

Amalgam Anosov representations

RICHARD D CANARY

MICHELLE LEE

MATTHEW STOVER

APPENDIX BY RICHARD D CANARY, MICHELLE LEE,

ANDRÉS SAMBARINO AND MATTHEW STOVER

Let Γ be a one-ended, torsion-free hyperbolic group and let G be a semisimple Lie group with finite center. Using the canonical JSJ splitting due to Sela, we define amalgam Anosov representations of Γ into G and prove that they form a domain of discontinuity for the action of $\text{Out}(\Gamma)$. In the appendix, we prove, using projective Anosov Schottky groups, that if the restriction of the representation to every Fuchsian or rigid vertex group of the JSJ splitting of Γ is Anosov, with respect to a fixed pair of opposite parabolic subgroups, then ρ is amalgam Anosov.

20H10, 22E40, 57M50

1 Introduction

We study the dynamics of the action of the outer automorphism group $\text{Out}(\Gamma)$ of a torsion-free word hyperbolic group Γ on the space

$$\mathbb{X}(\Gamma, G) = \text{Hom}(\Gamma, G)/G$$

of (conjugacy classes of) representations of Γ into a semisimple Lie group G . The subject is motivated by Fricke's result that the mapping class group $\text{Mod}(S)$ of a closed, oriented hyperbolic surface S acts properly discontinuously on the Teichmüller space $\mathcal{T}(S)$ of marked hyperbolic structures on S , which can be identified with a connected component of $\mathbb{X}(\pi_1(S), \text{PSL}_2(\mathbb{R}))$.

Labourie [21] introduced the notion of an Anosov representation of a word hyperbolic group Γ into a semisimple Lie group G with respect to a pair P^\pm of opposite parabolic subgroups of G . We will call a representation Anosov if it is Anosov with respect to some pair of opposite parabolic subgroups. If G has rank 1, then a representation is Anosov if and only if it is convex cocompact, so Anosov representations are natural generalizations of convex cocompact representations into the higher rank setting; see Guichard and Wienhard [16, Proposition 5.15]. Labourie [22, Theorem 1.0.2] and

Guichard and Wienhard [16, Corollary 5.4] proved (see also Canary [7, Theorem 6.2]) that $\text{Out}(\Gamma)$ acts properly discontinuously on the open subset $\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}(\Gamma, G)$ of Anosov representations. One might naturally ask whether $\mathbb{X}_A(\Gamma, G)$ is a maximal domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$.

In this paper we define amalgam Anosov representations of a one-ended, torsion-free hyperbolic group Γ into a semisimple Lie group G and prove that the space $\mathbb{X}_{A^2}(\Gamma, G)$ of amalgam Anosov representations is a domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$ that contains $\mathbb{X}_A(\Gamma, G)$. In Section 7, we exhibit examples in which $\mathbb{X}_{A^2}(\Gamma, G)$ is strictly larger than $\mathbb{X}_A(\Gamma, G)$.

Theorem 1.1 *Let Γ be a one-ended, torsion-free hyperbolic group and let G be a semisimple Lie group with finite center. Then the subset $\mathbb{X}_{A^2}(\Gamma, G)$ of $\mathbb{X}(\Gamma, G)$ consisting of amalgam Anosov representations is an open $\text{Out}(\Gamma)$ -invariant subset of $\mathbb{X}(\Gamma, G)$ such that*

- (1) $\mathbb{X}_{A^2}(\Gamma, G)$ contains the space $\mathbb{X}_A(\Gamma, G)$ of Anosov representations, and
- (2) the action of $\text{Out}(\Gamma)$ on $\mathbb{X}_{A^2}(\Gamma, G)$ is properly discontinuous.

Our definition of amalgam Anosov representations is based on Sela’s canonical JSJ splitting of a one-ended, torsion-free hyperbolic group Γ ; see Sela [31] and Bowditch [4]. Roughly, a JSJ splitting is a graph of groups decomposition for Γ such that each edge group is infinite cyclic and each vertex group is either maximal cyclic, Fuchsian, or rigid (ie admits no further \mathbb{Z} -splitting consistent with the given splitting). The JSJ splitting is preserved by every automorphism of Γ (see Section 3 for a precise statement), and therefore may be used to analyze $\text{Out}(\Gamma)$. In particular, there is a finite index subgroup of $\text{Out}(\Gamma)$ that is a central extension of the product of the mapping class groups of the Fuchsian vertex groups by a free abelian group generated by twists in the cyclic vertex groups; see Sela [31] and Levitt [25].

A representation $\rho: \Gamma \rightarrow G$ is *amalgam Anosov* if (1) the restriction of ρ to each Fuchsian vertex group is Anosov, and (2) for every cyclic vertex group Γ_v there exists a free subgroup H of Γ “registering” Γ_v such that $\rho|_H$ is Anosov. Here H is registering in the sense that, up to finite index, the group of twists in the cyclic vertex group Γ_v preserves H (up to conjugacy) and acts effectively on H . See Section 4 for a precise definition.

The key idea in the proof is that any sequence of distinct elements in $\text{Out}(\Gamma)$ has a subsequence that “projects to” a sequence of distinct elements in either the mapping class group of some Fuchsian vertex group Γ_v or in the group of twists in some cyclic vertex group Γ_v . In the first case, the fact that $\text{Out}(\Gamma_v)$ acts properly discontinuously

on $\mathbb{X}_A(\Gamma_v, G)$ guarantees that any orbit of the subsequence exits every compact subset of $\mathbb{X}_{A^2}(\Gamma, G)$, while in the second case we use the fact that $\text{Out}(H)$ acts properly discontinuously on $\mathbb{X}_A(H, G)$, where H is a subgroup registering Γ_v .

The condition that the restriction of ρ to various subgroups is Anosov is used in two distinct ways. First, the fact that Anosov representations are quasi-isometric embeddings (or, equivalently in this setting, are well-displacing) is the key ingredient in the proof of proper discontinuity. Second, the fact that the set of Anosov representations is open guarantees that $\mathbb{X}_{A^2}(\Gamma, G)$ is open. Neither fact relies on the choice of the pair of opposite parabolic subgroups, so we may allow different choices of parabolic subgroups for different subgroups in the definition.

One simple way to construct amalgam Anosov representations that are not Anosov is to glue together Anosov representations of vertex subgroups. We say that $\rho: \Gamma \rightarrow G$ is *strongly amalgam Anosov* if there exists a pair P^\pm of opposite parabolic subgroups of G such that the restriction of ρ to every rigid or Fuchsian vertex subgroup is (P^+, P^-) -Anosov. In the [appendix](#), we prove:

Theorem A.1 *Suppose that Γ is a one-ended, torsion-free word hyperbolic group and G is a semisimple Lie group with finite center. If $\rho \in \mathbb{X}(\Gamma, G)$ is strongly amalgam Anosov, then ρ is amalgam Anosov.*

The key tool in the proof of [Theorem A.1](#) is that, given a generic collection of finitely many biproximal elements of $\text{SL}_d(\mathbb{R})$, a group generated by sufficiently high powers of these elements is a projective Anosov Schottky group. This is a natural generalization of the classical fact that given any two hyperbolic elements of $\text{PSL}_2(\mathbb{C})$ with disjoint fixed point sets, the group generated by sufficiently high powers of these elements is a Schottky group. See [Theorem A.2](#) for a precise statement. We prove [Theorem A.2](#) using work of Benoist [1; 2], Quint [30] and Guéritaud, Guichard, Kassel and Wienhard [15]. Kapovich, Leeb and Porti [19, Theorem 7.40] earlier gave a proof of a more general version of [Theorem A.2](#) using different techniques.

Historical remarks Previously this subject was studied primarily in the case when $G = \text{PSL}_2(\mathbb{C})$. Minsky [28] showed that the space $\text{PS}(F_r)$ of primitive-stable representations of a free group F_r into $\text{PSL}_2(\mathbb{C})$ is a domain of discontinuity for the action of $\text{Out}(F_r)$ on $\mathbb{X}(F_r, \text{PSL}_2(\mathbb{C}))$ properly containing the space of convex cocompact representations. This was the first example where $\mathbb{X}_A(\Gamma, G)$ was shown to fail to be a maximal domain of discontinuity. Roughly, a representation $\rho \in \mathbb{X}(F_r, \text{PSL}_2(\mathbb{C}))$ is primitive-stable if the restriction of the associated orbit map of the Cayley graph of F_r into \mathbb{H}^3 is uniformly quasi-isometric on the axis of any primitive element of F_r . Lee [24; 23] found a domain of discontinuity for the action of $\text{Out}(\Gamma)$

on $\mathbb{X}(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ that properly contains $\mathbb{X}_A(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ when Γ is either the fundamental group of a closed nonorientable surface or a nontrivial free product of free groups and surface groups.

If M is a compact hyperbolizable 3-manifold for which $\pi_1(M)$ is one-ended and not a surface group, then Canary and Storm [9] again exhibited a domain of discontinuity for the action of $\mathrm{Out}(\pi_1(M))$ on $\mathbb{X}(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$ that strictly contains $\mathbb{X}_A(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$. However, Goldman [13] conjectured that if Γ is a closed surface group, then quasifuchsian space $\mathbb{X}_A(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is a maximal domain of discontinuity for the action of $\mathrm{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$. It seems likely that if Γ is not a closed orientable surface group, then $\mathbb{X}_A(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is not a maximal domain of discontinuity.

Our work generalizes the results and methods of Canary and Storm [9] to the setting of representations of a word hyperbolic group Γ into a semisimple Lie group G with finite center. The techniques are quite different than those used by Minsky [28] and Lee [23], since the outer automorphism group of a one-ended hyperbolic group and $\mathrm{Out}(F_r)$ can be structurally quite different. However, one sees a common link in the fact that amalgam Anosov representations have the property that the restrictions of the orbit map of the Cayley graph of Γ into the symmetric space associated to G to the Fuchsian vertex groups and to the registering subgroups are quasi-isometric embeddings. Therefore both amalgam Anosov and primitive-stable representations are quasi-isometric on subsets of the Cayley graph which are large enough to establish proper discontinuity for the action, but not big enough to guarantee that the representations are quasi-isometries on the entire Cayley graph. In higher rank semisimple Lie groups the set of representations that are quasi-isometric embeddings need not be open (see Guéritaud, Guichard, Kassel and Wienhard [15, Appendix A]), so if one attempted to define an analogue of amalgam Anosov representations using only the language of quasi-isometric embeddings, one would likely not obtain an open set. However, one could use recent work of Kapovich, Leeb and Porti [19] to give an alternate definition in the language of Morse embeddings of subgroups.

Outline of the paper In Section 2, we give the definition of an Anosov representation and recall some of their basic properties. In Section 3 we describe JSJ decompositions of one-ended hyperbolic groups and the associated structure theory of their outer automorphism groups, both originally due to Sela [31]. In Section 4, we formally define amalgam Anosov representations and develop their basic properties. In Section 5, we prove the main theorem. In Section 6 we briefly introduce *strongly* amalgam Anosov representations. In Section 7 we exhibit examples where $\mathbb{X}_A(\Gamma, G)$ is a proper subset of $\mathbb{X}_{A^2}(\Gamma, G)$, examples of amalgam Anosov representations that are not

strongly amalgam Anosov, and examples where $\mathbb{X}_{A^2}(\Gamma, G)$ is not a maximal domain of discontinuity. In the [appendix](#), we establish [Theorem A.1](#).

Acknowledgements The authors thank Fanny Kassel for conversations related to the [appendix](#) and her work with Guéritaud, Guichard and Wienhard, and for suggesting that [Lemma A.4](#) should be true. The authors also thank the referee for many helpful comments on the original version of the manuscript.

This material is based upon work supported by the National Science Foundation under grant numbers DMS-1045119, DMS-130692 and DMS-1361000. The authors also acknowledge support from the GEAR network (NSF grants DMS-1107452, DMS-1107263 and DMS-1107367).

2 Anosov representations

In this section, we recall the definition and basic properties of Anosov representations; see Labourie [\[21; 22\]](#) and Guichard and Wienhard [\[16\]](#) for further details. We finish the section with a brief discussion of the special case of projective Anosov representations.

2.1 Definitions

We first recall that Gromov [\[14\]](#) defined a *geodesic flow* $(U_0\Gamma, \{\phi_t\})$ associated with a hyperbolic group Γ . See Champetier [\[11\]](#) or Mineyev [\[27, Theorem 60\]](#) for further details. We follow Mineyev [\[27\]](#), since his definition gives properties best suited to our applications.

Let $\partial_\infty\Gamma^{(2)}$ be the space of pairs of distinct points on the Gromov boundary $\partial_\infty\Gamma$ of Γ . Mineyev [\[27\]](#) showed that there exists a flow $\{\tilde{\phi}_t\}$ on

$$\widetilde{U_0\Gamma} = \partial_\infty\Gamma^{(2)} \times \mathbb{R},$$

where \mathbb{R} acts by translation on the real factor, and a metric on $\widetilde{U_0\Gamma}$ such that $\{\tilde{\phi}_t\}$ satisfies the following properties:

- (1) Γ acts cocompactly and by isometries on $\widetilde{U_0\Gamma}$ so that any element γ in Γ takes the leaf $(z^+, z^-) \times \mathbb{R}$ to the leaf $(\gamma(z^+), \gamma(z^-)) \times \mathbb{R}$.
- (2) The action of \mathbb{R} by translation along the flow is bi-Lipschitz.
- (3) The actions of Γ and \mathbb{R} commute.
- (4) $t \mapsto \tilde{\phi}_t(y)$ is an isometric embedding of \mathbb{R} into $\widetilde{U_0\Gamma}$ for all $y \in \widetilde{U_0\Gamma}$.

Thus the flow descends to a flow $\{\phi_t\}$ on $U_0\Gamma = \widetilde{U_0\Gamma} / \Gamma$. While the construction depends on many choices, any flow space with the above properties will suffice to serve as the geodesic flow in the definition of an Anosov representation. For example, if Γ is the fundamental group of a closed negatively curved manifold M , then one may take $\widetilde{U_0\Gamma}$ to be the geodesic flow on the unit tangent bundle T^1M .

