BOUNDARY VALUE PROBLEMS WITH INTERIOR POINT
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Recently Neuberger, Zettl and Loud have revived interest in self-adjoint boundary value problems with interior point boundary conditions. All three have derived their results from rather extensive study of the Green's function associated with the nonhomogeneous problem. They require \( G(x, \xi) = G(\xi, x) \).

Rather than approach the problem via the Green's function, this article considers the problem as that of a differential operator in a Hilbert space, derives the adjoint operator, whose domain specifies the adjoint boundary conditions, and then produces necessary and sufficient conditions for self-adjointness.

To do this we employ a variation of the fundamental lemma of the calculus of variations in the Hilbert space setting, and we note our method is applicable even when the Green’s function fails to exist.

For convenience we only consider a first order vector equation, although our results are easily extended to \( n \)-th order vector systems. Finally, our method is extendable to systems whose boundary conditions are applied at an infinite set of points. We hope to pursue this line in a future paper.

1. The problem and its adjoint. Let us consider an interval \([a, b]\) which is subdivided into \( m \) subintervals by

\[
 a_1, a_2, \cdots, a_{m-1} (a = a_0 < a_1 < \cdots < a_{m-1} < a_m = b).
\]

We denote by \( H \) the Hilbert space of \( n \times 1 \) vectors

\[
 X = (x_1, x_2, \cdots, x_n)^t, \quad Y = (y_1, y_2, \cdots, y_n)^t,
\]

defined on \([a, b]\) whose components are in \( L^2(a, b) \) and whose inner product is given by

\[
 (X, Y) = \int_a^b Y^*X dx = \sum_{i=1}^m \int_a^{a_i} x_i y_i dx.
\]

Let us consider boundary operators of the form

\[
 M_i Y = \sum_{i=0}^m [A_{ij} Y(a_j +) + B_{ij} Y(a_j -)],
\]

\( i = 1, \cdots, k \), where \( A_{im} = 0, B_{i0} = 0 \), and \( Y(a_j \pm) \) indicates the limit of
Y(x) as x approaches \(a_j\) from above or below. We assume that these boundary operators are linearly independent. Thus \(k \leq 2nm\). Note, however, \(k\) does not have to equal \(nm\).

We let \(A_i\) and \(A_0\) be continuous \(n \times n\) matrices, and in addition assume that \(A_i'(x)\) exists and is continuous. We denote by \(D\) the set of all \(n \times 1\) vectors \(Y\) satisfying

1. \(Y\) is in \(H\).
2. \(Y\) is absolutely continuous in each subinterval \([a_j, a_{j+1}], j = 0, 1, \ldots, m - 1\) of \([a, b]\).
3. \(M_iY = 0, i = 1, \ldots, k\).
4. \(A_iY' + A_0Y\) is in \(H\).

We define a differential operator \(L\) by letting \(LY = A_iY' + A_0Y\) for all \(Y\) in \(D\).

It is evident that \(D\) is dense in \(H\), and therefore \(L\) has a well-defined adjoint operator \(L^*\) associated with it.

**Theorem 1.** If \(Z\) is in the domain of \(L^*\), then \(Z\) is absolutely continuous in each subinterval \([a_j, a_{j+1}], j = 0, 1, \ldots, m - 1\) of \([a, b]\).

\[L^*Z = -(A_i^*Z)' + A_0^*Z\] in each subinterval

\[(a_j, a_{j+1}), j = 0, 1, \ldots, m - 1\]
of \([a, b]\).

**Proof.** Let \(H_0\) denote the subspace of \(D\) whose elements vanish at \(a, a_1, \ldots, a_{m-1}, b\). \(H_0\) is also dense in \(H\).

If \(Y\) is in \(H_0\), then

\[\int_a^b (L^*Z)^*Ydx = \int_a^b Z^*[A_iY' + A_0Y]dx.\]

Thus

\[\int_a^b Z^*A_iY'dx = \int_a^b [L^*Z - A_0^*Z]^*Ydx.\]

Since \(Y\) vanishes at \(a, a_1, \ldots, a_{m-1}, b\), integrating by parts,

\[\int_a^b (A_i^*Z)^*Y'dx = -\int_a^b \left\{\int_a^z [L^*Z - A_0^*Z]dt\right\}^*Y'dx.\]

So

\[\int_a^b \left\{A_i^*Z + \int_a^z [L^*Z - A_0^*Z]dt\right\}^*Y'dx = 0.\]

We must now find those elements \(J\) such that \(\int_a^b J^*Y'dx = 0\). It is easily seen that \(\int_a^b K^*Ydx = 0\) if and only if
\[
\int_{a}^{b} \left[ \int_{a}^{x} K^{*} dt \right] Y' dx = 0 .
\]

Since \( Y \) is in \( H_{0} \), which is dense \( H \), \( Y' \) is only orthogonal to elements which are constant on each subinterval \((a_{j}, a_{j+1})\), \( j = 0, 1, \cdots, m-1 \). Thus

\[
A_{i}^{*} Z + \int_{a}^{x} [L^{*} Z - A_{0}^{*} Z] dt = C(Z) ,
\]

where \( C(Z) \) is constant on each subinterval \((a_{j}, a_{j+1})\), \( j = 0, 1, \cdots, m-1 \). If \( x \neq a_{j} \) for some \( j \), we may differentiate, and

\[
L^{*} Z = -(A_{i}^{*} Z)' + A_{0}^{*} Z .
\]

