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We study the relationship between L^∞ growth of eigenfunctions and their L^2 concentration as measured by defect measures. In particular, we show that scarring in the sense of concentration of defect measure on certain submanifolds is incompatible with maximal L^∞ growth. In addition, we show that a defect measure which is too diffuse, such as the Liouville measure, is also incompatible with maximal eigenfunction growth.

1. Introduction

Let (M, g) be a C^∞ compact manifold of dimension n without boundary. Consider the eigenfunctions

$$(-\Delta_g - \lambda_j^2)u_{\lambda_j} = 0, \quad \|u_{\lambda_j}\|_{L^2} = 1 \quad (1-1)$$

as $\lambda_j \rightarrow \infty$. It is well known [Avakumović 1956; Levitan 1952; Hörmander 1968], see also [Zworski 2012, Chapter 7], that solutions to (1-1) satisfy

$$\|u_{\lambda_j}\|_{L^\infty(M)} \leq C\lambda_j^{(n-1)/2} \quad (1-2)$$

and that this bound is saturated, e.g., on the sphere. It is natural to consider the situations which produce sharp examples for (1-2). In many cases, one expects polynomial improvements to (1-2), but rigorous results along these lines are few and far between [Iwaniec and Sarnak 1995]. In the case of negatively curved manifolds, log improvements can be obtained [Bérard 1977]. However, at present, under general dynamical assumptions, known results involve o -improvements to (1-2) [Toth and Zelditch 2002; Sogge et al. 2011; Sogge and Zelditch 2002; 2003; 2016a; 2016b]. These papers all study the connections between the growth of L^∞ norms of eigenfunctions and the global geometry of the manifold (M, g) . In this note, we examine the relationship between L^∞ growth and L^2 concentration of eigenfunctions. We measure L^2 concentration using the concept of a *defect measure* — a sequence $\{u_{\lambda_j}\}$ has defect measure μ if for any $a \in S_{\text{hom}}^0(T^*M \setminus \{0\})$,

$$\langle a(x, D)u_{\lambda_j}, u_{\lambda_j} \rangle \rightarrow \int_{S^*M} a(x, \xi) d\mu. \quad (1-3)$$

By an elementary compactness/diagonalization argument, it follows that any sequence of eigenfunctions u_{λ_j} solving (1-1) possesses a further subsequence that has a defect measure in the sense of (1-3) [Zworski 2012, Chapter 5; Gérard 1991]. Moreover, a standard commutator argument shows that if $\{u_{\lambda_j}\}$ is any

sequence of L^2 -normalized Laplace eigenfunctions, the associated defect measure μ is invariant under the geodesic flow; that is, if $G_t : S^*M \rightarrow S^*M$ is the geodesic flow, i.e., the Hamiltonian flow of $p = \frac{1}{2}|\xi|_g^2$, $(G_t)_*\mu = \mu$ for all $t \in \mathbb{R}$.

Definition 1.1. We say that an eigenfunction subsequence is *strongly scarring* provided that for any defect measure μ associated to the sequence, $\text{supp } \mu$ is a finite union of periodic geodesics.

Theorem 1. Let $\{u_{\lambda_j}\}$ be a strongly scarring sequence of solutions to (1-1). Then

$$\|u_{\lambda_j}\|_{L^\infty} = o(\lambda_j^{(n-1)/2}).$$

We also have improved L^∞ bounds when eigenfunctions are *quantum ergodic*, that is, their defect measure is the Liouville measure on S^*M , μ_L ; see, e.g., [Shnirelman 1974; Colin de Verdière 1985; Zelditch 1987] for the standard quantum ergodicity theorem.

Theorem 2. Let $\{u_{\lambda_j}\}$ be a quantum ergodic sequence of solutions to (1-1). Then

$$\|u_{\lambda_j}\|_{L^\infty} = o(\lambda_j^{(n-1)/2}).$$

Theorems 1 and 2 are corollaries of our next theorem, where we relax the assumptions on μ and make the following definitions. Define the *time- T flow-out* by

$$\Lambda_{x,T} := \bigcup_{t=-T}^T G_t(S_x^*M).$$

Definition 1.2. Let \mathcal{H}^n be the n -dimensional Hausdorff measure on S^*M induced by the Sasaki metric on T^*M ; see for example [Blair 2010, Chapter 9] for a treatment of the Sasaki metric. We say that the subsequence u_{λ_j} , $j = 1, 2, \dots$, is *admissible at x* if for any defect measure μ associated to the sequence there exists $T > 0$ such that

$$\mathcal{H}^n(\text{supp } \mu|_{\Lambda_{x,T}}) = 0. \tag{1-4}$$

We say that the subsequence is *admissible* if it is admissible at x for every $x \in M$.