Let G be a real semisimple Lie group with finite center, (P^+, P^-) a pair of opposite parabolic subgroups of G , and \mathcal{F}^\pm the (compact) flag variety G/P^\pm . Consider the Levi subgroup $L = P^+ \cap P^-$ associated with (P^+, P^-) , and let $X = X(P^+, P^-)$ be the space G/L , considered as an open subspace of $\mathcal{F}^+ \times \mathcal{F}^-$. This naturally equips X with a pair E^\pm of transverse distributions. If $\rho: \Gamma \rightarrow G$ is a representation, let $\widetilde{\mathcal{X}}_\rho = \widetilde{U_0\Gamma} \times X$ be the trivial X -bundle over $\widetilde{U_0\Gamma}$. Then Γ acts on $\widetilde{\mathcal{X}}_\rho$ so that $\gamma(y, x) = (\gamma(y), \rho(\gamma)(x))$ for all $\gamma \in \Gamma$. The quotient

$$\mathcal{X}_\rho = \Gamma \backslash \widetilde{\mathcal{X}}_\rho$$

is a bundle over $U_0\Gamma$ with fiber X . The distributions E^\pm on X induce associated distributions, also called E^\pm , on \mathcal{X}_ρ .

A representation $\rho: \Gamma \rightarrow G$ is (P^+, P^-) -Anosov if there exists a continuous section $\sigma: U_0\Gamma \rightarrow \mathcal{X}_\rho$ such that:

- (i) The section σ is flat along \mathbb{R} -orbits.
- (ii) The (lifted) action of ϕ_t on the pullback σ^*E^+ (resp. σ^*E^-) dilates (resp. contracts).

A section satisfying the above conditions will be called an *Anosov section*.

2.2 Basic properties

We say that $\rho: \Gamma \rightarrow G$ is an Anosov representation if there exist a pair P^\pm of proper opposite parabolic subgroups of G such that ρ is (P^+, P^-) -Anosov with respect to the pair P^\pm . The following summarizes the key properties of Anosov representations established by Labourie [21] and Guichard and Wienhard [16].

Theorem 2.1 *Let Γ be a torsion-free hyperbolic group and G be a semisimple Lie group with finite center.*

- (1) *The set $\mathbb{X}_A(\Gamma, G)$ of Anosov representations of Γ into G is open in $\mathbb{X}(\Gamma, G)$.*
- (2) *Every representation $\rho \in \mathbb{X}_A(\Gamma, G)$ is discrete and faithful.*
- (3) *Every representation $\rho \in \mathbb{X}_A(\Gamma, G)$ is a quasi-isometric embedding (with respect to any word metric on Γ and any left-invariant Riemannian metric on G).*

- (4) If G has real rank 1, then $\rho \in \mathbb{X}(\Gamma, G)$ is Anosov if and only if it is convex cocompact.
- (5) Every $\rho \in \mathbb{X}_A(\Gamma, G)$ is well-displacing.

Recall that a representation is *well-displacing* if there exists (J, B) so that

$$\frac{1}{J} \|\gamma\| - B \leq \ell_\rho(\gamma) \leq J \|\gamma\| + B,$$

where $\|\gamma\|$ denotes the translation length of γ on the Cayley graph of Γ , with respect to some fixed generating set, and $\ell_\rho(\gamma)$ denotes the minimal translation length of the action of $\rho(\gamma)$ on G .

The fact that Anosov representations are well-displacing — in fact, uniformly well-displacing on compact subsets of $\mathbb{X}_A(\Gamma, G)$ — can be used to show that $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}_A(\Gamma, G)$. Labourie [22] proved this in the setting of the Hitchin component of representations of a closed surface group into $\text{PSL}_n(\mathbb{R})$, while Guichard and Wienhard [16] established it in full generality; see also Canary [7]. Recall that the action of $\text{Aut}(\Gamma)$ on $\text{Hom}(\Gamma, G)$ given by $\phi(\rho) = \rho \circ \phi^{-1}$, for all $\phi \in \text{Aut}(\Gamma)$ and $\rho \in \text{Hom}(\Gamma, G)$, descends to an action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$.

In fact, we will need the following strengthening of the fact that $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}_A(\Gamma, G)$. We recall that a sequence $\{A_n\}_{n \in \mathbb{N}}$ of subsets of a topological space Y is said to *exit every compact subset of X* if given any compact subset R of Y , there exists N such that $A_n \cap R = \emptyset$ for $n \geq N$. Notice that $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}_A(\Gamma, G)$ if and only if whenever $\{\alpha_j\}$ is a sequence of distinct elements in $\text{Out}(\Gamma)$ and R is a compact subset of $\mathbb{X}_A(\Gamma, G)$, then $\{\alpha_j(R)\}$ exits every compact subset of $\mathbb{X}_A(\Gamma, G)$.

Theorem 2.2 (Guichard and Wienhard [16, Corollary 5.4]) *If Γ is a torsion-free word hyperbolic group, then $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}_A(\Gamma, G)$. Moreover, if R is a compact set in $\mathbb{X}_A(\Gamma, G)$ and $\{\alpha_j\}$ is a sequence of distinct elements in $\text{Out}(\Gamma)$, then $\{\alpha_j(R)\}$ exits every compact subset of the entire representation space $\mathbb{X}(\Gamma, G)$.*

Remark Although the referenced statements only give proper discontinuity, it is easy to see that the proof yields the exiting behavior. We sketch the argument; see Canary [7, Theorem 6.2]. If R is a compact subset of $\mathbb{X}_A(\Gamma, G)$, then there exists (J, B) such that every $\rho \in R$ is (J, B) -well-displacing. If $\{\phi_n\}$ is a sequence of distinct elements of $\text{Out}(\Gamma)$, then there exists $\beta \in \Gamma$ so that $\|\phi_n^{-1}(\beta)\| \rightarrow \infty$. Therefore, $\inf_{\rho \in R} \ell_\rho(\phi_n^{-1}(\beta)) \rightarrow \infty$, which implies that $\phi_n(R)$ exits every compact subset of $\mathbb{X}(\Gamma, G)$.

We also observe below that the restriction of an Anosov representation to a hyperbolic subgroup is Anosov if and only if the subgroup is quasiconvex.

Lemma 2.3 *Suppose that Γ is a word hyperbolic group, G is a semisimple Lie group with finite center, and P^\pm is a pair of proper opposite parabolic subgroups. If $\rho: \Gamma \rightarrow G$ is a (P^+, P^-) -Anosov representation and Λ is a word hyperbolic subgroup of Γ , then $\rho|_\Lambda$ is (P^+, P^-) -Anosov if and only if Λ is a quasiconvex subgroup of Γ .*

Proof We first suppose that Λ is quasiconvex. There is a continuous injection $\eta: \partial_\infty \Lambda \rightarrow \partial_\infty \Gamma$, which is called the *Cannon–Thurston map*. Consider the subset of $\widetilde{U}_0 \Gamma$ given by $\widetilde{U}_0 \Lambda = \partial \Lambda^{(2)} \times \mathbb{R}$. The action of Γ on $\widetilde{U}_0 \Gamma$ restricts to an action of Λ on $\widetilde{U}_0 \Lambda$ with properties (1)–(4) of Section 2.1. We can therefore regard $U_0 \Lambda = \widetilde{U}_0 \Lambda / \Lambda$ as the geodesic flow of Λ .

Let $\sigma: U_0 \Gamma \rightarrow \mathcal{X}_\rho$ be an Anosov section. Then σ lifts to a section $\tilde{\sigma}: \widetilde{U}_0 \Gamma \rightarrow \widetilde{\mathcal{X}}_\rho$. One then checks that the restriction of $\tilde{\sigma}$ to $\widetilde{U}_0 \Lambda$ descends to an Anosov section of $\mathcal{X}_{\rho|_\Lambda}$. Therefore, $\rho|_\Lambda$ is (P^+, P^-) -Anosov.

Conversely, suppose that ρ_Λ is (P^+, P^-) -Anosov. Since ρ quasi-isometrically embeds both Λ and Γ into G , it follows that Λ is quasi-isometrically embedded in Γ , hence is quasiconvex. □

2.3 Projective Anosov representations

If $G = \text{SL}_d(\mathbb{R})$, P^+ is the stabilizer of a line in \mathbb{R}^d and P^- is the stabilizer of a complementary hyperplane, then a (P^+, P^-) -Anosov representation $\rho: \Gamma \rightarrow \text{SL}_d(\mathbb{R})$ is called *projective Anosov*.

If $\rho: \Gamma \rightarrow \text{SL}_d(\mathbb{R})$ is a projective Anosov representation, then

$$G/L \subset G/P^+ \times G/P^- = \mathbb{P}(\mathbb{R}^d) \times \mathbb{P}(\mathbb{R}^d)^*,$$

and the associated section $\sigma: U_0 \Gamma \rightarrow \mathcal{X}_\rho$ lifts to a section

$$\tilde{\sigma}: \widetilde{U}_0 \Gamma \rightarrow \widetilde{\mathcal{X}}_\rho = \widetilde{U}_0 \Gamma \times G/L \subset \widetilde{U}_0 \Gamma \times \mathbb{P}(\mathbb{R}^d) \times \mathbb{P}(\mathbb{R}^d)^*.$$

The defining properties of an Anosov section imply that

$$\tilde{\sigma}(x, y, t) = ((x, y, t), \xi(x), \theta(y)),$$

where

$$\xi: \partial \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta: \partial \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*$$

are ρ -equivariant continuous injective maps. Moreover, since $\tilde{\sigma}(\widetilde{U}_0 \Gamma) \subset \widetilde{U}_0 \Gamma \times G/L$, the maps ξ and θ are *transverse*, ie if x and y are distinct points in $\partial \Gamma$, then $\xi(x)$

and $\theta(y)$ span \mathbb{R}^d . Notice that here we are making use of the canonical identification of $\mathbb{P}(\mathbb{R}^d)^*$ with the Grassmannian of hyperplanes in \mathbb{R}^d . (See Guichard and Wienhard [16, Section 2.2] for details.)

In many situations, the existence of transverse ρ -equivariant limit maps is enough to guarantee that ρ is projective Anosov. For example, we have the following.

Proposition 2.4 (Guichard and Wienhard [16, Proposition 4.10]) *If Γ is a word hyperbolic group, $\rho: \Gamma \rightarrow \mathrm{SL}_d(\mathbb{R})$ is an irreducible representation, and there exist transverse ρ -equivariant continuous injections $\xi: \partial\Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)$ and $\theta: \partial\Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*$, then ρ is projective Anosov.*

Moreover, Guichard and Wienhard [16, Proposition 4.3 and Remark 4.12] showed that one can often use a *Plücker representation* to reduce problems about general Anosov representations to problems about projective Anosov representations; see also Bridgeman, Canary, Labourie and Sambarino [5, Corollary 2.13].

Proposition 2.5 (Guichard and Wienhard [16]) *If G is a semisimple Lie group with finite center and P^\pm is a pair of proper opposite parabolic subgroups, then there exists an integer $d = d(G, P^\pm)$ and an irreducible representation*

$$\tau: G \rightarrow \mathrm{SL}_d(\mathbb{R})$$

such that if Γ is word hyperbolic, then $\rho: \Gamma \rightarrow G$ is (P^+, P^-) -Anosov if and only if $\tau \circ \rho$ is projective Anosov.

3 JSJ decompositions

In this section, we recall the JSJ decomposition of a one-ended, torsion-free word hyperbolic group Γ and the associated structure theory for $\mathrm{Out}(\Gamma)$. We refer the reader to Gromov [14] and Bridson and Haefliger [6] for basics on hyperbolic groups and to Serre [32] for the theory of graphs of groups. Recall that a torsion-free word hyperbolic group is one-ended if and only if it is freely indecomposable but not cyclic.

If Γ is the fundamental group of a finite graph of groups $\mathcal{G}(V, E)$ and every edge group is a cyclic subgroup of Γ , then $\mathcal{G}(V, E)$ is a \mathbb{Z} -splitting of Γ . A vertex group Γ_v of $\mathcal{G}(V, E)$ is *Fuchsian* if Γ_v is not cyclic and there exists a compact surface F_v with boundary ∂F_v such that $\Gamma_v \cong \pi_1(F_v)$ and the edge groups adjacent to v are exactly the (conjugacy classes of) cyclic subgroups of Γ_v associated with components of ∂F_v . A vertex group Γ_v is *rigid* if it is not infinite cyclic or Fuchsian and does not admit a

\mathbb{Z} -splitting for which every edge group adjacent to v is conjugate into a vertex group in the \mathbb{Z} -splitting of Γ_v .

Sela [31] developed a canonical JSJ decomposition for one-ended word hyperbolic groups. We use a version due to Bowditch [4], which essentially agrees with Sela's in the torsion-free case and provides slightly stronger uniqueness results. The following theorem records the key properties of the JSJ splitting.

Theorem 3.1 (Bowditch [4]; Sela [31]) *If Γ is a torsion-free, one-ended, indecomposable hyperbolic group, there exists a canonical \mathbb{Z} -splitting $\Gamma \cong \pi_1(\mathcal{G}(V, E))$ of Γ , called the JSJ splitting, where each vertex group is either a maximal infinite cyclic subgroup of Γ , a maximal Fuchsian subgroup, or a rigid vertex group, such that:*

- (1) *No two vertices of the same type are adjacent and no Fuchsian vertex is adjacent to a rigid vertex.*
- (2) *Every vertex group is a quasiconvex subgroup of Γ .*
- (3) *If H is an infinite cyclic subgroup of Γ and Γ splits over H , then H can be conjugated into an infinite cyclic or Fuchsian vertex group.*
- (4) *If $\phi \in \text{Aut}(\Gamma)$ and $v \in V$, then there exists $w \in V$ so that $\phi(\Gamma_v)$ is conjugate to Γ_w .*

Remark Any graph of groups decomposition of Γ gives rise to a Bass–Serre tree. Bowditch's JSJ splitting is canonical in the sense that the Bass–Serre trees associated to any two JSJ splittings are Γ -equivariantly isomorphic. In particular, the collection of vertex groups is well-defined up to conjugacy. In the language of Bass–Serre trees, one can strengthen (4) to say that if $\phi \in \text{Aut}(\Gamma)$, then there is an automorphism H_ϕ of the Bass–Serre tree that conjugates the action of Γ to the action twisted by ϕ , ie the action of $\phi(\gamma)H_\phi$ agrees with the action of $H_\phi\gamma$ for all $\gamma \in \Gamma$.

Sela [31] used the JSJ splitting of Γ to obtain a decomposition of a finite index subgroup of $\text{Out}(\Gamma)$; see also Levitt [25]. Let $\text{Out}_1(\Gamma)$ denote the finite index subgroup of $\text{Out}(\Gamma)$ consisting of all elements ϕ such that if $v \in V$, then $\phi(\Gamma_v)$ is conjugate to Γ_v . Notice that this property is invariant under inner automorphisms, so it makes sense in $\text{Out}(\Gamma)$.

