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**ON THE LEAST NUMBER OF FIXED POINTS FOR INFINITE
COMPLEXES**

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Let K be a connected infinite and locally finite simplicial complex. The main theorem of this paper is the following: let L be a two-dimensionally connected infinite subcomplex of K , whose boundary \dot{L} in K consists of vertices only, and $f: |K| \rightarrow |K|$ be a map. Then there exists a map $F: |K| \rightarrow |K|$, that has the following properties: (1) $F \cong f \text{ rel } \overline{|K-L|}$; and, (2) F has no fixed point on $|L| - |\dot{L}|$.

The main theorem implies that if an infinite and locally finite complex K is two dimensionally connected, then the least number of fixed points of any mapping class from $|K|$ to itself is null. At the same time, the main theorem also enables us to compute the least number $m(K)$ of the fixed points of the identity mapping class of $|K|$ by means of the following result: $m(K)$ is equal to the least number $n(K)$ of the fixed points of the good displacements of the welding set $\dot{M}(K)$ of K , where $\dot{M}(K)$ is the set of the boundary vertices of all these maximal two-dimensionally connected and finite subcomplexes of K .

In this paper, an infinite complex means a complex whose simplices are countable infinite. On the other hand, a locally finite complex means a complex K satisfying the following two conditions: For each simplex σ of K , $\text{St}_K(\sigma)$ consists of number of finite simplices and $|\text{St}_K(\sigma)|$ is an open subset of $|K|$. The second condition means the topology of $|K|$ is the weak topology. If x is a point of $|K|$, then it belongs to just one simplex of K which is called the carrier of x and is denoted by $\text{Tr}_K(x)$. A complex K is called two-dimensionally connected if for any two maximal simplices σ and τ of K , there are simplices of K

$$\sigma = \sigma_0, \sigma_1, \dots, \sigma_{n-1}, \sigma_n = \tau$$

such that σ_{i-1} and σ_i , $i = 1, \dots, n$, have a common face of dimension greater than zero.

Suppose that M is a subset of $|K|$ and that $f: M \rightarrow |K|$ is a map such that $\overline{\text{Tr}_K(x)} \cap \overline{\text{Tr}_K[f(x)]} \neq \emptyset$ for any $x \in M$, then we say that f satisfies $S(K)$ on M . The following Lemma 1 is the generalization of Lemma 2.3 and Lemma 1.3 of [6].

LEMMA 1. *Let K be a locally finite complex and τ the common face of its maximal simplices σ_1 and σ_2 , where the dimension of τ*

is greater than zero. Suppose we are given points $A \in \sigma_1$, $B \in \tau$ and a map $f: |K| \rightarrow |K|$ such that A is an isolated fixed point of f and it is the only fixed point of f on $[A, B]$. Then we can find a map $F: |K| \rightarrow |K|$ and $\delta > 0$ such that:

$$F \cong f \text{ rel } [|K| - U([A, B], \delta)]$$

and F on $U([A, B], \delta)$ has only one fixed point C belonging to σ_2 . If f satisfies $S(K)$ on $[A, B]$ then F satisfies $S(K)$ on $\bar{U}([A, B], \delta)$.

LEMMA 2. Let K be a locally finite complex and $f: |K| \rightarrow |K|$ be a map. Then there is a map F , $F \cong f: |K| \rightarrow |K|$ such that each fixed point of F is isolated and lies in a maximal simplex of K .

