LOCAL EVOLUTION SYSTEMS IN GENERAL
BANACH SPACES

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A local evolution system \( \{U(t, s)\} \) is defined and constructed from a family of nonlinear, multi-valued operators \( \{\Lambda(t)\} \) with common domain \( D \), in a real Banach space \( X \). In particular, it is shown that there is a family of operators \( \{U(t, s)\} \) with domains \( \{D(t, s)\} \) satisfying:

\[
U(t, s): D(t, s) \to \bar{D},
\]

\[
D \subset \bigcup_{s<t} D(t, s) \text{ for each } s,
\]

\[
D(t, r) \subset D(s, r) \text{ for } r \leq s \leq t,
\]

\[
U(t, t)x = x \text{ for } x \in D(t, t) \supset D, \text{ and}
\]

\[
U(s, r)D(t, r) \subset D(t, s) \text{ and } U(t, s)U(s, r) \supset U(t, r).
\]

The existence of \( \{U(t, s)\} \) is established by showing that \( \lim \prod_t (I - \Delta t \Lambda(t))^{-1}x \) exists for \( x \in D \), where \( \text{"lim"} \) denotes the refinement limit. When this limit exists it is called the product integral, and \( U(t, s)x \) is defined to be this product integral.

The time dependent evolution equation

\[
u'(t) \in A(t)u(t), \quad u(s) = x,
\]

is also studied, and it is shown that when \( X^* \) is uniformly convex, a strong solution exists on \([s, T]\). Finally, the notion of a solution of

\[
u'(t) \in A(t)u(t), \quad u(0) = x,
\]

with respect to \( \{D_n\} \) is defined, where \( \{D_n\} \) is a non-decreasing sequence of sets whose union is \( D \). Such solutions are shown to be unique, and an existence theorem is proved in the case when \( X^* \) is uniformly convex.

1. Local evolution systems. If \( A \) assigns to each \( x \in X \), a subset \( A_x \) of \( X \) then \( A \) will be called a \textit{multi-valued} operator in \( X \). The domain of \( A \), \( D(A) \), is the set \( \{x \in X: A_x \neq \emptyset\} \). The range of \( A \), \( R(A) \), is the set \( \cup \{A_x: x \in D(A)\} \).
The usual operations on operators are defined for multi-valued operators in a straightforward manner, see, e.g., [4].

A multi-valued operator \( A \) in \( X \) is said to be \( \omega \)-dissipative if \( \omega \) is a non-negative real number and

\[
\|(x_1 - \lambda y_1) - (x_2 - \lambda y_2)\| \geq (1 - \lambda \omega) \|x_1 - x_2\|
\]

whenever \( x_1, x_2 \in D(A), y_1 \in Ax_1, y_2 \in Ax_2 \) and \( \lambda > 0 \).

Multi-valued, \( \omega \)-dissipative operators are studied by numerous authors. See, for example, [5], [7], [19], [16], [14], [18], and [20].

**Proposition 1.1.** Suppose \( A \) is a multi-valued, \( \omega \)-dissipative operator and \( 0 < \lambda \omega < 1 \), then

(1) \( (I - \lambda A)^{-1} \) is a function, and

\[
\|(I - \lambda A)^{-1} x - (I - \lambda A)^{-1} y\| \leq (1 - \lambda \omega)^{-1} \|x - y\|
\]

for \( x, y \in R(I - \lambda A) \).

(2) \( \|(I - \lambda A)^{-1} x - x\| \leq \lambda (1 - \lambda \omega)^{-1} |Ax| \)

for \( x \in R(I - \lambda A) \cap D(A) \), where \( |Ax| = \inf_{y \in Ax} \|y\| \).

(3) \( (I - \lambda A)^{-1} x - x \in \lambda A (I - \lambda A)^{-1} x \)

for \( x \in R(I - \lambda A) \).

(4) If \( \lambda > 0 \) and \( \mu \) is a real number, then

\[
\frac{\mu}{\lambda} x + \frac{\lambda - \mu}{\lambda} (I - \lambda A)^{-1} x \in R(I - \mu A),
\]

and

\[
(I - \lambda A)^{-1} x = (I - \mu A)^{-1} \left( \frac{\mu}{\lambda} x + \frac{\lambda - \mu}{\lambda} (I - \lambda A)^{-1} x \right)
\]

for \( x \in R(I - \lambda A) \).

**Proof.** See Crandall and Liggett [4].

Whenever working with a composition of functions the following conventions are used.
Let $F$ be a mapping from $[a, b] \times [0, \lambda_0]$ into the set of mappings on $X$ and let $x \in X$. For each partition $R = \{r_i\}_{i=0}^n$ of $[a, b]$ with $\max_{1 \leq i \leq n} \Delta r_i < \lambda_0$, let the product $\prod_{i=1}^n F(r_i, \Delta r_i)x$ be denoted by $\prod_i F(R)x$. If there is a partition $P_0$ of $[a, b]$ so that $\|\prod_i F(P)x - w\| < \varepsilon$ whenever $P$ is a refinement of $P_0$, then one writes $\prod_i F(I, dI)x = w$, and $w$ is called the product integral of $F$ from $a$ to $b$ with respect to $x$. Some theorems about product integrals are found in [9], [23], [24], and [22]. Throughout the paper $\{A(t): 0 \leq t \leq T\}$ will denote a family of multi-valued operators with common domain $D$.

$\{A(t)\}$ is said to satisfy Condition $\mathcal{K}$ if there is a non-decreasing function $L: [0, \infty) \rightarrow [0, \infty)$ such that

$$|A(t)x| \leq |A(s)x| + |t - s| L(\|x\|)(1 + |A(s)x|)$$

for $x \in D$ and $0 \leq s, t \leq T$. Families of multi-valued operators which satisfy Condition $\mathcal{K}$ are studied in [4], [5], [13], and [10].

$\{A(t)\}$ is said to satisfy Condition $\mathcal{C}$ if there is a non-decreasing function $L: [0, \infty) \rightarrow [0, \infty)$ and $\lambda_0 > 0$ such that

$$\|(I - \lambda A(t))^{-1}x - (I - \lambda A(s))^{-1}x\| \leq \lambda |t - s| L(\|x\|)(1 + |A(s)x|)$$

whenever $0 \leq s, t \leq T$, $0 \leq \lambda < \lambda_0$, and $x \in D$. Families of operators which satisfy Condition $\mathcal{C}$ are studied in [4], [5], and [10].

Let $\Lambda_x(A(t)) = \Lambda_x$ be defined by

$$\Lambda_x = \{(\tau, r): r > 0 \text{ and } B(x, r) \cap D \subset R(I - \lambda A(t)) \text{ for each } t \in [0, T] \text{ and } 0 < \lambda < \tau\}.$$
In [7] Dorroh gives the definition of a local transformation semigroup. The above definition may be viewed as a generalization of that definition. Also, in a manner analogous to that in [7], one can show that a natural way for local evolution systems to arise is from solutions of time dependent nonlinear evolution equations.

