Pacific Journal of Mathematics

UNIFORM FINITE GENERATION OF THE AFFINE GROUP

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Vol. 40, No. 2

October 1972

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A connected Lie group H is said to be uniformly finitely generated by a given pair of one-parameter subgroups if there exists a positive integer n such that every element of H can be written as a finite product of length at most n of elements chosen alternately from the two one-parameter subgroups. Define the order of generation of H as the least such n. It is shown that the order of generation of the affine group is either 4 or 5 while its connected Lie subgroups (with two exceptions) have order of generation equal to their dimension.

A connected Lie group H is generated by a pair of one-parameter subgroups if every element of H can be written as a finite product of elements chosen alternately from the two one-parameter subgroups. If, moreover, there exists a positive integer n such that every element of H possesses such a representation of length at most n, then H is said to be uniformly finitely generated by the pair of one-parameter subgroups. In this case define the order of generation of H as the least such n; otherwise define it as infinity. Since the order of generation of H will, in general, depend upon the pair of one-parameter subgroups, H may have many different orders of generation. However, it is a simple consequence of Sard's theorem [4] that the order of generation of H must always be greater than or equal to the dimension of H.

The orders of generation of the isometry groups of the Euclidean and Non-Euclidean geometry are known. The order of generation of the isometry group of the spherical geometry may be any integer ≥ 3 ; it is determined by the cross-ratio of the fixed points of the pair of elliptic one-parameter subgroups [1]. The order of generation of the isometry group of the Euclidean geometry is infinite if both one-parameter subgroups are elliptic and it is 3 if one is elliptic and the other parabolic [2]. The order of generation of the isometry group of the hyperbolic geometry is finite if both one-parameter subgroups are elliptic, 3 if exactly one is elliptic and 4 in all other cases except that it is 6 if both are hyperbolic with interlacing fixed points [2].

Here all possible orders of generation of the affine group, i.e., the group of all transformations $w = \alpha z + \beta$ (α , β complex, $\alpha \neq 0$) and of all its connected Lie subgroups are determined. It is shown that for the affine group the possible orders of generation are 4 and 5 while its connected Lie subgroups (excluding the isometry group of the Euclidean geometry and the group $w = az + \beta$, a > 0) have order of

generation equal to their dimension.

II. Preliminaries. The affine group A, as defined above, may also be viewed as the group of 2×2 complex invertible matrices of the form $\begin{pmatrix} \alpha & \beta \\ 0 & 1 \end{pmatrix}$. It is easily shown that the Lie algebra \mathfrak{A} of the affine group consists of all 2×2 complex matrices $\begin{pmatrix} \gamma & \delta \\ 0 & 0 \end{pmatrix}$. These are in 1-1 correspondence with the transformations $\varepsilon = \gamma w + \delta$ of the complex plane, so that \mathfrak{A} may be viewed as the set of these (infinitesimal) transformations; this viewpoint will be adopted throughout this paper. By identifying the (proper) subalgebras of \mathfrak{A} and using exp, it can be shown that the proper connected Lie subgroups of A, excluding the isometry group of the Euclidean geometry and the oneparameter subgroups, are (to within an inner automorphism) (cf. [3]) (1) (a) $w = e^{(1+bi)t}z + \beta$ (t real, β complex); for each fixed real number

b this is a 3-dimensional subgroup of the affine group.

- (b) $w = z + \beta$; the 2-dimensional translation group.
- (c) $w = \alpha z, \alpha \neq 0$; the 2-dimensional subgroup that leaves the origin fixed.
- (d) w = az + b (a, b real, a > 0); the 2-dimensional component of the identity of the real affine group.