Proof. We can find a simplicial approximation $q: R \rightarrow K$ to f , where R is a barycentric subdivision of a subdivision H of the complex K . We first prove that q has a maximum of one fixed point on the closure of each simplex of R as follows. If σ^n is a simplex of R and x_1, x_2 are two fixed points of q such that the open segment $(x_1, x_2) \subset \sigma^n$ belongs to σ^n , then the straight line $y = tx_1 + (1-t)x_2$ intersects $\bar{\sigma}^n$ at two points y_1 and y_2 , which are fixed points of q . Because x_i is a fixed point of the simplicial map q , then $|\text{Tr}_R(x_i)| \subset |\text{Tr}_H(x_i)|$, so the dimension of $\text{Tr}_H(x_i)$ is n . The dimension of the carrier of (x_1, x_2) in H is n . Similarly, we have $|\text{Tr}_R(y_i)| \subset |\text{Tr}_H(y_i)|$, so the dimension of $\text{Tr}_H(y_i)$ is equal to the dimension of $\text{Tr}_R(y_i)$ and less than n , for $i = 1, 2$. Since R is the barycentric subdivision of H , σ^n has a face σ^{n-1} , such that all the points of $\bar{\sigma}^n$ which have the carrier in H of dimension less than n belong to $\bar{\sigma}^{n-1}$. This fact implies that $y_1, y_2 \in \bar{\sigma}^{n-1}$, which is a contradiction, because then we would have $(x_1, x_2) \subset \bar{\sigma}^{n-1}$.

Next we denote all the fixed points of q as x_1, x_2, \dots , so:

$$|\text{St}_R[\text{Tr}_R(x_i)]| \cap |\text{St}_R[\text{Tr}_R(x_j)]| = \phi, \text{ for } i \neq j.$$

We choose $\delta_i > 0$, $i = 1, 2, \dots$, such that:

$$\bar{U}(x_i, \delta_i) \subset |\text{St}_R[\text{Tr}_R(x_i)]|, \quad i = 1, 2, \dots,$$

then:

$$\bar{U}(x_i, \delta_i) \cap \bar{U}(x_j, \delta_j) = \phi, \quad i \neq j.$$

From [1] (Kapitel 14) we can find the maps $g_i: \bar{U}(x_i, \delta_i) \rightarrow |K|$ with $\varepsilon_i = \sup \{\rho[q(x), g_i(x)] | x \in \bar{U}(x_i, \delta_i)\}$, where ρ is the metric of $|K|$, with ε_i sufficiently small so that the following three conditions are satisfied:

$$(1) \quad \overline{\text{Tr}_K[g_i(x)]} \cap \overline{\text{Tr}_K[q(x)]} \neq \phi, \text{ for all } x \in \bar{U}(x_i, \delta_i);$$

(2) each fixed point of g_i is isolated and lies in a maximal simplex of R as well as in $\bar{U}(x_i, \delta_i/2)$; and,

(3) $\alpha[q(x), g_i(x), (2 - 2\rho(x, x_i)/\delta_i)t] \neq x$, for all $0 \leq t \leq 1$ when $\delta_i/2 \leq \rho(x, x_i) \leq \delta_i$.

Using the short homotopy α of Lemma 1.1 of [6] we define

$$f_i(x) = \begin{cases} q(x), & x \in |K| - \bigcup_i U(x_i, \delta_i), \\ \alpha[q(x), g_i(x), (2 - 2\rho(x, x_i)/\delta_i)t], & \delta_i/2 \leq \rho(x, x_i) \leq \delta_i, \\ \alpha[q(x), g_i(x), t], & 0 \leq \rho(x, x_i) \leq \delta_i/2, \end{cases}$$

so f_i is a homotopy between q and f_1 . Finally, let $F = f_1$, then each fixed point of F is isolated and lies in a maximal simplex of K .

LEMMA 3. *Assume that K is a locally finite complex, M is a subcomplex consisting of vertices only, and that $g = M \rightarrow |K|$ is a map satisfying $S(K)$ on M . Then there is a map $F_1: |K| \rightarrow |K|$ that has the following properties:*

- (1) F_1 satisfies $S(K)$ on $|K|$;
- (2) $F_1(x) = g(x)$, for all $x \in M$; and,
- (3) each fixed point of F_1 on $|K| - M$ is isolated and lies in a maximal simplex of K .

