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**ON A CHARACTERIZATION OF VELOCITY MAPS IN THE  
SPACE OF OBSERVABLES**

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**Motivated by Heisenberg's picture of quantum dynamics the notion of a velocity map is introduced and its properties are investigated. The main theorem in the present exposition strengthens the well-known result that every derivation on the algebra of all bounded operators on a complex separable Hilbert space is inner. A constructive proof leads to an inversion formula for the observables inducing the derivation.**

**1. Introduction.** Let  $\mathcal{A}$  be a von Neumann algebra. Then a derivation  $\delta$  on  $\mathcal{A}$  is a linear map  $\delta: \mathcal{A} \rightarrow \mathcal{A}$  satisfying  $\delta(XY) = X\delta(Y) + \delta(X)Y$  for every  $X, Y$  in  $\mathcal{A}$ . Inner derivations are the derivations of the form  $\delta(X) = [D, X]$  for some  $D$  in  $\mathcal{A}$ . It is a well-known result of Sakai and Kadison (cf. [1], [2]) that every derivation  $\delta$  on a von Neumann algebra  $\mathcal{A}$  is inner.

In Heisenberg's picture of quantum dynamics maps of the form  $\delta(X) = i[H, X]$ , where  $H, X$  are self-adjoint operators, determine the rate of change (or velocity) of observables. However, in this case, we are interested in the action of  $\delta$  only on the real linear space  $\mathcal{O}$  of observables (self-adjoint elements) of the algebra and not on the full algebra  $\mathcal{A}$ . Keeping this in mind K. R. Parthasarathy suggested the following "axioms" for a velocity map which measures rate of change of observables:

Let  $\mathcal{O}$  be the real linear space of all self-adjoint elements of a von Neumann algebra  $\mathcal{A}$ . Then a map  $\delta: \mathcal{O} \rightarrow \mathcal{O}$  is called a velocity map if it satisfies the following conditions.

$$(1.1) \quad \delta(aX) = a\delta(X) \quad \forall a \in \mathbb{R}, \forall X \in \mathcal{O},$$

$$(1.2) \quad \delta(X + Y) = \delta(X) + \delta(Y) \quad \forall X, Y \in \mathcal{O} \text{ with } [X, Y] = 0,$$

$$(1.3) \quad \delta(XY) = X\delta(Y) + \delta(X)Y \quad \forall X, Y \in \mathcal{O} \text{ with } [X, Y] = 0.$$

It should be noted that the requirement  $[X, Y] = 0$  in (1.3) is an algebraic necessity to define  $\delta(XY)$ . We insist on the same requirement in (1.2) for the purely physical reason that the observables  $X, Y$  and  $X + Y$  are simultaneously measurable if and only if  $[X, Y] = 0$ .

In this paper we study continuous velocity maps. (Here and throughout this paper by continuity we mean norm continuity.) Under the assumption of continuity we show that if a map  $\delta: \mathcal{O} \rightarrow \mathcal{O}$  satisfies (1.1) and (1.3) then it automatically satisfies (1.2) and hence becomes a velocity map.

A priori, it is not clear whether such a velocity map can be extended to a derivation on  $\mathcal{A}$ . We expect that such derivations are also inner in the sense  $\delta(X) = i[H, X]$  for some  $H$  in  $\mathcal{O}$  and hence can be extended to a derivation on  $\mathcal{A}$  in a unique way.

In this paper we have an elementary constructive proof that this is indeed so for linear velocity maps on the von Neumann algebra of all bounded operators on a complex separable Hilbert space. In fact we have an explicit inversion formula for  $H$  in terms of  $\delta$ .

**2. Velocity maps.** Let  $\mathcal{O}$  be the real linear space of observables of a von Neumann algebra  $\mathcal{A}$ . For non-zero real numbers  $c$  define the map  $\delta_c: \mathcal{O} \rightarrow \mathcal{O}$  by

$$(2.1) \quad \delta_c(X) = cX \log |X| \quad \forall X \in \mathcal{O}.$$

As the function  $f_c(x) = cx \log |x|$  (which is defined to be 0 at the origin) is a continuous function on the real line  $\delta_c$  is well-defined.  $\delta_c$  clearly satisfies the condition (1.3), that is,

$$\delta_c(XY) = X\delta_c(Y) + \delta_c(X)Y \quad \forall X, Y \text{ in } \mathcal{O} \text{ with } [X, Y] = 0.$$

However  $\delta_c$  does not satisfy conditions (1.1) and (1.2). In contrast to this we have the following theorem which shows that if a continuous map  $\delta: \mathcal{O} \rightarrow \mathcal{O}$  satisfies (1.3) and a weakened (1.1) namely,

$$(2.2) \quad \delta(aI) = 0 \quad \forall a \in \mathbb{R}$$

then  $\delta$  satisfies both (1.1) and (1.2).

**THEOREM 2.1.** *Let  $\mathcal{O}$  be the real linear space of all self-adjoint elements of a von Neumann algebra  $\mathcal{A}$ . If  $\delta: \mathcal{O} \rightarrow \mathcal{O}$  is a continuous map satisfying (1.3) and (2.2) then it is a velocity map.*

*Proof.* Condition (1.3) implies

$$\begin{aligned} \delta(aX) &= \delta(aI \cdot X) \\ &= aI \cdot \delta(X) + \delta(aI)X \\ &= a\delta(X) \quad \forall a \in \mathbb{R}, X \in \mathcal{O}. \end{aligned}$$

This proves (1.1).

