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NONOSCILLATORY FUNCTIONAL-DIFFERENTIAL
EQUATIONS Gerasimos E. Ladas, Y. G. Sficas and I. P. Stavroulakis

# NONOSCILLATORY FUNCTIONAL DIFFERENTIAL EQUATIONS 

G. Ladas, Y. G. Sficas and I. P. Stavroulakis


#### Abstract

Our aim in this paper is to obtain sufficient conditions under which certain functional differential equations have a "large" number of nonoscillatory solutions. Using the characteristic equation of a "majorant" delay differential equation with constant coefficients and Schauder's fixed point theorem, we obtain conditions under which the functional differential equation in question has a nonoscillatory solution. Then a known comparison theorem is employed as a tool to demonstrate that if the functional differential equation has a nonoscillatory solution, then it really has a "large" number of such solutions.


Our aim in this paper is to obtain sufficient conditions under which the functional differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{i}(t) x\left(t-\tau_{t}(t)\right)=0 \tag{1}
\end{equation*}
$$

has a "large" number of nonoscillatory solutions. It is to be noted that the literature is scarce concerning conditions under which there exist nonoscillatory solutions. Using the characteristic equation of a "majorant" delay differential equation with constant coefficients and Schauder's fixed point theorem, we obtain conditions under which (1) has a nonoscillatory solution. Then we employ a known comparison theorem [see 1, p. 224, also 4, Ch. 6] as a tool to demonstrate that if (1) has a nonoscillatory solution then it really has a "large" number of such solutions.

As it is customary, a solution is said to be oscillatory if it has arbitrarily large zeros. A differential equation is called oscillatory if all of its solutions oscillate; otherwise, it is called nonoscillatory. In this paper we restrict our attention to real valued solutions $x(t)$.

## 2. Non-oscillations.

Theorem 1. Consider the differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{l}(t) x\left(t-\tau_{l}(t)\right)=0 \tag{1}
\end{equation*}
$$

where $p_{i}(t)$ and $\tau_{i}(t)$ are continuous functions such that $\left|p_{i}(t)\right| \leq P_{i}$, $\left|\tau_{i}(t)\right| \leq T_{i},\left|p_{i}^{\prime}(t)\right| \leq A_{i}$ and $\left|\tau_{i}^{\prime}(t)\right| \leq B_{i}, i=1,2, \ldots, n$, where $P_{i}, T_{i}, A_{i}$ and $B_{l}$ are positive constants. Assume that

$$
\begin{equation*}
\lambda=\sum_{i=1}^{n} P_{i} e^{\lambda T_{i}} \tag{2}
\end{equation*}
$$

has a positive root. Then equation (1) has a nonoscillatory solution of the form

$$
\begin{equation*}
x(t)=\exp \left(-\int_{t_{0}}^{t} \lambda(s) d s\right) \tag{3}
\end{equation*}
$$

where $\lambda(t)$ is a bounded continuous function.
Proof. Suppose that $\lambda_{0}$ is a positive root of (2), i.e.,

$$
\lambda_{0}=\sum_{i=1}^{n} P_{t} e^{\lambda_{0} T_{i}} .
$$

We will prove that (1) has a nonoscillatory solution of the form (3). Substituuting (3) into (1) we obtain

$$
\begin{equation*}
\lambda(t)=\sum_{i=1}^{n} p_{i}(t) \exp \left(\int_{t-\tau_{i}(t)}^{t} \lambda(s) d s\right) \tag{4}
\end{equation*}
$$

It suffices to show that (4) has a bounded solution. We will employ Schauder's fixed point theorem. Define the sets

$$
X=\{\lambda(t): \text { bounded continuous functions mapping } \mathbf{R} \text { into } \mathbf{R}\}
$$

with sup-norm, which is a Banach space, and

$$
M=\left\{\lambda(t) \in X:\|\lambda(t)\| \leq \lambda_{0}\right\}
$$

which is a closed and convex subset of $X$. Consider the mapping $F$ on $M$ given by

$$
F \lambda(t)=\sum_{i=1}^{n} p_{i}(t) \exp \left(\int_{t-\tau_{i}(t)}^{t} \lambda(s) d s\right)
$$

Observe that

$$
\begin{aligned}
\|F \lambda(t)\| & \leq \sum_{i=1}^{n}\left|p_{i}(t)\right| \exp \left(\left|\int_{t-\tau_{i}(t)}^{t}\|\lambda(s)\| d s\right|\right) \\
& \leq \sum_{i=1}^{n} P_{l} e^{\lambda_{0} T_{i}}=\lambda_{0}
\end{aligned}
$$

Hence $F: M \rightarrow M$.

