# ANALYSIS \& PDE 

## Volume 16 No. 7 2023

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# A STRUCTURE THEOREM FOR ELLIPTIC AND PARABOLIC OPERATORS WITH APPLICATIONS TO HOMOGENIZATION OF OPERATORS OF KOLMOGOROV TYPE 

Malte Litsgård and Kaj Nyström

We consider the operators

$$
\nabla_{X} \cdot\left(A(X) \nabla_{X}\right), \quad \nabla_{X} \cdot\left(A(X) \nabla_{X}\right)-\partial_{t}, \quad \nabla_{X} \cdot\left(A(X) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t},
$$

where $X \in \Omega,(X, t) \in \Omega \times \mathbb{R}$ and $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, respectively, and where $\Omega \subset \mathbb{R}^{m}$ is an (unbounded) Lipschitz domain with defining function $\psi: \mathbb{R}^{m-1} \rightarrow \mathbb{R}$ being Lipschitz with constant bounded by $M$. Assume that the elliptic measure associated to the first of these operators is mutually absolutely continuous with respect to the surface measure $\mathrm{d} \sigma(X)$ and that the corresponding RadonNikodym derivative or Poisson kernel satisfies a scale-invariant reverse Hölder inequality in $L^{p}$, for some fixed $p, 1<p<\infty$, with constants depending only on the constants of $A, m$ and the Lipschitz constant of $\psi, M$. Under this assumption we prove that the same conclusions are also true for the parabolic measures associated to the second and third operators with $\mathrm{d} \sigma(X)$ replaced by the surface measures $\mathrm{d} \sigma(X) \mathrm{d} t$ and $\mathrm{d} \sigma(X) \mathrm{d} Y \mathrm{~d} t$, respectively. This structural theorem allows us to reprove several results previously established in the literature, as well as to deduce new results in, for example, the context of homogenization for operators of Kolmogorov type. Our proof of the structural theorem is based on recent results established by the authors concerning boundary Harnack inequalities for operators of Kolmogorov type in divergence form with bounded, measurable and uniformly elliptic coefficients.

## 1. Introduction

Let $\Omega \subset \mathbb{R}^{m}, m \geq 2$, be an (unbounded) Lipschitz domain

$$
\begin{equation*}
\Omega=\left\{X=\left(x, x_{m}\right) \in \mathbb{R}^{m-1} \times \mathbb{R}: x_{m}>\psi(x)\right\}, \tag{1-1}
\end{equation*}
$$

where $\psi: \mathbb{R}^{m-1} \rightarrow \mathbb{R}$ is Lipschitz with constant bounded by $M$. Let $A=A(X)=\left\{a_{i, j}(X)\right\}$ be a real $m \times m$ matrix-valued, measurable function such that $A(X)$ is symmetric and

$$
\begin{equation*}
\kappa^{-1}|\xi|^{2} \leq \sum_{i, j=1}^{m} a_{i, j}(X) \xi_{i} \xi_{j} \leq \kappa|\xi|^{2} \tag{1-2}
\end{equation*}
$$

[^0]for some $1 \leq \kappa<\infty$ and for all $\xi \in \mathbb{R}^{m}, X \in \mathbb{R}^{m}$. We consider the divergence form operators
\[

$$
\begin{aligned}
\mathcal{L}_{\mathcal{E}} & :=\nabla_{X} \cdot\left(A(X) \nabla_{X}\right) \\
\mathcal{L}_{\mathcal{P}} & :=\nabla_{X} \cdot\left(A(X) \nabla_{X}\right)-\partial_{t} \\
\mathcal{L}_{\mathcal{K}} & :=\nabla_{X} \cdot\left(A(X) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t}
\end{aligned}
$$
\]

in $\mathbb{R}^{2 m+1}, m \geq 1$, equipped with coordinates $(X, Y, t):=\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}, t\right) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \times \mathbb{R}$. Obviously $\mathcal{L}_{\mathcal{E}}$ only makes reference to the $X$-coordinate, $\mathcal{L}_{\mathcal{P}}$ makes reference to the $X$ - and $t$-coordinates and $\mathcal{L}_{\mathcal{K}}$ makes reference to all coordinates. The subscripts $\mathcal{E}, \mathcal{P}, \mathcal{K}$, refer to elliptic, parabolic and Kolmogorov.
$\mathcal{L}_{\mathcal{E}}$ is the standard second-order elliptic PDE with only measurable, bounded and uniformly elliptic coefficients, much-studied ever since the breakthroughs of Moser, Nash, De Giorgi and others. $\mathcal{L}_{\mathcal{P}}$ is the corresponding parabolic version, and $\mathcal{L}_{\mathcal{K}}$ is an operator of Kolmogorov type in divergence form, which up to now has only been modestly studied and understood. Recently, in [Golse et al. 2019] the authors extended the De Giorgi-Nash-Moser (DGNM) theorem, which in its original form only considers elliptic or parabolic equations in divergence form, to (hypoelliptic) equations with rough coefficients including the operator $\mathcal{L}_{\mathcal{K}}$ assuming (1-2). Their result is the correct scale- and translation-invariant estimates for local Hölder continuity and the Harnack inequality for weak solutions.

To give some perspective on the operator $\mathcal{L}_{\mathcal{K}}$, recall that the operator

$$
\mathcal{K}:=\nabla_{X} \cdot \nabla_{X}+X \cdot \nabla_{Y}-\partial_{t}
$$

was originally introduced and studied by Kolmogorov [1934]. He noted that $\mathcal{K}$ is an example of a degenerate parabolic operator having strong regularity properties, and he proved that $\mathcal{K}$ has a fundamental solution which is smooth off its diagonal. Today, using the terminology introduced by Hörmander [1967], we can conclude that $\mathcal{K}$ is hypoelliptic. Naturally, for the operator $\mathcal{L}_{\mathcal{K}}$, assuming only measurable coefficients and (1-2), the methods of Kolmogorov and Hörmander cannot be directly applied to establish the DGNM theorem and related estimates.

In this paper we are interested in the $L^{p}$ Dirichlet problem for the operators $\mathcal{L}_{\mathcal{E}}, \mathcal{L}_{\mathcal{P}}, \mathcal{L}_{\mathcal{K}}$ in the (unbounded) Lipschitz domains $\Omega, \Omega \times \mathbb{R}$ and $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ respectively, and where $X \in \Omega,(X, t) \in \Omega \times \mathbb{R}$ and $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. In particular, we consider the operators $\mathcal{L}_{\mathcal{P}}$ and $\mathcal{L}_{\mathcal{K}}$ in $t$-independent and $(Y, t)$-independent domains, respectively. We introduce a (physical) measure $\sigma_{\mathcal{K}}$ on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$,

$$
\begin{equation*}
\mathrm{d} \sigma_{\mathcal{K}}(X, Y, t):=\sqrt{1+\left|\nabla_{x} \psi(x)\right|^{2}} \mathrm{~d} x \mathrm{~d} Y \mathrm{~d} t, \quad(X, Y, t) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R} \tag{1-3}
\end{equation*}
$$

We refer to $\sigma_{\mathcal{K}}$ as the surface measure on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, where the subscript $\mathcal{K}$ indicates that we consider a setting appropriate for operators of Kolmogorov type. The corresponding measures relevant for $\mathcal{L}_{\mathcal{E}}$ and $\mathcal{L}_{\mathcal{P}}$ are $\sigma_{\mathcal{E}}$ and $\sigma_{\mathcal{P}}$,

$$
\begin{equation*}
\mathrm{d} \sigma_{\mathcal{E}}(X):=\sqrt{1+\left|\nabla_{x} \psi(x)\right|^{2}} \mathrm{~d} x, \quad \mathrm{~d} \sigma_{\mathcal{P}}(X, t):=\mathrm{d} \sigma_{\mathcal{E}}(X) \mathrm{d} t \tag{1-4}
\end{equation*}
$$

where $X \in \partial \Omega$ and $(X, t) \in \partial \Omega \times \mathbb{R}$, respectively.

The main results of the paper are Theorems 3.1, 3.2 and 3.3, stated in Section 3 below. Using these theorems we can derive new results concerning the $L^{p}$ Dirichlet problem for $\mathcal{L}_{\mathcal{K}}$ using results previously only proved for $\mathcal{L}_{\mathcal{E}}$ or $\mathcal{L}_{\mathcal{P}}$, and we can also conclude that some results proved in the literature concerning $\mathcal{L}_{\mathcal{P}}$ are straightforward consequences of the corresponding results for $\mathcal{L}_{\mathcal{E}}$. In particular, the main result of [Fabes and Salsa 1983] concerning parabolic measure is a consequence of the classical result of [Dahlberg 1977] concerning harmonic measure. Our proofs of Theorems 3.1, 3.2 and 3.3 are based on our recent results in [Litsgård and Nyström 2022] concerning boundary Harnack inequalities for operators of Kolmogorov type in divergence form with bounded, measurable and uniformly elliptic coefficients.

Theorem 3.1, 3.2 and 3.3, and their consequences, are deduced under the assumptions:
(A1) $\Omega \subset \mathbb{R}^{m}$ is a (unbounded) Lipschitz domain with constant $M$.
(A2) $A$ satisfies (1-2) with constant $\kappa$.
(A3) $A$ satisfies the qualitative assumptions stated in (2-16) and (2-17) below.
All quantitative estimates will only depend on $m, \kappa$ and $M$, and Theorems 3.1 and 3.2 are by their nature of local character. However, we have chosen to state our results in the unbounded geometric setting $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. To avoid being diverted by additional technical issues caused by the unbounded setting, we assume (2-16). Equation (2-17) is only imposed to ensure that all results (e.g., the existence of fundamental solutions) and all estimates used in the paper can be found in the literature. One can dispense of (2-17) at the expense of additional arguments.

We consider the following problems and we refer to the bulk of the paper for all definitions, and in particular for the definition of weak solutions to $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$.

Definition. Assume that $\Omega \subset \mathbb{R}^{m}$ is an (unbounded) Lipschitz domain with constant $M$. Assume that $A$ satisfies (1-2) with constant $\kappa$, and (2-16). Given $p \in(1, \infty)$, we say that the Dirichlet problem for $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ is solvable in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ if there exists, for every $f \in L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, a weak solution to the Dirichlet problem

$$
\begin{cases}\mathcal{L}_{\mathcal{K}} u=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \\ u=f & \text { nontangentially on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R},\end{cases}
$$

and a constant $c$, depending only on $m, \kappa, M$ and $p$, such that

$$
\|N(u)\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)},
$$

where $N(u)$ is introduced in Section $2 G$. For short we say that $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is solvable. If the solution is unique then we say that the Dirichlet problem for $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega$ is uniquely solvable in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$. For short we write that $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable. The notions that $D_{\mathcal{E}}^{p}\left(\partial \Omega, \mathrm{~d} \sigma_{\mathcal{E}}\right)$ and $D_{\mathcal{P}}^{p}\left(\partial \Omega \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{P}}\right)$ are uniquely solvable are defined analogously.

Using our structural theorems (i.e., combining Theorems 3.1, 3.2 and 3.3) we can conclude that if $D_{\mathcal{E}}^{p}\left(\partial \Omega, \mathrm{~d} \sigma_{\mathcal{E}}\right)$ is uniquely solvable for some $p \in(1, \infty)$, then also $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable. We can use this insight to state a number of results concerning the solvability of $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ and in particular we can conclude the following.

Theorem 1.1. Assume (A1)-(A3). Assume also

$$
\begin{equation*}
A\left(x, x_{m}\right)=A(x), \quad x \in \mathbb{R}^{m-1}, x_{m} \in \mathbb{R} \tag{1-5}
\end{equation*}
$$

i.e., $A$ is independent of $x_{m}$. Then there exists $\delta=\delta(m, \kappa, M) \in(0,1)$ such that if $2-\delta<p<\infty$, then $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable.
Theorem 1.2. Assume (A1)-(A3). Assume also

$$
\begin{equation*}
A\left(x, x_{m}+1\right)=A\left(x, x_{m}\right), \quad x \in \mathbb{R}^{m-1}, x_{m} \in \mathbb{R} \tag{1-6}
\end{equation*}
$$

i.e., A is 1-periodic in $x_{m}$, and that A satisfies a Dini-type condition in the $x_{m}$-variable,

$$
\begin{equation*}
\int_{0}^{1} \frac{\theta(\varrho)^{2}}{\varrho} \mathrm{~d} \varrho<\infty \tag{1-7}
\end{equation*}
$$

where $\theta(\varrho):=\sup \left\{\left|A\left(x, \lambda_{1}\right)-A\left(x, \lambda_{2}\right)\right|: x \in \mathbb{R}^{m-1},\left|\lambda_{1}-\lambda_{2}\right| \leq \varrho\right\}$. Then there exists $\delta=\delta(m, \kappa, M) \in$ $(0,1)$ such that if $2-\delta<p<\infty$, then $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable.

Using our structural theorems it follows that Theorem 1.1 is a consequence of [Jerison and Kenig 1981] and that Theorem 1.2 is a consequence of [Kenig and Shen 2011]. By the same argument we can conclude that the main result in [Fabes and Salsa 1983] is a consequence of [Dahlberg 1977] and that the main result in [Castro and Strömqvist 2018] is a consequence of [Kenig and Shen 2011].

With Theorem 1.2 in place we are also able to analyze a homogenization problem for operators of Kolmogorov type. In this case we assume, in addition to (1-2), that

$$
\begin{equation*}
A(X+Z)=A(X) \quad \text { for all } Z \in \mathbb{Z}^{m} \tag{1-8}
\end{equation*}
$$

and that

$$
\begin{equation*}
\int_{0}^{1} \frac{\Theta(\varrho)^{2}}{\varrho} \mathrm{~d} \varrho<\infty \tag{1-9}
\end{equation*}
$$

where $\Theta(\varrho):=\sup \left\{|A(X)-A(\tilde{X})|: X, \widetilde{X} \in \mathbb{R}^{m},|X-\widetilde{X}| \leq \varrho\right\}$. That is, $A$ is periodic with respect to the lattice $\mathbb{Z}^{m}$ and $A$ satisfies a Dini condition in all variables.

We consider, for $\epsilon>0$, the operator $\mathcal{L}_{\mathcal{E}}^{\epsilon}$,

$$
\begin{equation*}
\mathcal{L}_{\mathcal{E}}^{\epsilon}:=\nabla_{X} \cdot\left(A^{\epsilon}(X) \nabla_{X}\right), \quad A^{\epsilon}(X):=A(X / \epsilon) . \tag{1-10}
\end{equation*}
$$

Let

$$
\overline{\mathcal{L}}_{\mathcal{E}}:=\nabla_{X} \cdot\left(\bar{A} \nabla_{X}\right)
$$

where the matrix $\bar{A}$ is determined by

$$
\begin{equation*}
\bar{A} \alpha:=\int_{(0,1)^{m}} A(X) \nabla_{X} w_{\alpha}(X) \mathrm{d} X, \quad \alpha \in \mathbb{R}^{m} \tag{1-11}
\end{equation*}
$$

and the auxiliary function $w_{\alpha}$ solves the problem

$$
\left\{\begin{array}{l}
\nabla_{X} \cdot\left(A(X) \nabla_{X} w_{\alpha}(X)\right)=0 \quad \text { in }(0,1)^{m} \\
w_{\alpha}(X)-\alpha X \text { is 1-periodic (in all variables) } \\
\int_{(0,1)^{m}}\left(w_{\alpha}(X)-\alpha X\right) \mathrm{d} X=0
\end{array}\right.
$$

Finally, we also introduce

$$
\begin{equation*}
\mathcal{L}_{\mathcal{K}}^{\epsilon}:=\mathcal{L}_{\mathcal{E}}^{\epsilon}+X \cdot \nabla_{Y}-\partial_{t}, \quad \overline{\mathcal{L}}_{\mathcal{K}}:=\overline{\mathcal{L}}_{\mathcal{E}}+X \cdot \nabla_{Y}-\partial_{t} \tag{1-12}
\end{equation*}
$$

We prove the following homogenization result.
Theorem 1.3. Assume (A1)-(A3). Assume also (1-8) and (1-9). Then there exists $\delta=\delta(m, \kappa, M) \in(0,1)$ such that the following is true. Consider $\epsilon>0$. Given $p, 2-\delta<p<\infty$, and $f \in L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, there exists a unique weak solution $u_{\epsilon}$ to the Dirichlet problem

$$
\left\{\begin{aligned}
\mathcal{L}_{\mathcal{K}}^{\epsilon} u_{\epsilon}=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R} \\
u_{\epsilon}=f & \text { nontangentially on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{aligned}\right.
$$

and a constant $c=c(m, \kappa, M, p), 1 \leq c<\infty$, such that

$$
\left\|N\left(u_{\epsilon}\right)\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

Moreover, $u_{\epsilon} \rightarrow \bar{u}$ locally uniformly in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ as $\epsilon \rightarrow 0$, and $\bar{u}$ is the unique weak solution to the Dirichlet problem

$$
\left\{\begin{align*}
& \overline{\mathcal{L}}_{\mathcal{K}} \bar{u}=0  \tag{1-13}\\
& \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R} \\
& \bar{u}=f \\
& \text { nontangentially on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{align*}\right.
$$

and there exists a constant $c=c(m, \kappa, M, p), 1 \leq c<\infty$, such that

$$
\|N(\bar{u})\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

Theorem 1.2 and the first part of Theorem 1.3 were proved in [Kenig and Shen 2011] for $\mathcal{L}_{\mathcal{E}}$. In that work the Neumann and regularity problems are also treated. The theory for the Neumann and regularity problems is based on the use of integral identities to estimate certain nontangential maximal functions. Homogenization of Neumann and regularity problems for $\mathcal{L}_{\mathcal{P}}$ and $\mathcal{L}_{\mathcal{K}}$ remain interesting open problems.

To be clear, the main idea of this paper is that results concerning the $L^{p}$ Dirichlet problem for the operator $\mathcal{L}_{\mathcal{K}}$ in domains $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ (and for the operator $\mathcal{L}_{\mathcal{P}}$ in domains $\Omega \times \mathbb{R}$ ) can be derived from the corresponding results for the operator $\mathcal{L}_{\mathcal{E}}$ in $\Omega$, using boundary estimates and in particular boundary Harnack inequalities for the operator $\mathcal{L}_{\mathcal{K}}\left(\mathcal{L}_{\mathcal{P}}\right)$. In the case of $\mathcal{L}_{\mathcal{K}}$ the latter results are established in [Litsgård and Nyström 2022]; however, the relevant results in that work hold for more general operators

$$
\nabla_{X} \cdot\left(A(X, Y, t) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t}
$$

and in the more general class of domains

$$
\left\{(X, Y, t)=\left(x, x_{m}, y, y_{m}, t\right) \in \mathbb{R}^{2 m+1}: x_{m}>\tilde{\psi}(x, y, t)\right\}
$$

In particular, in [Litsgård and Nyström 2022] we allow for ( $Y, t$ )-dependent coefficients and domains. Therefore, one can repeat the analysis of this paper, taking any result concerning the solvability of the $L^{p}$ Dirichlet problem for parabolic operators

$$
\nabla_{X} \cdot\left(A(X, t) \nabla_{X}\right)-\partial_{t},
$$

in $\operatorname{Lip}\left(1, \frac{1}{2}\right)$ domains, as the point of departure. The results are the corresponding results for the operator

$$
\nabla_{X} \cdot\left(A(X, t) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t}
$$

in $Y$-independent Lipschitz-type domains. Similarly, focusing only on $\mathcal{L}_{\mathcal{E}}$ and $\mathcal{L}_{\mathcal{P}}$, one can replace $\Omega \subset \mathbb{R}^{m}$ by an NTA-domain in the sense of [Jerison and Kenig 1982], having an ( $m-1$ )-dimensional Ahlfors-regular boundary in the sense of [David and Semmes 1991; 1993]; see also [David and Jerison 1990].

The rest of the paper is organized as follows. In Section 2, which is of more preliminary nature, we introduce notation and state definitions including the notion of weak solutions. In this section we also discuss the Dirichlet problem, see Theorem 2.1, and we point out that in Theorems 1.3 and 1.4 in [Litsgård and Nyström 2021] we simply missed stating the obvious restriction $u \in L^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ under which the proofs there are given. With this clarification, Theorem 2.1 is a special case of Theorem 1.4 in [Litsgård and Nyström 2021]. In Section 3 we state our structural theorems: Theorems 3.1, 3.2 and 3.3. In Section 4 we state a number of lemmas concerning the interior regularity of weak solutions and concerning the boundary behavior of nonnegative solutions to $\mathcal{L}_{\mathcal{K}} u=0$; the latter were recently established in [Litsgård and Nyström 2022]. In Section 5 we prove Theorems 3.1 and 3.2. In Section 6 we prove Theorem 3.3 and hence, as outlined above and as a consequence, we prove Theorems 1.1 and 1.2. In Section 7 we also give, as we believe that the argument may be of independent interest in the case of operators of Kolmogorov type, a proof of Theorem 1.1 using Rellich-type inequalities along the proof of the corresponding result for the heat equation in [Fabes and Salsa 1983]. In Section 8 we apply our findings to homogenization, giving new results for homogenization of operators of Kolmogorov type, and in particular we prove Theorem 1.3.

