TRANSFORMATIONS ON TENSOR SPACES

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In this paper we consider those linear transformations from one tensor product of vector spaces to another which carry nonzero decomposable tensors into nonzero decomposable tensors. We obtain a general decomposition theorem for such transformations. If we suppose further that the transformation maps the space into itself then we have a complete structure theorem in the following two cases: (1) the transformation is onto, and (2) the field is algebraically closed and the tensor space is a product of finite dimensional vector spaces. The main results are contained in Theorems 3.5 and 3.8 which state that the transformation

\[ T: U_1 \otimes \cdots \otimes U_n \rightarrow U_1 \otimes \cdots \otimes U_n \]

has the form

\[ T(x_1 \otimes \cdots \otimes x_n) = T_1(x_{\pi(1)}) \otimes \cdots \otimes T_n(x_{\pi(n)}) \]

where \( T_i: U_{\pi(i)} \rightarrow U_i \) are nonsingular and \( \pi \) is a permutation. Case (2) generalizes a theorem of Marcus and Moyls.

Let \( F \) be a field and \( \{ U_a: a \in A \} \) be a finite set of vector spaces over \( F \). Let \( (U, t) = (\otimes(U_a: a \in A), t) \) be a tensor product. Then \( U \) is a vector space over \( F \), \( t: \Pi(U_a: a \in A) \rightarrow U \) is multilinear and, for any vector space \( V \) over \( F \) and multilinear map \( f: \Pi(U_a: a \in A) \rightarrow V \), there is a unique linear transformation \( g: U \rightarrow V \) such that \( g \cdot t = f \). The decomposable tensors of \( U \) are defined to be the vectors \( t(\Pi(u_a: a \in A)) \), denoted by \( \otimes(u_a: a \in A) \), where \( u_a \in U_a \) for \( a \in A \).

The proofs of the main theorems are based on the purely combinatorial results of the following section.

2. Adjacency preserving functions. In this section we define the adjacency preserving functions and find a decomposition theorem for them.

Let \( A \) be a nonempty finite set and for each \( a \in A \) let \( S_a \) be a nonempty set. If \( J \) is a nonempty subset of \( A \) we let \( p_J \) denote the projection of \( \Pi(S_a: a \in A) \) onto \( \Pi(S_a: a \in J) \). If \( J = \{ a \} \) we write \( p_a \) for \( p_J \).

For each \( J \subseteq A \) we define an equivalence relation, denoted by \( \equiv(\text{mod } J) \), on \( \Pi(S_a: a \in A) \) by setting \( x \equiv y \pmod{J} \) if and only if \( p_a(x) = p_a(y) \) for all \( a \in A \setminus J \). If \( X \subseteq \Pi(S_a: a \in A) \) is a nonempty subset of equivalent elements relative to \( \equiv(\text{mod } J) \) then we call \( X \) a \( J \)-subset. If \( J = \{ a \} \) is a singleton we use \( a \)-subset for \( J \)-subset. We note the following

2.1. Lemma. A subset \( X \subseteq \Pi(S_a: a \in A) \) is an equivalence class relative to \( \equiv(\text{mod } J) \) if and only if \( p_J(X) = \Pi(S_a: a \in J) \) and \( p_a(X) \)
is a singleton for each \( a \in A \setminus J \).

The equivalence classes will be called maximal \( J \)-subsets.

On the set of subsets of \( \prod (S_a : a \in A) \) we define, for each \( J \subseteq A \), the relation \( \text{adj} \mod (J) \) by setting \( X \text{adj} Y \mod (J) \) if and only if \( X \) and \( Y \) are \( J \)-subsets and for precisely one \( a \in A \setminus J \) we have \( p_a(X) \neq p_a(Y) \). If \( x, y \in \prod (S_a : a \in A) \) and \( \{x\} \text{adj} \{y\} \mod (\phi) \) then we say that \( x \) and \( y \) are adjacent. The relation \( \text{adj} \mod (J) \) is symmetric but neither reflexive nor transitive.

2.2. **Lemma.** Let \( J \subseteq A \) and let \( X \) and \( Y \) be distinct maximal \( J \)-subsets of \( \prod (S_a : a \in A) \). Then there is a finite sequence \( X_1, \ldots, X_n \) of maximal \( J \)-subsets such that \( X = X_1, Y = X_n \), and \( X_i \text{adj} X_{i+1} \mod (J) \) for \( i = 1, \ldots, n - 1 \).

