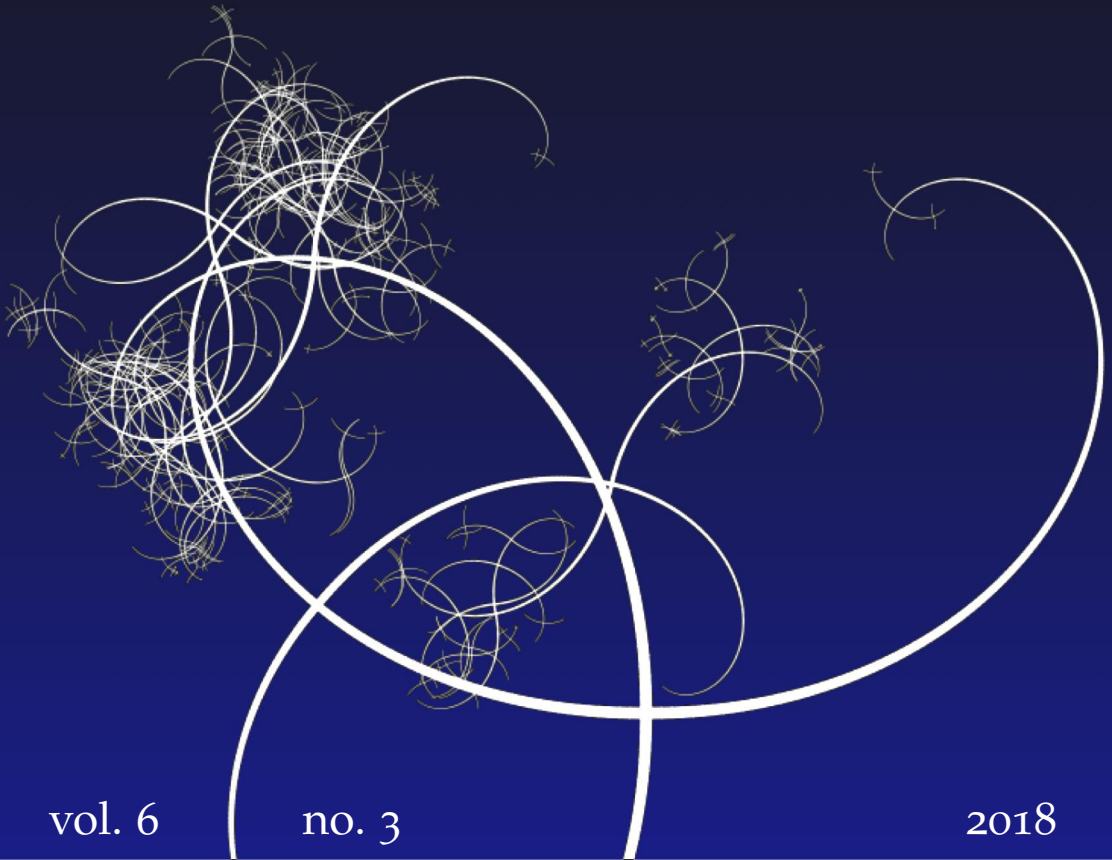


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DISCONTINUITY IN AN ANISOTROPIC LAYER OVERLYING AN
INITIALLY STRESSED
ELASTIC HALF-SPACE**





GENERATION OF SH-TYPE WAVES DUE TO SHEARING STRESS DISCONTINUITY IN AN ANISOTROPIC LAYER OVERLYING AN INITIALLY STRESSED ELASTIC HALF-SPACE

SANTOSH KUMAR AND DINBANDHU MANDAL

The paper investigates the generation of SH-type waves due to a sudden application of a stress discontinuity which moves after creation at the anisotropic layer of finite thickness overlying an initially stressed isotropic half-space. The displacements are obtained in exact form by the method due to Cagniard modified by de Hoop. Two cases of shearing stress discontinuities are considered. The numerical results are obtained for a particular model and discussed by plotting graphs for displacement component with the elapsed time of the disturbance for different values of initial stress and also for different values of initial time at which pulses arrive.