Proof. In the proof of Lemma 2, let $f = 1$; thus we can choose ε_i to be sufficiently small to ensure that $F(x)$ satisfies $S(K)$ on $|K|$. Since M consists of vertices of K , then

$$\overline{\text{Tr}_K(x)} \cap \overline{\text{Tr}_K[g(x)]} \cap \overline{\text{Tr}_K[F(x)]} \neq \phi,$$

for all $x \in M$. Writing $M = \{y_1, y_2, \dots\}$, we can find $\eta_i > 0$, that have the following properties:

$$\begin{aligned} \bar{U}(y_i, \eta_i) \cap \bar{U}(y_j, \eta_j) &= \phi, \quad i \neq j; \\ \bar{U}(y_i, \eta_i) &\subset \text{St}_K(y_i), \quad F[\bar{U}(y_i, \eta_i)] \subset \text{St}_K(y_i); \\ F[\bar{U}(y_i, \eta_i)] \cap \bar{U}(y_i, \eta_i) &= \phi, \quad i = 1, 2, \dots \end{aligned}$$

We choose a path $P_i = [F(y_i), A_i, y_i, B_i, g(y_i)]$ in $\text{St}_K(y_i)$, parametrized by length, such that points A and B belong to the maximal simplices of K . Defining the map $F_1: |K| \rightarrow |K|$ as:

$$F_1(x) = \begin{cases} F(x), & x \in |K| - \bigcup_i U(y_i, \eta_i); \\ F\left[\left(\frac{2\rho(x, y_i)}{\eta_i} - 1\right)x + \left(2 - \frac{2\rho(x, y_i)}{\eta_i}\right)y_i\right], & \eta_i/2 \leq \rho(x, y_i) \leq \eta_i; \\ P_i\left(1 - \frac{2\rho(x, y_i)}{\eta_i}\right), & 0 \leq \rho(x, y_i) \leq \eta_i/2, \end{cases}$$

F_1 satisfies the conditions of this lemma.

THEOREM 1. *Assume that K is an infinite and locally finite complex and that L is a two-dimensionally connected infinite subcomplex which has the boundary \dot{L} consisting of some vertices of K . Assume that $f: |K| \rightarrow |K|$ is a map and that each fixed point of f on $|L| - |\dot{L}|$ is isolated and lies in a maximal simplex of L . Then there exists a map $F: |K| \rightarrow |K|$ which has the following two properties:*

- (a) $F \cong f \text{ rel } |\overline{K - \dot{L}}|$; and,
- (b) F has no fixed points on $|L| - |\dot{L}|$.

If f satisfies $S(K)$ on $|K|$ then F also satisfies $S(K)$ on $|K|$.

Proof. The basic method of constructing F from f is to push a fixed point of f further away on L . First we choose the route of pushing the fixed point of f . We construct a one-dimensional complex R such that there exists a one-to-one correspondence g from all the maximal simplices of L to all the vertices of R , where two vertices $g(\sigma_1)$ and $g(\sigma_2)$ constitute a one-dimensional simplex in R if, and only if, σ_1 and σ_2 have a common face of dimension greater than zero. Then R is a connected, infinite and locally finite complex. We choose a tree S in R which is a simply connected subcomplex of R and contains all the vertices of R .

We now construct a function N on the simplices of S by inductive definition. In complex S , if a vertex τ^0 is a face of a single one-dimensional simplex τ^1 only, then we define $N(\tau^0) = 1$ and $N(\tau^1) = 1$. Evidently, $S - N^{-1}(1)$ is a subcomplex of S . In complex $S - \bigcup_{r=1}^{i-1} N^{-1}(r)$, if a vertex τ^0 is a face of a single one-dimensional simplex τ^1 only, then we define $N(\tau^0) = i$ and $N(\tau^1) = i$. Evidently, $S - \bigcup_{r=1}^i N^{-1}(r)$ is a subcomplex of S . Let $T = S - \bigcup_{r=1}^{\infty} N^{-1}(r)$. If T is nonempty, then T is a subcomplex of S and we define $N(\tau) = 0$ for all $\tau \in T$. As a result, function N has the following properties (1) and (2):

- (1) $S - \bigcup_{r=1}^i N^{-1}(r)$ is simply connected, for $i = 1, 2, \dots$.
- (2) if τ^0 is a vertex of $S - T$, then there exists another vertex σ^0 of S such that we have either $N(\sigma^0) > N(\tau^0)$ or $N(\sigma^0) = 0$, where τ^0 and σ^0 constitute a one-dimensional simplex of S .