**Proof.** Let \( a_1, \ldots, a_n \) be the distinct elements of \( A \setminus J \) for which \( p_{a_i}(X) \neq p_{a_i}(Y) \). Then the maximal \( J \)-subsets \( X_i \) for which \( p_{a_j}(X_i) = p_{a_j}(Y) \) for \( j \leq i \) and \( p_{a_j}(X_i) = p_{a_j}(X) \) for \( j > i \) will suffice.

2.3. **Definition.** A function from one cartesian product of sets into another is an *adjacency preserving* function if and only if the images of adjacent elements are adjacent.

2.4. **Lemma.** Let \( f : \prod (S_a : a \in A) \to \prod (R_b : b \in B) \) be an adjacency preserving function. For each \( a \in A \) let \( S_a \) contain at least three elements. Then there is a function \( \sigma : A \to B \) such that for any \( c \in A \) and any maximal \( c \)-subset \( X \) of \( \prod (S_a : a \in A) \), \( f(X) \) is a \( \sigma(c) \)-subset of \( \prod (R_b : b \in B) \).

**Proof.** Let \( c \in A \) and let \( X \) be a maximal \( c \)-subset of \( \prod (S_a : a \in A) \). Then \( f(X) \) is a \( d \)-subset of \( \prod (R_b : b \in B) \) for some \( d \in B \), where \( d \) depends on \( c \) and \( X \). For, let \( x_1 \) and \( x_2 \) be distinct elements of \( X \) and let \( d \in B \) be that element of \( B \) for which \( p_d(f(x_1)) \neq p_d(f(x_2)) \). Then, for any \( x \in X \), \( p_d(f(x)) \) differs from at least one of the \( p_d(f(x_i)) \) and so \( p_d(f(x)) \) is independent of \( x \in X \) for \( b \neq d \). Therefore \( f(X) \) is a \( d \)-subset. We let \( \sigma(c, X) = d \). We show that \( \sigma(c, X) \) is independent of the maximal \( c \)-subset \( X \). Suppose the contrary. Then, from Lemma 2.2 it follows easily that there is a pair of maximal \( c \)-subsets \( X \) and \( Y \) for which \( X \text{adj} Y \mod (\{c\}) \) and \( \sigma(c, X) = d_1 \neq d_2 = \sigma(c, Y) \). Let \( c' \) be the unique element of \( A \) for which \( p_{c'}(X) \neq p_{c'}(Y) \). Let \( q : X \to Y \) be defined on each \( x \in X \) by \( p_a(q(x)) = p_a(x) \) if \( a \neq c' \) and \( p_{c'}(q(x)) = p_{c'}(Y) \). Then \( q \) is one-to-one, onto, and for each \( x \in X \) the pair \( x \) and \( q(x) \) are adjacent. Since \( S_c \) has at least three elements there are at least two elements \( x \in X \) such that \( p_{d_1}(f(x)) \neq p_{d_1}(f(Y)) \),
and of these, at least one for which \( p_{\delta} (f(q(x))) \neq p_{\delta} (f(X)) \). Now, for any \( x \in X \) satisfying both of these inequalities, \( f(x) \) and \( f(q(x)) \) are not adjacent, contrary to the hypothesis on \( f \). Therefore \( \sigma(c, X) \) is independent of the \( c \)-subset \( X \) and so \( \sigma(c) = \sigma(c, X) \) is a well defined function satisfying the conclusion of the lemma.

2.5. **Theorem.** Let \( f: \prod (S_a : a \in A) \rightarrow \prod (R_b : b \in B) \) be an adjacency preserving function and suppose that each \( S_a \) contains at least three elements. Then there is a partition of \( A \) into subsets \( A_i, \cdots, A_k \) and distinct elements \( b_1, \cdots, b_k \) of \( B \) such that for each \( i = 1, \cdots, k \) there is a function \( f_i: \prod (S_a : a \in A_i) \rightarrow R_{b_i} \) satisfying \( p_{b_i} \cdot f = f_i \cdot p_{A_i} \). Furthermore, the image of \( \prod (S_a : a \in A) \) under \( f \) is the set \( \prod (Q_b : b \in B) \) where \( Q_b \) is the image of \( \prod (S_a : a \in A) \) under \( (p_b \cdot f) \).

