)$ to mean that $a < \lambda b$ for some constant $\lambda = \lambda(X, \kappa)$ without specifying the size of λ .

Remarks With modification to only the conclusion of the proof of [Lemma 3.6](#), our results hold when \mathbb{F}^m is replaced by a 1-connected nilpotent real Lie group. For example, this shows that a Heisenberg group cannot quasi-isometrically embed into $\mathbf{SL}_4(k)$ for any locally compact nondiscrete field k .

Also the proof presented below can be modified in [Lemma 3.2](#) to allow for the presence of \mathbb{R} -buildings in the target of the quasiflat with holes.

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2 Pinching functions and homology

Throughout the remainder, let X_p be a Euclidean building with a chosen basepoint $e_p \in X_p$, and let X_∞ be a symmetric space with basepoint $e_\infty \in X_\infty$. We will assume that X_∞ has no compact or Euclidean factors (see the conventions in the preceding section).

We let $X = X_\infty \times X_p$, and we define $\pi_\infty: X \rightarrow X_\infty$ and $\pi_p: X \rightarrow X_p$ to be the projection maps. Define the point $e \in X$ as the pair (e_∞, e_p) .

Throughout we let $n \in \mathbb{N}$ equal $\text{rank}(X)$.

Graded quasi-isometric embeddings We will put quasiflats with holes aside until the final section of this paper. We concentrate instead on embeddings of entire Euclidean spaces into X under a weaker assumption than our map is a quasi-isometry.

For points $x, y_1, y_2, \dots, y_n \in X$ and a number $\rho \geq 0$, we let

$$D_x(\rho; y_1, y_2, \dots, y_n) = \max\{\rho, d(x, y_1), \dots, d(x, y_n)\}.$$

For numbers $\kappa \geq 1$, $\rho \geq 0$, and $\varepsilon \geq 0$, we define a function $\phi: X \rightarrow Y$ to be a $(\kappa, \rho, \varepsilon)$ *graded quasi-isometric embedding based at $x \in X$* if for all $z, w \in X$:

$$\frac{1}{\kappa}d(z, w) - \varepsilon D_x(\rho; z, w) \leq d(\phi(z), \phi(w)) \leq \kappa d(z, w) + \varepsilon D_x(\rho; z, w).$$

A function $\phi: X \rightarrow Y$ is called (κ, ρ) *radial at $x \in X$* if for all $z \in X$:

$$\frac{1}{2\kappa}D_x(\rho; z) \leq d(\phi(z), \phi(x)) \leq (2\kappa)D_x(\rho; z).$$

Combining the two definitions above, $\phi: X \rightarrow Y$ is a $(\kappa, \rho, \varepsilon)$ *radial graded quasi-isometric embedding ((RGQIE) for short) based at x* if it is a $(\kappa, \rho, \varepsilon)$ graded quasi-isometric embedding at x , and κ radial at x .

In the proof of [Theorem 1.2](#), we will see that one can easily extend the domain of a quasiflat with holes to all of \mathbb{E}^m in such a way that the extension is a (RGQIE). From the behavior of (RGQIE)'s that is characterized in Sections 2 through 4, we will be able to characterize the image of a quasiflat with holes.

Until explicitly stated otherwise, let $\phi: \mathbb{E}^m \rightarrow X$ be a $(\kappa, \varepsilon, \rho)$ (RGQIE) based at 0 with $\phi(0) = e$. The image of such a function is a *graded quasiflat*.

Pinching on rays in buildings Let

$$K = \{g \in \text{Isom}(X) \mid ge = e\},$$

and let $\gamma_p: [0, \infty) \rightarrow \{e_\infty\} \times X_p$ be a geodesic ray with $\gamma_p(0) = e$. The space $K\gamma_p$ is a topological tree as can be seen by restricting the geodesic retraction $X_p \rightarrow \{e_p\}$. However, the tree $K\gamma_p$ will often not be convex. These trees in X are negatively curved, and our first goal is to show that large subsets of Euclidean space cannot embed into them, or even into small enough neighborhoods of them. This in itself is straightforward to show, but we shall want to handle this problem in a way that allows us to conclude that large Euclidean sets cannot embed into fattened neighborhoods of K translates of certain $(n-1)$ -dimensional spaces.

Let

$$K\gamma_p(\delta) = \{x \in \{e_\infty\} \times X_p \mid d(x, t) < \delta d(x, e) \text{ for some } t \in K\gamma_p\},$$

so that $K\gamma_p(\delta)$ is a neighborhood of $K\gamma_p$ in $\{e_\infty\} \times X_p$ that is fattened in proportion to the distance from the origin by a factor of δ . We will want to project $K\gamma_p(\delta)$ onto $K\gamma_p$ where calculations can be made more easily.

Define

$$\pi(\gamma_p, \delta): K\gamma_p(\delta) \rightarrow K\gamma_p$$

by choosing for any $x \in K\gamma_p(\delta)$, some $\pi(\gamma_p, \delta)(x) \in K\gamma_p$, such that

$$d(x, \pi(\gamma_p, \delta)(x)) \leq \delta d(x, e).$$

By definition, $\pi(\gamma_p, \delta)$ only modifies distances by a linear error of δ , so composing with ϕ will still be a (RGQIE). Precisely, we have the following:

Lemma 2.1 *If $\varepsilon < \delta < 1/2$, then $\pi(\gamma_p, \delta) \circ \phi: \phi^{-1}(K\gamma_p(\delta)) \rightarrow K\gamma_p$ is a $(2\kappa, \rho, 5\kappa\delta)$ (RGQIE) based at 0.*

Proof Verifying that $\pi(\gamma_p, \delta) \circ \phi$ is a graded quasi-isometric embedding is an easy sequence of inequalities:

$$\begin{aligned} & d(\pi(\gamma_p, \delta) \circ \phi(x), \pi(\gamma_p, \delta) \circ \phi(y)) \\ & \leq d(\pi(\gamma_p, \delta) \circ \phi(x), \phi(x)) + d(\pi(\gamma_p, \delta) \circ \phi(y), \phi(y)) + d(\phi(x), \phi(y)) \\ & \leq d(\phi(x), \phi(y)) + 2\delta D_e(0; \phi(x), \phi(y)) \\ & \leq \kappa d(x, y) + \varepsilon D_0(\rho; x, y) + 4\kappa\delta D_0(\rho; x, y). \end{aligned}$$

The other inequality is similar.

That $\pi(\gamma_p, \delta) \circ \phi$ is radial is also straightforward:

$$\begin{aligned} d(\pi(\gamma_p, \delta) \circ \phi(x), e) & \leq d(\pi(\gamma_p, \delta) \circ \phi(x), \phi(x)) + d(\phi(x), e) \\ & \leq (1 + \delta)d(\phi(x), e) \\ & \leq 2\kappa(1 + \delta)D_0(\rho; x). \end{aligned}$$

Again, the other inequality is similar. □

As in [3], for numbers $r \geq 0$, $\eta > 1$, and $\beta > 0$, we define an (r, η, β) *pinching function* on a set $W \subseteq \mathbb{E}^m$ to be a proper, continuous function $f: W \rightarrow \mathbb{R}_{\geq 0}$ such that for any $x, y \in W$, we have $d(x, y) < \beta s$ whenever the following two properties hold:

- (i) $r \leq s \leq f(x) \leq f(y) \leq \eta s$;
- (ii) there is a path $\psi: [0, 1] \rightarrow W$ such that $\psi(0) = x$, $\psi(1) = y$, and $s \leq f(\psi(t))$ for all $t \in [0, 1]$.

If there exists an (r, η, β) pinching function on some $W \subseteq \mathbb{E}^m$, then we say that W is (r, η, β) -*pinched*.

Eskin–Farb used pinching functions as a means of showing that large Euclidean sets cannot quasi-isometrically embed into certain negatively curved subspaces of symmetric spaces. To show the analogous result for our general X , we will first construct a

pinching function for $\phi^{-1}(K\gamma_p(\delta))$. Since Eskin–Farb constructed a pinching function on the similarly defined sets $\phi^{-1}(K\gamma_\infty(\delta))$, we will then be in a position to handle the case for a general ray by pulling back pinching functions obtained through projection to factors.

