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A CLASS OF PRIMARY REPRESENTATIONS ASSOCIATED WITH SYMMETRIC PAIRS AND RESTRICTED ROOT SYSTEMS

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Let $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$ be a representation of a complex reductive Lie algebra \mathfrak{r} on a complex vector space \mathfrak{p} . Assume that ν is the complexified differential of an orthogonal representation of a compact Lie group R . Then the exterior algebra $\bigwedge \mathfrak{p}$ becomes an \mathfrak{r} -module by extending ν . Let $\text{Spin } \nu : \mathfrak{r} \rightarrow \text{End } S$ be the composition of ν with the spin representation $\text{Spin} : \mathfrak{so}(\mathfrak{p}) \rightarrow \text{End } S$. We completely classify the representations ν for which the corresponding $\text{Spin } \nu$ representation is primary, give a description of the \mathfrak{r} -module structure of $\bigwedge \mathfrak{p}$, and present a decomposition of the Clifford algebra over \mathfrak{p} . It turns out that, if the $\text{Spin } \nu$ representation is primary, ν must be an isotropy representation of some symmetric pair. Our work generalizes Kostant's well-known results that dealt with the special case when ν is the adjoint representation of a semisimple Lie algebra. In the proof we introduce the "restricted" root system of a real semisimple Lie algebra, which is of independent interest.

1. Introduction

Let R be a compact Lie group. Let \mathfrak{p} be a finite-dimensional complex vector space with a nonsingular symmetric bilinear form $B_{\mathfrak{p}}$, and $C(\mathfrak{p})$ be the Clifford algebra over \mathfrak{p} with respect to $B_{\mathfrak{p}}$. Assume that $\nu : R \rightarrow \text{SO}(\mathfrak{p})$ is a $B_{\mathfrak{p}}$ -orthogonal representation of R on \mathfrak{p} . Let \mathfrak{r} be the complexified Lie algebra of R . We use ν also to denote $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$, the complexified differential of the representation of R on \mathfrak{p} . In particular, \mathfrak{r} is reductive and ν is completely reducible. Let

$$\beta : \mathfrak{r} \rightarrow \text{End } \bigwedge \mathfrak{p}$$

be the derivation extension of ν . Let

$$\text{Spin } \nu : \mathfrak{r} \rightarrow \text{End } S$$

be the composition of ν with the spin representation $\text{Spin} : \mathfrak{so}(\mathfrak{p}) \rightarrow \text{End } S$. When the representation $\text{Spin } \nu$ is primary of type π_{λ} , where $\pi_{\lambda} : \mathfrak{r} \rightarrow \text{End } V_{\lambda}$ is the

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irreducible representation of \mathfrak{t} with highest weight λ , then, given the well-known relation between $\bigwedge \mathfrak{p}$ and $S \otimes S$, we have

$$(1-1) \quad \bigwedge \mathfrak{p} \cong 2^l V_\lambda \otimes V_\lambda^*$$

as \mathfrak{t} -modules, for some nonnegative integer l . One also has an algebra isomorphism

$$(1-2) \quad C(\mathfrak{p}) \cong (\text{End } V_\lambda) \otimes J,$$

where $J = (\bigwedge \mathfrak{p})^\mathfrak{t}$, the space of \mathfrak{t} -invariants in $\bigwedge \mathfrak{p}$, is isomorphic to a matrix algebra if l is even, and is isomorphic to a sum of two matrix algebras if l is odd. See [Kostant 1997, Proposition 20].

In view of Equations (1-1) and (1-2), it is thus interesting to classify the representation ν such that $\text{Spin } \nu$ is primary, which is the main result of this paper. Many people are interested in the special case where ν is the adjoint representation of a semisimple complex Lie algebra \mathfrak{g} on itself. The study of an important graded submodule C of $\bigwedge \mathfrak{g}$ can be found in [Kostant 2000; 1965]. The well-known result that the representation $\text{Spin } \nu$ is primary of type π_ρ , where ρ is half the sum of the positive roots, was first given in [Kostant 1961]. Then the \mathfrak{g} -module structure of the exterior algebra $\bigwedge \mathfrak{g}$ is given by $\bigwedge \mathfrak{g} \cong 2^l V_\rho \otimes V_\rho$, where l is the rank of \mathfrak{g} . The Clifford algebra $C(\mathfrak{g})$ over \mathfrak{g} decomposes into the Clifford product

$$C(\mathfrak{g}) \cong (\text{End } V_\rho) \otimes J,$$

where the space $J = (\bigwedge \mathfrak{g})^\mathfrak{g}$ has dimension 2^l and has a Clifford algebra structure over some subspace of itself.

In this paper we classify the representations ν such that the corresponding $\text{Spin } \nu$ is primary, and study the \mathfrak{t} -module structure of $\bigwedge \mathfrak{p}$ under the condition that $\text{Spin } \nu$ be primary. Our work generalizes the above results of Kostant's in the case of adjoint representations.

Recall that a Lie subalgebra \mathfrak{k} of a Lie algebra \mathfrak{g} is called a *symmetric Lie subalgebra* if there exists an involutory automorphism θ of \mathfrak{g} such that \mathfrak{k} is the set of θ -invariants in \mathfrak{g} . In this case we call $(\mathfrak{k}, \mathfrak{g})$ a *symmetric pair*, and call the representation of \mathfrak{k} on $\mathfrak{p} \cong \mathfrak{g}/\mathfrak{k}$ the *isotropy representation* of $(\mathfrak{k}, \mathfrak{g})$. It is surprising to us that if $\text{Spin } \nu$ is primary then ν must be the isotropy representation of some symmetric pair; see Proposition 2.4. Then, in order to classify the primary $\text{Spin } \nu$ representations, we need only consider isotropy representations of symmetric pairs.

Let \mathfrak{g}_0 be a noncompact real semisimple Lie algebra and $\mathfrak{g}_0 = \mathfrak{k}_0 \oplus \mathfrak{p}_0$ be a Cartan decomposition. Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be its complexification and θ the corresponding involutory automorphism of \mathfrak{g} . Let $\mathfrak{h}_0 = \mathfrak{t}_0 \oplus \mathfrak{a}_0$ be a fundamental Cartan subalgebra of \mathfrak{g}_0 , where \mathfrak{t}_0 is a Cartan subalgebra of \mathfrak{k}_0 and $\mathfrak{a}_0 = \mathfrak{p}_0^{\mathfrak{t}_0}$, the centralizer of \mathfrak{t}_0 in \mathfrak{p}_0 . Let $\mathfrak{h} = \mathfrak{t} \oplus \mathfrak{a}$ be its complexification. Let $l_0 = \dim \mathfrak{a}$ and $r_0 = \frac{1}{2} \dim \mathfrak{p}/\mathfrak{a}$, which

will be shown to be an integer. For a complex vector space V , we will always use $\dim V$ to denote its complex dimension.

Let $\Delta(\mathfrak{g}, \mathfrak{h}) \subset \mathfrak{h}^*$ be the system of roots of \mathfrak{g} with respect to \mathfrak{h} , and let $\mathfrak{h}_{\mathbb{R}}^*$ be the real span of the roots in $\Delta(\mathfrak{g}, \mathfrak{h})$. Usually “restricted roots” refers to the roots of \mathfrak{g}_0 with respect to a maximal abelian subspace of \mathfrak{p}_0 , but in this paper, by abuse of language, we will call the roots of \mathfrak{g} with respect to \mathfrak{t} the *restricted roots*, and denote their set by $\Delta(\mathfrak{g}, \mathfrak{t})$. Let $\mathfrak{t}_{\mathbb{R}}^*$ be the real span of the roots in $\Delta(\mathfrak{g}, \mathfrak{t})$, which can be naturally identified with a subspace of $\mathfrak{h}_{\mathbb{R}}^*$. The restriction $B_{\mathfrak{g}}|_{\mathfrak{h}}$ of the Killing form $B_{\mathfrak{g}}$ of \mathfrak{g} is nonsingular and induces a symmetric nonsingular bilinear form $B_{\mathfrak{h}^*}$ on \mathfrak{h}^* . Because $B_{\mathfrak{h}^*}$ is positive definite on $\mathfrak{h}_{\mathbb{R}}^*$, it is also positive definite on $\mathfrak{t}_{\mathbb{R}}^*$. We will prove in Proposition 3.1 that *the set $\Delta(\mathfrak{g}, \mathfrak{t})$ of restricted roots is a (maybe nonreduced) root system in $\mathfrak{t}_{\mathbb{R}}^*$.*

In this paper we call $\Delta(\mathfrak{g}, \mathfrak{t})$ the *restricted root system* of \mathfrak{g}_0 , which is independent of the \mathfrak{t}_0 chosen. Let $\Delta(\mathfrak{k}, \mathfrak{t})$ be the system of roots of \mathfrak{k} with respect to \mathfrak{t} . Let $\Delta^+(\mathfrak{g}, \mathfrak{h})$ be a θ -stable positive root system in $\Delta(\mathfrak{g}, \mathfrak{h})$. Let Γ be the Dynkin diagram of $\Delta^+(\mathfrak{g}, \mathfrak{h})$. Then the involutory automorphism θ acts on Γ naturally, and we get a pair (Γ, θ) . The Dynkin diagram Γ' of $\Delta(\mathfrak{g}, \mathfrak{t})$ is completely determined by (Γ, θ) . When \mathfrak{g} is simple and θ is not the identity on Γ , we can get Γ' from Γ easily; see Figure 1. These results suggest that the restricted root system $\Delta(\mathfrak{g}, \mathfrak{t})$ plays an important role in the structure of a real semisimple Lie algebra and deserves more attention.

There is an important result on the structure of the representation $\text{Spin } \nu$, where ν is the isotropy representation of a symmetric pair; see [Wallach 1988, Lemma 9.3.2]. We restate this result in terms of $\Delta(\mathfrak{k}, \mathfrak{t})$ and the restricted root system $\Delta(\mathfrak{g}, \mathfrak{t})$ in Lemma 4.3, which reduces the problem of classification a lot. Then we first deal with the case when \mathfrak{g} is simple. It is interesting that, for each connected Dynkin diagram with a nontrivial involutory automorphism, there is exactly one symmetric pair such that $\text{Spin } \nu$ is primary; see Proposition 4.7. Next we deal with the general case when \mathfrak{g} is semisimple, and finish the classification completely in Theorem 4.13.