**Proof.** Let \( \sigma \) be given as in Lemma 2.4. Let \( \{b_1, \cdots, b_k\} = \sigma(A) \) and let \( A_i = \sigma^{-1}(b_i) \). Then \( A_i, \cdots, A_k \) is a partition of \( A \). Let \( J \) be one of the \( A_i \) and \( b \) the corresponding \( b \). Let \( X \) be a maximal \( J \)-subset of \( \prod (S_a : a \in A) \). We define \( f_x: \prod (S_a : a \in J) \rightarrow R_b \) by

\[
f_x = p_b \cdot f \cdot (p_J | X)^{-1}.
\]

Then \( f_x \) is well defined since \((p_J | X)\) is a one-to-one function from \( X \) onto \( \prod (S_a : a \in J) \). We prove that \( f_x = f_y \) for any two maximal \( J \)-subsets \( X \) and \( Y \). Suppose the contrary. Then, from Lemma 2.2, it follows that we can choose maximal \( J \)-subsets \( X \) and \( Y \) such that \( X \) \( \text{adj} \ (Y \text{mod } J) \) and \( f_x \neq f_y \). Let \( a' \in A \setminus J \) be an element for which \( p_a(X) \neq p_a(Y) \). Choose \( s \in \prod (S_a : a \in J) \) such that \( f_x(s) \neq f_y(s) \). Let

\[
x = (p_J | X)^{-1}(s) \quad \text{and} \quad y = (p_J | Y)^{-1}(s).
\]

Then \( x \in X \) and \( y \in Y \) are a pair of adjacent elements of \( \prod (S_a : a \in A) \). If we let \( b' = \sigma(a') \) then \( b' \neq b \) since \( a' \notin J = \sigma^{-1}(b) \). Therefore, \( f(x) \) and \( f(y) \) are adjacent and \( b' \) is the only element of \( B \) for which \( p_{b'}(f(x)) \neq p_{b'}(f(y)) \). But \( p_b(f(x)) = f_x(s) \neq f_y(s) = p_b(f(y)) \), a contradiction.

For each \( i \) we set \( f_i = f_x \) where \( X \) is any maximal \( A_i \)-subset of \( \prod (S_a : a \in A) \). Then, if \( x \in \prod (S_a : a \in A) \), we choose a maximal \( A_i \)-subset \( X \) containing \( x \) and note that

\[
(f_i \cdot p_{\delta_i})(x) = (p_{b_i} \cdot f \cdot (p_{A_i} | X)^{-1})(p_{A_i}(x)) = (p_{b_i} \cdot f)(x).
\]

If \( b \in \sigma(A) \) then the image of \( \prod (S_a : a \in A) \) under \((p_b \cdot f)\) consists of one element of \( R_b \). In fact, suppose \( x \) and \( y \) are adjacent elements of \( \prod (S_a : a \in A) \). Then \( f(x) \) and \( f(y) \) are adjacent and the element \( b' \in B \) for which \( p_{b'}(f(x)) \neq p_{b'}(f(y)) \) is in \( \sigma(A) \). Then \((p_b \cdot f)(x) = (p_b \cdot f)(y)\).

It is clear that \( f(\prod (S_a : a \in A)) \subseteq \prod (Q_b : b \in B) \). To show that we
have equality, suppose that \( x \in \Pi (Q_b: b \in B) \). Choose \( y_b \in \Pi (S_a: a \in A) \) such that \( (p_b \cdot f)(y_b) = p_b(x) \). Choose \( y \in \Pi (S_a: a \in A) \) such that \( p_a(y) = p_a(y_b) \) for \( i = 1, \ldots, k \). This can be done since the sets \( A_1, \ldots, A_k \) are pairwise disjoint. If \( b \in \sigma(A) \) then \( (p_b \cdot f)(y) = p_b(x) \) since the image is independent of \( y \).