Our candidate for a pinching function on $\phi^{-1}(K\gamma_p(\delta))$ is

$$f(\gamma_p, \delta): \phi^{-1}(K\gamma_p(\delta)) \rightarrow \mathbb{R}_{\geq 0},$$

where $f(\gamma_p, \delta)(x) = d(\pi(\gamma_p, \delta) \circ \phi(x), e)$.

Lemma 2.2 *If $\varepsilon < \delta < 1/2$, then $f(\gamma_p, \delta)$ is a $(5\kappa\rho, 1 + \delta, 84\kappa^3\delta)$ pinching function on the set $\phi^{-1}(K\gamma_p(\delta)) \subseteq \mathbb{E}^m$.*

Proof Note that we may assume $\pi(\gamma_p, \delta) \circ \phi$ is continuous by a connect-the-dots argument. Hence, $f(\gamma_p, \delta)$ is clearly continuous and proper. We assume $x, y \in \phi^{-1}(K\gamma_p(\delta))$ are such that

$$5\kappa\rho \leq s \leq f(\gamma_p, \delta)(x) \leq f(\gamma_p, \delta)(y) \leq (1 + \delta)s,$$

and there is a path $\psi: [0, 1] \rightarrow \phi^{-1}(K\gamma_p(\delta))$ with $s \leq f(\gamma_p, \delta)(\psi(t))$ for all $t \in [0, 1]$.

By the radial condition of [Lemma 2.1](#),

$$5\kappa\rho \leq d(\pi(\gamma_p, \delta) \circ \phi(x), e) \leq 4\kappa D_0(\rho; x).$$

It follows that $\rho < d(x, 0)$. Hence, by the radial condition of [Lemma 2.1](#) and our pinching assumptions,

$$d(x, 0) \leq 4\kappa d(\pi(\gamma_p, \delta) \circ \phi(x), e) \leq 4\kappa(1 + \delta)s.$$

The existence of ψ implies that $\pi(\gamma_p, \delta) \circ \phi(x)$ and $\pi(\gamma_p, \delta) \circ \phi(y)$ are in the same connected component of $K\gamma_p - B_e(s)$. Therefore,

$$d(\pi(\gamma_p, \delta) \circ \phi(x), \pi(\gamma_p, \delta) \circ \phi(y)) \leq 2\delta s.$$

We may assume $d(x, 0) \geq d(y, 0)$. Then, by the graded condition of [Lemma 2.1](#),

$$2\delta s \geq \frac{1}{2\kappa}d(x, y) - (5\kappa\delta)d(x, 0) \geq \frac{1}{2\kappa}d(x, y) - (5\kappa\delta)4\kappa(1 + \delta)s.$$

That is, $d(x, y) < 84\kappa^3\delta s$. □

Graded neighborhoods For a set $Y \subseteq X$, we can create a neighborhood of Y by fattening points in Y in δ -proportion to their distance from e . In symbols, we let

$$Y[\delta] = \{x \in X \mid d(x, y) < \delta d(x, e) \text{ for some } y \in Y\}.$$

Pinching on general rays Lemma 6.8 in [4] demonstrates a pinching function for sets of the form $\phi^{-1}(K\gamma_\infty(\delta))$ where $\gamma_\infty: [0, \infty) \rightarrow X_\infty \times \{e_p\}$ is a geodesic ray, and $K\gamma_\infty(\delta) \subseteq X_\infty \times \{e_p\}$ is defined analogously to $K\gamma_p(\delta) \subseteq \{e_\infty\} \times X_p$. We can use this pinching function along with the pinching function from Lemma 2.2 to show that $\phi^{-1}(K\gamma[\delta])$ is a pinched set, where $\gamma: [0, \infty) \rightarrow X$ is an arbitrary geodesic ray with $\gamma(0) = e$. Our argument proceeds by simply applying our already existing pinching functions to the image of $K\gamma[\delta]$ under the projection maps onto the factors of X .

We want to define a real valued *tilt parameter*, τ , on the space of geodesic rays $\gamma: [0, \infty) \rightarrow X$ with $\gamma(0) = e$. The parameter will measure whether γ leans more towards the X_p or the X_∞ factor. Notice that any such γ can be decomposed as $\gamma(t) = (\gamma_\infty(t), \gamma_p(at))$ for some number $a \geq 0$, and all $t \geq 0$, where $\gamma_\infty \subseteq X_\infty$ and $\gamma_p \subseteq X_p$ are unit speed geodesic rays based at e_∞ and e_p respectively. Now we simply set $\tau(\gamma) = a$. (For τ to be defined everywhere we allow for the case when $a = \infty$, which is just to say that γ is contained in the building factor.) Hence, if $\tau(\gamma) > 1$ (resp. < 1) then γ is leaning towards the building factor (resp. symmetric space factor), and when creating a pinching function on $K\gamma[\delta]$ it will be most efficient to project onto the X_p (resp. X_∞) factor of X .

We begin with the following technical observation.

Lemma 2.3 Assume $\gamma: [0, \infty) \rightarrow X$ is a geodesic ray with $\gamma(0) = e$ and that $y \in K\gamma[\delta]$. Then,

- (i) $\pi_p(y) \in K\gamma_p\left(\delta\sqrt{1 + \cot^2(|\tan^{-1} \tau(\gamma) - \sin^{-1} \delta|_+)}\right)$, and
- (ii) $\pi_\infty(y) \in K\gamma_\infty\left(\delta\sqrt{1 + \cot^2(|\tan^{-1} 1/\tau(\gamma) - \sin^{-1} \delta|_+)}\right)$,

where $|x|_+ = \max\{x, 0\}$.

Proof By definition of $K\gamma[\delta]$ there exists a $t \geq 0$ and a $k \in K$ such that

$$\begin{aligned} d(\pi_p(y), k\gamma_p(\tau(\gamma)t)) &= d(\pi_p(y), \pi_p(k\gamma(t))) \\ &\leq d(y, k\gamma(t)) \\ &< \delta d(y, e) \\ &\leq \delta \sqrt{d(\pi_p(y), e_p)^2 + d(\pi_\infty(y), e_\infty)^2}. \end{aligned}$$

Using straightforward trigonometry it can be verified that

$$d(\pi_\infty(y), e_\infty) \leq d(\pi_p(y), e_p) \cot(|\tan^{-1} \tau(\gamma) - \sin^{-1} \delta|_+).$$

Then (i) follows. The proof of (ii) is similar. □

We will use part (i) of the previous lemma to create a pinching function for geodesic rays that tilt towards X_p . This is the content of [Lemma 2.5](#), but we will first note that the projection onto X_p does not significantly distort distances.

Lemma 2.4 *Let $\gamma: [0, \infty) \rightarrow X$ be a geodesic ray with $\gamma(0) = e$. If $\varepsilon < \delta$ and $\tau(\gamma) \geq 1$, then $\pi_p \circ \phi: \phi^{-1}(K\gamma[\delta]) \rightarrow X_p$ is a $(2\kappa, \rho, \eta_1)$ (RGQIE) where $\eta_1 = O(\delta)$.*

Proof Note that on $K\gamma[\delta]$, π_p is a $(2, 0, O(\delta))$ (RGQIE) where 2 is an upper bound given by our restriction on $\tau(\gamma)$. Composition with ϕ completes the result. \square

Now for the pinching function:

Lemma 2.5 *Let $\gamma: [0, \infty) \rightarrow X$ be a geodesic ray with $\gamma(0) = e$. For $\tau(\gamma) \geq 1$ and $\varepsilon < \delta \ll 1$, the set $\phi^{-1}(K\gamma[\delta]) \subseteq \mathbb{E}^m$ is $(10\kappa\rho, 1 + \delta, O(\delta))$ -pinched.*

Proof Let $\delta_p = \max \left\{ 2\eta_1, \delta \sqrt{1 + \cot^2(\tan^{-1} \tau(\gamma) - \sin^{-1} \delta)} \right\}$, and note that our conditions on $\tau(\gamma)$ and δ imply that, say,

$$1 < \sqrt{1 + \cot^2(\tan^{-1} \tau(\gamma) - \sin^{-1} \delta)} < 2.$$

By [Lemma 2.3](#), $\pi_p(K\gamma[\delta]) \subseteq K\gamma_p(\delta_p)$. Hence, we can choose our pinching function $g: \phi^{-1}(K\gamma[\delta]) \rightarrow \mathbb{R}_{\geq 0}$ to be given by

$$g(z) = d(\pi(\gamma_p, \delta_p) \circ \pi_p \circ \phi(z), e_p).$$

Indeed, we can use [Lemma 2.4](#) to replace ϕ with $\pi_p \circ \phi$ in [Lemma 2.2](#). It follows that g is a $(10\kappa\rho, 1 + \delta_p, 672\kappa^3\delta_p)$ pinching function. \square