Now for any natural number  $n$  if we have  $n$  mutually orthogonal projections  $P_1, P_2, \dots, P_n$  in  $\mathcal{O}$ , we claim,

$$(2.3) \quad \delta \left( \sum_j a_j P_j \right) = \sum_j a_j \delta(P_j) \quad \text{for } a_j \in \mathbb{R} \forall j.$$

We have proved this for  $n = 1$ . For  $n \geq 1$ , put

$$P_{n+1} = I - \sum_{j=1}^n P_j, \quad a_{n+1} = 0.$$

Then we have

$$\sum_j P_j = I \quad \text{and} \quad \sum_{j=1}^{n+1} a_j P_j = \sum_{j=1}^n a_j P_j.$$

By (1.3), for every  $k \geq 1$

$$\begin{aligned} \delta \left( \left( \sum_j a_j P_j \right) P_k \right) &= \delta(a_k P_k) \\ &= \left( \sum_j a_j P_j \right) \delta(P_k) + \delta \left( \sum_j a_j P_j \right) P_k, \\ \delta \left( \sum_j a_j P_j \right) P_k &= \delta(a_k P_k) - \sum_j a_j P_j \delta(P_k) \\ &= a_k \delta(P_k) + \sum_{j \neq k} a_j \delta(P_j) P_k - a_k P_k \delta(P_k) \\ &= a_k (I - P_k) \delta(P_k) + \sum_{j \neq k} a_j \delta(P_j) P_k. \end{aligned}$$

Adding over  $k$  and using (1.3) we get

$$\begin{aligned} \delta \left( \sum_j a_j P_j \right) &= \sum_k a_k (I - P_k) \delta(P_k) + \sum_j a_j \delta(P_j) (I - P_j) \\ &= \sum_j a_j \{ (I - P_j) \delta(P_j) + \delta(P_j) (I - P_j) \} \\ &= \sum_j a_j \{ \delta(P_j) - P_j \delta(P_j) + \delta(P_j) - \delta(P_j) P_j \} \\ &= \sum_j a_j \delta(P_j). \end{aligned}$$

Let  $Z, W$  be commuting elements in  $\mathcal{O}$  with finite number of points in the spectrum. We know that spectral projections of elements of  $\mathcal{O}$  are in  $\mathcal{O}$ . So we can write  $Z, W$  in the form

$$Z = \sum_{i=1}^n a_i P_i, \quad W = \sum_{i=1}^n b_i P_i$$

where  $a_i$ 's and  $b_i$ 's are real numbers and  $P_i$ 's are mutually orthogonal projections.

By (2.3)

$$\begin{aligned} (2.4) \quad \delta(Z + W) &= \delta \left( \sum_i a_i P_i + \sum_i b_i P_i \right) \\ &= \delta \left( \sum_i (a_i + b_i) P_i \right) = \sum_i (a_i + b_i) \delta(P_i) \\ &= \sum_i a_i \delta(P_i) + \sum_i b_i \delta(P_i) = \delta(Z) + \delta(W). \end{aligned}$$

Let  $X, Y$  be any two commuting elements in  $\mathcal{O}$ . Using spectral theorem we can approximate  $X, Y$  by commuting finite spectrum elements of  $\mathcal{O}$ . By (2.4) and continuity of  $\delta$  we get

$$\delta(X + Y) = \delta(X) + \delta(Y). \quad \square$$

**REMARK 2.2.** In Theorem 2.1 if  $\mathcal{O}$  is finite dimensional then we need not assume that  $\delta$  is continuous.

This is clear from (2.4).

**3. Main result.** Let  $\mathcal{H}$  be a complex separable Hilbert space with inner product  $\langle \cdot | \cdot \rangle$  which is conjugate linear in the first variable and linear in the second variable. For any two vectors  $x, y$  in  $\mathcal{H}$ ,  $|x\rangle\langle y|$  is the operator defined by

$$(3.1) \quad |x\rangle\langle y|z = \langle y, z \rangle x \quad \forall z \in \mathcal{H}.$$

Observe that  $| \cdot \rangle \langle \cdot |$  is linear in the first variable and conjugate linear in the second variable and for any unit vector  $x$ ,  $|x\rangle\langle x|$  is the projection on the one dimensional subspace generated by  $x$ .

Let  $\mathcal{B}(\mathcal{H})$  be the von Neumann algebra of all bounded operators on  $\mathcal{H}$  and  $\mathcal{O}(\mathcal{H})$  be the real linear space of bounded self-adjoint operators on  $\mathcal{H}$ . Let  $\delta: \mathcal{O}(\mathcal{H}) \rightarrow \mathcal{O}(\mathcal{H})$  be a linear map satisfying the condition (1.3), that is,

$$\delta(XY) = X\delta(Y) + \delta(X)Y \quad \forall X, Y \text{ in } \mathcal{O}(\mathcal{H}) \text{ with } [X, Y] = 0.$$

Now we would like to obtain a self-adjoint operator  $H$  such that  $\delta(X) = i[H, X] \quad \forall X \in \mathcal{O}(\mathcal{H})$ . To recover the  $H$  from  $\delta$  we study the action of  $\delta$  on various rank one projections. To avoid trivialities, assume  $\dim \mathcal{H} \geq 3$ .