For \( \delta < \omega \) we have \( (p_b \cdot f)(y) = (p_b \cdot f)(y_b) = f^{(p_a(y_b))} = f^{(p_a(y_b))} = f^{(y_b)} = f^*(a \cdot y) \). Therefore \( f(y) = x \), and this completes the proof.

3. The preservers of decomposable tensors. In this section we require the

**3.1. Lemma.** Let \( U = \bigotimes (U_a: a \in A) \) be a tensor product where the \( U_a \) are vector spaces over a field \( F \). Let \( x_a, x'_a \in U_a \) for \( a \in A \). Then

1. \( \bigotimes (x_a: a \in A) = 0 \) if and only if \( x_a = 0 \) for some \( a \in A \).
2. If \( x = \bigotimes (x_a: a \in A) \) and \( x' = \bigotimes (x'_a: a \in A) \) are nonzero decomposable tensors then,
   1. \( \langle x_a \rangle = \langle x'_a \rangle \) if and only if \( \langle x_a \rangle = \langle x'_a \rangle \) for \( a \in A \).
   2. \( x + x' \) is a decomposable tensor if and only if \( \langle x_a \rangle = \langle x'_a \rangle \) for all except possibly one \( a \in A \).

**Proof.** The statements (1) and (2)(a) are elementary properties of \( U \). The sufficiency of the condition in (2)(b) is clear. We prove the necessity of this condition by the following indirect argument. Suppose \( x + x' = \bigotimes (y_a: a \in A) \) where \( \langle x_b \rangle \neq \langle x'_b \rangle \) and \( \langle x_c \rangle \neq \langle x'_c \rangle \) for a pair of indices \( b \) and \( c \). We may suppose that \( \langle y_b \rangle \neq \langle y_b \rangle \). We define a function \( f: \Pi (U_a: a \in A) \to F \) as follows. For each \( a \in A \) we choose a linear functional \( f_a \in L^0(U_a, F) \) such that

1. \( f_a(x_a) \neq 0 \) for all \( a \in A \),
2. \( f_b(y_b) = f_a(x'_a) = 0 \),

and set \( f(u) = \Pi (f_a(p_a(u)): a \in A) \). Then \( f \) is multilinear and it induces a linear transformation \( f': \bigotimes (U_a: a \in A) \to F \). But \( 0 = f'(y) = f'(x + x') = f'(x) + f'(x') = f'(x) \neq 0 \), which is impossible.

Throughout the rest of this section we let \( U = \bigotimes (U_a: a \in A) \) and \( W = \bigotimes (W_b: b \in B) \) where the \( U_a \) and \( W_b \) are vector spaces over a field \( F \). We also assume that \( \dim (U_a) \geq 2 \) and that \( A, B \) are finite sets. We let \( T: U \to W \) be a linear transformation mapping nonzero decomposable tensors into nonzero decomposable tensors.

Let \( S_a \) and \( R_b \) be the sets of one dimensional subspaces of \( U_a \) and \( W_b \) respectively. We define a function \( f: \Pi (S_a: a \in A) \to \Pi (R_b: b \in B) \) as follows. Let \( x_a \in U_a \) be nonzero and let \( T(\bigotimes (x_a: a \in A)) = \bigotimes (y_b: b \in B) \). Let \( x \in \Pi (S_a: a \in A) \) and \( y \in \Pi (R_b: b \in B) \) such that \( p_a(x) = \langle x_a \rangle \) and \( p_b(y) = \langle y_b \rangle \). We set \( f(x) = y \) and note that by the above lemma, \( f \) is well defined. We prove next the
3.2. **Lemma.** The function $f$ above is an adjacency preserving function.

**Proof.** Let $u, u' \in \prod (S_a: a \in A)$ be adjacent and choose $x_a, x'_a \in u_a$ such that $p_a(u) = \langle x_a \rangle$, $p_a(u') = \langle x'_a \rangle$. Let $x = \otimes (x_a: a \in A)$ and $x' = \otimes (x'_a: a \in A)$. Then, by (2)(b) of Lemma 3.1, $x + x'$ is a decomposable tensor and by (2)(a) we have that $\langle x \rangle \neq \langle x' \rangle$. Let $y = T(x) = \otimes (y_b: b \in B)$ and $y' = T(x') = \otimes (y'_b: b \in B)$. Then $y + y'$ is a decomposable tensor. Let $w, w' \in \prod (R_b: b \in B)$ be such that $p_b(w) = \langle y_b \rangle$ and $p_b(w') = \langle y'_b \rangle$. Let $w = w(x)$ and $w' = w(x')$. Then $w$ and $w'$ are either adjacent or equal. If they were equal then $y = ey'$ for some $e \in F$, from which we get $T(x - ex') = 0$, a contradiction since $x - ex'$ is a nonzero decomposable tensor for all $e \in F$.