Let $\Delta^+(\mathfrak{k}, \mathfrak{t})$ be a positive root system of $\Delta(\mathfrak{k}, \mathfrak{t})$. Choose $\Delta^+(\mathfrak{g}, \mathfrak{t})$ to be a positive root system of $\Delta(\mathfrak{g}, \mathfrak{t})$ that contains $\Delta^+(\mathfrak{k}, \mathfrak{t})$. Define ρ_n to be half the sum of roots in $\Delta^+(\mathfrak{g}, \mathfrak{t}) \setminus \Delta^+(\mathfrak{k}, \mathfrak{t})$. Combining Proposition 2.4 and Theorem 4.13, we get our main result, Theorem 4.14:

Theorem. *Assume that $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$ is the complexified differential of a faithful $B_{\mathfrak{p}}$ -orthogonal representation of a compact Lie group and that $\mathfrak{p}^{\mathfrak{r}} = 0$, where $\mathfrak{p}^{\mathfrak{r}}$ are the \mathfrak{r} -invariants in \mathfrak{p} . Assume that $\text{Spin } \nu$ is primary. Then $\mathfrak{g} = \mathfrak{r} \oplus \mathfrak{p}$ has a semisimple Lie algebra structure such that \mathfrak{r} is a Lie subalgebra of \mathfrak{g} , that $(\mathfrak{r}, \mathfrak{g})$ is a reduced symmetric pair, and that ν is the isotropy representation of $(\mathfrak{r}, \mathfrak{g})$.*

The symmetric pair $(\mathfrak{r}, \mathfrak{g})$ must be one of the following:

- (1) $(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{sl}(2n+1, \mathbb{C}))$, $n \geq 1$;
 $(\mathfrak{sp}(n, \mathbb{C}), \mathfrak{sl}(2n, \mathbb{C}))$, $n \geq 2$;
 $(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{so}(2n+2, \mathbb{C}))$, $n \geq 3$;
 (F_4, E_6) ;
- (2) $\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_1$ and $\mathfrak{r} = \{(X, X) \mid X \in \mathfrak{g}_1\}$, where \mathfrak{g}_1 is a complex simple Lie algebra;
- (3) direct sums of $(\mathfrak{r}, \mathfrak{g})$ in (1) and (2).

Furthermore, when $(\mathfrak{r}, \mathfrak{g})$ is in this list, $\text{Spin } \nu$ is primary of type π_{ρ_n} .

Dmitri I. Panyushev [2001, Theorem 3.7] classified the primary $\text{Spin } \nu$ representations under the condition that \mathfrak{r} is semisimple. Our assumption that ν is the complexified differential of an orthogonal representation of a compact Lie group is more general than his, although we did not get any new representation ν in the classification. Our approach is completely different from his and in our argument, based on results of Kostant, it is more direct to see that only isotropy representations of symmetric pairs may have primary $\text{Spin } \nu$ representations. It was also found in [Panyushev 2001] that when $\text{Spin } \nu$ is primary the space $(\wedge \mathfrak{p})^{\mathfrak{r}}$ of \mathfrak{r} -invariants in $\wedge \mathfrak{p}$ is still an exterior algebra.

Finally, as a corollary of [Kostant 1997, Proposition 20] — see Equations (1-1) and (1-2) — and recalling the definition of l_0 and r_0 , we get a result on the \mathfrak{r} -module structure of $\wedge \mathfrak{p}$ and a decomposition of the Clifford algebra $C(\mathfrak{p})$, when $\text{Spin } \nu$ is primary:

Corollary 1.1. *Let $(\mathfrak{r}, \mathfrak{g})$ be a symmetric pair in the list of the theorem above. The corresponding $\text{Spin } \nu$ representation is primary of type π_{ρ_n} . Let $J = (\wedge \mathfrak{p})^{\mathfrak{r}}$. Then $\dim V_{\rho_n} = 2^{r_0}$ and $\dim J = 2^{l_0}$. As a subalgebra of $C(\mathfrak{p})$, J is isomorphic to a matrix algebra if l_0 is even, and is isomorphic to a sum of two matrix algebras if l_0 is odd. Furthermore,*

$$C(\mathfrak{p}) \cong (\text{End } V_{\rho_n}) \otimes J$$

as algebras. Finally, as \mathfrak{r} -modules,

$$\wedge \mathfrak{p} \cong 2^{l_0} V_{\rho_n} \otimes V_{\rho_n}.$$

2. Preliminaries. A necessary condition for the representation $\text{Spin } \nu$ to be primary

Let \mathfrak{r} be a complex reductive Lie algebra and $B_{\mathfrak{r}}$ a nonsingular \mathfrak{r} -invariant symmetric bilinear form on \mathfrak{r} . Let \mathfrak{p} be a finite-dimensional complex vector space with a nonsingular symmetric bilinear form $B_{\mathfrak{p}}$ on \mathfrak{p} . We always assume that

$$(2-1) \quad \nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$$

is a $B_{\mathfrak{p}}$ -invariant representation of τ on \mathfrak{p} .

Next we recall some important relations arising from Chevalley's identification of the underlying vector spaces of the exterior algebra $\bigwedge \mathfrak{p}$ and the Clifford algebra $C(\mathfrak{p})$ over \mathfrak{p} with respect to $B_{\mathfrak{p}}$. We think of $\bigwedge \mathfrak{p}$ as having two multiplicative structures: $uw \in \bigwedge \mathfrak{p}$ denotes the Clifford product of u and w , while $u \wedge w \in \bigwedge \mathfrak{p}$ denotes their exterior product. The natural extension of $B_{\mathfrak{p}}$ to $\bigwedge \mathfrak{p}$ is also denoted by $B_{\mathfrak{p}}$. For more details see [Kostant 1997, §2].

For any $u \in \bigwedge^2 \mathfrak{p}$, let $\text{ad } u \in \text{End } \bigwedge \mathfrak{p}$ be the operator defined by

$$\text{ad } u(w) = uw - wu$$

for every $w \in \bigwedge \mathfrak{p}$. Then $\text{ad } u$ is not only a derivation of the Clifford algebra structure of $\bigwedge \mathfrak{p}$, but also a derivation of degree zero of the exterior algebra structure of $\bigwedge \mathfrak{p}$. In particular, $\bigwedge^2 \mathfrak{p}$ is a Lie algebra under the Clifford product, and

$$\text{ad} : \bigwedge^2 \mathfrak{p} \rightarrow \text{End } \bigwedge \mathfrak{p}, \quad u \mapsto \text{ad } u$$

is a Lie algebra representation. Furthermore,

$$(2-2) \quad \tau : \bigwedge^2 \mathfrak{p} \rightarrow \mathfrak{so}(\mathfrak{p})$$

is a Lie algebra isomorphism, where

$$\tau(u)(x) = \text{ad } u(x)$$

for any $u \in \bigwedge^2 \mathfrak{p}$ and $x \in \mathfrak{p}$. For proofs see [Kostant 1997, Proposition 7, Theorem 8].

It follows from (2-2) that there exists a unique Lie algebra homomorphism $\nu_* : \mathfrak{r} \rightarrow \bigwedge^2 \mathfrak{p}$ such that

$$(2-3) \quad \tau \circ \nu_* = \nu.$$

Let

$$\xi : \text{End } \mathfrak{p} \rightarrow \text{End } \bigwedge \mathfrak{p}$$

be defined so that $\xi(z)$, for any $z \in \text{End } \mathfrak{p}$, is the unique derivation in $\text{End } \bigwedge \mathfrak{p}$ that extends the action of z to $\bigwedge \mathfrak{p}$. We also use ξ to denote the above map restricted to $\mathfrak{so}(\mathfrak{p})$. One knows that if $u \in \bigwedge^2 \mathfrak{p}$ then $\text{ad } u = \xi(\tau(u))$ (see [Kostant 1997, Theorem 8]), that is,

$$(2-4) \quad \text{ad} = \xi \circ \tau.$$

Let

$$(2-5) \quad \beta : \mathfrak{r} \rightarrow \text{End } \bigwedge \mathfrak{p}$$

be the composition of $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$ with $\xi : \mathfrak{so}(\mathfrak{p}) \rightarrow \text{End } \bigwedge \mathfrak{p}$. We will always refer to $\bigwedge \mathfrak{p}$ as an \mathfrak{r} -module via β . The extended bilinear form $B_{\mathfrak{p}}$ is invariant under

$\beta(x)$, for any $x \in \mathfrak{r}$. By Equations (2-3) and (2-4),

$$\beta = \text{ad} \circ \nu_*.$$

Up to equivalence, the Clifford algebra $C(\mathfrak{p})$ has a unique faithful multiplicity-free module S . Let

$$(2-6) \quad \varepsilon : C(\mathfrak{p}) \rightarrow \text{End } S$$

be the corresponding homomorphism, and S is referred to as the *spin module* for $C(\mathfrak{p})$. Let

$$(2-7) \quad \text{Spin} : \mathfrak{so}(\mathfrak{p}) \rightarrow \text{End } S$$

be the composition of $\tau^{-1} : \mathfrak{so}(\mathfrak{p}) \rightarrow \wedge^2 \mathfrak{p}$ with ε . The composition of $\nu_* : \mathfrak{r} \rightarrow \wedge^2 \mathfrak{p}$ with ε , or equivalently, the composition of $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$ with Spin , defines a representation

$$(2-8) \quad \text{Spin } \nu : \mathfrak{r} \rightarrow \text{End } S,$$

called the *spin* of ν . The maps above are organized into the commutative diagram

$$\begin{array}{ccccc} \mathfrak{r} & \xrightarrow{\nu} & \mathfrak{so}(\mathfrak{p}) & \xrightarrow{\xi} & \text{End } \wedge \mathfrak{p} \\ & \searrow \nu_* & \uparrow \tau & \nearrow \text{ad} & \\ & & \wedge^2 \mathfrak{p} & \xrightarrow{\varepsilon} & \text{End } S \end{array}$$