1. Introduction

The notion of initial stress is essential to the study of seismic wave propagation. Biot [1940] is largely responsible for the notion's introduction and initial applications to elastic wave propagation; in [Biot 1965] he further developed the notion of initial stress. Many authors have used that book as fundamental to the study of wave propagation in an initially stressed medium. Abd-Alla and Ahmed [1999] analyzed Love waves propagation in a non-homogeneous orthotropic elastic layer under initial stress overlying semi-infinite medium. Khurana [2001] considered the effect of initial stress on the propagation of Love wave. Further significant steps were taken in [Das and Dey 1968; 1970, Dey 1971; Dey and Addy 1978; Chattopadhyay and De 1981; Chattopadhyay and Kar 1978; Majhi et al. 2016; 2017] to cite but a few works.

In addition to initial stress, shearing stress discontinuity also plays a vital role in the study of seismic wave propagation. Pal [1983] considered the problem of generation and propagation of SH-type waves due to non-uniformly moving stress

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discontinuity in layered anisotropic elastic half-space using Garvin's [1956] techniques, which are a modification of Cagniard's [1939] technique. Pal and Kumar [2000] considered the generation of SH waves by a moving stress discontinuity in an anisotropic soil layer over an elastic half-space using the Cagniard–de Hoop special reduction technique [de Hoop 1960]. Next de Hoop [2002] considered the reflection and transmission properties of an elastic interfacial bonding of two semi-infinite solids, investigated for the simplest possible case of a line-source excited two-dimensional SH-wave. Pal and Mandal [2014] studied the generation of SH-type waves due to sudden application of a stress discontinuity which moves after creation at the sandy layer of finite thickness overlying an isotropic and inhomogeneous elastic half-space. Mandal et al. [2014] considered the disturbance and propagation of SH-type waves in an anisotropic soil layer overlying an inhomogeneous elastic half-space by a moving stress discontinuity. All authors have considered the effect of initial stress and shearing stress discontinuity separately but haven't considered the initial stress and shearing stress discontinuity together.

In the present problem our intention is to investigate the two dimensional problem of generation of SH-type waves at the free surface of an anisotropic layer due to an impulsive stress discontinuity moving with uniform velocity along the interface of initially stressed isotropic medium. The displacement is calculated numerically for two particular distances on the surface for two different types of the discontinuity in the shearing stress for different value of initial stress. It involves Laplace and Fourier transform and the inversion is based on Garvin's [1956] method. The problem discussed may be of importance in connection with the propagation of cracks in the layer. Two cases of stress discontinuity are considered and the numerical results are shown graphically.

2. Formulation of problem

We consider an anisotropic elastic layer of thickness h with elastic constants L_1, N_1 and density ρ_1 over an initially stressed isotropic half-space with elastic constant μ_2 and density ρ_2 . The interface of these two media is considered at $z = 0$ whereas free surface is at $z = -h$. Here, z axis is directed vertically downward and x axis is assumed in the direction of the propagation of wave with velocity c . For SH-type of waves the displacement does not depend on y and if (u, v, w) be the displacement at any point $P(x, y, z)$ into the medium then $u = w = 0$ and v are function of x, z and t . The two equations of motion are identically satisfied. The geometrical configuration is depicted in Figure 1.

The equation of motion for the anisotropic layer (Medium I) without body forces is given by

$$N_1 \frac{\partial^2 v_1}{\partial x^2} + L_1 \frac{\partial^2 v_1}{\partial z^2} = \rho_1 \frac{\partial^2 v_1}{\partial t^2}. \quad (1)$$

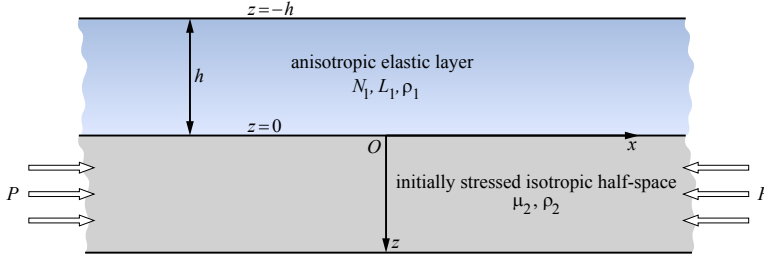


Figure 1. Geometry of problem.

The stress strain relation is given by $(\tau_{xy})_I = N_1 \frac{\partial v_1}{\partial x}$ and $(\tau_{yz})_I = L_1 \frac{\partial v_1}{\partial z}$.