If $\tau(\gamma) \leq 1$, we can apply [Lemma 2.3](#) to [Lemma 6.8](#) of [\[3\]](#) and obtain a similar result. Hence, we have a pinching function on $\phi^{-1}(K\gamma[\delta])$ for any geodesic ray γ that is based at the origin. Precisely, we have the following:

Lemma 2.6 *If $\varepsilon \ll \delta \ll 1$, then the set $\phi^{-1}(K\gamma[\delta]) \subseteq \mathbb{E}^m$ is $(r_0, 1 + O(\delta), O(\delta))$ -pinched for any geodesic ray $\gamma: [0, \infty) \rightarrow X$ with $\gamma(0) = e$. Here $r_0 = r_0(X, \kappa, \rho, \delta)$.*

Homology results of Eskin–Farb and their consequences Pinching functions were introduced in [\[3\]](#) as a tool for showing that sets which simultaneously support Euclidean metrics and “quasinegatively curved” metrics must be small and, hence, cannot have any interesting large-scale homology. Precisely, we can use our [Lemma 2.6](#) in the proof of [Corollary 6.9](#) from [\[3\]](#) to show:

Lemma 2.7 *There exists a $v_1 > 0$ such that if $1 \ll_{(\rho, \delta, \varepsilon)} r$, while $\varepsilon \ll \delta \ll 1$ and $W \subseteq \phi^{-1}(K\gamma[\delta])$, then the homology of the inclusion map $\iota_*: H_p(W \cup B_0(r)) \rightarrow H_p(W[v_1\delta] \cup B_0(r))$ is zero for all $p \geq 1$.*

The above lemma can be used to show, for example, that the image of ϕ cannot be contained in $K\gamma[\delta]$. Otherwise we could take a sphere of large radius in place of W to arrive at a contradiction. This is an interesting fact, but we care to know more. We are able to use this lemma to tell us that there are much larger subspaces of X that spheres cannot embed into.

The larger subspaces are defined in terms of walls, so we begin by defining the latter. A subset $H \subseteq X$ is called a *wall* if it is a codimension 1 affine subspace of a flat that is contained in at least two distinct flats. Note that the walls through the point $e \in X$ comprise the singular directions from e .

Our space X resembles a rank one space, from the vantage point of $e \in X$, in the regions bounded away from the singular directions. Properties of negative curvature are a powerful tool, so we will want to show the image of ϕ has a substantial portion of its image bounded away from the singular directions.

It is time to define $X_e(\delta)$ as the δ -nondegenerate space at $e \in X$ consisting of those points in X that are not contained in any δ -graded neighborhood of a wall containing e . That is

$$X_e(\delta) = \bigcap_{H \in \mathcal{W}_e} (H[\delta])^c,$$

where \mathcal{W}_e is the set of walls in X that contain e .

The complement $X_e(\delta)^c$ of the δ -nondegenerate space is the δ -degenerate space. We could repeat the definition for the special case that X is either a Euclidean building or a symmetric space and obtain the sets $X_{p, e_p}(\delta)$, $X_{p, e_p}(\delta)^c$, $X_{\infty, e_\infty}(\delta)$, and $X_{\infty, e_\infty}(\delta)^c$.

Our goal for this section is to show that the image of ϕ is forced to travel in $X_e(\delta)$. We can use [Lemma 2.7](#) along with a Mayer–Vietoris sequence to show that the image under ϕ of very large subsets of \mathbb{E}^m indeed cannot be contained in $X_e(\delta)^c$. Note that in the Tits boundary of X , $X_e(\delta)^c$ appears as a neighborhood of the $(n - 2)$ -skeleton. The spaces of the form $K\gamma[\delta]$ that we considered previously appear as neighborhoods of a family of points in the Tits building. It is clear how one would want to use [Lemma 2.7](#) and a Mayer–Vietoris argument to arrive at the following:

Lemma 2.8 *There exists a constant $v_2 > 0$, such that if $1 \ll_{(\rho, \delta, \varepsilon)} r$ while $\varepsilon \ll \delta \ll 1$ and $W \subseteq \phi^{-1}(X_e(\delta)^c)$, then the homology of the inclusion map $\iota_*: H_p(W \cup B_0(r)) \rightarrow H_p(W[v_2\delta] \cup B_0(r))$ is zero for all $p \geq n - 1$.*

The basic idea of the proof is clear but there are some technicalities to consider. This is essentially Lemma 5.6 of [3], whose proof takes place in the Tits boundary where there is no difference between symmetric spaces and buildings. Hence, the proof carries over completely to prove our Lemma 2.8.

Unbounded, nondegenerate components of graded quasiflats Note that the above lemma tells us that large metric $(n - 1)$ -spheres in \mathbb{E}^m cannot map into $X_e(\delta)^c$ under ϕ . In Lemma 5.8 of [3], this idea is extended to show that unbounded portions of \mathbb{E}^m map into $X_e(\delta)$ under ϕ . The arguments there only involve an application of what is our Lemma 2.8 to the homology of Euclidean sets. The proof applies verbatim to yield:

Corollary 2.9 *There is a constant $\nu_3 > 1$, such that if $\varepsilon \ll \delta \ll 1$ and $z \in \phi^{-1}(X_e(\delta))$ with $1 \ll_{(\delta, \varepsilon, \rho)} r \leq d(z, 0)$, then the connected component of $\phi^{-1}(X_e(\delta/\nu_3)) \cap B_0(r)^c$ that contains z is unbounded.*

Lemma 2.8 and Corollary 2.9 are the only results from this section that will be used in the remainder of this paper. We will apply Lemma 2.8 in Section 5 during the proof of Theorem 1.2. Corollary 2.9 is used in the proof of Proposition 3.5 below to create a path in the graded quasiflat that avoids the nondegenerate space and accumulates on a point in the boundary of X .

3 Limit points in Euclidean buildings

Boundary metric A subset of a Euclidean building $\mathfrak{S} \subseteq X_p$ is called a *sector* based at $x \in X_p$, if it is the closure of a connected component of an apartment less all the walls containing x .

Let \widehat{X}_p be the set of all sectors based at e_p . For any $\mathfrak{S} \in \widehat{X}_p$, let $\gamma_{\mathfrak{S}}: [0, \infty) \rightarrow \mathfrak{S}$ be the geodesic ray such that $\gamma_{\mathfrak{S}}(0) = e_p$, and such that $\gamma_{\mathfrak{S}}(\infty)$ is the center of mass of the boundary at infinity of \mathfrak{S} with its usual spherical metric. We will also use $\gamma_{\mathfrak{S}}$ to denote the image of $\gamma_{\mathfrak{S}}: [0, \infty) \rightarrow \mathfrak{S}$.

We endow \widehat{X}_p with the metric \widehat{d}_p where

$$\widehat{d}_p(\mathfrak{Y}, \mathfrak{Z}) = \begin{cases} \pi, & \text{if } \gamma_{\mathfrak{Y}} \cap \gamma_{\mathfrak{Z}} = \{e_p\}; \\ \frac{1}{|\gamma_{\mathfrak{Y}} \cap \gamma_{\mathfrak{Z}}|}, & \text{otherwise.} \end{cases}$$

In the above, $|\gamma_{\mathfrak{Y}} \cap \gamma_{\mathfrak{Z}}|$ is the length of the geodesic segment $\gamma_{\mathfrak{Y}} \cap \gamma_{\mathfrak{Z}}$.

Note that \hat{d}_p is invariant under the action of the stabilizer of e_p and is a complete ultrametric on \hat{X}_p . That \hat{d}_p is an ultrametric means that it is a metric, and

$$\hat{d}_p(\mathfrak{Y}, \mathfrak{Z}) \leq \max\{\hat{d}_p(\mathfrak{Y}, \mathfrak{X}), \hat{d}_p(\mathfrak{X}, \mathfrak{Z})\} \quad \text{for any } \mathfrak{Y}, \mathfrak{Z}, \mathfrak{X} \in \hat{X}_p.$$

We will use at times that

$$\mathfrak{Z} \in B_{\mathfrak{S}}(r) \text{ implies } B_{\mathfrak{Z}}(r) = B_{\mathfrak{S}}(r),$$

which is a reformulation of the ultrametric property.

