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We show that if p/q-surgery on a nontrivial knot K yields the branched double cover of an alternating knot, then $|p/q| \le 4g(K) + 3$. This generalises a bound for lens space surgeries first established by Rasmussen. We also show that all surgery coefficients yielding the double branched covers of alternating knots must be contained in an interval of width two and this full range can be realised only if the knot is a cable knot. The work of Greene and Gibbons shows that if $S_{p/q}^3(K)$ bounds a sharp 4-manifold X, then the intersection form of X takes the form of a changemaker lattice. We extend this to show that the intersection form is determined uniquely by the knot K, the slope p/q and the Betti number $b_2(X)$.

57M12, 57M25; 57M27

1 Introduction

For a knot $K \subset S^3$ and $p/q \in \mathbb{Q}$ we say that $S^3_{p/q}(K)$ is an *alternating surgery* if it is the double branched cover of an alternating knot or link. In this paper, we will prove some bounds on the slopes of alternating surgeries. The first of these generalises a bound for lens space surgeries originally due to Rasmussen [27].

Theorem 1.1 If *K* is a nontrivial knot with an alternating surgery $S_{p/q}^3(K)$, then the slope p/q satisfies the inequality $|p/q| \le 4g(K) + 3$.

The bound in Theorem 1.1 is sharp with equality being attained by the $T_{2,n}$ torus knots. It turns out that whenever this bound is realised, the resulting alternating surgery yields a lens space. Hence, work of Baker [1, Theorem 1.2] shows that the $T_{2,n}$ torus knots are the only knots achieving equality in Theorem 1.1.

We can also obtain a bound on the range of slopes yielding alternating surgeries.

Theorem 1.2 If *K* is a nontrivial knot admitting an alternating surgery, then there is an integer *N* such that for any alternating surgery $S_{p/q}^3(K)$, the coefficient p/q lies in the interval

$$N-1 \le \frac{p}{q} \le N+1.$$

The definition of N is given Section 4.3. Theorem 1.2 shows that the range of slopes which yield alternating surgeries is contained in an interval with integer endpoints of width two. When every slope in this interval yields an alternating surgery, then we will show that the knot must be a cable knot. For the purposes of this paper, we consider torus knots to be cable knots.

Theorem 1.3 Suppose that *K* is a nontrivial knot admitting alternating surgeries $S_r^3(K)$ for each of the slopes $r \in \{r_1, r_2, N\}$, where *N* is the integer appearing in Theorem 1.2. If r_1 and r_2 satisfy

$$N - 1 \le r_1 < N < r_2 < N + 1,$$

then $S_N^3(K)$ is a reducible surgery and K is a cable knot.

Remark 1.4 It can be shown that Theorem 1.3 still holds under the slightly weaker condition that $r_2 \le N+1$. However, this relatively minor extension requires a substantial amount of work so we will not prove it here.

The starting point for the proof of these results is the work of Gibbons [6], which generalizes the work of Greene [9; 10; 11]. It provides strong restrictions on the intersection form of a negative-definite sharp 4-manifold X bounding $S_{p/q}^3(K)$ for p/q > 0, which must take the form of a changemaker lattice. In order to prove Theorems 1.2 and 1.3, we are required to determine the extent to which this intersection form depends on the knot K and the surgery slope p/q. This leads us to define the stable coefficients of a changemaker lattice. The definition of a changemaker lattice and its stable coefficients are given in Section 2.1. Let p/q have continued fraction expansion $p/q = [a_0, \ldots, a_l]^-$, where $a_i \ge 2$ for $1 \le i \le l$ and $a_0 \ge 1$. Here $[a_0, \ldots, a_l]^-$ denotes the Hirzebruch–Jung continued fraction

$$[a_0, \dots, a_l]^- = a_0 - \frac{1}{a_1 - \frac{1}{\ddots - \frac{1}{a_l}}}.$$

A p/q-changemaker lattice takes the form of an orthogonal complement

$$L = \langle w_0, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1} = \langle f_1, \dots, f_t, e_0, \dots, e_s \rangle,$$

where the f_i and e_j form an orthonormal basis for \mathbb{Z}^{r+s+1} , and the w_i have the properties that

$$w_i \cdot w_j = \begin{cases} a_i & \text{if } i = j, \\ -1 & \text{if } |i - j| = 1, \\ 0 & \text{if } |i - j| \ge 2, \end{cases}$$

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and

$$w_0 \cdot e_0 = 1,$$

$$w_0 \cdot e_i = 0 \quad \text{for } 1 \le i \le s,$$

$$w_0 \cdot f_i \ge 0 \quad \text{for } 1 \le i \le t,$$

$$w_j \cdot f_i = 0 \quad \text{for } 1 \le i \le t \text{ and } 1 \le j \le l.$$

The stable coefficients of L are defined to be the values of $w_0 \cdot f_i$ satisfying $w_0 \cdot f_i > 1$.

Theorem 1.5 Let $K \subset S^3$ be a knot and suppose that $S^3_{p/q}(K)$ bounds a negativedefinite sharp 4-manifold X with intersection form Q_X for some p/q > 0. Then the positive-definite lattice $-Q_X$ embeds into $\mathbb{Z}^{b_2(X)+l+1}$ as a p/q-changemaker lattice, where the stable coefficients are determined by K.

The stable coefficients in Theorem 1.5 form an invariant of the knot K that can be calculated from the knot Floer homology of K. Section 2.3 provides an algorithm for this calculation. When K is an L-space knot, the stable coefficients can be computed directly from its Alexander polynomial. The integer N appearing in Theorems 1.2 and 1.3 is defined in terms of stable coefficients and hence is an invariant of K and can be calculated from the Alexander polynomial.

Remark 1.6 In addition to being a lower bound for alternating surgeries, the integer N - 1 appearing in Theorem 1.2 also has the property that if $S_{p/q}^3(K)$ bounds a negative-definite sharp 4-manifold then $p/q \ge N - 1$. We explain this observation after the proof of Theorem 1.2.

Given one negative-definite sharp 4-manifold, bounding a 3-manifold Y we can obtain another by taking a connected sum with $\overline{\mathbb{CP}}^2$. It follows from Theorem 1.5 that if $Y = S^3_{p/a}(K)$, then at the level of intersection forms this is the only possibility.

Corollary 1.7 Let $K \subset S^3$ be a knot such that for some p/q > 0, the 3-manifold $S^3_{p/q}(K)$ bounds negative-definite sharp 4-manifolds X and X', with $b_2(X') = b_2(X) + k$ for $k \ge 0$. Then

$$Q_{X'} \cong Q_X \oplus (-\mathbb{Z}^k) \cong Q_{X \#_k \overline{\mathbb{CP}^2}}.$$

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2 Changemaker lattices and sharp 4-manifolds

The aim of this section is to prove Theorem 1.5. We begin by defining changemaker lattices and recalling the necessary definitions and properties from Heegaard Floer homology. We finish the section by stating the properties of L-space surgeries that we will require to prove the results on alternating surgeries.

2.1 Changemaker lattices

We will define p/q-changemaker lattices for any p/q > 0. Changemaker lattices corresponding to the case q = 1 were defined by Greene in his solution to the lens space realisation problem [9] and work on the cabling conjecture [11]. The case q = 2 arose in his work on unknotting numbers [10]. The more general definition we state here is the one which arises in Gibbons' work [6].

Definition 2.1 We say $(\sigma_1, \ldots, \sigma_t)$ satisfies the *changemaker condition* if the following conditions hold:

 $0 \le \sigma_1 \le 1$ and $\sigma_{i-1} \le \sigma_i \le \sigma_1 + \dots + \sigma_{i-1} + 1$ for $1 < i \le t$.

The changemaker condition is equivalent to the following combinatorial result.

Proposition 2.2 (Brown [2]) Let $\sigma = (\sigma_1, \ldots, \sigma_t)$, with $\sigma_1 \leq \cdots \leq \sigma_t$. There is $A \subseteq \{1, \ldots, t\}$ such that $k = \sum_{i \in A} \sigma_i$ for every integer k with $0 \leq k \leq \sigma_1 + \cdots + \sigma_t$ if and only if σ satisfies the changemaker condition.

Now we are ready to define changemaker lattices. It is convenient to define integer and noninteger changemaker lattices separately, although the two are clearly similar.

Definition 2.3 (integral changemaker lattice) First suppose that q = 1, so that p/q > 0 is an integer. Let f_0, \ldots, f_t be an orthonormal basis for \mathbb{Z}^t . Let $w_0 = \sigma_1 f_1 + \cdots + \sigma_t f_t$ be a vector such that $||w_0||^2 = p$ and $(\sigma_1, \cdots, \sigma_t)$ satisfies the changemaker condition. Then

$$L = \langle w_0 \rangle^{\perp} \subseteq \mathbb{Z}^{t+1}$$

is a p/q-changemaker lattice. Let m be minimal such that $\sigma_m > 1$. We define the stable coefficients of L to be the tuple $(\sigma_m, \ldots, \sigma_t)$. If no such m exists, then we take the stable coefficients to be the empty tuple.

Definition 2.4 (nonintegral changemaker lattice) Now suppose that $q \ge 2$, so that p/q > 0 is not an integer. This has continued fraction expansion of the form $p/q = [a_0, a_1, \ldots, a_l]^-$, where $a_k \ge 2$ for $1 \le k \le l$ and $a_0 = \lceil p/q \rceil \ge 1$. Now define

$$m_0 = 0$$
 and $m_k = \sum_{i=1}^k a_i - k$ for $1 \le k \le l$.

Set $s = m_l$ and let $f_1, \ldots, f_t, e_0, \ldots, e_s$ be an orthonormal basis for the lattice \mathbb{Z}^{t+s+1} . Let $w_0 = e_0 + \sigma_1 f_1 + \cdots + \sigma_t f_t$ be a vector such that $(\sigma_1, \ldots, \sigma_t)$ satisfies the changemaker condition and $||w_0||^2 = a_0$. For $1 \le k \le l$, define

$$w_k = -e_{m_{k-1}} + e_{m_{k-1}+1} + \dots + e_{m_k}$$

We say that

$$L = \langle w_0, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1}$$

is a p/q-changemaker lattice. Let *m* be minimal such that $\sigma_m > 1$. We define the stable coefficients of *L* to be the tuple $(\sigma_m, \ldots, \sigma_t)$. If no such *m* exists, then we take the stable coefficients to be the empty tuple.

