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## HYPERBOLIC MANIFOLDS CONTAINING HIGH TOPOLOGICAL INDEX SURFACES

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#### Abstract

If a graph is in bridge position in a 3-manifold so that the graph complement is irreducible and boundary-irreducible, we generalize a result of Bachman and Schleimer to prove that the complexity of a surface properly embedded in the complement of the graph bounds the graph distance of the bridge surface. We use this result to construct, for any natural number $n$, a hyperbolic manifold containing a surface of topological index $n$.


## 1. Introduction

It has become increasingly common and useful to measure distances in complexes associated to surfaces between certain important subcomplexes associated with the surface embedded in a 3-manifold. These techniques provide a means to indicate the inherent complexity of links in a manifold, decomposing surfaces, or the manifold itself. Bachman [2010] defined the topological index of a surface as a topological analogue of the index of an unstable minimal surface. When the distance is small, the notion of topological index refines this distance, by looking at the homotopy type of a certain subcomplex.

In the same way that incompressible surfaces share important properties with strongly irreducible surfaces (distance $>2$ ) despite being compressible, the topological index provides a degree of measurement of how similar irreducible, but weakly reducible (distance $=1$ ) surfaces are to incompressible surfaces. Bachman [2012a; 2012b; 2012c] has shown that surfaces with a well-defined topological index in a 3-manifold can be put into a sort of normal form with respect to a triangulation of the manifold, generalizing the ideas of normal form introduced by Kneser [1929] and almost normal form introduced by Rubinstein [1995], and mirroring results about geometrically minimal surfaces due to Colding and Minicozzi [2004a; 2004b; 2004c; 2004d; 2015].

Lee [2015] has shown that an irreducible manifold containing an incompressible surface contains topologically minimal surfaces of arbitrarily high genus, but has

[^0]only shown that the topological index of such surfaces is at least two. Bachman and Johnson [2010] showed that surfaces of arbitrarily high index exist. These surfaces are the lifts of Heegaard surfaces in an $n$-fold cover of a manifold obtained by gluing together boundary components of the complement of a link in $S^{3}$. A byproduct of their construction is that the resulting manifolds are toroidal.

This leaves open the question of whether the much more ubiquitous class of hyperbolic manifolds can also contain high topological index surfaces. Here we construct certain hyperbolic manifolds containing such surfaces. We generalize the construction in [Bachman and Johnson 2010] by gluing along the boundary components of the complement of a graph in $S^{3}$ to show:

Theorem 1.1. There is a closed 3-manifold $M^{1}$, with an index 1 Heegaard surface $S$, such that for each $n$, the lift of $S$ to some $n$-fold cover $M^{n}$ of $M^{1}$ has topological index $n$. Moreover, $M^{n}$ is hyperbolic for all $n$.

In order to guarantee the hyperbolicity of $M^{n}$, we must rule out the existence of high Euler characteristic surfaces in the graph complement. To that end, we define the graph distance, $d_{\mathcal{G}}$, of graphs in $S^{3}$, an analogue of bridge distance of links. In the spirit of Hartshorn [2002] and Bachman and Schleimer [2005], we show that the complexity of an essential surface is bounded below by the graph bridge distance:

Theorem 1.2. Let $\Gamma$ be a graph in a closed, orientable 3-manifold, $M$, which is in bridge position with respect to a Heegaard surface, $B$, so that $M \backslash n(\Gamma)$ is irreducible and boundary-irreducible. Let $S$ be a properly embedded, orientable, incompressible, boundary-incompressible, non-boundary-parallel surface in $M \backslash n(\Gamma)$. Then $d_{\mathcal{G}}(B, \Gamma)$ is bounded above by $2(2 g(S)+|\partial S|-1)$.

In Section 2 we lay out the definitions of the various complexes and distances we will use, and prove Theorem 1.2. In Section 3, we prove Theorem 1.1.