## 2. Preliminaries

2A. Group law and metric. The natural family of dilations jointly for the operators $\mathcal{L}_{\mathcal{E}}, \mathcal{L}_{\mathcal{P}}, \mathcal{L}_{\mathcal{K}},\left(\delta_{r}\right)_{r>0}$, on $\mathbb{R}^{N+1}, N:=2 m$, is defined by

$$
\begin{equation*}
\delta_{r}(X, Y, t)=\left(r X, r^{3} Y, r^{2} t\right) \tag{2-1}
\end{equation*}
$$

for $(X, Y, t) \in \mathbb{R}^{N+1}, r>0$. Furthermore, the classes of operators $\mathcal{L}_{\mathcal{E}}, \mathcal{L}_{\mathcal{P}}, \mathcal{L}_{\mathcal{K}}$ are closed under the group law

$$
\begin{equation*}
(\tilde{X}, \tilde{Y}, \tilde{t}) \circ(X, Y, t)=(\widetilde{X}+X, \tilde{Y}+Y-t \tilde{X}, \tilde{t}+t) \tag{2-2}
\end{equation*}
$$

where $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$. Note that

$$
\begin{equation*}
(X, Y, t)^{-1}=(-X,-Y-t X,-t) \tag{2-3}
\end{equation*}
$$

and hence

$$
\begin{equation*}
(\tilde{X}, \tilde{Y}, \tilde{t})^{-1} \circ(X, Y, t)=(X-\widetilde{X}, Y-\widetilde{Y}+(t-\tilde{t}) \tilde{X}, t-\tilde{t}) \tag{2-4}
\end{equation*}
$$

whenever $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$.
Given $(X, Y, t) \in \mathbb{R}^{N+1}$ we let

$$
\begin{equation*}
\|(X, Y, t)\|:=|(X, Y)|+|t|^{1 / 2}, \quad|(X, Y)|:=|X|+|Y|^{1 / 3} \tag{2-5}
\end{equation*}
$$

We recall the following pseudotriangular inequalities: there exists a positive constant $c$ such that

$$
\begin{equation*}
\left\|(X, Y, t)^{-1}\right\| \leq c\|(X, Y, t)\|, \quad\|(X, Y, t) \circ(\tilde{X}, \tilde{Y}, \tilde{t})\| \leq c(\|(X, Y, t)\|+\|(\tilde{X}, \tilde{Y}, \tilde{t})\|), \tag{2-6}
\end{equation*}
$$

whenever $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$. Using (2-6) it follows immediately that

$$
\begin{equation*}
\left\|(\widetilde{X}, \tilde{Y}, \tilde{t})^{-1} \circ(X, Y, t)\right\| \leq c\left\|(X, Y, t)^{-1} \circ(\widetilde{X}, \tilde{Y}, \tilde{t})\right\|, \tag{2-7}
\end{equation*}
$$

whenever $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$. Let

$$
\begin{equation*}
d((X, Y, t),(\widetilde{X}, \widetilde{Y}, \tilde{t})):=\frac{1}{2}\left(\left\|(\widetilde{X}, \widetilde{Y}, \tilde{t})^{-1} \circ(X, Y, t)\right\|+\left\|(X, Y, t)^{-1} \circ(\tilde{X}, \tilde{Y}, \tilde{t})\right\|\right) . \tag{2-8}
\end{equation*}
$$

Using (2-7) it follows that

$$
\begin{equation*}
\left\|(\widetilde{X}, \tilde{Y}, \tilde{t})^{-1} \circ(X, Y, t)\right\| \approx d((X, Y, t),(\widetilde{X}, \widetilde{Y}, \tilde{t})) \approx\left\|(X, Y, t)^{-1} \circ(\tilde{X}, \tilde{Y}, \tilde{t})\right\|, \tag{2-9}
\end{equation*}
$$

with constants of comparison independent of $(X, Y, t),(\tilde{X}, \widetilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$. Again using (2-6) we also see that

$$
\begin{equation*}
d((X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t})) \leq c(d((X, Y, t),(\widehat{X}, \widehat{Y}, \hat{t}))+d((\widehat{X}, \widehat{Y}, \hat{t}),(\tilde{X}, \widetilde{Y}, \tilde{t}))), \tag{2-10}
\end{equation*}
$$

whenever $(X, Y, t),(\widehat{X}, \widehat{Y}, \hat{t}),(\widetilde{X}, \widetilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}$, and hence $d$ is a symmetric quasidistance. Based on $d$ we introduce the balls

$$
\begin{equation*}
\mathcal{B}_{r}(X, Y, t):=\left\{(\widetilde{X}, \widetilde{Y}, \tilde{t}) \in \mathbb{R}^{N+1}: d((\tilde{X}, \tilde{Y}, \tilde{t}),(X, Y, t))<r\right\} \tag{2-11}
\end{equation*}
$$

for $(X, Y, t) \in \mathbb{R}^{N+1}$ and $r>0$. The measure of the ball $\mathcal{B}_{r}(X, Y, t)$ is $\left|\mathcal{B}_{r}(X, Y, t)\right|=c(m) r^{q}$, where $\boldsymbol{q}:=4 m+2$.

2B. Surface cubes and reference points. Let $\Omega \subset \mathbb{R}^{m}, m \geq 2$, be an (unbounded) Lipschitz domain as defined in (1-1) and with constant $M$. Let

$$
\begin{equation*}
\Sigma:=\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}=\left\{\left(x, x_{m}, y, y_{m}, t\right) \in \mathbb{R}^{N+1}: x_{m}=\psi(x)\right\} . \tag{2-12}
\end{equation*}
$$

An observation is that ( $\Sigma, d, \mathrm{~d} \sigma_{\mathcal{K}}$ ) is a space of homogeneous type in the sense of [Coifman and Weiss 1971], with homogeneous dimension $\boldsymbol{q}-1$. Furthermore, $\left(\mathbb{R}^{N+1}, d, \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)$ is also a space of homogeneous type in the sense of [Coifman and Weiss 1971], but with homogeneous dimension $\boldsymbol{q}$.

Let

$$
Q:=(-1,1)^{m} \times(-1,1)^{m} \times(-1,1)
$$

and

$$
Q_{r}=\delta_{r} Q:=\left\{\left(r X, r^{3} Y, r^{2} t\right):(X, Y, t) \in Q\right\}
$$

Given a point $\left(X_{0}, Y_{0}, t_{0}\right) \in \mathbb{R}^{N+1}$ we let

$$
Q_{r}\left(X_{0}, Y_{0}, t_{0}\right):=\left(X_{0}, Y_{0}, t_{0}\right) \circ Q_{r}:=\left\{\left(X_{0}, Y_{0}, t_{0}\right) \circ(X, Y, t):(X, Y, t) \in Q_{r}\right\} .
$$

Furthermore, if $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ then we set

$$
\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right):=\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{r}\left(X_{0}, Y_{0}, t_{0}\right) .
$$

We will frequently, and for brevity, write $Q_{r}$ and $\Delta_{r}$ for $Q_{r}\left(X_{0}, Y_{0}, t_{0}\right)$ and $\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right)$ whenever the point $\left(X_{0}, Y_{0}, t_{0}\right)$ is clear from the context. At instances we will simply also write $\Delta$ for $\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right)$ whenever the point $\left(X_{0}, Y_{0}, t_{0}\right)$ and the scale $r$ do not have to be stated explicitly. Given a positive constant $c, c \Delta:=\Delta_{c r}\left(X_{0}, Y_{0}, t_{0}\right)$.

Given $\varrho>0$ and $\Lambda>0$, we let

$$
\begin{align*}
& A_{\varrho, \Lambda}^{+}:=\left(0, \Lambda \varrho, 0,-\frac{2}{3} \Lambda \varrho^{3}, \varrho^{2}\right) \in \mathbb{R}^{m-1} \times \mathbb{R} \times \mathbb{R}^{m-1} \times \mathbb{R} \times \mathbb{R}  \tag{2-13}\\
& A_{\varrho, \Lambda}^{-}:=\left(0, \Lambda \varrho, 0, \frac{2}{3} \Lambda \varrho^{3},-\varrho^{2}\right) \in \mathbb{R}^{m-1} \times \mathbb{R} \times \mathbb{R}^{m-1} \times \mathbb{R} \times \mathbb{R}
\end{align*}
$$

and

$$
A_{\varrho, \Lambda}^{ \pm}\left(X_{0}, Y_{0}, t_{0}\right):=\left(X_{0}, Y_{0}, t_{0}\right) \circ A_{\varrho, \Lambda}^{ \pm}
$$

whenever $\left(X_{0}, Y_{0}, t_{0}\right) \in \mathbb{R}^{N+1}$. Furthermore, given $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right)$ we let

$$
A_{\Delta, \Lambda}^{ \pm}:=A_{r, \Lambda}^{ \pm}\left(X_{0}, Y_{0}, t_{0}\right) .
$$

2C. Qualitative assumptions on the coefficients. Central to our arguments are the boundary estimates recently proved in [Litsgård and Nyström 2022], where we considered solutions to the equation $\mathcal{L} u=0$, where $\mathcal{L}$ is the operator

$$
\begin{equation*}
\nabla_{X} \cdot\left(A(X, Y, t) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t} \tag{2-14}
\end{equation*}
$$

in $\mathbb{R}^{N+1}, N=2 m, m \geq 1,(X, Y, t):=\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}, t\right) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \times \mathbb{R}$. We assume that

$$
A=A(X, Y, t)=\left\{a_{i, j}(X, Y, t)\right\}_{i, j=1}^{m}
$$

is a real-valued, $m \times m$-dimensional, symmetric-matrix-valued function satisfying

$$
\begin{equation*}
\kappa^{-1}|\xi|^{2} \leq \sum_{i, j=1}^{m} a_{i, j}(X, Y, t) \xi_{i} \xi_{j}, \quad|A(X, Y, t) \xi \cdot \zeta| \leq \kappa|\xi||\zeta| \tag{2-15}
\end{equation*}
$$

for some $\kappa \in[1, \infty)$, and for all $\xi, \zeta \in \mathbb{R}^{m},(X, Y, t) \in \mathbb{R}^{N+1}$. Throughout [Litsgård and Nyström 2022] we also assume that

$$
\begin{equation*}
A=A(X, Y, t) \equiv I_{m} \text { outside some arbitrary but fixed compact subset of } \mathbb{R}^{N+1} \tag{2-16}
\end{equation*}
$$

and that

$$
\begin{equation*}
a_{i, j} \in C^{\infty}\left(\mathbb{R}^{N+1}\right) \tag{2-17}
\end{equation*}
$$

for all $i, j \in\{1, \ldots, m\}$. In [Litsgård and Nyström 2022] the assumptions in (2-16) and (2-17) are only used in a qualitative fashion. In particular, from the perspective of the operator, the constants of the quantitative estimates in that work only depend on $m$ and $\kappa$. To be consistent with that paper, in (A1)-(A3) we have included the qualitative assumptions stated in (2-16), (2-17).

2D. Function spaces. Let $U_{X} \subset \mathbb{R}^{m}, U_{Y} \subset \mathbb{R}^{m}$ be bounded domains, i.e., bounded, open and connected sets in $\mathbb{R}^{m}$. Let $J \subset \mathbb{R}$ be an open and bounded interval. We denote by $H_{X}^{1}\left(U_{X}\right)$ the Sobolev space of functions $g \in L^{2}\left(U_{X}\right)$ whose distribution gradient in $U_{X}$ lies in $\left(L^{2}\left(U_{X}\right)\right)^{m}$, i.e.,

$$
H_{X}^{1}\left(U_{X}\right):=\left\{g \in L_{X}^{2}\left(U_{X}\right): \nabla_{X} g \in\left(L^{2}\left(U_{X}\right)\right)^{m}\right\}
$$

and we set

$$
\|g\|_{H_{X}^{1}\left(U_{X}\right)}:=\|g\|_{L^{2}\left(U_{X}\right)}+\| \| \nabla_{X} g \|_{L^{2}\left(U_{X}\right)}, \quad g \in H_{X}^{1}\left(U_{X}\right)
$$

We let $H_{X, 0}^{1}\left(U_{X}\right)$ denote the closure of $C_{0}^{\infty}\left(U_{X}\right)$ in the norm of $H_{X}^{1}\left(U_{X}\right)$. If $U_{X}$ is a bounded Lipschitz domain, then $C^{\infty}\left(\bar{U}_{X}\right)$ is dense in $H_{X}^{1}\left(U_{X}\right)$. In particular, equivalently we could define $H_{X}^{1}\left(U_{X}\right)$ as the closure of $C^{\infty}\left(\bar{U}_{X}\right)$ in the norm $\|\cdot\|_{H_{X}^{1}\left(U_{X}\right)}$. We let $H_{X}^{-1}\left(U_{X}\right)$ denote the dual to $H_{X}^{1}\left(U_{X}\right)$, whose elements act on functions in $H_{X, 0}^{1}\left(U_{X}\right)$ through the duality pairing $\langle\cdot, \cdot\rangle:=\langle\cdot, \cdot\rangle_{H_{X}^{-1}\left(U_{X}\right), H_{X, 0}^{1}\left(U_{X}\right)}$.

In analogy with the definition of $H_{X}^{1}\left(U_{X}\right)$, we let $W\left(U_{X} \times U_{Y} \times J\right)$ be the closure of $C^{\infty}\left(\overline{U_{X} \times U_{Y} \times J}\right)$ in the norm

$$
\begin{align*}
& \|u\|_{W\left(U_{X} \times U_{Y} \times J\right)} \\
& :=\|u\|_{L_{Y, t}^{2}\left(U_{Y} \times J, H^{1}\left(U_{X}\right)\right)}+\left\|\left(-X \cdot \nabla_{Y}+\partial_{t}\right) u\right\|_{L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{-1}\left(U_{X}\right)\right)} \\
& :=\left(\iint_{U_{Y} \times J}\|u(\cdot, Y, t)\|_{H_{X}^{1}\left(U_{X}\right)}^{2} \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2}+\left(\iint_{U_{Y} \times J}\left\|\left(-X \cdot \nabla_{Y}+\partial_{t}\right) u(\cdot, Y, t)\right\|_{H_{X}^{-1}\left(U_{X}\right)}^{2} \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2} \tag{2-18}
\end{align*}
$$

In particular, $W\left(U_{X} \times U_{Y} \times J\right)$ is a Banach space and $u \in W\left(U_{X} \times U_{Y} \times J\right)$ if and only if

$$
\begin{equation*}
u \in L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{1}\left(U_{X}\right)\right) \quad \text { and } \quad\left(-X \cdot \nabla_{Y}+\partial_{t}\right) u \in L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{-1}\left(U_{X}\right)\right) \tag{2-19}
\end{equation*}
$$

Let $\Omega \subset \mathbb{R}^{m}, m \geq 2$, be an (unbounded) Lipschitz domain as defined in (1-1) and with constant $M$. We say that $u \in W_{\text {loc }}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ if $u \in W\left(U_{X} \times U_{Y} \times J\right)$ whenever $U_{X} \subset \mathbb{R}^{m}, U_{Y} \subset \mathbb{R}^{m}$ are bounded domains, $J \subset \mathbb{R}$ is an open and bounded interval, and $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. 2E. Weak solutions. Let $U_{X}, U_{Y}$ and $J$ be as introduced in the previous subsection. We say that $u$ is a weak solution to

$$
\begin{equation*}
\mathcal{L}_{\mathcal{K}} u=0 \quad \text { in } U_{X} \times U_{Y} \times J \tag{2-20}
\end{equation*}
$$

if $u \in W\left(U_{X} \times U_{Y} \times J\right)$ and if

$$
\begin{equation*}
0=\iiint_{U_{X} \times U_{Y} \times J} A(X) \nabla_{X} u \cdot \nabla_{X} \phi \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t+\iint_{U_{Y} \times J}\left\langle\left(-X \cdot \nabla_{Y}+\partial_{t}\right) u(\cdot, Y, t), \phi(\cdot, Y, t)\right\rangle \mathrm{d} Y \mathrm{~d} t \tag{2-21}
\end{equation*}
$$

for all $\phi \in L_{Y, t}^{2}\left(U_{Y} \times J, H_{X, 0}^{1}\left(U_{X}\right)\right)$. Here, again, $\langle\cdot, \cdot\rangle=\langle\cdot, \cdot\rangle_{H_{X}^{-1}\left(U_{X}\right), H_{X, 0}^{1}\left(U_{X}\right)}$ is the duality pairing between $H_{X}^{-1}\left(U_{X}\right)$ and $H_{X, 0}^{1}\left(U_{X}\right)$.
Definition. Let $\Omega \subset \mathbb{R}^{m}, m \geq 2$, be an (unbounded) Lipschitz domain as defined in (1-1) and with constant $M$. We say that $u$ is a weak solution to

$$
\begin{equation*}
\mathcal{L}_{\mathcal{K}} u=0 \quad \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R} \tag{2-22}
\end{equation*}
$$

if $u \in W_{\mathrm{loc}}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ and if $u$ satisfies (2-21), whenever $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$.

Note that if $u$ is a weak solution to the equation $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, then it is a weak solution in the sense of distributions, i.e.,

$$
\begin{equation*}
\iiint\left(A(X) \nabla_{X} u \cdot \nabla_{X} \phi-u\left(-X \cdot \nabla_{Y}+\partial_{t}\right) \phi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t=0 \tag{2-23}
\end{equation*}
$$

whenever $\phi \in C_{0}^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$.

2F. The Dirichlet problem and associated boundary measures. In [Litsgård and Nyström 2021] we conducted a study of the existence and uniqueness of weak solutions to

$$
\nabla_{X} \cdot\left(A(X, Y, t) \nabla_{X} u\right)+X \cdot \nabla_{Y} u-\partial_{t} u=0,
$$

as well as the existence and uniqueness of weak solutions to the Dirichlet problem with continuous boundary data. In [Litsgård and Nyström 2021], Theorems 1.2, 1.3, and 1.4, are particularly relevant to this paper. Theorem 1.2 in [loc. cit.] concerns the existence of weak solutions to (2-24). However, in [loc. cit.] a stronger notion of weak solutions is used, see Definition 2 there, as we there demand certain Sobolev regularity up to the boundary of $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Theorem 1.3 in [loc. cit.] concerns the uniqueness of weak solutions to (2-24) and in Theorem 1.4 in [loc. cit.] we consider the continuous Dirichlet problem and the representation of the solution using associated parabolic measures. We here state the following consequence of these results.
Theorem 2.1. Assume that A satisfies (1-2) and (2-16). Let $f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Then there exists $u \in C\left(\bar{\Omega} \times \mathbb{R}^{m} \times \mathbb{R}\right)$ such that $u=u_{f}$ is a weak solution to the Dirichlet problem

$$
\left\{\begin{align*}
\mathcal{L}_{\mathcal{K}} u=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}  \tag{2-24}\\
u=f & \text { on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{align*}\right.
$$

in the sense of the Definition on page 1555. If $u$ is bounded, then $u=u_{f}$ is the unique weak solution to (2-24) and in this case there exists, for every $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, a unique probability measure $\omega_{\mathcal{K}}(X, Y, t, \cdot)$ on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ such that

$$
\begin{equation*}
u(X, Y, t)=\iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \omega_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) \tag{2-25}
\end{equation*}
$$

Proof. As stated above, the notion of weak solutions introduced in the Definition on page 1555 is weaker than the notion of weak solutions introduced in Definition 2 in [Litsgård and Nyström 2021]. In particular, concerning the existence part of Theorem 2.1, Theorems 1.2-1.4 in that work give a stronger result. Concerning uniqueness and Theorems 1.3 and 1.4 of that work, an important piece of information is neglected in the statements of these two theorems. As can be seen from the proofs of Theorems 1.3 and 1.4 there, this information concerns the fact that in the unbounded setting $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ we need a condition at infinity to ensure uniqueness, and what we prove is the uniqueness of bounded weak solutions. In particular, in Theorem 1.3 it should be stated that $g \in W\left(\mathbb{R}^{N+1}\right) \cap L^{\infty}\left(\mathbb{R}^{N+1}\right)$ and that $u$ is unique if $u \in L^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Similarly, in Theorem 1.4 it should be stated that $u$ is unique if $u \in L^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. In Theorems 1.3 and 1.4 we simply missed stating the obvious restriction $u \in L^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ under which the proofs in that work are given. With this clarification, Theorem 2.1 is a special case of Theorem 1.4 in [Litsgård and Nyström 2021].

The measure $\omega_{\mathcal{K}}(X, Y, t, E)$ introduced in Theorem 2.1 is referred to as the parabolic measure, or Kolmogorov measure to distinguish it from the parabolic measure associated to $\mathcal{L}_{\mathcal{P}}$, associated to $\mathcal{L}_{\mathcal{K}}$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, at $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and of $E \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Properties of $\omega_{\mathcal{K}}(X, Y, t, \cdot)$ govern the Dirichlet problem in (2-24). The corresponding elliptic and parabolic measures on $\partial \Omega$ and $\partial \Omega \times \mathbb{R}$, $\omega_{\mathcal{E}}$ and $\omega_{\mathcal{P}}$, are introduced analogously.