Measuring angles We also introduce a notion of angle between two points in a building as measured from e_p . We first define $\Phi_p: X_p \rightarrow \mathcal{P}(\hat{X}_p)$ by

$$\Phi_p(x) = \{ \mathfrak{S} \in \hat{X}_p \mid x \in \mathfrak{S} \},$$

where $\mathcal{P}(\hat{X}_p)$ denotes the power set of \hat{X}_p .

Then for any $x, y \in X_p$, we define

$$\Theta_p(x, y) = \inf \{ \hat{d}_p(\mathfrak{S}_x, \mathfrak{S}_y) \mid \mathfrak{S}_x \in \Phi_p(x) \text{ and } \mathfrak{S}_y \in \Phi_p(y) \}.$$

We think of $\Theta_p(x, y)$ as measuring an angle between x and y .

We will also be measuring angles formed by triangles in a single apartment. Since apartments are Euclidean spaces, we can simply use the Euclidean measure of angle. If $\mathcal{A} \subseteq X_p$ is an apartment and $x, y, z \in \mathcal{A}$, we let $\angle_z^{\mathcal{A}}(x, y)$ be the standard Euclidean angle in \mathcal{A} between x and y as measured at z . For any subset $H \subseteq \mathcal{A}$, and points $x, z \in \mathcal{A}$, we let

$$\angle_z^{\mathcal{A}}(x, H) = \min\{\angle_z^{\mathcal{A}}(x, h) \mid h \in H\}.$$

Core of a sector From here on we will assume that $0 \leq \delta \leq 1$. For any $\mathfrak{S} \in \hat{X}_p$, we let

$$\mathfrak{S}(\delta) = \{ x \in \mathfrak{S} \mid d(\partial\mathfrak{S}, x) \geq \delta d(e, x) \}.$$

We refer to $\mathfrak{S}(\delta)$ as the δ -core of \mathfrak{S} . Note that

$$\bigcup_{\mathfrak{S} \in \hat{X}_p} \mathfrak{S}(\delta) = X_{p, e_p}(\delta),$$

where $X_{p, e_p}(\delta)$ is the δ -nondegenerate space of X_p at e_p .

Relations between angles and distances It is clear that geodesic rays based at e_p and travelling into the core of a sector travel transversely to walls. We need a quantitative form of this fact which is the substance of the following:

Lemma 3.1 Suppose $\mathfrak{S} \in \widehat{X}_p$ and $\mathfrak{S} \subseteq \mathcal{A}$ for some apartment \mathcal{A} . Assume that $x \in \mathfrak{S}(\delta)$, $z \in \gamma_{\mathfrak{S}}$, and $H_z \subseteq \mathcal{A}$ is a wall containing z . Then

$$\angle_z^{\mathcal{A}}(x, H_z) \geq \sin^{-1}(\delta/2)$$

whenever $d(x, e_p) \geq r$ and $d(z, e_p) \leq (\delta r)/2$.

Proof Notice that $\angle_z^{\mathcal{A}}(x, H_z)$ is minimized when $x \in \partial\mathfrak{S}(\delta)$, $d(x, e_p) = r$, and H_z is parallel to a wall H_{e_p} that bounds \mathfrak{S} . Therefore, we will assume these three statements are true. Clearly, $\angle_z^{\mathcal{A}}(x, H_z) = \angle_z^{\mathcal{A}}(x, \pi_{H_z}(x))$ where $\pi_{H_z}: \mathcal{A} \rightarrow H_z$ is the orthogonal projection.

Note that
$$d(H_z, H_{e_p}) \leq d(z, e_p) \leq \frac{\delta r}{2},$$

and
$$d(x, H_{e_p}) = d(x, \partial\mathfrak{S}) = \delta r.$$

Therefore,

$$d(x, \pi_{H_z}(x)) = d(x, H_{e_p}) - d(H_{e_p}, H_z) \geq \delta r - \frac{\delta r}{2} = \frac{\delta r}{2}.$$

We conclude the proof by observing that

$$\angle_z^{\mathcal{A}}(x, \pi_{H_z}(x)) = \sin^{-1} \left[\frac{d(x, \pi_{H_z}(x))}{d(x, z)} \right] \geq \sin^{-1}(\delta/2)$$

since $d(x, z) \leq d(x, e_p) \leq r$. □

The next lemma shows that deep points in the nondegenerate region of X_p at e_p that are separated by a large angle measured at e_p must be a large distance apart. A form of notation we will use in the proof is $[e_p, z]$ to denote the geodesic segment with endpoints at e_p and z .

Lemma 3.2 Suppose $x, y \in X_{p, e_p}(\delta)$ and $\Theta_p(x, y) \geq 2/(\delta r)$, while $d(x, e_p) \geq r$ and $d(y, e_p) \geq r$. Then $d(x, y) \geq (\delta r)/2$ as long as $\delta \leq 1$.

Proof Choose sectors $\mathfrak{S}_x, \mathfrak{S}_y \in \widehat{X}_p$ such that $\mathfrak{S}_x \in \Phi_p(x)$ and $\mathfrak{S}_y \in \Phi_p(y)$. Let $z \in X_p$ be such that $\gamma_x \cap \gamma_y = [e_p, z]$. Then, we have $d(e_p, z) \leq (\delta r)/2$ since $\widehat{d}_p(\mathfrak{S}_x, \mathfrak{S}_y) \geq 2/(\delta r)$.

Choose an apartment \mathcal{A}_x containing \mathfrak{S}_x . Note that $\mathfrak{S}_y \cap \mathcal{A}_x$ is a convex polyhedron P in \mathcal{A}_x that is bounded by walls. Since $z \in \partial P$, there must be a wall $H_z \subseteq \mathcal{A}_x$ such that $z \in H_z$ and $\mathcal{A}_x - H_z$ has a component which does not intersect \mathfrak{S}_y . Choose a

chamber $c_z \subseteq \mathfrak{S}_x$ containing z whose interior lies in this component, and such that $F = c_z \cap \mathcal{A}_y$ is a codimension 1 simplex in c_z .

Let $c_y \subseteq \mathfrak{S}_y$ be a chamber containing y . Note that $[z, y] \cup c_z \subseteq \mathcal{B}(c_z, c_y)$, where $\mathcal{B}(c_z, c_y)$ is the union of minimal galleries from c_z to c_y . Hence, $[z, y] \cup c_z$ is contained in an apartment (see e.g. [1] VI.6). Therefore, $\varrho(\mathcal{A}_x, c_z)|_{\mathcal{B}(c_z, c_y)}$ is an isometry, where $\varrho(\mathcal{A}_x, c_z): X_p \rightarrow \mathcal{A}_x$ is the building retraction corresponding to the pair (\mathcal{A}_x, c_z) .

Since $F \subseteq \mathcal{A}_y$, there is a unique wall $H'_z \subseteq \mathcal{A}_y$ containing F . Since $F \subseteq H_z$ as well, we have $\angle_z^{\mathcal{A}_y}(y, H'_z) = \angle_z^{\mathcal{A}_x}(\varrho(\mathcal{A}_x, c_z)(y), H_z)$.

Since $\varrho(\mathcal{A}_x, c)$ is distance decreasing, and since H_z separates x from $\varrho(\mathcal{A}_x, c_z)(y)$, we have using Lemma 3.1:

$$\begin{aligned} d(x, y) &\geq d(\varrho(\mathcal{A}_x, c_z)(x), \varrho(\mathcal{A}_x, c_z)(y)) \\ &= d(x, \varrho(\mathcal{A}_x, c_z)(y)) \\ &\geq d(x, H_z) + d(\varrho(\mathcal{A}_x, c_z)(y), H_z) \\ &= \sin[\angle_z^{\mathcal{A}_x}(x, H_z)]d(z, x) + \sin[\angle_z^{\mathcal{A}_x}(\varrho(\mathcal{A}_x, c_z)(y), H_z)]d(z, \varrho(\mathcal{A}_x, c_z)(y)) \\ &= \sin[\angle_z^{\mathcal{A}_x}(x, H_z)]d(z, x) + \sin[\angle_z^{\mathcal{A}_y}(y, H'_z)]d(z, y) \\ &\geq \frac{\delta}{2} \left(d(x, e_p) - d(e_p, z) \right) + \frac{\delta}{2} \left(d(y, e_p) - d(e_p, z) \right) \\ &\geq \delta r \left(1 - \frac{\delta}{2} \right) \\ &\geq \frac{\delta r}{2}. \end{aligned} \quad \square$$

Our next lemma states that, after deleting a large compact set, if the core of two sectors based at e_p have a nontrivial intersection, then the two sectors are close in the boundary metric.