If Δ is a subgroup of Γ , then there is a restriction map

$$r_\Delta: \mathbb{X}(\Gamma, G) \rightarrow \mathbb{X}(\Delta, G),$$

where $r_\Delta(\rho) = \rho|_\Delta$. If $v \in V$, the normalizer of Γ_v in Γ is exactly Γ_v , which follows immediately from [6, Proposition III.Γ.16] if Γ_v is cyclic and from [10, Lemma 2.1] otherwise. Therefore, we obtain a well-defined map

$$\psi_v: \text{Out}_1(\Gamma) \rightarrow \text{Out}(\Gamma_v),$$

such that

$$r_{\Gamma_v}(\rho \circ \phi) = r_{\Gamma_v}(\rho) \circ \psi_v(\phi)$$

for all $\rho \in \mathbb{X}(\Gamma, G)$ and $\phi \in \text{Out}_1(\Gamma)$. Note that $\rho \circ \phi = \phi^{-1}(\rho)$ is well-defined since inner automorphisms of Γ act trivially on $\mathbb{X}(\Gamma, G)$.

If Γ_v is a Fuchsian vertex group, let $\text{Mod}_0(F_v)$ be the group of isotopy classes of homeomorphisms of F_v whose restriction to ∂F_v is homotopic to the identity. Equivalently, this is the subgroup of $\text{Out}(\Gamma_v)$ consisting of outer automorphisms preserving the conjugacy class of each peripheral element. Every element of $\text{Mod}_0(F_v)$ extends, though not uniquely, to an outer automorphism of Γ .

Let $\text{Out}_0(\Gamma)$ denote the subgroup of $\text{Out}_1(\Gamma)$ consisting of all $\phi \in \text{Out}_1(\Gamma)$ such that $\psi_v(\phi)$ is trivial if Γ_v is rigid or cyclic and $\psi_v(\phi) \in \text{Mod}_0(F_v)$ if Γ_v is Fuchsian. Define

$$\text{Mod}_F(\Gamma) = \bigoplus_{v \in V_f} \text{Mod}_0(F_v),$$

where V_f is the collection of Fuchsian vertices, and consider the homomorphism

$$\psi = \bigoplus_{v \in V_f} \psi_v: \text{Out}_0(\Gamma) \rightarrow \text{Mod}_F(\Gamma).$$

The kernel of ψ is generated by twists about cyclic vertex groups; see Levitt [25, Proposition 2.2]. If Γ_v is a cyclic vertex group and e is an edge with v as an endpoint, then there is an associated amalgamated free product $\Gamma = A *_{\Gamma_e} B$ (if e is separating) or HNN extension $\Gamma = A *_{\Gamma_e}$ (if e does not separate) and $\Gamma_v \subset A$. If $z \in \Gamma_v$, we define the *twist* $D_{z,e}$ as the image in $\text{Out}(\Gamma)$ of the automorphism that acts trivially on A and by conjugation by z on B in the amalgamated free product case, and acts by taking the stable letter t to zt in the HNN case. Notice that this definition is motivated by the group-theoretical reformulation of a Dehn twist about a simple closed curve on a surface. If v is a cyclic vertex, then the *characteristic twist subgroup* \mathcal{T}_v is the group generated by all twists about the cyclic vertex group Γ_v .

Let \mathcal{T} be the subgroup of $\text{Out}_0(\Gamma)$ generated by all characteristic twist groups. The group \mathcal{T} is free abelian. Moreover,

$$\mathcal{T} = \bigoplus_{v \in V_c} \mathcal{T}_v,$$

where V_c is the collection of cyclic vertices and each \mathcal{T}_v is a free abelian group of rank $n_v - 1$, where n_v is the number of edges adjacent to v ; see Levitt [25, Proposition 3.1 and Theorem 5.1]. For each $v \in V_c$, let

$$p_v: \mathcal{T} \rightarrow \mathcal{T}_v$$

be the obvious projection map.

Sela proved that $\text{Out}_0(\Gamma)$ has finite index in $\text{Out}(\Gamma)$ and is a central extension of $\text{Mod}_F(\Gamma)$ by \mathcal{T} .

Theorem 3.2 (Levitt [25, Theorem 5.1]; Sela [31, Theorem 1.9(ii)]) *Let Γ be a one-ended, torsion-free hyperbolic group with JSJ splitting $\mathcal{G}(V, E)$. Then, $\text{Out}_0(\Gamma)$ is a finite index subgroup of $\text{Out}(\Gamma)$ and $\psi: \text{Out}_0(\Gamma) \rightarrow \text{Mod}_F(\Gamma)$ gives rise to a central extension*

$$\{1\} \rightarrow \mathcal{T} \rightarrow \text{Out}_0(\Gamma) \xrightarrow{\psi} \text{Mod}_F(\Gamma) \rightarrow \{1\}.$$

4 Basic properties of amalgam Anosov representations

We are almost ready for the precise definition of an amalgam Anosov representation. It only remains to carefully define what it means to register a cyclic vertex group. Suppose that Γ_v is a cyclic vertex group and $\{w_1, \dots, w_{n_v}\}$ are the vertices of $\mathcal{G}(V, E)$ adjacent to v . We say that a free subgroup H of Γ registers Γ_v if H is freely generated by nontrivial elements $a_0 \in \Gamma_v$ and $\{a_1, \dots, a_{n_v}\}$ where $a_i \in \Gamma_{w_i}$ for each i . We will see that this implies that a finite index subgroup of the twist group \mathcal{T}_v preserves H (up to conjugacy) and embeds in $\text{Out}(H)$.

Definition 4.1 If Γ is a one-ended word hyperbolic group and G is a semisimple Lie group, we say that a representation $\rho \in \mathbb{X}(\Gamma, G)$ is *amalgam Anosov* if it satisfies the following two conditions:

- (1) If Γ_v is a Fuchsian vertex group, then $\rho|_{\Gamma_v}$ is Anosov.
- (2) If Γ_v is a cyclic vertex group, then there exists a free subgroup H of Γ that registers Γ_v such that $\rho|_H$ is Anosov.

We emphasize that the restricted representations of the form $\rho|_{\Gamma_v}$ or $\rho|_H$ in the above definition need not all be Anosov with respect to the same pair of opposite parabolic subgroups of G . We will see that the space $\mathbb{X}_{A^2}(\Gamma, G)$ of amalgam Anosov representations of Γ into G is an open, $\text{Out}(\Gamma)$ -invariant subset of $\mathbb{X}(\Gamma, G)$ and that Anosov representations are amalgam Anosov, ie $\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G)$.

It will be convenient to introduce some notation. Let

$$\mathbb{X}_F(\Gamma, G) = \bigcap_{v \in V_f} r_{\Gamma_v}^{-1}(\mathbb{X}_A(\Gamma_v, G)),$$

where V_f is the collection of Fuchsian vertices and $r_{\Gamma_v}: \mathbb{X}(\Gamma, G) \rightarrow \mathbb{X}(\Gamma_v, G)$ is the restriction map for each $v \in V_f$. Similarly, if $v \in V_c$ is a cyclic vertex, let

$$\mathbb{X}_v(\Gamma, G) = \bigcup_{H \text{ registers } \Gamma_v} r_H^{-1}(\mathbb{X}_A(H, G)) \quad \text{and} \quad \mathbb{X}_C(\Gamma, G) = \bigcap_{v \in V_c} \mathbb{X}_v(\Gamma_v, G).$$

Notice that $\mathbb{X}_{A^2}(\Gamma, G) = \mathbb{X}_C(\Gamma, G) \cap \mathbb{X}_F(\Gamma, G)$.

Proposition 4.2 *If Γ is a one-ended, torsion-free word hyperbolic group and G is a semisimple Lie group with finite center, $\mathbb{X}_{A^2}(\Gamma, G)$ is an open, $\text{Out}(\Gamma)$ -invariant subset of $\mathbb{X}(\Gamma, G)$ and*

$$\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G).$$

Further, $\mathbb{X}_C(\Gamma, G)$ and $\mathbb{X}_F(\Gamma, G)$ are also open, $\text{Out}(\Gamma)$ -invariant subsets of $\mathbb{X}(\Gamma, G)$.

Proof Since each r_{Γ_v} is continuous, each $\mathbb{X}_A(\Gamma_v, G)$ is open in $\mathbb{X}(\Gamma_v, G)$, and there are only finitely many Fuchsian vertex groups, $\mathbb{X}_F(\Gamma, G)$ is open in $\mathbb{X}(\Gamma, G)$. If v is a Fuchsian vertex and $\phi \in \text{Out}(\Gamma)$, then there exists a Fuchsian vertex w so that $\phi(\Gamma_v)$ is conjugate to Γ_w . It follows, since $\phi(\rho) = \rho \circ \phi^{-1}$, that

$$\phi(r_{\Gamma_v}^{-1}(\mathbb{X}_A(\Gamma_v, G))) = r_{\Gamma_w}^{-1}(\mathbb{X}_A(\Gamma_w, G)).$$

Therefore, $\mathbb{X}_F(\Gamma, G)$ is $\text{Out}(\Gamma)$ -invariant.

If H registers a cyclic vertex group Γ_v , then since $\mathbb{X}_A(H, G)$ is open in $\mathbb{X}(H, G)$ and r_H is continuous, $r_H^{-1}(\mathbb{X}_A(H, G))$ is open in $\mathbb{X}(\Gamma, G)$, so $\mathbb{X}_v(\Gamma, G)$ is an open subset of $\mathbb{X}(\Gamma, G)$. Since there are only finitely many cyclic vertex groups, $\mathbb{X}_C(\Gamma, G)$ is open in $\mathbb{X}(\Gamma, G)$. If $\phi \in \text{Out}(\Gamma)$, then ϕ permutes the cyclic vertex groups and takes registering subgroups to registering subgroups (up to conjugacy), so $\mathbb{X}_C(\Gamma, G)$ is $\text{Out}(\Gamma)$ -invariant.

Since $\mathbb{X}_C(\Gamma, G)$ and $\mathbb{X}_F(\Gamma, G)$ are open and $\text{Out}(\Gamma)$ -invariant in $\mathbb{X}(\Gamma, G)$, their intersection $\mathbb{X}_{A^2}(\Gamma, G)$ is as well.

We will need the following lemma in the proof that $\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G)$.

Lemma 4.3 *If Γ is a one-ended, torsion-free word hyperbolic group and Γ_v is a cyclic vertex group of its JSJ splitting, there exists a quasiconvex subgroup $H \subset \Gamma$ that registers Γ_v .*

Proof Choose a generator a for Γ_v , and for each vertex w_i adjacent to v by the edge e_i let g_i be an element of Γ_{w_i} , no power of which lies in the edge group Γ_{e_i} . Such an element g_i exists because Γ_{w_i} is not virtually cyclic.

Applying a ping-pong argument (eg Bridson and Haefliger [6, Section III. Γ .3]) one sees that there exists N so that, for all $n \geq N$, the group H_n generated by $\{a^n, g_1^n, \dots, g_{n_v}^n\}$ is a free subgroup of Γ freely generated by $\{a^n, g_1^n, \dots, g_{n_v}^n\}$. Thus, H_n is a registering subgroup for T . Moreover, one may choose N large enough so that H_n is quasiconvex for all $n \geq N$; see Gitik [12]. □

Let $\rho: \Gamma \rightarrow G$ be Anosov with respect to the parabolic subgroups P^\pm of G . If Γ_v is a Fuchsian vertex group of the JSJ decomposition of Γ , then Γ_v is a quasiconvex subgroup of Γ (see [Theorem 3.1](#)), so [Lemma 2.3](#) implies that $\rho|_{\Gamma_v}$ is Anosov. If Γ_v is a cyclic vertex subgroup, then [Lemma 4.3](#) guarantees that there exists a quasiconvex subgroup H of Γ that registers Γ_v . Therefore, again by [Lemma 2.3](#), H registers Γ_v and $\rho|_H$ is Anosov. It follows that ρ is amalgam Anosov. \square

Remark The fact that $\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G)$ can also be obtained almost immediately by combining [Theorem A.1](#) and [Lemma 2.3](#), but in the proof of [Proposition 4.2](#) we give a more self-contained and elementary argument.

When we construct examples it will be useful to observe that the Plücker representation interacts well with the definition of amalgam Anosov representations, especially when G has real rank 1.

Lemma 4.4 *Let G be a semisimple Lie group with finite center, P^\pm be a pair of proper opposite parabolic subgroups of G and $\tau: G \rightarrow \mathrm{SL}_d(\mathbb{R})$ be the Plücker representation given by [Proposition 2.5](#). If Γ is a one-ended, torsion-free hyperbolic group and $\rho: \Gamma \rightarrow G$ is a representation such that the restriction of ρ to each Fuchsian vertex subgroup of Γ is (P^+, P^-) -Anosov and for each cyclic vertex group Γ_v of Γ there is a registering subgroup H , such that $\rho|_H$ is (P^+, P^-) -Anosov, then $\tau \circ \rho$ is amalgam Anosov.*

In particular, if G has rank 1 and $\rho: \Gamma \rightarrow G$ is amalgam Anosov, then $\tau \circ \rho$ is amalgam Anosov.

Proof Properties (1) and (2) in [Definition 4.1](#) of an amalgam Anosov representation and [Proposition 2.5](#) imply that the restriction of $\tau \circ \rho$ to any Fuchsian vertex group is projective Anosov. Further, it implies that for each cyclic vertex group Γ_v of Γ there is a subgroup H registering Γ_v such that $(\tau \circ \rho)|_H$ is projective Anosov. Therefore, $\tau \circ \rho$ is amalgam Anosov.

If G has real rank 1, there is a unique conjugacy class of pairs of proper opposite parabolic subgroups. Consequently, every amalgam Anosov representation satisfies the assumptions of the lemma. \square

5 Proof of the main theorem

In this section we give the proof of our main result, [Theorem 1.1](#). Since $\mathrm{Out}_0(\Gamma)$ has finite index in $\mathrm{Out}(\Gamma)$, [Theorem 1.1](#) follows from [Proposition 4.2](#) and the following strong proper discontinuity result.