We note that in (1-4), $\mu|_{\Lambda_{x,T}}$ denotes the defect measure restricted to the flow-out $\Lambda_{x,T}$; for any A that is μ -measurable,

$$\mu|_{\Lambda_{x,T}}(A) := \mu(A \cap \Lambda_{x,T}).$$

Theorem 3. Let $\{u_{\lambda_j}\}$ be a sequence of L^2 -normalized Laplace eigenfunctions that is admissible in the sense of (1-4). Then

$$\|u_{\lambda_j}\|_{L^\infty} = o(\lambda_j^{(n-1)/2}).$$

Remark 1.3. We choose to use the Sasaki metric to define \mathcal{H}^n for concreteness, but this is not important and we could replace the Sasaki metric by any other metric on S^*M .

Theorem 3 can be interpreted as saying that eigenfunctions which strongly scar are too concentrated to have maximal L^∞ growth, while diffuse eigenfunctions are too spread out to have maximal growth. However, the reason the admissibility assumption is satisfied differs in these cases. In the diffuse case

(see [Theorem 2](#)), one has $\mu|_{\Lambda_{x,T}} = 0$, so that the admissibility assumption is trivially verified. In the case where the eigenfunctions strongly scar (see [Theorem 1](#)), $\mu|_{\Lambda_{x,T}} \neq 0$ but the Hausdorff dimension of $\text{supp } \mu|_{\Lambda_{x,T}}$ is $< n$; so again, (1-4) is satisfied. The zonal harmonics on the sphere S^2 , which saturate the L^∞ bound (1-2), lie precisely between being diffuse and strongly scarring (see [Section 4](#)).

Observe that the condition μ is diffuse is much more general than $\mu = \mu_L$. Jakobson and Zelditch [[1999](#)] show that any invariant measure on S^*S^n where S^n is the round sphere can be obtained as a defect measure for a sequence of eigenfunctions and in particular many non-Liouville but diffuse measures occur.

Remark 1.4. We note that the results here hold for any $o(\lambda)$ quasimode of $(-\Delta_g - \lambda^2)$ that is compactly microlocalized in frequency; see [[Galkowski 2017](#)].

Relation with previous results. [Theorem 2](#) is related to [[Sogge et al. 2011](#), [Theorem 3](#)], where the $o(h^{(1-n)/2})$ sup bound is proved for all Laplace eigenfunctions on a C^ω surface with ergodic geodesic flow. However, in [Theorem 2](#), we make no analyticity or dynamical assumptions on (M, g) whatsoever, only an assumption on the particular defect measure associated with the eigenfunction sequence. Recently, [Hezari \[2016\]](#) and [Sogge \[2016\]](#) gave independent proofs of [Theorem 2](#).

One consequence of the work of Sogge is the relation between L^p norms for eigenfunctions and the push forward of defect measures to the base manifold M . In particular, he showed [[Sogge 2016](#), (3.3)] that

$$\|u_\lambda\|_{L^\infty(M)} \leq C\lambda^{(n-1)/2} \sup_{x \in M} \delta^{-1/2} \|u_\lambda\|_{L^2(B_\delta(x))} \tag{1-5}$$

when $\lambda^{-1} \leq \delta \leq \text{inj}(M, g)$ and $\lambda \geq 1$. We note that when u_λ are quantum ergodic, $\|u_\lambda\|_{L^2(B_\delta(x))} \approx \delta^{n/2}$ and so the $o(\lambda^{(n-1)/2})$ -bound in [Theorem 2](#) follows from (1-5) as well; see also [Corollary 1.2](#) in [[Sogge 2016](#)].

However, neither the scarring result in [Theorem 1](#) nor the more general bound in [Theorem 3](#) follow from (1-5). To compare and contrast with (1-5), we observe that (1-5) implies for any $\delta > 0$ independent of λ ,

$$\limsup_{\lambda \rightarrow \infty} \lambda^{(1-n)/2} \|u_\lambda\|_{L^\infty(M)} \leq C \sup_{x \in M} \delta^{-1/2} (\mu(S^*B_\delta(x)))^{1/2}.$$

Our main estimate in (3-12) says that for any $x(\lambda)$ with $d(x(\lambda), x) = o(1)$,

$$\limsup_{\lambda \rightarrow \infty} \lambda^{(1-n)/2} |u_\lambda(x(\lambda))| \leq C'_\delta (\mathcal{H}^n(\text{supp } \mu|_{A_x(\delta/2, 3\delta)}))^{1/2}, \tag{1-6}$$

where for $\delta_2 > \delta_1$ we have $A_x(\delta_1, \delta_2) = \Lambda_{x, \delta_2} \setminus \Lambda_{x, \delta_1}$. This microlocalized bound allows us to deal with the more general scarring-type cases as well. In particular, the key differences are that we have replaced $S^*B_\delta(x)$ by $A_x(\delta/2, 2\delta) \subset \Lambda_x$ and the defect measure by Hausdorff n -measure. We note however that unlike (1-5), $\delta > 0$ can be arbitrarily small but is fixed independent of λ in (1-6).