**Theorem 1.2.** Let \( \{A(t): 0 \leq t \leq T\} \) be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \), which satisfies Conditions \( \mathcal{D}, \mathcal{K}, \) and \( \mathcal{E} \). Let \( x \in D, (\lambda, r) \in \Lambda_x \), and \( 0 \leq s \leq t \leq T \). Then there exists a positive real number \( b = b(s, x, r) \) such that if \( 0 < t - s < b \), then \( \Pi^s J(I, dI)x \) exists, where \( J(t, \lambda) = (I - \lambda A(t))^{-1} \).

The proof of this theorem will be given after the proof of Theorem 1.3.

**Theorem 1.3.** Let \( \{A(t): 0 \leq t \leq T\} \) be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \), which satisfies Conditions \( \mathcal{D}, \mathcal{K}, \) and \( \mathcal{E} \). Let \( E(t, s) \) denote the set of all vectors \( x \) belonging to \( D \) for which \( \Pi^s J(I, dI)x \) exists for \( s \leq t' \leq t \). Then

\[
\| \Pi^s J(I, dI)x - \Pi^s J(I, dI)y \| \leq \exp(\omega(t - s))\|x - y\|
\]

for \( x, y \in E(t, s) \), and if we define \( U(t, s): \overline{E(t, s)} \rightarrow \overline{D} \) by

\[
U(t, s)x = \begin{cases} 
\Pi^s J(I, dI)x, & x \in E(t, s) \\
\lim_{n \to \infty} \Pi^s J(I, dI)x_n, & x_n \in E(t, s), \ x_n \to x \in \overline{E(t, s)},
\end{cases}
\]

then \( \{U(t, s)\} \) is a local evolution system on \( D \) with \( D(t, s) = \overline{E(t, s)} \).

**Proof.** First note that for \( x, y \in E(t, s) \) there exists a partition \( P \) of \([s, t]\) such that if \( 0 < \|P\| \omega < 1 \), and \( P' = \{r_1, r_2, \cdots, r_n\} \) is a refinement of \( P \), then

\[
\| \Pi^s J(P')x - \Pi^s J(P')y \| \leq \prod_{i=1}^{n} \frac{1}{1 - \mu_i \omega} \|x - y\|
\]

where \( \mu_i = r_i - r_{i-1} \). Therefore, for \( x, y \in E(t, s) \)

\[
\| \Pi^s J(I, dI)x - \Pi^s J(I, dI)y \| \leq \exp(\omega(t - s))\|x - y\|
\]

and the first statement of the theorem is proved.
Now let \( D(t,s) = \overline{E(t,s)} \) and check the four properties of a local evolution system.

**Proof of (i).** Let \( s \in [0, T) \) and \( x \in D \). Choose \( t - s < b(s, x, r) \) (see Theorem 1.2) for some \( r > 0 \). By Theorem 1.2 it follows that \( x \in E(t,s) \), and hence \( D \subseteq \bigcup_{s < t} D(t,s) \).

**Proof of (iv).** One proves that \( U(s,r)E(t,r) \subseteq \overline{E(t,s)} \). Then by definition of \( U(s,r) \) the result will follow for \( \overline{E(t,r)} \). Let \( x \in E(t,r) \) and \( t' \in [s,t] \). Choose a sequence \( \{ R_n \} \) of partitions of \([r, t']\) such that \( s \in R_n \), and so that if \( P_n = R_n[[s,t]] \), then any refinement \( R'_n \) of \( R_n \) and any refinement \( P'_n \) of \( P_n \) have the property that

\[
\| \pi'_n J(R'_n)x - U(t,r)x \| < \frac{1}{n},
\]

and

\[
\| \pi'_n J(P'_n)x - U(s,r)x \| < \frac{1}{n}.
\]

Let \( P'_n \) be a refinement of \( P_n \) and \( y_n = \pi'_n J(P'_n)x \). One shows that \( y_n \in E(t,s) \) for large \( n \), and noting that \( y_n \to U(s,r)x \), it will follow that \( U(s,r)x \in \overline{E(t,s)} \). Let \( \epsilon > 0 \) be given, and choose \( n \) large enough so that \( 2/n < \epsilon \). Let \( Q_n = R_n[[s,t]] \). Suppose that \( Q'_n \) is a refinement of \( Q_n \), then \( \pi'_n J(Q'_n \cup P'_n)x \) is defined since \( Q'_n \cup P'_n \) is a refinement of \( R_n \). However,

\[
\pi'_n J(Q'_n \cup P'_n)x = \pi'_n J(Q'_n)\pi'_n J(P'_n)x
= \pi'_n J(Q'_n)y_n.
\]

Thus \( \pi'_n J(Q'_n)y_n \) is defined for each refinement \( Q'_n \) of \( Q_n \). Next, let \( Q'_n \) and \( Q''_n \) be refinements of \( Q_n \), then

\[
\| \pi'_n J(Q'_n)y_n - \pi'_n J(Q''_n)y_n \|
\leq \| \pi'_n J(Q'_n \cup P'_n)x - U(t,r)x \| + \| U(t,r)x - \pi'_n J(Q''_n \cup P'_n)x \|
\leq \frac{1}{n} + \frac{1}{n}
\leq \epsilon,
\]

because \( Q'_n \cup P'_n \) and \( Q''_n \cup P'_n \) are refinements of \( R_n \). Hence, by definition of \( E(t,s) \), \( y_n \in E(t,s) \), and thus it follows that \( U(s,r)x \in \overline{E(t,s)} \).

Now one proves that \( U(t,s)U(s,r)x = U(t,r)x \) for \( x \in E(t,r) \). Let \( y_n, R_n, P_n, \) and \( Q_n \) be as above. Then by definition of \( U(t,s) \),
Let \( \beta > 0 \) be given. Choose \( n \) large enough so that \( 1/n < \epsilon/2 \). Choose \( Q'_n \), a partition of \([s, t]\), so that \( \| \Pi_i J(Q'_n) y_n - U(t, s) y_n \| < \epsilon/2 \). Now for each such \( n \),

\[
\| U(t, s) y_n - U(t, r) x \| < \| U(t, s) y_n - \Pi_i J(Q'_n) y_n \|
\]

\[
+ \| \Pi_i J(Q''_n \cup P'_n) x - U(t, r) x \|
\]

\[
< \epsilon
\]

where \( Q''_n = Q'_n \cup Q_n \). This is the desired result.

In order to prove Theorem 1.2, the following four lemmas are needed. In these lemmas the notation given below is used.

(a) \( M(x) = \sup_{0 \leq t \leq T} | A(t)x | \) for \( x \in D \),
(b) \( J(t, \lambda) = (I - \lambda A(t))^{-1} \),
(c) \( \sigma(\mu, n) = \sum_{i=1}^n \mu_i \) for any sequence \( \{\mu_i\} \) of real numbers,
(d) \( u(a, \lambda, k) = \Pi_{i=1}^k J(a + \sigma(\lambda, i), \lambda, i) \) if \( \sigma(\lambda, k) < T \).