(3) If T is nonempty, from (1) we know that T is a simply connected and infinite subcomplex of S . (See Fig. 1). In this case, we pick a vertex A in T and construct a function V on all the vertices of T as follows: For a vertex τ^0 , $V(\tau^0)$ is defined to be the least number of edges from A to τ^0 in T . In this case the property (4) is similar to property (2):

- (4) if τ^0 is a vertex of T , then there exists another vertex

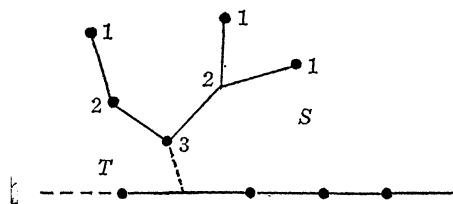


FIGURE 1

σ^0 of T such that $V(\sigma^0) > V(\tau^0)$, where τ^0 and σ^0 constitute a one-dimensional simplex of T .

Based on the Lemma 1 and property (2), we can move the fixed points of f from $g^{-1}N^{-1}(1)$ to $\{g^{-1}N^{-1}(r)/r = 0 \text{ or } r > 1\}$, and subsequently move the fixed points of f from $g^{-1}N^{-1}(i)$ to $\{g^{-1}N^{-1}(r)/r = 0 \text{ or } r > i\}$, and so on, thereby moving all the fixed points of f to $\{g^{-1}N^{-1}(0)\}$. Further, based on the Lemma 1 and property (4), we can move the fixed points of f from $g^{-1}V^{-1}(1)$ to $\{g^{-1}V^{-1}(r)/r > 1\}$, and subsequently move the fixed points of f from $g^{-1}V^{-1}(i)$ to $\{g^{-1}V^{-1}(r)/r > i\}$ and so on. Finally, we get a map F such that $F \cong f \text{ rel } |K - L|$ and F has no fixed points on $|L| - |\dot{L}|$.

From the Theorem 1 we deduce:

THEOREM 2. Suppose K is an infinite and locally finite two-dimensionally connected complex, then the least number of the fixed points of any mapping class from $|K|$ to itself is zero.

DEFINITION 1. Let K be a locally finite complex and $M_i, i = 1, 2, \dots$, be all its maximal two-dimensionally connected finite subcomplexes, thus the boundary \dot{M}_i consists of some vertices of K . Denote $\dot{M}(K) = \bigcup_i \dot{M}_i$, $\dot{M}(K)$ is called the welding set of K . A good displacement is a map $g: \dot{M}(K) \rightarrow |K|$ such that:

- (1) $g(a) \in |\text{St}_K(a)|$, for all $a \in \dot{M}(K)$; and,
- (2) if g has no fixed points in \dot{M}_i , then the number of points in \dot{M}_i whose images under g are outside $|M_i|$ is exactly $\chi(M_i)$.

THEOREM 3. Let K be a locally finite complex, then the least number $m(K)$ of fixed points of the identity mapping class is equal to the least number of fixed points $n(K)$ of all the good displace-

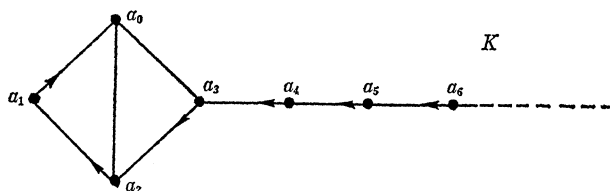


FIGURE 2

ments.

In Lemma 4 we shall prove $m(K) \leq n(K)$ and in Lemma 5 we shall prove $m(K) \geq n(K)$.

EXAMPLE 1. In Fig. 2, the welding set $\dot{M}(K)$ of K is $\{a_0, a_1, a_2, \dots\}$ and the arrows represent a good displacement which has the least fixed points. From Theorem 3 we have $m(K) = 1$. Replacing each 1-dimensional closed simplex $\tau_i = a_j a_k$ of K by a 2-dimensionally connected complex M_i , such that $\dot{M}_i = \{a_j, a_k\}$, we get a complex K_1 with $\dot{M}(K_1) = \dot{M}(K)$. If each M_i is an n -dimensional closed simplex, then $m(K_1) = 1$ results from Theorem 3; if for each M_i , either $\chi(M_i) > 2$ or $\chi(M_i) < 0$, then $m(K_1) = \infty$ from Theorem 3.