2G. The nontangential maximal operator. Given an (unbounded) Lipschitz domain $\Omega \subset \mathbb{R}^{m}$ with constant $M$,

$$
\left(X_{0}, Y_{0}, t_{0}\right)=\left(\left(x_{0}, \psi\left(x_{0}\right)\right), Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
$$

and $\eta>0$, we introduce the (nontangential) cone

$$
\begin{equation*}
\Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right):=\left\{(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}: d\left((X, Y, t),\left(X_{0}, Y_{0}, t_{0}\right)\right)<\eta\left|x_{m}-\psi\left(x_{0}\right)\right|\right\} \tag{2-26}
\end{equation*}
$$

Given a function $u$ defined in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ we consider the nontangential maximal operator

$$
\begin{equation*}
N^{\eta}(u)\left(X_{0}, Y_{0}, t_{0}\right):=\sup _{(X, Y, t) \in \Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)}|u(X, Y, t)| . \tag{2-27}
\end{equation*}
$$

If $f$ is defined on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, then we say that $u\left(X_{0}, Y_{0}, t_{0}\right)=$ $f\left(X_{0}, Y_{0}, t_{0}\right)$ nontangentially (n.t.) if

$$
\lim _{\substack{(X, Y, t) \in \Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right) \\(X, Y, t) \rightarrow\left(X_{0}, Y_{0}, t_{0}\right)}} u(X, Y, t)=f\left(X_{0}, Y_{0}, t_{0}\right),
$$

where $\eta=\eta(M)$ is chosen so that $\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap \Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)=\left\{\left(X_{0}, Y_{0}, t_{0}\right)\right\}$. With this choice of $\eta$ we simply write $N(u)$ for $N^{\eta}(u)$. Furthermore, given $\delta>0$ we introduce the truncated cone

$$
\begin{equation*}
\Gamma_{\delta}^{\eta}\left(X_{0}, Y_{0}, t_{0}\right):=\Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right) \cap \mathcal{B}_{\delta}\left(X_{0}, Y_{0}, t_{0}\right) \tag{2-28}
\end{equation*}
$$

and the truncated nontangential maximal operator

$$
\begin{equation*}
N_{\delta}^{\eta}(u)\left(X_{0}, Y_{0}, t_{0}\right):=\sup _{(X, Y, t) \in \Gamma_{\delta}^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)}|u(X, Y, t)| \tag{2-29}
\end{equation*}
$$

Again with $\eta$ fixed, we write $N_{\delta}(u)$ for $N_{\delta}^{\eta}(u)$. For more on nontangential maximal functions in the elliptic context we refer to [Kenig 1994].

2H. Conventions. Throughout the paper we will use following conventions. By $c$ we will, if not otherwise stated, denote a constant satisfying $1 \leq c<\infty$. We write $c_{1} \lesssim c_{2}$ if $c_{1} / c_{2}$ is bounded from above by a positive constant depending only on $m, \kappa$, and $M$, if not otherwise stated. We write $c_{1} \approx c_{2}$ if $c_{1} \lesssim c_{2}$ and $c_{2} \lesssim c_{1}$.

Given a point $(X, Y, t) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \times \mathbb{R}$, we let $\pi_{X}(X, Y, t):=X, \pi_{X, t}(X, Y, t):=(X, t)$. Similarly, if $\Delta \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, then we let $\pi_{X}(\Delta)$ denote the projection of $\Delta$ onto the $X$-coordinate, we let $\pi_{X, t}(\Delta)$ denote the projection of $\Delta$ onto the ( $X, t$ )-coordinates.

## 3. Statements of the structural theorems

Our structural theorems concern the quantitative relations between the measures $\omega_{\mathcal{E}}, \omega_{\mathcal{P}}, \omega_{\mathcal{K}}$ and the (physical) measures $\sigma_{\mathcal{E}}, \sigma_{\mathcal{P}}, \sigma_{\mathcal{K}}$. We first prove the following relations between the measures.

Theorem 3.1. Assume (A1)-(A3). Let $\omega_{\mathcal{E}}, \omega_{\mathcal{P}}$, and $\omega_{\mathcal{K}}$ be the elliptic, parabolic and Kolmogorov measures associated to $\mathcal{L}_{\mathcal{E}}, \mathcal{L}_{\mathcal{P}}, \mathcal{L}_{\mathcal{K}}$ in $\Omega, \Omega \times \mathbb{R}$ and $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, respectively. Then there exist
$\Lambda=\Lambda(m, M), 1 \leq \Lambda<\infty$ and $c=c(m, \kappa, M), 1 \leq c<\infty$ such that the following is true. Consider $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Then
$\frac{\sigma_{\mathcal{K}}(\Delta) \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)}{\sigma_{\mathcal{K}}(\tilde{\Delta})} \approx \frac{\sigma_{\mathcal{P}}\left(\pi_{X, t}(\Delta)\right) \omega_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X, t}(\tilde{\Delta})\right)}{\sigma_{\mathcal{P}}\left(\pi_{X, t}(\tilde{\Delta})\right)} \approx \frac{\sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right) \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}(\tilde{\Delta})\right)}{\sigma_{\mathcal{E}}\left(\pi_{X}(\tilde{\Delta})\right)}$,
whenever $\tilde{\Delta} \subset \Delta$.
Theorem 3.1 states that the measures $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right), \omega_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right), \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right)$ are all comparable in the sense stated when evaluated on the surface cube $\tilde{\Delta} \subset \Delta$. As we will prove, if $\tilde{\Delta}=\Delta_{\tilde{r}}$ and if

$$
\begin{equation*}
\lim _{\tilde{r} \rightarrow 0} \frac{\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(\Delta_{\tilde{r}}\right)\right)}{\sigma_{\mathcal{E}}\left(\pi_{X}\left(\Delta_{\tilde{r}}\right)\right)} \tag{3-1}
\end{equation*}
$$

exists, then also the limits

$$
\begin{equation*}
\lim _{\tilde{r} \rightarrow 0} \frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta_{\tilde{r}}\right)}{\sigma_{\mathcal{K}}\left(\Delta_{\tilde{r}}\right)} \quad \text { and } \quad \lim _{\tilde{r} \rightarrow 0} \frac{\omega_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X, t}\left(\Delta_{\tilde{r}}\right)\right)}{\sigma_{\mathcal{P}}\left(\pi_{X, t}\left(\Delta_{\tilde{r}}\right)\right)} \tag{3-2}
\end{equation*}
$$

exist and all limits are comparable in the sense of Theorem 3.1. Indeed, using (3-1) we will be able to deduce that the Poisson kernels

$$
\begin{aligned}
K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right) & :=\frac{\mathrm{d} \omega_{\mathcal{E}}}{\mathrm{d} \sigma_{\mathcal{E}}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right), \\
K_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right) & :=\frac{\mathrm{d} \omega_{\mathcal{P}}}{\mathrm{d} \sigma_{\mathcal{P}}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right), \\
K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) & :=\frac{\mathrm{d} \omega_{\mathcal{K}}}{\mathrm{d} \sigma_{\mathcal{K}}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)
\end{aligned}
$$

are all well-defined on $\Delta$ and that

$$
\begin{aligned}
\sigma_{\mathcal{K}}(\Delta) K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) & \approx \sigma_{\mathcal{P}}\left(\pi_{X, t}(\Delta)\right) K_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right) \\
& \approx \sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right) K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right)
\end{aligned}
$$

whenever $(X, Y, t) \in \Delta$.
Given $q, 1<q<\infty$, we say that $K_{\mathcal{E}}(X):=K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right) \in B_{q}\left(\pi_{X}(\Delta), \mathrm{d} \sigma_{\mathcal{E}}\right)$ with constant $\Gamma$, $1 \leq \Gamma<\infty$, if

$$
\begin{equation*}
\left(f_{\pi_{X}(\tilde{\Delta})}\left|K_{\mathcal{E}}(X)\right|^{q} \mathrm{~d} \sigma_{\mathcal{E}}(X)\right)^{1 / q} \leq \Gamma\left(f_{\pi_{X}(\tilde{\Delta})}\left|K_{\mathcal{E}}(X)\right| \mathrm{d} \sigma_{\mathcal{E}}(X)\right) \tag{3-3}
\end{equation*}
$$

for all $\tilde{\Delta} \subset \Delta$. Analogously, $K_{\mathcal{P}}(X, t):=K_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right) \in B_{q}\left(\pi_{X, t}(\Delta), \mathrm{d} \sigma_{\mathcal{P}}\right)$ and $K_{\mathcal{K}}(X, Y, t):=$ $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) \in B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)$, with constant $\Gamma$, if

$$
\begin{gather*}
\left(\iint_{\pi_{X, t}(\tilde{\Delta})}\left|K_{\mathcal{P}}(X, t)\right|^{q} \mathrm{~d} \sigma_{\mathcal{P}}(X, t)\right)^{1 / q} \leq \Gamma\left(\iint_{\pi_{X, t}(\tilde{\Delta})}\left|K_{\mathcal{P}}(X, t)\right| \mathrm{d} \sigma_{\mathcal{P}}(X, t)\right), \\
\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}(X, Y, t)\right|^{q} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / q} \leq \Gamma\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}(X, Y, t)\right| \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)\right), \tag{3-4}
\end{gather*}
$$

respectively, for all $\tilde{\Delta} \subset \Delta$.

We can now state our second main result.
Theorem 3.2. Assume (A1)-(A3). Let $\omega_{\mathcal{E}}, \omega_{\mathcal{P}}$, and $\omega_{\mathcal{K}}$ be as in the statement of Theorem 3.1. Then there exist $\Lambda=\Lambda(m, M), 1 \leq \Lambda<\infty$ and $c=c(m, \kappa, M), 1 \leq c<\infty$, such that the following is true. Consider $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Assume that $\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right)$ is mutually absolutely continuous on $\pi_{X}(\Delta)$ with respect to $\sigma_{\mathcal{E}}$ and that the associated Poisson kernel $K_{\mathcal{E}}(X):=K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right)$ satisfies

$$
K_{\mathcal{E}} \in B_{q}\left(\pi_{X}(\Delta), \mathrm{d} \sigma_{\mathcal{E}}\right)
$$

for some $q, 1<q<\infty$, and with constant $\Gamma, 1 \leq \Gamma<\infty$. Then $\omega_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right)$ and $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ are mutually absolutely continuous on $\pi_{X, t}(\Delta)$ and $\Delta$ with respect to $\sigma_{\mathcal{P}}$ and $\sigma_{\mathcal{K}}$, respectively, and the associated Poisson kernels $K_{\mathcal{P}}(X, t):=K_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right)$ and $K_{\mathcal{K}}(X, Y, t):=K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)$ satisfy

$$
K_{\mathcal{P}} \in B_{q}\left(\pi_{X, t}(\Delta), \mathrm{d} \sigma_{\mathcal{P}}\right), \quad K_{\mathcal{K}} \in B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)
$$

with constant $\widetilde{\Gamma}=\widetilde{\Gamma}(m, \kappa, M, \Gamma)$.
We also prove the following theorem.
Theorem 3.3. Assume (A1)-(A3). Let $p \in(1, \infty)$ be given and let $q$ denote the index dual to $p$. Assume that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is mutually absolutely continuous on $\Delta$ with respect to $\sigma_{\mathcal{K}}$ for all $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset$ $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Then the following statements are equivalent:
(i) $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot, \cdot, \cdot\right) \in B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)$ for all $\Delta \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, with a uniform constant $\Gamma$.
(ii) $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is solvable.

Furthermore, if $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is solvable then it is uniquely solvable.

## 4. Local regularity and boundary estimates

In this section we state a number of the lemmas concerning the interior regularity of weak solution and the boundary behavior of nonnegative solutions. The boundary estimates are proven in [Litsgård and Nyström 2022] for the more general operators stated in (2-14), assuming (2-15), (2-16) and (2-17). Concerning geometry, in that work we considered unbounded domains $\widetilde{\Omega} \subset \mathbb{R}^{N+1}$ of the form

$$
\begin{equation*}
\widetilde{\Omega}=\left\{(X, Y, t)=\left(x, x_{m}, y, y_{m}, t\right) \in \mathbb{R}^{N+1}: x_{m}>\tilde{\psi}\left(x, y, y_{m}, t\right)\right\}, \tag{4-1}
\end{equation*}
$$

imposing restrictions on $\tilde{\psi}$ of Lipschitz character accounting for the underlying non-Euclidean group structure. In particular, we also allowed for ( $Y, t$ )-dependent domains. Up to a point, the results in [Litsgård and Nyström 2022] are established allowing $A=A(X, Y, t)$ and $\tilde{\psi}=\tilde{\psi}\left(x, y, y_{m}, t\right)$ to depend on all variables with $y_{m}$ included. However, the more refined results established are derived assuming in addition that $A$ as well as $\psi$ are independent of the variable $y_{m}$. The reason for this is discussed in detail in that work. Obviously, the operators $\mathcal{L}_{\mathcal{K}}$ considered in this paper are, as $A=A(X)$, special cases of the more general operators of Kolmogorov type considered there. Also, the geometric setting of that work is more demanding compared to the domains considered in this paper, as $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ is a special case of the domains in (4-1).

Below we formulate the necessary auxiliary and boundary-type estimate results needed in our proofs, and in particular in the proofs of Theorems 3.1, 3.2 and 3.3, in the context of $\mathcal{L}_{\mathcal{K}}$ as these results follow from [Litsgård and Nyström 2022]. For the corresponding results for $\mathcal{L}_{\mathcal{E}}$ and $\mathcal{L}_{\mathcal{P}}$ we refer to [Kenig 1994] and [Fabes and Safonov 1997; Fabes et al. 1986; 1999; Nyström 1997], respectively.

4A. Energy estimates and local regularity. Consider $\left(X_{0}, Y_{0}, t_{0}\right) \subset \mathbb{R}^{N+1}$. In the following we will frequently use the notation $Q_{\varrho}:=Q_{\varrho}\left(X_{0}, Y_{0}, t_{0}\right)$ for $\varrho>0$.

Lemma 4.1. Assume that $u$ is a weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $Q_{2 r}=Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \mathbb{R}^{N+1}$. Then

$$
\iiint_{Q_{r}}\left|\nabla_{X} u\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t \lesssim \frac{1}{r^{2}} \iiint_{Q_{2 r}}|u|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t
$$

Proof. This is an energy estimate that can be proven using standard arguments. We refer to [Litsgård and Nyström 2022] for further details.

The following two lemmas are proved in [Golse et al. 2019].
Lemma 4.2. Assume that $u$ is a weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \mathbb{R}^{N+1}$. Given $p \in[1, \infty)$ there exists a constant $c=c(m, \kappa, p), 1 \leq c<\infty$ such that

$$
\begin{equation*}
\sup _{Q_{r}}|u| \leq c\left(\iiint_{Q_{2 r}}|u|^{p} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / p} \tag{4-2}
\end{equation*}
$$

Lemma 4.3. Assume that $u$ is a weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \mathbb{R}^{N+1}$. Then there exists $\alpha=\alpha(m, \kappa) \in(0,1)$ such that

$$
\begin{equation*}
|u(X, Y, t)-u(\tilde{X}, \tilde{Y}, \tilde{t})| \lesssim\left(\frac{d((X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}))}{r}\right)^{\alpha} \sup _{Q_{2 r}}|u| \tag{4-3}
\end{equation*}
$$

whenever $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in Q_{r}\left(X_{0}, Y_{0}, t_{0}\right)$.
To state the Harnack inequality we introduce

$$
\begin{equation*}
Q_{r}^{-}\left(X_{0}, Y_{0}, t_{0}\right):=Q_{r}\left(X_{0}, Y_{0}, t_{0}\right) \cap\left\{(X, Y, t): t_{0}-r^{2}<t<t_{0}\right\} \tag{4-4}
\end{equation*}
$$

The following Harnack inequality is proved in [Golse et al. 2019].
Lemma 4.4. There exist constants $c=c(m, \kappa)>1$ and $\alpha, \beta, \gamma, \theta \in(0,1)$, with $0<\alpha<\beta<\gamma<\theta^{2}$, such that the following is true. Assume that $u$ is a nonnegative weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $Q_{r}^{-}\left(X_{0}, Y_{0}, t_{0}\right) \subset$ $\mathbb{R}^{N+1}$. Then,

$$
\sup _{\tilde{Q}_{r}^{-}\left(X_{0}, Y_{0}, t_{0}\right)} u \leq c \inf _{\tilde{Q}_{r}^{+}\left(X_{0}, Y_{0}, t_{0}\right)} u,
$$

where

$$
\begin{aligned}
& \widetilde{Q}_{r}^{+}\left(X_{0}, Y_{0}, t_{0}\right)=\left\{(X, Y, t) \in Q_{\theta r}^{-}\left(X_{0}, Y_{0}, t_{0}\right): t_{0}-\alpha r^{2} \leq t \leq t_{0}\right\} \\
& \widetilde{Q}_{r}^{-}\left(X_{0}, Y_{0}, t_{0}\right)=\left\{(X, Y, t) \in Q_{\theta r}^{-}\left(X_{0}, Y_{0}, t_{0}\right): t_{0}-\gamma r^{2} \leq t \leq t_{0}-\beta r^{2}\right\}
\end{aligned}
$$

Remark. Note that the constants $\alpha, \beta, \gamma, \theta$ appearing in Lemma 4.4 cannot be chosen arbitrarily.

4B. Estimates for (nonnegative) solutions. We refer to [Litsgård and Nyström 2022] for the proofs of the following results.

Lemma 4.5. Assume (A1)-(A3). Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $r>0$. Let u be a weak solution of $\mathcal{L}_{\mathcal{K}} u=0$ in $\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$, vanishing continuously on $\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$. Then, there exists $\alpha=\alpha(m, \kappa, M) \in(0,1)$ such that

$$
\begin{equation*}
u(X, Y, t) \lesssim\left(\frac{d\left((X, Y, t),\left(X_{0}, Y_{0}, t_{0}\right)\right)}{r}\right)^{\alpha} \sup _{\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)} u \tag{4-5}
\end{equation*}
$$

whenever $(X, Y, t) \in\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{r / c}\left(X_{0}, Y_{0}, t_{0}\right)$.
Lemma 4.6. Let $\Omega$ and $A$ be as in Lemma 4.5. There exist $\Lambda=\Lambda(m, M), c=c(m, \kappa, M)$, and $\gamma=\gamma(m, \kappa, M), 0<\gamma<\infty$, such that the following holds. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $r>0$. Assume that $u$ is a nonnegative weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$. Then

$$
\begin{align*}
& u(X, Y, t) \lesssim(\varrho / d)^{\gamma} u\left(A_{\varrho, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right),  \tag{4-6}\\
& u(X, Y, t) \gtrsim(d / \varrho)^{\gamma} u\left(A_{\varrho, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right),
\end{align*}
$$

whenever $(X, Y, t) \in\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 \varrho / c}\left(X_{0}, Y_{0}, t_{0}\right), 0<\varrho<r / c$, where $d:=d\left((X, Y, t), \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Theorem 4.7. Let $\Omega$ and $A$ be as in Lemma 4.5. Then there exist $\Lambda=\Lambda(m, M)$ and $c=c(m, \kappa, M)$ such that the following holds. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $r>0$. Assume that $u$ is a nonnegative weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$, vanishing continuously on $\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap$ $Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$. Then

$$
u(X, Y, t) \lesssim u\left(A_{\varrho, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right)
$$

whenever $(X, Y, t) \in\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 \varrho / c}\left(X_{0}, Y_{0}, t_{0}\right), 0<\varrho<r / c$.
Theorem 4.8. Let $\Omega$ and $A$ be as in Lemma 4.5. Then there exist $\Lambda=\Lambda(m, M)$ and $c=c(m, \kappa, M)$ such that the following holds. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $r>0$. Assume that $u$ and $v$ are nonnegative weak solutions to $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, vanishing continuously on $\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{2 r}\left(X_{0}, Y_{0}, t_{0}\right)$. Let $\varrho_{0}=r / c$,

$$
\begin{array}{ll}
m_{1}^{+}=v\left(A_{\varrho_{0}, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right), & m_{1}^{-}=v\left(A_{\varrho_{0}, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right)  \tag{4-7}\\
m_{2}^{+}=u\left(A_{\varrho_{0}, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right), & m_{2}^{-}=u\left(A_{\varrho_{0}, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right)
\end{array}
$$

and assume $m_{1}^{-}>0, m_{2}^{-}>0$. Then there exist constants $c_{1}=c_{1}(m, M)$ and

$$
c_{2}=c_{2}\left(m, \kappa, M, m_{1}^{+} / m_{1}^{-}, m_{2}^{+} / m_{2}^{-}\right)
$$

$1 \leq c_{1}, c_{2}<\infty$, such that if we let $\varrho_{1}=\varrho_{0} / c_{1}$, then

$$
c_{2}^{-1} \frac{v\left(A_{\varrho, \Lambda}\left(\widetilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right)\right)}{u\left(A_{\varrho, \Lambda}\left(\widetilde{X}_{0}, \widetilde{Y}_{0}, \tilde{t}_{0}\right)\right)} \leq \frac{v(X, Y, t)}{u(X, Y, t)} \leq c_{2} \frac{v\left(A_{\varrho, \Lambda}\left(\tilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right)\right)}{u\left(A_{\varrho, \Lambda}\left(\widetilde{X}_{0}, \widetilde{Y}_{0}, \tilde{t}_{0}\right)\right)}
$$

whenever $(X, Y, t) \in\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{\varrho / c_{1}}\left(\tilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right)$ for some $0<\varrho<\varrho_{1}$ and $\left(\tilde{X}_{0}, \widetilde{Y}_{0}, \tilde{t}_{0}\right) \in$ $\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{\varrho_{1}}\left(X_{0}, Y_{0}, t_{0}\right)$.