The equation of motion for initially stressed isotropic half-space (Medium II) without body forces is given by

$$\frac{\partial(\tau_{xy})_{II}}{\partial x} + \frac{\partial(\tau_{yz})_{II}}{\partial z} - \frac{P}{2} \frac{\partial v_2}{\partial x^2} = \frac{\partial^2}{\partial t^2}(\rho_2 v_2). \tag{2}$$

The stress strain relation is given by $(\tau_{xy})_{II} = \mu_2 \frac{\partial v_2}{\partial x}$ and $(\tau_{yz})_{II} = \mu_2 \frac{\partial v_2}{\partial z}$.

The boundary conditions are

$$(\tau_{yz})_I = 0 \quad \text{at } z = -h, \tag{3}$$

$$v_1 = v_2 \quad \text{at } z = 0, \tag{4}$$

$$(\tau_{yz})_I - (\tau_{yz})_{II} = S(x, t)H(t) \quad \text{at } z = 0, \tag{5}$$

where $S(x, t)$ is a function of x and t ; $H(t)$ is the Heaviside unit function of time t .

3. Method of solution

The above problem can readily be solved by using the Laplace and Fourier transforms combined with the modified Cagniard–de Hoop [1960] method. The Laplace transform with respect to t and the Fourier transform with respect to x are defined by

$$\bar{v} \cong \int_{-\infty}^{\infty} e^{-i\xi x} dx \int_0^{\infty} e^{-pt} v(x, z; t) dt. \tag{6}$$

We can easily get the upper and lower layer with $v_2 \rightarrow 0$ as $z \rightarrow \infty$ in the form

$$\bar{v}_1(x, z; p) = \int_{-\infty}^{\infty} (A \cosh s_1 z + B \sinh s_1 z) e^{i\xi x} d\xi, \tag{7}$$

$$\bar{v}_2 = \int_{-\infty}^{\infty} C e^{(i\xi x - s_2 z)} d\xi, \tag{8}$$

where the constants A , B and C are to be determined from the boundary conditions

(3)–(5):

$$s_1 = \left(\phi_1^2 \xi^2 + \frac{p^2}{\beta_1^2} \right)^{\frac{1}{2}}, \quad s_2 = \left(\phi_2^2 \xi^2 + \frac{p^2}{\beta_2^2} \right)^{\frac{1}{2}}, \tag{9}$$

where $\beta_1^2 = \frac{L_1}{\rho_1}$, $\beta_2^2 = \frac{\mu_2}{\rho_2}$, $\phi_1^2 = \frac{N_1}{L_1}$ and $\phi_2^2 = 1 - \frac{P}{2\mu_2}$.

It follows from the boundary conditions (3) and (4) that

$$A = C, \quad A \cosh s_1 h = B \sinh s_1 h. \tag{10}$$

Case I. Let

$$S(x, t) = \begin{cases} Q, & a \leq x \leq b + Vt, \\ 0, & \text{elsewhere,} \end{cases} \tag{11}$$

where Q is constant.

This definition of stress discontinuity shows that it is created in the region $x = a$ to $x = b$ and then expands with the uniform velocity V in the x direction. In particular, when $a = b = 0$, the discontinuity is created at the origin and expands with uniform velocity V in the x direction.

From the boundary condition (5) one gets, with the help of (11),

$$BL_1s_1 + C\mu_2s_2 = \frac{Q}{2\pi p} \left[\frac{e^{-i\xi a} - e^{-i\xi b}}{i\xi} + \frac{e^{-i\xi b}}{i\xi + \frac{p}{V}} \right]. \tag{12}$$

Solving for A , B and C from (10) and (12), we get the displacement function at the free surface at $z = -h$ in the form

$$\begin{aligned} \bar{v}_1(x, -h; p) &= \frac{Q}{2\pi p} \int_{-\infty}^{\infty} \frac{e^{i\xi x}}{(L_1s_1 \sinh s_1 h + \mu_2s_2 \cosh s_1 h)} \left[\frac{e^{-i\xi a} - e^{-i\xi b}}{i\xi} + \frac{e^{-i\xi b}}{i\xi + \frac{p}{V}} \right] d\xi \\ &= \frac{Q}{\pi p} \int_{-\infty}^{\infty} \frac{e^{(i\xi x - hs_1)}}{(L_1s_1 + \mu_2s_2)} \left[\frac{e^{-i\xi a} - e^{-i\xi b}}{i\xi} + \frac{e^{-i\xi b}}{i\xi + \frac{p}{V}} \right] (1 - Ke^{-2hs_1})^{-1} d\xi, \end{aligned} \tag{13}$$