To show that (4) has a solution it suffices to show that the mapping $F$ has a fixed point. To this end it remains to show that $F$ is continuous and that $F M$ is a relatively compact subset of $X$.

We will show that $F$ is continuous by showing that each of the mappings

$$
F_{i} \lambda(t)=\exp \left(\int_{t-\tau_{t}}^{t} \lambda(s) d s\right), \quad i=1,2, \ldots, n
$$

is continuous. Let $\lambda_{n} \rightarrow \lambda$ where $\lambda_{n}, \lambda \in M$. Then

$$
\begin{aligned}
\left|F_{i} \lambda(t)-F_{i} \lambda(t)\right| & =F_{i} \lambda(t)\left|\frac{F_{t} \lambda_{n}(t)}{F_{t} \lambda(t)}-1\right| \\
& =F_{t} \lambda(t)\left|\exp \left(\int_{t-\tau_{t}}^{t}\left[\lambda_{n}(s)-\lambda(s)\right] d s\right)-1\right|
\end{aligned}
$$

But

$$
\left|\int_{t-\tau_{t}(t)}^{t}\left[\lambda_{n}(s)-\lambda(s)\right] d s\right| \leq\left\|\lambda_{n}-\lambda\right\| \cdot T_{l} \rightarrow 0 \quad \text { as } n \rightarrow \infty .
$$

and because $F_{l} \lambda(t)$ is bounded, it follows that $F_{l}$ is continuous.
To prove that $F M$ is a relatively compact subset of $X$ it suffices to prove that if $K$ is a positive constant and $\lambda$ is a function in $X$ such that $\|\lambda\| \leq K$, then $(F \lambda(t))^{\prime}$ is uniformly bounded. We have

$$
\begin{aligned}
(F \lambda(t))^{\prime}= & \sum_{l=1}^{n} p_{l}^{\prime}(t) \exp \left(\int_{t-\tau_{l}(t)}^{t} \lambda(s) d s\right) \\
& +\sum_{l=1}^{n} p_{l}(t)\left[\lambda(t)-\lambda\left(t-\tau_{l}(t)\right)\left(1-\tau_{i}^{\prime}(t)\right)\right] \\
& \cdot \exp \left(\int_{t-\tau_{l}(t)}^{t} \lambda(s) d s\right)
\end{aligned}
$$

and therefore

$$
\left|(F \lambda(t))^{\prime}\right| \leq \sum_{i=1}^{n} A_{i} e^{K T_{i}}+\sum_{i=1}^{n} P_{l} K B_{l} e^{K T_{t}}
$$

Therefore Schauder's fixed point theorem applies and the proof is complete.

Note that the r.h.s. of (2) is a positive convex function of $\lambda$ and so (2) has either two real roots, one real root, or no real root. Except in the case
that all the $P_{i}$ are zero, the roots are always positive. Thus (2) really just means $T_{1}, \ldots, T_{n}, P_{1}, \ldots, P_{\mathrm{i}} \mathrm{n}$ are fairly small.

For the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{t} x\left(t-\tau_{l}\right)=0 \tag{1}
\end{equation*}
$$

whose coefficients and delays are positive constants, it has been proved [5], see also [3], that every solution oscillates if and only if the characteristic equation

$$
\begin{equation*}
\lambda+\sum_{i=1}^{n} p_{l} e^{-\lambda \tau_{l}}=0 \tag{2}
\end{equation*}
$$

has no real roots. This is equivalent to saying that (1)' has a nonoscillatory solution if and only if (2)' has a real root.

The following are immediate corollaries of Theorem 1.
Corollary 1. Equation (1) is nonoscillatory provided that the " majorant" delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} P_{i} x\left(t-T_{i}\right)=0 \tag{5}
\end{equation*}
$$

where $P_{1}$ and $T_{i}$ are as defined in Theorem 1, is nonocillatory.

Corollary 2. The functional differential equation with constant coefficients and constant arguments

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{i} x\left(t-\tau_{l}\right)=0 \tag{6}
\end{equation*}
$$

is nonoscillatory provided that the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n}\left|p_{l}\right| x\left(t-\left|\tau_{l}\right|\right)=0 \tag{7}
\end{equation*}
$$

is nonoscillatory.
3. A comparison theorem and its applications. Next we will demonstrate how the following comparison result [see 1, p. 224, also 4, Ch. 6] may be used as a tool to establish that if a functional differential equation has a nonoscillatory solution then it has a "large" number of such solutions in a sense that will be made clear below.