3.3. **Definition.** For each $A' \subseteq A$ and $x \in \prod (U_a: a \in A')$ we define a multilinear function $N_x: \prod (U_a: a \in A') \to U$ by setting $N_x(v) = \langle v_a \rangle$ where $v_a = p_a(x)$ for $a \in A'$ and $v_a = p_a(u)$ for $a \in A'$. We let $M_x: \otimes (U_a: a \in A') \to U$ be the linear transformation induced by $N_x$.

Since $\dim (U_a) \geq 2$, each $S_a$ contains at least three elements, and therefore we can apply Lemma 2.4 to obtain the function $\sigma: A \to B$ satisfying the conclusions of that lemma. Let $\sigma(A) = \{b_1, \ldots, b_k\}$ and $A_i = \sigma^{-1}(b_i)$. Let $V_i = \otimes (U_a: a \in A_i)$, $V = \otimes (V_i: i = 1, \ldots, k)$ and let $\varphi: U \to V$ be the canonical isomorphism.

3.4. **Theorem.** The decomposable tensor preserver $T$ has the form $M_x \cdot (T_i \otimes \cdots \otimes T_k) \cdot \varphi$ where

1. $y \in \prod (W_b: b \in \sigma(A))$, or $M_y$ is deleted if $\sigma(A) = B$,
2. $T_i: V_i \to W_{b_i}$ is a linear transformation mapping nonzero decomposable tensors of $V_i$ into nonzero vectors of $W_{b_i}$.

**Proof.** Let $x_i \in \prod (U_a: a \in A_i)$ be chosen for $i = 1, \ldots, k$. Consider $T \cdot M_{x_i}: V_i \to W_i$. For each $v \in V_i$, $M_{x_i}(v) = \otimes (v_a: a \in A)$ where $\langle v_a \rangle$ does not depend on $v$ whenever $a \in A_i$. Therefore, since $(p_b \cdot f)(s)$, for $s \in \prod (S_a: a \in A)$, does not depend on the coordinates of $s$ in $A \setminus \sigma^{-1}(b)$, there are fixed $w_b \in W_b$ for each $b \in B$, $b \neq b_i$, such that the image of $V_i$ under $T \cdot M_{x_i}$ has the form $\otimes (w'_b: b \in B) = w'_b$ for $b \neq b_i$ and $w'_{b_i} \in W'_{b_i}$, where $W'_{b_i}$ is a subspace of $W_{b_i}$. Then $T \cdot M_{x_i}$ induces a linear transformation $T_i: V_i \to W_{b_i}$ defined by $T_i(v) = w'_{b_i}$ where $T \cdot M_{x_i}(v) = \otimes (w'_b: b \in B)$, $w'_b = w_b$ for $b \neq b_i$. If $x' \in \prod (U_a: a \in A_i)$ is another element and $T'_{i}: V_i \to W'_{b_i}$ is induced as above by $T \cdot M_{x_i}$, then for each decomposable tensor $x \in V_i$ there is a $c_x \in F$ such that $T_i(x) = c_x T'_i(x)$. It then follows easily that there is a $c \in F$ such that $T_i = c T'_i$.

By Theorem 2.5 the image of $\prod (S_a: a \in A)$ under $f$ is $\prod (Q_b: b \in B)$ where $Q_b \subseteq R_b$ can be given explicitly. For each $b \in \sigma(A)$, $Q_b$ consists...
of one element and we let $Q_b = \langle y_b \rangle$. Let $y \in \prod (W_i : b \in \sigma(A))$ where $p_b(y) = y_b$, and let $T' = M_y (T_1 \otimes \cdots \otimes T_k) \cdot \phi$. If $x \in U$ is a decomposable tensor then $T(x) = e_x T'(x)$ for some $e_x \in F$, and therefore it follows that $T = e T'$ on all of $U$ for some $e \in F$.