Lemma 3.3 *Let $\mathfrak{S}_1, \mathfrak{S}_2 \in \widehat{X}_p$, and suppose that $\mathfrak{S}_1(\delta) \cap \mathfrak{S}_2(\delta) \cap B_{e_p}(r)^c \neq \emptyset$. Then $\widehat{d}_p(\mathfrak{S}_1, \mathfrak{S}_2) \leq 2/(\delta r)$.*

Proof We prove the contrapositive. That is, we assume that $\gamma_{\mathfrak{S}_1} \cap \gamma_{\mathfrak{S}_2} = [e_p, z]$ where $d(e_p, z) < (\delta r)/2$.

Choose an apartment \mathcal{A} with $\mathfrak{S}_2 \subseteq \mathcal{A}$. We pick a wall, H_z , with $z \in H_z \subseteq \mathcal{A}$ and such that $\mathfrak{S}_1 \cap \mathfrak{S}_2 \subseteq \bar{J}$, where J is a component of $\mathcal{A} - H_z$ and \bar{J} is the closure of J .

By [Lemma 3.1](#), $x \in \mathfrak{S}_2(\delta) \cap B_e(r)^c$ implies that $\angle_z^A(x, H_z) \geq \sin^{-1}(\delta/2)$. Hence, any such x must be bounded away from H_z and, thus, from \bar{J} . We have shown

$$\mathfrak{S}_1(\delta) \cap \mathfrak{S}_2(\delta) \cap B_e(r)^c \subseteq \bar{J} \cap \mathfrak{S}_2(\delta) \cap B_e(r)^c = \emptyset$$

as desired. \square

To travel in the nondegenerate space between two deep points separated by a large angle, one must pass near the origin. More precisely we have the following:

Lemma 3.4 (No shifting) *Suppose there is a path $c: [0, 1] \rightarrow X_e(\delta) \cap B_e(r)^c$. Then $\Theta_p(c(0), c(1)) \leq 2/(\delta r)$.*

Proof Since $[0, 1]$ is compact, it is contained in finitely many sectors $\mathfrak{S}_0, \mathfrak{S}_1, \dots, \mathfrak{S}_k \in \hat{X}_p$. We may assume that these sectors are ordered so that there exists a partition of $[0, 1]$ of the form $0 = t_0 < t_1 < \dots < t_k = 1$ with $c(0) \in \mathfrak{S}_0$, $c(1) \in \mathfrak{S}_k$, and $c[t_i, t_{i+1}] \subseteq \mathfrak{S}_i$.

Notice that our partition requires that $c(t_i) \in \mathfrak{S}_i \cap \mathfrak{S}_{i+1}$. Hence, we can apply [Lemma 3.3](#) to obtain that $\hat{d}_p(\mathfrak{S}_i, \mathfrak{S}_{i+1}) \leq 2/(\delta r)$ for all i . Therefore,

$$\Theta_p(c(0), c(1)) \leq \hat{d}_p(\mathfrak{S}_0, \mathfrak{S}_k) \leq \max\{\hat{d}_p(\mathfrak{S}_i, \mathfrak{S}_{i+1})\} \leq \frac{2}{\delta r}. \quad \square$$

Limit points Let \hat{X}_∞ be the Furstenberg boundary of X_∞ . That is, we let \hat{X}_∞ be the space of all Weyl chambers up to Hausdorff equivalence. We endow \hat{X}_∞ with the standard metric, \hat{d}_∞ , invariant under the stabilizer of e_∞ . We let $\Phi_\infty: X_{\infty, e_\infty}(\delta) \rightarrow \hat{X}_\infty$ be the function that sends a point to its image at infinity. As X is the product of X_∞ and X_p , we define $\hat{X} = \hat{X}_\infty \times \hat{X}_p$.

A δ -limit point of ϕ from e is a boundary point $(\mathfrak{C}, \mathfrak{S}) \in \hat{X}$, such that there exists a path $\psi: [0, \infty) \rightarrow \phi^{-1}(X_e(\delta))$ that escapes every compact set, $\lim_{t \rightarrow \infty} \Phi_\infty \circ \phi \circ \psi(t) = \mathfrak{C}$, and $\lim_{t \rightarrow \infty} \Phi_p \circ \phi \circ \psi(t) = \{\mathfrak{S}\}$. If this is the case we call ψ a *limit path* from e , and we write that ψ *limits to* $(\mathfrak{C}, \mathfrak{S})$. We call the set of all δ limit points of ϕ from e , the δ -limit set of ϕ from e . We denote the δ -limit set of ϕ from e by $\mathcal{L}_{\phi, e}(\delta)$.

Existence of nondegenerate visual directions For the next result of this section, we return to the material of [Section 2](#) and in particular to [Corollary 2.9](#).

Later we will want to show there are a finite number of limit points in the limit set of ϕ to create the finite number of flats for the conclusion of [Theorem 1.2](#). This plan will only succeed if there is a limit point to start with. The results of [Section 2](#) were derived for the purpose of showing that limit points exist. By the Proposition below, we not only know they exist, we also have precise information on how to construct them.

Proposition 3.5 (Deep points extended to limit points) *Let v_3 be as in Corollary 2.9. There is a constant $\eta_2 = \eta_2(\kappa, \delta)$, such that if $\varepsilon \ll \delta \ll 1$ and $z \in \phi^{-1}(X_e(\delta))$ with $1 \ll_{(\delta, \varepsilon, \rho)} r \leq d(z, 0)$, then there exists a boundary point $(\mathfrak{C}, \mathfrak{S}) \in \mathcal{L}_{\phi, e}(\delta/v_3)$, such that*

$$\hat{d}_p(\mathfrak{S}, \Phi_p \circ \phi_p(z)) \leq \frac{2}{\delta r}$$

and

$$\hat{d}_\infty(\mathfrak{C}, \Phi_\infty \circ \phi_\infty(z)) \leq e^{-\eta_2 r}.$$

Proof Let U be the connected component of $\phi^{-1}(X_e(\delta/v_3)) \cap B_0(r)^c$ that contains z . From Corollary 2.9 we know that U is unbounded, so there exists a path $\psi: [0, \infty) \rightarrow U$ with $\psi(0) = z$ and such that ψ escapes every compact set.

Applying Lemma 3.4, we have that the diameter of $\Phi_p \circ \phi_p \circ \psi([s, \infty))$ is at most $2/(\delta R_s)$, where $R_s = d(0, \psi([s, \infty)))$. Notice that $R_s \rightarrow \infty$ as $s \rightarrow \infty$, and

$$\Phi_p \circ \phi_p \circ \psi([t, \infty)) \subseteq \Phi_p \circ \phi_p \circ \psi([s, \infty))$$

when $0 \leq s \leq t$. Therefore, $\lim_{s \rightarrow \infty} \Phi_p \circ \phi_p \circ \psi(s)$ exists. Call this limit $\{\mathfrak{S}\}$.

We conclude by remarking that $\hat{d}_p(\mathfrak{S}, \Phi_p \circ \phi_p(z)) \leq 2/(\delta r)$ since

$$\Phi_p \circ \phi_p(z) = \Phi_p \circ \phi_p \circ \psi(0) \in \Phi_p \circ \phi_p \circ \psi([0, \infty))$$

and $R_0 = r$.

The second part of the proposition is the content of Proposition 5.9 from [3]. \square

A bound on visual directions for annuli Once we show that there is a bound on the number of directions at infinity that a graded quasiflat can extend in, we can produce a finite collection of flats that will be our candidates for satisfying the conclusion of Theorem 1.2.

Before showing that the number of asymptotic directions a graded quasiflat travels in is bounded, we will show that the number of directions is bounded for a quasi-annuli. This bound is independent of the size of the quasi-annuli. We will then be in a position to apply the no shifting Lemma in a limiting argument to show that the same bound exists for the number of directions of a graded quasiflat.

Let $A_R \subseteq X_p$ be the annulus centered at e_p , with inner radius R and outer radius $2R$. Let $\phi_\infty = \pi_\infty \circ \phi$, and let $\phi_p = \pi_p \circ \phi$.