4C. Estimates of Green's functions and parabolic measures. The adjoint operator of $\mathcal{L}_{\mathcal{K}}$ is defined as

$$
\begin{equation*}
\mathcal{L}_{\mathcal{K}}^{*}:=\nabla_{X} \cdot\left(A(X) \nabla_{X}\right)-X \cdot \nabla_{Y}+\partial_{t}, \tag{4-8}
\end{equation*}
$$

as $A$ is assumed to be symmetric.
Remark. We remark that for nonnegative weak solutions to the adjoint equation $\mathcal{L}_{\mathcal{K}}^{*} u=0$, adjoint versions of Lemma 4.6, Theorem 4.7, and Theorem 4.8 hold. The statements in the adjoint versions are the same, except that the roles of $A_{\varrho, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)$ and $A_{\varrho, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)$ are reversed.
Definition. A fundamental solution for $\mathcal{L}_{\mathcal{K}}$ is a continuous and positive function $\Gamma_{\mathcal{K}}=\Gamma_{\mathcal{K}}(X, Y, t, \widetilde{X}, \tilde{Y}, \tilde{t})$, defined for $\tilde{t}<t$ and $(X, Y),(\tilde{X}, \tilde{Y}) \in \mathbb{R}^{N}$, such that
(i) $\Gamma_{\mathcal{K}}(\cdot, \cdot, \cdot, \widetilde{X}, \tilde{Y}, \tilde{t})$ is a weak solution of $\mathcal{L}_{\mathcal{K}} u=0$ in $\mathbb{R}^{N} \times(\tilde{t}, \infty)$ and $\Gamma_{\mathcal{K}}(X, Y, t, \cdot, \cdot, \cdot)$ is a weak solution of $\mathcal{L}_{\mathcal{K}}^{*} u=0$ in $\mathbb{R}^{N} \times(-\infty, t)$,
(ii) for any bounded function $\phi \in C\left(\mathbb{R}^{N}\right)$ and $(X, Y),(\tilde{X}, \tilde{Y}) \in \mathbb{R}^{N}$, we have

$$
\begin{equation*}
\lim _{\substack{(X, Y, t) \rightarrow(\widetilde{X}, \tilde{Y}, \tilde{t}) \\ t>\tilde{t}}} u(X, Y, t)=\phi(\tilde{X}, \tilde{Y}), \quad \lim _{\substack{(\widetilde{X}, \tilde{Y}, \tilde{t}) \rightarrow(X, Y, t) \\ t>\tilde{t}}} v(\tilde{X}, \tilde{Y}, \tilde{t})=\phi(X, Y), \tag{4-9}
\end{equation*}
$$

where

$$
\begin{align*}
u(X, Y, t) & :=\iint_{\mathbb{R}^{N}} \Gamma_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) \phi(\tilde{X}, \tilde{Y}) \mathrm{d} \tilde{X} \mathrm{~d} \tilde{Y} \\
v(\tilde{X}, \tilde{Y}, \tilde{t}) & :=\iint_{\mathbb{R}^{N}} \Gamma_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) \phi(X, Y) \mathrm{d} X \mathrm{~d} Y \tag{4-10}
\end{align*}
$$

Lemma 4.9. Assume that A satisfies (2-17). Then there exists a fundamental solution to $\mathcal{L}_{\mathcal{K}}$ in the sense of the Definition above. Let $\Gamma_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t})$ be the fundamental solution to $\mathcal{L}_{\mathcal{K}}$. Then we have the upper bound

$$
\begin{equation*}
\Gamma_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) \lesssim \frac{1}{d((X, Y, t),(\widetilde{X}, \tilde{Y}, \tilde{t}))^{q-2}} \tag{4-11}
\end{equation*}
$$

for all $(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t})$ with $t>\tilde{t}$.
Proof. We refer to [Delarue and Menozzi 2010; Di Francesco and Pascucci 2005; Polidoro 1997] for the existence of the fundamental solution for $\mathcal{L}$ under the additional condition that the coefficients are Hölder continuous. See also [Lanconelli et al. 2020]. For the quantitative estimate we refer to Lemma 4.17 in [Litsgård and Nyström 2022] and the subsequent discussion.

Assume that $\Omega \subset \mathbb{R}^{m}$ is an (unbounded) Lipschitz domain with constant $M$. We define the Green's function associated to $\mathcal{L}_{\mathcal{K}}$ for $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, with pole at $(\widehat{X}, \widehat{Y}, \hat{t}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, as

$$
\begin{align*}
& G_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t})=\Gamma_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t}) \\
&-\iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} \Gamma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t}, \widehat{X}, \widehat{Y}, \hat{t}) \mathrm{d} \omega_{\mathcal{K}}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}), \tag{4-12}
\end{align*}
$$

where $\Gamma_{\mathcal{K}}$ is the fundamental solution to the operator $\mathcal{L}_{\mathcal{K}}$. If we instead consider $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ as fixed, then, for $(\widehat{X}, \widehat{Y}, \hat{t}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$,

$$
\begin{align*}
& G_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t})=\Gamma_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t}) \\
&-\iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} \Gamma_{\mathcal{K}}(X, Y, t, \widetilde{X}, \widetilde{Y}, \tilde{t}) \mathrm{d} \omega_{\mathcal{K}}^{*}(\widehat{X}, \widehat{Y}, \hat{t}, \tilde{X}, \tilde{Y}, \tilde{t}), \tag{4-13}
\end{align*}
$$

where $\omega_{\mathcal{K}}^{*}(\widehat{X}, \widehat{Y}, \hat{t}, \cdot)$ is the associated adjoint Kolmogorov measure relative to $(\widehat{X}, \widehat{Y}, \hat{t})$ and $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. The corresponding Green's functions associated to $\mathcal{L}_{\mathcal{E}}$ and $\mathcal{L}_{\mathcal{P}}$, for $\Omega$ and $\Omega \times \mathbb{R}$, are denoted by $G_{\mathcal{E}}$ and $G_{\mathcal{P}}$, respectively.

Let $\theta \in C_{0}^{\infty}\left(\mathbb{R}^{N+1}\right)$. The following representation formulas are proved in Lemma 8.3 in [Litsgård and Nyström 2022]:

$$
\begin{align*}
\theta(\widehat{X}, \widehat{Y}, \hat{t})= & \iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} \theta(X, Y, t) \mathrm{d} \omega_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \\
& -\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} A(X) \nabla_{X} G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \cdot \nabla_{X} \theta(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& +\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)\left(X \cdot \nabla_{Y}-\partial_{t}\right) \theta(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
\theta(\widehat{X}, \widehat{Y}, \hat{t})= & \iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} \theta(X, Y, t) \mathrm{d} \omega_{\mathcal{K}}^{*}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)  \tag{4-14}\\
& -\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} A(X) \nabla_{X} G_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t}) \cdot \nabla_{X} \theta(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& +\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} G_{\mathcal{K}}(X, Y, t, \widehat{X}, \widehat{Y}, \hat{t})\left(-X \cdot \nabla_{Y}+\partial_{t}\right) \theta(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{align*}
$$

whenever $(\widehat{X}, \widehat{Y}, \hat{t}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$.
The following lemmas, Lemmas 4.10 and 4.11, are proved in [Litsgård and Nyström 2022]; see in particular Section 8. Theorem 4.12 stated below is one of the main results in that work.

Lemma 4.10. Let $\Omega$ and $A$ be as in Lemma 4.5. Then there exist $\Lambda=\Lambda(m, M), 1 \leq \Lambda<\infty, c=$ $c(m, \kappa, M), 1 \leq c<\infty$, such that the following is true. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, 0<\varrho<\infty$. Then

$$
\begin{aligned}
\varrho^{\boldsymbol{q - 2}} G_{\mathcal{K}}\left(X, Y, t, A_{\varrho, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right) & \lesssim \omega_{\mathcal{K}}\left(X, Y, t, \Delta_{\varrho}\left(X_{0}, Y_{0}, t_{0}\right)\right) \\
& \lesssim \varrho^{\boldsymbol{q}-2} G_{\mathcal{K}}\left(X, Y, t, A_{c \varrho, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right),
\end{aligned}
$$

whenever $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}, t \geq t_{0}+c \varrho^{2}$.
Lemma 4.11. Let $\Omega$ and $A$ be as in Lemma 4.5. Then there exist $\Lambda=\Lambda(m, M), 1 \leq \Lambda<\infty, c=$ $c(m, \kappa, M), 1 \leq c<\infty$, such that the following is true. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, 0<\varrho<\infty$. Then

$$
G_{\mathcal{K}}\left(X, Y, t, A_{\varrho, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right) \lesssim G_{\mathcal{K}}\left(X, Y, t, A_{\varrho, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right)\right) \lesssim G_{\mathcal{K}}\left(X, Y, t, A_{\varrho, \Lambda}^{-}\left(X_{0}, Y_{0}, t_{0}\right)\right)
$$

whenever $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}, t \geq t_{0}+c \varrho^{2}$.

Theorem 4.12. Let $\Omega$ and $A$ be as in Lemma 4.5. Then there exist $\Lambda=\Lambda(m, M), 1 \leq \Lambda<\infty$, $c=c(m, \kappa, M), 1 \leq c<\infty$, such that the following is true. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, 0<\varrho_{0}<\infty$. Then

$$
\omega_{\mathcal{K}}\left(A_{c \varrho_{0}, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right), \Delta_{2 \varrho}\left(\widetilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right)\right) \lesssim \omega_{\mathcal{K}}\left(A_{c \varrho_{0}, \Lambda}^{+}\left(X_{0}, Y_{0}, t_{0}\right), \Delta_{\varrho}\left(\tilde{X}_{0}, \widetilde{Y}_{0}, \tilde{t}_{0}\right)\right)
$$

for all $\Delta_{\varrho}\left(\tilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right),\left(\tilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ such that $\Delta_{\varrho}\left(\tilde{X}_{0}, \tilde{Y}_{0}, \tilde{t}_{0}\right) \subset \Delta_{4 \varrho_{0}}\left(X_{0}, Y_{0}, t_{0}\right)$.

## 5. Proof of the structural theorems: Theorems 3.1 and 3.2

The purpose of the section is to prove Theorems 3.1 and 3.2. Throughout the section we assume (A1)-(A3). Let $\omega_{\mathcal{E}}, \omega_{\mathcal{P}}$, and $\omega_{\mathcal{K}}$ be as in the statement of Theorem 3.1.

5A. Proof of Theorem 3.1. To prove Theorem 3.1 we need to prove that there exist $\Lambda=\Lambda(m, M)$, $1 \leq \Lambda<\infty, c=c(m, \kappa, M), 1 \leq c<\infty$, such that if $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, then the estimates stated in the theorems hold whenever $\tilde{\Delta} \subset \Delta$. The proof of Theorem 3.1 is based on the relation between $\omega_{\mathcal{E}}, \omega_{\mathcal{P}}, \omega_{\mathcal{K}}$ and the corresponding Green's functions and boundary Harnack inequalities.

To start the proof we first note that an immediate consequence of Lemma 4.10 is that there exists $c=c(m, \kappa, M), 1 \leq c<\infty$, such that given $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, we have

$$
\begin{equation*}
\tilde{r}^{\boldsymbol{q - 2}} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right) \lesssim \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right) \lesssim \tilde{r}^{\boldsymbol{q}-2} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right) \tag{5-1}
\end{equation*}
$$

whenever $\tilde{\Delta}=\Delta_{\tilde{r}} \subset \Delta$. Using this, and the corresponding results for $\mathcal{L}_{\mathcal{E}}$ and $\mathcal{L}_{\mathcal{P}}$, see [Kenig 1994] and [Fabes and Safonov 1997; Fabes et al. 1986; 1999; Nyström 1997], we obtain

$$
\begin{equation*}
\frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)} \lesssim \frac{\sigma_{\mathcal{K}}(\tilde{\Delta}) \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}(\tilde{\Delta})\right)}{\sigma_{\mathcal{E}}\left(\pi_{X}(\tilde{\Delta})\right) \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)} \lesssim \frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{c \tilde{\Delta}, \Lambda}^{-}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)} \tag{5-2}
\end{equation*}
$$

and

$$
\frac{G_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X, t}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)} \lesssim \frac{\sigma_{\mathcal{K}}(\tilde{\Delta}) \omega_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X, t}(\tilde{\Delta})\right)}{\sigma_{\mathcal{P}}\left(\pi_{X, t}(\tilde{\Delta})\right) \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)} \lesssim \frac{G_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X, t}\left(A_{c \tilde{\Delta}, \Lambda}^{-}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)}
$$

To this end we will now prove the theorem only for $\omega_{\mathcal{K}}$, the proof for $\omega_{\mathcal{P}}$ being analogous. We first relate $G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)$and $G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)$. Using that $G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot, \cdot, \cdot\right)$ solves the adjoint equation we can apply the adjoint version of Lemma 4.6 to conclude that

$$
\begin{array}{r}
G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right) \gtrsim G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{+}\right), \\
G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right) \gtrsim G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{-}\right) .
\end{array}
$$

Hence

$$
\begin{equation*}
\frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{+}\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)} \lesssim \frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)} \lesssim \frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{-}\right)} \tag{5-3}
\end{equation*}
$$

Therefore, applying Lemma 4.11 twice,

$$
\begin{equation*}
\frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \tilde{\Delta}, \Lambda}^{-}\right)} \approx 1 \tag{5-4}
\end{equation*}
$$

Furthermore, by the standard elliptic Harnack inequality

$$
\begin{equation*}
G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right) \approx G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{c \tilde{\Delta}, \Lambda}^{-}\right)\right) \tag{5-5}
\end{equation*}
$$

Putting (5-2)-(5-5) together we can conclude that

$$
\begin{equation*}
\frac{\sigma_{\mathcal{K}}(\tilde{\Delta}) \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}(\tilde{\Delta})\right)}{\sigma_{\mathcal{E}}\left(\pi_{X}(\tilde{\Delta})\right) \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)} \approx \frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)} \tag{5-6}
\end{equation*}
$$

Next, using Theorem 4.8

$$
\frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)} \approx \frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\Delta, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\Delta, \Lambda}^{+}\right)}
$$

Furthermore, $G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\Delta, \Lambda}^{+}\right)\right) \approx r^{-m} \approx\left(r \sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right)\right)^{-1}$ by classical estimates for the fundamental solution second-order elliptic equations in divergence form; see [Kenig 1994]. We claim that

$$
\begin{equation*}
G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\Delta, \Lambda}^{+}\right) \approx r^{2-q} \approx\left(r \sigma_{\mathcal{K}}(\Delta)\right)^{-1} \tag{5-7}
\end{equation*}
$$

To prove this we first note that the upper bound on $G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\Delta, \Lambda}^{+}\right)$follows from Lemma 4.9. The proof of the lower bound on $G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\Delta, \Lambda}^{+}\right)$is a bit more subtle but can be achieved analogously to the proof of the estimate in display (9.11) in [Litsgård and Nyström 2022]. Using (5-7), we deduce

$$
\frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\tilde{\Delta}, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\tilde{\Delta}, \Lambda}^{+}\right)} \approx \frac{G_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(A_{\Delta, \Lambda}^{+}\right)\right)}{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{\Delta, \Lambda}^{+}\right)} \approx \frac{\sigma_{\mathcal{K}}(\Delta)}{\sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right)}
$$

Combing this with (5-6),

$$
\frac{\sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right) \sigma_{\mathcal{K}}(\tilde{\Delta}) \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}(\tilde{\Delta})\right)}{\sigma_{\mathcal{K}}(\Delta) \sigma_{\mathcal{E}}\left(\pi_{X}(\tilde{\Delta})\right) \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)} \approx 1
$$

This proves Theorem 3.1.
5B. Proof of Theorem 3.2. Again we will only prove the theorem for $\omega_{\mathcal{K}}$, the proof for $\omega_{\mathcal{P}}$ being analogous. Assume that $\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right)$ is mutually absolutely continuous on $\pi_{X}(\Delta)$ with respect to $\sigma_{\mathcal{E}}$ and that the associated Poisson kernel $K_{\mathcal{E}}(X):=K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right)$ satisfies

$$
K_{\mathcal{E}} \in B_{q}\left(\pi_{X}(\Delta), \mathrm{d} \sigma_{\mathcal{E}}\right)
$$

for some $q, 1<q<\infty$, and with constant $\Gamma, 1 \leq \Gamma<\infty$. To prove Theorem 3.2 for $\omega_{\mathcal{K}}$ we have to prove that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is mutually absolutely continuous on $\Delta$ with respect to $\sigma_{\mathcal{K}}$, and that the $\underset{\sim}{\text { associated Poisson kernel }} K_{\mathcal{K}}(X, Y, t):=K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)$ satisfies $K_{\mathcal{K}} \in B_{q}\left(\Delta\right.$, d $\left.\sigma_{\mathcal{K}}\right)$ with a constant $\widetilde{\Gamma}=\widetilde{\Gamma}(m, \kappa, M, \Gamma)$.

Let $\mathrm{d} \mu_{\mathcal{K}}:=\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}(\cdot)\right) \mathrm{d} Y \mathrm{~d} t$. To prove that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is absolutely continuous on $\Delta$ with respect to $\sigma_{\mathcal{K}}$ it suffices to prove that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right) \ll \mu_{\mathcal{K}}$ on $\Delta$ and that $\mu_{\mathcal{K}} \ll \sigma_{\mathcal{K}}$ on $\Delta$. Recall that $\mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)=\mathrm{d} \sigma_{\mathcal{E}}(X) \mathrm{d} Y \mathrm{~d} t$. However, as $\mu_{\mathcal{K}}$ and $\sigma_{\mathcal{K}}$ are defined through the stated product structure, it follows immediately that $\mu_{\mathcal{K}} \ll \sigma_{\mathcal{K}}$ on $\Delta$ as $\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right) \ll \sigma_{\mathcal{E}}$ on $\pi_{X}(\Delta)$. In particular, by the assumptions it suffices to prove that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is absolutely continuous on $\Delta$ with respect to $\mu_{\mathcal{K}}$ and we will do this by using Theorem 3.1.

Recall that we previously observed that $\left(\Sigma, d, \mathrm{~d} \sigma_{\mathcal{K}}\right)$, where $\Sigma$ was introduced in (2-12), is a space of homogeneous type in the sense of [Coifman and Weiss 1971]. By the results in [Christ 1990] there exists what we here will refer to as a dyadic grid on $\Sigma$ having a number of important properties in relation to $d$. To formulate this we introduce, for any $(X, Y, t) \in \Sigma$ and $E \subset \Sigma$,

$$
\begin{equation*}
\operatorname{dist}((X, Y, t), E):=\inf \{d((X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t})):(\tilde{X}, \tilde{Y}, \tilde{t}) \in E\} \tag{5-8}
\end{equation*}
$$

and we let

$$
\begin{equation*}
\operatorname{diam}(E):=\sup \{d((X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t})):(X, Y, t),(\tilde{X}, \tilde{Y}, \tilde{t}) \in E\} \tag{5-9}
\end{equation*}
$$

Using [Christ 1990] we can conclude that there exist constants $\alpha>0, \beta>0$ and $c_{*}<\infty$ such that for each $k \in \mathbb{Z}$ there exists a collection of Borel sets, $\mathbb{D}_{k}$, which we will call cubes, such that

$$
\mathbb{D}_{k}:=\left\{Q_{j}^{k} \subset \Sigma: j \in \Im_{k}\right\}
$$

where $\mathfrak{I}_{k}$ denotes some index set depending on $k$, satisfying:
(i) $\Sigma=\bigcup_{j} Q_{j}^{k}$ for each $k \in \mathbb{Z}$.
(ii) If $m \geq k$ then either $Q_{i}^{m} \subset Q_{j}^{k}$ or $Q_{i}^{m} \cap Q_{j}^{k}=\varnothing$.
(iii) For each $(j, k)$ and each $m<k$, there is a unique $i$ such that $Q_{j}^{k} \subset Q_{i}^{m}$.
(iv) $\operatorname{diam}\left(Q_{j}^{k}\right) \leq c_{*} 2^{-k}$.
(v) Each $Q_{j}^{k}$ contains $\Sigma \cap \mathcal{B}_{\alpha 2^{-k}}\left(X_{j}^{k}, Y_{j}^{k}, t_{j}^{k}\right)$ for some $\left(X_{j}^{k}, Y_{j}^{k}, t_{j}^{k}\right) \in \Sigma$.
(vi) $\sigma_{\mathcal{K}}\left(\left\{(X, Y, t) \in Q_{j}^{k}: \operatorname{dist}\left((X, Y, t), \Sigma \backslash Q_{j}^{k}\right) \leq \varrho 2^{-k}\right\}\right) \leq c_{*} \varrho^{\beta} \sigma_{\mathcal{K}}\left(Q_{j}^{k}\right)$ for all $k, j$ and for all $\varrho \in(0, \alpha)$. We shall denote by $\mathbb{D}=\mathbb{D}(\Sigma)$ the collection of all $Q_{j}^{k}$, i.e.,

$$
\mathbb{D}:=\bigcup_{k} \mathbb{D}_{k}
$$

Note that (iv) and (v) above imply that for each cube $Q \in \mathbb{D}_{k}$ there is a point $\left(X_{Q}, Y_{Q}, t_{Q}\right) \in \Sigma$ and a cube $Q_{r}\left(X_{Q}, Y_{Q}, t_{Q}\right)$ such that $r \approx 2^{-k} \approx \operatorname{diam}(Q)$ and

$$
\begin{equation*}
\Delta_{r}\left(X_{Q}, Y_{Q}, t_{Q}\right) \subset Q \subset \Delta_{c r}\left(X_{Q}, Y_{Q}, t_{Q}\right) \tag{5-10}
\end{equation*}
$$

for some uniform constant $c$. We let

$$
\begin{equation*}
\Delta_{Q}:=\Delta_{r}\left(X_{Q}, Y_{Q}, t_{Q}\right) \tag{5-11}
\end{equation*}
$$

and we shall refer to the point $\left(X_{Q}, Y_{Q}, t_{Q}\right)$ as the center of $Q$. Given a dyadic cube $Q \subset \Sigma$, we define its $\gamma$ dilate by

$$
\begin{equation*}
\gamma Q:=\Delta_{\gamma \operatorname{diam}(Q)}\left(X_{Q}, Y_{Q}, t_{Q}\right) \tag{5-12}
\end{equation*}
$$

For a dyadic cube $Q \in \mathbb{D}_{k}$, we let $\ell(Q)=2^{-k}$, and we shall refer to this quantity as the length of $Q$. Clearly, $\ell(Q) \approx \operatorname{diam}(Q)$.