The one-parameter subgroups of A, identified by the procedure outlined above, may be viewed as the solutions of the differential system

(2)
$$\frac{dw}{dt} = \gamma w + \delta \qquad w(0, z) = z$$

i.e., for each $t, -\infty < t < +\infty$, w(t, z) is an element of A and the set of all solutions (2) forms a one-parameter subgroup. Under the transformations of the Lie algebra induced by an inner automorphism of A, the discriminant γ^2 of the infinitesimal transformation ε is an absolute invariant. An infinitesimal transformation ε together with the one-parameter subgroup that it generates is classified as loxodromic if its discriminant has nonzero imaginary part, and as elliptic, parabolic or hyperbolic if its discriminant is real and respectively negative, zero or positive. The infinitesimal transformations of the subgroups of A are respectively:

(3) (a) $\varepsilon = (1 + bi)w + \delta$ for $w = e^{(1+bi)t}z + \beta$.

- (b) $\varepsilon = \delta$ for the translation group.
 - (c) $\varepsilon = \gamma w$ for the group that leaves the origin fixed.
 - (d) $\varepsilon = qw + r$ (q, r real) for the real affine group.

The affine group A as well as all its subgroups listed in (1) except for the group $w = e^t z + \beta$ can be generated by an appropriate pair of one-parameter subgroups [3]. A pair of infinitesimal transformations whose one-parameter subgroups genenrate A can be simultaneously transformed into the normal form

(4)
$$\varepsilon = \gamma w, \eta = \lambda(w-1) \quad \operatorname{Im}\left(\frac{\lambda}{\gamma}\right) \neq 0$$

by means of a suitable inner automorphism of A. To establish this one need merely determine necessary and sufficient conditions for ε , η , $\sigma = [\varepsilon, \eta] = \eta (d\varepsilon/dw) - \varepsilon (d\eta/dw)$, $[\varepsilon, \sigma]$, and $[\eta, \sigma]$ to span a 4 dimensional vector space over the reals. A similar analysis shows that a pair of infinitesimal transformations whose one-parameter subgroups generate the subgroups of A listed in (1) (except for 1(a) with b = 0) can be simultaneously transformed into the respective normal form

(a) $\varepsilon = (1 + bi)w, b \neq 0, \eta = 1; \varepsilon$ loxodromic, η parabolic or $\varepsilon = (1 + bi)w, \eta = (1 + bi)(w - 1), b \neq 0;$ both loxodromic (5) (b) $\varepsilon = 1, \eta = \delta$ Im $(\delta) \neq 0$ (c) $\varepsilon = \gamma w, \eta = \lambda w$ Im $(\lambda/\gamma) \neq 0$ (d) $\varepsilon = w, \eta = 1; \varepsilon$ hyperbolic, η parabolic or

$$\varepsilon = w, \eta = w - 1$$
; both hyperbolic

by an inner automorphism.

Denote by $T_t(z)$ and $S_s(z)$ the one-parameter subgroups generated by ε and η respectively. The orbit under ε of the point z_0 is defined as $\{T_t(z_0), -\infty < t < +\infty\}$; in an analogous manner one defines the orbit of z_0 under η . The orbit of z_0 is a line parallel to the translation vector, a circle centered at the fixed point, a ray emanating from the fixed point or a spiral centered at the fixed point as ε is respectively parabolic, elliptic, hyperbolic or loxodromic. The lemma below gives a simple sufficient condition for a curve to intersect a spiral orbit.

LEMMA 1. Let C denote the range of the continuous map $f: [0, 1] \rightarrow$ complex plane and suppose f(0) = 0, $f(u) \neq 0$ on any subinterval [0, b]. Assume there exists a ray L emanating from the origin $(0 \notin L)$ and an a > 0 such that $f([0, a]) \cap L = \emptyset$. Then in any neighborhood of the origin, C and the spiral orbit $\{z_0e^{\gamma t}, -\infty < t < +\infty\}$ of $z_0 \neq 0$ under $\varepsilon = \gamma w (\operatorname{Im}(\gamma^2) \neq 0)$ must intersect infinitely often. In particular, the conclusion holds if f'(0) exists and is not zero.

Proof. The proof is based on the fact that C is connected; the details are omitted.

III. THEOREM 1. The order of generation of all the proper connected Lie subgroups of the affine group listed in (1) (except 1(a) with b = 0) is always equal to the dimension of the respective subgroup.