**LEMMA 3.1.** *Let  $u$  be a unit vector in  $\mathcal{H}$ . Then there is a unique vector  $\varphi(u)$  such that  $\delta(|u\rangle\langle u|) = i(|\varphi(u)\rangle\langle u| - |u\rangle\langle\varphi(u)|)$  and  $\langle u, \varphi(u) \rangle = 0$ . Moreover if  $v$  is a unit vector orthogonal to  $u$  then  $\langle \varphi(u), v \rangle = \langle u, \varphi(v) \rangle$ .*

*Proof.* Let  $u$  be a unit vector in  $\mathcal{H}$ . Define  $\varphi(u)$  by

$$(3.2) \quad \varphi(u) = -i\delta(|u\rangle\langle u|)u.$$

As  $|u\rangle\langle u|$  is a projection we have

$$(3.3) \quad \delta(|u\rangle\langle u|) = \delta(|u\rangle\langle u|)|u\rangle\langle u| + |u\rangle\langle u|\delta(|u\rangle\langle u|)$$

$$= |\delta(|u\rangle\langle u|)u\rangle\langle u| + |u\rangle\langle\delta(|u\rangle\langle u|)u|$$

$$(3.4) \quad = i(|\varphi(u)\rangle\langle u| - |u\rangle\langle\varphi(u)|).$$

To prove the second assertion use (3.3) to get

$$\langle u, \delta(|u\rangle\langle u|)u \rangle = \langle u, \delta(|u\rangle\langle u|)u \rangle + \langle u, \delta(|u\rangle\langle u|)u \rangle.$$

Then

$$\langle u, \delta(|u\rangle\langle u|)u \rangle = 0$$

which implies, by the definition of  $\varphi(u)$ ,

$$(3.5) \quad \langle u, \varphi(u) \rangle = 0.$$

Uniqueness is obvious as whenever  $\langle u, \varphi(u) \rangle = 0$  we have,

$$i(|\varphi(u)\rangle\langle u| - |u\rangle\langle\varphi(u)|)u = i\varphi(u).$$

Again by (1.3)

$$\delta(|u\rangle\langle u|)|v\rangle\langle v| + |u\rangle\langle u|\delta(|v\rangle\langle v|) = 0.$$

Now using the formula (3.4) for  $\delta(|u\rangle\langle u|)$  and  $\delta(|v\rangle\langle v|)$  we get

$$-i\langle\varphi(u), v\rangle|u\rangle\langle v| + i\langle u, \varphi(v)\rangle|u\rangle\langle v| = 0$$

which means

$$\langle\varphi(u), v\rangle = \langle u, \varphi(v)\rangle.$$

□

Analysing the action of  $\delta$  on some more projections we have

**LEMMA 3.2.** *Let  $u$ ,  $v$  and  $w$  be three mutually orthogonal unit vectors in  $\mathcal{H}$ . Then the following equalities hold:*

- (i)  $\langle w, \delta(|u\rangle\langle v| + |v\rangle\langle u|)w \rangle = 0$ ;
- (ii)  $\langle w, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle = i\langle w, \varphi(u) \rangle$ ;
- (iii)  $\operatorname{Re}\langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle = 0$ ;
- (iv)  $\langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)iv \rangle = \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle$ ;
- (v)  $\langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)u \rangle = i\langle u, \varphi(v) \rangle - i\langle v, \varphi(u) \rangle$ ;
- (vi)  $\langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle = \langle u, \delta(|u\rangle\langle w| + |w\rangle\langle u|)w \rangle$   
 $+ \langle w, \delta(|w\rangle\langle v| + |v\rangle\langle w|)v \rangle$ .

*Proof.* By linearity,

$$\delta(|u\rangle\langle v| + |v\rangle\langle u|) = \delta\left(\left|\frac{u+v}{\sqrt{2}}\right\rangle\left\langle\frac{u+v}{\sqrt{2}}\right|\right) - \delta\left(\left|\frac{u-v}{\sqrt{2}}\right\rangle\left\langle\frac{u-v}{\sqrt{2}}\right|\right).$$

Then (i) is obvious. To show (ii) we consider

$$\begin{aligned} & \langle w, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \\ &= \left\langle w, \delta\left(\left|\frac{u+v}{\sqrt{2}}\right\rangle\left\langle\frac{u+v}{\sqrt{2}}\right|\right)v \right\rangle \\ & \quad - \left\langle w, \delta\left(\left|\frac{u-v}{\sqrt{2}}\right\rangle\left\langle\frac{u-v}{\sqrt{2}}\right|\right)v \right\rangle \\ &= \frac{i}{\sqrt{2}} \left\langle w, \varphi\left(\frac{u+v}{\sqrt{2}}\right) \right\rangle + \frac{i}{\sqrt{2}} \left\langle w, \varphi\left(\frac{u-v}{\sqrt{2}}\right) \right\rangle \\ &= \frac{i}{\sqrt{2}} \left\langle \varphi(w), \frac{u+v}{\sqrt{2}} \right\rangle + \frac{i}{\sqrt{2}} \left\langle \varphi(w), \frac{u-v}{\sqrt{2}} \right\rangle \\ &= i\langle \varphi(w), u \rangle = i\langle w, \varphi(u) \rangle. \end{aligned}$$