Theorem 2. (Comparison Theorem.) Consider the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{i}(t) x\left(t-\tau_{i}\right)=0, \quad t \geq 0, n \geq 1 \tag{*}
\end{equation*}
$$

where $0=\tau_{0}<\tau_{1}<\cdots<\tau_{n}=\tau$ are constants, $p_{0}, p_{1}, \ldots, p_{n}$ are continuous functions and $p_{1}(t), p_{2}(t), \ldots, p_{n}(t)$ positive on $[0, \infty)$ Let $\theta, \tilde{\theta}$ : $[-\tau, 0) \rightarrow \mathbf{R}$ be continuous and such that

$$
\begin{equation*}
\theta(t)<\tilde{\theta}(t) \quad \text { on }[-\tau, 0) \quad \text { and } \quad \theta(0)=\tilde{\theta}(0)>0 . \tag{8}
\end{equation*}
$$

Let $x$ and $\tilde{x}$ be the unique solutions of $(*)$ with initial functions $\theta$ and $\tilde{\theta}$ respectively. Assume that

$$
\begin{equation*}
\tilde{x}(t)>0 \quad \text { on }[0, \infty) \tag{9}
\end{equation*}
$$

Then

$$
\begin{equation*}
x(t)>\tilde{x}(t) \quad \text { on }(0, \infty) \tag{10}
\end{equation*}
$$

Remark 1. If we denote by $x\left(t, t_{0}, \theta\right)$ the unique solution of $(*)$ with initial function $\theta$ at $t=t_{0}$, then $x\left(t, t_{0},-\theta\right)=-x\left(t, t_{0}, \theta\right)$. From this observation we obtain a dual to the above theorem by simply reversing the signs of the inequalities in (8), (9), and (10). That is, under the hypotheses of Theorem 2 we have, on $(0, \infty)$,

$$
x(t, 0, \theta)>\tilde{x}(t, 0, \tilde{\theta})>0 \quad \text { and } \quad x(t, 0,-\theta)<\tilde{x}(t, 0-\tilde{\theta})<0 .
$$

Finally a close look at the proof of the comparison theorem [see 1, p. 224] shows that the functional arguments in (*) do not have to be constants. The results is true if we assume tha $\tau_{i}(t)$ are continuous function satisfiying the following condition

$$
\left\{\begin{array}{l}
\text { (i) } \tau_{0}(t) \equiv 0 \quad \text { and } \quad \tau_{J}(t) \not \equiv 0 \text { for } j=1,2, \ldots, n ;  \tag{11}\\
\text { (ii) } \exists \tau>0 \quad \text { such that } 0 \leq \tau_{J}(t) \leq \tau, j=1,2, \ldots, n .
\end{array}\right.
$$

First we apply the comparison theorem to the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\sum_{i=1}^{n} p_{l} x\left(t-\tau_{i}\right)=0 \tag{1}
\end{equation*}
$$

where $p_{i}$ and $\tau$ are positive constants. As discussed above (1)' has a nonoscillatory solution provided that the characteristic equation

$$
\begin{equation*}
f(\lambda) \equiv \lambda+\sum_{i=1}^{n} p_{i} e^{-\lambda \tau_{i}}=0 \tag{2}
\end{equation*}
$$

has a real root. The condition, for example,

$$
\begin{equation*}
\left(\sum_{\imath=1}^{n} p_{l}\right) \rho \leq \frac{1}{e} \quad \text { where } \tau=\max \left\{\tau_{1}, \tau_{2}, \ldots, \tau_{n}\right\} \tag{12}
\end{equation*}
$$

implies that $f(0) f(-1 / \tau) \leq 0$ and therefore (2)' has a real (negative) root in the interval $(-1 / \tau, 0)$.

Now assume that (2)' has a real root $\lambda_{0}$. Then (1)' has the nonoscillatory solution

$$
\mu e^{\lambda_{0} t} \quad \text { for any } \mu \in \mathbf{R}, \mu \neq 0 .
$$

But then, by the comparison theorem, any solution of (1)' with initial function $\phi(t)$ satisfying

$$
\phi(t)<\phi(0) e^{\lambda_{0} t}, \quad-\tau \leq t<0 \quad \text { and } \quad \phi(0)>0
$$

and any solution of (1) with initial function $\psi(t)$ satisfying

$$
\psi(t)>\psi(0) e^{\lambda_{0} t}, \quad-\tau \leq t<0 \quad \text { and } \quad \psi(0)<0
$$

is nonoscillatory. In particular (and also when $\lambda$ is not known) we have the following result.