Proof. (a) $T_t(z) = e^{(1+bi)}tz$ and $S_s(z) = z + s$ if $\eta = 1$ or $S_s(z) = z + s$

 $e^{(1+bi)s}z + 1 - e^{(1+bi)s}$ if $\eta = (1 + bi)(w - 1)$. Let $V(z) = e^{(1+bi)t}z + \beta = e^{(1+bi)t}(z - \sigma)$, where $\sigma = -\beta/e^{(1+bi)t}$, be an arbitrary element of the subgroup. Note that $V(\sigma) = 0$ and that V(0) lies on the spiral orbit of $-\sigma$ under ε . The orbit of 0 under η is either the real axis if $\eta = 1$ or a spiral centered at 1 if $\eta = (1 + bi)(w - 1)$. By Lemma 1 both curves must intersect the spiral orbit of σ under ε . Choose t_1 and s_1 such that $S_{s_1}T_{t_1}(z)$ takes σ into 0. Since $S_{s_1}T_{t_1}(z)$ is an element of the subgroup, $S_{s_1}T_{t_1}(0)$ must lie on the spiral orbit of $-\sigma$ under ε . Choose t_2 such that $T_{t_2}S_{s_1}T_{t_1}(0) = V(0)$. Since V and $T_{t_2}S_{s_1}T_{t_1}$ agree on σ , 0 (and ∞), it follows that $T_{t_2}S_{s_1}T_{t_1} = V$.

(b) $T_t(z) = z + t$, $S_s(z) = z + s\delta$. Since $S_sT_t(z) = T_tS_s(z) = z + t + s\delta$ to represent an arbitrary translation $V(z) = z + \beta$ as a product of length 2 it suffices to choose s and t such that $t + s\delta = \beta$ —this is possible as Im $\delta \neq 0$.

(c) $T_t(z) = e^{\gamma t}z$, $S_s(z) = e^{\lambda s}z$. Since $S_sT_t(z) = T_tS_s(z) = e^{\gamma t + \lambda s}z$, to represent $V(z) = \alpha z = e^{\log \alpha} z$ as a product of length 2 it suffices to choose s and t such that $\gamma t + \lambda s = \log \alpha$ —this is possible as $\operatorname{Im}(\lambda/\gamma) \neq 0$.

(d) $T_t(z) = e^t z$ and $S_s(z) = z + s$ if $\eta = 1$ or $S_s(z) = e^s z + 1 - e^s$ if $\eta = w - 1$. In the first case, since $S_s T_t(z) = e^t z + s$, to represent an arbitrary real affine transformation V(z) = az + b, a > 0 as a product of length 2 choose s = b, $t = \ln a$. In the second case note that $S_s T_t(z) = e^{s+t}z + 1 - e^s$ and $T_t S_s(z) = e^{s+t}z + e^t(1 - e^r)$. If b < 1, V(z)can be represented as a product $S_s T_t(z)$ by choosing $s = \ln(1 - b)$ and $t = \ln(a/(1 - b))$. If $b \ge 1$, then a + b > 0 and V(z) can be represented as a product $T_t S_s(z)$ by choosing $t = \ln(a + b)$, $s = \ln(a/(a + b))$.

IV. THEOREM 2. The order of generation of the affine group is 4 except that if one infinitesimal transformation is elliptic and the other hyperbolic then it is 5.

Proof. $T_t(z) = e^{\gamma t}z$, $S_s(z) = e^{\lambda s}z + 1 - e^{\lambda s}$, $\operatorname{Im}(\lambda/\gamma) \neq 0$. Assume first that at least one infinitesimal transformation is loxodromic—without loss of generality let it be ε . To represent and arbitrary affine transformation $V(z) = \alpha z + \beta = \alpha z + \sigma - \alpha$ where $\sigma = \alpha + \beta = V(1)$ as a product $T_{t_2}S_{s_2}T_{t_1}S_{s_1}(z)$ of length 4 it is necessary and sufficient that the two equations

$$(6) T_{t_2} S_{s_2} T_{t_1} S_{s_1}(1) = \sigma$$

(7)
$$e^{\gamma(t_1+t_2)+\lambda(s_1+s_2)} = \alpha = e^{\log \alpha}$$

be satisfied. If $t_0 = t_1 + t_2$, $s_0 = s_1 + s_2$ equation (7) is satisfied if and only if

(8)
$$\gamma t_0 + \lambda s_0 = \log \alpha \pmod{2\pi i}$$
.