Before proceeding, note that $\pi_\infty(X_e(\delta)) = X_{\infty, e_\infty}(\delta)$ and $\pi_p(X_e(\delta)) = X_{p, e_p}(\delta)$.

Lemma 3.6 *The image of $\pi_p[\phi(A_R) \cap X_e(\delta)]$ under Φ_p can be covered by $c_p = O(1/\delta^{2m})$ disjoint balls of radius $(4\kappa)/(\delta^2 R)$ for $R > \rho$ and $\varepsilon \ll \delta$.*

Proof Let $\mathfrak{S}_i \in \widehat{X}_p$ be such that $\cup_i B_{\mathfrak{S}_i}(\frac{4\kappa}{\delta^2 R}) = \widehat{X}_p$, and $B_{\mathfrak{S}_i}(\frac{4\kappa}{\delta^2 R}) \cap B_{\mathfrak{S}_j}(\frac{4\kappa}{\delta^2 R}) = \emptyset$ if $i \neq j$. That the balls can be chosen to be disjoint is a consequence of the ultrametric property for \widehat{X}_p .

We will twice make use of the fact that if $x \in A_R \cap \phi^{-1}(X_e(\delta))$, then

$$(1) \quad \begin{aligned} d(\phi_p(x), e_p) &= d(\phi(x), (\phi_\infty(x), e_p)) \\ &\geq \delta d(\phi(x), e) \\ &\geq \frac{\delta}{2\kappa} D_0(\rho; x) \\ &\geq \frac{\delta R}{2\kappa}. \end{aligned}$$

We claim that for any $x \in A_R \cap \phi^{-1}(X_e(\delta))$,

$$\Phi_p(\phi_p(x)) \subseteq B_{\mathfrak{S}_i}\left(\frac{4\kappa}{\delta^2 R}\right) \quad \text{for some } i.$$

Indeed, suppose $\mathfrak{Z}, \mathfrak{Y} \in \Phi_p(\phi_p(x))$, and that $\mathfrak{Z} \in B_{\mathfrak{S}_i}(\frac{4\kappa}{\delta^2 R})$. Notice that $\phi_p(x) \in X_{p,e_p}(\delta)$, so we can apply (1) and [Lemma 3.3](#) to obtain

$$\widehat{d}_p(\mathfrak{Z}, \mathfrak{Y}) \leq \frac{4\kappa}{\delta^2 R}.$$

Therefore, $\widehat{d}_p(\mathfrak{Y}, \mathfrak{S}_i) \leq \max\{\widehat{d}_p(\mathfrak{Y}, \mathfrak{Z}), \widehat{d}_p(\mathfrak{Z}, \mathfrak{S}_i)\} \leq \frac{4\kappa}{\delta^2 R}$

as claimed.

Suppose $i \neq j$. If $\Phi_p(\phi_p(x)) \subseteq B_{\mathfrak{S}_i}(\frac{4\kappa}{\delta^2 R})$ and $\Phi_p(\phi_p(y)) \subseteq B_{\mathfrak{S}_j}(\frac{4\kappa}{\delta^2 R})$ for a pair of points $x, y \in A_R \cap \phi^{-1}(X_e(\delta))$, then $B_{\mathfrak{S}_i}(\frac{4\kappa}{\delta^2 R}) \cap B_{\mathfrak{S}_j}(\frac{4\kappa}{\delta^2 R}) = \emptyset$. Hence, by the ultrametric property of \widehat{X}_p we have

$$\widehat{d}_p(\Phi_p \circ \phi_p(x), \Phi_p \circ \phi_p(y)) \geq \frac{4\kappa}{\delta^2 R} = \frac{2}{\delta(\delta R/2\kappa)}.$$

Therefore, $d(\phi_p(x), \phi_p(y)) \geq \frac{\delta(\delta R/2\kappa)}{2} = \frac{\delta^2 R}{4\kappa}$

by (1) and [Lemma 3.3](#). Thus,

$$\begin{aligned}
 d(x, y) &\geq \frac{1}{\kappa} d(\phi(x), \phi(y)) - \varepsilon D_0(\rho; x, y) \\
 &\geq \frac{1}{\kappa} d(\phi_p(x), \phi_p(y)) - \varepsilon D_0(\rho; x, y) \\
 &\geq \frac{\delta^2 R}{4\kappa^2} - \varepsilon 2R \\
 &\geq \frac{\delta^2 R}{5\kappa^2}.
 \end{aligned}$$

In summary, we have shown that

$$(2) \quad d(B_i, B_j) \geq \frac{\delta^2 R}{5\kappa^2} \quad (i \neq j)$$

where

$$B_i = A_R \cap \phi^{-1} \left[\pi_p^{-1} \left[\Phi_p^{-1} \left[B_{\mathfrak{S}_i} \left(\frac{4\kappa}{\delta^2 R} \right) \right] \right] \cap X_e(\delta) \right].$$

If μ_m is Lebesgue measure on \mathbb{E}^m , then

$$(3) \quad \mu_m[A_R \cap \phi^{-1}(X_e(\delta))] \leq \mu_m[A_R] < \mu_m[B_0(1)](2R)^m.$$

Combining (2) and (3) tells us that the number of nonempty B_i is bounded above by

$$\frac{(10\kappa^2)^m (2R)^m}{(\delta^2 R)^m} = \frac{20^m \kappa^{2m}}{\delta^{2m}}. \quad \square$$

We will also need to know that projecting onto the symmetric space factor will produce a bound on the visual angles there. This is [Lemma 4.2](#) in [\[3\]](#) which we state as

Lemma 3.7 *There exists a constant $\eta_3 = \eta_3(\kappa, \delta)$, such that the image of $\pi_\infty[\phi(A_R) \cap X_e(\delta)]$ under Φ_∞ can be covered by $c_\infty = O(1/\delta^{2m})$ balls of radius $e^{-\eta_3 R}$ for $1 \ll_{(\rho, \delta)} R$ and $\varepsilon \ll \delta$.*

Note that in [\[3\]](#) there is no building factor. Thus, the statement of [Lemma 4.2](#) in [\[3\]](#) does not mention the projection map π_∞ . Also note that the number of balls in [\[3\]](#) [Lemma 4.2](#) is bounded by the smaller term $O(1/\delta^m)$. When projecting, a factor of δ makes its way into the proof from the inequality $d(\pi_\infty(x), e_\infty) \geq \delta d(x, e)$ for $x \in X_e(\delta)$. The extra factor of δ influences c_∞ by adjusting the bound from $O(1/\delta^m)$ to $O(1/\delta^{2m})$, and our constant η_3 is proportional to the corresponding constant in [\[3\]](#). Aside from these minor adjustments, the proof carries through without modification.

A bound on visual directions for entire quasiflats Using the bound on the number of visual directions for annuli, we are prepared to pass to the limit and produce a bound for the number of δ -limit points of ϕ .

Proposition 3.8 (Finite limit set) *For δ sufficiently small, $|\mathcal{L}_{\phi,e}(\delta)| < c_\infty c_p$.*

Proof Assume there are $c_\infty c_p + 1$ limit points $\{(\mathcal{C}_i, \mathfrak{S}_i)\}_{i=1}^{c_\infty c_p + 1}$. We will arrive at a contradiction.

There are two cases to consider as either

$$|\{\mathcal{C}_i\}_{i=1}^{c_\infty c_p + 1}| > c_\infty \quad \text{or} \quad |\{\mathfrak{S}_i\}_{i=1}^{c_\infty c_p + 1}| > c_p.$$

We will begin by assuming the latter.

After possibly re-indexing, let $\mathfrak{S}_1, \mathfrak{S}_2, \dots, \mathfrak{S}_{c_p+1}$ be distinct elements of $\{\mathfrak{S}_i\}_{i=1}^{c_\infty c_p + 1}$. Let $\alpha = \min_{i \neq j} \{\widehat{d}(\mathfrak{S}_i, \mathfrak{S}_j)\}$. By assumption, there are paths

$$\psi_i: [0, \infty) \rightarrow \phi^{-1}(X_e(\delta))$$

such that $\lim_{t \rightarrow \infty} \Phi_p \circ \phi_p \circ \psi_i(t) = \{\mathfrak{S}_i\}$. Pick $t_i > 0$ such that

$$(4) \quad \bigcup \Phi_p \circ \phi_p \circ \psi_i([t_i, \infty)) \subseteq B_{\mathfrak{S}_i}\left(\frac{\alpha}{2}\right) \quad \text{for all } 0 \leq i \leq c_p + 1.$$

We will need a more uniform choice for the t_i to allow us to apply [Lemma 3.6](#), so we let

$$R = \max \left\{ \frac{8\kappa}{\alpha\delta^2}, d(\psi_1(t_1), 0), d(\psi_2(t_2), 0), \dots, d(\psi_{c_p+1}(t_{c_p+1}), 0) \right\}.$$

Then we take $t'_i > 0$ such that $d(\psi_i(t'_i), e) = R$ for all $0 \leq i \leq c_p + 1$.