Sogge and Zelditch [[2002](#)] proved that any manifold on which (1-2) is sharp must have a self-focal point. That is, a point x such that $|\mathcal{L}_x| > 0$, where

$$\mathcal{L}_x := \{\xi \in S_x^*M : \text{there exists } T \text{ such that } \exp_x T\xi = x\}$$

and $|\cdot|$ denotes the normalized surface measure on the sphere. Subsequently, in [Sogge et al. 2011] the authors showed that one can replace \mathcal{L}_x by the set of recurrent directions $\mathcal{R}_x \subset \mathcal{L}_x$ and the assumption $|\mathcal{R}_x| > 0$ for some $x \in M$ is necessary to saturate the maximal bound in (1-2). Here,

$$\mathcal{R}_x := \left\{ \xi \in S_x^*M : \xi \in \left(\bigcap_{T>0} \overline{\bigcup_{t \geq T} G_t(x, \xi) \cap S_x^*M} \right) \cap \left(\bigcap_{T>0} \overline{\bigcup_{t \leq -T} G_t(x, \xi) \cap S_x^*M} \right) \right\}.$$

The example of the triaxial ellipsoid with x equal to an umbilic point shows that latter assumption is weaker than the former. Indeed, in such a case $|\mathcal{L}_x| = 1$, whereas $|\mathcal{R}_x| = 0$. Most recently, in [Sogge and Zelditch 2016a; 2016b], it was proved that for real-analytic surfaces, the maximal L^∞ bound can only be achieved if there exists a periodic point $x \in M$ for the geodesic flow, i.e., a point (x, ξ) such that all geodesics starting at $(x, \xi) \in S^*M$ close up smoothly after some finite time $T > 0$.

Together with our analysis, the results of [Sogge et al. 2011] imply that any sequence of eigenfunctions, $\{u_\lambda\}$ having maximal L^∞ growth near x and defect measure μ must have $\mu(\Lambda_{x,T}) > 0$ for all $T > 0$ and $|\mathcal{R}_x| > 0$. In particular, the results of that paper show that u_λ can only have maximal L^∞ growth near a point with a positive measure set of recurrent points and Theorem 3 shows that a point with maximal L^∞ growth must have $\mu(\Lambda_{x,T}) > 0$. As far as the authors are aware, the results in [Sogge et al. 2011; Sogge and Zelditch 2016a; 2016b] do not give additional information about μ .

On the other hand, under an additional regularity assumption on the measure μ , Theorem 3 can be used to show that when u_λ has maximal growth near x , the measure $\mu|_{\Lambda_{x,T}}$ is not mutually singular with respect to \mathcal{H}^n . Since the measure for a zonal harmonic is a smooth multiple of \mathcal{H}^n (see Section 4), this implies that the measure μ resembles the defect measure of a zonal harmonic. In [Galkowski 2017], the first author removed the necessity for any additional regularity assumption and gave a full characterization of defect measures for eigenfunctions with maximal L^∞ growth, in particular proving that if u_λ has maximal growth near x and defect measure μ , then $\mu|_{\Lambda_{x,T}}$ is not mutually singular with respect to \mathcal{H}^n . Finally, we note that unlike [Sogge et al. 2011; Sogge and Zelditch 2002; 2016a; 2016b], the analysis here is entirely local.

2. A local version of Theorem 3

In the following, we will freely use semiclassical pseudodifferential calculus where the semiclassical parameter is h with $h^{-1} = \lambda \in \text{Spec } \sqrt{-\Delta_g}$. We write $r(x, y) : M \times M \rightarrow \mathbb{R}$ for the Riemannian distance from x to y and write $B(x, \delta)$ for the geodesic ball of radius δ around x . We start with a local result:

Theorem 4. *Let $\{u_h\}$ be sequence of Laplace eigenfunctions that is admissible at x . Then for any $\delta(h) = o(1)$,*

$$\|u_h\|_{L^\infty(B(x, \delta(h)))} = o(h^{(1-n)/2}).$$

Theorem 3 is an easy consequence of Theorem 4.