By (3.5)

$$\left\langle \varphi\left(\frac{u+v}{\sqrt{2}}\right), \frac{u+v}{\sqrt{2}} \right\rangle = 0 \quad \text{and} \quad \left\langle \varphi\left(\frac{u-v}{\sqrt{2}}\right), \frac{u-v}{\sqrt{2}} \right\rangle = 0.$$

Making use of these equalities we obtain

$$\begin{aligned} & \left\langle u, \delta\left(\left|\frac{u+v}{\sqrt{2}}\right\rangle\left\langle\frac{u+v}{\sqrt{2}}\right|\right)v \right\rangle \\ &= \frac{i}{\sqrt{2}} \left\langle u, \varphi\left(\frac{u+v}{\sqrt{2}}\right) \right\rangle - \frac{i}{\sqrt{2}} \left\langle \varphi\left(\frac{u+v}{\sqrt{2}}\right), v \right\rangle \\ &= \frac{i}{\sqrt{2}} \left\langle u, \varphi\left(\frac{u+v}{\sqrt{2}}\right) \right\rangle + \frac{i}{\sqrt{2}} \left\langle \varphi\left(\frac{u+v}{\sqrt{2}}\right), u \right\rangle \\ &= i\sqrt{2} \operatorname{Re} \left\langle u, \varphi\left(\frac{u+v}{\sqrt{2}}\right) \right\rangle \end{aligned}$$

and

$$\begin{aligned}
& \left\langle u, \delta \left( \left| \frac{u-v}{\sqrt{2}} \right\rangle \left\langle \frac{u-v}{\sqrt{2}} \right| \right) v \right\rangle \\
&= \frac{-i}{\sqrt{2}} \left\langle u, \varphi \left( \frac{u-v}{\sqrt{2}} \right) \right\rangle - \frac{i}{\sqrt{2}} \left\langle \varphi \left( \frac{u-v}{\sqrt{2}} \right), v \right\rangle \\
&= \frac{-i}{\sqrt{2}} \left\langle u, \varphi \left( \frac{u-v}{\sqrt{2}} \right) \right\rangle - \frac{i}{\sqrt{2}} \left\langle \varphi \left( \frac{u-v}{\sqrt{2}} \right), u \right\rangle \\
&= -i\sqrt{2} \operatorname{Re} \left\langle u, \varphi \left( \frac{u-v}{\sqrt{2}} \right) \right\rangle.
\end{aligned}$$

So (iii) follows.

In order to show (iv) define the projection,

$$P_1 = \left| \frac{u}{\sqrt{2}} + \left( \frac{1+i}{2} \right) v \right\rangle \left\langle \frac{u}{\sqrt{2}} + \left( \frac{1+i}{2} \right) v \right|.$$

It is clear that

$$\begin{aligned}
(3.6) \quad \langle u, \delta(P_1)v \rangle &= \frac{1}{2} \langle u, \delta(|u\rangle\langle u|)v \rangle + \frac{1}{2} \langle u, \delta(|v\rangle\langle v|)v \rangle \\
&\quad + \frac{1}{2\sqrt{2}} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \\
&\quad + \frac{1}{2\sqrt{2}} \langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)v \rangle \\
&= \frac{-i}{2} \langle u, \varphi(v) \rangle + \frac{i}{2} \langle u, \varphi(v) \rangle \\
&\quad + \frac{1}{2\sqrt{2}} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \\
&\quad + \frac{(-i)}{2\sqrt{2}} \langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)iv \rangle \\
&= \frac{1}{2\sqrt{2}} \{ \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \\
&\quad - i \langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)iv \rangle \}.
\end{aligned}$$

As  $P_1$  is a projection we have

$$\begin{aligned}
\langle u, \delta(P_1)u \rangle &= \langle u, \delta(P_1)P_1u \rangle + \langle u, P_1\delta(P_1)u \rangle \\
&= 2 \operatorname{Re} \langle u, \delta(P_1)P_1u \rangle \\
&= 2 \operatorname{Re} \left\{ \frac{1}{\sqrt{2}} \left\langle u, \delta(P_1) \left( \frac{u}{\sqrt{2}} + \left( \frac{1+i}{2} \right) v \right) \right\rangle \right\} \\
&= \langle u, \delta(P_1)u \rangle + \sqrt{2} \operatorname{Re} \left\langle u, \delta(P_1) \left( \frac{1+i}{2} \right) v \right\rangle.
\end{aligned}$$



This means

$$\operatorname{Re}(1+i)\langle u, \delta(P_1)v \rangle = 0.$$

Then from earlier computation (3.6)

$$\operatorname{Re}(1+i)\{\langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle - i\langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)iv \rangle\} = 0$$

and from (iii)

$$\begin{aligned} \operatorname{Re}\{\langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle\} &= 0, \\ \operatorname{Re}\{\langle u, \delta(|u\rangle\langle iv| + |iv\rangle\langle u|)iv \rangle\} &= 0; \end{aligned}$$

combining these we obtain (iv).