By our choice of α ,

$$B_{\mathfrak{S}_i}\left(\frac{\alpha}{2}\right) \cap B_{\mathfrak{S}_j}\left(\frac{\alpha}{2}\right) = \emptyset \quad \text{for } i \neq j.$$

Therefore, by (4),

$$B_{\mathfrak{Z}_i}\left(\frac{\alpha}{2}\right) \cap B_{\mathfrak{Z}_j}\left(\frac{\alpha}{2}\right) = \emptyset \quad \text{for } i \neq j,$$

where $\mathfrak{Z}_i \in \widehat{X}_p$ is a sector containing $\phi_p \circ \psi_i(t'_i)$. In particular, $\mathfrak{Z}_i \notin B_{\mathfrak{Z}_j}(\alpha/2)$ for $i \neq j$. However, we can apply [Lemma 3.6](#) to obtain a proper subset P of $\{1, \dots, c_p + 1\}$ such that

$$\{\mathfrak{Z}_i\}_{i=1}^{c_p+1} \subseteq \bigcup_{i \in P} B_{\mathfrak{Z}_i}\left(\frac{\alpha}{2}\right).$$

This is a contradiction.

If we assume $|\{\mathcal{C}_i\}_{i=1}^{c_\infty c_p + 1}| > c_\infty$, we can arrive at a similar contradiction using [Lemma 3.7](#). The details are carried out in Proposition 5.2 in [\[3\]](#). \square

4 Independence of basepoint

So far we have limited ourselves by considering a fixed basepoint e . The proof of [Theorem 1.2](#) will require us to hop around from point to point in our quasiflat with holes, and to treat several points as basepoints for the nondegenerate space and, hence, for the limit set of ϕ . We will need to know therefore, that all of the corresponding nondegenerate spaces and limit sets are compatible with each other—that they are the same up to minor modifications of δ .

The following lemma is essentially Lemma 5.3 from [3].

Lemma 4.1 *Let $r > 0$ be given and let $e' \in X$ be such that $d(e, e') \leq r$. If $x \in \phi^{-1}(X_e(\delta))$ and $d(x, 0) \geq \max\{\rho, (6kr)/\delta\}$ for some $x \in \mathbb{E}^m$, then $x \in \phi^{-1}(X_{e'}(\delta/2))$ as long as $\delta \leq 1/3$.*

The next lemma is a short technical remark used in the final lemma of this section.

Lemma 4.2 *There exists a constant $\nu_4 = \nu_4(X_p)$ such that if $\mathfrak{S} \subseteq X_p$ is a sector based at e , and $\mathfrak{S}' \subseteq X_p$ is a sector based at $e' \in X_p$ with $\text{Hd}(\mathfrak{S}, \mathfrak{S}') < \infty$, then there is a sector $\mathfrak{Z} \subseteq \mathfrak{S} \cap \mathfrak{S}'$ such that $\text{Hd}(\mathfrak{Z}, \mathfrak{S}) \leq \nu_4 d(e, e')$.*

Proof Let \mathfrak{S} be contained in an apartment \mathcal{A} . Then there are isometries $a, n_1, n_2, \dots, n_k \in \text{Isom}(X_p)$ such that a stabilizes \mathcal{A} , each n_i stabilizes a half-space of \mathcal{A} containing a subsector of \mathfrak{S}' , and k is bounded by a constant depending only on X .

It is clear that the result holds if $\mathfrak{S}' = a\mathfrak{S}$ or $\mathfrak{S}' = n_i\mathfrak{S}$. Hence the result for the general \mathfrak{S}' holds by the triangle inequality. \square

We are prepared to show that the δ -limit set of ϕ is as independent of the choice of basepoint as one would expect. First though we need to identify the boundaries of X_p created using two different basepoints. Previously we had defined \widehat{X}_p in a way that depended on e_p . This was done mostly for notational convenience, but the dependence on a basepoint would now be a hindrance for us.

Our solution is to give an equivalent definition of \widehat{X}_p as the space of all sectors with arbitrary basepoints modulo the equivalence that two sectors be identified if they are a finite Hausdorff distance from each other (this is equivalent to the condition that the intersection of the two sectors contains a third sector). Now the metric on \widehat{X}_p is determined by a choice of a basepoint (only up to a Lipschitz equivalence though), but the space \widehat{X}_p itself is independent of that choice.

Lemma 4.3 *Let $e' = \phi(0')$ for some $0' \in \mathbb{E}^m$, and suppose ϕ is a $(\kappa, \rho, \varepsilon)$ (RGQIE) based at $0'$ as well as at 0 . If $\delta \ll 1$, then $\mathcal{L}_{\phi, e'}(\delta) \subseteq \mathcal{L}_{\phi, e}(\delta/2)$.*

Proof Suppose $(\mathcal{C}', \mathfrak{S}') \in \mathcal{L}_{\phi, e'}(\delta)$. Then there is a path $\psi: [0, \infty) \rightarrow \phi^{-1}(X_{e'}(\delta))$ such that the path $\phi_p \circ \psi: [0, \infty) \rightarrow X_{\pi_p(e')}(\delta)$ escapes every compact set and limits to $\{\mathfrak{S}'\}$ when observed from $\pi_p(e')$.

Let \mathfrak{S} be the sector based at e_p such that $\text{Hd}(\mathfrak{S}', \mathfrak{S}) < \infty$. Our goal is to show that $\phi_p \circ \psi$ limits to \mathfrak{S} when observed from e_p .

To this end, for a given $t > 0$, let \mathfrak{S}_t be a sector based at e_p such that $\phi_p \circ \psi(t) \in \mathfrak{S}_t$. Let \mathfrak{S}'_t be a sector based at $\pi_p(e')$ such that $\text{Hd}(\mathfrak{S}'_t, \mathfrak{S}_t) < \infty$. Note that, by [Lemma 4.2](#), $\phi_p \circ \psi(t) \in \mathfrak{S}'_t$ for sufficiently large values of t . Hence, the family \mathfrak{S}'_t limits to \mathfrak{S}' from the vantage point of $\pi_p(e')$.

Therefore, for any number $r > 0$ and sufficiently large values of t , we have $\gamma_{\mathfrak{S}'}(r) \in \mathfrak{S}'_t$. Recall that $\gamma_{\mathfrak{S}'}$ is the geodesic ray in \mathfrak{S}' based at $\pi_p(e')$ that travels down the center of \mathfrak{S}' and is used for measuring distances between points in \hat{X}_p from the vantage point of $\pi_p(e')$.

By [Lemmas 4.1](#) and [4.2](#), $\gamma_{\mathfrak{S}'}(r) \in \mathfrak{S}_t(\delta/2) \cap \mathfrak{S}(\delta/2)$. Now applying the no shifting Lemma gives us that

$$\hat{d}_p(\mathfrak{S}_t, \mathfrak{S}) \rightarrow 0$$

as $t \rightarrow \infty$. Therefore,

$$\lim_{t \rightarrow \infty} \Phi_p \circ \phi_p \circ \psi(t) = \{\mathfrak{S}\}$$

as desired.

For the symmetric space part of the proof, see [Lemma 5.4](#) of [\[3\]](#). □

5 Proof of [Theorem 1.2](#)

Using the tools we have assembled thus far (in particular large-scale homology of pinched sets, the no shifting Lemma, extending deep points to limit points, the bound on limit points, and the independence of basepoints) we can retrace the proof of Eskin–Farb given in [\[3\]](#) to prove the quasiflats with holes theorem. Since this proof is essentially contained in [\[3\]](#), we will at times only sketch the arguments.