Remark 2.5 Since $m_k - m_{k-1} = a_k - 1$, the vectors w_0, \ldots, w_l constructed in Definition 2.4 satisfy

$$w_i.w_j = \begin{cases} a_j & \text{if } i = j, \\ -1 & \text{if } |i - j| = 1, \\ 0 & \text{otherwise.} \end{cases}$$

Remark 2.6 Let *L* be a p/q-changemaker lattice

$$L = \langle w_0 = e_0 + \sigma_1 f_1 + \dots + \sigma_t f_t, w_1, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1}$$

By definition, the stable coefficients determine the values of the σ_i satisfying $\sigma_i > 1$. Since $||w_0||^2 = \lceil p/q \rceil$, the stable coefficients fix the number of σ_i equal to 1 and this accounts for all nonzero σ_i . It follows that the number of σ_i equal to zero can be deduced from the rank of L. Thus we see that the value p/q, the stable coefficients and the rank determine L uniquely. Since we have $f_i \in L$ if and only if $\sigma_i = 0$, any two p/q-changemaker lattices L and L' with the same stable coefficients and $\operatorname{rk}(L') = \operatorname{rk}(L) + k$ satisfy $L' \cong L \oplus \mathbb{Z}^k$

2.2 Sharp 4–manifolds

Now we will give a summary of the necessary background on Heegaard Floer homology and its d-invariants. Let Y be a rational homology 3-sphere. Its Heegaard Floer

homology, $\widehat{HF}(Y)$, when defined with coefficients in $\mathbb{Z}/2\mathbb{Z}$, takes the form of a finitedimensional vector space over $\mathbb{Z}/2\mathbb{Z}$. The group $\widehat{HF}(Y)$ splits as a direct sum over spin^{*c*}-structures:

$$\widehat{\mathrm{HF}}(Y) \cong \bigoplus_{\mathfrak{s} \in \mathrm{Spin}^c(Y)} \widehat{\mathrm{HF}}(Y, \mathfrak{s}),$$

where $\widehat{HF}(Y, \mathfrak{s}) \neq 0$ for all $\mathfrak{s} \in \operatorname{Spin}^{c}(Y)$. We say that Y is an *L*-space if $\widehat{HF}(Y)$ is as small as possible:

$$\dim_{\mathbb{F}_2} \widehat{\mathrm{HF}}(Y) = |H^2(Y;\mathbb{Z})| = |\mathrm{Spin}^c(Y)|.$$

Associated to each summand there is a numerical invariant $d(Y, \mathfrak{s}) \in \mathbb{Q}$, called the d-invariant [22]. If Y is the boundary of a smooth negative-definite 4-manifold X, then for any $\mathfrak{t} \in \text{Spin}^{c}(X)$ which restricts to $\mathfrak{s} \in \text{Spin}^{c}(Y)$ there is a bound on the corresponding d-invariant,

(2-1)
$$c_1(\mathfrak{t})^2 + b_2(X) \le 4d(Y,\mathfrak{s}).$$

We say that X is *sharp* if for every $\mathfrak{s} \in \text{Spin}^{c}(Y)$ there is some $\mathfrak{t} \in \text{Spin}^{c}(X)$ which restricts to \mathfrak{s} and attains equality in (2-1).

We will be interested in the case where Y arises as surgery on a knot in S^3 . Let $K \subset S^3$ be a knot. For fixed $p/q \in \mathbb{Q} \setminus \{0\}$, there are canonical identifications [26]

$$\operatorname{Spin}^{c}(S^{3}_{p/q}(K)) \leftrightarrow \mathbb{Z}/p\mathbb{Z} \leftrightarrow \operatorname{Spin}^{c}(S^{3}_{p/q}(U)).$$

Using these identifications we are able to define

$$D_{p/q}(i) := d(S_{p/q}^3(K), i) - d(S_{p/q}^3(U), i)$$

for each $i \in \mathbb{Z}/p\mathbb{Z}$.

The work of Ni and Wu shows that for $0 \le i \le p-1$ these values may be calculated by the formula [20, Proposition 1.6]

(2-2)
$$D_{p/q}(i) = -2 \max\{V_{\lfloor i/q \rfloor}, H_{\lfloor (i-p)/q \rfloor}\},$$

where V_j and H_j are sequences of positive integers, depending only on K, which are nonincreasing and nondecreasing, respectively. These further satisfy $H_{-j} = V_j = 0$ for $j \ge g(K)$, where g(K) is the genus of K. In fact, it can be shown that $V_j = H_{-j}$ for all j [21, Proof of Theorem 3]. Using these properties of the V_j and H_j , (2-2) can be rewritten as

(2-3)
$$D_{p/q}(i) = -2V_{\min\{\lfloor i/q \rfloor, \lceil (p-i)/q \rceil\}}.$$

Let $p/q = [a_0, ..., a_l]^-$ be the continued fraction of p/q with $a_0 \ge 1$ and $a_i \ge 2$ for $i \ge 1$. The changemaker theorem we will use is the following.

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Theorem 2.7 (Gibbons [6]) Let $K \subset S^3$ be a knot and suppose that $S^3_{p/q}(K)$ bounds a smooth, negative-definite 4-manifold X with intersection form Q_X for some p/q > 0. If the manifold X is sharp, then $-Q_X$ embeds into $\mathbb{Z}^{b_2(X)+l+1}$ as a p/q-changemaker lattice,

$$-Q_X \cong L = \langle w_0, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1},$$

where w_0 satisfies the formula

(2-4)
$$8V_{|i|} = \min_{\substack{c \cdot w_0 \equiv a_0 + 2i \mod 2a_0 \\ c \in \operatorname{Char}(\mathbb{Z}^{t+1})}} \|c\|^2 - t - 1$$

for $|i| \le \frac{1}{2}a_0$.

Here $\operatorname{Char}(\mathbb{Z}^{t+1})$ denotes the set of all characteristic vectors in \mathbb{Z}^{t+1} , where a *characteristic vector* $x \in \mathbb{Z}^{t+1}$ is one with odd coefficients with respect to any orthonormal basis for \mathbb{Z}^{t+1} .

The equation (2-4) is not explicitly stated by Gibbons. However, Greene shows that it holds in the case of integer surgeries [11] and it follows from Gibbons' proof that it must also hold for noninteger surgeries. Further discussion of this can be found in [15].

2.3 Calculating stable coefficients

We will deduce Theorem 1.5 from Theorem 2.7 by showing that (2-4) determines the stable coefficients uniquely. The argument is entirely combinatorial and uses only the properties of the V_i stated in Section 2.2.

Let $(V_i)_{i \ge 0}$ be the nonincreasing, nonnegative sequence

$$V_0 \ge V_1 \ge \cdots \ge V_{\widetilde{g}-1} > V_{\widetilde{g}} = V_{\widetilde{g}+1} = \cdots = 0,$$

for which $V_i = 0$ if and only if $i \ge \tilde{g}$ and $V_i \le V_{i+1} + 1$ for all *i*. Suppose that there is $\rho = (\rho_0, \dots, \rho_t) \in \mathbb{Z}^{t+1}$, with $\|\rho\|^2 = n \ge 2\tilde{g}$, such that

(2-5)
$$8V_{|k|} = \min_{\substack{c \cdot \rho \equiv n+2k \mod 2n \\ c \in \operatorname{Char}(\mathbb{Z}^{t+1})}} \|c\|^2 - t - 1$$

for $|k| \le \frac{1}{2}n$. Possibly after an automorphism of \mathbb{Z}^{t+1} , we may assume that $\rho_i \ge 0$ for all *i* and that the ρ_i form a decreasing sequence

$$\rho_0 \ge \rho_1 \ge \cdots \ge \rho_t \ge 0.$$

Observe that (2-5) has three pieces of input data: the sequence $(V_i)_{i\geq 0}$ and the integers n and t. Given some choice of $(V_i)_{i\geq 0}$, n and t, there is no guarantee that there is



Figure 1: A graph to show the relationship between the V_i and the T_i . We have also shown how ρ_0 and ρ_1 occur as the number of V_i equal to one and two, respectively.

 ρ satisfying (2-5). However, we will show that when there is such a ρ , it is unique. Moreover we will see that the coefficients of ρ satisfying $\rho_i > 1$ are determined by the sequence $(V_i)_{i \ge 0}$.

Remark 2.8 If $\rho_t = 0$, then any minimiser in the right-hand side of (2-5) must have $c_t = \pm 1$. So we see that $\rho' = (\rho_0, \dots, \rho_{t-1})$ satisfies

$$8V_{|k|} = \min_{\substack{c \cdot \rho' \equiv n+2k \mod 2n \\ c \in \operatorname{Char}(\mathbb{Z}^t)}} \|c\|^2 - t$$

for all $0 \le |k| \le \frac{1}{2}n$. This allows us to assume that $\rho_i \ge 1$ for all *i*.

If we restrict our attention to $0 \le k \le \frac{1}{2}n$, we find that (2-5) simplifies as follows.

Lemma 2.9 For $0 \le k \le \frac{1}{2}n$,

$$8V_k = \min_{\substack{c \cdot \rho = 2k-n \\ c \in Char(\mathbb{Z}^{t+1})}} \|c\|^2 - t - 1.$$

Proof Suppose $c \in \text{Char}(\mathbb{Z}^{t+1})$ satisfies $c \cdot \rho = 2mn - n + 2k$ for some $m \in \mathbb{Z}$. Consider the vector $c' = c - 2m\rho$. This satisfies

$$c' \cdot \rho = 2k - n \equiv c \cdot \rho \mod 2n$$

and

$$\|c'\|^2 = \|c\|^2 - 4mc \cdot \rho + 4m^2n = \|c\|^2 - 4m(nm - n + 2k).$$

Since we are assuming $-n \le 2k - n \le 0$, we have $m(nm + 2k - n) \ge 0$ for all $m \in \mathbb{Z}$. Therefore, we have $||c'||^2 \le ||c||^2$. This shows that if *c* is a minimiser in (2-5) we can assume it satisfies $c \cdot \rho = 2k - n$.