Since Im $(\lambda/\gamma) \neq 0$ it is always possible to satisfy equation (8) with real numbers t_0 and s_0 . Thus it suffices to prove that equation (6) can be solved with real numbers t_1 , t_2 , s_1 and s_2 such that $t_1 + t_2 = t_0$, $s_1 + s_2 = s_0$. Note that as $S_{s_1}(1) \equiv 1$, equation (6) is independent of s_1 ; hence it suffices to prove that there are real numbers t_1 , t_2 and s_2 with $t_1 + t_2 = t_0$ such that

(9)
$$e^{\gamma t_2}(e^{\lambda s_2}e^{\gamma t_1} + (1 - e^{\lambda s_2})) = \sigma$$

or equivalently that there are real numbers t_1 and s_2 such that

(10)
$$e^{\gamma(t_0-t_1)}(e^{\lambda s_2}e^{\gamma t_1}+(1-e^{\lambda s_2}))=\sigma$$

If $\sigma = e^{\gamma t_0}$, equation (10) will be satisfied if $s_2 = 0$. If $\sigma \neq e^{\gamma t_0}$, then equation (10) is equivalent to

(11)
$$\frac{1 - e^{\lambda s_2}}{\sigma e^{-\gamma t_0} - e^{\lambda s_2}} = e^{\gamma t_1} \cdot$$

If $F(s_2) = (1 - e^{\lambda s_2}) \setminus (\sigma e^{-\gamma t_0} - e^{\lambda s_2})$, then F(0) = 0, $F'(0) = \lambda \setminus (1 - \sigma e^{-\gamma t_0}) \neq 0$. Hence by Lemma 1 there exist real t_1 and s_2 that satisfy equation (11) and the proof in case at least one infinitesimal transformation is loxodromic is complete.

If neither infinitesimal transformation is loxodromic, it follows from (4) that one is elliptic and the other hyperbolic; assume without loss of generality that $\varepsilon = iw$, $\eta = w - 1$. First it will be shown that the affine transformation $V_0(z) = -z + 2$ ($\alpha = -1$, $\sigma = 1$) cannot be expressed as a product of length 4. If $V_0(z)$ were expressible as a product $T_{t_2}S_{s_2}T_{t_1}S_{s_1}(z)$, equations (8) and (11) with $\gamma = i, \lambda = 1$ require that

(12)
$$it_0 + s_0 = \pi i \pmod{2\pi i}$$
 and

(13)
$$\frac{1-e^{s_2}}{e^{-it_0}-e^{s_2}}=e^{it_1}$$

both be satisfied. Now (12) implies that $e^{-it_0} = -1$. Since

(14)
$$\left|\frac{e^{s_2}-1}{e^{s_2}+1}\right| < 1$$
 for all real s_2

equations (12) and (13) cannot be simultaneously satisfied.

If $V_0(z)$ were expressible as a product $S_{s_2}T_{t_2}S_{s_1}T_{t_1}(z)$, then equation (12) must be satisfied together with

(15)
$$S_{s_2}T_{t_2}S_{s_1}T_{t_1}(0) = V_0(0) = 2$$
.

Now (12) implies that $s_0 = 0$, i.e., $s_1 = -s_2$ and with this substitution (15) becomes

(16)
$$\frac{e^{s_2}+1}{e^{s_2}-1}=e^{it_2}$$

which has no solution.