## 2. Definitions

Given a link $\mathcal{L} \subset S^{3}$, a bridge sphere for $\mathcal{L}$ is a sphere, $B$, embedded in $S^{3}$, intersecting the link $\mathcal{L}$ transversely, and dividing $S^{3}$ into two 3-balls, $V$ and $W$, so that there exist disks $D_{V}$ and $D_{W}$ properly embedded in $V$ and $W$, respectively, so that $\mathcal{L} \cap V \subset D_{V}$ and $\mathcal{L} \cap W \subset D_{W}$ are each a collection of arcs. If there are $b$ arcs, the link is said to be $b$-bridge with respect to $B$.

Goda [1997] introduced the notion of a bridge sphere for a spatial $\theta$-graph, and this was extended by Ozawa [2012]. A bridge sphere for a (spatial) graph $\Gamma$ is a sphere, $B$, embedded in $S^{3}$, intersecting $\Gamma$ transversely in the interior of edges, and dividing $S^{3}$ into two 3-balls, $V$ and $W$, so that there exist disks $D_{V}$ and $D_{W}$ properly embedded in $V$ and $W$, respectively, so that $\Gamma \cap V \subset D_{V}$ and $\Gamma \cap W \subset D_{W}$ are each a collection of trees and/or arcs.

If $B$ is a bridge sphere for a link $\mathcal{L}$, then a bridge disk is a disk properly embedded in one of the components of $\left.\overline{\left(S^{3} \backslash n(\mathcal{L})\right) \backslash B}\right)$, whose boundary consists of exactly two arcs, meeting at their endpoints, with one arc essential in $B \backslash n(\mathcal{L})$, and the other essential in $\partial n(\mathcal{L}) \backslash B$. We refer to the arc in the boundary of the disk that is contained in $B$ as a bridge arc. Similarly, if $B$ is a bridge sphere for a graph $\Gamma$, then a graph-bridge disk is a disk properly embedded in one of the components of $\overline{\left.\left(S^{3} \backslash n(\Gamma)\right) \backslash B\right)}$, whose boundary consists of exactly two arcs, meeting at their endpoints, with one arc essential in $B \backslash n(\Gamma)$, and the other essential in $\partial n(\Gamma) \backslash B$. We refer to the arc in the boundary of the disk that is contained in $B$ as a graph-bridge arc.

Definition 2.1. The curve complex for a surface $B$ with (possibly empty) boundary is the complex with vertices corresponding to the isotopy classes of essential simple closed curves in $B$, so that a collection of vertices defines a simplex if representatives of the corresponding isotopy classes can be chosen to be pairwise disjoint. We will denote the curve complex for a surface $B$ by $\mathcal{C}(B)$.

Definition 2.2. The arc and curve complex for a surface $B^{\prime}$ with boundary is the complex with vertices corresponding to the (free) isotopy classes of essential simple closed curves and properly embedded arcs in $B^{\prime}$. A collection of vertices defines a simplex if representatives of the corresponding isotopy classes can be chosen to be pairwise disjoint. We will denote the arc and curve complex for a surface $B^{\prime}$ by $\mathcal{A C}\left(B^{\prime}\right)$.

If $B$ is a surface embedded in a manifold, and a 1 -dimensional complex intersects $B$ transversely, we will refer to the surface obtained by removing a neighborhood of the 1 -complex by $B^{\prime}$. We will often refer to $\mathcal{C}\left(B^{\prime}\right)$ simply by $\mathcal{C}(B)$, and $\mathcal{A C}\left(B^{\prime}\right)$ simply by $\mathcal{A C}(B)$.

Definition 2.3. Let $B$ be a surface with at least two distinct, essential curves. Given two collections $X$ and $Y$ of vertices in the complex $\mathcal{C}(B)$ (resp., $\mathcal{A C}(B)$ ), the distance between $X$ and $Y$, denoted $d_{\mathcal{C}(B)}(X, Y)$ (resp., $d_{\mathcal{A C}(B)}(X, Y)$ ), is the minimal number of edges in any path in $\mathcal{C}(B)$ (resp., $\mathcal{A C}(B)$ ) from a vertex in $X$ to a vertex in $Y$. When the surface is understood, we often just write $d_{\mathcal{C}}$ (resp., $d_{\mathcal{A C}}$ ).

We will be working with four subtly different but closely related subcomplexes, and some associated notions of distance.