3.5. Theorem. A decomposable tensor preserve of $U$ onto itself has the form $\otimes (T_a : a \in A)$ where $T_a : U_a \rightarrow U_{\sigma(a)}$ is an onto nonsingular linear transformation and $\sigma : A \rightarrow A$ is a permutation.

Proof. Let $f : \prod (S_a : a \in A) \rightarrow \prod (S_a : a \in A)$ be the adjacency preserving function induced by the decomposable tensor preserver and let $\sigma : A \rightarrow A$ be the function induced by $f$. Then the image of $\prod (S_a : a \in A)$ under $f$ has the form $\prod (Q_a : a \in A)$ and therefore the image of $U$ is spanned by elements $\otimes (u_a : a \in A)$ where $u_a$ belongs to the smallest subspace of $U_a$ which contains all the subspaces making up $Q_a$. Since $\dim (U_a) \geq 2$ and the tensor preserver is assumed to be onto, no $Q_a$ can consist of only one element. Therefore $\sigma$ is a permutation. The theorem now follows from Theorem 3.4. That $T_a$ is onto and nonsingular is clear.

3.6. Definition. If $V$ is a vector space over a field $F$ and if $\mathcal{L}(V)$ is the vector space of linear transformations of $V$ into itself, then a subspace of $\mathcal{L}(V)$ is called a nonsingular subspace if each of its nonzero elements is a nonsingular linear transformation.

3.7. Theorem. Let $k \geq 2$ be an integer and let $W_1, \cdots, W_k$ be vector spaces over a field $F$ where $2 \leq \dim (W_i) \leq \cdots \leq \dim (W_k) < \infty$. Then there is a linear transformation $L : \otimes (W_i : i = 1, \cdots, k) \rightarrow W_k$ mapping nonzero decomposable tensors into nonzero vectors if and only if $\mathcal{L}(W_k)$ contains a nonsingular subspace with dimension equal to $\dim (W_{k-1})$.

Proof. Suppose that $L$ exists. Let $w_i \in W_i$ for $i = 1, \cdots, k-2$ be nonzero vectors. For each $x \in W_{k-1}$ we let

$$\mathcal{W}_x = \{ w_1 \otimes \cdots \otimes w_{k-2} \otimes x \otimes y : y \in W_k \},$$

and note that $\mathcal{W}_x$ is a subspace consisting of decomposable tensors. Let $L_x = (L | \mathcal{W}_x)$ and let $I_x : W_k \rightarrow \mathcal{W}_x$ be defined by

$$I_x(y) = w_1 \otimes \cdots \otimes w_{k-2} \otimes x \otimes y$$

for $y \in W_k$. Then $L_x I_x \in \mathcal{L}(W_k)$ is nonsingular for $x \neq 0$. Let $\dim (W_{k-1}) = t$ and let $\{ x_1, \cdots, x_t \}$ be a basis of $W_{k-1}$. Then $\{ L_{x_1} I_{x_1}, \cdots, L_{x_t} I_{x_t} \}$ spans a nonsingular subspace of $\mathcal{L}(W_k)$. For,
suppose \( \sum_{i=1}^{t} a_i L_{x_i} x_i \) is singular. Choose \( y \neq 0 \) such that
\[
\sum_{i=1}^{t} a_i L_{x_i} x_i (y) = 0.
\]
Then, since \( \sum_{i=1}^{t} a_i L_{x_i} x_i (y) = L(w_1 \otimes \cdots \otimes w_{k-2} \otimes \sum_{i=1}^{t} a_i x_i \otimes y) \), we must have that \( \sum_{i=1}^{t} a_i x_i = 0 \). Therefore, \( a_1 = \cdots = a_t = 0 \).