**Lemma 1.4.** Let \( \{A(t) : 0 \leq t \leq T\} \) be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \), satisfying Conditions \( \mathcal{D} \) and \( \mathcal{K} \). Let \( x \in D \), \( s \in [0, T) \), \( (\lambda_0, r) \in \Lambda xx \), \( b = b(s, x, r) = \min\{T - s, r[\exp(2\omega(T - s))M(x)]^{-1}\} \), \( \{r_i\}_{i=0}^n \) be a partition of \([s, s + b]\), and let \( \mu_i = r_i - r_{i-1} \) for \( i = 1, 2, \ldots, n \). Suppose that \( 0 < \mu_i < \lambda_0 \) and that \( 0 < \mu_i \omega < \frac{1}{2} \) for \( i = 1, 2, \ldots, n \). If \( \sigma(\mu, k) < b \) for \( k = 1, 2, \ldots, n \) then \( u(s, \mu, k)x \) is defined, \( u(s, \mu, k)x \in B(x, r) \cap D \), and \( \| u(s, \mu, k)x - x \| < \sigma(\mu, k)M(x) \).

**Lemma 1.5.** Let the hypotheses of Lemma 1.4 be satisfied. If \( \sigma(\mu, k) < b \) for \( k = 1, 2, \ldots, n \), then

\[
| A(r_k)u(s, \mu, k)x | \leq \exp(2\omega \sigma(\mu, k))M_k,
\]

where

\[
M_k = M(x) \prod_{i=1}^k (1 + \mu_i L) + \sum_{i=1}^k \mu_i L \prod_{i=i+1}^k (1 + \mu_i L),
\]

and \( L = \mathcal{L}(r + \| x \|) \). Furthermore, there is a constant \( R = R(s, x, r) \) so that if \( \sigma(\mu, k) < b \), then

\[
| A(r_k)u(s, \mu, k)x | \leq R \quad \text{for} \quad k = 1, 2, \ldots, n.
\]

The proofs of Lemma 1.4 and Lemma 1.5 follow by induction on \( k \), using the Proposition 1.1. See also \([1]\).
As an aid in stating the following lemmas, the following notation is introduced.

Let \( \{a_k\}, \{b_k\} \) be sequences of nonnegative integers. For \( r \leq s \) and \( 0 \leq t \leq s - r + 1 \) let

\[
A(r, s, t) = \{(x_1, x_{r+1}, \cdots, x_r) \in R^{s-r+1} : \text{exactly } t \text{ of the components are 1 and the remaining components are 0}\}.
\]

Let \( f: A(r, s, t) \to R \) be given by

\[
f(x_1, x_{r+1}, \cdots, x_r) = \prod_{i=1}^s \eta_i \quad \text{where} \quad \begin{cases} 
\eta_i = a_i & \text{if } x_i = 1 \\
\eta_i = b_i & \text{if } x_i = 0.
\end{cases}
\]

Finally, define

\[
[a, b]_t = \sum_{y \in A(r,s,t)} f(y).
\]

For notational convenience if \( s < r \) and \( t \geq 0 \) define

\[
[a, b]_r = 1.
\]

**Lemma 1.6.** Let the hypotheses of Lemma 1.4 be satisfied. Let \( \mu_1, \mu_2, \cdots, \mu_n \leq \lambda \) and \( 0 < \lambda < \lambda_0 \). In addition, let \( a_k = \mu_k / \lambda, b_k = 1 - a_k, s_k = k\lambda, m\lambda = b \), for \( k = 1, 2, \cdots, n \), and

\[
d_{m,n} = \left\| \prod_{k=1}^n J(r_k, \mu_k)x - \prod_{k=1}^m J(s_k, \lambda)x \right\|.
\]

Then

(i) \( d_{k,j} \leq \exp(2\omega\mu_j)\{a, d_{k-1,j-1} + b, d_{k,j-1} + e_{k,j}\} \),

and

(ii) \( d_{m,n} \leq \exp(2\omega\sigma(\mu, n))\left\{ \sum_{j=0}^m [a, b]_{m-j, 0} \ight\}

\[
+ \sum_{j=m}^n a_{n-j+1} \sum_{n-j+2}^n [a, b]_{m-1, n-j} d_{0, n-j} \
+ \sum_{k=0}^{m-1} \sum_{i=1}^{n-k} [a, b] \sum_{k+i+1}^n e_{m-k,i} \right\}.
\]
for \( 1 \leq m \leq n \), where

\[
e_{k,j} = \left\| J(s_k, \mu_j) \prod_{i=1}^{j-1} J(r_i, \mu_i) \prod_{i=1}^{j-1} J(r_i, \mu_i)x - J(r_j, \mu_j) \prod_{i=1}^{j-1} J(r_i, \mu_i)x \right\|.
\]

**Proof of (i).** See Crandall and Pazy [1].

The proof of (ii) involves a rather lengthy induction argument and can be found in the appendix to the author’s dissertation.

**Lemma 1.7.** Let the hypotheses of Lemma 1.6 and Condition $\mathcal{C}$ be satisfied. If $\sigma(a, n) = m$, then

(i) \[
\sum_{j=0}^{m} [a, b]_j (m - j) = \sum_{j=m}^{n} \sum_{k=1}^{n-j+1} a_k a_{n-j+1} [a, b]_{m-1},
\]

(ii) \[
\sum_{j=0}^{m} (m - j) [a, b]_j \leq \sqrt{m},
\]

(iii) \[
\sum_{k=0}^{m-1} \sum_{r=0}^{n-k} a_i [a, b]_{r} \left| (m - k) - \sigma(a, i) \right| \leq m \sqrt{m}, \quad \text{and}
\]

(iv) \[
d_{m,n} \leq \exp(2\omega m \lambda)\{2\lambda \sqrt{m} + \lambda^2 m \sqrt{m}\}C \text{ for some constant } C.
\]

**Proof.** The proof of the (i) involves another lengthy induction argument and is given in the author’s dissertation. The proof of (ii) is similar to the proof of (iii) and is easier, so only the proof of (iii) is given

**Proof of (iii).**

\[
\sum_{k=0}^{m-1} \sum_{r=0}^{n-k} a_i [a, b]_{r} \left| (m - k) - \sigma(a, i) \right|
\]

\[
= \sum_{i=1}^{n} \sum_{k=0}^{m} a_i [a, b]_{k} \left| (m - k) - \sigma(a, i) \right|
\]

\[
+ \sum_{i=n-m+1}^{n-1} \sum_{k=0}^{m-1} a_i [a, b]_{k} \left| (m - k) - \sigma(a, i) \right|
\]

\[
\leq \sum_{i=1}^{n} a_i \sum_{k=0}^{n-i} [a, b]_{k} \left| k - (a_{i+1} + \cdots + a_n) \right|.
\]
However,
\[ \sum_{k=0}^{n-i} \sum_{i+1}^{n} [a, b]_k |k - (a_{i+1} + \cdots + a_n)| \]
\begin{align*}
&= \left\{ \sum_{k=0}^{n-i} \sum_{i+1}^{n} [a, b]_k \right\}^{1/2} \left\{ \sum_{k=0}^{n-i} \sum_{i+1}^{n} [a, b]_k (k - (a_{i+1} + \cdots + a_n))^2 \right\}^{1/2} \\
&= \sum_{k=0}^{n-i} \sum_{i+1}^{n} k^2 [a, b]_k - 2(a_{i+1} + \cdots + a_n) \sum_{k=0}^{n-i} \sum_{i+1}^{n} [a, b]_k \\
&\quad + (a_{i+1} + \cdots + a_n)^2 \sum_{k=0}^{n-i} \sum_{i+1}^{n} [a, b]_k \right\}^{1/2} \\
&= \left\{ \left( \sum_{k=0}^{n} a_k \right)^2 - \sum_{k=0}^{n} a_k^2 + \sum_{k=0}^{n} a_k \\
&\quad - 2(a_{i+1} + \cdots + a_n) \sum_{k=0}^{n} a_k + \left( \sum_{k=0}^{n} a_k \right)^2 \right\}^{1/2} \\
&= \left\{ \sum_{k=0}^{n} a_k - \sum_{k=0}^{n} a_k^2 \right\}^{1/2} \\
&\leq \left\{ \sum_{k=0}^{n} a_k \right\}^{1/2} \\
&\leq \sqrt{m}.
\end{align*}

Therefore,
\[ \sum_{k=0}^{n} a_i [a, b]_k |(m - k) - \sigma(a, i)| \]
\[ \leq \sum_{i=0}^{n} a_i \sqrt{m} \]
\[ = m \sqrt{m}. \]

This completes the proof of (iii).