Definition 2.4. Let $B$ be a properly embedded surface separating a manifold $M$ into two components, $V$ and $W$. Define the disk set of $V$ (resp., $W$ ), denoted $\mathcal{D}_{V} \subset \mathcal{C}(B)$, (resp., $\mathcal{D}_{W} \subset \mathcal{C}(B)$ ), as the set of all vertices corresponding to essential simple closed curves in $B$ that bound embedded disks in $V$ (resp., $W$ ). Define the disk set of $B$, denoted $\mathcal{D}_{B}$, as the set of all vertices corresponding to essential simple closed curves in $B$ that bound embedded disks in $M$.

Definition 2.5. Let $B$ be a bridge sphere for a link $\mathcal{L}$, bounding 3-balls $V$ and $W$, with at least 6 marked points corresponding to the transverse intersections of $\mathcal{L}$ with $B$. The distance of the bridge surface, denoted $d_{\mathcal{C}}(B, \mathcal{L})$, is $d_{\mathcal{C}\left(B^{\prime}\right)}\left(\mathcal{D}_{V}, \mathcal{D}_{W}\right)$, the distance in the curve complex of $B^{\prime}$ between $\mathcal{D}_{V}$ and $\mathcal{D}_{W}$.

The fundamental building block in our construction will be the exterior of a graph that is highly complex as viewed from the arc and curve complex. The existence of such a block will follow from a result of Blair, Tomova, and Yoshizawa, using "warped pants decompositions" and Dehn twists to construct gluing maps resulting in high bridge distance link complements. It is a special case of [Blair et al. 2013, Corollary 5.3 and the proof of Theorem 4.9].
Theorem 2.6 [Blair et al. 2013]. Given nonnegative integers $b_{1}, b_{2}$ and $d$, with $b_{1}+b_{2} \geq 3$, there exists a 2 -component link $\mathcal{L}$ in $S^{3}$, and a bridge sphere $B$ for $\mathcal{L}$ so that $\mathcal{L}$ is $\left(b_{1}+b_{2}\right)$-bridge with respect to $B$, the components of $\mathcal{L}$ are $b_{1}$ - and $b_{2}$-bridge with respect to $B$, and $d_{\mathcal{C}}(B, \mathcal{L}) \geq d$.
Definition 2.7. Let $B$ be a bridge sphere for a link $\mathcal{L}$, bounding 3-balls $V$ and $W$. Define the bridge disk set of $V$ (resp., $W$ ), denoted $\mathcal{B} \mathcal{D}_{V} \subset \mathcal{A C}(B)$ (resp., $\mathcal{B} \mathcal{D}_{W}$ ), as the set of all vertices either corresponding to essential simple closed curves in $B^{\prime}$ that bound embedded disks in $V \backslash \mathcal{L}$ (resp., $W \backslash \mathcal{L}$ ), or corresponding to bridge arcs in $B^{\prime}$ contained in the boundaries of bridge disks in $V$ (resp., $W$ ).
Definition 2.8. Let $B$ be a bridge sphere for a link $\mathcal{L}$, bounding 3-balls $V$ and $W$. The bridge distance of the bridge surface $B$, which we denote by $d_{\mathcal{B D}}(B, \mathcal{L})$, is $d_{\mathcal{A C}\left(B^{\prime}\right)}\left(\mathcal{B} \mathcal{D}_{V}, \mathcal{B} \mathcal{D}_{W}\right)$, the distance in the arc and curve complex of $B^{\prime}$ between $\mathcal{B} \mathcal{D}_{V}$ and $\mathcal{B} \mathcal{D}_{W}$.
Lemma 2.9 [Blair et al. 2017, Lemma 2]. If $B$ is a bridge surface which is not a sphere with four or fewer punctures, then $d_{\mathcal{B D}}(B, \mathcal{L}) \leq d_{\mathcal{C}}(B, \mathcal{L}) \leq 2 d_{\mathcal{B D}}(B, \mathcal{L})$.
Definition 2.10. Let $B$ be a bridge sphere for graph $\Gamma$, bounding 3-balls $V$ and $W$. The graph disk set of $V$ (resp., $W$ ) denoted $\mathcal{G D}_{V} \subset \mathcal{A C}(B)$ (resp., $\mathcal{G} \mathcal{D}_{W} \subset \mathcal{A C}(B)$ ), is the set of all vertices either corresponding to essential simple closed curves in $B \backslash n(\Gamma)$ that bound embedded disks in $V \backslash n(\Gamma)$ (resp., $W \backslash n(\Gamma)$ ), or corresponding to graph-bridge arcs in $B \backslash n(\Gamma)$ contained in the boundaries of graph-bridge disks in $V$ (resp., $W$ ).
Definition 2.11. Let $B$ be a bridge sphere for graph $\Gamma$. The graph distance of the bridge surface, denoted $d_{\mathcal{G}}(B, \Gamma)$ is $d_{\mathcal{A C}\left(B^{\prime}\right)}\left(\mathcal{G D} \mathcal{D}_{V}, \mathcal{G} \mathcal{D}_{W}\right)$, the distance in the arc and curve complex of $B^{\prime}=B \backslash n(\Gamma)$ between $\mathcal{G} \mathcal{D}_{V}$ and $\mathcal{G} \mathcal{D}_{W}$.
Lemma 2.12. Let $\mathcal{L}$ be a link in bridge position with respect to a bridge sphere $B$, bounding 3-balls $V$ and $W$, and let $\Gamma_{\mathcal{L}}$ be a graph in bridge position with respect to $B$ formed by adding edges to $\mathcal{L}$ in $V$ that are simultaneously parallel into $B$ in the complement of $\mathcal{L}$, and so that $\Gamma_{\mathcal{L}} \cap V$ has at least two components.