Proof that Theorem 4 implies Theorem 3. Suppose that u is admissible and

$$\limsup_{h \rightarrow 0} h^{(n-1)/2} \|u_h\|_{L^\infty} \neq 0.$$

Then, there exist $c > 0$, $h_k \rightarrow 0$, x_{h_k} so that

$$|u_{h_k}(x_{h_k})| \geq ch_k^{-(n-1)/2}.$$

Since M is compact, by taking a subsequence, we may assume $x_{h_k} \rightarrow x$. But then $r(x, x_{h_k}) = o(1)$ and since u is admissible at x , [Theorem 4](#) implies

$$\limsup_{k \rightarrow \infty} h_k^{(n-1)/2} |u_{h_k}(x_{h_k})| = 0. \quad \square$$

3. Proof of [Theorem 4](#)

In view of the above, it suffices to prove the local result: [Theorem 4](#).

Proof. Fix $T > 3\delta > 0$ and let $\rho \in \mathcal{S}(\mathbb{R})$ with $\rho(0) = 1$ and $\text{supp } \hat{\rho} \subset (\delta, 2\delta)$. Let

$$S^*M(\varepsilon) := \{(x, \xi) : ||\xi|_x - 1| \leq \varepsilon\}$$

and $\chi(x, \xi) \in C_0^\infty(T^*M)$ be a cutoff near the cosphere S^*M with $\chi(x, \xi) = 1$ for $(x, \xi) \in S^*M(\varepsilon)$ and $\chi(x, \xi) = 0$ when $(x, \xi) \in T^*M \setminus S^*M(2\varepsilon)$. Let $\chi(x, hD) \in \text{Op}_h(C_0^\infty(T^*M))$ be the corresponding h -pseudodifferential cutoff. Also, in the following, we will use the notation

$$\Gamma_x := \text{supp } \mu|_{\Lambda_{x,T}}$$

to denote the support of the restricted defect measure corresponding to the eigenfunction sequence $\{u_{h_j}\}$ in [Theorem 3](#).

Then, we have

$$u_h = \rho\left(\frac{1}{2h}[-h^2\Delta - 1]\right)u_h = \int_{\mathbb{R}} \hat{\rho}(t)e^{i(t/2)[-h^2\Delta - 1]/h} \chi(y, hD_y)u_h dt + O_\varepsilon(h^\infty). \quad (3-1)$$

Microlocalization to the flow-out Λ_x . Set

$$V(t, x, y, h) := (\hat{\rho}(t)e^{i(t/2)[-h^2\Delta - 1]/h} \chi(y, hD_y))(t, x, y).$$

Then, by Egorov's theorem [[Zworski 2012](#), Theorem 11.1]

$$\text{WF}'_h(V(t, \cdot, \cdot, h)) \subset \{(x, \xi, y, \eta) : (x, \xi) = G_t(y, \eta), ||\xi|_x - 1| \leq 2\varepsilon\}; \quad (3-2)$$

see, e.g., [[Dyatlov and Zworski 2017](#), Definition E.37] for a definition of WF'_h .

Let $b_{x,\varepsilon}(x, hD) \in \text{Op}_h(C_0^\infty(T^*M))$ be a family of h -pseudodifferential cutoffs with principal symbols $b_{x,\varepsilon} \in C_0^\infty(\{(y, \eta) : (y, \eta) = G_t(x_0, \xi) \text{ for some } (x_0, \xi) \in S_{x_0}^*M(3\varepsilon) \text{ with } r(x, x_0) < 2\varepsilon, \delta/2 < t < 3\delta\})$, with

$$b_{x,\varepsilon} \equiv 1 \quad \text{on } \{(y, \eta) : (y, \eta) = G_t(x_0, \xi) \text{ for some } (x_0, \xi) \in S_{x_0}^*M(2\varepsilon) \text{ with } r(x, x_0) < \varepsilon, \delta < t < 2\delta\}.$$

By the definition of WF'_h together with (3-1) and (3-2), it follows that for $r(x(h), x) = o(1)$,

$$u_h(x(h)) = \int_M \bar{V}(x(h), y, h) b_{x,\varepsilon}(y, hD_y) u_h(y) dy + O_\varepsilon(h^\infty), \quad (3-3)$$

where,

$$\bar{V}(x(h), y, h) := \int_{\mathbb{R}} \hat{\rho}(t) (e^{i(t/2)[-h^2\Delta-1]/h} \chi(y, hD_y))(t, x(h), y) dt.$$

By a standard stationary phase argument,

$$\bar{V}(x, y, h) = h^{(1-n)/2} e^{-ir(x,y)/h} a(x, y, h) \hat{\rho}(r(x, y)) + O_\varepsilon(h^\infty), \tag{3-4}$$

where $a(x, y, h) \in S^0(1)$.