**Proof of (iv).** Using Lemma 1.4, Lemma 1.5, Lemma 1.6 and Condition $\mathcal{C}$ one can show that there are constants $c_1 = c_1(x)$ and $c_2 = c_2(s, x, r)$ so that
\[ d_{m,n} \leq \exp(2\omega \sigma(\mu, n)) \left\{ \lambda \sum_{j=0}^{m} [a, b]_j (m - j)c_1 \\
+ \lambda \sum_{j=m}^{n} \sum_{k=1}^{n-j} a_k a_{n-j+1} \sum_{n-j+2}^{n} [a, b]_{m-1} c_1 \\
+ \lambda^2 \sum_{k=0}^{n-1} \sum_{i+1}^{n-k} a_i [a, b]_k |(m - k) - \sigma(a, i)| c_2 \right\} \]
for $1 \leq m \leq n$. 


Letting $C = \max(c_1, c_2)$ it follows from (i), (ii) and (iii) that

$$d_{m,n} \leq \exp(2\omega m\lambda) \left\{ 2\lambda \sum_{j=0}^{m} [a, b]_1 (m-j) + \lambda^2 \sum_{k=0}^{m-1} \sum_{i=1}^{n-k} a_i \left[ a, b \right]_k (m-k) - \sigma(a, i) \right\} C$$

$$\leq \exp(2\omega m\lambda) \{ 2\lambda \sqrt{m} + \lambda^2 m \sqrt{m} \} C.$$

This completes the proof of Lemma 1.7.
Now for the proof of Theorem 1.2.

**Proof of Theorem 1.2.** Let $\epsilon < 0$ be given. Let

$$P_m = \left\{ s + i \left( \frac{t-s}{m} \right) \right\}^{m}_{i=0}, \quad m = 1, 2, \cdots.$$

Choose $m_0$ large enough so that

$$\exp(2\omega(t-s))(2(t-s) + (t-s)^2) \frac{C}{\sqrt{m_0}} < \frac{\epsilon}{2},$$

where $C$ is chosen as in Lemma 1.7. Let $P' = \{ r'^n \}_{i=0}^n$ and $P'' = \{ r''^k \}_{i=0}^k$ be refinements of $P_{m_0}$ satisfying Lemma 1.4. Then,

$$\| \Pi_i'(P')x - \Pi_i'(P'')x \|$$

$$\leq \| \Pi_i'(P')x - \Pi_i'(P_{m_0})x \| + \| \Pi_i'(P_{m_0})x - \Pi_i'(P'')x \|$$

$$= d_{m_0,n} + d_{m_0,k}$$

$$\leq 2 \exp \left( 2\omega m_0 \left( \frac{t-s}{m_0} \right) \left\{ 2 \frac{t-s}{m_0} \sqrt{m_0} + \frac{(t-s)^2}{m_0^2} \right\} m_0 \sqrt{m_0} \right) C$$

$$\leq \epsilon.$$

Thus $\Pi_i'(J(I, dI)x)$ exists, and Theorem 1.2 is proved.

**Remark.** Notice that if $\bar{D} \subset R(I - \lambda A(t))$, for $t \in [0, T]$ and $0 < \lambda < \lambda_0$, then choosing $r = \infty$ and $b(s, x, r) = T - s$, the condition $0 \leq t - s < b(s, x, r)$ becomes $s \leq t \leq T$. Hence Theorem 1.2 implies Theorem 2.1 of Crandall and Pazy [6].

After obtaining these results, it was discovered that A. T. Plant [22] had proven the existence of a slightly more general type of product integral. He uses a stronger substitute for Condition $\mathcal{D}$ and his results
only apply when there is a global evolution system. This proof is very similar to Plant's except that he uses probabilistic methods instead of mathematical induction.

2. Time dependent evolution equations. The results found in this section are similar to those of Crandall and Pazy [6] and Brezis and Pazy [1].

Let \{A(t): 0 \leq t \leq T\} be a family of multi-valued operators with common domain \(D\). Let \(x \in D\) and \(s \in [0, T)\).

A function \(u: [s, T] \to X\) is said to be a strong solution of

\[
u'(t) \in A(t)u(t), \quad u(s) = x
\]

if \(u\) satisfies the following conditions:

(i) \(u\) is Lipschitz continuous;
(ii) \(u'(t)\) exists a.e. on \((s, T)\); and
(iii) \(u(t) \in D\) a.e. on \((s, T)\), \(u(s) = x\), and \(u'(t) \in A(t)u(t)\) a.e. on \((s, T)\).

**Theorem 2.1.** Let \{\(A(t): 0 \leq t \leq T\}\} be a family of \(\omega\)-dissipative, multi-valued operators with common domain \(D\), satisfying Conditions \(\mathcal{D}\), \(\mathcal{K}\), and \(\mathcal{C}\). Let \(x \in D\), \(s \in [0, T)\), and \((\lambda_0, r) \in \Lambda_x\). If the problem

\[
u'(t) \in A(t)u(t), \quad u(s) = x
\]

has a strong solution \(u\) on \([s, T]\), then

\[
U(t, s)x = u(t) \quad \text{on} \quad [s, s+b),
\]

where \(b\) is chosen as in Theorem 1.2.

**Proof.** The proof of this theorem follows from Theorem 1.2 using arguments like those found in [6].

Let \(X^*\) denote the dual space of \(X\). Let \(\langle x, f \rangle\) denote the value of \(f\) at \(x\), for \(x \in X\) and \(f \in X^*\). The duality mapping \(F\) is the mapping of \(X\) into \(X^*\) defined by

\[
F(x) = \{f \in X^* : \langle x, f \rangle = \|x\|^2 = \|f\|^2\}.
\]

The following three facts are well-known, see [13].

1. If \(X^*\) is uniformly convex then \(F\) is single-valued and uniformly continuous on bounded sets.

2. Let \(x, y \in X\). Then \(\|x\| \leq \|x + \alpha y\|\) for every \(\alpha > 0\) if and only if there is an \(f \in F(x)\) so that \(\langle y, f \rangle \geq 0\).
(3) Let \( u \) be an \( X \)-valued function on an interval of real numbers. Suppose \( u \) has a weak derivative \( u'(s) \in X \) at \( s \). If \( \| u(\cdot) \| \) is also differentiable at \( s \), then
\[
\| u(s) \| \frac{d}{ds} \| u(s) \| = \langle u'(s), f \rangle
\]
for every \( f \in F(u(s)) \).