We now prove that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is absolutely continuous on $\Delta$ with respect to $\mu_{\mathcal{K}}$ using Theorem 3.1. Indeed, let $E \subset \Delta$ and $\delta>0$, and let $\left\{Q_{j}\right\}$ be a (finite) dyadic Vitali covering of $E$ such that

$$
\mu_{\mathcal{K}}\left(\bigcup Q_{j}\right)<\mu_{\mathcal{K}}(E)+\delta
$$

and such that $\gamma Q_{i} \cap \gamma Q_{j}=\varnothing$ for some small $\gamma=\gamma(m, M)>0$, whenever $i \neq j$. Using Theorem 3.1 and the doubling property of $\omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \cdot\right)$ we see that

$$
\begin{equation*}
\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, Q_{j}\right) \leq \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta_{c Q_{j}}\right) \lesssim \omega_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), \pi_{X}\left(\Delta_{c Q_{j}}\right)\right) \ell\left(c Q_{j}\right)^{3 m+2} \lesssim \mu_{\mathcal{K}}\left(\gamma Q_{j}\right) \tag{5-13}
\end{equation*}
$$

where now the implicit constants may depend on $|\Delta|$, which is fixed. Hence

$$
\begin{equation*}
\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, E\right) \leq \sum_{j} \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, Q_{j}\right) \lesssim \sum_{j} \mu_{\mathcal{K}}\left(\gamma Q_{j}\right) \lesssim \mu_{\mathcal{K}}\left(\bigcup Q_{j}\right) \lesssim\left(\mu_{\mathcal{K}}(E)+\delta\right) \tag{5-14}
\end{equation*}
$$

In particular, given $\epsilon>0$ there exists $\delta=\delta(m, \kappa, M, \epsilon,|\Delta|)>0$ such that if $E \subset \Delta$, and if $\mu_{\mathcal{K}}(E)<\delta$, then $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, E\right)<\epsilon$, proving that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right) \ll \mu_{K}$.

By the above we can conclude that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right) \ll \sigma_{\mathcal{K}}$ on $\Delta$ and that

$$
K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right):=\frac{\mathrm{d} \omega_{\mathcal{K}}}{\mathrm{d} \sigma_{\mathcal{K}}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)=\lim _{\tilde{r} \rightarrow 0} \frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta_{\tilde{r}}(X, Y, t)\right)}{\sigma_{\mathcal{K}}\left(\Delta_{\tilde{r}}(X, Y, t)\right)}
$$

exists and is well-defined for $\sigma_{\mathcal{K}}$-almost every $(X, Y, t) \in \Delta$. Using Theorem 3.1

$$
\begin{align*}
\sigma_{\mathcal{K}}(\Delta) K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) & \approx \sigma_{\mathcal{P}}\left(\pi_{X, t}(\Delta)\right) K_{\mathcal{P}}\left(\pi_{X, t}\left(A_{c \Delta, \Lambda}^{+}\right), X, t\right) \\
& \approx \sigma_{\mathcal{E}}\left(\pi_{X}(\Delta)\right) K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right) \tag{5-15}
\end{align*}
$$

whenever $(X, Y, t) \in \Delta$. Using the assumption on $K_{\mathcal{E}}(X)=K_{\mathcal{E}}\left(\pi_{X}\left(A_{c \Delta, \Lambda}^{+}\right), X\right)$, and (5-15), it follows that $K_{\mathcal{K}}(X, Y, t):=K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)$ satisfies

$$
K_{\mathcal{K}} \in B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)
$$

with a constant $\widetilde{\Gamma}=\widetilde{\Gamma}(m, \kappa, M, \Gamma)$. This completes the proof of Theorem 3.2.

## 6. The $L^{p}$ Dirichlet problem for $\mathcal{L}_{\mathcal{K}}$ : Theorem 3.3

Recall the notation $\Sigma$ introduced in (2-12). Given $f \in L_{\mathrm{loc}}^{1}\left(\Sigma, \mathrm{~d} \sigma_{\mathcal{K}}\right)$, we let

$$
M(f)(X, Y, t):=\sup _{\Delta_{r}=\Delta_{r}(X, Y, t) \subset \Sigma} \iint f_{\Delta_{r}}|f| \mathrm{d} \sigma_{\mathcal{K}}
$$

denote the Hardy-Littlewood maximal function of $f$, with respect to $\sigma_{\mathcal{K}}$. In the following we assume that $\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot\right)$ is mutually absolutely continuous on $\Delta$ with respect to $\sigma_{\mathcal{K}}$ for every $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset$ $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$.

We first prove that (i) implies (ii) and hence we assume, given $\Delta \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, that $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot, \cdot, \cdot\right) \in$ $B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)$. As $\omega_{\mathcal{K}}$ is a doubling measure we can use the classical results of Coifman and Fefferman [1974, Theorem IV] to conclude that $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot, \cdot, \cdot\right) \in B_{\tilde{q}}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)$ for some $\tilde{q}>q$ independent of $\Delta$. Let $\tilde{p}$ be the index dual to $\tilde{q}$ and note that $\tilde{p}<p$.

Consider first $f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, and recall the (nontangential) cone $\Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)$. Let $(\widehat{X}, \widehat{Y}, \hat{t}) \in \Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)$ and let $\delta:=d\left((\widehat{X}, \widehat{Y}, \hat{t}),\left(X_{0}, Y_{0}, t_{0}\right)\right)$. Then, by Theorem 2.1 we know that there exists a unique bounded weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, with $u=f$ on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Furthermore,

$$
u(\widehat{X}, \widehat{Y}, \hat{t})=\iiint_{\partial \Omega} K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)
$$

We write

$$
\begin{aligned}
u(\widehat{X}, \widehat{Y}, \hat{t})= & \iiint_{\Delta_{4 \delta}\left(X_{0}, Y_{0}, t_{0}\right)} K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t) \\
& +\sum_{j=2}^{\infty} \iiint_{R_{j}\left(X_{0}, Y_{0}, t_{0}\right)} K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t) \\
= & u_{1}(\widehat{X}, \widehat{Y}, \hat{t})+\sum_{j=2}^{\infty} u_{j}(\widehat{X}, \widehat{Y}, \hat{t})
\end{aligned}
$$

where $R_{j}\left(X_{0}, Y_{0}, t_{0}\right):=\Delta_{2^{j+1} \delta}\left(X_{0}, Y_{0}, t_{0}\right) \backslash \Delta_{2^{j} \delta}\left(X_{0}, Y_{0}, t_{0}\right)$. Using

$$
\begin{equation*}
K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)=\frac{\mathrm{d} \omega_{\mathcal{K}}}{\mathrm{d} \sigma_{\mathcal{K}}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)=\lim _{\tilde{r} \rightarrow 0} \frac{\omega_{\mathcal{K}}\left(\widehat{X}, \widehat{Y}, \hat{t}, \Delta_{\tilde{r}}(X, Y, t)\right)}{\sigma_{\mathcal{K}}\left(\Delta_{\tilde{r}}(X, Y, t)\right)} \tag{6-1}
\end{equation*}
$$

in combination with Theorem 4.7, we see that

$$
K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \lesssim K_{\mathcal{K}}\left(A_{c \Delta_{48}, \Lambda}^{+}, X, Y, t\right)
$$

whenever $(X, Y, t) \in \Delta_{4 \delta}\left(X_{0}, Y_{0}, t_{0}\right)$, and where $\Delta_{4 \delta}:=\Delta_{4 \delta}\left(X_{0}, Y_{0}, t_{0}\right)$. Hence, using Cauchy-Schwarz,

$$
\begin{aligned}
\left|u_{1}(\widehat{X}, \widehat{Y}, \hat{t})\right| & \leq \sigma_{\mathcal{K}}\left(\Delta_{4 \delta}\right)\left(\iiint_{\Delta_{4 \delta}}\left|K_{\mathcal{K}}\left(A_{c \Delta_{4 \delta}, \Lambda}^{+}, X, Y, t\right)\right|^{\tilde{q}} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / \tilde{q}}\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}} \\
& \leq c \omega_{\mathcal{K}}\left(A_{c \Delta_{4 \delta}, \Lambda}^{+}, \Delta_{4 \delta}\right)\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}} \\
& \leq c\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}}
\end{aligned}
$$

by (i). Similarly, using also Lemma 4.5 we have

$$
K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \lesssim 2^{-\alpha j} K_{\mathcal{K}}\left(A_{c \Delta_{2} j_{\delta}, \Lambda}^{+}, X, Y, t\right)
$$

whenever $(X, Y, t) \in R_{j}\left(X_{0}, Y_{0}, t_{0}\right)$. Using this estimate, and essentially just repeating the estimates conducted in the estimate of $u_{1}$, we deduce that

$$
\left|u_{j}(\widehat{X}, \widehat{Y}, \hat{t})\right| \leq c 2^{-\alpha j}\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}}
$$

In particular,

$$
|u(\widehat{X}, \widehat{Y}, \hat{t})| \leq\left|u_{1}(\widehat{X}, \widehat{Y}, \hat{t})\right|+\sum_{j=2}^{\infty}\left|u_{j}(\widehat{X}, \widehat{Y}, \hat{t})\right| \leq c\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}}
$$

and hence

$$
N(u)\left(X_{0}, Y_{0}, t_{0}\right) \leq c\left(M\left(|f|^{\tilde{p}}\right)\left(X_{0}, Y_{0}, t_{0}\right)\right)^{1 / \tilde{p}}
$$

We can conclude that

$$
\begin{align*}
\|N(u)\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} & \leq c\left\|\left(M\left(|f|^{\tilde{p}}\right)\right)^{1 / \tilde{p}}\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \\
& \leq c\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \tag{6-2}
\end{align*}
$$

by the continuity of the Hardy-Littlewood maximal function and where the constant $c$ depends only on ( $m, \kappa, M, p$ ). We now remove the restriction that $f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Indeed, given $f \in$ $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ there exist, by density of $C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, a sequence of functions $\left\{f_{j}\right\}, f_{j} \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$, converging to $f$ in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$. In particular, there exists a sequence of functions $\left\{u_{j}\right\}$, where $u_{j}$ is the unique bounded weak solution to $\mathcal{L}_{\mathcal{K}} u_{j}=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, with $u_{j}=f_{j}$ on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. By (6-2),

$$
\begin{equation*}
\left\|N\left(u_{k}-u_{l}\right)\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\left\|f_{k}-f_{l}\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \rightarrow 0 \quad \text { as } k, l \rightarrow \infty . \tag{6-3}
\end{equation*}
$$

Consider $U_{X} \times U_{Y} \times J \subset \mathbb{R}^{N+1}$, where $U_{X} \subset \mathbb{R}^{m}$ and $U_{Y} \subset \mathbb{R}^{m}$ are bounded domains and $J=(a, b)$ with $-\infty<a<b<\infty$. Assume that $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and that the distance from $\overline{U_{X} \times U_{Y} \times J}$ to $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ is $r>0$. By a covering argument with cubes of size, say, $r / 2$, Lemma 4.2, and the finiteness of $N\left(u_{j}\right)$ in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, it follows that $\left\{u_{j}\right\}$ is uniformly bounded in $L^{2}\left(U_{X} \times U_{Y} \times J\right)$, whenever $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Using this, and the energy estimate of Lemma 4.1 , we can conclude that

$$
\begin{equation*}
\left\|\nabla_{X} u_{j}\right\|_{L^{2}\left(U_{X} \times U_{Y} \times J\right)} \text { is uniformly bounded. } \tag{6-4}
\end{equation*}
$$

Using (6-4) and the weak formulation of the equation $\mathcal{L}_{\mathcal{K}} u_{j}=0$ it follows that $\left(X \cdot \nabla_{Y}-\partial_{t}\right) u_{j}$ is uniformly bounded, with respect to $j$, in $L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{-1}\left(U_{X}\right)\right)$. Let $W\left(U_{X} \times U_{Y} \times J\right)$ be defined as in (2-18). By the above argument we can conclude, whenever $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, that

$$
\begin{equation*}
\left\|u_{j}\right\|_{W\left(U_{X} \times U_{Y} \times J\right)} \text { is uniformly bounded. } \tag{6-5}
\end{equation*}
$$

Using (6-3), and arguing as in the deductions in (6-4) and (6-5), we can also conclude that

$$
\begin{equation*}
\left\|u_{k}-u_{l}\right\|_{W\left(U_{X} \times U_{Y} \times J\right)} \rightarrow 0 \quad \text { as } k, l \rightarrow \infty \tag{6-6}
\end{equation*}
$$

Using (6-6) it follows that a subsequence $\left\{u_{j_{k}}\right\}$ of $\left\{u_{j}\right\}$ converges to a weak solution $u$ to

$$
\mathcal{L}_{\mathcal{K}} u=0 \quad \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}
$$

and that

$$
\|N(u)\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

Note also, using the notation introduced above, that

$$
\begin{equation*}
\left\|N\left(u-u_{j}\right)\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \leq c\left\|f-f_{j}\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \rightarrow 0 \quad \text { as } j \rightarrow \infty \tag{6-7}
\end{equation*}
$$

To complete the proof that (i) implies (ii) we have to prove that $u=f$ n.t. on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Consider $f \in L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ and let $\left\{f_{j}\right\}, f_{j} \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$, be a sequence of functions converging to $f$ in $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ be a Lebesgue point of $f$. Given $\delta>0$ we have

$$
\begin{equation*}
N_{\delta}(u-f)\left(X_{0}, Y_{0}, t_{0}\right) \leq N_{\delta}\left(u-u_{j}\right)\left(X_{0}, Y_{0}, t_{0}\right)+N_{\delta}\left(u_{j}-f_{j}\right)\left(X_{0}, Y_{0}, t_{0}\right)+M\left(f-f_{j}\right)\left(X_{0}, Y_{0}, t_{0}\right) \tag{6-8}
\end{equation*}
$$

where $N_{\delta}$ was introduced in (2-29) and $N_{\delta}(u-f)\left(X_{0}, Y_{0}, t_{0}\right)$ should be interpreted as

$$
\sup _{(X, Y, t) \in \Gamma_{\delta}^{\eta}\left(X_{0}, Y_{0}, t_{0}\right)}\left|u(X, Y, t)-f\left(X_{0}, Y_{0}, t_{0}\right)\right| .
$$

In the following we assume, as we may without loss of generality, that $(0,0,0) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Given $\epsilon>0$ small and $R \gg 1$, let

$$
S_{\epsilon}(R, \delta):=\left\{(X, Y, t) \in \Delta_{R}(0,0,0): N_{\delta}(u-f)(X, Y, t)>\epsilon\right\} .
$$

Using (6-8), weak estimates and (6-7) we deduce

$$
\begin{equation*}
\sigma_{\mathcal{K}}\left(S_{\epsilon}(R, \delta)\right) \leq c \epsilon^{-p}\left(\left\|f-f_{j}\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}^{p}+\left\|N_{\delta}\left(u_{j}-f_{j}\right)\right\|_{L^{p}\left(\Delta_{R}(0,0,0), \mathrm{d} \sigma_{\mathcal{K}}\right)}^{p}\right) \tag{6-9}
\end{equation*}
$$

Now letting $\delta \rightarrow 0, j \rightarrow \infty, R \rightarrow \infty$, in that order, we deduce that the set of points $\left(X_{0}, Y_{0}, t_{0}\right) \in$ $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ at which

$$
\lim _{\substack{(X, Y, t) \in \Gamma^{\eta}\left(X_{0}, Y_{0}, t_{0}\right) \\(X, Y, t) \rightarrow\left(X_{0}, Y_{0}, t_{0}\right)}}\left|u(X, Y, t)-f\left(X_{0}, Y_{0}, t_{0}\right)\right|>\epsilon
$$

has $\sigma_{\mathcal{K}}$ measure zero. As $\epsilon$ is arbitrary we can conclude that $u=f$ n.t. on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$.
Next we prove that (ii) implies (i) and hence we assume that $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is solvable. Let $\left(X_{0}, Y_{0}, t_{0}\right) \in \partial \Omega, \Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and $f \in C_{0}(\Delta), f \geq 0$. Let $u$ be the unique bounded solution to the Dirichlet problem with boundary data $f$. Then

$$
u\left(A_{c \Delta, \Lambda}^{+}\right)=\iiint_{\Delta} K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)
$$

Using the estimate in Lemma 4.2, and (ii),

$$
\begin{aligned}
u\left(A_{c \Delta, \Lambda}^{+}\right) & \lesssim\left(\iiint_{Q_{r / c}\left(A_{c \Delta, \Lambda}^{+}\right)}|u(X, Y, t)|^{p} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / p} \\
& \lesssim\left(\frac{1}{\sigma_{\mathcal{K}}(\Delta)} \iiint_{4 \Delta}|N(u)(X, Y, t)|^{p} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / p} \\
& \lesssim\left(\frac{1}{\sigma_{\mathcal{K}}(\Delta)} \iiint_{\Delta}|f(X, Y, t)|^{p} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / p}
\end{aligned}
$$

In particular, for all $f \in C_{0}(\Delta)$ with $\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}=1$, we have

$$
\left|\iiint_{\Delta} K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)\right| \leq\left(\frac{1}{\sigma_{\mathcal{K}}(\Delta)}\right)^{1 / p}
$$

Hence, since $\left(\Delta, \sigma_{\mathcal{K}}\right)$ is a finite measure space,

$$
\left(\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{q} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / q} \leq\left(\frac{1}{\sigma_{\mathcal{K}}(\Delta)}\right)^{1 / p}
$$

Furthermore, Lemmas 4.5 and 4.6 imply

$$
\iiint_{\Delta} K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)=\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta\right) \gtrsim 1
$$

Combining the estimates,

$$
\left(\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{q} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / q} \lesssim \iiint_{\Delta} K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)
$$

Hence $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \cdot, \cdot, \cdot\right) \in B_{q}\left(\Delta, \mathrm{~d} \sigma_{\mathcal{K}}\right)$ and the proof that (ii) implies (i) is complete. Put together we have proved that the statements in Theorem 3.3(i) and (ii) are equivalent.

6A. Proof of the uniqueness statement in Theorem 3.3. Having proved that Theorem 3.3(i) and (ii) are equivalent it remains to prove that if $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is solvable, then $D_{\mathcal{K}}^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable. That is, we have to prove that if $N(u) \in L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, and if $u$ is a weak solution to the Dirichlet problem

$$
\left\{\begin{aligned}
\mathcal{L}_{\mathcal{K}} u=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R} \\
u=0 & \text { n.t. on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{aligned}\right.
$$

then $u \equiv 0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Note that the proof of this is considerably more involved compared to the corresponding arguments in the elliptic setting [Kenig 1994; Kenig and Shen 2011]. One reason is, again, the (time-)lag in the Harnack inequality for parabolic equations.