The underlying vector spaces of $\wedge \mathfrak{p}$ and $C(\mathfrak{p})$ are identified by Chevalley's map. When $\dim \mathfrak{p}$ is even,

$$C(\mathfrak{p}) \cong \text{End } S$$

as algebras, where S is the spin module of $C(\mathfrak{p})$, which splits into two half-spin representations of $\wedge^2 \mathfrak{p}$ ($\cong \mathfrak{so}(\mathfrak{p})$) and is self-dual as a $\wedge^2 \mathfrak{p}$ -module. Under the adjoint representation ad , we have $\text{End } S \cong S \otimes S^*$ as $\wedge^2 \mathfrak{p}$ -modules. Then, as $\wedge^2 \mathfrak{p}$ -modules, and hence as \mathfrak{r} -modules,

$$(2-9) \quad \wedge \mathfrak{p} \cong S \otimes S.$$

When $\dim \mathfrak{p}$ is odd, the spin module S of $C(\mathfrak{p})$ splits into two equivalent $\wedge^2 \mathfrak{p}$ -modules, S_1 and S_2 . The space S_1 (or S_2) is called the *spin representation* of $\wedge^2 \mathfrak{p}$ and is also self-dual. One has

$$(2-10) \quad C(\mathfrak{p}) \cong \text{End } S_1 \oplus \text{End } S_2$$

as algebras. See, for example, §3 of [Kostant 1997] for details. Under the adjoint action ad , we have $\text{End } S \cong S_1 \otimes S_1^* \oplus S_2 \otimes S_2^* \cong 2 S_1 \otimes S_1$ as $\wedge^2 \mathfrak{p}$ -modules. Then, as $\wedge^2 \mathfrak{p}$ -modules, and hence as \mathfrak{t} -modules, $\wedge \mathfrak{p} \cong 2 S_1 \otimes S_1$, or

$$(2-11) \quad S \otimes S \cong 2 \wedge \mathfrak{p}.$$

Recall that a completely reducible representation $\pi : \mathfrak{t} \rightarrow \text{End } V$ is primary if there exists a representation $\pi_\lambda : \mathfrak{t} \rightarrow \text{End } V_\lambda$, the irreducible representation of \mathfrak{t} with highest weight λ , such that every irreducible component of π is equivalent to π_λ . More specifically, in such a case we say that π is *primary of type* π_λ .

The relations (2-9) and (2-11) imply that, if S is primary of type π_λ , then

$$\wedge \mathfrak{p} \cong 2^l V_\lambda \otimes V_\lambda$$

as \mathfrak{t} -modules, for some nonnegative integer l .

Let $\nu_* : U(\mathfrak{t}) \rightarrow C^0(\mathfrak{p})$ be the algebra homomorphism extending $\nu_* : \mathfrak{t} \rightarrow \wedge^2 \mathfrak{p}$, where $U(\mathfrak{t})$ is the universal enveloping algebra of \mathfrak{t} . Let E be the image of $U(\mathfrak{t})$ and let $J = (\wedge \mathfrak{p})^\mathfrak{t}$. Then J equals the centralizer of E in $C(\mathfrak{p})$. If S is primary of type π_λ , one has

$$C(\mathfrak{p}) \cong E \otimes J$$

as algebras, and $E \cong \text{End } V_\lambda$. See [Kostant 1997, Proposition 20].

Let \mathfrak{g} be a complex Lie algebra and let θ be an involutory automorphism of \mathfrak{g} . Then (\mathfrak{g}, θ) is called an *involutory complex Lie algebra*, and θ is referred to as the corresponding *Cartan involution*. Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be the *Cartan decomposition* of \mathfrak{g} into $(+1)$ - and (-1) -eigenspaces of θ . A Lie subalgebra \mathfrak{k} is called a *symmetric Lie subalgebra* of \mathfrak{g} if there exists an involutory automorphism θ of \mathfrak{g} such that \mathfrak{k} is the set of θ -invariants in \mathfrak{g} . In this case $(\mathfrak{k}, \mathfrak{g})$ is called a *symmetric pair*.

Two involutory Lie algebra $(\mathfrak{g}_1, \theta_1)$ and $(\mathfrak{g}_2, \theta_2)$ are *isomorphic* if there exists an isomorphism $\psi : \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$ satisfying $\psi \theta_1 = \theta_2 \psi$. In fact, since \mathfrak{k} and θ uniquely determine each other, we will often refer to either as corresponding to the other. We say that two symmetric pairs are *isomorphic* if their corresponding involutory Lie algebras are isomorphic. Let $\text{ad}_{\mathfrak{g}}$ denote the adjoint representation of \mathfrak{g} on itself. Since $[\mathfrak{k}, \mathfrak{p}] \subseteq \mathfrak{p}$, we can define

$$\mathfrak{k} \rightarrow \text{End } \mathfrak{p}, \quad x \mapsto (\text{ad}_{\mathfrak{g}} x)|_{\mathfrak{p}}$$

for any $x \in \mathfrak{k}$; we call it the *isotropy representation* of the symmetric pair $(\mathfrak{k}, \mathfrak{g})$. It is easy to see that, for isomorphic symmetric pairs, the corresponding symmetric Lie subalgebras \mathfrak{k} are isomorphic and the corresponding isotropy representations are equivalent. The involutory complex Lie algebra (\mathfrak{g}, θ) and the symmetric pair $(\mathfrak{k}, \mathfrak{g})$ are said to be *reduced* if \mathfrak{k} contains no nonzero ideal of \mathfrak{g} .

Recall that $\nu : \mathfrak{t} \rightarrow \mathfrak{so}(\mathfrak{p})$ is a $B_{\mathfrak{p}}$ -invariant representation of \mathfrak{t} on \mathfrak{p} , where \mathfrak{t} is a complex reductive Lie algebra with a nonsingular ad \mathfrak{t} -invariant symmetric bilinear form $B_{\mathfrak{t}}$ and \mathfrak{p} is a complex vector space with a nonsingular symmetric bilinear form $B_{\mathfrak{p}}$.

Let $\mathfrak{g} = \mathfrak{t} \oplus \mathfrak{p}$ and let $B_{\mathfrak{g}}$ be the nonsingular symmetric bilinear form on \mathfrak{g} defined so that $B_{\mathfrak{g}}|_{\mathfrak{t}} = B_{\mathfrak{t}}$, $B_{\mathfrak{g}}|_{\mathfrak{p}} = B_{\mathfrak{p}}$, and \mathfrak{p} is $B_{\mathfrak{g}}$ -orthogonal to \mathfrak{t} . As in [Kostant 1999, §1.1], we say that the representation $(\nu, B_{\mathfrak{g}})$ is of *Lie type* if there exists a Lie algebra structure $[\cdot, \cdot]$ on \mathfrak{g} such that \mathfrak{t} is a Lie subalgebra of \mathfrak{g} and $[x, y] = \nu(x)y$ for $x \in \mathfrak{t}$, $y \in \mathfrak{p}$, and if moreover $B_{\mathfrak{g}}$ is \mathfrak{g} -invariant. Let $\text{Cas}_{\mathfrak{t}}$ denote the Casimir element of \mathfrak{t} with respect to $B_{\mathfrak{t}}$.

Kostant proved an important relation between the representations $\text{Spin } \nu$ and ν :

Theorem 2.1 [Kostant 1999]. *The following conditions are equivalent:*

- (1) $(\text{Spin } \nu)(\text{Cas}_{\mathfrak{t}})$ is a scalar multiple of the identity operator on S ;
- (2) $(\nu, B_{\mathfrak{g}})$ is of Lie type and $(\mathfrak{t}, \mathfrak{g})$ is a symmetric pair, where \mathfrak{p} is the (-1) -eigenspace for a corresponding Cartan involution.

Remark 2.2. There are four equivalent conditions listed in [Kostant 1999, Theorem 1.59], but for our purpose we only list two of them here. When any of the conditions of the theorem are satisfied, the Lie algebra structure of $\mathfrak{g} = \mathfrak{t} \oplus \mathfrak{p}$ is determined in §1 of [Kostant 1999].

Theorem 2.3 [Kostant 1999, Theorem 1.61]. *Assume that ν is the complexified differential of a faithful $B_{\mathfrak{p}}$ -orthogonal representation of a compact Lie group and that $\mathfrak{p}^{\mathfrak{t}} = 0$. Assume that any of the conditions of Theorem 2.1 is satisfied. Then \mathfrak{g} is semisimple, and \mathfrak{p} is the orthogonal complement of \mathfrak{t} in \mathfrak{g} with respect to the Killing form.*

Our desired result follows as a corollary:

Proposition 2.4. *Assume that $\nu : \mathfrak{t} \rightarrow \mathfrak{so}(\mathfrak{p})$ is the complexified differential of a faithful $B_{\mathfrak{p}}$ -orthogonal representation of a compact Lie group and that $\mathfrak{p}^{\mathfrak{t}} = 0$. If $\text{Spin } \nu$ is primary, then $(\nu, B_{\mathfrak{g}})$ is of Lie type, $(\mathfrak{t}, \mathfrak{g})$ is a reduced symmetric pair with \mathfrak{g} semisimple, and ν is the isotropy representation of $(\mathfrak{t}, \mathfrak{g})$.*

Proof. If the representation $\text{Spin } \nu$ is primary, say, of type π_{λ} , then $(\text{Spin } \nu)(\text{Cas}_{\mathfrak{t}})$ is a scalar multiple of the identity operator on S , because $\text{Cas}_{\mathfrak{t}}$ is in the center of $U(\mathfrak{t})$. Then, by Theorem 2.1, $(\nu, B_{\mathfrak{g}})$ is of Lie type and $(\mathfrak{t}, \mathfrak{g})$ is a symmetric pair where \mathfrak{p} is the (-1) -eigenspace for a corresponding Cartan involution. So ν is the isotropy representation of $(\mathfrak{t}, \mathfrak{g})$. The symmetric pair $(\mathfrak{t}, \mathfrak{g})$ is reduced because ν is faithful. Since all the assumptions of Theorem 2.3 are satisfied, \mathfrak{g} is semisimple. \square

Hence, in order to classify all the primary $\text{Spin } \nu$ representations, we need only consider the isotropy representations of symmetric pairs $(\mathfrak{t}, \mathfrak{g})$ with \mathfrak{g} semisimple.