where

$$K = \frac{L_1s_1 - \mu_2s_2}{L_1s_1 + \mu_2s_2} < 1, \tag{14}$$

represents the reflection coefficient of SH-waves incident from the sandy medium at the interface between two half-spaces. The coefficients of different power of K in series of (13) are associated with the pulses undergoing repeated reflection in the upper layer. Using the inverse Laplace transform, we can rewrite (13) in a convenient form:

$$v_1(x, -h; p) = L^{-1}(I_1 + I_2 + I_3) = L^{-1}(I_1) + L^{-1}(I_2) + L^{-1}(I_3), \tag{15}$$

where I_1, I_2 and I_3 are defined in the Appendix. The inverse Laplace transforms of I_1, I_2 and I_3 are obtained by following [Garvin 1956]; details are in the Appendix.

Equation (15) gives the exact value of the surface displacement field $v_1(x, -h, t)$ surface.

Case II. Let

$$S(x, t) = Qh\delta(x - Vt), \tag{16}$$

where Q is a constant and $\delta(x - Vt)$ is Dirac's delta function of argument $(x - Vt)$. A term h is included on the right-hand side of (16) so as to give S as the dimension of a stress.

The boundary condition (5) gives

$$BL_1s_1 + C\mu_2s_2 = \frac{Qh}{2\pi V(i\xi + \frac{p}{V})}. \tag{17}$$

Solving for A, B and C from (10) and (17) one gets

$$\bar{v}_1(x, -h; p) = \frac{Qh}{\pi V} \int_{-\infty}^{\infty} \frac{e^{(i\xi x - hs_1)}(1 + Ke^{-2hs_1} + K^2e^{-4hs_1} + \dots)}{(i\xi + \frac{p}{V})(L_1s_1 + \mu_2s_2)} d\xi \tag{18}$$

Proceeding similarly as in Case I we obtain

$$v_1(x, -h, t) = \frac{2Q\beta_1h}{\pi L_1} \sum_{n=1,3,5,\dots} \int_0^t G_n[\zeta_n(\lambda)] d\lambda, \tag{19}$$

where

$$G_n[\zeta_n(t)] = \text{Re} \left[\left\{ 1 + \phi_1^2 \zeta_n^2(t) \right\}^{\frac{1}{2}} + \mu \left(\varepsilon^2 + \phi_2^2 \zeta_n^2(t) \right)^{\frac{1}{2}} \right]^{-1} \times \left[\frac{\beta_1}{V} + i\zeta_n(t) \right]^{-1} \\ \times K^{\frac{n-1}{2}} [\zeta_n(t)] \frac{d\zeta_n(t)}{dt} H \left[t - (x^2 + n^2h^2)^{\frac{1}{2}} \beta_1^{-1} \right] \tag{20}$$

and

$$\zeta_n(t) = \frac{\beta_1}{x^2 + n^2h^2\phi_1^2} \left[itx + nh \left\{ t^2 - (x^2 + n^2h^2\phi_1^2)\beta_1^{-2} \right\}^{\frac{1}{2}} \right], \quad n = 1, 3, 5, \dots \tag{21}$$

If the stress discontinuity is taken as $H(x) - H(x - Vt)$ in place of $\delta(x - Vt)$ the corresponding expression on the right-hand side of (18) will differ only by a constant factor from I_3 (with $a = b = 0$).

4. Numerical results and discussion

For numerical results, we have taken data for anisotropic layer and initially stressed half-space from [Babuska and Cara 1991]:

$$\begin{aligned} N_1 &= 175 \text{ GPa}, & L_1 &= 202 \text{ GPa}, & \rho_1 &= 4408 \text{ kg/m}^3 \\ \mu_2 &= 91.6 \text{ GPa}, & \rho_2 &= 3582 \text{ kg/m}^3. \end{aligned}$$

The values of $K_1 v_1(x, -h, t)$ for $x = 7h$ and $x = 14h$ have been plotted against $\tau_1 = \tau - \tau_0$, where τ_0 denotes the time at which the disturbance arrives at the point of observation with $K_1 = \frac{\pi L_1}{2Q\beta_1 h}$, $\tau = \frac{t\beta_1}{h}$ is the time of the disturbance to arrive from source to initial point. The value of τ at $x = 7h$ is $(7^2 + n^2\phi_1^2)^{1/2}$, $n = 1, 3, 5, \dots$ and $\tau_0 = 7.06$ at $n = 1$ and the value of τ at $x = 14h$ is $(14^2 + n^2\phi_1^2)^{1/2}$, $n = 1, 3, 5, \dots$ and $\tau_0 = 14.03$ at $n = 1$.