In order to show (v) define the projection

$$P_2 = \left| \frac{u}{2} + \frac{\sqrt{3}}{2}v \right\rangle \left\langle \frac{u}{2} + \frac{\sqrt{3}}{2}v \right|.$$

Evidently,

$$\begin{aligned} (3.7) \quad \langle u, \delta(P_2)u \rangle &= \left\langle u, \delta \left( \left| \frac{u}{2} + \frac{\sqrt{3}}{2}v \right\rangle \left\langle \frac{u}{2} + \frac{\sqrt{3}}{2}v \right| \right) u \right\rangle \\ &= \frac{\sqrt{3}}{4} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \end{aligned}$$

and

$$\begin{aligned} \langle u, \delta(P_2)P_2u \rangle &= \frac{1}{2} \left\langle u, \delta(P_2) \left( \frac{u}{2} + \frac{\sqrt{3}}{2}v \right) \right\rangle \\ &= \frac{1}{4} \langle u, \delta(P_2)u \rangle \\ &\quad + \frac{\sqrt{3}}{4} \left\{ \frac{1}{4} \langle u, \delta(|u\rangle\langle u|)v \rangle + \frac{3}{4} \langle u, \delta(|v\rangle\langle v|)v \rangle \right. \\ &\quad \left. + \frac{\sqrt{3}}{4} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \right\} \\ &= \frac{1}{4} \langle u, \delta(P_2)u \rangle \\ &\quad + \frac{\sqrt{3}}{4} \left\{ \left( \frac{-i}{4} \right) \langle u, \varphi(v) \rangle + \frac{3i}{4} \langle u, \varphi(v) \rangle \right. \\ &\quad \left. + \frac{\sqrt{3}}{4} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle \right\}. \end{aligned}$$

So by (iii)

$$\begin{aligned} (3.8) \quad 2 \operatorname{Re}\langle u, \delta(P_2)P_2u \rangle &= \frac{1}{2} \langle u, \delta(P_2)u \rangle \\ &\quad + \frac{\sqrt{3}}{8} \{i\langle u, \varphi(v) \rangle - i\langle v, \varphi(u) \rangle\}. \end{aligned}$$

But by (3.7)

$$(3.9) \quad \begin{aligned} 2 \operatorname{Re}\langle u, \delta(P_2)P_2u \rangle &= \langle u, \delta(P_2)u \rangle \\ &= \frac{\sqrt{3}}{4} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle. \end{aligned}$$

Combining (3.8) and (3.9) we get (v).

The relation (vi) is obtained in a similar way by considering the projection

$$P_3 = \left| \frac{u+v+w}{\sqrt{3}} \right\rangle \left\langle \frac{u+v+w}{\sqrt{3}} \right|$$

and the equation

$$\langle u, \delta(P_3)v \rangle = \langle u, \delta(P_3)P_3v \rangle + \langle P_3u, \delta(P_3)v \rangle. \quad \square$$

Now we would like to exploit the linearity of  $\delta$  by considering unit vectors of the form  $cu + dv$  for some complex numbers  $c$  and  $d$ . For this purpose we extend Lemma 3.2 to get

**LEMMA 3.3.** *Let  $u, v$  and  $w$  be three mutually orthogonal unit vectors in  $\mathcal{H}$ . Let  $c$  and  $d$  be any two complex numbers. Then we have the following relations:*

- (i)  $\langle w, \delta(|cu\rangle\langle dv| + |dv\rangle\langle cu|)w \rangle = 0$ ;
- (ii)  $\langle w, \delta(|cu\rangle\langle dv| + |dv\rangle\langle cu|)v \rangle = \overline{cd}i \langle w, \varphi(u) \rangle$ ;
- (iii)  $\langle u, \delta(|cu\rangle\langle dv| + |dv\rangle\langle cu|)v \rangle = \overline{cd} \langle u, \delta(|u\rangle\langle v| + |v\rangle\langle u|)v \rangle$ ;
- (iv)  $\langle u, \delta(|cu\rangle\langle dv| + |dv\rangle\langle cu|)u \rangle = \overline{cd}i \langle u, \varphi(v) \rangle - cd i \langle v, \varphi(u) \rangle$ .

*Proof.* Write  $c, d$  in  $\mathbb{C}$  as

$$\begin{aligned} c &= c_1 + ic_2, & c_1, c_2 &\in \mathbb{R}, \\ d &= d_1 + id_2, & d_1, d_2 &\in \mathbb{R}. \end{aligned}$$

Then we have

$$\begin{aligned} \delta(|cu\rangle\langle dv| + |dv\rangle\langle cu|) &= (c_1d_1 + c_2d_2)\delta(|u\rangle\langle v| + |v\rangle\langle u|) \\ &\quad + (c_1d_2 - c_2d_1)\delta(|u\rangle\langle iv| + |iv\rangle\langle u|). \end{aligned}$$

Now note that  $(iv)$  is also a unit vector orthogonal to  $u$  and  $w$ . Then the result is immediate from Lemma 3.2 and linearity of  $\delta$ .  $\square$