3. Restricted root system of a real semisimple Lie algebra

Let (\mathfrak{g}, θ) be an involutory complex semisimple Lie algebra. Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be the corresponding Cartan decomposition. Let $B_{\mathfrak{g}}$ be an \mathfrak{g} -invariant nonsingular symmetric bilinear form on \mathfrak{g} . Assume that the isotropy representation $\nu : \mathfrak{k} \rightarrow \mathfrak{so}(\mathfrak{p})$ is faithful, which is equivalent to $(\mathfrak{k}, \mathfrak{g})$ being reduced. The \mathfrak{k} -module \mathfrak{p} is completely reducible and there is no nonzero trivial submodule of \mathfrak{p} ; hence the space $\mathfrak{p}^{\mathfrak{k}}$ of \mathfrak{k} invariants in \mathfrak{p} is always 0. Now our objective is to classify all the reduced symmetric pairs $(\mathfrak{k}, \mathfrak{g})$ such that the corresponding Spin ν representation is primary. Considering that ν is completely reducible, it is not hard to see that the \mathfrak{k} -module structure of S does not depend on the nonsingular \mathfrak{g} -invariant symmetric bilinear form $B_{\mathfrak{g}}$. So from now on we will just assume $B_{\mathfrak{g}}$ to be the Killing form on \mathfrak{g} .

For a noncompact real semisimple Lie algebra \mathfrak{g}_0 , let $\mathfrak{g}_0 = \mathfrak{k}_0 \oplus \mathfrak{p}_0$ be a Cartan decomposition of \mathfrak{g}_0 . Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be its complexification and θ the corresponding involution of \mathfrak{g} . Then (\mathfrak{g}, θ) is an involutory complex semisimple Lie algebra. Conversely, for a complex semisimple involutory Lie algebra (\mathfrak{g}, θ) , there exists a real form \mathfrak{g}_0 of \mathfrak{g} such that $\theta|_{\mathfrak{g}_0}$ is a Cartan involution of \mathfrak{g}_0 . Up to isomorphism, \mathfrak{g}_0 and (\mathfrak{g}, θ) uniquely determine each other. Let $\mathfrak{h}_0 = \mathfrak{t}_0 \oplus \mathfrak{a}_0$ be a maximally compact Cartan subalgebra of \mathfrak{g}_0 , that is, \mathfrak{t}_0 is a Cartan subalgebra of \mathfrak{k}_0 and $\mathfrak{a}_0 = \mathfrak{p}_0^{\mathfrak{t}_0}$. Let $\mathfrak{h} = \mathfrak{t} \oplus \mathfrak{a}$ be its complexification, which is also a Cartan subalgebra of \mathfrak{g} . We call such an \mathfrak{h} a *maximally compact Cartan subalgebra* of (\mathfrak{g}, θ) . Let $l_0 = \dim \mathfrak{a}$. Let

$$\mathfrak{h}_{\mathbb{R}} = i\mathfrak{t}_0 \oplus \mathfrak{a}_0,$$

which is a real form of \mathfrak{h} .

Let $\Delta(\mathfrak{g}, \mathfrak{h}) \subset \mathfrak{h}^*$ be the set of roots of \mathfrak{g} with respect to \mathfrak{h} . Obviously, we have $\theta(\Delta(\mathfrak{g}, \mathfrak{h})) = \Delta(\mathfrak{g}, \mathfrak{h})$. Let $\mathfrak{h}_{\mathbb{R}}^*$ be the real span of the roots in $\Delta(\mathfrak{g}, \mathfrak{h})$, so that $\mathfrak{h}_{\mathbb{R}}^*$ is a real form of \mathfrak{h}^* and can be taken as the real dual space to $\mathfrak{h}_{\mathbb{R}}$, because the roots in $\Delta(\mathfrak{g}, \mathfrak{h})$ take real values on $\mathfrak{h}_{\mathbb{R}}$. Let θ act on \mathfrak{h}^* by $(\theta\sigma)(H) = \sigma(\theta H)$, where $\sigma \in \mathfrak{h}^*$, $H \in \mathfrak{h}$. Clearly $\mathfrak{h}_{\mathbb{R}}^*$ is θ -stable. Let

$$(3-1) \quad \mathfrak{h}_{\mathbb{R}}^* = \mathfrak{t}_{\mathbb{R}}^* \oplus \mathfrak{a}_{\mathbb{R}}^*$$

be the decomposition of $\mathfrak{h}_{\mathbb{R}}^*$ into $(+1)$ - and (-1) -eigenspaces of θ . Let

$$p : \mathfrak{h}_{\mathbb{R}}^* \rightarrow \mathfrak{t}_{\mathbb{R}}^*$$

be the projection of $\mathfrak{h}_{\mathbb{R}}^*$ onto $\mathfrak{t}_{\mathbb{R}}^*$.

Set $\Delta(\mathfrak{g}, \mathfrak{t}) = \{p(\alpha) \mid \alpha \in \Delta(\mathfrak{g}, \mathfrak{h})\}$. Then $\mathfrak{t}_{\mathbb{R}}^*$ is the real span of the roots in $\Delta(\mathfrak{g}, \mathfrak{t})$. The restriction $B_{\mathfrak{g}}|_{\mathfrak{h}}$ is nonsingular and induces a symmetric nonsingular bilinear form $B_{\mathfrak{h}^*}$ on \mathfrak{h}^* . One knows that $B_{\mathfrak{h}^*}$ is positive definite on $\mathfrak{h}_{\mathbb{R}}^*$; hence

also on $\mathfrak{t}_{\mathbb{R}}^*$. Then (3-1) is clearly an orthogonal direct-sum decomposition, and $p(\alpha) = (\alpha + \theta(\alpha))/2$ for $\alpha \in \mathfrak{h}_{\mathbb{R}}^*$. Let (γ, δ) denote the value of $B_{\mathfrak{h}^*}$ on $\gamma, \delta \in \mathfrak{h}_{\mathbb{R}}^*$.

For any $\alpha, \gamma \in \Delta(\mathfrak{g}, \mathfrak{h})$ or $\alpha, \gamma \in \Delta(\mathfrak{g}, \mathfrak{t})$, define

$$\langle \alpha, \gamma \rangle = \frac{2(\alpha, \gamma)}{(\gamma, \gamma)}.$$

It is well-known that $\Delta(\mathfrak{g}, \mathfrak{h})$ is a root system in $\mathfrak{h}_{\mathbb{R}}^*$. Moreover:

Proposition 3.1. *The set $\Delta(\mathfrak{g}, \mathfrak{t})$ is a root system (maybe nonreduced) in $\mathfrak{t}_{\mathbb{R}}^*$.*

Proof. For any $\alpha \in \Delta(\mathfrak{g}, \mathfrak{h})$, we use α' to denote $p(\alpha) \in \Delta(\mathfrak{g}, \mathfrak{t})$. Then $(\alpha', \gamma') = (\alpha, \gamma')$ as $(\alpha' - \alpha, \gamma') = 0$. For any $\alpha, \gamma \in \Delta(\mathfrak{g}, \mathfrak{h})$ (respectively, any $\alpha, \gamma \in \Delta(\mathfrak{g}, \mathfrak{t})$), define $s_{\gamma} \alpha = \alpha - \langle \alpha, \gamma \rangle \gamma$, the reflection of α along γ . Then we need only show that, for any $\alpha', \gamma' \in \Delta(\mathfrak{g}, \mathfrak{t})$, we have $\langle \alpha', \gamma' \rangle \in \mathbb{Z}$ and $s_{\gamma'} \alpha' \in \Delta(\mathfrak{g}, \mathfrak{t})$. We distinguish two cases.

$\theta\gamma = \gamma$: Then $\gamma' = \gamma$, and

$$\langle \alpha', \gamma' \rangle = \frac{2(\alpha', \gamma)}{(\gamma, \gamma)} = \frac{2(\alpha, \gamma)}{(\gamma, \gamma)} = \langle \alpha, \gamma \rangle \in \mathbb{Z}.$$

Thus, $s_{\gamma'} \alpha' = \alpha' - \langle \alpha', \gamma' \rangle \gamma' = \alpha' - \langle \alpha, \gamma \rangle \gamma' = (s_{\gamma} \alpha)'$.

$\theta\gamma \neq \gamma$: Since \mathfrak{h} is a maximally compact Cartan subalgebra of (\mathfrak{g}, θ) , there is no real root (that is, vanishing on \mathfrak{t}) in $\Delta(\mathfrak{g}, \mathfrak{h})$. So $(\gamma, \theta\gamma) \leq 0$, as otherwise $\gamma - \theta\gamma$ will be a real root.

If $(\gamma, \theta\gamma) < 0$, then $\gamma + \theta\gamma = 2\gamma'$ is a root in $\Delta(\mathfrak{g}, \mathfrak{h})$ and also in $\Delta(\mathfrak{g}, \mathfrak{t})$. Then $s_{\gamma'} \alpha' = s_{\gamma + \theta\gamma} \alpha' = (s_{\gamma + \theta\gamma} \alpha) \in \Delta(\mathfrak{g}, \mathfrak{t})$. But $(s_{\gamma + \theta\gamma} \alpha)' = \alpha' - 2\langle \alpha, \gamma + \theta\gamma \rangle \gamma'$, and so $\langle \alpha', \gamma' \rangle = 2\langle \alpha, \gamma + \theta\gamma \rangle \in \mathbb{Z}$.