When $x = 7h$, for six initial values, we have

$$K_1 v_1(x, -h, t) = \sum_{n=1,3,5,7,9,11} A^0(\theta_n) \cosh^{-1}\left(\tau / \sqrt{7^2 + n^2\phi_1^2}\right) H\left(\tau - \sqrt{7^2 + n^2\phi_1^2}\right),$$

where

$$A^0(\theta_n) = \text{Re} \frac{\left[(1 - \phi_1^2 \cos^2 \theta_n)^{\frac{1}{2}} - \mu(\varepsilon^2 - \phi_2^2 \cos^2 \theta_n)^{\frac{1}{2}} \right]^{\frac{n-1}{2}} \sin \theta_n}{\left[(1 - \phi_1^2 \cos^2 \theta_n)^{\frac{1}{2}} + \mu(\varepsilon^2 - \phi_2^2 \cos^2 \theta_n)^{\frac{1}{2}} \right]^{\frac{n-3}{2}} \left(\frac{\beta_1}{V} - \cos \theta_n \right)}$$

represents the reflection coefficient of SH-type waves incident from the anisotropic medium to initially stressed isotropic half-space. When $x = 14h$, for six initial values, we have the same expression for $K_1 v_1(x, -h, t)$, with 7^2 replaced by 14^2 .

Figures 2 and 3 show graphs of the variation of displacement with elapsed time τ_1 for different values of initial stress and for different values of initial time at which pulses arrive.

In Figure 2, top, the graph is plotted for the disturbance effect for $x = 7h$ and $x = 14h$ and fixed value of $P = 1$ GPa. From the figure it can be observed that all the curves start from the origin with sharp changes in their slope and after sometime the curves get smooth. Also, it reflects that the disturbance is more prominent for early arrival of pulses i.e. for $x = 7h$ has more jumping effect than for $x = 14h$. If the place of observation has more distance from the source the impact of pluses is less. In Figure 2, bottom, the graph is plotted for the disturbance effect for $x = 7h$ and $x = 14h$ and fixed value of $P = 10$ GPa. The nature of the curves remains the same, but the magnitude of disturbance increases to a large extent as initial stress increases.

In Figure 3, top, the graph is plotted for the disturbance for $x = 7h$ and different values of P (1 GPa, 10 GPa and 100 GPa). The nature of the curves is oscillating

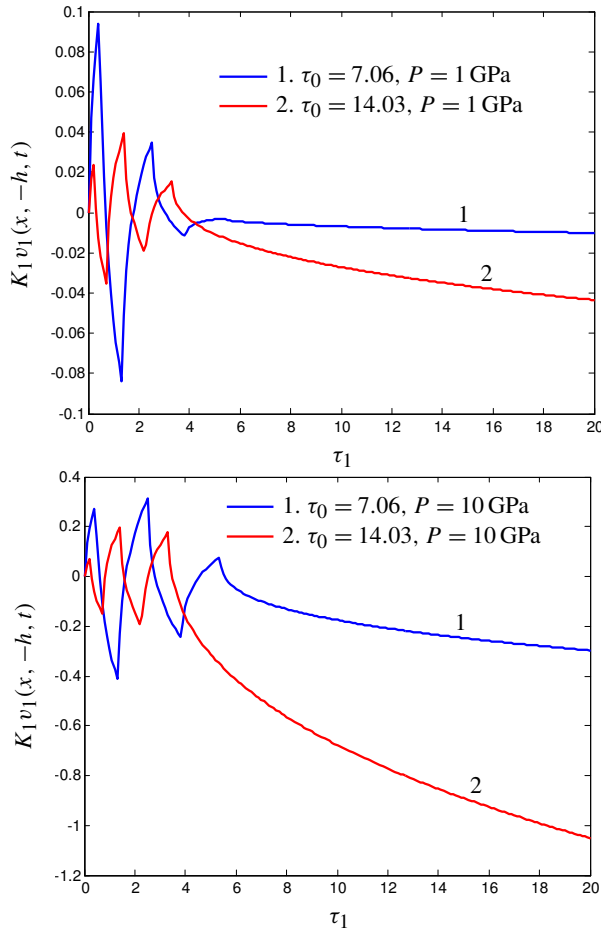


Figure 2. Variation of $K_1 v_1(x, -h, t)$ with τ_1 for $x = 7h$ and $x = 14h$, for $P = 1$ GPa (top) and $P = 10$ GPa.