For $m \ge 1$, it will be convenient to consider the quantities

$$T_m = |\{0 \le i < \widetilde{g} \mid 0 < V_i \le m\}|.$$

These are illustrated in Figure 1. We will show how to calculate these in terms of ρ . First we need to define the following collection of tuples for each $m \ge 0$:

 $S_m = \big\{ \alpha \in \mathbb{Z}^{r+1} : \alpha_i \ge 0, \ 2m = \sum \alpha_i (\alpha_i + 1) \big\}.$

Lemma 2.10 For $0 \le m < V_0$, we can calculate T_m by

$$T_m = \max_{\alpha \in S_m} \rho \cdot \alpha$$

and T_{V_0} satisfies

$$T_{V_0} = \widetilde{g} = \frac{1}{2} \sum_{i=0}^{l} \rho_i^2 - \rho_i \quad \text{and} \quad T_{V_0} \le \max_{\alpha \in S_{V_0}} \rho \cdot \alpha.$$

Proof Since the V_k form a decreasing sequence with $V_k = 0$ if and only if $k \ge \tilde{g}$, we necessarily have $T_{V_0} = \tilde{g}$. Using Lemma 2.9, we that $V_k = 0$ if and only if there is $c \in \{\pm 1\}^{t+1}$ with $c \cdot \rho = 2k - n$. The smallest of value k for which this is true is $k = \frac{1}{2}(n - \sum_{i=0}^{t} \rho_i)$, which is obtained by taking $c = \{-1\}^{t+1}$. Thus $2\tilde{g} = \sum_{i=0}^{t} \rho_i^2 - \rho_i$, as required (see [11, Proposition 3.1]).

Now observe that for $0 \le m < V_0$, we have

$$T_m = \tilde{g} - \min\{k : V_k = m\}.$$

By Lemma 2.9, $V_k = m$ and $0 \le k < \frac{1}{2}n$ implies there is $c \in \text{Char}(\mathbb{Z}^{t+1})$ such that $||c||^2 - t - 1 = 8m$ and $c \cdot \rho = 2k - n$. If we write the coefficients of c in the form $c_i = -(2\alpha_i + 1)$, then $\sum_{i=0}^t \alpha_i(\alpha_i + 1) = 2m$ and

(2-6)
$$2k = n - \sum_{i=0}^{l} \rho_j - 2\alpha \cdot \rho = 2\tilde{g} - 2\alpha \cdot \rho.$$

We see that for any α minimising (2-6), we must have $\alpha \in S_m$, since it must satisfy $\alpha_i \ge 0$ for all *i*. Thus we see that

$$T_m = \max_{\alpha \in S_m} \rho \cdot \alpha$$

for $0 \le m < V_0$. The equation (2-6) also shows that there must exist α satisfying $\sum_{i=0}^{t} \alpha_i(\alpha_i + 1) = 2V_0$ and $\alpha \cdot \rho = \tilde{g}$. This implies the inequality

$$T_{V_0} \leq \max_{\alpha \in S_{V_0}} \rho \cdot \alpha,$$

which completes the proof.

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Remark 2.11 It follows from this lemma that $T_1 = \rho_0$ and $T_2 = \rho_0 + \rho_1$. In particular this implies that $\rho_1 = T_2 - T_1$. This is illustrated in Figure 1.

We now begin the process of showing how the remaining ρ_i can be recovered from the sequence $(V_i)_{i\geq 0}$. We begin with the simplest case, which is when $V_0 \leq 1$.

Lemma 2.12 If $V_0 \le 1$, then $\tilde{g} \le 3$ and ρ takes the form

$$\rho = \begin{cases} (1, 1, \dots, 1) & \text{if } \tilde{g} = 0, \\ (2, 1, \dots, 1) & \text{if } \tilde{g} = 1, \\ (2, 2, 1, \dots, 1) & \text{if } \tilde{g} = 2, \\ (3, 1, \dots, 1) & \text{if } \tilde{g} = 3. \end{cases}$$

Proof If $V_0 = 0$, then $\tilde{g} = 0$ and Lemma 2.10 implies that $\sum_{i=0}^{t} \rho_i^2 - \rho_i = 0$. This shows that we have $\rho_i = 1$ for all $0 \le i \le t$.

Suppose now that $V_0 = 1$. By Lemma 2.10, we have

$$0 < T_1 = \widetilde{g} = \frac{1}{2} \sum_{i=0}^{l} \rho_i^2 - \rho_i \le \max_{\alpha \in S_1} \rho \cdot \alpha.$$

Since S_1 consists of vectors with a single nonzero coordinate, which equals one, we have $\max_{\alpha \in S_1} \rho \cdot \alpha = \rho_0$. Thus we must have $\rho_0^2 - \rho_0 \le 2\rho_0$, and hence $\rho_0 \le 3$. If $\rho_0 = 3$, then we have

$$\tilde{g} = 3 + \frac{1}{2} \sum_{i=1}^{t} \rho_i (\rho_i - 1) \le \rho_0 = 3,$$

which implies that $\rho_i = 1$ for $1 \le i \le t$ and $\tilde{g} = 3$. If $\rho_0 = 2$, then $\tilde{g} \le 2$ implies that $\rho_1 \in \{1, 2\}$, giving the other two possibilities in the statement of the lemma.

From now on we will suppose that $V_0 > 1$. This allows us to define the quantity

$$\mu = \min_{1 \le i < V_0} \{ T_i - T_{i-1} \}.$$

Since $T_1 = \rho_0$ and $T_0 = 0$, we must have $\mu \le \rho_0$.

Lemma 2.13 If $\rho_0 \ge 5$ or $\sum_{\rho_i \text{ even }} \rho_i \ge 6$, then $\mu \le 2$.

Proof For $m < V_0$, Lemma 2.10 shows that there is $\alpha \in S_m$ such that $\rho \cdot \alpha = T_m$. If $\alpha_l > 0$, then consider α' defined by

$$\alpha_i' = \begin{cases} \alpha_i & \text{if } i \neq l, \\ \alpha_i - 1 & \text{if } i = l. \end{cases}$$

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By construction, we have $\alpha' \in S_{m-\alpha_l}$ and $\alpha' \cdot \rho = \alpha \cdot \rho - \rho_l = T_m - \rho_l$. As $\alpha' \cdot \rho \leq T_{m-\alpha_l}$, we get

$$(2-7) \qquad \qquad \rho_l \ge T_m - T_{m-\alpha_l} \ge \alpha_l \mu$$

If we have a maximiser $\alpha \in S_m$ such that $\rho \cdot \alpha = T_m$ and α does not satisfy

(2-8)
$$\alpha_{i} \leq \begin{cases} \frac{1}{2}(\rho_{i}-2) & \text{if } \rho_{i} \text{ is even,} \\ \frac{1}{2}(\rho_{i}-3) & \text{if } \rho_{i} > 3 \text{ is odd,} \\ \frac{1}{2}(\rho_{i}-1) & \text{if } \rho_{i} \in \{1,3\}, \end{cases}$$

for all *i*, then there is *l* such that $\rho_l/\alpha_l < 3$. So, by (2-7), we see that $\mu \le 2$. We will show that if ρ satisfies the hypotheses of the lemma, then such a maximiser must exist.

Let $c \in \text{Char}(\mathbb{Z}^{t+1})$ be such that $c \cdot \rho = n$. By (2-5), we have

$$8V_0 \ge \|c\|^2 - t - 1.$$

On the other hand, the Cauchy-Schwarz inequality implies that

$$|c \cdot \rho|^2 = n^2 \le \|\rho\|^2 \|c\|^2 = n \|c\|^2$$

showing that $||c||^2 \ge n$ with equality if and only if $c = \rho$. Altogether, this yields

$$V_0 \ge \frac{1}{8} (\|\rho\|^2 - t - 1) = \frac{1}{8} \sum_{i=0}^t (\rho_i^2 - 1),$$

with equality if and only if $\rho \in \operatorname{Char}(\mathbb{Z}^{t+1})$. We will let N denote the quantity

$$N = \left\lfloor \frac{1}{8} \sum_{i=0}^{t} (\rho_i^2 - 1) \right\rfloor \le V_0.$$

Now take $\alpha \in S_m$, which satisfies the conditions given by (2-8). It follows that

(2-9)
$$m = \frac{1}{2} \sum_{i=0}^{t} \alpha_i (\alpha_i + 1)$$
$$\leq \sum_{\rho_i > 3 \text{ odd}} \frac{(\rho_i - 3)(\rho_i - 1)}{8} + \sum_{\rho_i \text{ even}} \frac{\rho_i (\rho_i - 2)}{8} + \sum_{\rho_i \in \{1,3\}} \frac{\rho_i^2 - 1}{8}$$
$$= \sum_{i=0}^{t} \frac{\rho_i^2 - 1}{8} + \sum_{\rho_i > 3 \text{ odd}} \frac{1 - \rho_i}{2} + \sum_{\rho_i \text{ even}} \frac{1 - 2\rho_i}{8}.$$

If ρ_0 is odd and $\rho_0 \ge 5$, then (2-9) shows that

$$m \le \sum_{i=0}^{t} \frac{\rho_i^2 - 1}{8} - 2 < N - 1$$

In particular, there is no $\beta \in S_{N-1}$ satisfying (2-8). Since $N-1 < V_0$, there is $\beta \in S_{N-1}$ with $\beta \cdot \rho = T_{N-1}$ and so (2-7) implies that $\mu \le 2$. If $\sum_{\rho_i \text{ even }} \rho_i \ge 6$, then we must have $\sum_{\rho_i \text{ even }} (2\rho_i - 1) \ge \frac{3}{2} \sum_{\rho_i \text{ even }} \rho_i \ge 9$. Therefore, (2-9) shows that

$$m < \sum_{i=0}^{t} \frac{\rho_i^2 - 1}{8} - 1 < N.$$

In particular, there is no $\beta \in S_N$ satisfying (2-7). Since we are assuming there is an even ρ_i , we have $N < V_0$ and so there exists $\beta \in S_N$ such that $\beta \cdot \rho = T_N$ and so (2-7) implies that $\mu \leq 2$.