Let \{\( A(t): 0 \leq t \leq T \)\} be a family of multi-valued operators with common domain \( D \). \{\( A(t) \)\} is said to satisfy Condition \( \mathcal{M} \) if whenever \( t_n \in (0, T) \) and \((x_n, y_n) \in A(t_n)\), \( n = 1, 2, 3, \ldots, \) and \( t_n \to t, \ x_n \to x, \ \) and \( y_n \to y, \) then \((x, y) \in A(t)\).

Multi-valued operators satisfying this type of condition are studied in [17].

The existence theorem which follows and its proof are generalizations of the work of Brezis and Pazy [1] to the time dependent case.

**Theorem 2.2.** Let \( X^* \) be uniformly convex. Let \{\( A(t): 0 \leq t \leq T \)\} be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \), satisfying Conditions \( \mathcal{D}, \mathcal{K}, \mathcal{E}, \) and \( \mathcal{M} \). Let \( x \in D \) and \( s \in [0, T) \), then there exists a unique strong solution to the initial value problem
\[
u(t) \in A(t)u(t), \ u(s) = x\]
on the interval \([s, T]\).

The three lemmas below and the following definition are needed in the proof of this theorem.

Let \{\( A(t): 0 \leq t \leq T \)\} be a family of multi-valued operators. \( A(t) \) is said to satisfy Condition \( \mathcal{R} \) if whenever \( t_n \in [0, T] \) and \((x_n, y_n) \in A(t_n)\), \( n = 1, 2, 3, \ldots \) and \( x_n \to x, \ y_n \to y, \ t_n \to t, \) then \((x, y) \in A(t)\).

**Lemma 2.3.** Let \( X^* \) be uniformly convex. Let \{\( A(t): 0 \leq t \leq T \)\} be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \), satisfying Conditions \( \mathcal{D}, \mathcal{K}, \mathcal{E}, \) and \( \mathcal{M} \). Let \( x \in D \), \((\lambda_0, r) \in \Lambda_{\alpha}, \ s \in [0, T) \) and \( b = b(s, x, r) \). If the sequence of functions \{\( u_n \)\} defined below converges pointwise to a function \( u \) on \([s, s + b]\), then \( u(t) \in D \) for \( t \in [s, s + b] \).

**Proof.** Define the sequences \( u_n: [s, s + b) \to X \),
\[
v_n: [s, s + b) \to X
\]
as follows:
Let \( \{\lambda_n\} = \{b/n\} \) and \( \{r_{i,n}\} = \{s + i\lambda_n\} \) for \( i = 0, 1, 2, \ldots, n \). Then
\[
\begin{align*}
u_n(t) &= u(s, \lambda, k-1)x \
& \quad \text{for } r_{k-1,n} \leq t < r_{k,n}, \ k = 1, 2, \ldots, n
\end{align*}
\]
and
\[
\begin{align*}u_n(t) &= u(s, \lambda, k-1)x + \frac{1}{\lambda_n}[u(s, \lambda, k)x - u(s, \lambda, k-1)x](t - r_{k,n})
\end{align*}
\]
for \( r_{k-1,n} \leq t < r_{k,n}, \ k = 1, 2, \ldots, n \).

Let \( t \in [s, s+b) \) and choose a sequence of nonnegative integers \( \{k_n\} \) so that \( t_n = s + k_n\lambda_n, \ t_n < t, \) and \( t - t_n < \lambda_n \). Letting \( x_n = J(t_n, \lambda_n)v_n(t_n) \), and \( y_n = \lambda_n^{-1}[J(t_n, \lambda_n)v_n(t_n) - v_n(t_n)] \), we obtain that \( y_n \in A(t_n)x_n \) and that \( \|y_n\| \leq (1 - \lambda_n\omega)^{-1}|A(t_n)v_n(t_n)| \). Thus, it follows from Lemma 1.5 that \( \{y_n\} \) is bounded. Because \( X^* \) is uniformly convex, \( y_n \to y \) for some subsequence \( \{y_{n_k}\} \) of \( \{y_n\} \) and some \( y \in X \). Using Lemma 1.5 and the fact that \( v_n(t) \to u(t) \) if and only if \( u_n(t) \to u(t) \), it is not hard to show that \( x_n \to u(t) \). Thus by Condition \( M \) \( (u(t), y) \in A(t) \), i.e., \( u(t) \in D \).

**Lemma 2.4.** Let \( X^* \) be uniformly convex. Let \( \{A(t): 0 \leq t \leq T\} \) be a family of \( \omega \)-dissipative, multi-valued operators with common domain \( D \) satisfying Condition \( R \). Let \( A(t)x \subset B(t)x \) for \( x \in D \), where \( \{B(t): 0 \leq t \leq T\} \) is also \( \omega \)-dissipative. Suppose that \( D(B(t)) = D_B \) for each \( t \in [0, T] \). Suppose that for each \( x \in D_B \), there is a ball \( B(x, r) \) and a number \( \lambda_0 > 0 \) such that
\[
B(x, r) \cap D_B \subset R(I - \lambda A(t))
\]
for \( 0 < \lambda < \lambda_0 \), and \( 0 \leq t \leq T \). Suppose that \( 0 \leq s < b' < T \), and that there is a function \( u: [s, b'] \to X \) satisfying: \( u(t) \in D_B \) for \( t \in [s, b'] \), \( u \) is differentiable a.e. on \( (s, b') \), and \( u'(t) \in B(t)u(t) \) a.e. on \( (s, b') \). Then \( u(t) \in D \) a.e. on \( (s, b') \), and \( u'(t) \in A(t)u(t) \) a.e. on \( (s, b') \).

**Proof.** Choose \( t \in (s, b') \) so that \( x \equiv u(t) \in D_B \), \( u \) is differentiable at \( t \), and \( u'(t) \in B(t)u(t) \). Let \( \lambda_0 \) and \( r \) be chosen such that
\[
B(x, r) \cap D_B \subset R(I - \lambda A(t))
\]
for \( 0 < \lambda < \lambda_0 \) and \( 0 \leq t \leq T \). Note that for \( t' \) close to \( t \), \( u(t') \in B(x, r) \), since \( u \) is continuous at \( t \). Choose an increasing sequence \( \{t_n\} \) so that \( t_n \to t \) and let \( \lambda_n = t - t_n \). Then
\[
u(t_n) \in B(x, r) \cap D_B \subset R(I - \lambda_n A(t_n))
\]
for large \( n \). So \((I - \lambda_n A(t_n))^{-1}u(t_n) \equiv x_n \in D \), and \( u(t_n) = x_n - \lambda_n y_n \) for
some \( y_n \in A(t_n)x_n \subset B(t_n)x_n \). Since \( u'(t) \in B(t)u(t) \) and \( B(t) \) is \( \omega \)-dissipative,

\[
\langle u'(t) - y_n, F(x - x_n) \rangle \leq \omega \| x - x_n \|^2.
\]

Now let

\[
\phi(s) = u'(t) - \frac{u(s) - u(t)}{s - t}.
\]