and after some time the curves become smooth and steady. As we increase the values of initial stress, the jumping effect increases. In Figure 3, bottom, the graph is plotted for the disturbance for $x = 14h$ and the same values of P . The nature of the curves remains the same, but the effect of disturbance is reduced to a large extent due to the late arrival of the pulses.

5. Conclusions

The generation of SH-type waves at the free surface of an anisotropic layer due to an impulsive stress discontinuity moving with uniform velocity along the interface of initially stressed isotropic medium has been considered. The displacement is calculated numerically for two particular distances on the surface for two different

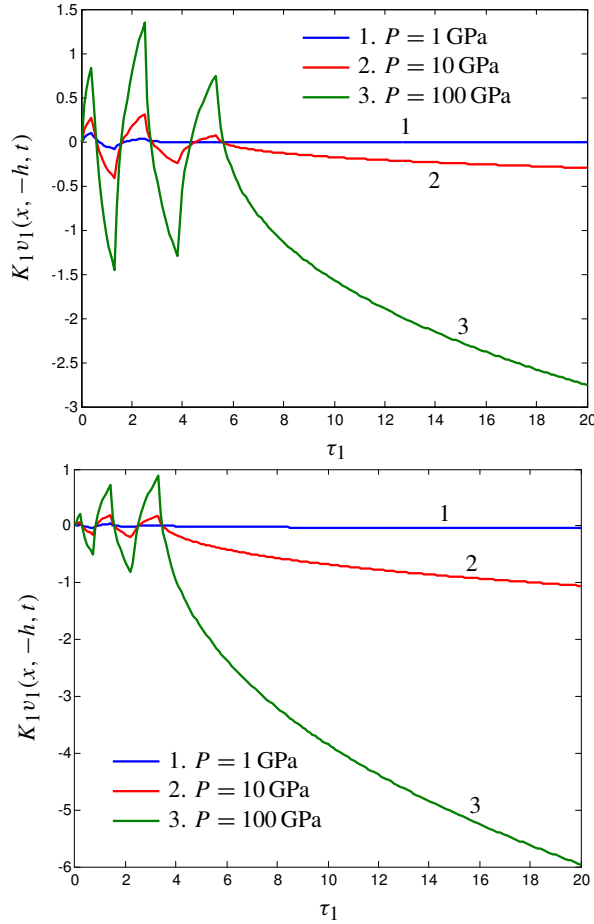


Figure 3. Variation of $K_1 v_1(x, -h, t)$ with τ_1 for $x = 7h$ (top) and $x = 14h$ (bottom) for different values of P .

types of the discontinuity in the shearing stress for different value of initial stress. It involves Laplace and Fourier transform and the inversion is based on Garvin's [1956] method. The numerical results are obtained for a particular model. From the figures it can be observed that initial stress and initial time at which pulses arrive has a significant effect. From the graph it is visible that that the displacement factor starts oscillating and after sometime it gets stable. The results are more comprising with the real scenario as we see that the disturbance arrives at the surface, it shakes the surface for a while and slowly gets stable. Also, from the figures it is visible that if the observer is nearer to the source then pulses arrive early and produce more disturbance and if the medium is highly pre-stressed then it produces more disturbance.

Appendix

We have

$$\begin{aligned}
 I_1 &= \frac{Q}{\pi p} \int_{-\infty}^{\infty} \frac{(1 - Ke^{-2hs_1})^{-1}}{i\xi(L_1s_1 + \mu_2s_2)} e^{(i\xi x_1 - hs_1)} d\xi, \\
 I_2 &= \frac{Q}{\pi p} \int_{-\infty}^{\infty} \frac{(1 - Ke^{-2hs_1})^{-1}}{i\xi(L_1s_1 + \mu_2s_2)} e^{(i\xi x_2 - hs_1)} d\xi, \\
 I_3 &= \frac{Q}{\pi p} \int_{-\infty}^{\infty} \frac{(1 - Ke^{-2hs_1})^{-1}}{(i\xi + \frac{p}{V})(L_1s_1 + \mu_2s_2)} e^{(i\xi x_2 - hs_1)} d\xi,
 \end{aligned}$$

with $x_1 = x - a$ and $x_2 = x - b$. In order to evaluate the Laplace inversion integral, we have used Garvin’s method; see [Garvin 1956] for discussion of the contour integration and mapping.