Now we are ready to recover  $H$  from  $\delta$ . Note that if  $\delta(X) = i[H, X]$  for every  $X$  in  $\mathcal{O}(\mathcal{H})$  then for any real number  $a$  we have  $\delta(X) = i[H + aI, X]$ . This nonuniqueness of  $H$  is taken care of

by insisting  $\langle u_0, Hu_0 \rangle = 0$  for some fixed unit vector  $u_0$  in  $\mathcal{H}$ . So choose and fix a unit vector  $u_0$  in  $\mathcal{H}$ . Define  $H : \mathcal{H} \rightarrow \mathcal{H}$  by

$$(3.10) \quad \begin{aligned} Hu_0 &= -i\delta(|u_0\rangle\langle u_0|)u_0 = \varphi(u_0), \\ Hv &= -i\delta(|v\rangle\langle v|)v + i\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v \rangle v \\ &\quad \text{for } v \in \mathcal{H} \text{ with } \langle v, u_0 \rangle = 0 \text{ and } \|v\| = 1. \\ H(au_0 + z) &= aHu_0 + \|z\|H\left(\frac{z}{\|z\|}\right) \\ &\quad \text{for } a \in \mathbb{C} \text{ and } z \in \mathcal{H} \text{ with } \langle z, u_0 \rangle = 0. \end{aligned}$$

Note that we do have  $\langle u_0, Hu_0 \rangle = 0$ . We use Lemma 3.2 and Lemma 3.3 to obtain the linearity of  $H$ .

LEMMA 3.4. *The map  $H$  defined above in (3.10) is linear.*

*Proof.* Let  $v, w$  be mutually orthogonal unit vectors in  $\mathcal{H}$  which are also orthogonal to  $u_0$ . Let  $z$  be a vector in  $\mathcal{H}$  orthogonal to  $v$  and  $w$ . Let  $c, d$  be any two complex numbers. Then we show

$$(3.11) \quad \langle v, H(cv + dw) \rangle = c\langle v, Hv \rangle + d\langle v, Hw \rangle$$

and

$$(3.12) \quad \langle z, H(cv + dw) \rangle = c\langle z, Hv \rangle + d\langle z, Hw \rangle.$$

From these linearity of  $H$  follows. From the definition of  $H$ ,

$$\begin{aligned} H(iv) &= -i\delta(|iv\rangle\langle iv|)iv + i\langle u_0, \delta(|u_0\rangle\langle iv| + |iv\rangle\langle u_0|)iv \rangle iv \\ &= i\{-i\delta(|v\rangle\langle v|)v + i\langle u_0, \delta(|u_0\rangle\langle iv| + |iv\rangle\langle u_0|)iv \rangle v\}. \end{aligned}$$

By (iv) of Lemma 3.2 we get  $H(iv) = iHv$ .

Now a simple computation shows that  $H(ax) = aHx$  for any complex number  $a$  and any vector  $x$ . So without loss of generality we can assume  $|c|^2 + |d|^2 = 1$ , while showing (3.11) and (3.12). As  $(cv + dw)$  is now a unit vector, we have

$$(3.13) \quad \begin{aligned} \langle v, H(cv + dw) \rangle &= -i\langle v, \delta(|cv + dw\rangle\langle cv + dw|)(cv + dw) \rangle \\ &\quad + ic\langle u_0, \delta(|u_0\rangle\langle cv + dw| + |cv + dw\rangle\langle u_0|)(cv + dw) \rangle \\ &= S_1 + S_2 \quad (\text{say}). \end{aligned}$$

Linearity of  $\delta$  implies

$$\begin{aligned} S_1 &= (-i)\{d|c|^2\langle v, \delta(|v\rangle\langle v|)w \rangle + d|d|^2\langle v, \delta(|w\rangle\langle w|)w \rangle \\ &\quad + c\langle v, \delta(|cv\rangle\langle dw| + |dw\rangle\langle cv|)v \rangle \\ &\quad + d\langle v, \delta(|cv\rangle\langle dw| + |dw\rangle\langle cv|)w \rangle\}. \end{aligned}$$

Using (3.4) in the first two terms and (iv) and (iii) of Lemma 3.3 in the next two terms we get

$$\begin{aligned}
S_1 &= (-i)\{d|c|^2(-i)\langle\varphi(v), w\rangle + d|d|^2(i)\langle\varphi(v), w\rangle \\
&\quad + c\bar{c}d i\langle\varphi(v), w\rangle - c\bar{c}\bar{d}i\langle\varphi(w), v\rangle \\
&\quad + d\bar{c}\bar{d}\langle v, \delta(|v\rangle\langle w| + |w\rangle\langle v|)w\rangle\} \\
&= (-i)\{d|d|^2(i)\langle\varphi(v), w\rangle - c^2\bar{d}(i)\langle\varphi(w), v\rangle \\
&\quad + c|d|^2\langle v, \delta(|v\rangle\langle w| + |w\rangle\langle v|)w\rangle\}, \\
S_2 &= ic\{c\langle u_0, \delta(|u_0\rangle\langle dw| + |dw\rangle\langle u_0|)v\rangle \\
&\quad + d\langle u_0, \delta(|u_0\rangle\langle cv| + |cv\rangle\langle u_0|)w\rangle \\
&\quad + c\langle u_0, \delta(|u_0\rangle\langle cv| + |cv\rangle\langle u_0|)v\rangle \\
&\quad + d\langle u_0, \delta(|u_0\rangle\langle dw| + |dw\rangle\langle u_0|)w\rangle\}.
\end{aligned}$$