To prove that in case ε is elliptic, and η hyperbolic the order of generation of A is 5 it suffices to represent $V(z) = \alpha z + \beta$ as a product $T_{t_3}S_{s_2}T_{t_2}S_{s_1}T_{t_1}(z)$ of length 5. This is possible if and only if there exist real numbers t_1, t_2, t_3, s_1 and s_2 such that the equations

(17)
$$it_0 + s_0 = \log \alpha, t_0 = t_1 + t_2 + t_3, s_0 = s_1 + s_2$$

(18)
$$e^{it_3}(e^{s_2}e^{it_2}(1-e^{s_1})+1-e^{s_2})=\beta$$

can be simultaneously satisfied. Clearly it suffices to prove the existence of real numbers t_2 , s_1 and s_2 such that

(19)
$$s_1 + s_2 = \operatorname{Re} \log \alpha = \ln |\alpha|$$

(20)
$$e^{s_2}e^{it_2}(1-e^{s_1})+1-e^{s_2}=-|\beta|$$

both hold, since if equation (20) holds t_3 can be chosen so that equation (18) holds and t_1 can then be chosen so that equation (17) holds. In view of equation (19) equation (20) becomes

(21)
$$e^{it_2}(e^{s_2} - |\alpha|) = e^{s_2} - 1 - |\beta|.$$

If $|\alpha| = 1 + |\beta|$, choose $t_2 = 0$; otherwise a simple application of the intermediate value theorem shows that for some real s the function

(22)
$$F(s) = \frac{e^s - 1 - |\beta|}{e^s - |\alpha|}$$

assumes the value -1.

V. Let $n \neq \infty$ be the order of generation of a connected Lie group H by T_i and S_s . It is of interest to determine whether every element of H can, in fact, be represented as a product of length n whose last element is a T_i ; a dual quention may be asked of S_s (both questions are trivial in the commutative case). Note that any element that can be expressed as a product of length < n can be expressed both as a product of length n whose last element is an S_s by inserting the identity $I = T_0 = S_0$ an appropriate number of times.

If there is an inner automorphism of the group (or even if there is any automorphism of the group) that interchanges T_t and S_s , then both questions must have the same answer. The same conclusion holds under the quite different assumption that n is even; if an element is

346

not representable as a product of length n ending in a T_i , then its inverse is not representable as a product of length n ending in an S_i .

THEOREM 3. If both infinitesimal transformations are loxodromic, then every element of the group $w = e^{(1+bi)t}z + \beta$ ($b \neq 0$) has both a representation at as product of length 3 ending in a T_t and one of length 3 ending in an S_s . If ε is loxodromic, η parabolic, then every element of the group has a representation as a product of length 3 ending in a T_t but there are elements of the group that cannot be represented as a product of length 3 ending in an S_s .

Proof. In both cases the existence of a product of length 3 ending in a T_t was shown in the proof of Theorem 1. If both infinitesimal transformations are loxodromic, then there is an automorphism of the group that interchanges T_t and S_s . If ε is loxodromic, η parabolic (assume $\eta = 1$) then the translations $w = z + \beta$, Im $\beta \neq 0$, cannot be represented as a product $S_{s_2}T_{t_1}S_{s_1}(z)$ since this would imply that $T_{t_1}, t_1 \neq$ 0, were also a translation.

THEOREM 4. If one infinitesimal transformation is hyperbolic and the other parabolic, then every real affine transformation has both a representation as a product of length 2 ending in a T_t and one of length 2 ending in an S_s . If both $\varepsilon = w$ and $\eta = w - 1$ are hyperbolic, then all real affine transformations w = az + b with $a + b \leq 0$ cannot be expressed as a product of length 2 ending in a T_t and those with $b \geq 1$ cannot be expressed as a product of length 2 ending in an S_s .

Proof. See the proof of Theorem 1.

THEOREM 5. If at least one infinitesimal transformation is loxodromic, then every affine transformation has both a representation as a product of length 4 ending in a T_t and one of length 4 ending in an S_s . If $\varepsilon = iw$ is elliptic, $\eta = w - 1$ is hyperbolic, then every element of the affine group can be represented as a product of length 5 ending in a T_t but none of the transformations w = -az + b, a > 0, $b - a \ge 1$ can be represented as a product of length 5 ending in an S_s .