Next for non-dimensionalisation, we substitute $\xi = \frac{\zeta p}{\beta_1}$, $\mu = \frac{\mu_2}{L_1}$, $\frac{\beta_1}{\beta_2} = \varepsilon$ in the integral above so that $s_1 = \frac{p}{\beta_1}(1 + \phi_1^2\zeta^2)^{\frac{1}{2}}$, $s_2 = \frac{p}{\beta_2}(\varepsilon^2 + \phi_2^2\zeta^2)^{\frac{1}{2}}$ and

$$K = \frac{(1 + \phi_1^2\zeta^2)^{\frac{1}{2}} - \mu(\varepsilon^2 + \phi_2^2\zeta^2)^{\frac{1}{2}}}{(1 + \phi_1^2\zeta^2)^{\frac{1}{2}} + \mu(\varepsilon^2 + \phi_2^2\zeta^2)^{\frac{1}{2}}}.$$

Thus we obtain

$$I_1 = \frac{2Q}{\pi p} \text{Im} \int_0^{\infty} \frac{e^{(i\xi x_1 - hs_1)}(1 + Ke^{-2hs_1} + K^2e^{-4hs_1} + \dots)}{\xi(L_1s_1 + \mu_2s_2)} d\xi. \tag{A.1}$$

The first term in I_1 is

$$I_{1,1} = \frac{2Q\beta_1}{\pi p L_1} \text{Im} \int_0^{\infty} \frac{\exp\left[-p\left\{-i\zeta x_1 + h(1 + \phi_1^2\zeta^2)^{\frac{1}{2}}\right\}/\beta_1\right]}{p\zeta\left[(1 + \phi_1^2\zeta^2)^{\frac{1}{2}} + \mu(\varepsilon^2 + \phi_2^2\zeta^2)^{\frac{1}{2}}\right]} d\zeta. \tag{A.2}$$

The integrand (A.2) has singularities at $\zeta = 0, \pm \frac{i}{\phi_1}, \pm \frac{i\varepsilon}{\phi_2}$. Let $t = \left\{-i\zeta x_1 + h(1 + \phi_1^2\zeta^2)^{\frac{1}{2}}\right\}/\beta_1$. Then by inversion $\zeta(t) = \frac{\beta_1}{x_1^2 + \phi_1^2 h^2} \left[itx_1 + h\left\{t^2 - (x_1^2 + \phi_1^2 h^2)\beta_1^{-2}\right\}^{\frac{1}{2}} \right]$. The mapping of the ζ -plane into the t -plane is shown in Figure 4.

Making the reference to the Figure 4 and the paper of [Pal 1983], we find

$$L^{-1}I_{1,1} = \frac{2Q\beta_1}{\pi L_1} \int_0^t (t - \lambda_1)G_{1,1}[\zeta_{1,1}(\lambda_1)] d\lambda_1, \tag{A.3}$$

where $L[tH(t)] = \frac{1}{p^2}$ and

$$\begin{aligned}
 G_{1,1}[\zeta_{1,1}(t)] &= \text{Im} \left[(1 + \phi_1^2\zeta_{1,1}^2)^{\frac{1}{2}} + \mu(\varepsilon^2 + \phi_2^2\zeta_{1,1}^2)^{\frac{1}{2}} \right]^{-1} \zeta_{1,1}^{-1}(t) \\
 &\times \frac{d\zeta_{1,1}(t)}{dt} H \left[t - \left\{ \eta(x_1^2 + h^2\phi_1^2) \right\}^{\frac{1}{2}} \beta_1^{-1} \right].
 \end{aligned}$$