Proposition 5.1 *If R is a compact subset of $\mathbb{X}_{A^2}(\Gamma, G)$ and $\{\phi_n\}$ is a sequence of distinct elements of $\text{Out}_0(\Gamma)$, then $\{\phi_n(R)\}$ exits every compact subset of the entire representation space $\mathbb{X}(\Gamma, G)$.*

We break the proof of [Proposition 5.1](#) into the analysis of sequences in the twist group \mathcal{T} and sequences that project to a sequence of distinct elements of $\text{Mod}_F(\Gamma)$.

The following lemma is a nearly immediate consequence of [Theorem 2.2](#) and our definitions.

Lemma 5.2 *If R is a compact subset of $\mathbb{X}_F(\Gamma, G)$ and $\{\phi_n\}$ is a sequence of elements in $\text{Out}_0(\Gamma)$ such that $\{\psi(\phi_n)\}$ is a sequence of distinct elements of $\text{Mod}_F(\Gamma)$, then $\{\phi_n(R)\}$ exits every compact subset of $\mathbb{X}(\Gamma, G)$.*

Proof If not, we can pass to a subsequence so that there exists $v \in V_f$ such that $\{\psi_v(\phi_n)\}$ is a sequence of distinct elements of $\text{Mod}_0(F_v)$ and $\{\phi_n(R)\}$ does not exit every compact subset of $\mathbb{X}(\Gamma, G)$. Then, $r_{\Gamma_v}(R)$ is a compact subset of $\mathbb{X}_A(\Gamma_v, G)$ and $\{\psi_v(\phi_n)(r_{\Gamma_v}(R))\}$ does not exit every compact subset of $\mathbb{X}(\Gamma_v, G)$. However, this contradicts [Theorem 2.2](#). □

We now use [Theorem 2.2](#) to study the action of \mathcal{T} on $\mathbb{X}_C(\Gamma, G)$.

Lemma 5.3 *If R is a compact subset of $\mathbb{X}_C(\Gamma, G)$ and $\{\phi_n\}$ is a sequence of distinct elements of \mathcal{T} , then $\{\phi_n(R)\}$ exits every compact set of $\mathbb{X}(\Gamma, G)$.*

Proof Let R be a compact subset of $\mathbb{X}_C(\Gamma, G)$. Suppose, for a contradiction, that there exists a sequence $\{\phi_n\}$ of distinct elements of \mathcal{T} such that $\{\phi_n(R)\}$ does not exit every compact subset of $\mathbb{X}(\Gamma, G)$. We can pass to a subsequence so that there exists a characteristic twist subgroup Γ_v such that $\{p_v(\phi_n)\}$ is a sequence of distinct elements of Γ_v and $\{\phi_n(R)\}$ still does not exit every compact subset of $\mathbb{X}(\Gamma, G)$. Since R is compact, $r_H^{-1}(\mathbb{X}_A(H, G))$ is open for each H , and $\mathbb{X}(\Gamma, G)$ is locally compact, we can pass to a further subsequence so that there exists a compact subset R_0 of R and a subgroup H_0 of Γ that registers Γ_v such that $R_0 \subset r_{H_0}^{-1}(\mathbb{X}_A(H_0, G))$ and $\{\phi_n(R_0)\}$ does not exit every compact subset of $\mathbb{X}(\Gamma, G)$.

Let a_0 be the generator of Γ_v that lies in the generating set $\{a_0, a_1, \dots, a_{n_v}\}$ of H_0 and let \mathcal{T}_{H_0} be the subgroup of \mathcal{T}_v generated by twists of the form $D_{z,e}$ where z is a power of a_0 and e is an edge incident to v . Since \mathcal{T}_{H_0} has finite index in \mathcal{T}_v , we can pass to a further subsequence so that there exists $\phi_0 \in \mathcal{T}_v$ with

$$\phi_0 \circ p_v(\phi_n) = p_v(\phi_0 \circ \phi_n) \in \mathcal{T}_{H_0}$$

for all n , where $p_v: \mathcal{T} \rightarrow \mathcal{T}_v$ is the projection map.

Notice that if e_i is an edge connecting v to w_i , then there is a representative of D_{z,e_i} that preserves H_0 and acts on H_0 by taking a_i to za_iz^{-1} and taking every other generator to itself. If $\{e_1, \dots, e_{n_v}\}$ are the edges adjacent to v , then \mathcal{T}_{H_0} is generated by $\{D_{a_0,e_1}, \dots, D_{a_0,e_{n_v-1}}\}$. Therefore, there is an injective homomorphism

$$s_{H_0}: \mathcal{T}_{H_0} \rightarrow \text{Out}(H_0).$$

so that

$$r_{H_0}(\rho \circ \phi) = r_{H_0}(\rho) \circ s_{H_0}(\phi)$$

for all $\rho \in \mathbb{X}(\Gamma, G)$ and $\phi \in \mathcal{T}_{H_0}$. Moreover, if \mathcal{T}_w is the characteristic twist subgroup for a different cyclic vertex group, then every element of \mathcal{T}_w acts trivially on H_0 (up to conjugacy), since no cyclic vertices are adjacent. Therefore, $\mathcal{T}_0 = p_v^{-1}(\mathcal{T}_{H_0})$ is a finite index subgroup of \mathcal{T} and s_{H_0} extends to a map

$$s_0: \mathcal{T}_0 \rightarrow \text{Out}(H_0)$$

that is trivial on \mathcal{T}_w if $w \in V_c \setminus \{v\}$ and such that

$$r_{H_0}(\rho \circ \phi) = r_{H_0}(\rho) \circ s_0(\phi)$$

for all $\rho \in \mathbb{X}(\Gamma, G)$ and $\phi \in \mathcal{T}_0$.

Since $\{s_0(\phi_0 \circ \phi_n)\}$ is a sequence of distinct elements of $\text{Out}(H_0)$, [Theorem 2.2](#) implies that $\{s_0(\phi_0 \circ \phi_n)(r_{H_0}(R_0))\}$ exits every compact subset of $\mathbb{X}(H_0, G)$. Therefore, $\{\phi_0(\phi_n(R_0))\}$ exits every compact subset of $\mathbb{X}(\Gamma, G)$. Since ϕ_0 induces a homeomorphism of $\mathbb{X}(\Gamma, G)$, it follows that $\{\phi_n(R_0)\} = \{\phi_0^{-1}(\phi_0(\phi_n(R_0)))\}$ also exits every compact subset of $\mathbb{X}(\Gamma, G)$. This contradiction completes the proof. \square

We now combine [Lemmas 5.2](#) and [5.3](#) to establish [Proposition 5.1](#).

Proof of [Proposition 5.1](#) If the proposition fails, then there exists a compact subset R of $\mathbb{X}_{A^2}(\Gamma, G)$ and a sequence $\{\phi_n\}$ of distinct elements of $\text{Out}_0(\Gamma)$ such that $\{\phi_n(R)\}$ does not exit every compact subset of $\mathbb{X}(\Gamma, G)$. After passing to a subsequence, we can assume that $\{\psi(\phi_n)\}$ is either a sequence of distinct elements in $\text{Mod}_F(\Gamma)$ or is constant. If $\{\psi(\phi_n)\}$ is a sequence of distinct elements, then [Lemma 5.2](#) immediately implies that $\{\phi_n(R)\}$ leaves every compact subset of $\mathbb{X}(\Gamma, G)$. If $\{\psi(\phi_n)\}$ is a constant sequence, then [Theorem 3.2](#) implies that there exists a sequence $\{\beta_n\}$ of distinct elements of \mathcal{T} such that $\phi_n = \phi_1 \circ \beta_n$ for all n . [Lemma 5.3](#) implies that $\{\beta_n(R)\}$ exits every compact subset of $\mathbb{X}(\Gamma, G)$. Since ϕ_1 induces a homeomorphism of $\mathbb{X}(\Gamma, G)$, it follows that $\{\phi_n(R)\} = \{\phi_1(\beta_n(R))\}$ also exits every compact subset of $\mathbb{X}(\Gamma, G)$. This contradiction completes the proof of [Proposition 5.1](#) and the proof of [Theorem 1.1](#). \square

6 Strongly amalgam Anosov representations

Strongly amalgam Anosov representations are a natural and easy to construct class of amalgam Anosov representations.

Definition 6.1 If Γ is a one-ended, torsion-free word hyperbolic group and G is a semisimple Lie group with finite center, we say that a representation $\rho: \Gamma \rightarrow G$ is *strongly amalgam Anosov* if there exists a pair P^\pm of opposite parabolic subgroups such that if Γ_v is a Fuchsian or rigid vertex group of the JSJ splitting of Γ , then $\rho|_{\Gamma_v}$ is (P^+, P^-) -Anosov.

Let $\mathbb{X}_{\text{SA}}(\Gamma, G) \subset \mathbb{X}(\Gamma, G)$ be the set of strongly amalgam Anosov representations. In the [appendix](#) we will show that strongly amalgam Anosov representations are amalgam Anosov; see [Theorem A.1](#). On the other hand, it is an immediate consequence of [Lemma 2.3](#) and the fact that vertex subgroups are quasiconvex that Anosov representations are strongly amalgam Anosov. Therefore,

$$\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{\text{SA}}(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G).$$

Moreover, the proof of [Proposition 4.2](#) may easily be adapted to show that $\mathbb{X}_{\text{SA}}(\Gamma, G)$ is an open, $\text{Out}(\Gamma)$ -invariant subset of $\mathbb{X}(\Gamma, G)$. It then follows immediately from our main result, [Theorem 1.1](#), that $\mathbb{X}_{\text{SA}}(\Gamma, G)$ is a domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$.

Corollary 6.2 *If Γ is a one-ended word hyperbolic group and G is a semisimple Lie group with finite center, then $\mathbb{X}_{\text{SA}}(\Gamma, G)$ is an open, $\text{Out}(\Gamma)$ -invariant subset of $\mathbb{X}(\Gamma, G)$ and $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}_{\text{SA}}(\Gamma, G)$.*

7 Examples

Since

$$\mathbb{X}_A(\Gamma, G) \subset \mathbb{X}_{\text{SA}}(\Gamma, G) \subset \mathbb{X}_{A^2}(\Gamma, G)$$

and each of these sets is a domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$, it is natural to ask whether these inclusions are proper and whether $\mathbb{X}_{A^2}(\Gamma, G)$ is a maximal domain of discontinuity for $\text{Out}(\Gamma)$.

In this section, we study families of examples exhibiting various phenomena. In [Section 7.1](#), we note that if Γ is rigid, then $\mathbb{X}_A(\Gamma, G) = \mathbb{X}_{\text{SA}}(\Gamma, G) \neq \mathbb{X}_{A^2}(\Gamma, G) = \mathbb{X}(\Gamma, G)$. In [Section 7.2](#), we survey previous results and conjectures in the case where Γ is a

closed surface group. In Section 7.3, we see that if Γ is the fundamental group of a compact, hyperbolizable 3-manifold with boundary, but not a surface group, then $\mathbb{X}_A(\Gamma, \text{PSL}_2(\mathbb{C})) \neq \mathbb{X}_{A^2}(\Gamma, \text{PSL}_2(\mathbb{C}))$. In Section 7.4, we exhibit examples where $\mathbb{X}_A(\Gamma, G)$ is empty, but $\mathbb{X}_{SA}(\Gamma, G)$ has positive dimension. In Section 7.5, we exhibit nonrigid groups Γ , where $\mathbb{X}_{SA}(\Gamma, G) \neq \mathbb{X}_{A^2}(\Gamma, G)$. Finally, in Section 7.6, we exhibit examples where $\mathbb{X}_{A^2}(\Gamma, G)$ is not a maximal domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$.

7.1 Rigid groups

If a one-ended hyperbolic group Γ has a trivial JSJ splitting then it is either rigid, ie admits no \mathbb{Z} -splitting, or is a surface group. If Γ is rigid and nontrivial then every representation in $\mathbb{X}(\Gamma, G)$ is amalgam Anosov, while the trivial representation fails to be either Anosov or strongly amalgam Anosov, so

$$\mathbb{X}_A(\Gamma, G) = \mathbb{X}_{SA}(\Gamma, G) \neq \mathbb{X}_{A^2}(\Gamma, G) = \mathbb{X}(\Gamma, G).$$

On the other hand, if Γ is not rigid, then the trivial representation is not amalgam Anosov, so $\mathbb{X}(\Gamma, G) \neq \mathbb{X}_{A^2}(\Gamma, G)$. Further, $\text{Out}(\Gamma)$ is infinite and does not act properly discontinuously on all of $\mathbb{X}(\Gamma, G)$, since it fixes the trivial representation.

Lemma 7.1 *If Γ is a one-ended, torsion-free hyperbolic group and G is a semisimple Lie group with finite center, then $\mathbb{X}(\Gamma, G) = \mathbb{X}_{A^2}(\Gamma, G)$ if and only if Γ is rigid. Moreover, $\text{Out}(\Gamma)$ acts properly discontinuously on $\mathbb{X}(\Gamma, G)$ if and only if Γ is rigid.*

7.2 Surface groups

If Γ is the fundamental group of a closed, oriented hyperbolic surface S , then

$$\mathbb{X}_A(\Gamma, G) = \mathbb{X}_{SA}(\Gamma, G) = \mathbb{X}_{A^2}(\Gamma, G),$$

and $\mathbb{X}_A(\pi_1(S), \text{PSL}_2(\mathbb{R}))$ is the disjoint union $\mathcal{T}(S) \cup \mathcal{T}(\bar{S})$ of the Teichmüller spaces of S and S with the opposite orientation. If $G = \text{PSL}_2(\mathbb{C})$, then $\mathbb{X}_A(\pi_1(S), \text{PSL}_2(\mathbb{C}))$ is the space of quasifuchsian representations and may be identified with $\mathcal{T}(S) \times \mathcal{T}(\bar{S})$. Goldman made the following conjecture.

Conjecture (Goldman [13]) *If S is a closed orientable hyperbolic surface and G is $\text{PSL}_2(\mathbb{R})$ or $\text{PSL}_2(\mathbb{C})$, then $\mathbb{X}_A(\pi_1(S), G)$ is a maximal domain of discontinuity for the action of $\text{Out}(\pi_1(S))$ on $\mathbb{X}(\pi_1(S), G)$. Moreover, $\text{Out}(\pi_1(S))$ acts ergodically on*

$$\mathbb{X}(\pi_1(S), \text{PSL}_2(\mathbb{C})) \setminus \mathbb{X}_A(\pi_1(S), \text{PSL}_2(\mathbb{C}))$$

and on each component of

$$\mathbb{X}(\pi_1(S), \mathrm{PSL}_2(\mathbb{R})) \setminus \mathbb{X}_A(\pi_1(S), \mathrm{PSL}_2(\mathbb{R}))$$

(unless S has genus 2 and the component consists of representations with Euler number zero).