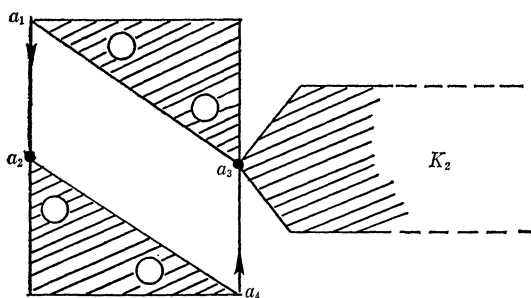


FIGURE 3

EXAMPLE 2. In Fig. 3, the welding set $\dot{M}(K_2)_\Delta$ of K_2 is $\{a_1, a_2, a_3, a_4\}$, and the arrows represent a good displacement which has least fixed points. From Theorem 3 we have $m(K_2) = 2$.

LEMMA 4. If g is a good displacement of K , there will be a map $G: |K| \rightarrow |K|$ such that:

- (1) $G(x) = g(x)$, for all $x \in \dot{M}(K)$;
- (2) G satisfies $S(K)$ on $|K|$; and,
- (3) G has no fixed points on $|K| - \dot{M}(K)$.

Proof. Applying Lemma 3, we get a map $F_1: |K| \rightarrow |K|$ that has the following three properties:

- (1) F_1 satisfies $S(K)$ on $|K|$;
- (2) $F_1(x) = g(x)$, for all $x \in \dot{M}(K)$; and,
- (3) each fixed point of F_1 on $|K| - \dot{M}(K)$ is isolated and lies in a maximal simplex of K .

From Theorem 1, there exists a map F , such that, F satisfies $S(K)$ on $|K|$, $F \cong F_1: |K| \rightarrow |K| \text{ rel } \bigcup_i M_i$, and F in $|K - \bigcup_i M_i|$ has no fixed points.

Since g is a good displacement, if g has no fixed points on \dot{M}_i , the fixed point index of F in M_i is zero, (see Appendix). From Lemma 1, we may move all the fixed points of F on $|M_i - \dot{M}_i|$ to any single point and then cancel this fixed point (see page 123 of [2]). If the map g in \dot{M}_i has a fixed point A , then applying Lemma 1 as many times as necessary we may move all the fixed points of F on $|M_i| - |\dot{M}_i|$ to A and finally get the map G .

In order to prove $n(K) \leq m(K)$, we introduce the concept of fixed point classes on an open subset.

DEFINITION 2. Assume that U is an open subset of the polyhedron $|K|$ of a locally finite complex K where \bar{U} is compact. Assume that a map $f: \bar{U} \rightarrow |K|$ has no fixed point on \dot{U} . Fixed points a and b of f in U are said to belong to the same *fixed point class* if there is a path $P(t)$ on U such that $P(0) = a$, $P(1) = b$, and $f[P(t)] \cong P(t) \text{ rel } \{a, b\}$ on $|K|$.

We may define the index of fixed point classes. The fixed point class with a nonzero index is called an essential fixed point class. The number of essential fixed point classes of f on U is finite.

DEFINITION 3. Suppose that a homotopy $f_t: \bar{U} \rightarrow |K|$, $0 \leq t \leq 1$, has no fixed points on \dot{U} , $f_0(a) = a$, $f_1(b) = b$ and that $P(t)$ is a path on U connecting a and b such that

$$f_t[P(t)] \cong P(t) \text{ rel } \{a, b\} \text{ on } |K|.$$

Thus we say there is a *homotopy correspondence* between the fixed point class of f_0 on U which contains a and the fixed point class of f_1 on U which contains b . This homotopy correspondence is a one-to-one correspondence between all the essential fixed point classes of f_0 and all the essential fixed point classes of f_1 . The corresponding classes have the same index.

LEMMA 5. Suppose that K is a locally finite complex and that $1 \cong f: |K| \rightarrow |K|$. Then there exists a good displacement g such that the number of fixed points of g is not greater than the number of fixed points of f .

Proof.