If $\mu > 2$, then ρ must fall into one of a small number of cases.

Lemma 2.14 If $\mu > 2$ then either $T_1 = 3$ or $T_1 = 4$. If $T_1 = 3$, then ρ takes the form

$$\rho = \begin{cases} (\underbrace{3, \dots, 3}_{d}, 1, \dots, 1) & \text{if } \tilde{g} = 3d, \\ (\underbrace{3, \dots, 3}_{d}, 2, 1, \dots, 1) & \text{if } \tilde{g} = 3d + 1, \\ (\underbrace{3, \dots, 3}_{d}, 2, 2, 1, \dots, 1) & \text{if } \tilde{g} = 3d + 2. \end{cases}$$

If $T_1 = 4$, then ρ must take the form

$$\rho = (4, \underbrace{3, \dots, 3}_{d}, 1, \dots, 1), \text{ where } \tilde{g} = 3d + 6.$$

Proof If $\mu > 2$, then Lemma 2.13 and the observation that $\mu \le T_1 = \rho_0$, we must have $\rho_0 \in \{3, 4\}$. If $\rho_0 = 3$, then Lemma 2.13 implies that we have $\rho_i = 2$ for at most two values *i*. If $\rho_0 = 4$, then Lemma 2.13 implies that ρ_i is odd for all $i \ge 1$. It is then easy to deduce that ρ must take the required form by using the formula $\tilde{g} = \frac{1}{2} \sum_{i=0}^{t} \rho_i^2 - \rho_i$.

Remark 2.15 Although it suffices for our purposes, Lemma 2.14 does not quite tell the full story. If $\rho = (4, 3, ..., 3, 1, ..., 1)$, then one can show that we have $\mu = 1$. This shows that the only cases with $\mu > 2$ are those given in Lemma 2.14 with $\rho_0 = 3$. For these examples we do have $\mu = 3$.

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Now we show that the sequence $(V_i)_{i\geq 0}$ determines ρ when $\mu \leq 2$.

Lemma 2.16 If $\mu \leq 2$, then the vector ρ satisfying (2-5) is unique.

Proof We will show that can calculate the coefficients of ρ iteratively from the values $T_0 < T_1 < \cdots < T_{V_0} = \tilde{g}$. Using the T_i , we will construct a sequence $s^{(0)}$, $s^{(1)}$, \ldots , $s^{(N)}$, which we will show to satisfy

$$s^{(k)} = (\rho_0, \dots, \rho_k, 0, \dots, 0)$$

for each $k \leq N$. The integer N will be large enough that $S^{(N)}$ satisfies

$$\max_{\alpha \in S_t} s^{(N)} \cdot \alpha = T_t$$

for all $t < V_0$. We will show we can deduce ρ_i for any i > N by considering $T_{V_0} = \tilde{g}$. Start by setting

$$s^{(0)} = (T_1, 0, \dots, 0) = (\rho_0, 0, \dots, 0)$$

Now suppose that for $l \ge 0$ we have $s_i^{(l)} = \rho_i$ for all $i \le l$. Suppose there is $t < V_0 - 1$ minimal such that $M = \max_{\alpha \in S_t} s^{(l)} \cdot \alpha < T_t$.

Claim 1 We have $\rho_{l+1} = T_t - T_{t-1}$.

Proof of Claim 1 Let $\alpha \in S_{t-1}$ be such that $s^{(l)} \cdot \alpha = T_{t-1}$. Such an α must also satisfy $\rho \cdot \alpha = T_{t-1}$. In particular, $\alpha_i = 0$ for i > l.

Now we consider $\alpha' \in S_t$ defined by

$$\alpha_i' = \begin{cases} \alpha_i & \text{if } i \neq l+1, \\ 1 & \text{if } i = l+1. \end{cases}$$

We have $\alpha' \cdot \rho = T_{t-1} + \rho_{l+1} \leq T_t$. This implies that

(2-10)
$$\rho_{l+1} \le T_t - T_{t-1}.$$

Let $\beta \in S_t$ be such that $\rho \cdot \beta = T_t$. Since $M < T_t$, we may assume $\beta_{l+1} > 0$. Thus we can define β' by

$$\beta'_i = \begin{cases} \beta_i & \text{if } i \neq l, \\ \beta_i - 1 & \text{if } i = l+1. \end{cases}$$

We have $\beta' \in S_{t-\beta_l}$. Therefore we obtain

(2-11)
$$T_{t-1} \ge T_{t-\beta_l} \ge \rho \cdot \beta' = T_t - \rho_{l+1}.$$

Combining (2-10) and (2-11) gives $\rho_{l+1} = T_t - T_{t-1}$, as claimed.

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Thus if we define $s^{(l+1)}$ by

$$s_i^{(l+1)} = \begin{cases} s_i^{(l)} & \text{if } i \neq l+1, \\ T_t - T_{t-1} & \text{if } i = l+1, \end{cases}$$

we see that $s^{(l+1)}$ satisfies

$$s^{(l+1)} = (\rho_0, \dots, \rho_{l+1}, 0, \dots, 0)$$

and

$$s^{(l+1)} \cdot \alpha' = \max_{\alpha \in S_t} \alpha \cdot s^{(l+1)} = T_t,$$

where $\alpha' \in S_t$ is as defined in the proof of Claim 1

Proceeding in this way, we eventually obtain $s^{(N)}$ such that $T_t = \max_{\alpha \in S_t} \alpha \cdot s^{(N)}$ for all $0 \le t < V_0$ and

$$s^{(N)} = (\rho_0, \dots, \rho_N, 0, \dots, 0).$$

Claim 2 We have $\rho_l \leq \mu \leq 2$ for all l > N.

Proof of Claim 2 Let $\tau < V_0 - 1$ be such that $T_{\tau+1} - T_{\tau} = \mu$. There is $\alpha \in S_{\tau}$ such that $\alpha \cdot \rho = \alpha \cdot s^{(N)} = T_{\tau}$. Such an α must satisfy $\alpha_l = 0$ for l > N. Let $\alpha' \in S_{\tau+1}$ be defined by

$$\alpha'_i = \begin{cases} \alpha_i & \text{if } i \neq l, \\ 1 & \text{if } i = l. \end{cases}$$

We have

$$\rho_l = \alpha' \cdot \rho - T_{\tau} \le T_{\tau+1} - T_{\tau} = \mu \le 2,$$

as required.

It remains to determine how many values of i > N satisfy $\rho_i = 2$. Since we have the formula $T_{V_0} = \frac{1}{2} \sum_{i=0}^{t} \rho_i (\rho_i - 1)$, we see that there are

$$T_{V_0} - \frac{1}{2} \sum_{i=0}^{t} s_i^{(N)} (s_i^{(N)} - 1)$$

values of i > N with $\rho_i = 2$. Since $\rho_i = 1$ for all remaining values of i, this shows that ρ is determined by the T_i .

The proof of Lemma 2.16 combined with Lemmas 2.12 and 2.14 provides an algorithm for calculating ρ . This shows that ρ is the unique vector with $\rho_0 \ge \rho_1 \ge \cdots \ge \rho_t > 0$ and $\|\rho\|^2 = n$ satisfying (2-5). Moreover, if we take *m* to be maximal such that $\rho_m > 1$, then this algorithm calculates the tuple (ρ_0, \ldots, ρ_m) using only the sequence $(V_i)_{i\ge 0}$.

This allows us to deduce Theorem 1.5 and Corollary 1.7 from Theorem 2.7.

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Proof of Theorem 1.5 Theorem 2.7 shows that the intersection form Q_X takes the form of a p/q-changemaker lattice,

$$-Q_X \cong L = \langle w_0, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1}$$

where the sequence $(V_i)_{i\geq 0}$, which is an invariant of K, can be calculated from $w_0 = \sigma_t f_t + \cdots + \rho_1 f_1 + e_0$ by the formula (2-4). Thus, w_0 satisfies (2-5) and using the algorithm provided by Lemma 2.12, Lemma 2.14 and the proof of Lemma 2.16, we see that the tuple $(\sigma_m, \ldots, \sigma_t)$, where m is minimal such that $\sigma_m > 1$, is independent of t and $||w_0||^2 = \lceil p/q \rceil$. By definition, $(\sigma_m, \ldots, \sigma_t)$ are the stable coefficients of L and it follows that they are independent of $b_2(X)$ and p/q.

Proof of Corollary 1.7 This follows combining Theorem 1.5 with Remark 2.6. Theorem 1.5 shows that $-Q_X$ and $-Q_{X'}$ are both p/q-changemaker lattices with the same stable coefficients. Remark 2.6 then shows that $Q_{X'} \cong Q_X \oplus (-\mathbb{Z}^k)$. The isomorphism of intersection forms $Q_X \oplus (-\mathbb{Z}^k) \cong Q_{X\#_k \mathbb{CP}^2}$ is clear. \Box

2.4 *L*-space knots

Now we specialise to the case of *L*-space surgeries. A knot *K* is said to be an *L*-space *knot* if $S_{p/q}^3(K)$ is an *L*-space for some $p/q \in \mathbb{Q}$. The knot Floer homology of an *L*-space knot is known to be determined by its Alexander polynomial, which can be written in the form

$$\Delta_{K}(t) = a_0 \sum_{i=1}^{g} a_i (t^i + t^{-i}),$$

where g = g(K), $a_g = 1$ and the nonzero values of a_i alternate in sign and assume values in $\{\pm 1\}$ [23; 24]. Given an Alexander polynomial in this form, we can compute its *torsion coefficients* by the formula

$$t_i(K) = \sum_{j \ge 1} j a_{|i|+j}.$$

When K is an L-space knot, the V_i appearing in (2-3) satisfy $V_i = t_i(K)$ for $i \ge 0$ [26]. Thus if $S_{p/q}^3(K)$ is an L-space bounding a negative-definite sharp 4-manifold X, then Theorem 1.5 shows that the intersection form is isomorphic to a p/q-changemaker lattice L, where the stable coefficients, $(\sigma_r, \ldots, \sigma_m)$, are determined by the torsion coefficients. Since $t_i(K) = 0$ if and only if $i \ge g(K)$, Lemma 2.10 shows that the genus can be computed by the formula

(2-12)
$$g(K) = \frac{1}{2} \sum_{i=m}^{\prime} \sigma_i (\sigma_i - 1),$$

which was first proven by Greene [11, Proposition 3.1].