If $(\gamma, \theta\gamma) = 0$, then $(\gamma', \gamma') = (\gamma, \gamma)/2$. By computation,

$$s_{\gamma'} \alpha' = \alpha' - \frac{2(\alpha, \gamma + \theta\gamma)}{(\gamma, \gamma)} \gamma' = (s_{\gamma} s_{\theta\gamma} \alpha)'$$

In this case

$$\langle \alpha', \gamma' \rangle = \frac{2(\alpha, \gamma + \theta\gamma)}{(\gamma, \gamma)} = \frac{2(\alpha + \theta\alpha, \gamma)}{(\gamma, \gamma)} = \langle \alpha, \gamma \rangle + \langle \theta\alpha, \gamma \rangle$$

is also an integer. □

Remark 3.2. In this paper we call $\Delta(\mathfrak{g}, \mathfrak{t})$ the restricted root system of \mathfrak{g}_0 , which is clearly independent of the Cartan subalgebra \mathfrak{t}_0 of \mathfrak{k}_0 chosen. For a θ -stable positive root system $\Delta^+(\mathfrak{g}, \mathfrak{h})$ of $\Delta(\mathfrak{g}, \mathfrak{h})$, it is obvious that $p(\Delta^+(\mathfrak{g}, \mathfrak{h}))$ is also a positive root system in $\Delta(\mathfrak{g}, \mathfrak{t})$. Furthermore, for the set of simple roots Π of $\Delta^+(\mathfrak{g}, \mathfrak{h})$, $p(\Pi)$ is also the set of simple roots in $p(\Delta^+(\mathfrak{g}, \mathfrak{h}))$. Conversely, if $\Delta^+(\mathfrak{g}, \mathfrak{t})$ is a positive root system in $\Delta(\mathfrak{g}, \mathfrak{t})$, then $p^{-1}(\Delta^+(\mathfrak{g}, \mathfrak{t}))$ is a θ -stable positive root system of $\Delta(\mathfrak{g}, \mathfrak{h})$. Consequently, the θ -stable positive root systems of $\Delta(\mathfrak{g}, \mathfrak{h})$

and the positive root systems of $\Delta(\mathfrak{g}, \mathfrak{t})$ are in one-to-one correspondence under p . Let $W(\Delta(\mathfrak{g}, \mathfrak{h}))$ be the Weyl group of $\Delta(\mathfrak{g}, \mathfrak{h})$. The Weyl group of $\Delta(\mathfrak{g}, \mathfrak{t})$ is in fact isomorphic to the subgroup of $W(\Delta(\mathfrak{g}, \mathfrak{h}))$ consisting of those elements of $W(\Delta(\mathfrak{g}, \mathfrak{h}))$ commuting with θ .

Let \mathfrak{g}_α be the one-dimensional root space corresponding to α . Let

$$\Delta_1 = \{\alpha \in \Delta(\mathfrak{g}, \mathfrak{h}) \mid \mathfrak{g}_\alpha \subset \mathfrak{k}\},$$

$$\Delta_2 = \{\alpha \in \Delta(\mathfrak{g}, \mathfrak{h}) \mid \mathfrak{g}_\alpha \subset \mathfrak{p}\},$$

$$\Delta_3 = \Delta(\mathfrak{g}, \mathfrak{h}) \setminus (\Delta_1 \cup \Delta_2).$$

The roots in Δ_1 and Δ_2 are called *imaginary*. We call an imaginary root *compact* if $\alpha \in \Delta_1$ and *noncompact* if $\alpha \in \Delta_2$. The roots in Δ_3 are called *complex*. Then $\Delta(\mathfrak{g}, \mathfrak{h}) = \Delta_1 \sqcup \Delta_2 \sqcup \Delta_3$. We choose a positive root system $\Delta^+(\mathfrak{g}, \mathfrak{h})$ such that $\theta(\Delta^+(\mathfrak{g}, \mathfrak{h})) = \Delta^+(\mathfrak{g}, \mathfrak{h})$. Let Π be the set of simple roots in $\Delta^+(\mathfrak{g}, \mathfrak{h})$. Then θ permutes the simple roots in Π and induces an involutory automorphism of the Dynkin diagram Γ of Π . For the complex semisimple involutory Lie algebra (\mathfrak{g}, θ) , by abuse of language, we call (Γ, θ) its Dynkin diagram. We also call (Γ, θ) the Dynkin diagram of the corresponding \mathfrak{g}_0 . Obviously, θ fixes the imaginary simple roots in Γ and permutes in 2-cycles the complex simple roots in Γ .

Lemma 3.3. *The Dynkin diagram (Γ, θ) of (\mathfrak{g}, θ) is independent of the θ -stable positive root system chosen.*

Proof. Assume that Δ_1^+ and Δ_2^+ are two θ -stable positive root systems of $\Delta(\mathfrak{g}, \mathfrak{h})$. For $i = 1$ or 2 , let Π_i be the set of simple roots in Δ_i^+ and Γ_i the Dynkin diagram of Π_i . Then there exists $\phi \in W(\Delta(\mathfrak{g}, \mathfrak{h}))$, the Weyl group of $\Delta(\mathfrak{g}, \mathfrak{h})$, such that $\phi(\Delta_1^+) = \Delta_2^+$. One also has $\phi(\Pi_1) = \Pi_2$. Then $\phi\theta(\Delta_1^+) = \theta\phi(\Delta_1^+)$, so $\phi^{-1}\theta^{-1}\phi\theta(\Delta_1^+) = \Delta_1^+$. Since $W(\Delta(\mathfrak{g}, \mathfrak{h}))$ is a normal subgroup of the automorphism group of $\Delta(\mathfrak{g}, \mathfrak{h})$, one has $\phi^{-1}\theta^{-1}\phi\theta \in W(\Delta(\mathfrak{g}, \mathfrak{h}))$. Because $W(\Delta(\mathfrak{g}, \mathfrak{h}))$ acts simply transitively on the set of positive root systems, $\phi^{-1}\theta^{-1}\phi\theta = 1$. So $\phi\theta = \theta\phi$. Hence, under ϕ the actions of θ on Δ_1^+ and Δ_2^+ are equivalent. Therefore (Γ_1, θ) and (Γ_2, θ) are the same. \square

Note that (Γ, θ) gives less information for \mathfrak{g}_0 than the Vogan diagram of \mathfrak{g}_0 , and nonisomorphic \mathfrak{g}_0 's may have the same (Γ, θ) .

For any $\alpha \in \Delta(\mathfrak{g}, \mathfrak{t})$, also let

$$\mathfrak{g}_\alpha = \{X \in \mathfrak{g} \mid [H, X] = \alpha(H)X \text{ for all } H \in \mathfrak{t}\}$$

be the root space corresponding to α . The multiplicity of $\alpha \in \Delta(\mathfrak{g}, \mathfrak{t})$ is defined to be the dimension of \mathfrak{g}_α . Let $\Delta(\mathfrak{k}, \mathfrak{t}) \subset \mathfrak{t}^*$ be the set of roots of \mathfrak{k} with respect to \mathfrak{t} . Define

$$\Delta(\mathfrak{p}, \mathfrak{t}) = \{\alpha \in \Delta(\mathfrak{g}, \mathfrak{t}) \mid \mathfrak{g}_\alpha \cap \mathfrak{p} \neq 0\}.$$

Then $\Delta(\mathfrak{g}, \mathfrak{t}) = \Delta(\mathfrak{k}, \mathfrak{t}) \cup \Delta(\mathfrak{p}, \mathfrak{t})$. For any $\alpha \in \Delta(\mathfrak{p}, \mathfrak{t})$, let $\mathfrak{p}_\alpha = \mathfrak{g}_\alpha \cap \mathfrak{p}$. Then

$$\mathfrak{p} = \mathfrak{a} \oplus \sum_{\alpha \in \Delta(\mathfrak{p}, \mathfrak{t})} \mathfrak{p}_\alpha.$$

$\Delta(\mathfrak{p}, \mathfrak{t})$ is just the set of nonzero weights of \mathfrak{p} with respect to the Cartan subalgebra \mathfrak{t} of \mathfrak{k} , because \mathfrak{p} is the space of the isotropy representation of \mathfrak{k} .

Lemma 3.4. \mathfrak{p}_α is one-dimensional, for any $\alpha \in \Delta(\mathfrak{p}, \mathfrak{t})$.

Proof. If $\alpha \in \Delta_2$, then $\mathfrak{p}_\alpha = \mathfrak{g}_\alpha$ is one-dimensional. Otherwise, assume that $\alpha = p(\gamma)$ for some $\gamma \in \Delta_3$. Because there are no real roots in $\Delta(\mathfrak{g}, \mathfrak{h})$, we see that $p(\gamma) \neq p(\alpha)$, for any $\alpha, \gamma \in \Delta(\mathfrak{g}, \mathfrak{h})$ such that $\gamma \neq \alpha$ and $\gamma \neq \theta\alpha$. Then

$$\mathfrak{g}_\alpha = \sum_{\substack{\beta \in \Delta(\mathfrak{g}, \mathfrak{h}) \\ p(\beta) = \alpha}} \mathfrak{g}_\beta = \mathfrak{g}_\gamma \oplus \mathfrak{g}_{\theta\gamma}.$$

Let X_γ be a root vector of γ . Then θX_γ is a root vector of $\theta\gamma$. So both $\mathfrak{k}_\alpha = \mathfrak{g}_\alpha \cap \mathfrak{k} = \mathbb{C}(X_\gamma + \theta X_\gamma)$ and $\mathfrak{p}_\alpha = \mathbb{C}(X_\gamma - \theta X_\gamma)$ are one-dimensional. \square

The proof of the lemma also implies that

$$\begin{aligned} \Delta(\mathfrak{k}, \mathfrak{t}) &= \Delta_1 \sqcup p(\Delta_3), \\ \Delta(\mathfrak{p}, \mathfrak{t}) &= \Delta_2 \sqcup p(\Delta_3), \\ \Delta(\mathfrak{k}, \mathfrak{t}) \cap \Delta(\mathfrak{p}, \mathfrak{t}) &= p(\Delta_3). \end{aligned}$$

The multiplicity of $\alpha \in \Delta(\mathfrak{g}, \mathfrak{t})$ (that is, the dimension of \mathfrak{g}_α) is 1 if $\alpha \in \Delta_1 \sqcup \Delta_2$, and is 2 if $\alpha \in p(\Delta_3)$.