If $D \subset\left(V \backslash n\left(\Gamma_{\mathcal{L}}\right)\right)$ is a graph-bridge disk for $\Gamma_{\mathcal{L}}$, then there is a bridge disk $D^{\prime}$ for $\mathcal{L}$ in $(V \backslash n(\mathcal{L}))$ which is disjoint from $D$.
Proof. Let $\Gamma_{1}, \ldots, \Gamma_{\ell}$ be the connected components $\Gamma_{\mathcal{L}} \cap V$, and let $\Gamma_{i}$ be the component of $\Gamma_{\mathcal{L}} \cap V$ to which $D$ is incident.

Over all bridge disks $E \subset V$ for $\mathcal{L}$ disjoint from $\Gamma_{i}$, choose one which minimizes $|D \cap E|$. Suppose the intersection is nonempty. Any loops of intersection can be removed because $(V \backslash n(\Gamma))$ is a handlebody and therefore irreducible. Any points of intersection between $\partial D$ and $\partial E$ are contained in $\partial D \cap B$ and $\partial E \cap B$. Choose an arc $\gamma$ of $|D \cap E|$. The arc $\gamma$ cuts $D$ into two disks $D_{\gamma_{1}}$ and $D_{\gamma_{2}}$. For one of $j=1$ or 2 , $\partial D_{\gamma_{j}} \cap \partial D$ is contained in $B$. Call that disk $D_{\gamma}$. Consider an arc $\alpha$ of $|D \cap E|$ outermost in $D_{\gamma}$. If the interior of $D_{\gamma}$ is disjoint from $E$ then take $\alpha$ to be $\gamma$. The arc $\alpha$ cuts off a disk $D_{\alpha}$ from $D_{\gamma}$ and cuts $E$ into two disks $E_{1}$ and $E_{2}$, only one of whose (say $E_{2}$ ) boundary is incident to $\mathcal{L}$. The disk $E_{2} \cup D_{\alpha}=E^{\prime}$ is a bridge disk for $\mathcal{L}$ and intersects $D$ fewer times than $E$, contradicting the minimality of $|D \cap E|$.