To see this, observe that by [Zworski 2012, Theorem 10.4]

$$\bar{V}(x, y, h) = (2\pi h)^{-n} \int e^{i\varphi(t,x,y,\eta)/h} \alpha(t, x, y, \eta, h) \hat{\rho}(t) d\eta dt + O(h^\infty),$$

where $b \in C_c^\infty$ and φ solves

$$\partial_t \varphi = \frac{1}{2} (|\partial_x \varphi|_{g(x)}^2 - 1), \quad \varphi(0, x, y, \eta) = \langle x - y, \eta \rangle. \tag{3-5}$$

In particular, for all (t, x, y, η) , we have $\exp(tH_{|\xi|_g^2/2})(\partial_\eta \varphi + y, \eta) = (x, \partial_x \varphi)$. The phase function

$$\varphi(t, x, y, \eta) = \langle \exp_y^{-1}(x), \eta \rangle + \frac{1}{2} t (|\eta|_y^2 - 1)$$

satisfies (3-5).

We next perform stationary phase in (t, η) . First, observe that the phase is stationary at

$$\exp(tH_{|\xi|_g^2/2})(y, \eta) = (x, \partial_x \varphi), \quad |\partial_x \varphi|_{g(x)} = 1.$$

In particular, $t = r(x, y)$ and the geodesic through (y, η) passes through x . Since $\text{supp } \hat{\rho} \subset (\delta, 2\delta)$, by performing nonstationary phase, we may assume $t \in (\delta, 2\delta)$ and hence $\delta < r(x, y) < 2\delta$. Then, we observe that $\partial_{(t,\eta)}^2 \varphi$ is nondegenerate for $t \in (\delta, 2\delta)$. The solutions (t_c, η_c) of the critical point equations $\partial_t \varphi = 0$ and $\partial_\eta \varphi = 0$ are given by

$$t_c = |\exp_y^{-1}(x)| = r(x, y), \quad \eta_c = -\frac{\exp_y^{-1}(x)}{r(x, y)}.$$

Consequently, (3-4) follows from an application of stationary phase; see also [Sogge 1993, Lemma 5.1.3; Burq et al. 2007, Theorem 4].

Then, in view of (3-4) and (3-3),

$$u_h(x(h)) = v_h(x(h)) + O_\varepsilon(h^\infty),$$

$$v_h(x(h)) = h^{(1-n)/2} \int_{\delta/2 < r(x,y) < 2\delta} e^{-ir(x(h),y)/h} a(x(h), y, h) \hat{\rho}(r(x(h), y)) b_{x,\varepsilon}(y, hD_y) u_h(y) dy. \tag{3-6}$$

Now, note that for any $\psi \in C_0^\infty(M)$,

$$v_h(x(h)) = I_1(x(h), h) + I_2(x(h), h), \tag{3-7}$$

where

$$I_1 := (2\pi h)^{(1-n)/2} \int_{\delta/2 < r(x,y) < 2\delta} e^{-ir(x(h),y)/h} a(x(h), y, h) \hat{\rho}(r(x(h), y)) \psi(y) (b_{x,\varepsilon}(y, hD_y) u_h) dy,$$

$$I_2 := (2\pi h)^{(1-n)/2} \int_{\delta/2 < r(x,y) < 2\delta} e^{-ir(x(h),y)/h} a(x(h), y, h) \hat{\rho}(r(x(h), y)) (1-\psi(y)) (b_{x,\varepsilon}(y, hD_y) u_h) dy.$$

Therefore, by Cauchy–Schwarz applied to I_1 and I_2 ,

$$|h^{(n-1)/2}v_h(x(h))| \leq C_\delta (\|\psi\|_{L^2} \|b_{x,\varepsilon}(y, hD_y)u_h(y)\|_{L^2} + \|(1 - \psi(y))[b_{x,\varepsilon}(y, hD_y)u_h]\|_{L^2}).$$