4. Classification of primary Spin ν representations and some consequence

We continue using the previous notation and complete the classification of symmetric pairs with primary Spin ν representations. Let (\mathfrak{g}, θ) be a reduced involutory complex semisimple Lie algebra, and $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be the corresponding Cartan decomposition. Let $B_{\mathfrak{g}}$ be the Killing form on \mathfrak{g} . Let $\mathfrak{h} = \mathfrak{t} \oplus \mathfrak{a}$ be a maximally compact Cartan subalgebra of (\mathfrak{g}, θ) . Let

$$(4-1) \quad \text{Spin } \nu : \mathfrak{k} \rightarrow \text{End } S$$

be the representation defined as the composition of the isotropy representation $\nu : \mathfrak{k} \rightarrow \mathfrak{so}(\mathfrak{p})$ with the spin representation $\text{Spin} : \mathfrak{so}(\mathfrak{p}) \rightarrow \text{End } S$, as in (2-7). Let

$$\beta : \mathfrak{k} \rightarrow \text{End } \bigwedge \mathfrak{p}$$

be the derivation extension of $\nu : \mathfrak{k} \rightarrow \mathfrak{so}(\mathfrak{p})$, as in Equation (2-5).

From now on, we fix a system $P_{\mathfrak{k}}$ of positive roots of $\Delta(\mathfrak{k}, \mathfrak{t})$. Let $C(P_{\mathfrak{k}})$ be the set of θ -stable positive root systems P of $\Delta(\mathfrak{g}, \mathfrak{h})$ such that $p(P) \supseteq P_{\mathfrak{k}}$. For a

subset $Q \subseteq \Delta(\mathfrak{g}, \mathfrak{h})$ or $Q \subseteq \Delta(\mathfrak{g}, \mathfrak{t})$, we set $\rho(Q) = \frac{1}{2} \sum_{\alpha \in Q} \alpha$. For $P \in C(P_{\mathfrak{k}})$, let $\rho_n(P) = \rho(P) - \rho(P_{\mathfrak{k}})$. Because P is θ -stable, $\rho(P)$ and $\rho_n(P)$ are both in \mathfrak{t}^* . Recall that $l_0 = \dim \mathfrak{a}$.

Lemma 4.1 [Wallach 1988, Lemma 9.3.2]. *Let $\text{Spin } \nu : \mathfrak{k} \rightarrow \text{End } S$ be the representation defined as in (4-1). Then*

$$\text{Spin } \nu = \sum_{P \in C(P_{\mathfrak{k}})} 2^{\lfloor (l_0+1)/2 \rfloor} \pi_{\rho_n(P)},$$

where $\pi_{\rho_n(P)}$ denotes the irreducible representation of \mathfrak{k} with highest weight $\rho_n(P)$.

Remark 4.2. For Wallach, the definition of the $\text{Spin } \nu$ representation is slightly different from ours. When $\dim \mathfrak{p}$ is even, the two definitions agree. When $\dim \mathfrak{p}$ is odd, his S is the spin representation S_1 of $\mathfrak{so}(\mathfrak{p})$ in our Equation (2-10). This results in the difference of the scalar in Lemma 4.1; the scalar in Lemma 9.3.2 of [Wallach 1988] is $2^{\lfloor l_0/2 \rfloor}$.

In terms of the restricted root system $\Delta(\mathfrak{g}, \mathfrak{t})$, we get an equivalent statement which is convenient to use. Let

$$D(P_{\mathfrak{k}}) = \{p(P) \mid P \in C(P_{\mathfrak{k}})\}$$

be the set of the positive root systems of $\Delta(\mathfrak{g}, \mathfrak{t})$ containing $P_{\mathfrak{k}}$. Remark 3.2 implies that the projection p sets up a one-to-one correspondence between $C(P_{\mathfrak{k}})$ and $D(P_{\mathfrak{k}})$. For $P' = p(P) \in D(P_{\mathfrak{k}})$, define $\rho_n(p(P)) = \rho_n(P)$.

Lemma 4.3. *Let $\text{Spin } \nu : \mathfrak{k} \rightarrow \text{End } S$ be the representation defined as in (4-1). Then*

$$\text{Spin } \nu = \sum_{P \in D(P_{\mathfrak{k}})} 2^{\lfloor (l_0+1)/2 \rfloor} \pi_{\rho_n(P)}.$$

By this lemma, $\text{Spin } \nu$ is primary if and only if $\text{card } D(P_{\mathfrak{k}}) = 1$, that is, if there exists only one positive root system of $\Delta(\mathfrak{g}, \mathfrak{t})$ containing $P_{\mathfrak{k}}$. Note that $\Delta(\mathfrak{k}, \mathfrak{t})$ and $\Delta(\mathfrak{g}, \mathfrak{t})$ are both root systems in $\mathfrak{t}_{\mathbb{R}}^*$, and $\Delta(\mathfrak{k}, \mathfrak{t})$ is a root subsystem of $\Delta(\mathfrak{g}, \mathfrak{t})$. Let $W_{\mathfrak{g}}$ and $W_{\mathfrak{k}}$ be the Weyl groups of $\Delta(\mathfrak{g}, \mathfrak{t})$ and $\Delta(\mathfrak{k}, \mathfrak{t})$. Then $W_{\mathfrak{k}}$ is a subgroup of $W_{\mathfrak{g}}$. Let \mathcal{C} be the Weyl chamber relative to $P_{\mathfrak{k}}$. It is clear that $\text{card } D(P_{\mathfrak{k}})$ equals the number of Weyl chambers of $\Delta(\mathfrak{g}, \mathfrak{t})$ contained in \mathcal{C} , which also equals the index of $W_{\mathfrak{k}}$ in $W_{\mathfrak{g}}$.

For a nonreduced root system Δ , we call a subset $\Delta_0 \subset \Delta$ a *reduced root system* of Δ if Δ_0 is a reduced root system and contains a multiple of α for any $\alpha \in \Delta$. (Such a multiple must be $\alpha/2$, α or 2α .) For example, B_n and C_n are reduced root systems of $(BC)_n$. Obviously, for a reduced root system Δ_0 of Δ , the Weyl groups of Δ_0 and Δ are the same. Therefore, if $\Delta(\mathfrak{g}, \mathfrak{t})$ is reduced, $\text{card } D(P_{\mathfrak{k}}) = 1$ if and

only if $\Delta(\mathfrak{k}, \mathfrak{t}) = \Delta(\mathfrak{g}, \mathfrak{t})$. If $\Delta(\mathfrak{g}, \mathfrak{t})$ is nonreduced, $\text{card } D(P_{\mathfrak{k}}) = 1$ if and only if $\Delta(\mathfrak{k}, \mathfrak{t})$ is a reduced root system of $\Delta(\mathfrak{g}, \mathfrak{t})$.

Assume that $\text{Spin } \nu$ is primary. There exists only one positive root system P of $\Delta(\mathfrak{g}, \mathfrak{t})$ containing $P_{\mathfrak{k}}$. We define $\rho_n = \rho_n(P)$. Then $\text{Spin } \nu$ is primary of type π_{ρ_n} . Let $P_{\mathfrak{p}} = P \cap \Delta(\mathfrak{p}, \mathfrak{t})$. Then $\Delta(\mathfrak{p}, \mathfrak{t}) = P_{\mathfrak{p}} \sqcup -P_{\mathfrak{p}}$ and $\rho_n = \rho_n(P) = \rho(P \setminus P_{\mathfrak{k}}) = \rho(P_{\mathfrak{p}})$. Summarizing:

Lemma 4.4. *The representation $\text{Spin } \nu$ is primary if and only if $\Delta(\mathfrak{k}, \mathfrak{t})$ equals $\Delta(\mathfrak{g}, \mathfrak{t})$ or is a reduced root system of $\Delta(\mathfrak{g}, \mathfrak{t})$. In this case, $\text{Spin } \nu$ is primary of type π_{ρ_n} .*

Remark 4.5. Let $r_0 = \text{card } P_{\mathfrak{p}}$. Considering Lemma 3.4, one has

$$\dim \mathfrak{p} = l_0 + 2r_0.$$

Hence, when $\text{Spin } \nu$ is primary, by applying Equations (2-9) and (2-11) one has

$$\bigwedge \mathfrak{p} \cong 2^{l_0} V_{\rho_n} \otimes V_{\rho_n},$$

as \mathfrak{k} -modules. Comparing the dimensions of $\bigwedge \mathfrak{p}$ and $2^{l_0} V_{\rho_n} \otimes V_{\rho_n}$, we get that

$$\dim V_{\rho_n} = 2^{r_0}.$$

Lemma 4.6. *Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ be the Cartan decomposition corresponding to θ . If $\text{Spin } \nu$ is primary, then $\text{rank } \mathfrak{g} > \text{rank } \mathfrak{k}$ and the action of θ on Γ is nontrivial, where (Γ, θ) is the Dynkin Diagram of (\mathfrak{g}, θ) .*

Proof. If $\text{rank } \mathfrak{g} = \text{rank } \mathfrak{k}$, the Cartan subalgebra \mathfrak{t} of \mathfrak{k} is also that of \mathfrak{g} . So $\Delta(\mathfrak{g}, \mathfrak{t})$ and $\Delta(\mathfrak{k}, \mathfrak{t})$ are both irreducible and reduced root systems. Since $\Delta(\mathfrak{g}, \mathfrak{t}) \supseteq \Delta(\mathfrak{k}, \mathfrak{t})$, $\text{Spin } \nu$ cannot be primary by Lemma 4.4. Let (Γ, θ) be the Dynkin diagram of (\mathfrak{g}, θ) . If $\text{rank } \mathfrak{g} > \text{rank } \mathfrak{k}$, then \mathfrak{a} is nonzero and the action of θ on a θ -stable positive root system of $\Delta(\mathfrak{g}, \mathfrak{h})$ is nontrivial, so the action of θ on Γ is nontrivial. Conversely, if the action of θ on Γ is nontrivial, $\text{rank } \mathfrak{g} > \text{rank } \mathfrak{k}$. \square

Next we classify the symmetric pairs $(\mathfrak{k}, \mathfrak{g})$ with primary $\text{Spin } \nu$ representations under the condition that \mathfrak{g} be simple.