The above implies that the distance in the arc and curve complex of $B \backslash n(\Gamma)$ between $\mathcal{G} \mathcal{D}_{V}$ and $\mathcal{B} \mathcal{D}_{V}$ is less than or equal to 1.
Corollary 2.13. Let $\mathcal{L}$ and $\Gamma_{\mathcal{L}}$ be as above. Then $d_{\mathcal{B D}}(B, \mathcal{L}) \leq 1+d_{\mathcal{G}}\left(B, \Gamma_{\mathcal{L}}\right)$.
Proof. Since $W \backslash n(\Gamma)$ contains no graph-bridge disks, $\mathcal{G} \mathcal{D}_{W}=\mathcal{B} \mathcal{D}_{W}$. Suppose that the distance in $\mathcal{A C}\left(B^{\prime}\right)$ between $\mathcal{G} \mathcal{D}_{W}=\mathcal{B} \mathcal{D}_{W}$ and $\mathcal{G} \mathcal{D}_{V}$ is realized by a path between vertices $X \in \mathcal{G} \mathcal{D}_{W}$ and $Y \in \mathcal{G} \mathcal{D}_{V}$. Then, by Lemma 2.12, there is a vertex $Z$ of $\mathcal{B D} \mathcal{D}_{V}$ so that the distance between $Y$ and $Z$ is at most 1 , and therefore $d_{\mathcal{A C}\left(B^{\prime}\right)}\left(\mathcal{B \mathcal { D } _ { W }}, \mathcal{B D}_{V}\right) \leq d_{\mathcal{A C}\left(B^{\prime}\right)}\left(\mathcal{G} \mathcal{D}_{W}, \mathcal{G} \mathcal{D}_{V}\right)+1$.

Hartshorn [2002] proved that an essential closed surface in a 3-manifold creates an upper bound on the possible distances of Heegaard splittings of that manifold in terms of the genus of the essential surface.
Theorem 2.14 [Hartshorn 2002, Theorem 1.2]. Let M be a Haken 3-manifold containing an incompressible surface of genus $g$. Then any Heegaard splitting of $M$ has distance at most $2 g$.

This idea has been generalized in numerous ways, including in [Bachman and Schleimer 2005] where it is shown that the distance of a bridge Heegaard surface in a knot complement is bounded by twice the genus plus the number of boundary components of an essential properly embedded surface.
Theorem 2.15 [Bachman and Schleimer 2005, Theorem 5.1]. Let $K$ be a knot in a closed, orientable 3-manifold $M$ which is in bridge position with respect to a Heegaard surface B. Let $S$ be a properly embedded, orientable, essential surface in $M \backslash n(K)$. Then the distance of $K$ with respect to $B$ is bounded above by twice the genus of $S$ plus $|\partial S|$.

We will need a yet more general version, since we will be concerned with surfaces properly embedded in graph complements.

The essence of both results is that the distance of a bridge or Heegaard surface is bounded above in terms of the complexity of an essential properly embedded surface. We will generalize this result to link and graph complements, with the additional benefit of avoiding many of the technical details of [Bachman and Schleimer 2005] necessary to treat the boundary components. Unfortunately, our bound will be worse than that obtained by Bachman and Schleimer, though it will be sufficient for many applications of this type of bound (see, e.g., [Mossessian 2016; Du and Qiu 2016; Ohshika and Sakuma 2016; Bachman 2013; Namazi 2007]). We note also that our proof requires a minimal starting position similar to that used by Hartshorn, an assumption Bachman and Schleimer's method was able to avoid.

We now prove Theorem 1.2.
Theorem 1.2. Let $\Gamma$ be a graph in a closed, orientable 3-manifold, $M$, which is in bridge position with respect to a Heegaard surface, $B$, so that $M \backslash n(\Gamma)$ is irreducible and boundary-irreducible. Let $S$ be a properly embedded, orientable, incompressible, boundary-incompressible, non-boundary-parallel surface in $M \backslash n(\Gamma)$. Then $d_{\mathcal{G}}(B, \Gamma)$ is bounded above by $2(2 g(S)+|\partial S|-1)$.
Proof of Theorem 1.2. In the case that $S$ is closed, we note that the proofs of Theorems 2.14 and 2.15 both apply to closed surfaces in manifolds with boundary as long as the manifold is irreducible. In the case that $\partial S \neq \varnothing$ we will double $M \backslash n(\Gamma)$ along $\partial n(\Gamma)$ to obtain a closed surface and show that the surface can be made to fulfill all the hypotheses necessary to use the machinery in the proof of Theorem 2.14 to obtain the bound on distance.