Corollary 3. Assume that (2)' has a real root. Then any solution of (1)' with initial function $\phi$ or $\psi$ satisfying

$$
\phi(t)<\phi(0), \quad-\tau \leq t<0 \quad \text { and } \quad \phi(0)>0
$$

or

$$
\psi(t)>\psi(0), \quad-\tau \leq t<0 \quad \text { and } \quad \psi(0)<0
$$

is nonoscillatory.
Example 1. For the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+\frac{1}{2} e^{-1 / 3} x\left(t-\frac{1}{3}\right)+\frac{1}{2} e^{-1 / 2} x\left(t-\frac{1}{2}\right)=0 \tag{13}
\end{equation*}
$$

condition (12) is satisfied. Therefore its characteristic equation

$$
\begin{equation*}
\lambda+\frac{1}{2} e^{-1 / 3-\lambda / 3}+\frac{1}{2} e^{-1 / 2-\lambda / 2}=0 \tag{14}
\end{equation*}
$$

has a real (negative) root in the interval $(-2, \infty)$. Observe that $\lambda=-1$ is a root of (14). Thus (13) has the nonoscillatory solution $\mu e^{-t}$ for any $\mu \in \mathbf{R}, \mu \neq 0$. Also, using the comparison theorem, any solution of (13) with initial function $\phi$ or $\psi$ satisfying

$$
\phi(t)<\phi(0) e^{-t}, \quad-\tau \leq t<0 \quad \text { and } \quad \phi(0)>0
$$

or

$$
\psi(t)>\psi(0) e^{-t}, \quad-\tau \leq t<0 \quad \text { and } \quad \psi(0)<0
$$

is nonoscillatory.

In view of Theorems 1 and 2 and Remark 1, we obtain the following result equation (1).

Corollary 4. Consider the differential equation (1) subject to the hypotheses of Theorem 1 and in addition assume that $p_{t}(t)>0, i=$ $1,2, \ldots, n$, and condition (11) is satisfied. Then, any solution of (1) with initial function $\phi$ or $\psi$ satisfying

$$
\phi(t)<\phi(0), \quad-\tau \leq t<0 \quad \text { and } \quad \phi(0)>0
$$

or

$$
\psi(t)>\psi(0), \quad-\tau \leq t<0 \quad \text { and } \quad \psi(0)<0
$$

is nonoscillatory.
Finally we apply the comparison theorem to the delay differential equation

$$
\begin{equation*}
x^{\prime}(t)+p(t) x(t-\tau)=0, \quad t \geq t_{0}, \tag{15}
\end{equation*}
$$

where $\tau$ is a positive constant and $p(t)$ is a $\tau$-periodic continuous function with

$$
\begin{equation*}
K \equiv \int_{t-\tau}^{t} p(s) d s \leq \frac{1}{e} . \tag{16}
\end{equation*}
$$

With these hypotheses equation (15) has a nonoscillatory solution of the form

$$
\begin{equation*}
x(t)=\exp \left(\lambda \int_{t_{0}}^{t} p(s) d s\right) \tag{17}
\end{equation*}
$$

with $\lambda<0$. In fact, substituting (17) into (15), we obtain

$$
g(\lambda) \equiv \lambda e^{K \lambda}+1=0 .
$$

It suffices to show that $g(\lambda)$ has a negative root.
Case 1. $K<0$. Then $g(-\infty)=-\infty$ and $g(0)=1$. Therefore $g(\lambda)$ has a root in $(-\infty, 0)$.

Case 2. $K=0$. Then $\lambda=-1$ is a root
Case 3. $K>0$. Then $g(-1 / K)=(K e-1) / K e \leq 0$ and $g(0)=1$. Therefore $g(\lambda)$ has a root in $[-1 / K, 0)$.

Thus in each case (15) has a nonoscillatory solution of the form given by (17). If in addition to (16) we assume that $p(t)>0$ then the comparison theorem applies and we have the following result.

Corollary 5. Consider the differential equation (15) under the assumptions that $p(t)>0$ and (16) holds. Then the solution of (15) with initial function $\phi$ and $\psi$ satisfying

$$
\phi(t)<\phi\left(t_{0}\right), \quad t_{0}-\tau \leq t<t_{0} \quad \text { and } \quad \phi\left(t_{0}\right)>0
$$

or

$$
\psi(t)>\psi\left(t_{0}\right), \quad t_{0}-\tau \leq t<t_{0} \quad \text { and } \quad \psi\left(t_{0}\right)<0
$$

is nonoscillatory.
Example 2. Consider the differential equation

$$
x^{\prime}(t)+(\sin t) x(t-2 \pi)=0, \quad t \geq 0 .
$$

Observe that $\sin t$ is a $2 \pi$-periodic function and condition (15) is satisfied, with $K=0$. Note that $e^{\cos t}$ is a multiple of the nonoscillatory solution given by (17).

Remark 2. When $p(t)>0$ the condition $K>1 / e$ implies, see [2], that every solution of (15) oscillates. This is our motivation for the following

Conjecture. If $K>1 / e$ then (15) is oscillatory.

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