Proof of [Theorem 1.2](#) Since $\Omega_{(\varepsilon, \rho')} \subseteq \Omega_{(\varepsilon, \rho)}$ when $\rho' < \rho$, we may assume that $1 \ll_{(C)} \rho$. We let ε and δ be positive numbers such that $\varepsilon \ll \delta \ll 1$.

As in the proof of Theorem 8.1 of [3], if $x \in \Omega_{(\varepsilon, \rho)}$, we can use a connect-the-dots construction to define a continuous map $\phi_x: \mathbb{E}^m \rightarrow X$ such that $d(\phi_x(y), \varphi(y)) \leq O(\varepsilon)D_x(\rho; y)$. Hence, ϕ_x is a $(\kappa, \rho, O(\varepsilon))$ (RGQIE) based at x .

Let ∂X be the Tits building for X . Because \hat{X} can be identified with the simplices of maximal dimension in ∂X , we can measure their distances under the Tits metric. It is well known that if a pair of points in \hat{X} have maximal Tits distance (“opposite points”), then there is a unique flat that contains the pair up to Hausdorff equivalence. Let F_1, \dots, F_M be the flats so obtained from pairs of opposite points in $\mathcal{L}_{\phi_x, \phi_x(x)}(\delta)$. Note that $M \leq (c_\infty c_p)^2$ where c_∞ and c_p are as in Lemmas 3.6 and 3.7.

We will show that $\phi_x(x)$ is contained in a bounded neighborhood of $\cup_{i=1}^M F_i$, but first we want to demonstrate that the limit set, and hence our choice of flats, is independent of x .

Suppose $z \in \Omega_{(\varepsilon, \rho)}$ and ϕ_z is constructed as ϕ_x to be a $(\kappa, \rho, O(\varepsilon))$ (RGQIE) of \mathbb{E}^m based at z .

By construction, we have for any point $y \in X$:

$$(5) \quad d(\phi_z(y), \phi_x(y)) \leq O(\varepsilon)(D_z(\rho; y) + D_x(\rho; y)).$$

It follows that ϕ_z is a $(2\kappa, \rho + 2d(x, z), O(\varepsilon))$ (RGQIE) based at x . Hence, we obtain through Lemma 4.3 that

$$\mathcal{L}_{\phi_z, \phi_z(z)}(\delta) \subseteq \mathcal{L}_{\phi_z, \phi_z(x)}(\delta/2).$$

If $(\mathfrak{C}, \mathfrak{S}) \in \mathcal{L}_{\phi_z, \phi_z(x)}(\delta/2)$, then there is a corresponding limit path $\psi: [0, \infty) \rightarrow \phi_z^{-1}(X_{\phi_z(x)}(\delta/2))$ that limits to $(\mathfrak{C}, \mathfrak{S})$.

It follows from (5) that $\psi(t) \in \phi_x^{-1}(X_{\phi_x(x)}(\delta/4))$ for sufficiently large values of t .

By projecting ψ onto factors and applying Lemma 3.2 of this paper and Lemma 4.1.i of [3] respectively, we see that

$$\Theta_{p, \phi_x(x)}(\pi_p \circ \phi_x \circ \psi(t), \pi_p \circ \phi_z \circ \psi(t)) \rightarrow 0$$

and

$$\Theta_{\infty, \phi_x(x)}(\pi_\infty \circ \phi_x \circ \psi(t), \pi_\infty \circ \phi_z \circ \psi(t)) \rightarrow 0$$

as $t \rightarrow \infty$. The function $\Theta_{p, \phi_x(x)}$ above is defined analogously to Θ_p with a basepoint of $\pi_p(\phi_x(x))$ rather than e_p , and $\Theta_{\infty, \phi_x(x)}$ is the Furstenberg angle between points in X_∞ measured at the point $\pi_\infty(\phi_x(x))$.

Therefore, it must be that $(\mathfrak{C}, \mathfrak{S}) \in \mathcal{L}_{\phi_x, \phi_x(x)}(\delta/4)$, and hence,

$$\mathcal{L}_{\phi_z, \phi_z(x)}(\delta/2) \subseteq \mathcal{L}_{\phi_x, \phi_x(x)}(\delta/4).$$

Joining this inclusion with the previous inclusion of limit sets we have

$$\mathcal{L}_{\phi_z, \phi_z(z)}(\delta) \subseteq \mathcal{L}_{\phi_x, \phi_x(x)}(\delta/4).$$

This shows that our choice of flats is well defined up to replacing δ with $\delta/4$.

Now we return to the task of showing that $\phi_x(x)$ is within a bounded distance of $\cup_{i=1}^M F_i$. For the remainder of the proof we let $\phi = \phi_x$.

For a fixed $1 \ll_{(\rho, \delta, \varepsilon)} R$ there must be a $y \in \phi^{-1}(X_{\phi(x)}(\delta))$ such that $d(\phi(y), \phi(x)) = 2R$. Otherwise, we could apply [Lemma 2.8](#) with $W \subseteq \mathbb{E}^m$ equal to the sphere centered at x with radius $d(x, y)$ to obtain a contradiction.

Let $e = (e_\infty, e_p)$ be the midpoint of the geodesic between $\phi(y)$ and $\phi(x)$ so that $\phi(x), \phi(y) \in X_e(\delta)$. We project to each factor. Again we will examine the case of a building.

By [Proposition 3.5](#), there are limit points $(\mathfrak{C}_i, \mathfrak{S}_i) \in \mathcal{L}_{\phi, e}(\delta)$ for $i = 1, 2$ such that $\hat{d}_p(\mathfrak{S}_1, \Phi_p \circ \phi_p(x)) \leq 2/(\delta R)$ and $\hat{d}_p(\mathfrak{S}_2, \Phi_p \circ \phi_p(y)) \leq 2/(\delta R)$. This implies that in the link at e_p —denoted by $L_{e_p} \subseteq X_p$ —the chambers $\mathfrak{S}_1 \cap L_{e_p}$ and $\mathfrak{S}_2 \cap L_{e_p}$ are opposite. Therefore, \mathfrak{S}_1 and \mathfrak{S}_2 are opposite in \hat{X}_p under the Tits metric, and there is a unique apartment $\mathcal{A}^{12} \subseteq X_p$ that contains subsectors of \mathfrak{S}_1 and \mathfrak{S}_2 .

We also note that the geodesic segments $[e_p, \phi_p(x)]$ and $[e_p, \phi_p(y)]$ can be extended to geodesic rays $\gamma_x \subseteq \mathfrak{S}_1$ and $\gamma_y \subseteq \mathfrak{S}_2$ respectively. The bi-infinite path $\gamma_x \cup \gamma_y$ is a local geodesic, so it is a global geodesic which we name γ .

As γ is a convex subset of Euclidean space, it is contained in an apartment $\mathcal{A}' \subseteq X_p$. Since $\gamma \subseteq \mathcal{A}'$, we have that \mathcal{A}' contains subsectors of \mathfrak{S}_1 and \mathfrak{S}_2 . Hence,

$$e_p \in \gamma \subseteq \mathcal{A}' = \mathcal{A}^{12}.$$

Therefore,

$$d(\phi_p(x), \mathcal{A}^{12}) \leq d(\phi_p(x), e_p) \leq R.$$

In the proof of [Theorem 1.1](#) of [\[3\]](#), it is shown that there is a constant Λ , depending only on X_∞ , and a flat $F^{12} \subseteq X_\infty$ that contains \mathfrak{C}_1 and \mathfrak{C}_2 up to Hausdorff equivalence, and such that

$$d(\phi_\infty(x), F^{12}) \leq \frac{1}{2}(\kappa R + C) + \Lambda.$$

Combining this inequality with its building analogue above yields:

$$d(\phi(x), F^{12} \times \mathcal{A}^{12}) \leq \sqrt{R^2 + \left(\frac{1}{2}(\kappa R + C) + \Lambda\right)^2}.$$

The proof of [Theorem 1.2](#) is completed by observing that $F^{12} \times \mathcal{A}^{12} \subseteq X$ is the unique flat that contains $(\mathcal{C}_1, \mathfrak{S}_1)$ and $(\mathcal{C}_2, \mathfrak{S}_2)$ up to Hausdorff equivalence. Hence, $F^{12} \times \mathcal{A}^{12} \in \{F_i\}_{i=1}^M$. We take the constant N in the statement of [Theorem 1.2](#) to be $\sqrt{R^2 + (1/2(\kappa R + C) + \Lambda)^2}$. \square

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