Remark 2.17 Lemma 2.10 shows that σ_r and σ_{r-1} have particularly simple interpretations in terms of torsion coefficients:

 $\sigma_r = \#\{0 \le i < g \mid t_i(K) = 1\} \text{ and } \sigma_{r-1} = \#\{0 \le i < g \mid t_i(K) = 2\}.$

As in the proof of Lemma 2.16, the remaining stable coefficients can be also be computed from the torsion coefficients. However, the relationship is more complicated.

3 Graph lattices and obtuse superbases

In this section, we gather together some lattice-theoretic concepts and properties that we will need.

3.1 Graph lattices

We recall the definition of a graph lattice and state the results that we will require for this paper. All statements in this section can be found with proof in [17].

Let G = (V, E) be a finite, connected, undirected graph with no self-loops. For a pair of disjoint subsets $R, S \subset V$, let E(R, S) be the set of edges between R and S. Define e(R, S) = |E(R, S)|. We will use the notation $d(R) = e(R, V \setminus R)$.

Let $\overline{\Lambda}(G)$ be the free abelian group generated by $v \in V$. Define a symmetric bilinear form on $\overline{\Lambda}(G)$ by

$$v \cdot w = \begin{cases} d(v) & \text{if } v = w, \\ -e(v, w) & \text{if } v \neq w. \end{cases}$$

In this section we will use the notation $[R] = \sum_{v \in R} v$, for $R \subseteq V$. The above definition gives

(3-1)
$$v \cdot [R] = \begin{cases} -e(v, R) & \text{if } v \notin R, \\ e(v, V \setminus R) & \text{if } v \in R. \end{cases}$$

From this it follows that $[V] \cdot x = 0$ for all $x \in \overline{\Lambda}(G)$. We define the graph lattice of *G* to be $\overline{\Lambda}(G)$

$$\Lambda(G) := \frac{\Lambda(G)}{\mathbb{Z}[V]}.$$

The bilinear form on $\overline{\Lambda}(G)$ descends to $\Lambda(G)$. Since we have assumed that G is connected, the pairing on $\Lambda(G)$ is positive-definite. This makes $\Lambda(G)$ into an integral lattice. Henceforth, we will abuse notation by using v to denote its image in $\Lambda(G)$.

Recall that a vector z in a lattice is *irreducible* if it cannot be written in the form z = x + y for nonzero x and y with $x \cdot y \ge 0$. The irreducible vectors in $\Lambda(G)$ can be characterised in terms of the graph G.

Lemma 3.1 The vector $x \in \Lambda(G) \setminus \{0\}$ is irreducible if and only if x = [R] for some $R \subseteq V$ such that R and $V \setminus R$ induce connected subgraphs of G.

A connected graph is said to be 2-*connected* if it cannot be disconnected by deleting a vertex. This property is equivalent to $\Lambda(G)$ being *indecomposable*, that is, $\Lambda(G)$ cannot be written as the orthogonal direct sum $\Lambda(G) = L_1 \oplus L_2$ with L_1 and L_2 nonzero sublattices.

Lemma 3.2 The following are equivalent:

- (i) The graph G is 2-connected.
- (ii) Every vertex $v \in V$ is irreducible.
- (iii) The lattice $\Lambda(G)$ is indecomposable.

Given a graph lattice of some graph G, the following lemma will be useful for identifying other graphs with isomorphic graph lattices.

Lemma 3.3 Suppose that *G* is 2–connected. Let *v* be a vertex such that we can find $x, y \in \Lambda(G)$, with v = x + y and $x \cdot y = -1$. Then there is a cut edge *e* in $G \setminus \{v\}$ and, if *R* and *S* are the vertices of the two components of $(G \setminus \{v\}) \setminus \{e\}$, then $\{x, y\} = \{[R] + v, [S] + v\}$. Let u_1 and u_2 be the endpoints of *e*. These are the unique vertices $u_1, u_2 \neq v$, with $x \cdot u_1 = y \cdot u_2 = 1$. Furthermore, any vertex $w \notin \{v, u_1, u_2\}$ satisfies $w \cdot x, w \cdot y \leq 0$.

3.2 Obtuse superbases

Given a positive definite integral lattice L of rank r, we say that L admits an obtuse superbase if it contains a set $B = \{v_0, \ldots, v_r\}$ such that v_1, \ldots, v_r form a basis for L, $v_0 + \cdots + v_r = 0$ and $v_i \cdot v_j \leq 0$ for all $0 \leq i \neq j \leq r$. We will call the set B a an obtuse superbase for L. This terminology is taken from the work of Conway and Sloane [3].

Given an obtuse superbase $B = \{v_0, \ldots, v_r\}$ for L, we can construct a graph G_B by taking vertex set B with $|v_i \cdot v_j|$ edges between vertices v_i and v_j for $i \neq j$. With this construction in mind, we will frequently refer to elements of a given obtuse superbase as vertices of L.

Proposition 3.4 The graph G_B is connected and L is isomorphic to $\Lambda(G_B)$.

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Figure 2: The graphs G_B and $G_{B'}$ corresponding to the obtuse superbases appearing in Lemma 3.5

Proof First we show that G_B is connected. Let $R \subseteq B$ be the vertices of a nonempty connected component of G_B . We see that the vector $[R] = \sum_{x \in R} x$ satisfies $[R] \cdot v_i = 0$ for all $0 \le i \le r$ (see (3-1)). Since *L* is positive-definite, this implies that [R] = 0. By definition, v_1, \ldots, v_r must be linearly independent. It follows that R = B and hence G_B is connected, as required.

To show that $\Lambda(G_B)$ is isomorphic to L, take the linear map which takes vertices to the corresponding vectors in L. Since $v_0 + \cdots + v_r = 0$, we have

$$d(v_k) = -\sum_{i \neq k} v_k \cdot v_i = \|v_k\|^2,$$

and by construction we have $e(v_i, v_j) = -v_i \cdot v_j$ for $i \neq j$. This shows that this map is the required isomorphism.

For any given lattice there may be many choices of obtuse superbase. The following lemma shows one way to convert one obtuse superbase into another.

Lemma 3.5 Let *L* be an indecomposable lattice with an obtuse superbase *B*. Suppose that we have $v \in B$ which can be written as v = x + y, where $x, y \in L$ and $x \cdot y = -1$. There are unique $u_1, u_2 \in B$ with $u_1 \cdot x > 0$ and $u_2 \cdot y > 0$ and the set $B' = (B \setminus \{v, u_1, u_2\}) \cup \{x, y, u_1 + u_2\}$ is also an obtuse superbase for *L*.

Proof Since *L* is indecomposable, Lemma 3.2 shows that the graph G_B is 2connected. Thus we may apply Lemma 3.3, which shows that there are disjoint connected subgraphs G_1 and G_2 of G_B and vertices u_1 and u_2 such that $x = v + u_1 + \sum_{z \in G_1} z$ and $y = v + u_2 + \sum_{z \in G_2}$, with a unique edge between u_1 and u_2 which is a cut-edge in $G_B \setminus \{v\}$. It is straightforward to verify that $B' = (B \setminus \{v, u_1, u_2\}) \cup \{x, y, u_1 + u_2\}$ is an obtuse superbase for *L*. An illustration of how the graph $G_{B'}$ is obtained from G_B is given in Figure 2.

4 Alternating surgeries

In this section, we will prove our main results.

4.1 The Goeritz form

A diagram *D* of a link *L* divides the plane into connected regions. We may colour these regions black and white in a chessboard fashion. This colouring can be done in two different ways. Each of the possible colourings gives an incidence number, $\mu(c) \in \{\pm 1\}$, at each crossing *c* of *D*, as shown in Figure 3. We construct a planar graph, Γ_D , by drawing a vertex in each white region and an edge *e* for every crossing *c* between the two white regions it joins. We define an incidence number on each edge by $\mu(e) = \mu(c)$. We call this the *white graph* corresponding to *D*. This gives rise to a *Goeritz matrix*, $G_D = (G_{ij})$, defined by labelling the vertices of Γ_D by v_1, \ldots, v_{r+1} and, for $1 \le i, j \le r$, setting

$$g_{ij} = \sum_{e \in E(v_i, v_j)} \mu(e)$$

for $i \neq j$ and

$$g_{ii} = -\sum_{e \in E(v_i, \Gamma_D \setminus v_i)} \mu(e)$$

otherwise [13, Chapter 9].

Now suppose that L is an alternating, nonsplit link. If D is any alternating diagram, then we may fix the colouring so that $\mu(c) = -1$ for all crossings. In this case, G_D defines a positive-definite bilinear form. This in turn gives a lattice, Λ_D , which we will refer to as the *white lattice* of D. Observe that if D is reduced (ie contains no nugatory crossings), then Γ_D contains no self-loops or cut-edges and Λ_D is isomorphic to the graph lattice $\Lambda(\Gamma_D)$.

Ozsváth and Szabó have shown that the Heegaard Floer homology d-invariants of the branched double cover $\Sigma(L)$ are determined by Λ_D [25].



Figure 3: The incidence number of a crossing

Theorem 4.1 [25] Let *L* be a nonsplit alternating link with a reduced alternating diagram *D*. The double branched cover $\Sigma(L)$ is an *L*-space which bounds a simply connected negative-definite sharp 4–manifold with intersection form isomorphic to $-\Lambda_D$.