Using (ii) of Lemma 3.3 in the first two terms and (iii) of Lemma 3.3 in the last two terms we obtain

$$\begin{aligned}
S_2 &= ic\{c\bar{d}(-i)\langle\varphi(w), v\rangle + \bar{c}d(-i)\langle\varphi(v), w\rangle \\
&\quad + |c|^2\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle \\
&\quad + |d|^2\langle u_0, \delta(|u_0\rangle\langle w| + |w\rangle\langle u_0|)w\rangle\}.
\end{aligned}$$

Now coming back to (3.13) we have

$$\begin{aligned}
\langle v, H(cv + dw)\rangle &= S_1 + S_2 \\
&= d(|d|^2 + |c|^2)\langle\varphi(v), w\rangle \\
&\quad + (-i)c|d|^2\langle v, \delta(|v\rangle\langle w| + |w\rangle\langle v|)w\rangle \\
&\quad + ic|c|^2\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle \\
&\quad + ic|d|^2\langle u_0, \delta(|u_0\rangle\langle w| + |w\rangle\langle u_0|)w\rangle.
\end{aligned}$$

(iii) and (vi) of Lemma 3.2 imply

$$\begin{aligned}
\langle v, H(cv + dw)\rangle &= d\langle\varphi(v), w\rangle + ic|d|^2\langle w, \delta(|w\rangle\langle v| + |v\rangle\langle w|)v\rangle \\
&\quad + ic|c|^2\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle \\
&\quad + ic|d|^2\langle u_0, \delta(|u_0\rangle\langle w| + |w\rangle\langle u_0|)w\rangle \\
&= d\langle\varphi(v), w\rangle + ic(|c|^2 + |d|^2)\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle \\
&= d\langle\varphi(v), w\rangle + ic\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle \\
&= d\langle v, Hw\rangle + c\langle v, Hv\rangle.
\end{aligned}$$

This proves (3.11). To show (3.12) we consider

$$\begin{aligned} \langle z, H(cv + dw) \rangle &= (-i)\langle z, \delta(|cv + dw\rangle\langle cv + dw|)(cv + dw) \rangle \\ &= (-i)\{c|c|^2\langle z, \delta(|v\rangle\langle v|)v \rangle + d|d|^2\langle z, \delta(|w\rangle\langle w|)w \rangle \\ &\quad + c\langle z, \delta(|cv\rangle\langle dw| + |dw\rangle\langle cv|)v \rangle \\ &\quad + d\langle z, \delta(|cv\rangle\langle dw| + |dw\rangle\langle cv|)w \rangle\}. \end{aligned}$$

Then use (3.4) in the first two terms and (ii) of Lemma 3.3 in the last two terms to obtain

$$\begin{aligned} \langle z, H(cv + dw) \rangle &= (-i)\{c|c|^2i\langle z, \varphi(v) \rangle + d|d|^2i\langle z, \varphi(w) \rangle \\ &\quad + c\bar{c}di\langle z, \varphi(w) \rangle + d\bar{c}i\langle z, \varphi(v) \rangle\} \\ &= (-i)\{ci\langle z, \varphi(v) \rangle + di\langle z, \varphi(w) \rangle\} \\ &= c\langle z, Hv \rangle + d\langle z, Hw \rangle. \quad \square \end{aligned}$$

Now we are ready to prove our main result.

**THEOREM 3.5.** *Let  $\mathcal{H}$  be a complex separable Hilbert space. Let  $\mathcal{O}(\mathcal{H})$  be the real linear space of all bounded self-adjoint operators on  $\mathcal{H}$ . If  $\delta : \mathcal{O}(\mathcal{H}) \rightarrow \mathcal{O}(\mathcal{H})$  is a continuous linear map satisfying*

$$\delta(XY) = X\delta(Y) + \delta(X)Y \quad \forall X, Y \text{ in } \mathcal{O}(\mathcal{H}) \text{ with } [X, Y] = 0.$$

Define  $H : \mathcal{H} \rightarrow \mathcal{H}$  by

$$\begin{aligned} H(au_0 + bv) &= a(-i)\delta(|u_0\rangle\langle u_0|)u_0 \\ &\quad + b\{-i\delta(|v\rangle\langle v|)v + i\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v \rangle v\} \end{aligned}$$

for a fixed unit vector  $u_0$  in  $\mathcal{H}$  and  $a, b \in \mathbb{C}$ ,  $v \in \mathcal{H}$  with  $\langle v, v \rangle = 1$  and  $\langle v, u_0 \rangle = 0$ . Then  $H$  is a bounded self-adjoint operator on  $\mathcal{H}$  satisfying

$$\delta(X) = i[H, X] \quad \forall X \in \mathcal{O}(\mathcal{H}).$$

*Proof.* We have already shown that  $H$  is linear. For any unit vector  $v$  we have

$$\langle v, Hv \rangle = i\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v \rangle.$$