There has been some recent progress on this conjecture when $G = \mathrm{PSL}_2(\mathbb{R})$. Marché and Wolff [26] proved that if S_2 is the closed orientable surface of genus 2, then $\mathrm{Out}(\pi_1(S_2))$ acts ergodically on the two components of $\mathbb{X}(\pi_1(S_2), \mathrm{PSL}_2(\mathbb{R}))$ consisting of representations of Euler number 1 and -1 . Souto [33] subsequently proved that if S does not have genus 2, then $\mathrm{Out}(\pi_1(S))$ acts ergodically on the component consisting of representations with Euler number zero. In genus 2, Marché and Wolff showed that the set of nonelementary representations with Euler number zero is the disjoint union of two $\mathrm{Out}(\Gamma)$ -invariant open sets on which the action is ergodic.

Lee [24] proved that if S is a closed orientable surface and $\mathrm{Out}(\pi_1(S))$ preserves and acts properly discontinuously on an open subset U inside $\mathbb{X}(\pi_1(S), \mathrm{PSL}_2(\mathbb{C}))$, then U cannot intersect $\partial\mathbb{X}_A(\pi_1(S), \mathrm{PSL}_2(\mathbb{C}))$. On the other hand, Lee [24] proved that if S is a closed, nonorientable, hyperbolic surface, then $\mathbb{X}_A(\pi_1(S), \mathrm{PSL}_2(\mathbb{C}))$ is not a maximal domain of discontinuity.

Theorem 7.2 (Lee [24]) *If S is a closed, nonorientable hyperbolic surface, then there is an open $\mathrm{Out}(\pi_1(S))$ -invariant subset $W(S)$ of $\mathbb{X}(\pi_1(S), \mathrm{PSL}_2(\mathbb{C}))$ such that:*

- (1) $\mathrm{Out}(\pi_1(S))$ acts properly discontinuously on $W(S)$.
- (2) $\mathbb{X}_A(\pi_1(S), \mathrm{PSL}_2(\mathbb{C})) = \mathbb{X}_{A^2}(\pi_1(S), \mathrm{PSL}_2(\mathbb{C}))$ is a proper subset of $W(S)$.
- (3) $W(S)$ contains representations that are neither discrete nor faithful.

7.3 3-manifold groups

Suppose that M is a compact, hyperbolizable 3-manifold whose boundary is nonempty with no toroidal components and that $\pi_1(M)$ is one-ended and not a surface group. Sullivan [34] showed that the set $\mathbb{X}_A(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$ of convex cocompact representations is the interior of the set $\mathrm{AH}(M)$ of discrete, faithful representations of $\pi_1(M)$ into $\mathrm{PSL}_2(\mathbb{C})$. Jørgensen [17] showed that $\mathrm{AH}(M)$ is a closed subset of $\mathbb{X}(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$.

Canary and Storm [9] described a domain of discontinuity for the action of $\mathrm{Out}(\Gamma)$ on $\mathbb{X}(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$ that is strictly larger than $\mathbb{X}_A(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$ and contains representations that are not discrete and faithful. It seems likely that their domain of discontinuity contains $\mathbb{X}_{A^2}(\pi_1(M), \mathrm{PSL}_2(\mathbb{C}))$. The following result is immediate from their analysis.

Theorem 7.3 *Suppose that M is a compact, hyperbolizable 3–manifold whose boundary is nonempty with no toroidal components and that $\pi_1(M)$ is one-ended and not a surface group. Then the set $\mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ is a proper subset of $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$.*

Moreover, the set

$$\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C})) \setminus \mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C}))$$

of amalgam Anosov representations that are not Anosov, contains representations that are discrete and faithful and representations that are not discrete and faithful.

Proof Proposition 4.2 implies that $\mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C})) = \text{int}(\text{AH}(M))$ is a subset of $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$.

Lemma 4.2 in Canary and Hersonsky [8] guarantees that $\partial\text{AH}(M)$ contains representations that are purely hyperbolic, ie the image of every nontrivial element of $\pi_1(M)$ is a hyperbolic element of $\text{PSL}_2(\mathbb{C})$. Let $\rho \in \partial\text{AH}(M)$ be purely hyperbolic. Lemma 8.2 in Canary and Storm [9] implies that the restriction of ρ to any Fuchsian vertex group is Anosov, while Lemma 8.3 in [9] guarantees that for every cyclic vertex group there is a registering subgroup H of $\pi_1(M)$ so that $\rho|_H$ is Anosov. It follows that ρ is amalgam Anosov. Since $\rho \in \partial\text{AH}(M)$ it is not Anosov, so

$$\rho \in \mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C})) \setminus \mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C})).$$

In particular, $\mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ is a proper subset of $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$.

Since ρ is a smooth point of $\mathbb{X}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ (see Kapovich [18, Theorem 8.44]), $\rho \in \partial\text{AH}(M) \cap \mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ and $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ is open, there exist representations in $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C})) \setminus \mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ that do not lie in $\text{AH}(M)$, and hence are not discrete and faithful. □

Remark If the JSJ splitting of $\pi_1(M)$ has no rigid vertices, eg if M is a book of I –bundles, then the above proof shows that any purely hyperbolic representation in $\partial\text{AH}(M)$ is strongly amalgam Anosov, so $\mathbb{X}_A(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ is a proper subset of $\mathbb{X}_{SA}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$.

If $\tau: \text{PSL}_2(\mathbb{C}) \rightarrow \text{SL}_{15}(\mathbb{R})$ is the Plücker representation, then Theorem 7.3 and Lemma 4.4 immediately apply to establish the following corollary. (One may easily compute, by examining the proof, that one can take $d(\text{PSL}_2(\mathbb{C})) = 15$ in Proposition 2.5.)

Corollary 7.4 *Suppose that M is a compact, hyperbolizable 3–manifold whose boundary is nonempty and has no toroidal components and that $\pi_1(M)$ is one-ended and not a surface group. Then*

$$\mathbb{X}_A(\pi_1(M), \mathrm{SL}_{15}(\mathbb{R})) \subset \mathbb{X}_{A^2}(\pi_1(M), \mathrm{SL}_{15}(\mathbb{R}))$$

is a proper subset. In particular, the set $\mathbb{X}_{A^2}(\pi_1(M), \mathrm{SL}_{15}(\mathbb{R}))$ contains representations that are not discrete and faithful, hence not Anosov.

7.4 Rank-1 Lie groups

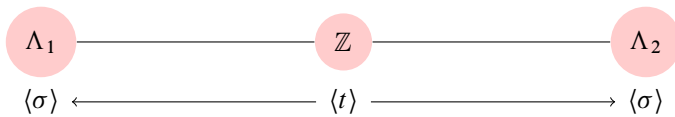
For every noncompact rank-1 Lie group G , one can construct a nonrigid hyperbolic group Γ such that $\mathbb{X}_A(\Gamma, G)$ is empty and $\mathbb{X}_{SA}(\Gamma, G)$ has positive dimension.

Proposition 7.5 *If G is a noncompact, connected, rank-1, simple Lie group with finite center, then there exists a one-ended, torsion-free hyperbolic group Γ such that*

- (1) $\mathbb{X}_A(\Gamma, G) = \emptyset$,
- (2) $\mathrm{Out}(\Gamma)$ is infinite, and
- (3) $\mathbb{X}_{SA}(\Gamma, G)$ has positive dimension.

Moreover, there is a continuous family $\{\rho_z\}$ of distinct representations in $\mathbb{X}_{SA}(\Gamma, G)$ each of which is either indiscrete or not faithful.

Proof We first suppose that G is not locally isomorphic to $\mathrm{PSL}_2(\mathbb{R})$. Let Λ be a torsion-free cocompact lattice in G . Then Λ is a rigid one-ended hyperbolic group. Our basic construction is to double Λ . Let $C = \langle \sigma \rangle$ be a maximal infinite cyclic subgroup of Λ and let Γ be the double of Λ along C . By definition, Γ is then a graph of groups with two rigid vertex groups Λ_1 and Λ_2 on either side of a single infinite cyclic vertex group. By the Bestvina–Feighn combination theorem (see the first corollary on page 100 of [3]), Γ is again a torsion-free hyperbolic group. The JSJ splitting for Γ has 3 vertices, one cyclic vertex between the two rigid vertices with groups Λ_1 and Λ_2 , respectively, both isomorphic to Λ :



We first observe that no representation in $\mathbb{X}(\Gamma, G)$ is discrete and faithful. Since Λ is a cocompact lattice, $H_n(\Lambda, \mathbb{Z}) \cong \mathbb{Z}$ where n is the dimension of the symmetric space X associated with G . If $\rho \in \mathbb{X}(\Gamma, G)$ is discrete and faithful, then, since

$$H_n(\rho(\Lambda_1), \mathbb{Z}) \cong H_n(\Lambda, \mathbb{Z}) \cong \mathbb{Z},$$

we see that $X/\rho(\Lambda_1)$ is compact. However, this is impossible since $\rho(\Gamma)$ is discrete and $\rho(\Lambda_1)$ has infinite index in $\rho(\Gamma)$. Notice that this implies, in particular, that $\mathbb{X}_A(\Gamma, G)$ is empty, since every Anosov representation of a torsion-free hyperbolic group is discrete and faithful.

We next construct a family of amalgam Anosov representations of Γ . Let Z be the centralizer of $C \subset \Lambda$ in G . Then Z contains the Zariski closure of the diagonalizable group C , and thus has positive dimension. Given $z \in Z$, we define $\rho_z \in \mathbb{X}(\Gamma, G)$ to be the identity on Λ_1 and to take every $\gamma \in \Lambda_2$ to $z\gamma z^{-1}$. The restriction of ρ_z to each Λ_i is a discrete, faithful representation with image a lattice. Thus $\rho_z|_{\Lambda_i}$ is convex cocompact and hence Anosov. (Recall that a discrete, faithful representation into a rank-1 Lie group is Anosov if and only if it is convex cocompact; see Guichard and Wienhard [16, Theorem 5.15].) Therefore, ρ_z is strongly amalgam Anosov for all $z \in Z$. Since the group Z has positive dimension, this produces a positive dimensional subset of $\mathbb{X}_{SA}(\Gamma, G)$.

If G is locally isomorphic to $\mathrm{PSL}_2(\mathbb{R})$, we must choose C carefully to carry out the above argument. Let Λ be a torsion-free, cocompact lattice in G , so $S = \mathbb{H}^2/\Lambda$ is a closed orientable surface, and let C be a maximal infinite cyclic subgroup of Λ . We again form Γ by doubling Λ along C . Then Γ has a \mathbb{Z} -splitting connecting two vertex groups, each isomorphic to Λ , and one cyclic vertex group associated with C . If a generator of C is represented by a simple closed curve α on S , then the noncyclic vertex groups of this splitting will not be rigid (as one will obtain a further \mathbb{Z} -splitting associated with a simple closed curve disjoint from α). However, if a generator of C is represented by a filling curve α on S , ie a curve that essentially intersects every homotopically nontrivial simple closed curve and we again form Γ by doubling Λ along C , then the noncyclic vertex groups will be rigid, since any \mathbb{Z} -splitting of Λ arises from a simple closed curve on S . Since this simple closed curve must intersect α , the edge group associated to C cannot lie in a vertex group of the splitting. With this choice of Λ and C , our splitting is a JSJ splitting and we can complete the proof as above. \square

If $\tau_G: G \rightarrow \mathrm{SL}_{d(G)}(\mathbb{R})$ is the Plücker representation given by Proposition 2.5, then Lemma 4.4 implies that each $\tau_G \circ \rho_z$ is amalgam Anosov but not discrete and faithful, hence not Anosov. Therefore we obtain the following immediate corollary.

Corollary 7.6 *There exist infinitely many distinct values of d such that there exists a torsion-free one-ended hyperbolic group Γ_d with infinite $\mathrm{Out}(\Gamma_d)$ so that*

$$\mathbb{X}_A(\Gamma_d, \mathrm{SL}_d(\mathbb{R})) \neq \mathbb{X}_{A^2}(\Gamma_d, \mathrm{SL}_d(\mathbb{R})).$$

7.5 Amalgam Anosov representations that are not strongly amalgam Anosov

In this section we modify the construction in [Proposition 7.5](#) to build amalgam Anosov representations of nonrigid groups that are not strongly amalgam Anosov.

Proposition 7.7 *There are infinitely many one-ended, torsion-free hyperbolic groups Γ such that $\text{Out}(\Gamma)$ is infinite and there exists an amalgam Anosov representation $\rho: \Gamma \rightarrow \text{PSL}(2, \mathbb{C})$ that is not strongly amalgam Anosov.*

Proof Let M be a compact, acylindrical and hyperbolizable 3-manifold and let $\sigma: \pi_1(M) \rightarrow \text{PSL}_2(\mathbb{C})$ be a discrete, faithful, purely hyperbolic representation that is not Anosov (see [Theorem 7.3](#)). Let C be a maximal cyclic subgroup of $\pi_1(M)$ and let Γ be the double of $\pi_1(M)$ along C . Again Γ is hyperbolic and its JSJ splitting has two rigid vertices, each isomorphic to $\pi_1(M)$, and a single cyclic vertex group associated to C . We construct a representation ρ by letting ρ agree with σ on each copy of $\pi_1(M)$ in Γ . Then, by construction, ρ is not strongly amalgam Anosov.

On the other hand, we can choose elements g_1 and g_2 of $\pi_1(M)$ so that the fixed points of $\rho(g_1)$, $\rho(g_2)$ and $\rho(c)$ in $\mathbb{CP}^1 = \partial_\infty \mathbb{H}^3$ are all disjoint, where c is a generator of C . Therefore, again by a ping-pong argument, there exists N so that the group generated by $\sigma(g_1^n)$, $\sigma(g_2^n)$ and $\sigma(c^n)$ is a Schottky group for $n \geq N$. In particular it is a convex cocompact free group of rank 3. Let $\gamma_1 \in \Gamma$ be the copy of g_1 in the first copy of $\pi_1(M)$ and let $\gamma_2 \in \Gamma$ be the copy of g_2 in the second copy of $\pi_1(M)$. Then, if $n \geq N$, the group generated by $\rho(\gamma_1^n)$, $\rho(\gamma_2^n)$ and $\rho(c^n)$ is free of rank 3 and convex cocompact, so the subgroup H of Γ generated by γ_1^n , γ_2^n and c^n registers Γ_v , where v is the cyclic vertex of the JSJ decomposition of Γ , and $\rho|_H$ is Anosov. Therefore, ρ is amalgam Anosov.