First, isotope $S$ to intersect $B$ minimally, among all isotopy representatives of $S$. Let $V$ and $W$ be the handlebodies on either side of $B$. Double $M \backslash n(\Gamma)$ along $\partial n(\Gamma)$, and call the resulting manifold $\widehat{M}$. Let the doubles of $S, B, V$, and $W$ be $\widehat{S}$, $\widehat{B}, \widehat{V}$, and $\widehat{W}$, respectively, and let $G$ be $\partial n(\Gamma)$ in $\widehat{M}$, with respective copies $M_{i}$, $S_{i}, B_{i}, V_{i}$, and $W_{i}$, for $i=1,2$.

Note that $\widehat{B}$ is a Heegaard surface for $\widehat{M}$. (The proof of this is very similar to the proof of Proposition 3.2 below.) Also, note that since $S$ is incompressible and $\partial$-incompressible in $M \backslash n(\Gamma), \widehat{S}$ is an incompressible closed surface in $\widehat{M}$, for otherwise an outermost arc of intersection between a compressing disk and $G$ would show $S$ to have been $\partial$-compressible in $M \backslash n(\Gamma)$. Since $\partial n(\Gamma)$ was incompressible in $M \backslash n(\Gamma), G$ is incompressible in $\widehat{M}$.
Claim 1. Each of $\widehat{S} \cap \widehat{V}$ and $\widehat{S} \cap \widehat{W}$ are incompressible.
Proof. If, say, $\widehat{S} \cap \widehat{V}$ had a compressing disk $D$, then since $\widehat{S}$ is incompressible in $\widehat{M}$, there would have to be a disk $D^{\prime}$ in $\widehat{S}$ with $\partial D^{\prime}=\partial D$, and $D^{\prime} \cap \widehat{B} \neq \varnothing$. We may choose $D$ to be a compressing disk which intersects $G$ minimally. Further,
since $G$ is incompressible, we may choose $D$ to intersect $G$ only in arcs, if at all. But $\widehat{M}$ is irreducible, so $D \cup D^{\prime}$ bounds a ball and we may isotope $\widehat{S}$ across this ball from $D^{\prime}$ to $D$, lowering the number of intersections between $\widehat{S}$ and $\widehat{B}$.

If $D^{\prime} \cap G=\varnothing$, then this can be viewed as an isotopy of $S$ in $M \backslash n(\Gamma)$ which reduces the number of intersections between $S$ and $B$, a contradiction.

If $D^{\prime} \cap G \neq \varnothing$ we still arrive at a contradiction. Consider a loop, $\ell$, of intersection in $\left(D \cup D^{\prime}\right) \cap G$, innermost in $D \cup D^{\prime}$. Since $D \cap G$ only contains arcs, $\ell$ consists of two arcs, $\alpha$ and $\alpha^{\prime}$ in $D$ and $D^{\prime}$ respectively. Thus $\ell$ bounds a disk $D_{\ell}$ in $G, \alpha$ cuts off a subdisk $D_{\alpha}$ of $D$ and $\alpha^{\prime}$ cuts off a subdisk $D_{\alpha^{\prime}}$ of $D^{\prime}$, both of which are in either $M_{1}$ or $M_{2}$, say $M_{1}$. Now we have an isotopy of $S_{1}$ from $D_{\alpha} \cup D_{\alpha^{\prime}}$ to $D_{\ell}$.

Independent of whether $D_{\alpha^{\prime}}$ intersected $B$, we could have chosen $D$ to have fewer intersections with $G$, contradicting our choice of $D$ to minimize intersections.
Claim 2. Every intersection of $\widehat{S}$ with $\widehat{B}$ is essential in $\widehat{B}$.
Proof. Curves of intersection in $\widehat{S} \cap \widehat{B}$ which are inessential in both surfaces would either give rise to a reduction in $|S \cap B|$ or could have come from the doubling of arcs in $S \cap B$ which would give rise to a reduction in $|S \cap B|$ in a fashion similar to the previous claim.
Claim 3. There are no д-parallel annular components of $\widehat{S} \cap \widehat{W}$ or $\widehat{S} \cap \widehat{V}$.
Proof. Any such component disjoint from $G$ would have been eliminated when $|S \cap B|$ was minimized. The intersection of any such component intersecting $G$ with $M_{1}$ would be a $\partial$-parallel disk which also would have been eliminated when $|S \cap B|$ was minimized.