Proposition 4.7. *Let (\mathfrak{g}, θ) be an involutory complex simple Lie algebra and $(\mathfrak{k}, \mathfrak{g})$ be the corresponding symmetric pair. Then $\text{Spin } \nu$ is primary if and only if $(\mathfrak{k}, \mathfrak{g})$ is one of the following:*

$$\begin{aligned} &(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{sl}(2n+1, \mathbb{C})), & n \geq 1; \\ &(\mathfrak{sp}(n, \mathbb{C}), \mathfrak{sl}(2n, \mathbb{C})), & n \geq 2; \\ &(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{so}(2n+2, \mathbb{C})), & n \geq 3; \\ &(F_4, E_6). \end{aligned}$$

Proof. In view of Lemma 4.6, only those \mathfrak{g} with a Dynkin diagram admitting a nontrivial involutory diagram automorphism may have primary Spin ν representations. In these cases, θ is an outer automorphism of \mathfrak{g} . Since \mathfrak{g} is simple, \mathfrak{g} must be of type A_n with $n \geq 2$, D_n with $n \geq 4$, or E_6 ; in each case θ is the obvious one. In each case the roots have the same length. First, we compute the Dynkin diagram of $\Delta(\mathfrak{g}, \mathfrak{t}) = p(\Delta(\mathfrak{g}, \mathfrak{h}))$ by using the fact that p maps the simple roots of $\Delta^+(\mathfrak{g}, \mathfrak{h})$ to the simple roots of $\Delta^+(\mathfrak{g}, \mathfrak{t}) = p(\Delta^+(\mathfrak{g}, \mathfrak{h}))$.

For any $\alpha \in \Delta(\mathfrak{g}, \mathfrak{h})$, we use α' to denote $p(\alpha) \in \Delta(\mathfrak{g}, \mathfrak{t})$. Let Π be a θ -stable simple root system in $\Delta(\mathfrak{g}, \mathfrak{h})$. Let α', γ' be two different simple roots in $p(\Pi)$, and compute $\langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle$. There are three situations:

(1) If $\alpha' = \alpha$ and $\gamma' = \gamma$, then $\langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle = \langle \alpha, \gamma \rangle \langle \gamma, \alpha \rangle$.

(2) If $\alpha' = \alpha$ and $\gamma' \neq \gamma$, then there are two subcases:

(a) If $\langle \alpha, \gamma \rangle = 0$, then $\langle \alpha', \gamma' \rangle = 0$ and $\langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle = 0$.

(b) If $\langle \alpha, \gamma \rangle \neq 0$, then $\langle \gamma, \theta\gamma \rangle = 0$ and

$$\begin{aligned} \langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle &= \frac{2(\alpha', \gamma')}{(\gamma', \gamma')} \cdot \frac{2(\gamma', \alpha')}{(\alpha', \alpha')} = \frac{4(2\alpha, \gamma + \theta\gamma)^2}{(\gamma + \theta\gamma, \gamma + \theta\gamma) (2\alpha, 2\alpha)} \\ &= 2 \langle \alpha, \gamma \rangle \langle \gamma, \alpha \rangle. \end{aligned}$$

(3) If $\alpha' \neq \alpha$ and $\gamma' \neq \gamma$, we may assume that $\langle \alpha, \theta\gamma \rangle = 0$, and then

$$\begin{aligned} \langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle &= \frac{2(\alpha', \gamma')}{(\gamma', \gamma')} \cdot \frac{2(\gamma', \alpha')}{(\alpha', \alpha')} \\ &= \frac{4(\alpha + \theta\alpha, \gamma + \theta\gamma)^2}{(\gamma + \theta\gamma, \gamma + \theta\gamma) (\alpha + \theta\alpha, \alpha + \theta\alpha)}. \end{aligned}$$

There are again two subcases:

(a) If $\langle \alpha, \theta\alpha \rangle = 0$ and $\langle \gamma, \theta\gamma \rangle = 0$, then

$$\langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle = \frac{4(\alpha, \gamma)^2}{(\gamma, \gamma)(\alpha, \alpha)} = \langle \alpha, \gamma \rangle \langle \gamma, \alpha \rangle.$$

(b) If one of $\langle \alpha, \theta\alpha \rangle$ and $\langle \gamma, \theta\gamma \rangle$ is 0, then, assuming $\langle \alpha, \theta\alpha \rangle = 0$, we have $\langle \gamma, \theta\gamma \rangle = -\frac{1}{2}(\gamma, \gamma)$ and

$$\langle \alpha', \gamma' \rangle \langle \gamma', \alpha' \rangle = \frac{8(\alpha, \gamma)^2}{(\gamma, \gamma)(\alpha, \alpha)} = 2 \langle \alpha, \gamma \rangle \langle \gamma, \alpha \rangle.$$

Thus, when the Dynkin diagram of Π is A_{2n} , A_{2n-1} , D_{n+1} or E_6 , the Dynkin diagram of $p(\Pi)$ is respectively B_n , C_n , B_n or F_4 , as shown in Figure 1.

But when $\Delta(\mathfrak{g}, \mathfrak{h})$ is A_{2n} , the root system $p(\Delta(\mathfrak{g}, \mathfrak{h}))$ is not B_n , but $(BC)_n$. Indeed, if α is the simple root from (a) of Figure 1, then $\alpha + p(\alpha) = 2\alpha'$ is in

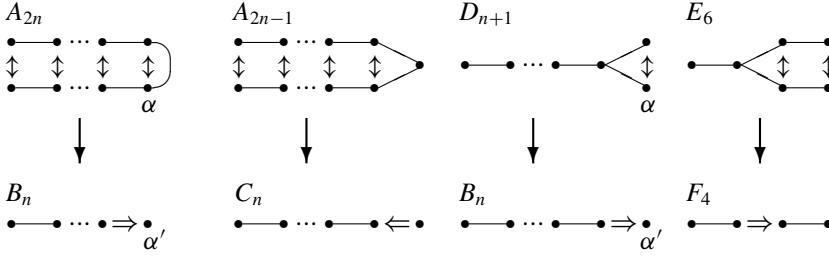


Figure 1

$p(\Delta(\mathfrak{g}, \mathfrak{h}))$. When $\Delta(\mathfrak{g}, \mathfrak{h})$ is D_{n+1} , the root system $p(\Delta(\mathfrak{g}, \mathfrak{h}))$ is just B_n . Indeed, for α from (c) of Figure 1, $2\alpha'$ is not in $p(\Delta(\mathfrak{g}, \mathfrak{h}))$. Then we get

$$\begin{aligned} p(A_{2n}) &= (BC)_n, \quad n \geq 1; & p(A_{2n-1}) &= C_n, \quad n \geq 2; \\ p(D_{n+1}) &= B_n, \quad n \geq 3; & p(E_6) &= F_4. \end{aligned}$$

One knows that such (\mathfrak{g}, θ) and noncompact noncomplex real simple Lie algebras correspond to each other and all such Lie algebras have been classified by their Vogan diagrams.

For (A_{2n}, θ) , only $\mathfrak{sl}(2n+1, \mathbb{R})$'s Dynkin diagram is (A_{2n}, θ) . Now $\mathfrak{k}_0 = \mathfrak{so}(2n+1)$ and $\Delta(\mathfrak{k}, \mathfrak{t}) = B_n$ is a reduced root system of $\Delta(\mathfrak{g}, \mathfrak{t}) = (BC)_n$, so $\text{Spin } \nu$ is primary. In this case,

$$(\mathfrak{k}, \mathfrak{g}) = (\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{sl}(2n+1, \mathbb{C})), \quad n \geq 1.$$

The Dynkin diagrams of $\mathfrak{sl}(2n, \mathbb{R})$ and $\mathfrak{su}^*(2n)$ are (A_{2n-1}, θ) . If $\mathfrak{g}_0 = \mathfrak{sl}(2n, \mathbb{R})$, then $\mathfrak{k}_0 = \mathfrak{so}(2n)$, and $\Delta(\mathfrak{k}, \mathfrak{t}) = D_n$ does not equal $\Delta(\mathfrak{g}, \mathfrak{t}) = C_n$, so the $\text{Spin } \nu$ representation is not primary. If $\mathfrak{g}_0 = \mathfrak{su}^*(2n)$, then $\mathfrak{k}_0 = \mathfrak{sp}(n)$ and $\Delta(\mathfrak{k}, \mathfrak{t}) = C_n = \Delta(\mathfrak{g}, \mathfrak{t})$, so the $\text{Spin } \nu$ representation is primary. In this case,

$$(\mathfrak{k}, \mathfrak{g}) = (\mathfrak{sp}(n, \mathbb{C}), \mathfrak{sl}(2n, \mathbb{C})), \quad n \geq 2.$$

The Dynkin diagrams of $\mathfrak{so}(2r+1, 2n-2r+1)$, with $n \geq 3$ and $0 \leq r \leq [n/2]$, are (D_{n+1}, θ) . If $\mathfrak{g}_0 = \mathfrak{so}(2r+1, 2n-2r+1)$, then $\mathfrak{k}_0 = \mathfrak{so}(2r+1) \oplus \mathfrak{so}(2n-2r+1)$ and $\Delta(\mathfrak{k}, \mathfrak{t}) = B_r \sqcup B_{n-r}$. Therefore $\Delta(\mathfrak{k}, \mathfrak{t}) = \Delta(\mathfrak{g}, \mathfrak{t}) = B_n$ if and only if $r = 0$. So, when $\mathfrak{g}_0 = \mathfrak{so}(1, 2n+1)$, or $(\mathfrak{k}, \mathfrak{g}) = (\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{so}(2n+2, \mathbb{C}))$ with $n \geq 3$, the $\text{Spin } \nu$ representation is primary.

The Dynkin diagrams of $\mathfrak{e}_6(-26)$ and $\mathfrak{e}_6(6)$ are (E_6, θ) . If $\mathfrak{g}_0 = \mathfrak{e}_6(-26)$ then $\mathfrak{k}_0 = \mathfrak{f}_4$. Then $\Delta(\mathfrak{k}, \mathfrak{t}) = F_4 = \Delta(\mathfrak{g}, \mathfrak{t})$ and the $\text{Spin } \nu$ representation is primary. In this case $(\mathfrak{k}, \mathfrak{g}) = (F_4, E_6)$, where we use E_6 (respectively, F_4) to denote the simple complex Lie algebra of type E_6 (respectively, F_4). If $\mathfrak{g}_0 = \mathfrak{e}_6(6)$, then $\mathfrak{k}_0 = \mathfrak{sp}(4)$. Obviously, $\Delta(\mathfrak{k}, \mathfrak{t}) = C_4$ does not equal $\Delta(\mathfrak{g}, \mathfrak{t})$, so the $\text{Spin } \nu$ representation is not primary. \square

Remark 4.8. The isotropy representations ν of (F_4, E_6) , of $(\mathfrak{sp}(n, \mathbb{C}), \mathfrak{sl}(2n, \mathbb{C}))$, and of $(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{so}(2n+2, \mathbb{C}))$, and are the little adjoint representations (that is, the representation having the short dominant root of \mathfrak{k} as the highest weight).