To start the proof we fix $(\widehat{X}, \widehat{Y}, \hat{t}) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and we intend to prove that $u(\widehat{X}, \widehat{Y}, \hat{t})=0$. Let $\theta \in C_{0}^{\infty}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ with $\theta=1$ in a neighborhood of $(\widehat{X}, \widehat{Y}, \hat{t})$. Then, using (4-14),

$$
\begin{align*}
u(\widehat{X}, \widehat{Y}, \hat{t})= & (u \theta)(\widehat{X}, \widehat{Y}, \hat{t}) \\
= & -\iiint A(X) \nabla_{X} G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \cdot \nabla_{X}(u \theta)(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& +\iiint G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)\left(X \cdot \nabla_{Y}-\partial_{t}\right)(u \theta)(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{6-10}
\end{align*}
$$

By the results in [Golse et al. 2019], see Lemma 4.3, we know that any weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ is Hölder continuous. As $A$ is independent of $(Y, t)$, it follows that partial derivatives of $u$ with respect to $Y$ and $t$ are also weak solutions. As a consequence, as $A$ is independent of $(Y, t)$, any weak solution to $\mathcal{L}_{\mathcal{K}} u=0$ is $C^{\infty}$-smooth as a function of $(Y, t)$. Hence the term $\left(X \cdot \nabla_{Y}-\partial_{t}\right)(u \theta)$ appearing in the last display is well-defined. Using (6-10), and that $\mathcal{L}_{\mathcal{K}} u=0$,

$$
\begin{equation*}
|u(\widehat{X}, \widehat{Y}, \hat{t})| \lesssim(I+I I+I I I) \tag{6-11}
\end{equation*}
$$

where

$$
\begin{align*}
I & :=\iiint\left|G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)\right|\left|\nabla_{X} u(X, Y, t)\right|\left|\nabla_{X} \theta(X, Y, t)\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
I I & :=\iiint\left|\nabla_{X} G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)\right| \| u(X, Y, t)| | \nabla_{X} \theta(X, Y, t) \mid \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t  \tag{6-12}\\
I I I & :=\iiint\left|G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)\right||u(X, Y, t)|\left|\left(\partial_{t}-X \cdot \nabla_{Y}\right) \theta(X, Y, t)\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{align*}
$$

Recall the notation $Q:=(-1,1)^{m} \times(-1,1)^{m} \times(-1,1)$. Given $(\widehat{X}, \widehat{Y}, \hat{t})=\left(\hat{x}, \hat{x}_{m}, \widehat{Y}, \hat{t}\right) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ fixed, we have

$$
((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
$$

fixed. We consider $Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})=((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \circ Q_{R}$ and we let $\epsilon$ and $R$ satisfy

$$
\epsilon<\lambda / 8, \quad R>8 \lambda, \quad \text { where } \lambda:=\hat{x}_{m}-\psi(\hat{x})
$$

When taking limits, we will always first let $\epsilon \rightarrow 0$ before letting $R \rightarrow \infty$.
Let $\varphi_{1}=\varphi_{1}(X, Y, t) \in C_{0}^{\infty}\left(Q_{2 R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})\right), 0 \leq \varphi_{1} \leq 1$, be such that $\varphi_{1} \equiv 1$ on $Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})$. Let $\varphi_{2}=\varphi_{2}(X)=\varphi_{2}\left(x, x_{m}\right)$ be a smooth function with range $[0,1]$ such that $\varphi_{2}\left(x, x_{m}\right) \equiv 1$ on $\left\{\left(x, x_{m}\right): x_{m} \geq \psi(x)+2 \epsilon\right\}$ and $\varphi_{2}\left(x, x_{m}\right) \equiv 0$ on $\left\{\left(x, x_{m}\right): x_{m} \leq \psi(x)+\epsilon\right\}$. Note that $\varphi_{1}$ can be constructed so that $\left\|R \nabla_{X} \varphi_{1}\right\|_{L^{\infty}}+\left\|R^{2}\left(X \cdot \nabla_{Y}-\partial_{t}\right) \varphi_{1}\right\|_{L^{\infty}} \lesssim 1$. Similarly, $\varphi_{2}$ can be constructed so that $\left\|\epsilon \nabla_{X} \varphi_{2}\right\|_{L^{\infty}} \leq c$, where $c$ is independent of $\epsilon$. We let

$$
\theta=\theta(X, Y, t)=\theta\left(x, x_{m}, Y, t\right):=\varphi_{1}(X, Y, t) \varphi_{2}\left(x, x_{m}\right)
$$

Then $\theta \in C_{0}^{\infty}\left(Q_{2 R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})\right), 0 \leq \theta \leq 1, \theta \equiv 1$ on the set of points $(X, Y, t)=\left(x, x_{m}, Y, t\right) \in$ $Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})$ which satisfy $x_{m} \geq \psi(x)+2 \epsilon$ and $\theta \equiv 0$ on the set of points in $(X, Y, t)=$ $\left(x, x_{m}, Y, t\right) \in Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})$ which satisfy $x_{m} \leq \psi(x)+\epsilon$. Let
(i) $D_{1}:=Q_{2 R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \cap\left\{(X, Y, t): \psi(x)+\epsilon<x_{m}<\psi(x)+2 \epsilon\right\}$,
(ii) $D_{2}:=Q_{2 R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \cap\left\{(X, Y, t): \psi(x)+R<x_{m}<\psi(x)+2 R\right\}$,
(iii) $D_{3}:=D_{4} \cap\left\{(X, Y, t): \psi(x)+2 \epsilon \leq x_{m} \leq \psi(x)+R\right\}$,
where

$$
D_{4}:=Q_{2 R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \backslash Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})
$$

Using this notation, the domains where the integrands in $I$, $I I$, and $I I I$ are nonzero are contained in the union $D_{1} \cup D_{2} \cup D_{3}$. By the construction of $\theta$,
(i') $\left\|\epsilon \nabla_{X} \theta\right\|_{L^{\infty}\left(D_{1}\right)}+\left\|R^{2}\left(X \cdot \nabla_{Y}-\partial_{t}\right) \theta\right\|_{L^{\infty}\left(D_{1}\right)} \leq c$,
(ii') $\left\|R \nabla_{X} \theta\right\|_{L^{\infty}\left(D_{2}\right)}+\left\|R^{2}\left(X \cdot \nabla_{Y}-\partial_{t}\right) \theta\right\|_{L^{\infty}\left(D_{2}\right)} \leq c$,
(iii') $\left\|R \nabla_{X} \theta\right\|_{L^{\infty}\left(D_{3}\right)}+\left\|R^{2}\left(X \cdot \nabla_{Y}-\partial_{t}\right) \theta\right\|_{L^{\infty}\left(D_{3}\right)} \leq c$,
where $c$ is a constant which is independent of $\epsilon$ and $R$. Note that if $(X, Y, t) \in D_{3}$, then $\theta(X, Y, t)=$ $\varphi_{1}(X, Y, t)$ and this explains (iii').

Using the sets $D_{1}, D_{2}$, and $D_{3}$, and letting

$$
G_{\mathcal{K}}(\cdot, \cdot, \cdot):=G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, \cdot, \cdot, \cdot)
$$

we see that

$$
\begin{equation*}
I+I I+I I I \lesssim T_{1}+T_{2}+T_{3}, \tag{6-13}
\end{equation*}
$$

where

$$
\begin{aligned}
T_{1} & :=\frac{1}{\epsilon^{2}} \iiint_{D_{1}}\left(\epsilon\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right|+\epsilon\left|\nabla_{X} G_{\mathcal{K}}\right||u|+\epsilon^{2} R^{-2}\left|G_{\mathcal{K}}\right||u|\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
T_{2} & :=\frac{1}{R^{2}} \iiint_{D_{2}}\left(R\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right|+R\left|\nabla_{X} G_{\mathcal{K}}\right||u|+\left|G_{\mathcal{K}}\right||u|\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
T_{3} & :=\frac{1}{R^{2}} \iiint_{D_{3}}\left(R\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right|+R\left|\nabla_{X} G_{\mathcal{K}}\right||u|+\left|G_{\mathcal{K}}\right||u|\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

We need to estimate $T_{1}, T_{2}$, and $T_{3}$. To improve readability we will in the following use the notation

$$
\Delta_{\varrho}:=\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{\varrho}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t}) \quad \text { for } \varrho>0
$$

We first consider $T_{1}$. We start by estimating the contribution from the term $\left|G_{\mathcal{K}}\right||u|$ and in this case we prove a harder estimate than we need. The argument will be used for further reference. Note that $\frac{1}{\epsilon^{2}} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right||u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t$

$$
\begin{aligned}
& \lesssim \iiint_{\Delta_{2 R}} \tilde{N}_{\epsilon}(u)\left(\frac{1}{\epsilon} \int_{\psi(x)+\epsilon}^{\psi(x)+2 \epsilon} \frac{G_{\mathcal{K}}\left(\left(x, x_{m}\right), Y, t\right)}{\epsilon} \mathrm{d} x_{m}\right) \mathrm{d} \sigma_{\mathcal{K}} \\
& \lesssim\left\|\widetilde{N}_{\epsilon}(u)\right\|_{L^{p}\left(\Delta_{2 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)}\left(\iiint_{\Delta_{2 R}}\left(\frac{1}{\epsilon} \int_{\psi(x)+\epsilon}^{\psi(x)+2 \epsilon} \frac{G_{\mathcal{K}}\left(\left(x, x_{m}\right), Y, t\right)}{\epsilon} \mathrm{d} x_{m}\right)^{q} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / q}
\end{aligned}
$$

where $\widetilde{N}_{\epsilon}$ is a truncated maximal operator defined as

$$
\tilde{N}_{\epsilon}(u)(X, Y, t):=\sup _{\psi(x)<x_{m}<\psi(x)+2 \epsilon}\left|u\left(\left(x, x_{m}\right), Y, t\right)\right| .
$$

Using Lemma 4.10 and the definition of $K_{\mathcal{K}}$, see (6-1), we have, for every $(X, Y, t) \in \Delta_{2 R}, 1 \leq \sigma \leq 2$, and denoting by $e_{m}$ the unit vector in $\mathbb{R}^{m}$ pointing into $\Omega$ in the $x_{m}$-direction,

$$
\lim _{\epsilon \rightarrow 0} \frac{G_{\mathcal{K}}\left(\widehat{X}, \widehat{Y}, \hat{t}, X+\sigma \epsilon e_{m}, Y, t\right)}{\epsilon} \lesssim \lim _{\epsilon \rightarrow 0} \frac{\omega_{\mathcal{K}}\left(\widehat{X}, \widehat{Y}, \hat{t}, \Delta_{c \sigma \epsilon}(X, Y, t)\right)}{\epsilon^{q-1}} \lesssim K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)
$$

Note that if $\hat{t} \leq t$, then this is trivial as the left-hand side is identically zero. If $\hat{t}>t$, then we may apply Lemma 4.10 in the deduction as we are considering the limiting situation $\epsilon \rightarrow 0$. Using these estimates, and Lebesgue's theorem on dominated convergence, we obtain

$$
\begin{align*}
\limsup _{\epsilon \rightarrow 0} \frac{1}{\epsilon^{2}} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right||u| & \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \lesssim\left(\limsup _{\epsilon \rightarrow 0}\left\|\tilde{N}_{\epsilon}(u)\right\|_{L^{p}\left(\Delta_{2 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)}\right)\left\|K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, \cdot, \cdot, \cdot)\right\|_{L^{q}\left(\Delta_{2 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)}=0 \tag{6-14}
\end{align*}
$$

as $u$ vanishes at the boundary in the nontangential sense. We next consider the term

$$
\frac{1}{\epsilon} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
$$

In this case, we first note, using Lemma 4.6 and the construction of $D_{1}$, that if $\epsilon$ is small enough, then

$$
\begin{equation*}
G_{\mathcal{K}}(X, Y, t)=G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \lesssim(R / \lambda)^{\gamma} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \tag{6-15}
\end{equation*}
$$

whenever $(X, Y, t) \in D_{1}$. Let $\left\{Q_{j}\right\}$ be all Whitney cubes in a Whitney decomposition of $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ which intersects $D_{1}$. Then $\left|Q_{j}\right| \approx \epsilon^{q}$. Using (6-15) and Hölder's inequality

$$
\begin{align*}
& \frac{1}{\epsilon} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \quad \lesssim(R / \lambda)^{\gamma} \frac{1}{\epsilon} \sum_{j} \iiint_{Q_{j}} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right)\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \quad \lesssim(R / \lambda)^{\gamma} \frac{1}{\epsilon} \sum_{j}\left(\iiint_{Q_{j}}\left|G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2}\left(\iiint_{Q_{j}}\left|\nabla_{X} u\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2} \tag{6-16}
\end{align*}
$$

Using the adjoint version of Lemmas 4.6, and 4.11, we see that

$$
\begin{equation*}
\sup _{4 Q_{j}} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \lesssim \inf _{4 Q_{j}} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \tag{6-17}
\end{equation*}
$$

Furthermore, using the energy estimate of Lemma 4.1, assuming that the Whitney decomposition is such that $8 Q_{j} \subset \Omega \times \mathbb{R}^{m} \times \mathbb{R}$,

$$
\begin{equation*}
\iiint_{Q_{j}}\left|\nabla_{X} u\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t \lesssim \epsilon^{-2} \iiint_{2 Q_{j}}|u|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t \lesssim \epsilon^{-2}\left|Q_{j}\right|\left(\sup _{2 Q_{j}}|u|\right)^{2} \tag{6-18}
\end{equation*}
$$

Using (6-16)-(6-18) we deduce

$$
\begin{equation*}
\frac{1}{\epsilon} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \lesssim(R / \lambda)^{\gamma} \frac{1}{\epsilon^{2}} \sum_{j}\left|Q_{j}\right|\left(\inf _{4 Q_{j}} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right)\right)\left(\sup _{2 Q_{j}}|u(X, Y, t)|\right) \tag{6-19}
\end{equation*}
$$

Using Lemma 4.2

$$
\begin{equation*}
\sup _{2 Q_{j}}|u| \lesssim\left(\iiint_{4 Q_{j}}|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right) \tag{6-20}
\end{equation*}
$$

This inequality in combination with (6-19) imply that

$$
\begin{equation*}
\frac{1}{\epsilon} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \lesssim(R / \lambda)^{\gamma} \frac{1}{\epsilon^{2}} \iiint_{\widetilde{D}_{1}} G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, X, Y, t\right)|u(X, Y, t)| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{6-21}
\end{equation*}
$$

where $\widetilde{D}_{1}$ is the enlargement of $D_{1}$ defined as the union of the cubes $\left\{4 Q_{j}\right\}$. We can now repeat the argument leading up to (6-14), with $G_{\mathcal{K}}$ replaced by $G_{\mathcal{K}}\left(A_{c \Delta_{R}, \Lambda}^{+}, \cdot, \cdot, \cdot\right)$ and with $D_{1}$ replaced by $\widetilde{D}_{1}$, to conclude that

$$
\begin{equation*}
\limsup _{\epsilon \rightarrow 0} \frac{1}{\epsilon} \iiint_{D_{1}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t=0 \tag{6-22}
\end{equation*}
$$

The remaining term in $T_{1}$ can be handled analogously and hence we can conclude that

$$
\begin{equation*}
T_{1} \rightarrow 0, \quad \text { as } \epsilon \rightarrow 0 \tag{6-23}
\end{equation*}
$$

Next we consider $T_{2}$ and we first consider the contribution from the term

$$
\begin{equation*}
\frac{1}{R^{2}} \iiint_{D_{2}}\left|G_{\mathcal{K}}\right||u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{6-24}
\end{equation*}
$$

In this case we first note, using Lemma 4.9, that

$$
G_{\mathcal{K}}(X, Y, t)=G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \leq \Gamma_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \lesssim R^{2-q}
$$

whenever $(X, Y, t) \in D_{2}$. Hence,

$$
\begin{aligned}
\frac{1}{R^{2}} \iiint_{D_{2}}\left|G_{\mathcal{K}}\right||u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \lesssim R^{1-\boldsymbol{q}} \iiint_{\Delta_{2 R}} N(u) \mathrm{d} \sigma_{\mathcal{K}} \\
& \lesssim R^{1-\boldsymbol{q}} R^{(\boldsymbol{q}-1)(1-1 / p)}\|N(u)\|_{L^{p}\left(\Delta_{2 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)} \\
& =R^{(1-\boldsymbol{q}) / p}\|N(u)\|_{L^{p}\left(\Delta_{2 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)} \rightarrow 0, \quad \text { as } R \rightarrow \infty
\end{aligned}
$$

We next consider the contribution from the term

$$
\frac{1}{R} \iiint_{D_{2}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
$$

Using the energy estimate of Lemma 4.1, as well as Lemma 4.2,

$$
\left(\iiint_{D_{2}}\left|\nabla_{X} u\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2} \lesssim R^{-1-q / 2} \iiint_{\widetilde{D}_{2}}|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
$$

where $\widetilde{D}_{2}$ is an enlargement of $D_{2}$. Using this, and also again using the bound on $G_{\mathcal{K}}$ stated above, we see that

$$
\begin{aligned}
\frac{1}{R} \iiint_{D_{2}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \lesssim R^{1-\boldsymbol{q} / 2} R^{-1-\boldsymbol{q} / 2} \iiint_{\widetilde{D}_{2}}|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \lesssim R^{1-\boldsymbol{q}} \iiint_{\Delta_{4 R}}|N(u)| \mathrm{d} \sigma_{K} \\
& \lesssim R^{1-q} R^{(\boldsymbol{q}-1) / q}\|N(u)\|_{L^{p}\left(\Delta_{4 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)} \\
& \lesssim R^{(1-\boldsymbol{q}) / p}\|N(u)\|_{L^{p}\left(\Delta_{4 R}, \mathrm{~d} \sigma_{\mathcal{K}}\right)} \rightarrow 0, \quad \text { as } R \rightarrow \infty
\end{aligned}
$$

The remaining term in $T_{2}$ can be handled analogously and hence we can conclude that

$$
\begin{equation*}
T_{2} \rightarrow 0, \quad \text { as } R \rightarrow \infty \tag{6-25}
\end{equation*}
$$

Finally we consider $T_{3}$. The term in $T_{3}$ containing the integrand $\left|G_{\mathcal{K}} \| u\right|$ can be handled as we handled the term in (6-24). For the other terms we first recall that by construction $G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \neq 0$ if and only if $t<\hat{t}$. Furthermore, for $(X, Y, t) \in D_{3}$ fixed, $G_{\mathcal{K}}(\cdot, \cdot, \cdot, X, Y, t)$ is a nonnegative solution to $\mathcal{L}_{\mathcal{K}} u=0$ in $\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap Q_{R}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})$. In particular, if $R$ is large enough, then by Theorem 4.7 we have that

$$
\begin{equation*}
G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \lesssim G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \tag{6-26}
\end{equation*}
$$

whenever $(X, Y, t) \in D_{3}$ and we can ensure that $A_{c^{-1} \Delta_{R}, \Lambda}^{+} \subset Q_{R / 2}((\hat{x}, \psi(\hat{x})), \widehat{Y}, \hat{t})$. To proceed we let $C=C(m) \gg 1$ be a large but fixed constant, and we introduce

$$
D_{3}^{*}:=D_{3} \cap\left\{(X, Y, t): \psi(x)+2 \epsilon \leq x_{m} \leq \psi(x)+R / C\right\}
$$

Then the domain of integration in the terms defining $T_{3}$ is partitioned into integration over $D_{3}^{*}$ and $D_{3} \backslash D_{3}^{*}$. Integration over the latter set can be handled as we handled $T_{2}$. Therefore we here only consider the remaining terms in $T_{3}$ but with domain of integration defined by $D_{3}^{*}$. We now let $\left\{Q_{j}\right\}$ be all Whitney cubes in a Whitney decomposition of $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ which intersects $D_{3}^{*}$. Focusing on the term in $T_{3}$ containing the integrand $\left|G_{\mathcal{K}} \| \nabla_{X} u\right|$ we see that

$$
\begin{align*}
& \frac{1}{R} \iiint_{D_{3}^{*}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \leq \frac{1}{R} \sum_{j} \iiint_{Q_{j} \cap D_{3}^{*}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& \lesssim \frac{1}{R} \sum_{j}\left|Q_{j}\right|^{1 / 2} l\left(Q_{j}\right)^{-1}\left(\iiint_{Q_{j} \cap D_{3}^{*}}\left|G_{\mathcal{K}}\right|^{2} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right)^{1 / 2}\left(\iiint_{4 Q_{j}}|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right) \\
& \lesssim \frac{1}{R} \sum_{j}\left|Q_{j}\right| l\left(Q_{j}\right)^{-1}\left(\sup _{Q_{j}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)\right)\left(\iiint_{4 Q_{j}}|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right) \tag{6-27}
\end{align*}
$$

where we have used Lemma 4.1, Lemma 4.2 and (6-26). Furthermore, (6-17) remains valid in this context and hence

$$
\begin{align*}
\left.\sup _{Q_{j}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)\right)\left(\iiint_{4 Q_{j}}|u| \mathrm{d} X\right. & \mathrm{d} Y \mathrm{~d} t) \\
& \lesssim\left(\iiint_{4 Q_{j}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right) \tag{6-28}
\end{align*}
$$