Since there are infinitely many choices for M , there are infinitely many choices for Γ . □

Remark In [Propositions 7.5](#) and [7.7](#), one can construct examples where $\text{Out}(\Gamma)$ is not virtually abelian. For example, if $G = \text{PSL}_2(\mathbb{C})$, one may choose Γ to be the amalgamation of either a lattice Λ or the fundamental group of a compact acylindrical 3-manifold M with $\pi_1(F)$, where F is a compact surface of genus at least one with connected boundary and one identifies a maximal cyclic subgroup of Λ or $\pi_1(M)$ with a maximal cyclic group in the conjugacy class of $\pi_1(\partial F)$.

7.6 $\mathbb{X}_{A^2}(\Gamma, G)$ need not be a maximal domain of discontinuity

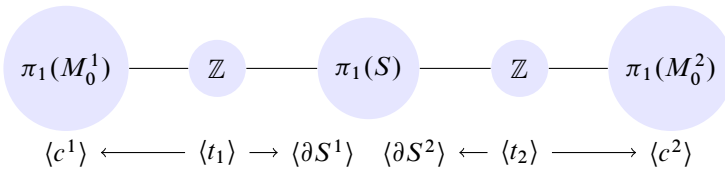
We now exhibit examples where $\mathbb{X}_{A^2}(\Gamma, G)$ is not a maximal domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$.

Proposition 7.8 *There exists a compact, hyperbolizable 3–manifold M such that:*

- (1) $\pi_1(M)$ is one-ended, torsion-free and hyperbolic.
- (2) $\text{Out}(\pi_1(M))$ is not virtually abelian.
- (3) *There exists an open, $\text{Out}(\Gamma)$ –invariant subset $Y(M)$ of $\mathbb{X}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ so that $\mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ is a proper subset of $Y(M)$ and $\text{Out}(\pi_1(M))$ acts properly discontinuously on $Y(M)$.*

Proof Let M_0 be a compact, acylindrical, hyperbolizable 3–manifold without toroidal boundary components such that there exists an epimorphism $\alpha: \pi_1(M_0) \rightarrow F_2$, where F_2 is the free group on 2 elements. Furthermore, suppose that there exists a simple closed curve c on ∂M_0 such that $\alpha(c)$ is a generator of F_2 . Let S be a compact, orientable 2–holed surface of genus 3 with boundary components ∂S^1 and ∂S^2 .

Let M_0^1 and M_0^2 be two copies of M_0 containing copies c^1 and c^2 of c . We form M from $S \times [0, 1]$, M_0^1 and M_0^2 by identifying $\partial S^i \times [0, 1]$ with a collar neighborhood C^i of c^i in ∂M_0^i for $i = 1, 2$. Results of Bestvina and Feighn [3] again imply that $\pi_1(M)$ is hyperbolic. Since $S \times [0, 1]$, M_0^1 and M_0^2 are irreducible, and they are attached to one another along incompressible annuli to form M , the manifold M is also irreducible. Thurston’s geometrization theorem (see Morgan [29]) then implies that M is hyperbolizable. Moreover, there is a graph of groups decomposition of $\pi_1(M)$ which has 5 vertices, two rigid vertices identified with $\pi_1(M_0^1)$ and $\pi_1(M_0^2)$, two cyclic vertices, identified with $\pi_1(C^1)$ and $\pi_1(C^2)$, and one Fuchsian vertex, identified with $\pi_1(S)$. Therefore, $\pi_1(M)$ is torsion-free, freely indecomposable, and not cyclic, hence $\pi_1(M)$ is one-ended and the given graph of groups decomposition is the JSJ splitting:



Let $W(M)$ be the domain of discontinuity constructed by Canary and Storm [9] for the action of $\text{Out}(\pi_1(M))$ on $\mathbb{X}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$. Recall that $\rho \in W(M)$ if and only if

- (1) the restriction of ρ to the free group $\pi_1(S)$ is primitive-stable, and
- (2) for $i = 1, 2$, there exists a subgroup H^i of $\pi_1(M)$ freely generated by $c^i = \partial S^i$, an element of $\pi_1(M_0^i)$, and an element of $\pi_1(S)$ such that the restriction of ρ to H^i is primitive-stable.

We refer the reader to Minsky [28] for the definition of a primitive-stable representation of a free group F_n , but we recall that the set of primitive-stable representations is a domain of discontinuity for the action of $\text{Out}(F_n)$ on $\mathbb{X}(F_n, \text{PSL}_2(\mathbb{C}))$ that contains $\mathbb{X}_A(F_n, \text{PSL}_2(\mathbb{C}))$ as a proper subset.

Let

$$Y(M) = W(M) \cup \mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C})).$$

Then $Y(M)$ is an $\text{Out}(\pi_1(M))$ -invariant open subset of $\mathbb{X}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$ on which $\text{Out}(\pi_1(M))$ acts properly discontinuously. It only remains to prove that

$$W(M) \setminus \mathbb{X}_{A^2}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$$

is nonempty.

Let $\rho_S: \pi_1(S) \rightarrow \text{PSL}_2(\mathbb{C})$ be a primitive-stable representation that is not convex cocompact, hence not Anosov. For $i = 1, 2$, let J^i be a proper free factor of rank 3 of $\pi_1(S)$ so that ∂S^i is an element of a minimal generating set $\{\partial S^i, a_2^i, a_3^i\}$ for J^i . (For example, one may choose J^i to be the fundamental group of an essential twice-punctured torus subsurface of S with ∂S^i as one boundary component.) Lemma 3.2 in Minsky [28] then implies that the restriction of ρ_S to J^i is convex cocompact. Let g be an element of $\pi_1(M_0)$ such that $\alpha(g)$ and $\alpha(c)$ generate F_2 and let g^i be the copy of g in M_0^i . Let $\alpha^i: \pi_1(M_0^i) \rightarrow F_2$ be the result of precomposing α with the identification of $\pi_1(M_0^i)$ with $\pi_1(M_0)$; define $v^i: F_2 \rightarrow \text{PSL}_2(\mathbb{C})$ by $v^i(\alpha^i(c^i)) = \rho_S(\partial S^i)$ and $v^i(\alpha^i(g^i)) = \rho_S(a_3^i)$.

We define $\rho: \pi_1(M) \rightarrow \text{PSL}_2(\mathbb{C})$ to agree with ρ_S on $\pi_1(S)$ and agree with $v^i \circ \alpha^i$ on $\pi_1(M_0^i)$ for each i . For each i , let H^i be the subgroup of $\pi_1(M)$ generated by c^i, a_2^i and g^i . Then $\rho(H^i) = \rho_S(J^i)$ is a convex cocompact free group on 3 generators, which implies that H^i is a free group on 3 generators and the restriction of ρ to H^i is convex cocompact. It follows that $\rho \in W(M)$. However, since ρ_S is not Anosov, ρ is not amalgam Anosov. This completes the proof. \square

Remarks (1) If $P(F_n, G)$ is a domain of discontinuity for the action of $\text{Out}(F_n)$ on $\mathbb{X}(\Gamma, G)$ that is strictly larger than $\mathbb{X}_A(F_n, G)$ for all $n \geq 2$, and the JSJ splitting of Γ is nontrivial and contains a Fuchsian vertex group, then one may generalize the construction of Canary and Storm [9] by considering the set $Q(\Gamma, G) \subset \mathbb{X}(\Gamma, G)$

of representations so that (i) if Γ_v is a Fuchsian vertex group, then $\rho|_{\Gamma_v} \in P(\Gamma_v, G)$, and (ii) if Γ_v is a cyclic vertex group, then there exists a group H registering Γ_v so that $\rho|_H \in P(\Gamma_v, G)$. The set $Q(\Gamma, G)$ will be a domain of discontinuity for the action of $\text{Out}(\Gamma)$ on $\mathbb{X}(\Gamma, G)$ that contains $\mathbb{X}_{A^2}(\Gamma, G)$. It seems likely that it would often be the case that $Q(\Gamma, G)$ strictly contains $\mathbb{X}_{A^2}(\Gamma, G)$.

(2) It is an open question whether or not $W(M)$ is a maximal domain of discontinuity for the action of $\text{Out}(\pi_1(M))$ on $\mathbb{X}(\pi_1(M), \text{PSL}_2(\mathbb{C}))$. This is related to the question of whether or not the set of primitive-stable representations is a maximal domain of discontinuity for the action of $\text{Out}(F_n)$ on $\mathbb{X}(F_n, \text{PSL}_2(\mathbb{C}))$.

Appendix: Projective Anosov Schottky groups and strongly amalgam Anosov representations

by Richard D Canary, Michelle Lee, Andrés Sambarino and Matthew Stover

The purpose of this appendix is to prove that strongly amalgam Anosov representations are amalgam Anosov. We recall that if Γ is a one-ended, torsion-free hyperbolic group and G is a semisimple Lie group with finite center, then $\rho \in \mathbb{X}(\Gamma, G)$ is *strongly amalgam Anosov* if there exists a pair P^\pm of proper opposite parabolic subgroups so that $\rho|_{\Gamma_v}$ is (P^+, P^-) -Anosov for every Fuchsian or rigid vertex group Γ_v in the JSJ decomposition of Γ .

Theorem A.1 *Suppose that Γ is a one-ended, torsion-free word hyperbolic group and G is a semisimple Lie group with finite center. If $\rho \in \mathbb{X}(\Gamma, G)$ is strongly amalgam Anosov, then ρ is amalgam Anosov.*

The proof is based on the fact (see [Theorem A.2](#)) that if one is given a well-positioned collection of biproximal elements of $\text{SL}_d(\mathbb{R})$, then one may pass to large enough powers that the group they generate is a free, projective Anosov group, ie a projective Anosov Schottky group. The existence of a result of this form has been well known among experts. For example, in the typical situation where the Schottky group produced by Benoist [[1](#), Section 6] is irreducible, it follows immediately that it is projective Anosov from results of Quint [[30](#), Proposition 3.3] and Guichard and Wienhard [[16](#), Proposition 4.10]. Kapovich, Leeb and Porti [[19](#), Theorem 7.40] previously established a generalization of [Theorem A.2](#) to the setting of general semisimple Lie groups. Our proof of [Theorem A.2](#) relies heavily on results and techniques of Benoist [[1](#); [2](#)] and Quint [[30](#)] as well as a criterion for a representation to be projective Anosov due to Guéritaud, Guichard, Kassel and Wienhard [[15](#)].

Recall that a matrix $\gamma \in \mathrm{SL}_d(\mathbb{R})$ is *proximal* if its eigenvalue of maximal modulus is real and of multiplicity one. It is *biproximal* if both γ and γ^{-1} are proximal. If γ is proximal, then it has a unique attracting fixed point $\gamma^+ \in \mathbb{P}(\mathbb{R}^d)$, which is the eigenline associated to the eigenvalue of maximal modulus. Let $\gamma^- \in \mathbb{P}(\mathbb{R}^d)^*$ denote the repelling hyperplane of γ . (We regularly use the identification of $\mathbb{P}(\mathbb{R}^d)^*$ with the Grassmannian of hyperplanes in \mathbb{R}^d .) If $\rho: \Gamma \rightarrow \mathrm{SL}_d(\mathbb{R})$ is projective Anosov with associated limit maps $\xi: \partial\Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)$ and $\theta: \partial\Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*$ and $c \in \partial_\infty\Gamma$ is an attracting fixed point of an element $\gamma \in \Gamma$, then $\rho(\gamma)$ is biproximal and

$$\xi(c) = \rho(\gamma)^+ \quad \text{and} \quad \theta(c) = (\rho(\gamma)^-)^-$$

(see Lemma 3.1 and Corollary 3.2 in Guichard and Wienhard [16]).

A set S of matrices is *symmetric* when $\gamma \in S$ if and only if $\gamma^{-1} \in S$. A symmetric set $S = \{\gamma_1, \dots, \gamma_{2r}\}$ of biproximal matrices in $\mathrm{SL}_d(\mathbb{R})$ is *well-positioned* if

- (1) $\gamma_i^+ \neq \gamma_j^+$ if $i \neq j$, and
- (2) γ_i^+ is not contained in the hyperplane γ_j^- whenever $\gamma_j \neq \gamma_i^{-1}$.

Notice that conditions (1) and (2) immediately imply that $\gamma_i^- \neq \gamma_j^-$ if $i \neq j$.

The key technical result needed for the proof of [Theorem A.1](#) is the following.

Theorem A.2 (Tits [35]; Benoist [1]; Quint [30]; Kapovich, Leeb and Porti [19]) *If $S = \{\gamma_1, \dots, \gamma_{2r}\}$ is a well-positioned symmetric set of biproximal matrices in $\mathrm{SL}_d(\mathbb{R})$, then there exists $N > 0$ such that if $n \geq N$, then the subgroup of $\mathrm{SL}_d(\mathbb{R})$ generated by*

$$S^n = \{\gamma_1^n, \dots, \gamma_{2r}^n\}$$

is a free group of rank r and the induced representation $\rho: F_r \rightarrow \mathrm{SL}_d(\mathbb{R})$ is projective Anosov.

We now prove [Theorem A.1](#) assuming [Theorem A.2](#), and return to the proof of [Theorem A.2](#) afterwards.

Proof of [Theorem A.1](#) We first suppose that $\rho: \Gamma \rightarrow \mathrm{SL}_d(\mathbb{R})$ is a representation such that the restriction of ρ to any Fuchsian or rigid vertex group of the JSJ decomposition of Γ is projective Anosov. If w is a Fuchsian or rigid vertex of the JSJ decomposition of Γ , let

$$\xi_w: \partial_\infty\Gamma_w \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta_w: \partial_\infty\Gamma_w \rightarrow \mathbb{P}(\mathbb{R}^d)^*$$

be the limit maps for $\rho|_{\Gamma_w}$.