(1) If f has fixed points on $|M_s| - \dot{M}_s$ for some M_s of K , we arbitrarily assign a point in \dot{M}_s . The set of the assigned points and the fixed points of f on $\dot{M}(K)$ are denoted by $\{b_1, b_2, \dots\}$, then the number of points in $\{b_1, b_2, \dots\}$ is not greater than the number

of fixed points of f . We write

$$\{c_1, c_2, \dots\} = \dot{M}(K) - \{b_1, b_2, \dots\}.$$

Let $f_i: 1 \cong f: |K| \rightarrow |K|$, then $f_i(c_i)$ is a path from c_i to $f(c_i)$. Based on $f_i(c_i)$, we can construct a path $Q_i(t) = \alpha_1^i \cdot \alpha_2^i \cdots \alpha_h^i \cdot \beta^i$ that has the following four properties:

(a) for $j = 1, 2, \dots, h$, there are points $b_j^i, c_j^i \in \text{St}_K(c_i)$ and polygonal arcs θ_j^i from b_j^i to c_j^i not containing c_i (see Fig. 4) such that

$$\alpha_j^i = [c_i, b_j^i] \cdot \theta_j^i \cdot [c_j^i, c_i], j = 1, 2, \dots, h;$$

$$(b) \quad \beta^i = [c_i, b_{h+1}^i] \cdot \theta_{h+1}^i;$$

where $b_{h+1}^i \in \text{St}_K(c_i)$ and θ_{h+1}^i is a polygonal arc from b_{h+1}^i to $f(c_i)$ not containing c_i ;

$$(c) \quad \alpha_1^i \cdot \alpha_2^i \cdots \alpha_r^i \not\cong 1, r = 1, \dots, h;$$

$$(d) \quad f_i(c_i) \cong Q_i(t) \text{ rel } \{c_i, f(c_i)\}, 1 = 1, 2, \dots.$$

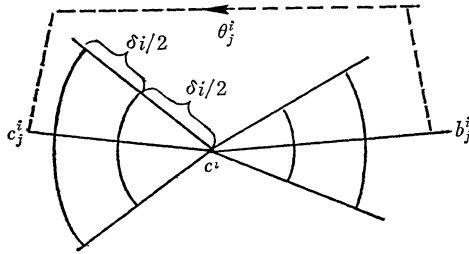


FIGURE 4

From the homotopy extension theorem, there is another homotopy $f_i: 1 \cong f: |K| \rightarrow |K|$ with $f_i(c_i) = Q_i(t)$, $i = 1, 2, \dots$.

(2) For each c_i , we choose a sufficiently small $\delta_i > 0$ such that:

$$(a) \quad \bar{U}(c_i, \delta_i) \subset \text{St}_K(c_i);$$

$$(b) \quad \bar{U}(c_i, \delta_i) \cap \bar{U}(c_j, \delta_j) = \phi, i \neq j;$$

$$(c) \quad \bar{U}(c_i, \delta_i) \cap \theta_j^i = \phi, j = 1, \dots, h+1;$$

$$(d) \quad b_j^i \in |K| - \bigcup_i U(c_i, \delta_i), j = 1, \dots, h+1,$$

$$c_j^i \in |K| - \bigcup_i U(c_i, \delta_i), j = 1, \dots, h.$$

We define a map $F: |K| \rightarrow |K|$ by

$$F(x) = \begin{cases} x, & x \in |K| - \bigcup_i U(c_i, \delta_i), \\ \left[\frac{2\rho(x, c_i) - 1}{\delta_i} x + \left[2 - \frac{2\rho(x, c_i)}{\delta_i} \right] c_i, & \delta_i/2 \leq \rho(x, c_i) \leq \delta_i, \\ Q_i \left[1 - \frac{2\rho(x, c_i)}{\delta_i} \right], & 0 \leq \rho(x, c_i) \leq \delta_i/2, \end{cases}$$

thus

$$F \cong f \text{ rel } \{c_1, c_2, \dots\}.$$

(3) The fixed point set of F on $|K|$ is $N_1 \cup N_2$, where

(a) $N_1 = |K| - \bigcup_i U(c_i, \delta_i)$;

(b) $N_2 = \bigcup_i \{d_1^i, d_2^i, \dots, d_{h+1}^i, e_1^i, e_2^i, \dots, e_h^i\}$, where $d_j^i \in (c_i, b_j^i)$, $j = 1, 2, \dots, h+1$, and $e_j^i \in (c_j^i, c_i)$, $j = 1, \dots, h$; moreover,

(c) $\delta_i/2 > \rho(c_i, d_1^i) > \rho(c_i, e_1^i) > \rho(c_i, d_2^i) > \rho(c_i, e_2^i) \cdots \rho(c_i, d_{h+1}^i) > 0$.