Hence letting $h \rightarrow 0$ then $\varepsilon \rightarrow 0$, and using that

$$\|b_{x,\varepsilon}(y, hD_y)u_h(y)\|_{L^2} \leq (\sup |b_{x,\varepsilon}| + o_\varepsilon(1))\|u_h\|_{L^2},$$

see for example [Zworski 2012, Theorem 5.1], we have

$$\limsup_{h \rightarrow 0} h^{(n-1)/2}|u_h(x(h))| \leq C_\delta \left(\|\psi\|_{L^2} + \left(\int_{\Lambda_{x,3\delta} \setminus \Lambda_{x,\delta/2}} (1 - \psi(y))^2 d\mu \right)^{\frac{1}{2}} \right). \tag{3-8}$$

Further microlocalization along $\text{supp } \mu|_{\Lambda_x}$. Let \mathcal{H}^n be the n -dimensional Hausdorff measure on the flow-out Λ_x . By assumption, $\mathcal{H}^n(\text{supp } \mu|_{\Lambda_x}) = 0$. In view of the microlocalization above, we are only interested in the annular subset

$$A_x(\delta/2, 3\delta) := \Lambda_{x,3\delta} \setminus \Lambda_{x,\delta/2}.$$

Since \mathcal{H}^n is Radon, for any $\varepsilon_1 > 0$, there exist n -dimensional balls $B(r_j) \subset A_x(\delta/4, 4\delta)$, $j = 1, 2, \dots$, with radii $r_j > 0$, $j = 1, 2, \dots$, such that

$$\text{supp } \mu|_{A_x(\delta/2,3\delta)} \subset \bigcup_{j=1}^\infty B(r_j), \quad \mathcal{H}^n\left(\bigcup_{j=1}^\infty B(r_j)\right) < \mathcal{H}^n(\text{supp } \mu|_{A_x(\delta/2,3\delta)}) + \varepsilon_1.$$

Note that for $\delta > 0$ small enough, the canonical projection $\pi : T^*M \rightarrow M$ restricts to a diffeomorphism

$$\pi : A_x\left(\frac{1}{4}\delta, 4\delta\right) \rightarrow \{y \in M : \delta/4 < r(x, y) < 4\delta\}.$$

Consider the closed set

$$K = \pi(\text{supp } \mu|_{A_x(\delta/2,3\delta)}) \subset M$$

with open covering

$$G := \pi\left(\bigcup_{j=1}^\infty B(r_j)\right) \quad \text{satisfying } \mathcal{H}^n(G) = \mathcal{H}^n(K) + O(\varepsilon_1). \tag{3-9}$$

By the C^∞ Urysohn lemma, there exists $\chi_{\Gamma_x} \in C_0^\infty(M; [0, 1])$ with

$$\chi_{\Gamma_x}|_K = 1, \quad \text{supp } \chi_{\Gamma_x} \subset G. \tag{3-10}$$

(Note that χ_{Γ_x} depends on ε_1 , but we suppress this dependence to simplify notation.) We now apply (3-8) with $\psi = \chi_{\Gamma_x}$. First, observe that by (3-9) and (3-10)

$$\|\chi_{\Gamma_x}\|_{L^2} \leq (\mathcal{H}^n(G))^{1/2} \leq (\mathcal{H}^n(K))^{1/2} + O(\varepsilon_1^{1/2}). \tag{3-11}$$

Next, by construction, for all $\varepsilon_1 > 0$,

$$(1 - \chi_{\Gamma_x})(y) = 0 \quad \text{for all } y \in \pi(\text{supp } \mu|_{\Lambda_{x,4\delta} \setminus \Lambda_{x,\delta/4}})$$

and hence

$$\int_{\Lambda_{x,3\delta} \setminus \Lambda_{x,\delta/2}} (1 - \chi_{\Gamma_x})^2 d\mu = 0.$$

Using this together with (3-11) in (3-8) and sending $\varepsilon_1 \rightarrow 0$ gives

$$\limsup_{h \rightarrow 0} h^{(n-1)/2} |u_h(x(h))| \leq C_\delta (\mathcal{H}^n(\pi(\text{supp } \mu|_{A_x(\delta/2,3\delta)})))^{1/2} \leq C'_\delta (\mathcal{H}^n(\text{supp } \mu|_{A_x(\delta/2,3\delta)}))^{1/2}, \quad (3-12)$$

where the last inequality follows from the fact that $\pi|_{A(\delta/2,3\delta)}$ is a diffeomorphism. Finally, since u_h is admissible at x ,

$$\mathcal{H}^n(\text{supp } \mu|_{A_x(\delta/2,3\delta)}) = 0. \quad \square$$

Remark 3.1. For $r(x(h), x) = o(1)$, the estimate

$$\limsup_{h \rightarrow 0} h^{(n-1)/2} |u_h(x(h))| \leq C'_\delta (\mathcal{H}^n(\text{supp } \mu|_{A_x(\delta/2,3\delta)}))^{1/2}$$

in (3-12) holds for any sequence of eigenfunctions with defect measure μ . It gives a quantitative estimate relating the behaviour of the defect measure to L^∞ norms of eigenfunctions. This estimate can also be obtained as a consequence of [Galkowski 2017, Theorem 2] by replacing the absolutely continuous part of μ with $1_{\text{supp } \mu|_{\Lambda_x}} d\mathcal{H}^n$.