Now we have satisfied all the hypotheses to obtain the sequence of isotopic copies of $\widehat{S}$ described in Lemmas 4.4 and 4.5 of [Hartshorn 2002]. Depending on whether either of $\widehat{S} \cap \widehat{V}$ or $\widehat{S} \cap \widehat{W}$ contains disk components or not, we apply either Lemma 4.4 or 4.5 , respectively, of [Hartshorn 2002] to obtain a sequence of boundary compressions of $\widehat{S}$ in $\widehat{V}$ or $\widehat{W}$, which gives rise to a path in $\mathcal{C}(\widehat{S})$. A priori, this path would not restrict to a path in $\mathcal{A C}(S)$, but the following claim shows that we can choose the compressions to be symmetric across $G$, and so each compression will correspond to an edge in $\mathcal{A C}(S)$.
Claim 4. If there exists an elementary $\partial$-compression of $\widehat{S}$ in $\widehat{V}$ (resp., $\widehat{W}$ ), then there exists an elementary compression of $\widehat{S}$ in $\widehat{V}$ (resp., $\widehat{W}$ ) which is symmetric across $G$ in the sense that either
(1) the $\partial$-compressing disk $D_{1}$ is disjoint from $G$ in $M_{1}$, and there is a corresponding $\partial$-compressing disk $D_{2}$ in $M_{2}$, or
(2) the $\partial$-compression is along a disk that is symmetric across $G$.

Proof. Let $D$ be an elementary $\partial$-compression disk for, say, $\widehat{S} \cap \widehat{V}$ chosen to minimize $|D \cap G|$. We may restrict attention to such disks with $|D \cap G|>0$.

First, we observe that $D \cap G$ cannot contain any loops of intersection, for a loop of $D \cap G$ innermost in $D$ bounds a subdisk of $D$ which would either give rise to a compression for $G$ or would provide a means of isotoping $D$ so as to lower $|D \cap G|$. Thus, $D \cap G$ consists only of arcs. These arcs are either

- vertical arcs, with one endpoint on each of $\widehat{S}$ and $\widehat{B}$,
- $\widehat{S}$-arcs, with both endpoints on $\widehat{S}$, or
- $\widehat{B}$-arcs, with both endpoints on $\widehat{B}$.

Consider an $\widehat{S}$-arc of $D \cap G$, outermost in $D$, cutting off subdisk $D^{\prime}$ from $D$, with boundary consisting of $\sigma$ in $\widehat{S}$ and $\gamma$ in $G$. Without loss of generality, assume $D^{\prime} \subset M_{1}$. If $\sigma$ is essential in $\widehat{S} \cap M_{1}$, then $D^{\prime}$ is a boundary-compression disk for $S$ in $M$, which is impossible. If $\sigma$ is inessential in $\widehat{S} \cap M_{1}$, then it must cobound a disk $E$ in $\widehat{S} \cap M_{1}$ together with an arc $\sigma^{\prime} \subseteq \partial\left(\widehat{S} \cap M_{1}\right)$. The curve $\gamma \cup \sigma^{\prime}$ cannot be essential in $G$, else $D^{\prime} \cup E$ would be a compressing disk for $G$. Thus, $\gamma \cup \sigma^{\prime}$ bounds a disk, $F \subseteq G$. Now $F \cup D^{\prime} \cup E$ is a sphere bounding a ball in $M_{1}$, so $D \cup E$ is isotopic to $F$, and replacing $D^{\prime}$ with $F$ results in an elementary boundarycompressing disk for $\widehat{S} \cap V$ with fewer intersections with $G$ than $D$. Thus we may assume that $D \cap G$ contains no $\widehat{S}$-arcs.