(4) If $\dot{M}_s \subset \{c_1, c_2, \dots\}$, then F on \dot{M}_s has no fixed points, and we can discuss the fixed point classes of F on $|M_s| - \dot{M}_s$.

(a) If $d_1^i \in |M_s|$, then d_1^i and $N_1 \cap |M_s|$ belong to the same fixed point class, the reason being $b_1^i \in N_1 \cap |M_s|$, and $F([b_1^i, d_1^i]) \cdot [d_1^i, b_1^i] = [b_1^i, c_i] \cdot [c_i, d_1^i] \cdot [d_1^i, b_1^i] \cong 1$. Excluding these $(\bigcup_i d_1^i) \cap |M_s|$, each fixed point of $N_2 \cap |M_s|$ does not belong to the same fixed point class as $N_1 \cap |M_s|$. This fact will be proved in (b) and (c).

(b) Suppose $b(t)$ is a path from b_r^i to d_r^i ($r > 1$) in $|M_s| - \dot{M}_s$, then there exists a loop β based at b_r^i such that $\beta \subset |M_s| \cap N_1$ and $b(t) \cong \beta \cdot [b_r^i, d_r^i] \text{ rel } \{b_r^i, d_r^i\}$. Hence,

$$\begin{aligned} F(b(t)) \cdot b(t)^{-1} &\cong F(\beta \cdot [b_r^i, d_r^i]) \cdot [d_r^i, b_r^i] \cdot \beta^{-1} \\ &= \beta \cdot F([b_r^i, d_r^i]) \cdot [d_r^i, b_r^i] \cdot \beta^{-1} \\ &\cong \beta \cdot [b_r^i, c_i] \cdot \alpha_1^i \cdot \alpha_2^i \cdots \alpha_{r-1}^i \cdot [c_i, d_r^i] \cdot [d_r^i, b_r^i] \cdot \beta^{-1} \\ &\cong \beta \cdot [b_r^i, c_i] \cdot \alpha_1^i \cdot \alpha_2^i \cdots \alpha_{r-1}^i \cdot [c_i, b_r^i] \cdot \beta^{-1} \neq 1 \end{aligned}$$

on $|K|$; because we required that $\alpha_1^i \cdot \alpha_2^i \cdots \alpha_{r-1}^i \neq 1$.

(c) Similarly, suppose $b(t)$ is a path from c_r^i to e_r^i ($r \geq 1$) in $|M_s| - \dot{M}_s$, then there exists a loop β of c_r^i such that $\beta \subset |M_s| \cap N_1$ and $b(t) \cong \beta \cdot [c_r^i, e_r^i] \text{ rel } \{c_r^i, e_r^i\}$. Hence,

$$b(t) \not\cong F(b(t)) \text{ on } |K|.$$

(d) Since f in $|M_s|$ has no fixed points, the index of each fixed point class of F on $|M_s| - \dot{M}_s$ is zero, in particular the index of the fixed point class containing $|M_s| \cap N_1$ is zero.

(5) We define a map $g: \dot{M}(K) \rightarrow |K|$ as follows:

$$g(c_i) = b_1^i, \quad i = 1, 2, \dots;$$

and,

$$g(b_j) = b_j, \quad j = 1, 2, \dots.$$

Consider the fixed point class of F on $|M_s| - \dot{M}_s$. Since the index of the fixed point class containing $|M_s| \cap N_1$ is zero, then there are exactly $\chi(M_s)$ points in \dot{M}_s , whose images under g are outside $|M_s|$ (see Appendix), so g is a good displacement.