4. The example of zonal harmonics

Let (S^2, g_{can}) be the round sphere and (r, θ) be polar variables centred at the north pole $p = (0, 0, 1) \in \mathbb{R}^3$. The geodesic flow is a completely integrable system with Hamiltonian

$$H = |\xi|_g^2 = \xi_r^2 + (\sin r)^{-2} \xi_\theta^2, \quad r \in (0, \pi), \quad (4-1)$$

and Clairault integral $p = \xi_\theta$ satisfying $\{H, p\} = 0$. The associated moment mapping is $\mathcal{P} = (H, p) : T^*S^2 \rightarrow \mathbb{R}^2$ and the connected components of the level sets are, by the Liouville–Arnold theorem, Lagrangian tori Λ_c indexed by the values of the moment map $(1, c) \in \mathcal{P}(T^*S^2)$.

The associated quantum integrable system is given by the Laplacian Δ_g and the rotation operator hD_θ . The corresponding L^2 -normalized joint eigenfunctions are the standard spherical harmonics Y_m^k with

$$-\Delta_g Y_m^k = k(k+1)Y_m^k, \quad hD_\theta Y_m^k = mY_m^k.$$

These eigenfunctions can be separated into various sequences (i.e., *ladders*) associated with different values ($\in \mathcal{P}(T^*S^2)$); specifically, the correspondence is given by $c = \lim_{m \rightarrow \infty} m/k$. The eigenfunctions with maximal L^∞ blow-up are the sequence of *zonal* harmonics given by

$$u_h(r, \theta) = Y_0^k(r, \theta) = \frac{\sqrt{2k+1}}{2\pi} \int_0^{2\pi} (\cos r + i \sin r \cos \tau)^k d\tau, \quad h = k^{-1}, \quad k = 1, 2, 3, \dots \quad (4-2)$$

It is obvious from (4-2) that

$$|Y_0^k(p)| \approx k^{1/2}$$

and thus attains the maximal sup growth at p (similarly, at the south pole). At the classical level, the zonals $u_h = Y_0^k$ concentrate microlocally on the Lagrangian tori $\Lambda_0 = \mathcal{P}^{-1}(1, 0)$. From the formula (4-1)

it is clear that away from the poles (where (r, θ) are honest coordinates),

$$\Lambda_0 \setminus \{\pm p\} = \{(r, \theta, \xi_r = \pm 1, \xi_\theta = 0) : r \in (0, \pi)\} \cong S^2 \setminus \{\pm p\}. \tag{4-3}$$

The choice of $\xi_r = \pm 1$ determines the Lagrangian torus (there are two of them) and also, either torus clearly covers the entire sphere. At the poles themselves, the projection $\pi_{\Lambda_0} : \Lambda_0 \rightarrow S^2$ has a blowdown singularity with

$$\pi_{\Lambda_0}^{-1}(\pm p) = S_\pm^*(S^2) \cong S^1. \tag{4-4}$$

To see this, consider the behaviour at p (with a similar computation at $-p$). Rewriting the integral in involution in Euclidean coordinates $(x, y, z) \in \mathbb{R}^3$, one has $H = (x\xi_y - y\xi_x)^2 + (x\xi_z - z\xi_x)^2 + (y\xi_z - z\xi_y)^2$ and $\xi_\theta = x\xi_y - y\xi_x$. Setting $H = 1$, $x\xi_y - y\xi_x = 0$ and $(x, y, z) = (0, 0, 1)$ gives

$$\pi_{\Lambda_0}^{-1}(p) \cong \{(\xi_x, \xi_y) \in \mathbb{R}^2 : \xi_x^2 + \xi_y^2 = 1\}.$$

It is then clear from (4-3) and (4-4) that $\pi_{\Lambda_0} : \Lambda_0 \rightarrow S^2$ is surjective and a diffeomorphism away from the poles (modulo choice of Lagrangian cover) and the fibres above the poles are $S_\pm^*(S^2) \cong S^1$. We also note that the Lagrangian $\Lambda_0 = \Lambda_{p, 2\pi}$ is the 2π -flow-out Lagrangian of $S_p^*(S^2)$ and the cylinder $A_p(\delta/2, 3\delta)$ is just a local slice of this Lagrangian.