4.2 Changemaker lattices admitting obtuse superbases

We will establish some restrictions on changemaker lattice which admits an obtuse superbase. The following proposition, which combines results from [17; 16], will allow us to restrict our attention to integer changemaker lattices.

Proposition 4.2 Suppose that for some p/q = n - r/q with $q > r \ge 1$, the changemaker lattice

$$L_{p/q} = \langle w_0, \ldots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{t+s+1},$$

where $w_0 = e_0 + \sigma_1 f_1 + \dots + \sigma_t f_t$, admits an obtuse superbase. Then the changemaker lattices

$$L_n = \langle w_0 \rangle^{\perp} \subseteq \mathbb{Z}^{t+1} = \langle e_0, f_1, \dots, f_t \rangle,$$
$$L_{n-1} = \langle w_0 - e_0 \rangle^{\perp} \subseteq \mathbb{Z}^t = \langle f_1, \dots, f_t \rangle,$$

both admit obtuse superbases. Furthermore, if $\sigma_t > 1$, then we can assume the obtuse superbase for L_{n-1} contains a vector x with $x \cdot f_1 = -2$.

Proof Since $L_{p/q}$ admits an obtuse superbase, it follows from [16, Proposition 7.7] that the lattice

$$L_{n-1/2} = \langle w_0, e_1 - e_0 \rangle^{\perp} \subseteq \mathbb{Z}^{t+2} = \langle e_1, e_0, f_1, \dots, f_t \rangle$$

also admits an obtuse superbase, which we will call *B*. The results of [17] show that there are precisely two vertices v and w in *B* with $v \cdot e_0$, $w \cdot e_0 \neq 0$ and they satisfy $v \cdot w \leq -1$. Moreover, the results of the same paper show that we can assume that $v = -f_1 + e_0 + e_1$ and $w \cdot e_0 = w \cdot e_1 = -1$, and if there is k such that $\sigma_k > 1$, then we can assume that $w \cdot f_1 = -1$.

Consider the set $B' = B \setminus \{v, w\} \cup \{v + w\}$. Since $(v + w) \cdot e_0 = (v + w) \cdot e_1 = 0$, we have $B' \subset L_{n-1}$. Since B spans $L_{n-1/2}$, we see that B' must span L_{n-1} . Since B is an obtuse superbase for $L_{n-1/2}$, it follows that B' is an obtuse superbase for $L_{n-1/2}$, where the graph $G_{B'}$ is obtained from G_B by contracting the edge between v and w. Furthermore, if there is $\sigma_k > 1$, then x = v + w is the required vector with $x \cdot f_1 = -2$.

Now consider the set $B'' = B \setminus \{v, w\} \cup \{v - e_1, w + e_1\}$. Since every element $x \in B \setminus \{v, w\}$ has $x \cdot e_1 = 0$, we see that every $x \in B''$ satisfies $x \cdot e_1 = 0$, so we

have $B'' \subseteq \langle e_0, f_1, \ldots, f_t \rangle$ and hence $B'' \subseteq L_{n+1}$. Since *B* is an obtuse superbase for $L_{n-1/2}$ and $v \cdot w \leq -1$, it follows that B'' is an obtuse superbase for L_{n+1} , where the graph $G_{B''}$ is obtained from G_B by deleting an edge between v and w. \Box

The next lemma gives bounds on when a changemaker lattice can be decomposable.

Lemma 4.3 [9, Lemma 5.1] Suppose that $L = \langle w_0 \rangle^{\perp} \subseteq \mathbb{Z}^t$ is a changemaker lattice, where $w_0 = \sigma_1 f_1 + \dots + \sigma_t f_t$ with $\sigma_i \ge 1$ for all *i* and $\sigma_t > 1$. Let $m \le t$ be minimal such that $\sigma_m > 1$. If *L* is decomposable, then $\sigma_m = m - 1$.

We get a similar bound on a changemaker lattice admitting an obtuse superbase in terms of its stable coefficients. This will allow us to prove the upper bound in Theorem 1.2.

Lemma 4.4 Suppose that $L = \langle w_0 \rangle^{\perp} \subseteq \mathbb{Z}^t$ is a changemaker lattice, where $w_0 = \sigma_1 f_1 + \cdots + \sigma_t f_t$ with $\sigma_i \ge 1$ for all *i*. If the stable coefficients $(\sigma_m, \ldots, \sigma_t)$ are a nonempty tuple and *L* admits an obtuse superbase, then $\sigma_m \ge m - 2$ and

$$||w_0||^2 \le 1 + \sigma_m + \sum_{i=m}^t \sigma_i^2.$$

Proof If L is decomposable, then Lemma 4.3 shows that the bound is automatically satisfied. We will assume from now on that L is indecomposable.

For $2 \le i \le m-1$, let v_i be the vector $v_i = e_i - e_{i-1}$. Since $\sigma_i = \sigma_{i-1} = 1$ for *i* in this range, we have $v_i \in L$. We will use Lemma 3.5 to show that *L* admits an obtuse superbase containing the vectors v_2, \ldots, v_{m-1} .

Let *B* be an obtuse superbase and let $k \le m-1$, be minimal such that v_k is not in *B*. Suppose first that k = 2. Since v_2 is irreducible, Lemma 3.1 implies that it can be written as a sum of elements of *B*. Hence, there is a vector $u \in B$ with $u \cdot v_2 > 0$. By Lemma 3.2, the indecomposability of *L* implies that *u* is irreducible. In turn, this implies that $(u - v_2) \cdot v_2 = u \cdot v_2 - 2 = -1$. Therefore by applying Lemma 3.5, we see that there is an obtuse superbase containing v_2 .

Now we suppose that k > 2. Since v_k is irreducible, Lemma 3.1 shows that it can be written as a sum of elements of B. Since v_{k-1} is a vertex of B and $v_k \cdot v_{k-1} = -1$, there is $u \in B$ with $u \cdot v_k = -u \cdot v_{k-1} = 1$. This must satisfy $(u - v_k) \cdot v_k = -1$. By Lemma 3.5, this implies we can find an obtuse superbase containing v_k . Moreover, since $(u - v_k) \cdot v_j \le 0$ and $v_k \cdot v_j \le 0$ for all $2 \le j < k$, we can assume that v_2, \ldots, v_{k-1} are also in this obtuse superbase. Thus, proceeding inductively, we see that we can assume that v_2, \ldots, v_{m-1} are all contained in the obtuse superbase B.

Suppose that $\sigma_m = m - b$ for some $m - 2 \ge b \ge 2$. Consider the vector $v_m = -e_m + e_{m-1} + \cdots + e_b \in L$. Since this is irreducible, Lemma 3.1 shows that we may write it as a sum of vertices $v_m = \sum_{x \in R} x$ for some subset $R \subseteq B$. Since $v_m \cdot v_b = -1$, we have $v_b \notin R$ and there must exist $u \in R$ with $u \cdot v_b = -1$ and $u \cdot v_m = 1$. However, as $||v_b||^2 = 2$, there are at most two vectors in B which pair nontrivially with v_b . If $b \ge 3$ then we have $v_{b-1} \cdot v_b = v_{b+1} \cdot v_b = -1$ and $v_{b-1} \cdot v_m = v_{b+1} \cdot v_m = 0$. This implies that the required $u \in B$ cannot exist if $b \ge 3$. Thus we must have b = 2. This shows that $\sigma_m \ge m-2$, as required. Since $\sigma_i = 1$ for i < m, we have

$$||w_0||^2 = m - 1 + \sum_{i=m}^t \sigma_i^2 \le 1 + \sigma_m + \sum_{i=m}^t \sigma_i^2,$$

which is the required bound. This completes the proof.

This allows us to prove the inequality which will give Theorem 1.1.

Lemma 4.5 Suppose that $L = \langle \sigma_1 f_1 + \dots + \sigma_t f_t \rangle^{\perp} \subseteq \mathbb{Z}^t$ is a changemaker lattice which admits an obtuse superbase and $\sigma_t > 1$. Then

$$\sum_{i=1}^{t} \sigma_i^2 \le 2 \sum_{i=1}^{t} \sigma_i (\sigma_i - 1) + 3.$$

Proof Let *m* be minimal such that $\sigma_m > 1$. Since *L* admits an obtuse superbase, Lemma 4.4 shows that we have

$$\sum_{i=1}^{t} \sigma_i^2 \le \sum_{i=m}^{t} \sigma_i^2 + \sigma_m + 1.$$

Observe that if $\sigma_i \ge 2$, then $\sigma_i^2 \le 2\sigma_i(\sigma_i - 1)$. Since $\sigma_m \ge 2$, we also have $\sigma_m^2 + \sigma_m \le 2\sigma_m(\sigma_m - 1) + 2$. Combining these inequalities, we obtain

$$\sum_{i=1}^{t} \sigma_i^2 \le \sum_{i=m}^{t} \sigma_i^2 + \sigma_m + 1 \le 2 \sum_{i=m}^{t} \sigma_i (\sigma_i - 1) + 3 = 2 \sum_{i=1}^{t} \sigma_i (\sigma_i - 1) + 3,$$

which is the required inequality.

4.3 The main results

Suppose that *K* is an nontrivial knot such that $S_{p/q}^3(K)$ is an alternating surgery, that is, $S_{p/q}^3(K) = \Sigma(L)$ for an alternating knot or link *L*. Since a nontrivial *L*-space knot cannot admit both positive and negative *L*-space surgeries and

$$-S_r^3(K) = S_{-r}^3(\overline{K}) = \Sigma(\overline{L}),$$

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we may assume that p/q > 0 and that all other alternating surgeries on K arise from positive slopes.

Let D be a reduced alternating diagram of L. By Theorems 1.5 and 4.1, the lattice Λ_D is isomorphic to a p/q-changemaker lattice,

$$\Lambda_{p/q} = \langle w_0, \dots, w_l \rangle^{\perp} \subseteq \mathbb{Z}^{\operatorname{rk} \Lambda_D + l + 1},$$

whose stable coefficients are determined by the Alexander polynomial of K.