Now we will deal with the general case when \mathfrak{g} , from a symmetric pair $(\mathfrak{k}, \mathfrak{g})$, is semisimple.

Suppose $\mathfrak{g} = \mathfrak{g}_1 \oplus \cdots \oplus \mathfrak{g}_n$ is a decomposition of \mathfrak{g} into direct sum of ideals and $\theta(\mathfrak{g}_i) = \mathfrak{g}_i$ for all i . Let $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$, and $\mathfrak{g}_i = \mathfrak{k}_i \oplus \mathfrak{p}_i$ be the Cartan decomposition. Then $\mathfrak{k} = \mathfrak{k}_1 \oplus \cdots \oplus \mathfrak{k}_n$ and $\mathfrak{p} = \mathfrak{p}_1 \oplus \cdots \oplus \mathfrak{p}_n$.

Lemma 4.9. *The representation $\text{Spin } \nu : \mathfrak{k} \rightarrow \text{End } S$ is primary if and only if $\text{Spin } \nu_i : \mathfrak{k}_i \rightarrow \text{End } S_i$ is primary for all i .*

Proof. Let \mathfrak{t}_i be a Cartan subalgebra of \mathfrak{k}_i . Then $\mathfrak{t} = \bigoplus_i \mathfrak{t}_i$ is a Cartan subalgebra of \mathfrak{k} . We know that $\Delta(\mathfrak{g}, \mathfrak{t}) = \bigsqcup_i \Delta(\mathfrak{g}_i, \mathfrak{t}_i)$ and $\Delta(\mathfrak{k}, \mathfrak{t}) = \bigsqcup_i \Delta(\mathfrak{k}_i, \mathfrak{t}_i)$, as well as $\Delta(\mathfrak{g}_i, \mathfrak{t}_i) \perp \Delta(\mathfrak{g}_j, \mathfrak{t}_j)$ and $\Delta(\mathfrak{k}_i, \mathfrak{t}_i) \perp \Delta(\mathfrak{k}_j, \mathfrak{t}_j)$ for $i \neq j$. Fix a positive root system $P_{\mathfrak{k}}$ of $\Delta(\mathfrak{k}, \mathfrak{t})$; then $P_{\mathfrak{k}_i} = P \cap \Delta(\mathfrak{k}_i, \mathfrak{t}_i)$ is a positive root system of $\Delta(\mathfrak{k}_i, \mathfrak{t}_i)$. If P_i is a positive root system of $\Delta(\mathfrak{g}_i, \mathfrak{t}_i)$, then $P = \bigsqcup_i P_i$ is a positive root system of $\Delta(\mathfrak{g}, \mathfrak{t})$, and all the positive root systems of $\Delta(\mathfrak{g}, \mathfrak{t})$ can be obtained in this way. Then it is clear that $\text{card } D(P_{\mathfrak{k}}) = \prod_i \text{card } D(P_{\mathfrak{k}_i})$. Since $\text{card } D(P_{\mathfrak{k}}) = 1$ if and only if $\text{card } D(P_{\mathfrak{k}_i}) = 1$ for all i , it follows that $\text{Spin } \nu$ is primary if and only if $\text{Spin } \nu_i$ are primary for all i . \square

Thus, we need only find all the “minimal” reduced symmetric pairs such that the corresponding $\text{Spin } \nu$ representations are primary. The complex semisimple Lie algebra \mathfrak{g} can be uniquely decomposed into a direct sum of simple ideals. Since θ is an involutory automorphism, it acts on the set of simple ideals and it must fix some of them and permute in 2-cycles the rest of them. So one has

Lemma 4.10. *The semisimple Lie algebra \mathfrak{g} can be decomposed as*

$$\mathfrak{g} = (\mathfrak{g}_1 \oplus \mathfrak{g}_1) \oplus (\mathfrak{g}_2 \oplus \mathfrak{g}_2) \oplus \cdots \oplus (\mathfrak{g}_s \oplus \mathfrak{g}_s) \oplus \mathfrak{g}_{s+1} \oplus \cdots \oplus \mathfrak{g}_{s+l},$$

where every \mathfrak{g}_i is a simple ideal of \mathfrak{g} such that: when $1 \leq i \leq s$, we have $\theta(\mathfrak{g}_i \oplus \mathfrak{g}_i) = \mathfrak{g}_i \oplus \mathfrak{g}_i$ and θ interchanges the two \mathfrak{g}_i ; and, when $s < i \leq s + j$, we have $\theta(\mathfrak{g}_i) = \mathfrak{g}_i$.

Note that θ must be an isomorphism of the two \mathfrak{g}_i 's when $1 \leq i \leq s$, but that θ cannot be the identity on \mathfrak{g}_i when $s < i \leq s + j$, because (\mathfrak{g}, θ) is reduced.

Lemma 4.11. *If $\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_1$, with \mathfrak{g}_1 a simple ideal, and θ interchanges the two ideals, then $\text{Spin } \nu$ is primary of type $\pi_{\rho_{\mathfrak{g}_1}}$.*

Proof. Because θ interchanges the two ideals, $\theta(X, Y) = (\varphi^{-1}(Y), \varphi(X))$ for some isomorphism φ of \mathfrak{g}_1 . Recall the definition of an isomorphism of involutory Lie algebras from page 39. Define an isomorphism $\psi = (\varphi, I) : \mathfrak{g}_1 \oplus \mathfrak{g}_1 \rightarrow \mathfrak{g}_1 \oplus \mathfrak{g}_1$ by $(X, Y) \mapsto (\varphi(X), Y)$. Then (\mathfrak{g}, θ) is isomorphic to (\mathfrak{g}, θ') through ψ , where

$\theta'(X, Y) = (Y, X)$. With respect to θ' , we have $\mathfrak{k} = \{(X, X) \mid X \in \mathfrak{g}_1\} \cong \mathfrak{g}_1$ and $\mathfrak{p} = \{(X, -X) \mid X \in \mathfrak{g}_1\}$, and the representation ν is just the adjoint representation of \mathfrak{g}_1 . By Theorem 40 of [Kostant 1997], $\text{Spin } \nu$ is primary of type $\pi_{\rho_{\mathfrak{g}_1}}$. \square

Remark 4.12. In this case it can be computed directly that $\rho_n = \rho_{\mathfrak{g}_1}$.

Combining the results from Proposition 4.7 to Lemma 4.11, we get:

Theorem 4.13. *Let (\mathfrak{g}, θ) be a reduced involutory complex semisimple Lie algebra and $(\mathfrak{k}, \mathfrak{g})$ be the corresponding symmetric pair. Then $\text{Spin } \nu$ is primary if and only if $(\mathfrak{k}, \mathfrak{g})$ is one of the following:*

- (1) $(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{sl}(2n+1, \mathbb{C}))$, $n \geq 1$;
 $(\mathfrak{sp}(n, \mathbb{C}), \mathfrak{sl}(2n, \mathbb{C}))$, $n \geq 2$;
 $(\mathfrak{so}(2n+1, \mathbb{C}), \mathfrak{so}(2n+2, \mathbb{C}))$, $n \geq 3$;
 (F_4, E_6) ;
- (2) $\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_1$ and $\mathfrak{k} = \{(X, X) \mid X \in \mathfrak{g}_1\}$, where \mathfrak{g}_1 is a complex simple Lie algebra;
- (3) direct sums of $(\mathfrak{k}, \mathfrak{g})$ in (1) and (2).

When $(\mathfrak{k}, \mathfrak{g})$ is as above, $\text{Spin } \nu$ is primary of type π_{ρ_n} .

Combining Proposition 2.4 and Theorem 4.13, we get our main result:

Theorem 4.14. *Assume that $\nu : \mathfrak{r} \rightarrow \mathfrak{so}(\mathfrak{p})$ is the complexified differential of a faithful $B_{\mathfrak{p}}$ -orthogonal representation of a compact Lie group and that $\mathfrak{p}^{\mathfrak{r}} = 0$. Assume that $\text{Spin } \nu$ is primary. Then $\mathfrak{g} = \mathfrak{r} \oplus \mathfrak{p}$ has a semisimple Lie algebra structure such that \mathfrak{r} is a Lie subalgebra of \mathfrak{g} , that $(\mathfrak{r}, \mathfrak{g})$ is a reduced symmetric pair, and that ν is the isotropy representation of $(\mathfrak{r}, \mathfrak{g})$. Furthermore, the symmetric pair $(\mathfrak{r}, \mathfrak{g})$ must be one of those listed in Theorem 4.13, and $\text{Spin } \nu$ is primary of type π_{ρ_n} .*

Recalling Remark 4.5, we get, as a corollary of Proposition 20 of [Kostant 1997]:

Corollary 4.15. *Let $(\mathfrak{k}, \mathfrak{g})$ be a symmetric pair in the list of Theorem 4.13. Then the corresponding $\text{Spin } \nu$ representation is primary of type π_{ρ_n} . Let \mathfrak{k} act on $\wedge \mathfrak{p}$ via β , and let $J = (\wedge \mathfrak{p})^{\mathfrak{k}}$. Then $\dim V_{\rho_n} = 2^{l_0}$ and $\dim J = 2^{l_0}$. As a subalgebra of $C(\mathfrak{p})$, J is isomorphic to a matrix algebra if l_0 is even, and is isomorphic to a sum of two matrix algebras if l_0 is odd. Furthermore,*

$$C(\mathfrak{p}) \cong \text{End } V_{\rho_n} \otimes J$$

as algebras. Finally, as \mathfrak{k} -modules,

$$\wedge \mathfrak{p} \cong 2^{l_0} V_{\rho_n} \otimes V_{\rho_n}.$$

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