The defect measure μ associated with the zonals is

$$d\mu = |d\theta_1 d\theta_2|,$$

where $(\theta_1, \theta_2; I_1, I_2) \in \mathbb{R}^2/\mathbb{Z}^2 \times \mathbb{R}^2$ are symplectic action-angle variables defined in a neighbourhood of the Lagrangian torus Λ_0 [Toth and Zelditch 2003]. One can choose one of the angle variables $\theta_1 \in S_p^*(S^2)$ to parametrize the circle fibre above p (a homology generator of the torus). Then, by the Liouville–Arnold theorem, the geodesic flow on the torus $\Lambda_0 = \{I_1 = c_1, I_2 = c_2\}$ is affine with

$$\theta_j(t) = \theta_j(0) + \alpha_j t, \quad \alpha_j = \frac{\partial H}{\partial I_j} \neq 0.$$

It is then clear that

$$\mu(\Lambda_{p, \delta}) = \int_0^{2\pi} d\theta_1 \cdot \int_{|t| < \delta} \alpha_2 dt \approx \delta \neq 0$$

and $\text{supp } \mu|_{\Lambda_p} = \Lambda_p$. Therefore, this case violates the assumption in Theorem 3 and that is of course consistent with the maximal L^∞ growth of zonal harmonics.

The analysis above extends in a straightforward fashion to the case of a more general sphere of rotation [Toth and Zelditch 2003].

5. Eigenfunctions of Schrödinger operators

Consider a Schrödinger operator $P(h) = -h^2 \Delta_g + V$ with $V \in C^\infty(M; \mathbb{R})$ on a compact, closed Riemannian manifold (M, g) and let u_h be an L^2 -normalized eigenfunction with

$$P(h)u_h = E(h)u_h, \quad E(h) = E + o(1), \quad E > \min V, \quad \|u_h\|_{L^2} = 1. \tag{5-1}$$

Any sequence u_h of solutions to (5-1) has a subsequence u_{h_k} with a defect measure μ in the sense that for $a \in C_0^\infty(T^*M)$

$$\langle a(x, hD)u_h, u_h \rangle \rightarrow \int_{T^*M} a \, d\mu.$$

Such a measure μ is supported on $\{p = 0\}$ and is invariant under the bicharacteristic flow $G_t := \exp(tH_p)$.

In analogy with the homogeneous case, we define for $x \in M$ the *time- T flow-out* by

$$\Lambda_{x,T,V} := \bigcup_{t=-T}^T G_t(\Sigma_x),$$

where

$$\Sigma_x = \{\xi \in T_x^*M : |\xi|_g^2 + V(x) = E\}.$$

Definition 5.1. Let \mathcal{H}^n be n -dimensional Hausdorff measure on $\{|\xi|_g^2 + V(x) = E\}$ induced by the Sasaki metric on T^*M . We say that the sequence u_h of solutions to (5-1) is *admissible at x* if for any defect measure μ associated to the sequence, there exists $T > 0$ so that

$$\mathcal{H}^n(\text{supp } \mu|_{\Lambda_{x,T,V}}) = 0. \tag{5-2}$$

With these definitions we have the analog of [Theorem 3](#):

Theorem 5. *Let $B \subset V^{-1}(E)$ be a closed ball in the classically allowable region and μ be a defect measure associated with the eigenfunction sequence u_h . Then, if the eigenfunction sequence is admissible for all $x \in B$ in the sense of (5-2),*

$$\sup_{x \in B} |u_h(x)| = o(h^{(1-n)/2}).$$

Proof. In analogy with the homogeneous case [[Christianson et al. 2015](#), Lemma 5.1], we have

$$\rho(h^{-1}[P(h) - E])(x, y) = h^{(1-n)/2} a(x, y, h) e^{-iA(x,y)/h} + R(x, y, h),$$

where $A(x, y) \in [(2C_0)^{-1}\varepsilon, 2C_0\varepsilon]$ for some $C_0 > 1$ and is the action function defined to be the integral of the Lagrangian $L(x, \xi) = |\xi|_g^2 - V(x)$ along the bicharacteristic in $\{p = E\}$ starting at (y, η) and ending at (x, ξ) . For (x, y) in a small neighbourhood of the diagonal, there is a unique such η satisfying this condition. The remainder $R(x, y, h)$ is equal to $O(h^\infty)$ pointwise and with all derivatives. The proof then follows using the same argument as in the homogeneous case. □

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