Then

\[
\phi(t_n) = u'(t) - \frac{u(t_n) - u(t)}{t_n - t} = u'(t) - \frac{x_n - \lambda_n y_n - x}{\lambda_n} = u'(t) - \frac{x - x_n}{\lambda_n} - y_n.
\]

Thus,

\[
\phi(t_n) + \frac{x - x_n}{\lambda_n} = u'(t) - y_n,
\]

and

\[
\left\langle \phi(t_n) + \frac{x - x_n}{\lambda_n}, F(x - x_n) \right\rangle \leq \omega \| x - x_n \|^2.
\]

So

\[
\langle \phi(t_n), F(x - x_n) \rangle \leq \frac{\lambda_n \omega - 1}{\lambda_n} \| x - x_n \|^2,
\]

or

\[
\frac{1 - \lambda_n \omega}{\lambda_n} \| x - x_n \|^2 \leq \langle \phi(t_n), -F(x - x_n) \rangle \leq \| \phi(t_n) \| \cdot \| x - x_n \|,
\]

or

\[
\| x - x_n \| \leq \frac{\lambda_n}{1 - \lambda_n \omega} \| \phi(t_n) \|.
\]

Therefore, \( x_n \to x \). Now

\[
\| u'(t) - y_n \| \leq 3 \| \phi(t_n) \|
\]

for large \( n \), so that \( y_n \to u'(t) \). Hence Condition \( \mathcal{R} \) shows that \( u'(t) \in A(t)u(t) \) and the proof is complete.
LEMMA 2.5. Let $X$ be a reflexive Banach space and let $\{v_n(t)\}$ be a sequence in $L^p(a, b; X)$, $p > 1$, such that $\{v_n(t)\}$ is bounded for almost all $t \in (a, b)$. Let $V(t)$ denote the set of weak cluster points of $\{v_n(t)\}$. If $v_n$ converges weakly to $u$ in $L^p(a, b; X)$ then $u(t)$ belongs to the closed convex hull of $V(t)$ a.e. on $(a, b)$.

Proof. See Kato [14].

Proof of Theorem 2.2. The proof of the uniqueness of solution is standard and will not be given here.

Define $B(t)$, an extension of $A(t)$ for $t \in [0, T]$, as follows:

$$D(B(t)) = D \quad \text{for} \quad 0 \leq t \leq T,$$

$$B(t)x = \text{closed convex hull of} \quad A(t)x.$$

$B(t)$ is $\omega$-dissipative for each $t \in [0, T]$. Let $0 < b' < b$, and $x \in D$. Then by Theorem 1.2, the sequence $\{u_n\}$ of functions defined in Lemma 2.1 converges uniformly to $U(t, s)x$ on $[s, b']$.

Let $u(t) = U(t, s)x$. Then by Lemma 2.3, $u(t) \in D$ for $t \in [s, b']$. Also, note that since $u$ is Lipschitz continuous and $X^*$ is uniformly convex, $u'(t)$ exists almost everywhere on $(s, s + b')$.

Let $\{v_n\}$ be the sequence of functions defined in Lemma 2.3. We show that $v_n \rightharpoonup u'$ in $L^p(s, s + b'; X)$ for $1 < p < \infty$. Since $u_n$ converges uniformly to $u$, it follows that $v_n$ also converges uniformly to $u$ on $[s, s + b']$. Thus

$$\int_s^{s + b'} v_n'(t)f(t)dt \to \int_s^{s + b'} u'(t)f(t)dt,$$

for $f \in C^0_0(s, s + b'; R)$ where $C^0_0(a, b; R)$ denotes the continuously differentiable real-valued functions which vanish outside of $(a, b)$. Note also that

$$\int_s^{s + b'} v_n'(t)f(t)dt \to \int_s^{s + b'} u'(t)f(t)dt$$

for $f \in C^0_0(s, s + b'; R)$, so that

$$g\left(\int_s^{s + b'} v_n'(t)f(t)dt\right) \to g\left(\int_s^{s + b'} u'(t)f(t)dt\right)$$

for $f \in C^0_0(s, s + b'; R)$ and $g \in X^*$. Since the Lipschitz norm of $v_n'$ is bounded, it follows that some subsequence $\{v'_{n_k}\}$ of $\{v_n'\}$ converges to some element $w$ belonging to $L^p$, for $1 < p < \infty$. Thus,
$$g \left( \int_s^{s+b'} v_n'(t) f(t) dt \right) \rightarrow g \left( \int_s^{s+b'} w f(t) dt \right)$$

for \( f \in C_0'(s, s+b'; R) \) and \( g \in X^* \), so it follows that \( w = w' \) and \( v_n' \rightarrow u' \) in \( L_p \).

Next observe that from Condition \( \mathcal{M} \) it follows that the set of weak cluster points of \( \{v_n'(t)\} \), denoted by \( V(t) \), is contained in \( A(t)u(t) \). Thus, from Lemma 2.5,

$$u'(t) \in V(t) \subset \text{closed convex hull of } A(t)u(t) = B(t)u(t).$$

Now since \( \{A(t): 0 \leq t \leq T\} \) and \( \{B(t): 0 \leq t \leq T\} \) satisfy the hypothesis of Lemma 2.4,

$$u'(t) \in A(t)u(t) \text{ a.e. on } (s, s+b').$$

Next, show that \( u \) is a solution on \([s, T]\). Let \( u \) be a solution on \([s, T_1]\), where \( T_1 \) is maximal. If \( T_1 \neq T \), choose \( t_n \rightarrow T \). Then \( u(t_n) \rightarrow u_0 \in X \), because \( u \) is Lipschitz continuous. Since \( \{A(t): 0 \leq t \leq T\} \) satisfies Condition \( \mathcal{M} \), \( u_0 \in D \). Hence consider the problem

$$u'(t) \in A(t)u(t), \quad u(T_1) = u_0.$$

It will have a solution \( v(t) \) on \([T_1, T_\omega]\). Letting

$$f(t) = \begin{cases} u(t) & \text{on } [s, T_1] \\ v(t) & \text{on } [T_1, T_\omega] \end{cases},$$

extend the original solution, contradicting the maximality of \( T_1 \).

This concludes the proof of Theorem 2.2.

3. A local abstract Cauchy problem. In [1], Brezis and Pazy show that if \( X^* \) is uniformly convex, and \( A \) is a dissipative, demi-closed operator which satisfies Condition \( I \), then the initial value problem

$$u'(t) \in Au(t), \quad u(0) = x$$

has a unique global solution. The techniques of Brezis and Pazy may also be used in solving a local abstract Cauchy problem of a similar nature. Attention is confined to multi-valued operators which satisfy the Condition \( \mathcal{S} \) below.
Let \( \{A(t) : 0 \leq t \leq T\} \) be a family of multi-valued operators with common domain \( D \). \( \{A(t)\} \) is said to satisfy Condition \( \mathcal{S} \) if there is a non-decreasing sequence of sets \( \{D_n\} \) so that \( D = \bigcup_{n=1}^{\infty} D_n \), and \( sA_n(t) = A(t)D_n \) is \( \omega_n \)-dissipative with \( 0 \leq \omega_1 \leq \omega_2 \leq \cdots \).

Multi-valued operators satisfying similar conditions are studied in [3].