**Theorem 2.** If \( Z \) is in the domain of \( L^{*} \), then \( Z \) satisfies the following equations.

\[
A_{i}^{*} (a_{j} -) Z(a_{j} -) - \sum_{i=1}^{k} B_{ij}^{*} \phi_{i}(Z) = 0 ,
\]

\[
-A_{i}^{*} (a_{j+1} -) Z(a_{j+1} -) - \sum_{i=1}^{k} A_{ij}^{*} \phi_{i}(Z) = 0 ,
\]

where \( j = 1, 2, \cdots, m \), and \( \phi_{i}(Z) \) are functionals which depend upon \( Z \).

**Proof.** Let \( Y \) be in the domain of \( L \) and \( Z \) be in the domain of \( L^{*} \). Then

\[
(L Y, Z) - (Y, L^{*} Z) = \int_{a}^{b} [Z^{*}(L Y) - (L^{*} Z)^{*} Y] dx
\]

\[
= \int_{a}^{b} (Z^{*} A_{i} Y)' dx
\]

\[
= \sum_{j=1}^{m} \int_{a_{j-1}}^{a_{j}} (Z^{*} A_{i} Y)' dx
\]

\[
= \sum_{j=1}^{m} (Z^{*} A_{i} Y) \big|_{a_{j-1}}^{a_{j}} = 0 .
\]

Let \( \phi_{i}(Z) \) be arbitrary parameters, \( i = 1, \cdots, k \). Then, since \( M_{i} Y = 0, i = 1, \cdots, k \),

\[
0 = \sum_{j=1}^{m} (Z^{*} A_{i} Y) \big|_{a_{j-1}}^{a_{j}} - \sum_{i=1}^{k} \phi_{i}^{*}(Z) \sum_{j=0}^{m} [A_{ij} Y(a_{j} +) + B_{ij} Y(a_{j} -)] .
\]

Collecting like terms,

\[
0 = \sum_{j=1}^{m} [Z(a_{j} -) A_{i} (a_{j} -) - \sum_{i=1}^{k} \phi_{i}^{*}(Z) B_{ij}] Y(a_{j} -) + \sum_{j=0}^{m-1} \left[ -Z(a_{j} +) A_{i} (a_{j} +) - \sum_{i=1}^{k} \phi_{i}^{*}(Z) A_{ij} \right] Y(a_{j} +) .
\]
Since $Y(a_j^+)$ and $Y(a_j^-)$ may be *arbitrary*, the result follows.

The parameters $\phi_i(Z)$ seem somewhat artificial in this setting. However, if the boundary conditions also involve an integral, they enter in a very natural way, not only into the adjoint boundary conditions, but also into the *form* of the adjoint operator.

2. Reduction to an end point problem. The results of this section are very similar to a procedure of Mansfield's [2]. Mansfield, however, parameterized each subinterval $[a_j, a_{j+1}]$, $j = 0, \ldots, m - 1$. This is unnecessary.

We make the following definitions. Let $I_j = [a_{j-1}, a_j]$, $j = 1, \ldots, m$. Let $\mathcal{Y}$ denote the $nm \times 1$ vector $\mathcal{Y} = (Y(x_1), Y(x_2), \ldots, Y(x_m))^t$ where $x_j$ is in $I_j$.

\[
\mathcal{A}_i = \begin{pmatrix}
A_i(x_1) & 0 & \cdots & 0 \\
0 & A_i(x_2) & \cdots & 0 \\
& \vdots & \ddots & \vdots \\
0 & 0 & \cdots & A_i(x_m)
\end{pmatrix},
\]

\[
\mathcal{A}_o = \begin{pmatrix}
(A_o(x_1) & 0 & \cdots & 0 \\
0 & A_o(x_2) & \cdots & 0 \\
& \vdots & \ddots & \vdots \\
0 & 0 & \cdots & A_o(x_m)
\end{pmatrix},
\]

$\mathcal{A} = (A_{i-1})$, $\mathcal{B} = (B_{ij})$. Let $A$ consist of the $m$-tuple

$$(a_0^+, a_1^+, \ldots, a_{m-1}^+)$$

$B$ the $m$-tuple $(a_1^-, a_2^-, \ldots, a_m^-)$. By $\mathcal{Y}(A)$ we mean the $nm \times 1$ vector $(Y(a_0^+), Y(a_1^+), \ldots, Y(a_{m-1}^+))^t$ with a similar expression for $\mathcal{Y}(B)$.