Let v be a cyclic vertex and let $\{w_1, \dots, w_r\}$ be the vertices adjacent to v and a be the generator for Γ_v . Since Γ_{w_1} is nonelementary, pairs of fixed points of elements of Γ_{w_1} are dense in $\partial\Gamma_{w_1} \times \partial\Gamma_{w_1}$. Thus, since ξ_{w_1} is injective and θ_{w_1} is transverse to ξ_{w_1} , we can find $g_1 \in \Gamma_{w_1}$ so that $\rho(g_1)^+$ is distinct from $\rho(a)^+$ and not contained in $\rho(a)^-$, and $\rho(g_1)^-$ is distinct from $\rho(a)^-$ and does not contain $\rho(a)^+$. Therefore, $\{\rho(a)^{\pm 1}, \rho(g_1)^{\pm 1}\}$ is a well-positioned symmetric set of biproximal matrices.

Similarly, we iteratively choose $g_i \in \Gamma_{w_i}$ so that

$$\{\rho(a)^{\pm 1}, \rho(g_1)^{\pm 1}, \dots, \rho(g_i)^{\pm 1}\}$$

is a well-positioned symmetric set of biproximal matrices. Let

$$S = \{\rho(a)^{\pm 1}, \rho(g_1)^{\pm 1}, \dots, \rho(g_r)^{\pm 1}\}$$

be the final result of this process. [Theorem A.2](#) implies that there is a positive integer N such that if $n \geq N$, then

$$\Lambda_n = \langle S^n \rangle$$

is a free group of rank $r + 1$ and the restriction of ρ to Λ_n is projective Anosov. Therefore, for $n \geq N$, the subgroup $H_n = \langle a^n, g_1^n, \dots, g_r^n \rangle$ registers Γ_v and the restriction of ρ to H_n is projective Anosov. Therefore, for every cyclic vertex group there exists a registering subgroup H such that the restriction of ρ to H is projective Anosov. Since the restriction of ρ to every Fuchsian vertex group is projective Anosov by assumption, it follows that ρ is amalgam Anosov.

Now suppose that $\rho: \Gamma \rightarrow G$ is strongly amalgam Anosov and P^\pm is a pair of proper opposite parabolic subgroups so that the restriction of ρ to each Fuchsian or rigid vertex group is (P^+, P^-) -Anosov. Let $\tau: G \rightarrow \mathrm{SL}_d(\mathbb{R})$ be the irreducible representation provided by [Proposition 2.5](#). Then the restriction of $\tau \circ \rho$ to every rigid and Fuchsian vertex group is projective Anosov. It follows from the above analysis that for every cyclic vertex group there exists a registering subgroup H such that the restriction of $\tau \circ \rho$ to H is projective Anosov, which implies that the restriction of ρ to H is (P^+, P^-) -Anosov. Therefore, ρ is amalgam Anosov. \square

We now turn to the proof of [Theorem A.2](#). We first recall the criterion of Guéritaud, Guichard, Kassel and Wienhard [\[15\]](#) for a representation to be projective Anosov. (We have been informed that one can derive an analogue of this criterion, see [Theorem A.3](#) below, from the work in [\[19\]](#).)

Choose the maximal torus \mathfrak{a} for the Lie algebra $\mathfrak{sl}_d(\mathbb{R})$ of $\mathrm{SL}_d(\mathbb{R})$ for which $\exp(\mathfrak{a})$ is the group of diagonal matrices in $\mathrm{SL}_d(\mathbb{R})$. We can then choose a positive Weyl chamber \mathfrak{a}^+ to be the interior of $\bar{\mathfrak{a}}^+$, where $\exp(\bar{\mathfrak{a}}^+)$ is the set of positive diagonal

matrices with entries in descending order (from left to right). If α_1 is the root of highest weight for \mathfrak{a}^+ , then

$$\alpha_1(a_1, a_2, \dots, a_d) = a_1 - a_2.$$

Let $K \exp(\bar{\mathfrak{a}}^+)K$ be the Cartan decomposition of $SL_d(\mathbb{R})$ with respect to \mathfrak{a}^+ and a maximal compact subgroup $K = SO(d)$,

$$\mu: G \rightarrow \bar{\mathfrak{a}}^+$$

be the associated Cartan projection (see [1; 30; 16]), and $\mu_i(g)$ denote the i^{th} entry of $\mu(g)$. Fix a norm $\| \cdot \|$ on \mathbb{R}^d arising from a K -invariant inner product and let $\| \gamma \|$ be the operator norm of a linear transformation γ with respect to $\| \cdot \|$. Notice that

$$\mu_1(g) = \log \| g \|.$$

Similarly, let

$$\lambda: G \rightarrow \bar{\mathfrak{a}}^+$$

be the Jordan projection (see [2; 30; 16]), and let $\lambda_i(g)$ denote the i^{th} entry of $\lambda(g)$. If g is proximal, then $\Lambda_1(g) = e^{\lambda_1(g)}$ is the modulus of the eigenvalue of maximal modulus.

If Γ is a hyperbolic group, we recall that maps

$$\xi: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*$$

are *transverse* if $\xi(x)$ and $\theta(y)$ span \mathbb{R}^d for all distinct elements $x \neq y$ in $\partial_\infty \Gamma$. Moreover, ξ and θ are said to be *dynamics-preserving* if, whenever $c \in \partial_\infty \Gamma$ is an attracting fixed point of $\gamma \in \Gamma$, its image $\xi(c)$ is an attracting eigenline of γ and its image $\theta(c)$ is an attracting hyperplane of γ .

Theorem A.3 (Guéritaud, Guichard, Kassel and Wienhard [15, Theorem 1.3]) *Suppose that $r \geq 2$ and $\rho: F_r \rightarrow SL_d(\mathbb{R})$ is a representation so that there exist transverse, dynamics-preserving, ρ -equivariant, injective, continuous maps*

$$\xi: \partial_\infty F_r \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta: \partial_\infty F_r \rightarrow \mathbb{P}(\mathbb{R}^d)^*.$$

If

$$\lim_{n \rightarrow \infty} \alpha_1(\mu(x_0 \cdots x_n)) = +\infty$$

for every infinite reduced word (x_n) in the generators of F_r , then ρ is projective Anosov.

We will show that Benoist’s construction of Schottky groups in [1] can be slightly modified so that the Schottky groups produced satisfy the assumptions of **Theorem A.3**.

Benoist [1] defines the distance between two lines $X, Y \in \mathbb{P}(\mathbb{R}^d)$ to be

$$d(X, Y) = \min\{\|x - y\| : x \in X, y \in Y, \|x\| = 1, \|y\| = 1\}.$$

Given a subset Z of $\mathbb{P}(\mathbb{R}^d)$ and $\epsilon > 0$, define $b(Z, \epsilon)$ and $B(Z, \epsilon)$ by

$$b(Z, \epsilon) = \{X \in \mathbb{P}(\mathbb{R}^d) : d(X, Z) \leq \epsilon\},$$

$$B(Z, \epsilon) = \{X \in \mathbb{P}(\mathbb{R}^d) : d(X, Z) \geq \epsilon\}.$$

Following Benoist [1], we say that a proximal matrix γ is ϵ -proximal if

- (1) $d(\gamma^+, \gamma^-) \geq 2\epsilon$,
- (2) γ is ϵ -Lipschitz on $B(\gamma^-, \epsilon)$, and
- (3) $\gamma(B(\gamma^-, \epsilon)) \subset b(\gamma^+, \epsilon)$.

Benoist [1] further says that a symmetric set $S = \{\gamma_1, \dots, \gamma_{2r}\}$ of ϵ -proximal matrices is ϵ -Schottky if $d(\gamma_i^+, (\gamma_j^{-1})^-) \geq 6\epsilon$ for all $i \neq j$. Notice that this implies that $b(\gamma_i^+, \epsilon) \subset B(\gamma_j^-, \epsilon)$ whenever $\gamma_j \neq \gamma_i^{-1}$.

For an element $\gamma \in \text{SL}_d(\mathbb{R})$, let γ^* be the element of $\text{SL}((\mathbb{R}^d)^*)$ defined by

$$\gamma^*(\theta) = \theta \circ \gamma^{-1}$$

for all $\theta \in (\mathbb{R}^d)^*$. Recall that if γ is a biproximal element of $\text{SL}_d(\mathbb{R})$, then

$$(\gamma^*)^+ = ((\gamma^{-1})^-)^* \quad \text{and} \quad (\gamma^*)^- = ((\gamma^{-1})^+)^*.$$

We will use the following additional properties of ϵ -Schottky sets.

Lemma A.4 *If $\epsilon > 0$ and $S = \{\gamma_1, \dots, \gamma_{2r}\}$ and $S^* = \{\gamma_1^*, \dots, \gamma_{2r}^*\}$ are ϵ -Schottky sets of proximal matrices in $\text{SL}_d(\mathbb{R})$ and $\text{SL}((\mathbb{R}^d)^*)$, then*

- (1) $V = \bigcap_{1 \leq i \leq 2r} B(\gamma_i^-, \epsilon)$ is nonempty,
- (2) $W = \bigcap_{1 \leq i \leq 2r} B((\gamma_i^*)^-, \epsilon) \subset \mathbb{P}(\mathbb{R}^d)^*$ is nonempty, and
- (3) if $i \neq j$, $X \in b(\gamma_i^+, \epsilon)$ and $Y \in b((\gamma_j^*)^+, \epsilon)$, then X and Y span \mathbb{R}^d .

Proof Since S is symmetric and ϵ -Schottky, if $v \in \mathbb{P}(\mathbb{R}^d)$ and $d(v, \gamma_i^+) < 5\epsilon$, then $d(v, \gamma_j^-) > \epsilon$ if $\gamma_j \neq \gamma_i^{-1}$. Therefore, V contains any point such that $d(v, \gamma_1^+) < 5\epsilon$ and $d(v, (\gamma_1^{-1})^-) > \epsilon$, so (1) holds. One can apply the same argument to S^* to verify (2).

Finally, to prove (3) we must show that if X is a line in $b(\gamma_i^+, \epsilon)$ and Y is a hyperplane in $b((\gamma_j^*)^+, \epsilon)$, then X is not contained in Y . However, any line contained in Y lies within ϵ of a line in $(\gamma_j^{-1})^-$, which would imply that $d(\gamma_j^+, \gamma_j^-) < 2\epsilon$, which contradicts the fact that S is ϵ -Schottky. □

We now apply techniques of Benoist [1] and Quint [30] to produce limit maps for the Schottky groups generated by ϵ -Schottky groups of matrices in $SL_d(\mathbb{R})$. These techniques are another instance of the ping-pong construction which goes back to Klein [20] in the Kleinian setting and Tits [35] in the general linear setting. The following proposition is our version of Proposition 3.3 in Quint [30], which in turn sharpens the discussion in Section 6.5 of Benoist [1].

Proposition A.5 (Quint [30]) *If $\epsilon > 0$ and S and S^* are ϵ -Schottky symmetric sets of proximal matrices in $SL_d(\mathbb{R})$ and $SL((\mathbb{R}^d)^*)$, then the subgroup Γ of $SL_d(\mathbb{R})$ generated by S is free of rank r . Furthermore, there exist transverse, dynamics-preserving, Γ -equivariant, injective, continuous maps*

$$\xi: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*$$

such that if $c \in \partial_\infty \Gamma$ is the attracting fixed point of an element $\gamma \in \Gamma$, then $\xi(c)$ is an attracting eigenline of γ and $\theta(c)$ is an attracting hyperplane for γ .

Proof By Lemma A.4,

$$V = \bigcap_{1 \leq i \leq 2r} B(\gamma_j^-, \epsilon)$$

is nonempty. Choose $v \in V$, and let $x = x_0 x_1 \cdots x_n$ be any reduced word in the elements of S . Then, one may iteratively check that

$$x(v) \in x_0 x_1 \cdots x_{i-1}(b(x_i^+, \epsilon)) \subset b(x_0, \epsilon).$$

In particular, $x(v)$ does not lie in V , since it does not lie in $B((x_0^{-1})^-, \epsilon)$, so $x \neq 1$. Therefore, Γ is free on r generators. Each element $x_j \in S$ is ϵ -Lipschitz on $b(x_j^+, \epsilon)$, so $x_0 \cdots x_{i-1}(b(x_i^+, \epsilon))$ has diameter at most $\epsilon^i D$, where D is the diameter of $\mathbb{P}(\mathbb{R}^d)$.

Recall that the boundary of a free group can be identified with the set of infinite reduced words in its generators. If $x = (x_i)$ is an infinite reduced word in the elements of S , then it follows that $\{x_0 x_1 \cdots x_n(v)\}$ is a Cauchy sequence and we can define

$$\xi(x) = \lim_{n \rightarrow \infty} x_0 \cdots x_n(v).$$

If w is any point in V , then $x_0 \cdots x_n(w)$ also lies in $x_0 x_1 \cdots x_{i-1}(b(x_i^+, \epsilon))$, which has diameter at most $\epsilon^n D$. It follows that $\xi(x) = \lim_{n \rightarrow \infty} x_0 \cdots x_n(w)$. In particular, if $c \in \partial_\infty \Gamma$ is the attracting fixed point of $\gamma \in \Gamma$, then $\gamma^n(V)$ converges to $\xi(c)$ which implies that $\xi(c)$ is an attracting eigenline of γ .

Given two infinite reduced words $x = (x_i)$ and $y = (y_i)$, let $r = r(x, y)$ be the first index at which they differ. Then

$$\xi(x), \xi(y) \in x_0 \cdots x_{r-2}(b(x_{r-1}^+, \epsilon)),$$

so $d(\xi(x), \xi(y)) \leq \epsilon^{r-1} D$, which implies that ξ is continuous. Furthermore,

$$\xi(x) \in x_0 \cdots x_{r-1}(b(x_r^+, \epsilon)) \quad \text{and} \quad \xi(y) \in x_0 \cdots x_{r-1}(b(y_r^+, \epsilon)),$$

which are disjoint sets since $b(x_r^+, \epsilon)$ and $b(y_r^+, \epsilon)$ are disjoint. Therefore, ξ is injective.

Lemma A.4 also gives us that

$$W = \bigcap_{1 \leq i \leq 2r} B((\gamma_i^*)^-, \epsilon) \subset \mathbb{P}(\mathbb{R}^d)^*$$

is nonempty. The same argument as above applied to the dual representation gives θ .