Proof. Assume at least one infinitesimal transformation is loxodromic. That every affine transformation can be represented as a product of length 4 ending in a T_t was, in fact, established in the proof of Theorem 2; since the order of generation is even, the dual result for S_s follows.

Assume $\varepsilon = iw$, $\eta = w - 1$. The assertion concerning products ending in a T_i again was established in the proof of Theorem 2. Next observe

FRANKLIN LOWENTAL

that a simple modification of the argument used in Theorem 2 to show that $V_0(z) = -z + 2$ was not representable as a product $T_{t_2}S_{s_2}T_{t_1}S_{s_1}(z)$ shows that all transformations V(z) = -az + b, a > 0 $b - a \ge 1$ (and hence $V(1) \ge 1$) are not so representable. If V(z) = -az + b were equal to $S_{s_3}T_{t_2}S_{s_2}T_{t_1}S_{s_1}(z)$, then it would follow that

(23)
$$S_{s_3}^{-1}V(z) = T_{t_2}S_{s_2}T_{t_1}S_{s_1}(z) .$$

But one may directly verify that $S_{s_3}^{-1}V(z) = -cz + d, c > 0, d - c \ge 1$ (note that the ray x > 1 as well as $\{1\}$ are both orbits under η).

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Received September 30, 1970.

UNIVERSITY OF OREGON

PACIFIC JOURNAL OF MATHEMATICS

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Subscriptions, orders for back numbers, and changes of address should be sent to Pacific Journal of Mathematics, 103 Highland Boulevard, Berkeley, California, 94708.

PUBLISHED BY PACIFIC JOURNAL OF MATHEMATICS, A NON-PROFIT CORPORATION

Printed at Kokusai Bunken Insatsusha (International Academic Printing Co., Ltd.), 270, 3chome Totsuka-cho, Shinjuku-ku, Tokyo 160, Japan.

Pacific Journal of Mathematics Vol. 40, No. 2 October, 1972

Louis I. Alpert and L. V. Toralballa, An elementary definition of surface area in E^{n+1} for smooth surfaces	261
Eamon Boyd Barrett, A three point condition for surfaces of constant mean	
<i>curvature</i>	269
Jan-Erik Björk, On the spectral radius formula in Banach algebras	279
Peter Botta, Matrix inequalities and kernels of linear transformations	285
Bennett Eisenberg, Baxter's theorem and Varberg's conjecture	291
Heinrich W. Guggenheimer, Approximation of curves	301
A. Hedayat, An algebraic property of the totally symmetric loops associated	
with Kirkman-Steiner triple systems	305
Richard Howard Herman and Michael Charles Reed, Covariant	
representations of infinite tensor product algebras	311
Domingo Antonio Herrero, Analytic continuation of inner	
function-operators	327
Franklin Lowenthal, Uniform finite generation of the affine group	341
Stephen H. McCleary, 0-primitive ordered permutation groups	349
Malcolm Jay Sherman, Disjoint maximal invariant subspaces	373
Mitsuru Nakai, Radon-Nikodým densities and Jacobians	375
Mitsuru Nakai, <i>Royden algebras and quasi-isometries of Riemannian</i> manifolds	397
Russell Daniel Rupp, Jr., A new type of variational theory sufficiency	
theorem	415
Helga Schirmer, Fixed point and coincidence sets of biconnected	
multifunctions on trees	445
Murray Silver, On extremal figures admissible relative to rectangular	4.5.1
lattices	451
James DeWitt Stein, The open mapping theorem for spaces with unique	450
Armo Stroy, Annuovingtion and intermolation	439
Arne Stray, Approximation and interpolation	405
applications	477
Florian Vasilescu, On the operator $M(Y) = TYS^{-1}$ in locally convex algebras	489
Philip William Walker, Asymptotics for a class of weighted eigenvalue problems	501
Kenneth S. Williams, <i>Exponential sums over</i> $GF(2^n)$	511