Since Λ_D is the graph lattice associated to the white graph of D, the lattice $\Lambda_{p/q}$ admits an obtuse superbase. We write w_0 in the form

$$w_0 = \begin{cases} e_0 + \sigma_1 f_1 + \dots + \sigma_t f_t & \text{if } q > 1, \\ \sigma_1 f_1 + \dots + \sigma_t f_t & \text{if } q = 1. \end{cases}$$

Since *D* is reduced, Γ_D contains no cut-edges. This implies that Λ_D contains no vectors of norm 1 and so $\sigma_i \ge 1$ for all *i*. As we are assuming that g(K) > 0, (2-12) implies that $\sigma_t > 1$. So the stable coefficients form a nonempty tuple, $(\sigma_m, \ldots, \sigma_t)$. This allows us to define

$$N = \sigma_m + \sum_{i=m}^{l} \sigma_i^2,$$

which will be the integer appearing in the statement of Theorem 1.2.

Proof of Theorems 1.1 and 1.2 Proposition 4.2 implies that the $\lceil p/q \rceil$ -changemaker lattice

$$\Lambda' = \langle w_0 \rangle^{\perp} \subseteq \begin{cases} \mathbb{Z}^{t+1} & \text{if } q > 1, \\ \mathbb{Z}^t & \text{if } q = 1, \end{cases}$$

also admits an obtuse superbase. As shown by (2-12), we have

$$2g(K) = \sum_{i=1}^{t} \sigma_i (\sigma_i - 1).$$

Therefore, Lemma 4.5 gives the bound

$$\left\lceil \frac{p}{q} \right\rceil = \|w_0\|^2 \le 4g(K) + 3.$$

This proves Theorem 1.1. From Lemma 4.4, we get the upper bound

$$\frac{p}{q} \le ||w_0||^2 \le 1 + \sigma_m + \sum_{i=m}^t \sigma_i^2 = N + 1.$$

Since $(\sigma_1, \ldots, \sigma_t)$ satisfies the changemaker condition, we must have

$$\sigma_m \le 1 + \sum_{i=1}^{m-1} \sigma_i = 1 + \sum_{i=1}^{m-1} \sigma_i^2,$$

where the second inequality holds since $\sigma_i = 1$ for $1 \le i < m$. Thus we obtain

$$\frac{p}{q} \ge \sum_{i=1}^{t} \sigma_i^2 \ge \sum_{i=m}^{t} \sigma_i^2 + \sigma_m - 1 = N - 1.$$

This completes the proof of Theorem 1.2.

The lower bound N-1 appearing in this proof arises from the fact that there can be no r-changemaker lattice for any r < N-1 with stable coefficients $(\sigma_m, \ldots, \sigma_t)$. Thus it follows from Theorem 1.5 that if $S_r^3(K)$ bounds a negative-definite sharp manifold for r > 0, then $r \ge N-1$. This justifies the claim made in Remark 1.6.

Now it remains to prove Theorem 1.3.

Proof of Theorem 1.3 Assume that $S_r^3(K)$ is an alternating surgery for $r \in \{r_1, N, r_2\}$ with $N - 1 \le r_1 < N < r_2 < N + 1$. Let $S_{r_i}^3(K) = \Sigma(L_i)$ for i = 1, 2 and $S_N^3(K) = \Sigma(L)$ for L and L_i alternating. For i = 1, 2, let D_i be a reduced alternating diagram for L_i and let D be a reduced alternating diagram for L. Theorem 1.5 shows that there is $w_0 = \sigma_t f_t + \dots + \sigma_2 f_2$ such that Λ_{D_1} is isomorphic to the r_1 -changemaker lattice

$$\Lambda_{r_1} = \langle w_0 + e_0, w_1, \dots, w_{l_1} \rangle^{\perp} \subseteq \langle f_2, \cdots, f_t, e_0, \dots, e_{s_1} \rangle,$$

 Λ_{D_2} is isomorphic to the r_2 -changemaker lattice

$$\Lambda_{r_2} = \langle w_0 + f_1 + e_0, w_1, \dots, w_{l_2} \rangle^{\perp} \subseteq \langle f_1, f_2, \cdots, f_t, e_0, \dots, e_{s_2} \rangle,$$

and Λ_D is isomorphic the N-changemaker lattice

$$\Lambda_N = \langle w_0 \rangle^{\perp} \subseteq \langle f_1, \dots, f_t \rangle.$$

Since Λ_{r_2} admits an obtuse superbase, Proposition 4.2 implies that Λ_N admits an obtuse superbase containing a vertex v with $v \cdot f_1 = -2$. Since Λ_{r_1} is a changemaker lattice, $(\sigma_2, \ldots, \sigma_t)$ must satisfy the changemaker condition. Therefore, if g > 1 is minimal such that $v \cdot f_g \ge 0$, then Proposition 2.2 implies that there is $A \subseteq \{2, \ldots, g-1\}$ with $\sigma_g - 1 = \sum_{i \in A} \sigma_i$. If we set $z = f_g - f_1 - \sum_{i \in A} f_i$, we have $z \in \Lambda_N$ and we

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can compute

$$\begin{aligned} (v-z)\cdot z &= v\cdot f_g - 1 + -(v\cdot f_1 + 1) - \sum_{i\in A} (v\cdot f_i + 1) \\ &\geq v\cdot f_g - v\cdot f_1 - 2 = v\cdot f_g \geq 0. \end{aligned}$$

Since $z \neq v$, this shows that v is reducible. Thus Lemma 3.2 implies that Λ_N is decomposable and that if Λ_N is isomorphic to a graph lattice $\Lambda(G)$ for any connected graph G, then G contains a cut vertex. This shows that the white graph Γ_D contains a cut vertex. Since, we have assumed that D is reduced, this implies that $L = L_1 \# L_2$ for nontrivial L_1 and L_2 . Therefore $S_N^3(K) = \Sigma(L_1) \# \Sigma(L_2)$ is reducible. Using work of Hoffman [12], Matignon and Sayari [14] showed that if $S_N^3(K)$ is a reducible surgery, then either $N \leq 2g(K) - 1$ or K is a cable knot. Since we have

$$N > 2g(K) = \sum_{i=1}^{t} \sigma_i (\sigma_i - 1),$$

it follows that K is cable knot. This completes the proof of Theorem 1.3.

5 Examples and questions

We give some examples relating to alternating surgeries and sharp 4-manifolds to illustrate the results of this paper. We then conclude the paper by discussing some questions that arise naturally from this work.

5.1 Alternating surgeries via the Montesinos trick

We will now describe a construction for building knots admitting alternating surgeries. As far as the author is aware, this construction accounts for all known examples of alternating surgeries.

An *almost-alternating diagram* D is one which can be obtained by a crossing change from an alternating diagram. We call a crossing which can be changed to obtain an alternating diagram a *dealternating crossing*. Now let D be an almost-alternating diagram of the unknot with a dealternating crossing c and let B be a small ball containing c. Since the double cover of S^3 branched over the unknot is S^3 , the ball Blifts to a solid torus $T \subseteq S^3$ when we take the double cover of S^3 branched over D. Let $K \subseteq S^3$ be the knot given by the core of T. If D' is obtained from D by replacing c with some other rational tangle, then the Montesinos trick shows that $\Sigma(D')$ is obtained by surgery on K [18]. Since we may perform tangle replacements such that the resulting diagram is alternating, we see that K admits alternating surgeries. If we take D' to be the alternating diagram obtained by changing c, then the resulting surgery is half-integral:

$$S_{n+1/2}^3(K) = \Sigma(D')$$

for some $n \in \mathbb{Z}$. By reflecting D, if necessary, we may assume that n is positive. It can be shown (eg [16, Proposition 5.4]) there are tangle replacements showing that $S_r^3(K)$ is an alternating surgery for all r in the range $n \le r \le n + 1$.

Remark 5.1 It follows from the work of Watson that for all $r \ge n$, the manifold $S_r^3(K)$ is the double branched cover of a quasi-alternating link L [28]. However, Theorem 1.2 shows that when K is nontrivial L can only be alternating for $r \le n+2$. Thus we see that almost-alternating diagrams of the unknot gives rise to infinite families of nonalternating quasi-alternating knots and links.

Remark 5.2 It follows from Theorem 1.3 that if K is not a cable knot or the unknot, then K can admit at most one other alternating surgery with r = n + 2 or r = n - 1. If one uses the generalisation of Theorem 1.3 asserted in Remark 1.4, then we see that actually neither of these possibilities can arise and that $S_r^3(K)$ is an alternating surgery if and only if $n \le r \le n + 1$.

As an example, we see what the results of this paper say about alternating surgeries on the (-2, 3, 7)-pretzel knot and describe how they arise through the construction given in this section.

Example 5.3 Let K denote the (-2, 3, 7)-pretzel knot. It is well known that K admits two lens space surgeries [5]. This implies that K is an L-space knot and in particular that it has alternating surgeries. The Alexander polynomial is

$$\Delta_K(t) = t^5 + t^{-5} - (t^4 + t^{-4}) + t^2 + t^{-2} - (t^1 + t^{-1}) + 1.$$

The corresponding nonzero torsion coefficients are $t_0 = t_1 = 2$ and $t_2 = t_3 = t_4 = 1$. From Lemma 2.13 we can deduce that the stable coefficients of the corresponding changemaker vector are (2, 2, 3). If we apply Theorem 1.2 to K, then integer N we obtain is $N = 3^2 + 2^2 + 2^2 + 2 = 19$. Therefore, if $S_r^3(K)$ is an alternating surgery, then $18 \le r \le 20$.

Since the changemaker lattice

$$L = \langle 3f_6 + 2f_5 + 2f_4 + f_3 + f_2 + f_1 \rangle^{\perp}$$

does not admit an obtuse superbase, we see that $S_r^3(K)$ cannot be an alternating surgery for $19 < r \le 20$.