APPENDIX. The proof of Lemma 2 of [7] (it was published previously in Chinese).

LEMMA. Assume that K is a locally finite complex and M is a maximal two-dimensionally connected finite subcomplex. Assume that $g: \dot{M} \rightarrow |K|$ is a map such that

- (1) $g(a) \in |\text{St}_K(a)|$, for all $a \in \dot{M}$;
- (2) $g(a) \neq a$, for all $a \in \dot{M}$, and g maps χ_g points of \dot{M} outside of $|M|$; and
- (3) $[a, g(a)] \cap [b, g(b)] = \emptyset$, for any $a, b \in \dot{M}$.

If a map $F: |M| \rightarrow |K|$ has the following two properties:

- (i) $F(a) = g(a)$, for all $a \in \dot{M}$; and
- (ii) F satisfies $S(K)$ on $|M|$,

then $J(F, |M| - \dot{M})$ the index of fixed points of F on $|M| - \dot{M}$, equals $\chi(M) - \chi_g$.

Proof. We denote the points of \dot{M} by a_j , $j = 1, \dots, r$. Assume that $g(a_j) \notin |M|$ for $j = 1, 2, \dots, \chi_g$ and $g(a_j) \in |M|$ for $j = \chi_g + 1, \chi_g + 2, \dots, r$. First choose b_j , $j = 1, \dots, \chi_g$, so that $g(a_j) \in (a_j, b_j)$, $[a_j, b_j] \subset \text{St}_K(a_j) \subset |K|$ and that any two segments of $\{[a_j, b_j] | j = 1, \dots, \chi_g\}$ are disjoint (from property 3). Let K' denote the complex composed of M and $[a_j, b_j]$, $j = 1, \dots, \chi_g$. Let g' be the map g considered as a map from \dot{M} to $|K'|$. Applying Lemma 3 to g' and K' , we know there exists a map $G_1: |K'| \rightarrow |K'|$ such that $G_1(a_j) = g'(a_j) = g(a_j)$, $j = 1, \dots, r$, G_1 satisfies $S(K')$ on $|K'|$. Define a map $G_2: |K'| \rightarrow |K'|$ as follows:

$$G_2(x) = \begin{cases} G_1(x), & x \in |M|; \\ g(a_j), & x \in [a_j, b_j], j = 1, 2, \dots, \chi_g. \end{cases}$$

Since G_2 is homotopic to the identity map,

$$J(G_2, K') = \chi(K') = \chi(M)$$

by "Axiom 4" on page 52 of [2]. Since G_2 on $[a_j, b_j]$, $j = 1, \dots, \chi_g$, only has one fixed point $g(a_j)$ of index +1, we obtain

$$J(G_2, |M| - \dot{M}) + \chi_g = \chi(M)$$

i.e.,

$$J(G_2, |M| - \dot{M}) = \chi(M) - \chi_g.$$

Now, denote the inclusion map of $|K'|$ into $|K|$ by I , and let $G_3 = IG_2: |M| \rightarrow |K|$. We have $J(G_3, |M| - \dot{M}) = \chi(M) - \chi_g$. Finally, recall the map $F: |M| \rightarrow |K|$ assumed in this lemma. Since it has the two properties listed, the map $\alpha(x, F(x), t)$ ([2], pages 124–126), for $x \in |M|$, $0 \leq t \leq 1$, is a homotopy equivalence between the identity mapping I and F . Since G_1 satisfies $S(K')$ on $|K'|$, it also satisfies $S(K)$ on $|K'|$. Moreover, G_3 satisfies $S(K)$ on $|M|$. So $\alpha(x, G_3(x), t)$,

$x \in |M|$, $0 \leq t \leq 1$, is a homotopy equivalence from I to G_3 . Furthermore $\alpha(x, F(x), t) = \alpha(x, G_3(x), t)$ when $x \in \dot{M}$, $0 \leq t \leq 1$. Consequently, employing the homotopy extension theorem on $|M|$, $F \cong G_3 \text{ rel } \dot{M}$. Thus we get the conclusion of this lemma: $J(F, |M| - \dot{M}) = J(G_3; |M| - \dot{M}) = \chi(M) - \chi_g$.

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