(iii) of Lemma 3.2 implies

$$\langle v, Hv \rangle \in \mathbb{R}.$$

As  $H$  is defined on the whole of  $\mathcal{H}$  we conclude that  $H$  is a bounded self-adjoint operator. It remains to show that

$$\delta(X) = i[H, X] \quad \forall X \in \mathcal{O}(\mathcal{H}).$$

First, we prove this for rank one projections, then for all projections and finally use the continuity of  $\delta$  to prove the result for all  $X$  in  $\mathcal{O}(\mathcal{H})$ . It is clear that if  $X = |v\rangle\langle v|$  is a rank one projection, then

$$\begin{aligned}
i[H, X] &= i[H, |v\rangle\langle v|] \\
&= i(|Hv\rangle\langle v| - |v\rangle\langle Hv|) \\
&= i\{(-i)\delta(|v\rangle\langle v|)v\}\langle v| + i\{\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\}\}|v\rangle\langle v| \\
&\quad - |v\rangle\langle(-i)\delta(|v\rangle\langle v|)v| \\
&\quad\quad\quad + (-i)\langle u_0, \delta(|u_0\rangle\langle v| + |v\rangle\langle u_0|)v\rangle|v\rangle\langle v| \\
&= i(|\varphi(v)\rangle\langle v| - |v\rangle\langle\varphi(v)|) \\
&= \delta(|v\rangle\langle v|).
\end{aligned}$$

Let  $P$  be a projection and  $v$  be a unit vector in the range of  $P$ . We have

$$\begin{aligned}
P|v\rangle\langle v| &= |v\rangle\langle v|P = |v\rangle\langle v|, \\
\delta(|v\rangle\langle v|) &= \delta(P)|v\rangle\langle v| + P\delta(|v\rangle\langle v|).
\end{aligned}$$

Applying on  $v$  and using  $g(|v\rangle\langle v|) = i[H, |v\rangle\langle v|]$  we have

$$\begin{aligned}
i[H, |v\rangle\langle v|]v &= \delta(P)v + P(i[H, |v\rangle\langle v|])v, \\
iHv - i\langle Hv, v\rangle v &= \delta(P)v + iPHv - i\langle Hv, v\rangle v.
\end{aligned}$$

So

$$(3.14) \quad \delta(P)v = iHv - iPHv = iHPv - iPHv = i[H, P]v.$$

On the other hand if  $w$  is a unit vector orthogonal to the range of  $P$ ,

$$P|w\rangle\langle w| = |w\rangle\langle w|P = 0.$$

So

$$\begin{aligned}
\delta(P)(|w\rangle\langle w|) + P(\delta(|w\rangle\langle w|)) &= 0, \\
\delta(P)(|w\rangle\langle w|) + P(i[H, |w\rangle\langle w|]) &= 0, \\
|\delta(P)w\rangle\langle w| + i|PHw\rangle\langle w| &= 0.
\end{aligned}$$

This means

$$\begin{aligned}
\langle w, w\rangle\delta(P)w + \langle w, w\rangle iPHw &= 0, \\
(3.15) \quad \delta(P)w &= -iPHw = iHPw - iPHw = i[H, P]w.
\end{aligned}$$

Combining (3.14) and (3.15)  $\delta(P) = i[H, P]$ . That is  $\delta(X) = i[H, X]$  whenever  $X$  is a projection. By linearity  $\delta(X) = i[H, X]$  whenever  $X$  is a finite linear combination of projections. Now an application of the spectral theorem combined with the continuity of  $\delta$  completes the proof.  $\square$

The proof in [1] of the fact that every derivation on a  $C^*$  algebra is bounded can be imitated to show that every linear velocity map is continuous. So we have

**REMARK 3.6.** Theorem 3.5 is true even without the assumption of continuity of  $\delta$ .

Let  $\mathcal{O}_1, \mathcal{O}_2$  be the spaces of self-adjoint elements of von Neumann algebras  $\mathcal{A}_1, \mathcal{A}_2$  respectively. Then  $\mathcal{O}_1 \oplus \mathcal{O}_2$  is the space of self-adjoint elements of the von Neumann algebra  $\mathcal{A}_1 \oplus \mathcal{A}_2$ . If  $\delta$  is a linear velocity map on  $\mathcal{O}_1 \oplus \mathcal{O}_2$  then we can write  $\delta$  as  $\delta_1 \oplus \delta_2$  where  $\delta_1$  and  $\delta_2$  are linear velocity maps on  $\mathcal{O}_1, \mathcal{O}_2$  respectively. If  $\delta_1$  and  $\delta_2$  are inner in the sense  $\delta_1(X) = i[H_1, X]$  for some  $H_1$  in  $\mathcal{O}_1$  and  $\delta_2(Y) = i[H_2, Y]$  for some  $H_2$  in  $\mathcal{O}_2$ , where  $X, Y$  are elements of  $\mathcal{O}_1, \mathcal{O}_2$  respectively then  $\delta$  is also inner as we have

$$\delta(X \oplus Y) = i[H_1 \oplus H_2, X \oplus Y].$$

As a corollary we have the following generalisation of Theorem 3.5.

**THEOREM 3.7.** *Let  $\mathcal{A}$  be a subalgebra with identity of  $M_n(\mathbb{C})$  for some natural number  $n$ . If  $\delta$  is a linear velocity map on the space  $\mathcal{O}$  of all self-adjoint elements in  $\mathcal{A}$ , then  $\delta(X) = i[H, X]$   $X \in \mathcal{O}$ , for some  $H$  in  $\mathcal{O}$ .*

*Proof.* This is clear from the discussion above as  $\mathcal{A}$  is isomorphic to  $M_{n_1}(\mathbb{C}) \oplus M_{n_2}(\mathbb{C}) \oplus \dots \oplus M_{n_k}(\mathbb{C})$  for some natural numbers  $n_1, n_2, \dots, n_k$  and we can use Theorem 3.5.  $\square$

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