Suppose that \( \mathcal{L}(W_k) \) has a nonsingular subspace with dimension \( t = \dim (W_{k-1}) \). We construct \( L \) inductively. Suppose that
\[
L_0: W_2 \otimes \cdots \otimes W_k \to W_k
\]
has been defined such that nonzero decomposable tensors of \( W_2 \otimes \cdots \otimes W_k \) are mapped into nonzero vectors of \( W_k \). Let \( s = \dim (W_1) \) and let \( \{L_1, \ldots, L_s\} \) be a basis of an \( s \)-dimensional nonsingular subspace of \( \mathcal{L}(W_k) \). Such a basis exists since \( s = \dim (W_1) \leq \dim (W_{k-1}) \). Let \( \{x_1, \ldots, x_s\} \) be a basis of \( W_1 \). Let \( N: W_1 \otimes W_k \to W_k \) be the linear transformation induced by the multilinear function \( N: \mathbf{W}_1 \times W_k \to W_k \) where
\[
N(\sum_{i=1}^{s} a_i x_i, y) = \sum_{i=1}^{s} a_i L_i (y).
\]
Then \( N(x, y) = 0 \) implies that \( x = 0 \) or \( y = 0 \) and therefore \( N(x \otimes y) = 0 \) if and only if \( x \otimes y = 0 \). Let \( I: W_1 \to W_1 \) be the identity and let \( L = N \cdot (I \otimes L_0) \).

Then \( L(w_1 \otimes \cdots \otimes w_k) = N(w_1 \otimes L_0 (w_2 \otimes \cdots \otimes w_k)) = 0 \) implies that \( w_1 = 0 \) or \( L_0 (w_2 \otimes \cdots \otimes w_k) = 0 \). Therefore, either \( w_1 = 0 \) or \( w_2 \otimes \cdots \otimes w_k = 0 \), and in both cases \( w_1 \otimes \cdots \otimes w_k = 0 \). This completes the proof.

3.8. Theorem. Let \( F \) be algebraically closed and let \( T: U \to U \) be a decomposable tensor preserver where \( \dim (U_a) \) is finite for all \( a \in A \). Then \( T = \bigotimes (T_a; a \in A) \) where \( T_a: U_a \to U_{\sigma (a)} \) is a nonsingular linear transformation and \( \sigma: A \to A \) is a permutation satisfying \( \dim (U_a) = \dim (U_{\sigma (a)}) \) for \( a \in A \).

Proof. We prove that \( \sigma \) is a permutation. By Theorem 3.4, \( T = M_y \cdot (T_1 \otimes \cdots \otimes T_k) \cdot \varphi \) where the domain of \( T_i \) is \( V_i = \bigotimes (U_a; a \in A_i) \) and \( A_i = \sigma^{-1} (a_i) \) for some \( a_i \in A \). For each \( a \in A_i \), \( V_i \) contains a subspace with dimension equal to \( \dim (U_a) \) which consists of decomposable tensors only. It follows that \( U_{a_i} \), which is the range space of \( V_i \) under \( T_i \), has dimension at least as large as the maximum of the \( \dim (U_a) \) for \( a \in A_i \). Therefore, for each \( a \in A \), \( \dim (U_a) \leq \dim (U_{\sigma (a)}) \). Suppose that \( \sigma \) is not one-to-one. Of those \( a \in A \) for which \( \sigma^{-1} (\sigma (a)) \) consists of at least two elements, choose one, say \( b \), for which \( \dim (U_b) \) is maximal. Then \( \dim (U_b) = \dim (U_{\sigma (b)}) \). For, suppose that \( \dim (U_b) < \dim (U_{\sigma (b)}) \). Then \( \sigma \) maps the set \( \{a \mid \dim (U_a) > \dim (U_b)\} \) into the set \( \{a \mid \dim (U_a) > \dim (U_b)\} \), and consequently, there is a \( b' \in A \) for which \( \sigma^{-1} (\sigma (b')) \) has at least two elements and \( \dim (U_{b'}) > \dim (U_b) \).
This contradicts the choice of \( b \). Now, \( \sigma(b) \in \sigma(A) \) so that \( \sigma(b) = a_i \) for some \( i \) and \( T_i : V_i \to U_{a_i} \). By Theorem 3.7, \( \mathcal{L}(U_{a_i}) \) contains a nonsingular subspace with dimension at least two. This is impossible since \( F \) is assumed to be algebraically closed (for nonsingular \( C \) and \( D, C - eD \) is singular for any eigenvalue \( e \) of \( D^{-1}C \)). Therefore \( \sigma \) is a permutation and the theorem follows from Theorem 3.4.

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