Combining these insights we see, using the notation $\delta(X):=\left(x_{m}-\psi(x)\right)$, that

$$
\begin{align*}
\frac{1}{R} \iiint_{D_{3}^{*}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \lesssim \frac{1}{R} \sum_{j} l\left(Q_{j}\right)^{-1}\left(\iiint_{4 Q_{j}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)|u| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right) \\
& \lesssim \frac{1}{R}\left(\iiint_{\widetilde{D}_{3}^{*}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)|u| \delta(X)^{-1} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right) \tag{6-29}
\end{align*}
$$

where $\widetilde{D}_{3}^{*}$ is a slight enlargement of $D_{3}^{*}$ due to the enlargement from $Q_{j}$ to $4 Q_{j}$. In particular,

$$
\begin{equation*}
\frac{1}{R} \iiint_{D_{3}^{*}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \lesssim \frac{1}{R}\left(\iiint_{D_{5}} G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right)|u| \delta(X)^{-1} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t\right) \tag{6-30}
\end{equation*}
$$

where $D_{5}$ is defined as the set

$$
\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap\left(Q_{c R}(\widehat{X}, \widehat{Y}, \hat{t}) \backslash\left\{(X, Y, t):(x, \psi(x), Y, t) \in \Delta_{R / c}, \psi(x) \leq x_{m}<\psi(x)+2 c R\right\}\right)
$$

for some $c=c(m) \gg 1$. Note that points in $D_{5}$ can be represented as

$$
(X, Y, t)=((x, \psi(x)), Y, t)+(0, \delta(X), 0,0)
$$

where $((x, \psi(x)), Y, t) \in \Delta_{c R} \backslash \Delta_{R / c}$. Consider one such point $(X, Y, t)$. We claim that

$$
\begin{equation*}
G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \delta(X)^{-1} \lesssim M\left(K_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \cdot\right) \chi_{\Delta_{2 c R} \backslash \Delta_{R /(2 c)}}(\cdot)\right)((x, \psi(x)), Y, t) \tag{6-31}
\end{equation*}
$$

where again $M$ denotes the Hardy-Littlewood maximal function on $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ with respect to $\sigma_{\mathcal{K}}$, and $\chi_{\Delta_{c R} \backslash \Delta_{R / c}}(\cdot)$ is the indicator function for the set $\Delta_{c R} \backslash \Delta_{R / c}$. To prove (6-31) we simply note, using Lemma 4.10, that

$$
G_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, X, Y, t\right) \delta(X)^{-1} \lesssim \frac{\omega_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \Delta_{c r}((x, \psi(x)), Y, t)\right)}{\sigma_{\mathcal{K}}\left(\Delta_{c r}((x, \psi(x)), Y, t)\right)}
$$

where $r:=\delta(X)$, and that $\omega_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \Delta_{c r}((x, \psi(x)), Y, t)\right)$ can be expressed as
$\iiint_{\Delta_{c r}((x, \psi(x)), Y, t)} K_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \tilde{X}, \tilde{Y}, \tilde{t}\right) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t})$

$$
=\iiint_{\Delta_{c r}((x, \psi(x)), Y, t)} K_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \tilde{X}, \tilde{Y}, \tilde{t}\right) \chi_{\Delta_{2 c R} \backslash \Delta_{R /(2 c)}}(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t})
$$

Using (6-31) we can continue the estimate in (6-30) to conclude that

$$
\frac{1}{R} \iiint_{D_{3}^{*}}\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \lesssim \iiint_{\Delta_{c R} \backslash \Delta_{R / c}} M\left(K_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \cdot\right) \chi_{\Delta_{2 c R} \backslash \Delta_{R /(2 c)}}(\cdot)\right) N(u) \mathrm{d} \sigma_{\mathcal{K}}
$$

Hence, the term on the left-hand side in the last display can estimated by

$$
\begin{aligned}
&\left(\iiint_{\Delta_{c R \backslash} \backslash \Delta_{R / c}}\left|K_{\mathcal{K}}\left(A_{c^{-1} \Delta_{R}, \Lambda}^{+}, \cdot\right)\right|^{q} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / q}\left(\iiint_{\Delta_{c R} \backslash \Delta_{R / c}}|N(u)|^{p} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / p} \\
& \quad \lesssim\left(\sigma_{\mathcal{K}}\left(\Delta_{c R}\right)\right)^{1 / q-1}\left(\iiint_{\Sigma \backslash \Delta_{R / c}}|N(u)|^{p} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / p} \rightarrow 0
\end{aligned}
$$

as $R \rightarrow \infty$. This completes the estimate of the term in $T_{3}$ containing the integrand $\left|G_{\mathcal{K}}\right|\left|\nabla_{X} u\right|$. The term containing the integrand $\left|\nabla_{X} G_{\mathcal{K}} \| u\right|$ can be estimated in a similar manner. We omit further details and claim that

$$
\begin{equation*}
T_{3} \rightarrow 0, \quad \text { as } R \rightarrow \infty \tag{6-32}
\end{equation*}
$$

To summarize, we have proved that

$$
\begin{equation*}
|u(\widehat{X}, \widehat{Y}, \hat{t})| \lesssim \lim _{R \rightarrow \infty} \limsup _{\epsilon \rightarrow 0}(I+I I+I I I) \lesssim \lim _{R \rightarrow \infty} \limsup _{\epsilon \rightarrow 0}\left(T_{1}+T_{2}+T_{3}\right)=0 \tag{6-33}
\end{equation*}
$$

i.e., $|u(\widehat{X}, \widehat{Y}, \hat{t})|=0$, and as $(\widehat{X}, \widehat{Y}, \hat{t})$ is an arbitrary but fixed point in the argument, we can conclude that $u \equiv 0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$. This completes the proof of uniqueness and hence the proof of Theorem 3.3.

## 7. An alternative proof of Theorem 1.1 along the lines of [Fabes and Salsa 1983]

In this section we give, as we believe that the argument may be of independent interest in the case of operators of Kolmogorov type, a proof of the key estimate underlying Theorem 1.1 using Rellich-type inequalities instead of the structural theorem. Hence, the proof is along the lines of the corresponding proof for the heat equation in [Fabes and Salsa 1983]. To avoid formal calculations and manipulations we will, for simplicity, throughout the section assume

$$
\begin{equation*}
\text { (A1)-(A3) and that } \partial \Omega \text { is } C^{\infty} \text {-smooth. } \tag{7-1}
\end{equation*}
$$

The assumptions in (7-1) will only be used in a qualitative fashion and the constants of our quantitative estimates will only depend on $m, \kappa$ and $M$. The general case follows by approximation arguments that we leave to the interested reader.

In addition to (7-1) we also assume (1-5), i.e., that $A$ is independent of $x_{m}$. Then the unique bounded solution to the Dirichlet problem $\mathcal{L}_{\mathcal{K}} u=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}, u=f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$, equals

$$
u(\widehat{X}, \widehat{Y}, \hat{t})=\iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) f(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)
$$

and due to (7-1),

$$
K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t):=A(x) \nabla_{X} G_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t) \cdot N(X)
$$

for all $(X, Y, t) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and where $N(X)$ is the outer unit normal to $\partial \Omega$ at $X \in \partial \Omega$.
We are going to prove that if $\Delta:=\Delta_{r}\left(X_{0}, Y_{0}, t_{0}\right) \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$, then

$$
\begin{equation*}
\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / 2} \lesssim\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right| \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t)\right) \tag{7-2}
\end{equation*}
$$

for all $\tilde{\Delta} \subset \Delta$. In fact, we claim that it suffices to prove (7-2) for $\tilde{\Delta}=\Delta$. To see this, we assume that (7-2) holds for all $\Delta$ with $\tilde{\Delta}$ replaced by $\Delta$, and we start by noting that we have the representations

$$
\begin{aligned}
K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) & =A(x) \nabla_{X} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) \cdot N(X) \\
& =\frac{\mathrm{d} \omega_{\mathcal{K}}}{\mathrm{d} \sigma_{\mathcal{K}}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)=\lim _{\hat{r} \rightarrow 0} \frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta_{\hat{r}}(X, Y, t)\right)}{\sigma_{\mathcal{K}}\left(\Delta_{\hat{r}}(X, Y, t)\right)}
\end{aligned}
$$

for $(X, Y, t) \in \Delta$. Consider $(X, Y, t) \in \tilde{\Delta}$ and $\hat{r}>0$ small. Writing $\hat{\Delta}:=\Delta_{\hat{r}}(X, Y, t)$ and

$$
\begin{equation*}
\frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \hat{\Delta}\right)}{\sigma_{\mathcal{K}}(\hat{\Delta})}=\frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \hat{\Delta}\right) \omega_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, \hat{\Delta}\right)}{\omega_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, \hat{\Delta}\right) \sigma_{\mathcal{K}}(\hat{\Delta})} \tag{7-3}
\end{equation*}
$$

we first apply Lemma 4.10 to deduce

$$
\begin{equation*}
\frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \hat{\Delta}\right)}{\omega_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, \hat{\Delta}\right)} \lesssim \frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{c \hat{\Delta}, \Lambda}^{-}\right)}{G_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, A_{c \hat{\Delta}, \Lambda}^{-}\right)} \tag{7-4}
\end{equation*}
$$

Next, applying Theorem 4.8 in (7-4), and passing to the limit by letting $\hat{r} \rightarrow 0$ in (7-3),

$$
K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right) \lesssim \frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right)}{G_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right)} K_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, X, Y, t\right)
$$

Using this, and (7-2) with $\Delta$ replaced by $\tilde{\Delta}$ (which holds by the assumption), we deduce

$$
\begin{equation*}
\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / 2} \lesssim \frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right)}{G_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right) \sigma_{\mathcal{K}}(\tilde{\Delta})} \tag{7-5}
\end{equation*}
$$

However, again using the bound $G_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right) \gtrsim \tilde{r}^{2-q}$, see (5-7), we see that

$$
\begin{equation*}
\frac{G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right)}{G_{\mathcal{K}}\left(A_{c \tilde{\Delta}, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right)} \frac{1}{\sigma_{\mathcal{K}}(\tilde{\Delta})} \lesssim \tilde{r}^{-1} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right) \tag{7-6}
\end{equation*}
$$

Next, using Lemma 4.11, Lemma 4.10 and Theorem 4.12, in that order, we deduce

$$
\begin{equation*}
G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, A_{4 \tilde{\Delta}, \Lambda}^{-}\right) \lesssim \tilde{r}^{2-\boldsymbol{q}} \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right) \tag{7-7}
\end{equation*}
$$

and hence, by combining the estimates above, see that

$$
\begin{equation*}
\left(\iiint_{\tilde{\Delta}}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)\right)^{1 / 2} \lesssim \frac{\omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \tilde{\Delta}\right)}{\sigma_{\mathcal{K}}(\tilde{\Delta})} \tag{7-8}
\end{equation*}
$$

which completes the proof of our claim.
Based on the above it remains to prove (7-2) for $\tilde{\Delta}=\Delta$ and the rest of the proof is devoted to this. We note that we can without loss of generality assume that $\left(X_{0}, Y_{0}, t_{0}\right)=(0,0,0)$. A key observation in the following argument, and this is a consequence of $A$ and $\Omega$ being independent of $(Y, t)$, is that $K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)$ depends on $(\widehat{Y}, \hat{t}, Y, t)$ only through the differences $(\widehat{Y}-Y),(\hat{t}-t)$.

In particular,

$$
\begin{equation*}
K_{\mathcal{K}}(\widehat{X}, \widehat{Y}, \hat{t}, X, Y, t)=K_{\mathcal{K}}(\widehat{X}, \widehat{Y}-Y, \hat{t}-t, X, 0,0) \tag{7-9}
\end{equation*}
$$

Note that $\Delta$ is invariant under the change of coordinates $(X, Y, t) \rightarrow(X,-Y,-t)$. Hence,

$$
\begin{aligned}
I & :=\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t) \\
& =(-1)^{m+1} \iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)
\end{aligned}
$$

Using (7-9), Harnack's inequality, i.e., Lemma 4.4, and more specifically Lemma 4.6, we see that

$$
K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right) \lesssim K_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right)
$$

for all $(X, Y, t) \in \Delta$. Hence,

$$
\begin{equation*}
\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right|^{2} \lesssim K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right) K_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \tag{7-10}
\end{equation*}
$$

for all $(X, Y, t) \in \Delta$. Let

$$
\phi \in C_{0}^{\infty}\left(\mathbb{R}^{N+1} \backslash\left(\left\{A_{c \Delta, \Lambda}^{+}\right\} \cup\left\{A_{4 c \Delta, \Lambda}^{+}\right\}\right)\right)
$$

be such that

$$
\begin{equation*}
\phi(X, Y, t)=1 \tag{7-11}
\end{equation*}
$$

whenever $(X, Y, t)=\left(\left(x, x_{m}\right), Y, t\right)$ is such that $(x, Y, t) \in[-r, r]^{m-1} \times\left[-r^{3}, r^{3}\right]^{m} \times\left[-r^{2}, r^{2}\right], x_{m} \in$ $[\psi(x)-r / 16, \psi(x)+r / 16]$, and

$$
\begin{equation*}
\phi(X, Y, t)=0 \tag{7-12}
\end{equation*}
$$

whenever $(X, Y, t)=\left(\left(x, x_{m}\right), Y, t\right)$ is in the complement of the set defined through the restrictions $(x, Y, t) \in[-2 r, 2 r]^{m-1} \times\left[-(2 r)^{3},(2 r)^{3}\right]^{m} \times\left[-(2 r)^{2},(2 r)^{2}\right], x_{m} \in[\psi(x)-r / 8, \psi(x)+r / 8]$. Furthermore, we choose $\phi$ so that

$$
\begin{equation*}
\left|\nabla_{X} \phi(X, Y, t)\right| \lesssim r^{-1}, \quad\left|\left(X \cdot \nabla_{Y}-\partial_{t}\right) \phi(X, Y, t)\right| \lesssim r^{-2} \tag{7-13}
\end{equation*}
$$

whenever $(X, Y, t) \in \mathbb{R}^{N+1}$. We introduce

$$
\begin{equation*}
v(X, Y, t):=G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right), \quad \tilde{v}(X, Y, t):=G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \tag{7-14}
\end{equation*}
$$

and

$$
\begin{equation*}
\Psi(X, Y, t):=\phi(X, Y, t) \partial_{x_{m}} v(X, Y, t) \tag{7-15}
\end{equation*}
$$

Recalling that $\mathcal{L}_{X, Y, t}^{*}=\nabla_{X} \cdot\left(A(X) \nabla_{X}\right)-X \cdot \nabla_{Y}+\partial_{t}$ and using the definition of the Green's function, we see that

$$
\begin{aligned}
0 & =\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} \mathcal{L}^{*} G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \Psi(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& =\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} \mathcal{L}^{*} \tilde{v}(X, Y, t) \Psi(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

Hence

$$
\begin{aligned}
& 0=\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}}\left(\mathcal{L}^{*} \tilde{v}(X, Y, t) \Psi(X, Y, t)-\tilde{v}(X, Y, t) \mathcal{L} \Psi(X, Y, t)\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
&+\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} \tilde{v}(X, Y, t) \mathcal{L} \Psi(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

Using this identity, and integrating by parts,

$$
\begin{align*}
& 0=\iiint_{\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}} K_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \Psi(X, Y, t) \mathrm{d} \sigma_{\mathcal{K}}(X, Y, t) \\
&+\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} \tilde{v}(X, Y, t) \mathcal{L} \Psi(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{7-16}
\end{align*}
$$

Note that by construction, $\Psi(X, Y, t)=\partial_{x_{m}} v(X, Y, t)$ if $(X, Y, t) \in \Delta$. Consider the vector field $A(x) N(X)$. Obviously, $A(x) N(X) \cdot N(X) \leq \kappa$ by the boundedness of $A$ and hence we can write

$$
e_{m}=T(X)+c(X) A(x) N(X)
$$

for all $(X, Y, t) \in \Delta$ and for some function $c(\cdot)$ such that $c(X) \geq c(m, \kappa, M)$ for all $(X, Y, t) \in \Delta$. Here $T(X)$ denotes a vector tangent to $\partial \Omega$ at $X$. Using these observations we see that

$$
\Psi(X, Y, t)=\partial_{x_{m}} v(X, Y, t)=c(X) A(x) N(X) \cdot \nabla_{X} v(X, Y, t),
$$

whenever $(X, Y, t) \in \Delta$. In particular, using this and the fact that $K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}\right)$and $\Psi$ are nonnegative functions,

$$
I \lesssim\left|\iiint_{\Omega \times \mathbb{R}^{m} \times \mathbb{R}} \tilde{v}(X, Y, t) \mathcal{L} \Psi(X, Y, t) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t\right|
$$

We next observe that

$$
\begin{aligned}
\mathcal{L} \Psi(X, Y, t) & =\left(\nabla_{X}\left(A(x) \nabla_{X}\right)+X \cdot \nabla_{Y}-\partial_{t}\right) \Psi \\
& =2 A(X) \nabla_{X}\left(\partial_{x_{m}} v\right) \nabla_{X} \phi+\partial_{x_{m}} v \mathcal{L} \phi+\phi \mathcal{L}\left(\partial_{x_{m}} v\right),
\end{aligned}
$$

and that

$$
\mathcal{L} v(X, Y, t)=\mathcal{L}\left(G\left(A_{c \Delta, \Lambda}, X,-Y,-t\right)\right)=\left(\mathcal{L}^{*} G_{\mathcal{K}}\right)\left(A_{c \Delta, \Lambda}, X,-Y,-t\right)=0
$$

Using this we see that

$$
\mathcal{L}\left(\partial_{x_{m}} v\right)=\mathcal{L}\left(\partial_{x_{m}} v\right)-\partial_{x_{m}} \mathcal{L}(v)=\partial_{y_{m}} v .
$$

In particular,

$$
\mathcal{L} \Psi(X, Y, t)=2 A(x) \nabla_{X}\left(\partial_{x_{m}} v\right) \nabla_{X} \phi+\partial_{x_{m}} v \mathcal{L} \phi+\phi \partial_{y_{m}} v .
$$

We note that these calculations essentially only use that $A$ is independent of $x_{m}$. Recall that $\phi$ satisfies (7-11)-(7-13) and let

$$
E=\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \cap\{\overline{(X, Y, t): \phi(X, Y, t) \neq 0}\}
$$

Using this notation and elementary manipulations,

$$
I \lesssim I_{1}+I_{2}+I_{3}+I_{4}
$$

where

$$
\begin{aligned}
I_{1} & :=r^{-2} \iiint_{E}\left|\nabla_{X} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right| G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
I_{2} & :=r^{-1} \iiint_{E}\left|\nabla_{X} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right|\left|\nabla_{X} G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right)\right| \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
I_{3} & :=r^{-1} \iiint_{E}\left|\nabla_{X} \partial_{x_{m}} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right| G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
I_{4} & :=\iiint_{E}\left|\partial_{y_{m}} G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right| G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

Using the energy estimate of Lemma 4.1, and that

$$
\left|G_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X,-Y,-t\right)\right|+\left|G_{\mathcal{K}}\left(A_{4 c \Delta, \Lambda}^{+}, X, Y, t\right)\right| \lesssim r^{2-q}
$$

whenever $(X, Y, t) \in E$, we deduce that

$$
I_{1}+I_{2} \lesssim \sigma_{\mathcal{K}}(\Delta)^{-1}
$$

Similarly, using a slightly more involved argument, a Whitney decomposition, Lemma 4.1 and the fact that $A$ is independent of $x_{m}$, we can proceed in a manner similar to the proof of Lemma 2.6 in [Nyström 2017] to also deduce that

$$
I_{3}+I_{4} \lesssim \sigma_{\mathcal{K}}(\Delta)^{-1}
$$

Putting these estimates together we can conclude that

$$
\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}(X, Y, t)=I \lesssim \sigma_{\mathcal{K}}(\Delta)^{-1}
$$

whenever $\Delta \subset \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Furthermore, as $1 \lesssim \omega_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, \Delta\right)$, we have

$$
\left(\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right|^{2} \mathrm{~d} \sigma_{\mathcal{K}}\right)^{1 / 2} \lesssim\left(\iiint_{\Delta}\left|K_{\mathcal{K}}\left(A_{c \Delta, \Lambda}^{+}, X, Y, t\right)\right| \mathrm{d} \sigma_{\mathcal{K}}\right)
$$

which is (7-2) with $\tilde{\Delta}=\Delta$. This completes the proof.