$H$ is exactly equivalent to the Hilbert space $\mathcal{H}$ of $nm \times 1$ vectors $\mathcal{Y}$, where the norm is computed by integrating the first $n$ components over $I_1$, the next $n$ over $I_2$, etc. In this notation, however $D$ corresponds to the set $\mathcal{D}$ which consists of all $nm \times 1$ matrices $\mathcal{Y}$ satisfying

1. $\mathcal{Y}$ is in $\mathcal{H}$.
2. $\mathcal{Y}$ is absolutely continuous in the $m$-tuple interval $[A, B]$.
3. $\mathcal{A}\mathcal{Y}(A) + \mathcal{B}\mathcal{Y}(B) = 0$.
4. $\mathcal{A}\mathcal{Y}^t + \mathcal{A}_{\mathcal{Y}}$ is in $\mathcal{H}$.

Then $L$ corresponds to the operator $\mathcal{L}$ which is defined by $\mathcal{L}\mathcal{Y} = \mathcal{A}\mathcal{Y}^t + \mathcal{A}_{\mathcal{Y}}$ for all $\mathcal{Y}$ in $\mathcal{D}$.

In this setting our problem has been reduced to one with end point boundary conditions.

If $\mathcal{Z} = (Z(x_1), Z(x_2), \cdots, Z(x_m))^t$ and
The adjoint operator takes the form.

\[ L^* \varphi = -(A^* \varphi)' + A^0 \varphi \]
on \([A, B]. The domain of \( L^* \) is determined by the boundary conditions

\[ A^*(A) \varphi(A) + A^* \Phi(\varphi) = 0, \]
\[ A^*(B) \varphi(B) - B^* \Phi(\varphi) = 0. \]

Green's formula takes the form

\[ \int_A^B [ \varphi^*(L \varphi) - (L^* \varphi)^* \varphi ] dx = (\varphi^* A \varphi) \bigg|_A^B = \Phi(\varphi)^*[A \varphi(A) + B \varphi(B)] = 0. \]

On the other hand if \( C \varphi(A) + D \varphi(B) \) completes the number of independent boundary forms, then there exist complimentary forms \( \tilde{A} \varphi(A) + \tilde{B} \varphi(B) \) and \( \tilde{C} \varphi(A) + \tilde{D} \varphi(B) \) such that

\[ \int_A^B [ \varphi^*(L \varphi) - (L^* \varphi)^* \varphi ] dX = (\tilde{A} \varphi^*(A) + \tilde{B} \varphi^*(B)) [A \varphi(A) + B \varphi(B)] + (\tilde{C} \varphi^*(A) + \tilde{D} \varphi^*(B)) [C \varphi(A) + D \varphi(B)]. \]

The coefficients of these forms satisfy

\[ \begin{pmatrix} \tilde{A}^* & \tilde{C}^* \\ \tilde{B}^* & \tilde{D}^* \end{pmatrix} \begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} -A(A) & 0 \\ 0 & A(B) \end{pmatrix} \]

which yields the equivalent boundary condition \( \tilde{C} \varphi^*(A) + \tilde{D} \varphi^*(B) = 0 \), and the formula \( \Phi(\varphi) = \tilde{A} \varphi^*(A) + \tilde{B} \varphi^*(B). \) The following theorem follows in a manner similar to that of Reid [4].

**Theorem 3.** \( L \) is self-adjoint in \( \mathcal{H} \) if and only if

\[ A = -A^1, A_0 = A^0 - A^1', A_1(A)^{-1} A^* = B_1(B)^{-1} B^*. \]

The last result may also be found by substituting the parametric adjoint boundary conditions into those for \( L \).

If the number of boundary conditions \( k \) in the original problem is equal to \( nm \), and if the homogeneous problem \( (L - \lambda) \varphi = 0 \) has only the trivial solution in \( \mathcal{H} \), then the nonhomogeneous problem \( (L - \lambda) \varphi = \varphi \) has a unique solution, which is generated by an in-
integral equation.

\[ \mathcal{D}(X) = \int_{A}^{B} \mathcal{D}(X, \xi) \mathcal{F}(\xi) d\xi. \]

The Green's function \( \mathcal{D}(X, \xi) \) has the form

\[
\begin{pmatrix}
G(x_1 \times x_1) & G(x_1 \times x_2) \cdots G(x_1 \times x_m) \\
G(x_2 \times x_1) & G(x_2 \times x_2) \cdots G(x_2 \times x_m) \\
\vdots & \vdots & \ddots & \vdots \\
G(x_m \times x_1) & G(x_m \times x_2) \cdots G(x_m \times x_m)
\end{pmatrix}
\]

As a function of \( X \) it formally satisfies \((\mathcal{L} - \lambda) \mathcal{D} = 0\) and the boundary conditions defining \( \mathcal{D} \). As a function of \( \xi \), \( \mathcal{D}(X, \xi)^* \) formally satisfies the adjoint equation \((\mathcal{L}^* - \lambda) \mathcal{D}^* = 0\) and the adjoint boundary conditions. If \( \mathcal{L} \) is self-adjoint in \( \mathcal{H} \), \( \mathcal{D}(X, \xi) \) automatically exhibits the usual symmetric properties associated with self-adjoint boundary value problems which were illustrated by Loud [1].

We finally remark that these results can be extended to higher order systems with the standard modifications. In the self-adjoint situations the usual eigenfunction expansions are valid. In the non-self-adjoint situations expansions similar to Birkhoff's are possible.

References


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