In the pages which follow, the problem

\[
u'(t) \in A_n(t)u(t), \ u(0) = x \in D
\]

will be denoted by \( ACP_n \), and the problem

\[
u'(t) \in A(t)u(t), \ u(0) = x
\]

will be denoted by \( ACP \).

Now consider the problem of finding a solution of \( ACP \) with \( u(0) = x \in D_1 \), where \( \{A(t)\} \) satisfies Condition \( \mathcal{S} \). It is easy to show that if \( x \in D_1 \), and \( ACP_n \) has a solution on \([0, b_n)\) and \( b_n \to b \), then \( ACP \) has a solution on \([0, b)\). This is proved in Theorem 3.3. With only the Condition \( \mathcal{S} \), this solution does not have to be unique, as the following example illustrates.

Define \( A : R \times [0, 1] \setminus (0, 1) \times (0, 1) \to R \times R \), by

\[
A(x, y) = \begin{cases}
(0, 0), & -\infty < x \leq 0, \ 0 \leq y \leq 1 \\
(x, 0), & 0 \leq x \leq 1, \ y = 1 \\
(1, 0), & 1 \leq x < \infty, \ 0 \leq y \leq 1 \\
(\sqrt{x}, 0), & 0 \leq x \leq 1, \ y = 0.
\end{cases}
\]

Let \( D_n = D(A) \setminus (0, n^{-2}) \times \{0\} \). Then \( A(t) = A \) satisfies Condition \( \mathcal{S} \). In particular, each \( A_n \) is \( n \)-dissipative, closed, and satisfies Condition \( \mathcal{D} \). Thus it follows from Theorem 2.2 that \( ACP_n \) with \( x = (0, 0) \) has a unique solution. This solution is, of course, \( u_n(t) = (0, 0) \). However, \( ACP \) with \( x = (0, 0) \) has \( u(t) = (t^2/4, 0) \) for \( 0 \leq t \leq 2 \) as a solution, together with \( u(t) = (0, 0) \). We therefore make the following definition.

Let \( \{A(t) : 0 \leq t \leq T\} \) be a family of multi-valued operators with common domain \( D \), which satisfies Condition \( \mathcal{S} \), with \( D = \bigcup_{n=1}^{\infty} D_n \) \( u \) is said to be a solution of \( ACP \) with respect to \( \{D_n\} \) on \([0, b)\), if for each \( t_0 \in [0, b) \), \( u \) is a solution of \( ACP_n \) on \([0, t_0)\) for some \( n = n(t_0) \).

In the above example, \( u(t) = (t^2/4, 0) \) is not a solution of \( ACP \) with respect to \( \{D_n\} \), while \( u(t) = (0, 0) \) is such a solution.

**Theorem 3.1.** Let \( \{A(t) : 0 \leq t \leq T\} \) be a family of multi-valued operators with common domain \( D \). If \( \{A(t)\} \) satisfies Condition \( \mathcal{S} \) with
$D = \bigcup_{n=1}^{\infty} D_n$, then ACP with $x \in D$, has at most one solution with respect to \{D_n\} on the interval [0, b).

Proof. Suppose that $u$ and $v$ are solutions of ACP with respect to \{D_n\} on [0, b). Choose $t_0 \in [0, b)$. Then $u(t) \in D_n$ and $u'(t) \in A_n(t)u(t)$ for some $n$ and almost all $t \in [0, b)$. Also, $v(t) \in D_m$ and $v'(t) \in A_m(t)v(t)$ for some $m$ and almost all $t \in [0, b)$. Suppose that $m < n$. Then

$$\|u(t) - v(t)\| \frac{d}{dt} \|u(t) - v(t)\| = \langle u'(t) - v'(t), f(t) \rangle \leq \omega_n \|u(t) - v(t)\|^2$$

because

$$v'(t) \in A_m(t)v(t) \subset A_n(t)v(t),$$

and

$$f(t) \in F(u(t) - v(t)).$$

Hence, if $t \in [0, t_0)$ then

$$\|u(t) - v(t)\| \leq \omega_n \int_0^t \|u(s) - v(s)\| ds,$$

and it follows that $u(t) = v(t)$. Since $t_0$ was arbitrary, $u(t) = v(t)$ for all $t \in [0, b)$.

Remark. An interesting question whose answer is unknown to the author is: If $u$ is a solution of ACP with respect to \{D_n\} and $v$ is a solution of ACP with respect to \{E_n\}, where $D = \bigcup_{n=1}^{\infty} D_n = \bigcup_{n=1}^{\infty} E_n$, does $u = v$?

Theorem 3.2. Let \{A(t): 0 \leq t \leq T\} be a family of multi-valued operators with common domain $D$, which also satisfies Condition $\mathcal{F}$. If $u_n$ is a solution of ACP$_n$ on $[0, b_n)$, and if $0 < b_1 \leq b_2 \leq \cdots$, then $u_n = u_{n+1}[0, b_n)$.

Proof. The proof is straightforward and will not be given.

Theorem 3.3. Let \{A(t): 0 \leq t \leq T\} be a family of multi-valued operators with common domain $D$, which satisfies Condition $\mathcal{F}$. If $u_n$ is a solution of ACP$_n$ on $[0, b_n)$, with \{b_n\} increasing and $b_n \to b$, then
is a solution of ACP with respect to \{D_n\} on \([0, b)\).

The proof is omitted.

**Theorem 3.4.** Let \(X^*\) be uniformly convex. Let \(\{A(t): 0 \leq t \leq T\}\) be a family of multi-valued operators with common domain \(D\). Suppose that \(\{A(t)\}\) is \(\omega\)-dissipative and satisfies Conditions \(\mathcal{D}, \mathcal{K},\) and \(\mathcal{C}\). Let \(\tilde{A}(t)\) denote the smallest extension of \(A(t)\) for which \(\{\tilde{A}(t): 0 \leq t \leq T\}\) satisfies Condition \(\mathcal{M}\). Let \(\tilde{A}(t)x\) denote the closed convex hull of \(\tilde{A}(t)x\) for \(x \in D(\tilde{A}(t))\). Then there is a number \(b > 0\) and a unique function \(u: [0, b) \to X\) such that \(u'(t) \in \tilde{A}(t)u(t)\) a.e. on \([0, b)\), and \(u(0) = x \in D\).

**Proof.** Let \(b\) be as in Lemma 1.4. Let \(u_n: [0, b) \to X\), and \(v_n: [0, b) \to X\), be as in Lemma 2.3. Then by Condition \(\mathcal{M}\), as in the proof of Lemma 2.3, if \(t \in [0, b)\) and \(u_n(t) \to u(t)\), then

\[
u(t) \in D(\tilde{A}(T)) \subset D(\tilde{A}(t)).\]

Now as in the proof of Theorem 2.2 it follows that \(u'(t)\) exists a.e. on \((0, b)\), and \(u' \to u'\) in \(L^p(0, b; X)\) for \(1 < p < \infty\). Again, as in the proof of Theorem 2.2 it follows that the set of weak cluster points of \(\{v_n'(t)\}\), denoted by \(V(t)\), is contained in \(\tilde{A}(t)u(t)\). Finally, using Lemma 2.5,

\[
u'(t) \in \text{closed convex hull of } V(t) \subset \text{closed convex hull of } \tilde{A}(t)u(t) = \tilde{A}(t)u(t)
\]

for almost all \(t \in (0, b)\). This concludes the proof of Theorem 3.4.