## 8. Applications to homogenization: Theorem 1.3

By making the change of variables $(X, Y, t) \mapsto(\tilde{X}, \tilde{Y}, \tilde{t}),(X, Y, t)=\left(\epsilon \tilde{X}, \epsilon^{3} \tilde{Y}, \epsilon^{2} \tilde{t}\right)$, the boundary

$$
\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}=\left\{(X, Y, t) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \times \mathbb{R}: x_{m}=\psi(x)\right\}
$$

is transformed into

$$
\partial \Omega_{\epsilon} \times \mathbb{R}^{m} \times \mathbb{R}:=\left\{(\tilde{X}, \tilde{Y}, \tilde{t}) \in \mathbb{R}^{m} \times \mathbb{R}^{m} \times \mathbb{R}: \tilde{x}_{m}=\psi_{\epsilon}(\tilde{x})\right\},
$$

where $\psi_{\epsilon}(x):=\epsilon^{-1} \psi(\epsilon x)$. Note that $\psi$ and $\psi_{\epsilon}$ have the same Lipschitz constant. Let

$$
v_{\epsilon}(\tilde{X}, \tilde{Y}, \tilde{t}):=u_{\epsilon}(X, Y, t), \quad f_{\epsilon}\left(\tilde{x}, \psi_{\epsilon}(\tilde{x}), \tilde{Y}, \tilde{t}\right):=f(x, \psi(x), Y, t)
$$

Then,

$$
\left\{\begin{align*}
\mathcal{L}_{\mathcal{K}}^{\epsilon} u_{\epsilon}=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}  \tag{8-1}\\
u_{\epsilon}=f & \text { n.t. on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{align*}\right.
$$

where $\mathcal{L}_{\mathcal{K}}^{\epsilon}$ is as in (1-12), if and only if

$$
\left\{\begin{align*}
\mathcal{L}_{\mathcal{K}}^{1} v_{\epsilon}=0 & \text { in } \Omega_{\epsilon} \times \mathbb{R}^{m} \times \mathbb{R}  \tag{8-2}\\
v_{\epsilon}=f_{\epsilon} & \text { n.t. on } \partial \Omega_{\epsilon} \times \mathbb{R}^{m} \times \mathbb{R}
\end{align*}\right.
$$

By Theorem 1.2 we see that (8-2) has a unique weak solution which satisfies

$$
\left\|N\left(v_{\epsilon}\right)\right\|_{L^{p}\left(\partial \Omega_{\epsilon} \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \lesssim\left\|f_{\epsilon}\right\|_{L^{p}\left(\partial \Omega_{\epsilon} \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

Changing back to the ( $X, Y, t$ )-coordinates, we get that (8-1) has a unique weak solution satisfying the estimate

$$
\begin{equation*}
\left\|N\left(u_{\epsilon}\right)\right\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \lesssim\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \tag{8-3}
\end{equation*}
$$

and in the last two displays the implicit constants are also allowed to depend on $p$, but are independent of $\epsilon$ and $f$. This settles the proof of the first part of Theorem 1.3.

To settle the proof of the second part of Theorem 1.3 we want to let $\epsilon \rightarrow 0$ and prove, given $f \in$ $L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$, that $u_{\epsilon} \rightarrow \bar{u}$ and that $\bar{u}$ is a weak solution to the Dirichlet problem

$$
\left\{\begin{align*}
\overline{\mathcal{L}}_{\mathcal{K}} \bar{u}=0 & \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}  \tag{8-4}\\
\bar{u}=f & \text { n.t. on } \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}
\end{align*}\right.
$$

and that

$$
\begin{equation*}
\|N(\bar{u})\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)} \lesssim\|f\|_{L^{p}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}, \tag{8-5}
\end{equation*}
$$

where the implicit constant also is allowed to depend on $p$. Note that $\bar{A}$ is a constant matrix, and once existence is established, uniqueness for the problem stated follows from the uniqueness part of Theorem 3.3. We also note that in the following it suffices to consider the case $p=2$, again by the classical arguments in [Coifman and Fefferman 1974].

Consider $U_{X} \times U_{Y} \times J \subset \mathbb{R}^{N+1}$, where $U_{X} \subset \mathbb{R}^{m}$ and $U_{Y} \subset \mathbb{R}^{m}$ are bounded domains and $J=(a, b)$, with $-\infty<a<b<\infty$. Assume that $\overline{U_{X} \times U_{Y} \times J}$ is contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$ and that the distance from $\overline{U_{X} \times U_{Y} \times J}$ to $\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$ is $r>0$. By a covering argument with cubes of size, say, $r / 2$, Lemma 4.2, and (8-3), it follows that $u_{\epsilon}$ is uniformly bounded, with respect to $\epsilon$, in $L^{2}\left(U_{X} \times U_{Y} \times J\right)$, whenever $\overline{U_{X} \times U_{Y} \times J} \subset \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Using this, and the energy estimate of Lemma 4.1, we can conclude that

$$
\begin{equation*}
\left\|\nabla_{X} u_{\epsilon}\right\|_{L^{2}\left(U_{X} \times U_{Y} \times J\right)} \text { is uniformly bounded in } \epsilon \text {. } \tag{8-6}
\end{equation*}
$$

Next, using (8-6) and the weak formulation of the equation $\mathcal{L}_{\mathcal{K}}^{\epsilon} u_{\epsilon}=0$ it follows that $\left(X \cdot \nabla_{Y}-\partial_{t}\right) u_{\epsilon}$ is uniformly bounded, with respect to $\epsilon$, in $L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{-1}\left(U_{X}\right)\right)$. Let $W\left(U_{X} \times U_{Y} \times J\right)$ be defined as in (2-18). By the above argument we can conclude, whenever $\overline{U_{X} \times U_{Y} \times J}$ is compactly contained in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$, that

$$
\begin{equation*}
\left\|u_{\epsilon}\right\|_{W\left(U_{X} \times U_{Y} \times J\right)} \text { is uniformly bounded in } \epsilon, \tag{8-7}
\end{equation*}
$$

and, by ellipticity of $A^{\epsilon}$, that

$$
\begin{equation*}
\left\|A^{\epsilon} \nabla_{X} u_{\epsilon}\right\|_{\left(L_{X, Y, t}^{2}\left(U_{X} \times U_{Y} \times J\right)\right)^{m}} \text { is uniformly bounded in } \epsilon . \tag{8-8}
\end{equation*}
$$

Using the Sobolev embedding theorem one can prove that there exists a compact injection

$$
\begin{equation*}
W\left(U_{X} \times U_{Y} \times J\right) \rightarrow L^{2}\left(U_{X} \times U_{Y} \times J\right) \tag{8-9}
\end{equation*}
$$

Using this, (8-7) and (8-8) we see that there exists a subsequence of $\left\{u_{\epsilon}\right\}$, still denoted by $\left\{u_{\epsilon}\right\}$, such that

$$
\begin{align*}
u_{\epsilon} \rightarrow \bar{u} & \text { in } L^{2}\left(U_{X} \times U_{Y} \times J\right), \\
A^{\epsilon} \nabla_{X} u_{\epsilon} \rightarrow \xi & \text { weakly in }\left(L^{2}\left(U_{X} \times U_{Y} \times J\right)\right)^{m},  \tag{8-10}\\
\left(X \cdot \nabla_{Y}-\partial_{t}\right) u_{\epsilon} \rightarrow\left(X \cdot \nabla_{Y}-\partial_{t}\right) \bar{u} & \text { weakly in } L_{Y, t}^{2}\left(U_{Y} \times J, H_{X}^{-1}\left(U_{X}\right)\right) .
\end{align*}
$$

In particular,

$$
u_{\epsilon} \rightarrow \bar{u} \quad \text { weakly in } W\left(U_{X} \times U_{Y} \times J\right)
$$

Furthermore, using this and the local regularity estimate in Lemma 4.3 we also have that

$$
u_{\epsilon} \rightarrow \bar{u}, \quad \text { locally uniformly in } \Omega \times \mathbb{R}^{m} \times \mathbb{R} \text { as } \epsilon \rightarrow 0
$$

We now have sufficient information to pass to the limit in the weak formulation of the equation $\mathcal{L}_{\mathcal{K}}^{\epsilon} u_{\epsilon}=0$ and doing so we obtain

$$
\begin{equation*}
0=\iiint_{U_{X} \times U_{Y} \times J} \xi \cdot \nabla_{X} \phi \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t+\iint_{U_{Y} \times J}\left\langle\left(-X \cdot \nabla_{Y}+\partial_{t}\right) \bar{u}(\cdot, Y, t), \phi(\cdot, Y, t)\right\rangle \mathrm{d} Y \mathrm{~d} t \tag{8-11}
\end{equation*}
$$

for all $\phi \in L_{Y, t}^{2}\left(U_{Y} \times J, H_{X, 0}^{1}\left(U_{X}\right)\right)$. We need to show that $\xi=\bar{A} \nabla_{X} \bar{u}$. To this end, we consider the functions

$$
\begin{equation*}
w_{\alpha}^{\epsilon}(X):=\epsilon w_{\alpha}(X / \epsilon) \tag{8-12}
\end{equation*}
$$

with $w_{\alpha}$ defined as in (1-11). Following [Cioranescu and Donato 1999], we see that

$$
\begin{array}{ll}
w_{\alpha}^{\epsilon} \rightarrow \alpha \cdot X & \text { weakly in } H_{X}^{1}\left(U_{X}\right) \\
w_{\alpha}^{\epsilon} \rightarrow \alpha \cdot X & \text { in } L^{2}\left(U_{X}\right) \tag{8-13}
\end{array}
$$

In particular

$$
\begin{equation*}
A^{\epsilon} \nabla_{X} w_{\alpha}^{\epsilon} \rightarrow \bar{A} \alpha \quad \text { weakly in }\left(L^{2}\left(U_{X}\right)\right)^{m} \tag{8-14}
\end{equation*}
$$

and

$$
\begin{equation*}
\int A^{\epsilon}(X) \nabla_{X} w_{\alpha}^{\epsilon} \cdot \nabla_{X} \phi \mathrm{~d} X=0 \tag{8-15}
\end{equation*}
$$

for all $\phi \in C_{0}^{\infty}\left(U_{X}\right)$; see [Cioranescu and Donato 1999, Section 8.1].
Pick $\varphi \in C_{0}^{\infty}\left(U_{X}\right), \psi \in C_{0}^{\infty}\left(U_{Y} \times J\right)$. We choose $\phi=\varphi u_{\epsilon} \psi$ in (8-15), and integrate with respect to $Y$ and $t$ :

$$
\begin{equation*}
0=\iiint\left(A^{\epsilon}(X) \nabla_{X} w_{\alpha}^{\epsilon} \cdot \nabla_{X} u_{\epsilon}\right) \varphi \psi \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t+\iiint\left(A^{\epsilon}(X) \nabla_{X} w_{\alpha}^{\epsilon} \cdot \nabla_{X} \varphi\right) u_{\epsilon} \psi \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{8-16}
\end{equation*}
$$

Picking $\varphi w_{\alpha}^{\epsilon} \psi$ as a test function in the weak formulation of $\mathcal{L}_{\mathcal{K}}^{\epsilon} u_{\epsilon}=0$ yields

$$
\begin{aligned}
& 0=\iiint\left(\left(A^{\epsilon}(X) \nabla_{X} u_{\epsilon} \cdot \nabla_{X} w_{\alpha}^{\epsilon}\right) \varphi \psi+\left(A^{\epsilon}(X) \nabla_{X} u_{\epsilon} \cdot \nabla_{X} \varphi\right) w_{\alpha}^{\epsilon} \psi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
&+\iiint\left(X \cdot \nabla_{Y} \psi-\partial_{t} \psi\right) \varphi w_{\alpha}^{\epsilon} u_{\epsilon} \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

where we have used that $\varphi$ and $w_{\alpha}^{\epsilon}$ only depend on $X$ and that $\psi$ only depends on $Y$ and $t$. Subtracting the expression in the last display from (8-16) yields

$$
\begin{align*}
0=\iiint\left(\left(A^{\epsilon}(X) \nabla_{X} w_{\alpha}^{\epsilon} \cdot \nabla_{X} \varphi\right) u_{\epsilon} \psi-\left(A^{\epsilon}(X) \nabla_{X} u_{\epsilon}\right.\right. & \left.\left.\cdot \nabla_{X} \varphi\right) w_{\alpha}^{\epsilon} \psi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
& -\iiint\left(X \cdot \nabla_{Y} \psi-\partial_{t} \psi\right) \varphi w_{\alpha}^{\epsilon} u_{\epsilon} \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \tag{8-17}
\end{align*}
$$

Using (8-10), (8-13), and (8-14), we see that

$$
\begin{aligned}
\iiint\left(\left(A^{\epsilon}(X) \nabla_{X} w_{\alpha}^{\epsilon} \cdot \nabla_{X} \varphi\right) u_{\epsilon} \psi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \rightarrow \iiint\left(\left(\bar{A} \alpha \cdot \nabla_{X} \varphi\right) \bar{u} \psi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
\iiint\left(A^{\epsilon}(X) \nabla_{X} u_{\epsilon} \cdot \nabla_{X} \varphi\right) w_{\alpha}^{\epsilon} \psi \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \rightarrow \iiint\left(\xi \cdot \nabla_{X} \varphi\right)(\alpha \cdot X) \psi \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \\
\iiint\left(X \cdot \nabla_{Y} \psi-\partial_{t} \psi\right) \varphi w_{\alpha}^{\epsilon} u_{\epsilon} \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t & \rightarrow \iiint\left(X \cdot \nabla_{Y} \psi-\partial_{t} \psi\right)(\alpha \cdot X) \varphi \bar{u} \mathrm{~d} X \mathrm{~d} Y \mathrm{~d} t
\end{aligned}
$$

as $\epsilon \rightarrow 0$; i.e., passing to the limit in (8-17) we obtain

$$
\iiint\left(\left(\bar{A} \alpha \cdot \nabla_{X} \varphi\right) \bar{u} \psi-\left(\xi \cdot \nabla_{X} \varphi\right)(\alpha \cdot X) \psi-\left(X \cdot \nabla_{Y} \psi-\partial_{t} \psi\right)(\alpha \cdot X) \varphi \bar{u}\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t=0
$$

Using that

$$
\left(\nabla_{X} \varphi\right)(\alpha \cdot X) \psi=\nabla_{X}(\varphi(\alpha \cdot X) \psi)-\alpha \varphi \psi
$$

and (8-11), now with $\phi=(\alpha \cdot X) \varphi \psi$ as test function, we get

$$
\begin{equation*}
\iiint\left(\left(\bar{A} \alpha \cdot \nabla_{X} \varphi\right) \bar{u} \psi-(\xi \cdot \alpha) \varphi \psi\right) \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t=0 \tag{8-18}
\end{equation*}
$$

Since $\bar{A}$ is constant, this implies that

$$
\xi \cdot \alpha=\left(\bar{A} \nabla_{X} \bar{u}\right) \cdot \alpha \quad \text { for all } \alpha \in \mathbb{R}^{m},
$$

and consequently, $\xi=\bar{A} \nabla_{X} \bar{u}$. In particular, $\left\{u_{\epsilon}\right\}_{\epsilon>0}$ has a subsequence that converges weakly to $\bar{u}$ and $\bar{u}$ is a weak solution to $\overline{\mathcal{L}}_{\mathcal{K}} \bar{u}=0$ in $\Omega \times \mathbb{R}^{m} \times \mathbb{R}$.

Next, assume that $f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$. Then

$$
\begin{equation*}
u_{\epsilon}(X, Y, t)=\iiint K_{\epsilon}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t}) \tag{8-19}
\end{equation*}
$$

and we need to extract a convergent subsequence from the sequence of kernels $\left\{K_{\epsilon}\right\}$. Using the representation in (8-19) we see that if

$$
\begin{equation*}
(X, Y, t) \in U_{X} \times U_{Y} \times J \quad \text { and } \quad \operatorname{dist}\left(U_{X}, \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right) \geq 2 r \tag{8-20}
\end{equation*}
$$

then as above, i.e., again using a covering argument, Lemma 4.2 and (8-3), we deduce that

$$
\left|\iiint K_{\epsilon}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t})\right|=\left|u_{\epsilon}(X, Y, t)\right| \leq c\|f\|_{L^{2}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

for some positive constant $c<\infty$ independent of $\epsilon$. It thus follows by duality that

$$
\left\|K_{\epsilon}(X, Y, t, \cdot, \cdot, \cdot)\right\|_{L^{2}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)}
$$

is bounded uniformly in $\epsilon$ for $(X, Y, t)$ as in (8-20). This clearly implies that

$$
\left\|K_{\epsilon}\right\|_{L^{2}\left(U_{X} \times U_{Y} \times J \times \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \mathrm{~d} \sigma_{\mathcal{K}}\right)}
$$

is bounded uniformly in $\epsilon$. Thus, for a subsequence,

$$
K_{\epsilon} \rightarrow \bar{K}, \quad \text { as } \epsilon \rightarrow 0, \quad \text { weakly in } L^{2}\left(U_{X} \times U_{Y} \times J \times \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \mathrm{~d} \sigma_{\mathcal{K}}\right)
$$

Suppose now that $\left\{u_{\epsilon_{j}}\right\}$ converges weakly in $W\left(U_{X} \times U_{Y} \times J\right)$ to $\bar{u}$. Then, by the above argument there exists a subsequence $\left\{\epsilon_{j^{\prime}}\right\}$ of $\left\{\epsilon_{j}\right\}$ such that $K_{\epsilon_{j^{\prime}}}$ converges weakly to $\bar{K}$ in

$$
L^{2}\left(U_{X} \times U_{Y} \times J \times \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \mathrm{~d} \sigma_{\mathcal{K}}\right)
$$

This implies, as $u_{\epsilon}(X, Y, t) \rightarrow \bar{u}(X, Y, t)$, and by continuity for all $(X, Y, t)$ as in (8-20), that

$$
\begin{aligned}
u_{\epsilon}(X, Y, t) & =\iiint K_{\epsilon}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t}) \\
& \rightarrow \iiint \bar{K}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t})=\bar{u}(X, Y, t)
\end{aligned}
$$

as $\epsilon \rightarrow 0$ and for all $(X, Y, t)$ as in (8-20). As $U_{X} \times U_{Y} \times J$ is arbitrary in this argument, we conclude that for a certain subsequence of $\left\{u_{\epsilon}\right\}_{\epsilon>0}$,

$$
u_{\epsilon} \rightarrow \bar{u} \quad \text { weakly in } W_{\mathrm{loc}}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)
$$

and

$$
\begin{equation*}
K_{\epsilon} \rightarrow \bar{K} \quad \text { weakly in } L_{\mathrm{loc}}^{2}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R} \times \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \mathrm{~d} \sigma_{\mathcal{K}}\right) \tag{8-21}
\end{equation*}
$$

Furthermore,

$$
\overline{\mathcal{L}}_{\mathcal{K}} \bar{u}=0 \quad \text { in } \Omega \times \mathbb{R}^{m} \times \mathbb{R}
$$

and

$$
\bar{u}(X, Y, t)=\iiint \bar{K}(X, Y, t, \tilde{X}, \tilde{Y}, \tilde{t}) f(\tilde{X}, \tilde{Y}, \tilde{t}) \mathrm{d} \sigma_{\mathcal{K}}(\tilde{X}, \tilde{Y}, \tilde{t})
$$

whenever $(X, Y, t) \in \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. Note that the space

$$
L_{\mathrm{loc}}^{2}\left(\Omega \times \mathbb{R}^{m} \times \mathbb{R} \times \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} X \mathrm{~d} Y \mathrm{~d} t \mathrm{~d} \sigma_{\mathcal{K}}\right)
$$

in (8-21) should be interpreted as local only in the first three variables $X, Y$ and $t$. As $\bar{A}$ is a constant matrix, the Kolmogorov measure $\omega_{\overline{\mathcal{L}}_{\mathcal{K}}}$ is absolutely continuous with respect to $\sigma_{\mathcal{K}}$ and this can be seen as a consequence of Theorem 1.1. In particular, the problem $D_{\mathcal{K}}^{2}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ is uniquely solvable for the operator $\overline{\mathcal{L}}_{\mathcal{K}}$ and $\bar{K}(X, Y, t, \widetilde{X}, \widetilde{Y}, \tilde{t})$ is the Radon-Nikodym derivative of the Kolmogorov measure $\omega_{\overline{\mathcal{L}}_{\mathcal{K}}}(X, Y, t, \cdot)$ with respect to $\sigma_{\mathcal{K}}$ at $(\tilde{X}, \tilde{Y}, \tilde{t}) \in \partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}$. As a consequence, using Theorem 3.3 we can conclude that for $f \in C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ given, $\bar{u}$ is the unique solution to the problem in (8-4) which satisfies (8-5). For $f \in L^{2}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$ the same conclusion follows from the density of $C_{0}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}\right)$ in $L^{2}\left(\partial \Omega \times \mathbb{R}^{m} \times \mathbb{R}, \mathrm{d} \sigma_{\mathcal{K}}\right)$; see the final part in the proof of (i) implies (ii) in Theorem 3.3 for reference. Summing up, the proof of Theorem 1.3 is complete.

## Acknowledgement

The authors thank two anonymous referees for valuable comments and suggestions.

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Received 14 Dec 2020. Revised 15 Dec 2021. Accepted 14 Feb 2022.

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T. J. Christiansen
A structure theorem for elliptic and parabolic operators with applications to homogenization ..... 1547of operators of Kolmogorov typeMalte Litsgård and Kaj Nyström
Dimension-free Harnack inequalities for conjugate heat equations and their applications to ..... 1589geometric flowsLi-Juan Cheng and Anton Thalmaier
The regularity of the boundary of vortex patches for some nonlinear transport equations ..... 1621
Juan Carlos Cantero, Joan Mateu, Joan Orobitg and Joan Verdera
Directional square functions ..... 1651
Natalia Accomazzo, Francesco Di Plinio, Paul Hagelstein, Ioannis Parissis and Luz Roncal
Partial regularity for Navier-Stokes and liquid crystals inequalities without maximum ..... 1701principle
GABRIEL S. KOCH


[^0]:    Nyström was partially supported by grant 2017-03805 from the Swedish research council (VR).
    MSC2020: 35K65, 35K70, 35H20, 35R03.
    Keywords: Kolmogorov equation, elliptic, parabolic, ultraparabolic, hypoelliptic, operators in divergence form, Dirichlet problem, Lipschitz domain, doubling measure, elliptic measure, parabolic measure, Kolmogorov measure, $A_{\infty}$, Lie group, homogenization.