Figure 4: A diagram of 8_{17} with its unknotting crossing circled. For each r in the range $18 \le r \le 19$, r-surgery on the (-2, 3, 7)-pretzel knot yields the branched double cover of an alternating knot or link obtained by replacing the unknotting crossing in 8_{17} by some rational tangle. Note that both resolutions of the unknotting crossing give a 2-bridge knot or link. The two resolutions correspond to the cases r = 18 and 19.

In fact, K arises through the construction given in Section 5.1, and for each r in $18 \le r \le 19$, $S_r^3(K)$ branches over an alternating knot or link obtained by tangle replacement on the knot 8_{17} , as shown in Figure 4.

5.2 Some knots with no alternating surgeries

We use the results of this paper to exhibit two examples of L-space knots which do not admit any alternating surgeries. Although both are cables of the trefoil, they do not admit alternating surgeries for different reasons: in one case, the cabling slope is "too large" and in the other it is "too small".

Example 5.4 Let K be the (2, 15)-cable of $T_{2,3}$. Since

$$S_{30}^3(K) = S_{15/2}^3(T_{3,2}) \# L(2,1)$$

is an L-space, K is an L-space knot. We will show that this does not admit any alternating surgeries. The Alexander polynomial of K is given by

$$\Delta_K(t) = t^9 + t^{-9} - (t^8 + t^{-8}) + t^5 + t^{-5} - (t^4 + t^{-4}) + t^3 + t^{-3} - (t^2 + t^{-2}) + t + t^{-1} - 1.$$

By the observations of Remark 2.17 and (2-12), we see that the stable coefficients given by K must be (2, 2, 2, 4). Thus the quantity N in Theorem 1.2 is given by N = 30. Combining this with Proposition 4.2, we see that to verify that K has no alternating surgeries we need only check that none of the three changemaker lattices

$$L_{29} = \langle 4e_0 + 2e_1 + 2e_2 + 2e_3 + e_4 \rangle^{\perp},$$

$$L_{30} = \langle 4e_0 + 2e_1 + 2e_2 + 2e_3 + e_4 + e_5 \rangle^{\perp},$$

$$L_{31} = \langle 4e_0 + 2e_1 + 2e_2 + 2e_3 + e_4 + e_5 + e_6 \rangle^{\perp},$$

admit obtuse superbases. Since this can be verified relatively easily, for example by using that in each case there are only a small number of irreducible vectors v with $v \cdot e_0 \neq 0$, we see that K does not admit any alternating surgeries.

Example 5.5 Let K be the (2, 3)-cable of $T_{2,3}$. We will show that this is an L-space knot not admitting any alternating surgeries. The Alexander polynomial of K is

$$\Delta_K(t) = t^3 - t^2 + 1 - t^{-2} + t^{-3}.$$

Observe that this is the same as the Alexander polynomial for the torus knot $T_{3,4}$. If $S_r^3(K) = \Sigma(L)$ were an alternating surgery, then for any reduced alternating diagram D of L, the white lattice Λ_D would be isomorphic to an r-changemaker lattice with stable coefficients the tuple (3). It follows that we must have $11 \le r \le 13$. Since $S_r^3(T_{4,3})$ is an alternating surgery for any r in this range, we must have $\Lambda_D \cong \Lambda_{D'}$, where D' and is any reduced alternating diagram for an alternating knot or link L' such that $\Sigma(L') = S_r^3(T_{4,3})$. Since L and L' are alternating, this isomorphism of white lattices implies that L and L' must be mutants of one another and that $\Sigma(L) = \Sigma(L') = S_r^3(T_{4,3})$ [8]. Surgery on a torus knot is always a small Seifert fibred space [19], but $S_r^3(K)$ is a small Seifert fibred space only if r takes the form $r = 6 \pm 1/q$ [7]. Thus K admits no alternating surgeries.

5.3 Surgeries bounding sharp 4-manifold

It seems natural to wonder what we can say about the set of positive surgery slopes for which a given knot bounds a negative-definite sharp manifold. It can be shown that if it is nonempty then this set is an unbounded interval.

Theorem 5.6 [15, Theorem 1.2] Let K be a knot in S^3 . If $S^3_{p/q}(K)$ bounds a sharp negative-definite 4-manifold for some p/q > 0, then $S^3_{p'/q'}(K)$ bounds a sharp negative-definite 4-manifold for all $p'/q' \ge p/q$.

This allows us to characterise the set of all such slopes for torus knots admitting positive L-space surgeries.

Proposition 5.7 For r, s > 1 and p/q > 0, the manifold $S^3_{p/q}(T_{r,s})$ bounds a negativedefinite sharp 4-manifold if and only if $p/q \ge rs - 1$.

Proof Since $S_{rs-1}^3(T_{r,s})$ is a lens space [19], Theorem 5.6 shows that $S_{p/q}^3(T_{r,s})$ bounds a negative-definite sharp 4-manifold for any $p/q \ge rs - 1$. To obtain the converse, observe that $S_{rs+1}^3(T_{r,s})$ is also a lens space and hence also an alternating surgery. Thus, for $K = T_{r,s}$, we see that the integer N in Theorem 1.2 is N = rs. Thus Remark 1.6 gives the desired lower bound.

There are also examples of L-space knots for which no such slopes exist.

Example 5.8 Let *K* be the (2, 5)–cable of $T_{2,3}$. We will show that *K* is an *L*–space knot such that $S_r^3(K)$ cannot bound a sharp negative-definite 4–manifold for any r > 0. Since $S_{10}^3(K) = S_{5/2}^3(T_{3,2}) \# L(2, 1)$ is an *L*–space, *K* is an *L*–space knot. To show that $S_r^3(K)$ cannot bound a sharp 4–manifold, we show there is no vector satisfying (2-4). The Alexander polynomial of *K* is

$$\Delta_K(t) = t^4 - t^3 + 1 - t^{-3} + t^{-4},$$

which has nonzero torsion coefficients $t_0(K) = t_1(K) = t_2(K) = t_3(K) = 1$. Thus, by Remark 2.17, we can assume that the first coordinate of any vector satisfying (2-4) is $\sigma_0 = 4$. However this contradicts (2-12), which implies that we must have $\sigma_0(\sigma_0 - 1) \le 2g(K) = 8$.

5.4 Further questions

Given the results of this paper, it is natural to wonder how the set of knots admitting alternating surgeries are contained within the set of all *L*-space knots. For the purposes of this discussion we define several classes of *L*-space knots. We will restrict our attention to those admitting positive *L*-space surgeries. We say that $S_r^3(K)$ is a *quasi-alternating surgery* if it is the double branched cover of a quasi-alternating knot or link.

 $\mathcal{L} = \{K : S_r^3(K) \text{ is an } L\text{-space for some } r > 0\},\$ $\mathcal{A} = \{K : S_r^3(K) \text{ is an alternating surgery for some } r > 0\},\$ $\mathcal{D} = \{K : K \text{ is the double branched cover of an unknotting arc in an } K \in \mathbb{C}\}$

alternating diagram},

 $QA = \{K : S_r^3(K) \text{ is a quasi-alternating surgery for some } r > 0\}.$

Since the double branched cover of a quasi-alternating knot is an L-space and any alternating link is quasi-alternating, these sets satisfy the inclusions

$$\mathcal{D} \subseteq \mathcal{A} \subseteq \mathcal{Q} \mathcal{A} \subseteq \mathcal{L}.$$

Watson has shown that any sufficiently large cable of a torus knot is in QA [28]. In particular, the (2, 15)–cable of T(2, 3) is in QA. As we have shown that it is not in A, this shows that $A \subsetneq QA$.

Remark 5.9 It seems probable that there are *L*-space knots which do not admit quasi-alternating surgeries. The (2,3)-cable of $T_{2,3}$ and the (2,5)-cable of $T_{2,3}$ seem to be potential candidates for knots in $\mathcal{L} \setminus \mathcal{QA}$.

As far as the author is aware, all known examples of knots in \mathcal{A} are also in \mathcal{D} , ie they arise through the construction in Section 5.1. Moreover, it is known that for every noninteger alternating surgeries, there is a knot in \mathcal{D} with the same surgery.

Theorem 5.10 [16, Theorem 1.2] If $S^3_{p/q}(K)$ is an alternating surgery with q > 1, then there is $K' \in \mathcal{D}$ with $S^3_{p/q}(K) = S^3_{p/q}(K')$.

This suggests the following conjecture.

Conjecture 1 Every alternating surgery arises as tangle replacement on an almostalternating diagram of the unknot, that is, we have A = D.

Since lens spaces arise as the double branched covers of alternating links, one can ask how this conjecture agrees with results and conjectures on lens space surgeries. The cyclic surgery theorem of Culler, Gordon, Luecke and Shalen shows that only torus knots admit noninteger lens space surgeries [4]. Since torus knots are in \mathcal{D} , this verifies Conjecture 1 in certain cases.

Short of attacking Conjecture 1 in full, there are various related questions we can ask.

Question 2 Does Theorem 5.10 extend to the case of integer alternating surgeries?

It follows from their construction that every knot in \mathcal{D} admits a strong inversion.

Question 3 Is every knot in A strongly invertible?

It seems likely that any progress on Conjecture 1 would require an alternative description of the class \mathcal{D} .

Question 4 Is there a characterisation of \mathcal{D} which does not refer to almost-alternating diagrams of the unknot?

Finally, as we demonstrated with the (2, 5)-cable of $T_{2,3}$, (2-4) can be used to show that for some knots no manifold obtained by positive surgery can bound a negative-definite sharp manifold. As we saw in Example 5.5, the (2, 3)-cable of $T_{2,3}$ passes this obstruction as it has the same Alexander polynomial as $T_{3,4}$. However, it seems unlikely that any positive surgery on the (2, 3)-cable of $T_{2,3}$ bounds a sharp manifold.

Question 5 Can one find alternative ways to show that surgery on a knot does not bound a sharp 4-manifold? In particular, is it possible to show that no positive surgery on the (2, 3)-cable of $T_{2,3}$ bounds a sharp manifold?

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