**Theorem 3.5.** Let \(X^*\) be uniformly convex. Let \(\{A(t): 0 \leq t \leq T\}\) be a family of multi-valued operators with common domain \(D\). Suppose that \(\{A(t)\}\) satisfies Condition \(\mathcal{S}\) with \(D = \bigcup_{n=1}^{\infty} D_n\), and each \(\{A_n(t): 0 \leq t \leq T\}\) satisfies Conditions \(\mathcal{D}, \mathcal{K},\) and \(\mathcal{C}\), and that

\[
\tilde{A}_n(t) \subset A_{n+1}(t)
\]

(see Theorem 3.4) for each positive integer \(n\) and each \(t \in [0, T]\). Then there is a number \(b > 0\) and a unique function \(u: [0, b) \to X\) so that \(u\) is a solution of ACP with respect to \(\{D_n\}\) on \([0, b)\).
Proof. The family \( \{A_n(t): 0 \leq t \leq T\} \) satisfies Conditions \( \mathcal{D}, \mathcal{K}, \text{ and } \mathcal{C} \), so by Theorem 3.4 there exists a number \( b_n > 0 \) and a function \( u_n: [0, b_n) \to X \) such that \( u_n'(t) \in \tilde{A}_n(t)u_n(t) \) a.e. on \([0, b_n)\) for \( n = 1, 2, 3, \ldots \). Thus, \( u_n'(t) \in A_{n+1}(t)u_n(t) \) a.e. on \([0, b_n)\). If the sequence \( \{b_n\} \) is bounded, let \( b = \sup_n \{b_n\} \); otherwise, let \( b = +\infty \). In either instance, if \( b_k = b \) for some \( k \), define \( u: [0, b) \to X \) by \( u(t) = u_k(t) \). If \( b_n \neq b \) for all \( n \), then select an increasing subsequence \( \{b_{n_k}\} \) of \( \{b_n\} \) so that \( b_{n_k} \to b \) and define \( u: [0, b) \to X \) as in Theorem 3.3, and the result follows from that theorem.

The uniqueness follows from Theorem 3.1.

Now consider alternative approaches to solving the problem

\[
u'(t) \in A(t)u(t), \quad u(0) = x,
\]

where \( \{A(t)\} \) satisfies Condition \( \mathcal{F} \). In order to facilitate the discussion, consider the specific case in which \( X = \mathbb{R}, A(t)x = Ax = x^2 \) for \( x \in \{X \in \mathbb{R}: x \geq 0\} = D(A), \) and \( D_n = [0, n) \). Letting \( b_n = (n - x)/nx \) for \( x \in D_n \), one gets \( u_n(t) = x/(1 - tx) \) as solutions of ACP\( _n \) on \([0, b_n)\).

Theorem 3.1 of [1] does not apply to ACP\( _n \) because \( \tilde{A}_n \) is not closed, and it does not apply directly to \( u' \in \tilde{A}_nu \), or \( u' \in \tilde{A}_nu \) because the operators \( \tilde{A}_n \) and \( A_n \) do not satisfy Condition I of [1].

In Theorem 3.5, this problem is solved by using the methods (but not the results) of [1] because \( \tilde{A}_n \subset A_{n+1} \).

It should be noted that Theorem 3.1 of [1] can be applied in a different way, at least in this example. Let

\[
A_n^*x = \begin{cases} A_nx & \text{if } 0 \leq x < n \\ [0, n^2] & \text{if } x = n \end{cases}
\]

Then \( A_n^* \) is closed and satisfies Condition I. Furthermore, the solution \( v_n \) of \( v' \in A_n^*v \) agrees with \( u_n \) on \([0, b_n)\) and is constant thereafter.

It is not clear that this method of finding closed extensions of \( A_n \) which satisfy Condition I can be generalized. This process may sometimes be possible, at least in Hilbert spaces, by using methods like those in [2]. However, even if such extensions can be found, it is not clear how a solution of ACP can be constructed from the solutions \( v_n \) of \( v' \in A_n^*v \). This is because one would not know in general that \( v_n'(t) \in Av_n(t) \), or even that \( v_n(t) \in D \), for small positive \( t \). It can happen, for example, that \( A_nv \) is properly contained in \( A_n^*v \) for \( v \in D_n \), and \( D_n \) is not open in \( D(A_n^*) \). See Example 2 in [7].
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Received April 28, 1975.
Mieczyslaw Altman, *Contractor directions, directional contractors and directional contractions for solving equations* .......................................................... 1
Michael Peter Anderson, *Subgroups of finite index in profinite groups* ........... 19
Zvi Arad, *Abelian and nilpotent subgroups of maximal order of groups of odd order* .......................................................... 29
John David Baildon and Ruth Silverman, *On starshaped sets and Helly-type theorems* .......................................................... 37
John W. Baker and R. C. Lacher, *Some mappings which do not admit an averaging operator* .......................................................... 43
Joseph Barback, *Composite numbers and prime regressive isols* ...................... 49
David M. Boyd, *Composition operators on \( H^p(A) \) ........................................ 55
Maurice Chacron, *Co-radical extension of PI rings* ........................................ 61
Fred D. Crary, *Some new engulfing theorems* .................................................. 65
Victor Dannon and Dany Leviatan, *A representation theorem for convolution transform with determining function in \( L^p \) ........................................ 81
Mahlon M. Day, *Lumpy subsets in left-amenable locally compact semigroups* .......................................................... 87
Michael A. Gauger, *Some remarks on the center of the universal enveloping algebra of a classical simple Lie algebra* ........................................ 93
David K. Haley, *Equational compactness and compact topologies in rings satisfying A.C.C* .......................................................... 99
Raymond Heitmann, *Generating ideals in Prüfer domains* .............................. 117
Gerald Norman Hile, *Entire solutions of linear elliptic equations with Laplacian principal part* .................................................. 127
Richard Oscar Hill, *Moore-Postnikov towers for fibrations in which \( \pi_1(\text{fiber}) \) is non-abelian* .................................................. 141
John Rast Hubbard, *Approximation of compact homogeneous maps* ................ 149
Russell L. Merris, *Relations among generalized matrix functions* .................... 153
V. S. Ramamurthi and Edgar Andrews Rutter, *On cotorsion radicals* ............... 163
Ralph Tyrrell Rockafellar and Roger Jean-Baptiste Robert Wets, *Stochastic convex programming: basic duality* ........................................ 173
Alban J. Roques, *Local evolution systems in general Banach spaces* ............... 197
I. Bert Russak, *An indirect sufficiency proof for problems with bounded state variables* .......................................................... 219
Richard Alexander Sanerib, Jr., *Ultrafilters and the basis property* .................. 255
H. A. Seid, *The decomposition of multiplication operators on \( L_p \)-spaces* ........ 265
Franklin D. Tall, *The density topology* .................................................. 275
John Campbell Wells, *Invariant manifolds on non-linear operators* .................. 285
James Chin-Sze Wong, *A characterization of topological left thick subsets in locally compact left amenable semigroups* ........................................ 295