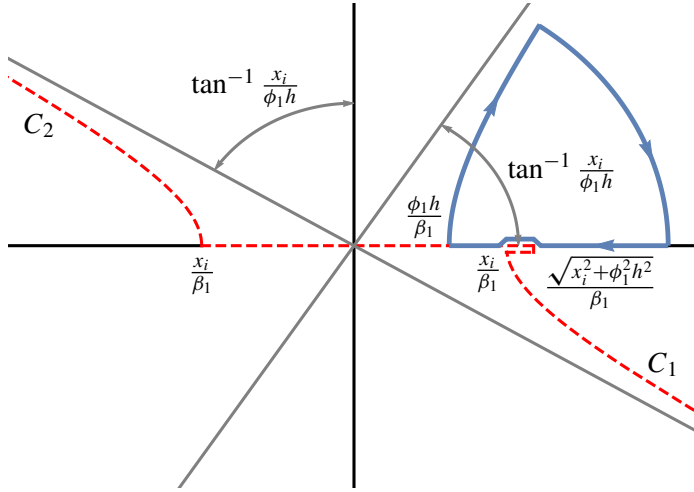


Figure 4. The t -plane showing the mapping and the contour of integration.

Since for $\frac{\phi_1 h}{\beta_1} < t < \frac{(x_1^2 + h^2 \phi_1^2)^{\frac{1}{2}}}{\beta_1}$, $\left[(1 + \phi_1^2 \zeta_{1,1}^2)^{\frac{1}{2}} + \mu (\varepsilon^2 + \phi_2^2 \zeta_{1,1}^2)^{\frac{1}{2}} \right] \zeta_{1,1}^{-1}(t) \times \frac{d\zeta_{1,1}(t)}{dt}$ is real. In general,

$$L^{-1} I_{1,n} = \frac{2Q\beta_1}{\pi L_1} \int_0^t (t - \lambda_1) G_{1,n}[\zeta_{1,n}(\lambda_1)] d\lambda_1, \tag{A.4}$$

where

$$G_{1,n}[\zeta_{1,n}(t)] = \text{Im} \left[\left\{ 1 + \phi_1^2 \zeta_{1,n}^2(t) \right\}^{\frac{1}{2}} + \mu (\varepsilon^2 + \phi_2^2 \zeta_{1,n}^2(t))^{\frac{1}{2}} \right]^{-1} \zeta_{1,n}^{-1}(t) \\ \times K^{\frac{n-1}{2}}[\zeta_{1,n}(t)] \frac{d\zeta_{1,n}(t)}{dt} H \left[t - \left\{ (x_1^2 + h^2 \phi_1^2) \right\}^{\frac{1}{2}} \beta_1^{-1} \right],$$

and

$$\zeta_{1,n}(t) = \frac{\beta_1}{x_1^2 + n^2 h^2 \phi_1^2} \left[itx_1 + nh \left\{ t^2 - (x_1^2 + n^2 h^2 \phi_1^2) \beta_1^{-2} \right\}^{\frac{1}{2}} \right], \quad n = 1, 3, 5, \dots$$

So that

$$L^{-1} I_1 = \sum_{n=1,3,5,\dots} L^{-1} I_{1,n}. \tag{A.5}$$

Similarly

$$L^{-1} I_2 = \sum_{n=1,3,5,\dots} L^{-1} I_{2,n}, \tag{A.6}$$

where x_1 is replaced by x_2 .

Proceeding in the same way, we get

$$L^{-1}I_3 = \sum_{n=1,3,5,\dots} L^{-1}I_{3,n}, \tag{A.7}$$

where

$$L^{-1}I_{3,n} = \frac{2Q\beta_1}{\pi L_1} \int_0^t (t - \lambda_1) G_{3,n}[\zeta_{2,n}(\lambda_1)] d\lambda_1 \tag{A.8}$$

$$G_{3,n}[\zeta_{2,n}(t)] = \text{Re} \left[\left\{ 1 + \phi_1^2 \zeta_{2,n}^2(t) \right\}^{\frac{1}{2}} + \mu \left(\varepsilon^2 + \phi_2^2 \zeta_{2,n}^2(t) \right)^{\frac{1}{2}} \right]^{-1} \times \left[\frac{\beta_1}{V} + i \zeta_{2,n}(t) \right]^{-1} \\ \times K^{\frac{n-1}{2}} [\zeta_{2,n}(t)] \frac{d\zeta_{2,n}(t)}{dt} H \left[t - (x_2^2 + n^2 h^2 \phi_1^2)^{\frac{1}{2}} \beta_1^{-1} \right],$$

and $\zeta_{2,n}(t)$ is given by Appendix with x_2 in place of x_1 .

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