Given two infinite reduced words $x = (x_i)$ and $y = (y_i)$, let $r = r(x, y)$ be the first index at which they differ. Then

$$\xi(x) \in x_0 \cdots x_{r-1}(b(x_r^+, \epsilon)) \quad \text{and} \quad \theta(y) \in x_0 \cdots x_{r-1}(b((y_r^*)^+, \epsilon)).$$

If $X = (x_0 x_1 \dots x_r)^{-1}(\xi(x))$ and $Y = ((x_0 x_1 \dots x_r)^{-1})^*(\theta(y))$, then Lemma A.4 implies that X and Y span \mathbb{R}^d . Therefore, since $x_0 \cdots x_{r-1}$ is a linear transformation, $\xi(x)$ and $\theta(y)$ span \mathbb{R}^d . This implies that ξ and θ are transverse. \square

If Γ is irreducible, it follows immediately from Proposition 2.4 that the injection of Γ into $SL_d(\mathbb{R})$ guaranteed by Proposition A.5 is projective Anosov. However, this is not necessarily the case. We also need the following estimate of Benoist. We note that in Benoist [1] the Cartan and Jordan projections map into $\exp(\bar{a}^+)$.

Proposition A.6 (Benoist [1]) *If $\epsilon > 0$ and S is ϵ -Schottky, then there exists a constant $C_\epsilon \in (0, 1)$ such that if $x_0 \cdots x_n$ is a reduced word in S , then $x_0 \cdots x_n$ is proximal and*

$$\frac{\|x_0 \cdots x_n\|}{\|x_0\| \cdots \|x_n\|} \geq C_\epsilon^{n+2}.$$

Proof Proposition 6.4 in Benoist [1] asserts that $x_0 \cdots x_n$ is proximal and there exists $C_\epsilon > 0$ so that

$$\frac{\|x_0 \cdots x_n\|}{\Lambda_1(x_0) \cdots \Lambda_1(x_n)} \geq C_\epsilon^{n+2}.$$

Since $1 < \Lambda_1(x_i) \leq \|x_i\|$ for all i (see, for example, [1, Corollary 6.3]), the estimate follows. \square

We now establish our criterion for a collection of elements to generate a projective Anosov Schottky group.

Proposition A.7 *If $\epsilon > 0$ and $S = \{\gamma_1, \dots, \gamma_{2r}\}$ and $S^* = \{\gamma_1^*, \dots, \gamma_{2r}^*\}$ are ϵ -Schottky symmetric sets of proximal matrices in $SL_d(\mathbb{R})$ and $SL((\mathbb{R}^d)^*)$ such that*

$$\alpha_1(\mu(\gamma_i)) \geq -3 \log(C_\epsilon)$$

for all i , where C_ϵ is the constant in Proposition A.6, then the group Γ generated by S is free of rank r and the injection of Γ into $SL_d(\mathbb{R})$ is projective Anosov.

Proof Proposition A.5 guarantees that Γ is a free group of rank r and that there exist transverse, dynamics-preserving, Γ -equivariant, injective continuous maps

$$\xi: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d) \quad \text{and} \quad \theta: \partial_\infty \Gamma \rightarrow \mathbb{P}(\mathbb{R}^d)^*.$$

Theorem A.3 then implies that if

$$\lim \alpha_1(\mu(x_0 \cdots x_n)) = +\infty$$

for every infinite reduced word (x_n) in S , then the injection of Γ into $SL_d(\mathbb{R})$ is projective Anosov.

Let $\wedge^2 g$ be the second exterior product of $g \in SL_d(\mathbb{R})$. Then

$$\alpha_1(\mu(g)) = \log \frac{\|g\|^2}{\|\wedge^2 g\|}$$

since $\log \|g\| = \mu_1(g)$ and $\log \|\wedge^2 g\| = \log \|\wedge^2(\exp(\mu(g)))\| = \mu_1(g) + \mu_2(g)$. Therefore,

$$\begin{aligned} \alpha_1(\mu(x_0 \cdots x_n)) &= \log \frac{\|x_0 \cdots x_n\|^2}{\|\wedge^2(x_0 \cdots x_n)\|} \\ &= \log \frac{\|x_0 \cdots x_n\|^2}{\|x_0\|^2 \cdots \|x_n\|^2} + \log \frac{\|x_0\|^2 \cdots \|x_n\|^2}{\|\wedge^2(x_0 \cdots x_n)\|} \\ &\geq 2(n+2) \log C_\epsilon + \log \frac{\|x_0\|^2 \cdots \|x_n\|^2}{\|\wedge^2 x_0\| \cdots \|\wedge^2 x_n\|} \\ &= 2(n+2) \log C_\epsilon + \sum_{i=0}^n \alpha_1(\mu(x_i)) \\ &\geq (2n+4-3(n+1)) \log C_\epsilon = -(n-1) \log C_\epsilon. \end{aligned}$$

Since $C_\epsilon \in (0, 1)$, we have that $-(n-1) \log C_\epsilon \rightarrow \infty$ as $n \rightarrow \infty$, so

$$\lim_{n \rightarrow \infty} \alpha_1(\mu(x_0 \cdots x_n)) = +\infty.$$

This completes the proof. □

Remark Our original proof of [Proposition A.7](#) showed that, in our setting, one could use the fact $\lim \alpha_1(\mu(x_0 \cdots x_n)) = +\infty$ for every infinite reduced word (x_n) in S to verify condition (iv) of [Proposition 3.16](#) in [Guichard and Wienhard \[16\]](#). As the results of [Guéritaud, Guichard, Kassel and Wienhard \[15\]](#) are much more general, we make use of their work instead.

[Theorem A.2](#) then follows immediately from [Proposition A.7](#) and the following lemma.

Lemma A.8 *Let $S = \{\gamma_1, \dots, \gamma_{2r}\}$ be a well-positioned symmetric set of biproximal matrices in $SL_d(\mathbb{R})$. Then there exists $\epsilon \in (0, 1)$ and $N > 0$ such that if $n \geq N$, then*

- (1) S^n and $(S^n)^*$ are ϵ -Schottky, and
- (2) $\alpha_1(\mu(\gamma_i^n)) \geq -3 \log(C_\epsilon)$ for all i , where C_ϵ is the constant in [Proposition A.6](#).

Proof Choose ϵ_1 to satisfy

$$\epsilon_1 = \min_{\gamma_j \neq \gamma_i^{-1}} d(\gamma_i^+, \gamma_j^-) > 0,$$

and set $\epsilon = \frac{1}{6}\epsilon_1$. Notice that if $\gamma_j \neq \gamma_i^{-1}$, then

$$d((\gamma_i^*)^+, (\gamma_j^*)^-) = d((\gamma_i^{-1})^-, (\gamma_j^{-1})^+) \geq \epsilon.$$

As in the remark in [Section 6.2](#) of [\[1\]](#), there exists N so that if $n > N$, then γ_i^n and $(\gamma_i^n)^*$ are ϵ -proximal for all i , so S and S^* are ϵ -Schottky symmetric sets of proximal matrices in $SL_d(\mathbb{R})$ and $SL((\mathbb{R}^d)^*)$.

[Benoist \[2, Corollary 2.5.2\]](#) showed that

$$\lambda(\gamma_i) = \lim_{n \rightarrow \infty} \frac{1}{n} \mu(\gamma_i^n).$$

Since each γ_i is proximal, $\exp(\lambda(\gamma_i))$ is proximal, so $\alpha_1(\lambda(\gamma_i)) > 0$ for all i . In particular, $\lim_{n \rightarrow \infty} \alpha_1(\mu(\gamma_i^n)) = +\infty$, and hence we can also choose N large enough that

$$\alpha_1(\mu(\gamma_i^n)) \geq -3 \log(C_\epsilon),$$

for all i and $n \geq N$. This completes the proof of the lemma. □

Remark One may use the Plücker embedding (see [Proposition 2.5](#)) to produce analogues of [Theorem A.2](#) for any semisimple Lie group with finite center and any pair P^\pm of proper opposite parabolic subgroups.

References

- [1] **Y Benoist**, *Actions propres sur les espaces homogènes réductifs*, Ann. of Math. 144 (1996) 315–347 [MR](#)
- [2] **Y Benoist**, *Propriétés asymptotiques des groupes linéaires*, Geom. Funct. Anal. 7 (1997) 1–47 [MR](#)
- [3] **M Bestvina, M Feighn**, *A combination theorem for negatively curved groups*, J. Differential Geom. 35 (1992) 85–101 [MR](#)
- [4] **B H Bowditch**, *Cut points and canonical splittings of hyperbolic groups*, Acta Math. 180 (1998) 145–186 [MR](#)
- [5] **M Bridgeman, R Canary, F Labourie, A Sambarino**, *The pressure metric for Anosov representations*, Geom. Funct. Anal. 25 (2015) 1089–1179 [MR](#)
- [6] **M R Bridson, A Haefliger**, *Metric spaces of non-positive curvature*, Grundle. Math. Wissen. 319, Springer (1999) [MR](#)
- [7] **RD Canary**, *Dynamics on character varieties: a survey*, from “Handbook of group actions, II” (L Ji, A Papadopoulos, S-T Yau, editors), Adv. Lect. Math. 32, International Press, Somerville, MA (2015) 175–200 [MR](#)
- [8] **RD Canary, S Hersonsky**, *Ubiquity of geometric finiteness in boundaries of deformation spaces of hyperbolic 3-manifolds*, Amer. J. Math. 126 (2004) 1193–1220 [MR](#)
- [9] **RD Canary, P A Storm**, *Moduli spaces of hyperbolic 3-manifolds and dynamics on character varieties*, Comment. Math. Helv. 88 (2013) 221–251 [MR](#)
- [10] **M Carette**, *The automorphism group of accessible groups*, J. Lond. Math. Soc. 84 (2011) 731–748 [MR](#)
- [11] **C Champetier**, *Petite simplification dans les groupes hyperboliques*, Ann. Fac. Sci. Toulouse Math. 3 (1994) 161–221 [MR](#)
- [12] **R Gitik**, *Ping-pong on negatively curved groups*, J. Algebra 217 (1999) 65–72 [MR](#)
- [13] **WM Goldman**, *Mapping class group dynamics on surface group representations*, from “Problems on mapping class groups and related topics” (B Farb, editor), Proc. Sympos. Pure Math. 74, Amer. Math. Soc. (2006) 189–214 [MR](#)
- [14] **M Gromov**, *Hyperbolic groups*, from “Essays in group theory” (S M Gersten, editor), Math. Sci. Res. Inst. Publ. 8, Springer (1987) 75–263 [MR](#)
- [15] **F Guéritaud, O Guichard, F Kassel, A Wienhard**, *Anosov representations and proper actions*, Geom. Topol. 21 (2017) 485–584
- [16] **O Guichard, A Wienhard**, *Anosov representations: domains of discontinuity and applications*, Invent. Math. 190 (2012) 357–438 [MR](#)
- [17] **T Jørgensen**, *On discrete groups of Möbius transformations*, Amer. J. Math. 98 (1976) 739–749 [MR](#)

- [18] **M Kapovich**, *Hyperbolic manifolds and discrete groups*, Progress in Mathematics 183, Birkhäuser, Boston (2001) [MR](#)
- [19] **M Kapovich**, **B Leeb**, **J Porti**, *Morse actions of discrete groups on symmetric space*, preprint (2014) [arXiv](#)
- [20] **F Klein**, *Neue Beiträge zur Riemann'schen Functionentheorie*, Math. Ann. 21 (1883) 141–218 [MR](#)
- [21] **F Labourie**, *Anosov flows, surface groups and curves in projective space*, Invent. Math. 165 (2006) 51–114 [MR](#)
- [22] **F Labourie**, *Cross ratios, Anosov representations and the energy functional on Teichmüller space*, Ann. Sci. Éc. Norm. Supér. 41 (2008) 439–471 [MR](#)
- [23] **M Lee**, *Dynamics on the $\mathrm{PSL}(2, \mathbb{C})$ -character variety of a compression body*, Algebr. Geom. Topol. 14 (2014) 2149–2179 [MR](#)
- [24] **M Lee**, *Dynamics on the $\mathrm{PSL}(2, \mathbb{C})$ -character variety of a twisted I -bundle*, Groups Geom. Dyn. 9 (2015) 187–201 [MR](#)
- [25] **G Levitt**, *Automorphisms of hyperbolic groups and graphs of groups*, Geom. Dedicata 114 (2005) 49–70 [MR](#)
- [26] **J Marché**, **M Wolff**, *The modular action on $\mathrm{PSL}_2(\mathbb{R})$ -characters in genus 2*, Duke Math. J. 165 (2016) 371–412 [MR](#)
- [27] **I Mineyev**, *Flows and joins of metric spaces*, Geom. Topol. 9 (2005) 403–482 [MR](#)
- [28] **Y N Minsky**, *On dynamics of $\mathrm{Out}(F_n)$ on $\mathrm{PSL}_2(\mathbb{C})$ characters*, Israel J. Math. 193 (2013) 47–70 [MR](#)
- [29] **J W Morgan**, *On Thurston's uniformization theorem for three-dimensional manifolds*, from “The Smith conjecture” (J W Morgan, H Bass, editors), Pure Appl. Math. 112, Academic Press, Orlando, FL (1984) 37–125 [MR](#)
- [30] **J-F Quint**, *L'indicateur de croissance des groupes de Schottky*, Ergodic Theory Dynam. Systems 23 (2003) 249–272 [MR](#)
- [31] **Z Sela**, *Structure and rigidity in (Gromov) hyperbolic groups and discrete groups in rank 1 Lie groups, II*, Geom. Funct. Anal. 7 (1997) 561–593 [MR](#)
- [32] **J-P Serre**, *Trees*, Springer (1980) [MR](#)
- [33] **J Souto**, *Ergodicity of the action of the mapping class group on a component of the character variety*, in preparation
- [34] **D Sullivan**, *Quasiconformal homeomorphisms and dynamics, II: Structural stability implies hyperbolicity for Kleinian groups*, Acta Math. 155 (1985) 243–260 [MR](#)
- [35] **J Tits**, *Free subgroups in linear groups*, J. Algebra 20 (1972) 250–270 [MR](#)

*Department of Mathematics, University of Michigan
2074 East Hall, 530 Church St, Ann Arbor, MI 48109-1043, United States*

*Department of Mathematics, University of Maryland
William E Kirwan Hall, 4176 Campus Dr, College Park, MD 20742-4015, United States*

*Department of Mathematics, Temple University
Wachman Hall, 1805 N Broad St, Philadelphia, PA 19122, United States*

*Faculté de Mathématiques, Université Paris VI Pierre et Marie Curie
4 Place Jussieu, 75005 Paris, France*

canary@umich.edu, michelle.dongeun.lee@gmail.com, mstover@temple.edu,
andres.sambarino@gmail.com

Proposed: David Gabai

Received: 9 November 2014

Seconded: Jean-Pierre Otal, Martin Bridson

Revised: 17 December 2015