Now consider a subdisk $D^{\prime}$ of $D$ which is cut off by all the arcs of $D \cap G$ and whose boundary consists of no more than one vertical arc. Without loss of generality, assume $D^{\prime} \subseteq M_{1}$. Suppose $\partial D^{\prime}$ has $\widehat{B}$-arcs, $\beta_{1}, \beta_{2}, \ldots, \beta_{k}$. Then all the $\beta_{i}$ are disjoint arcs on $G$. If any of them are inessential in $G \cap \widehat{V}$ then they bound disks $B_{i} \subseteq G \cap V_{1}$. If any of the $\beta_{i}$ are essential in $G \cap \widehat{V}$, then they bound disks $B_{i} \subseteq V_{1}$ that are bridge disks for $n(\Gamma)$ in $V_{1}$. In either case, $D^{\prime} \cup\left(\bigcup_{i=1}^{k} B_{i}\right)$ results in a boundary-compressing disk for $S \cap \widehat{V}$ with fewer intersections with $G$ than $D$. This boundary-compressing disk is still elementary as the arc in $\widehat{S}$ remains unchanged. Thus, we may assume that $D \cap G$ consists solely of vertical arcs.

Let $\gamma$ be an arc of $D \cap G$ outermost in $D$, cutting off a subdisk $D_{1}$ from $D$. Without loss of generality, $D_{1} \subseteq M_{1}$. The boundary of $D_{1}$ consists of three arcs; $\gamma \subseteq G, \sigma_{1} \subseteq S_{1}$ and $\beta_{1} \subseteq B_{1}$. By symmetry, there exists disk $D_{2} \subseteq M_{2}$ in $M_{2}$, so that $D_{1} \cup D_{2}$ is a disk in $\widehat{V}$ with boundary consisting of $\operatorname{arcs} \sigma=\sigma_{1} \cup \sigma_{2} \subseteq \widehat{S}$ and $\beta=\beta_{1} \cup \beta_{2} \subseteq \widehat{B}$, intersecting $G$ in exactly one arc, $\gamma$. Finally, we must show that $\sigma$ is a "strongly essential" arc in $\widehat{S} \cap \widehat{V}$.

If $\sigma$ is not strongly essential then it is either the meridian of a boundary-parallel annulus of $\widehat{S} \cap \widehat{V}$, which is not possible since $\sigma_{1}$ was a subarc of the original elementary compression disk $D$, or $\sigma$ is inessential in $\widehat{S} \cap \widehat{V}$. If $\sigma$ is inessential then it would cobound a disk $E$ in $\widehat{S}$ together with an arc $\sigma^{\prime} \subseteq \widehat{S} \cap \widehat{B}$. This disk provides an isotopy in $\widehat{S}$ of $\sigma_{1}$ to $\sigma_{2}$.

If the disk $D^{\prime}=D \backslash D_{1}$ only intersects $D_{2}$ in $\gamma$ then $D^{\prime} \cup D_{2}$ is a compressing disk for $\widehat{S} \cap \widehat{V}$ with fewer arcs of intersection with $G$, as the disk can be isotoped away from $\gamma$. This disk is still an elementary compressing disk because $\sigma_{1}$ is isotopic to $\sigma_{2}$, and so contradicts our original choice of $D$.

Thus, $\sigma$ is strongly essential in $\widehat{S} \cap \widehat{V}$, and $D_{1} \cup D_{2}$ is a new compressing disk for $\widehat{S} \cap \widehat{V}$ that is symmetric across $G$.

We may, thus, proceed exactly as in Theorem 2.14. Each elementary boundary compression of $\widehat{S}$ towards either of $\widehat{V}$ or $\widehat{W}$ can be performed in a symmetric way, demonstrating a path from $\mathcal{D}_{\widehat{V}}$ to $\mathcal{D}_{\widehat{W}}$ in $\mathcal{C}(\widehat{S})$ of length no greater than twice the genus of $\widehat{S}$, which is $2(g(S)+|\partial S|-1)$.

Each time a boundary compression for $\widehat{S}$ corresponds to a pair of curves $\hat{c}_{i}$ and $\hat{c}_{i+1}$ in $S_{1}$ that contribute an edge in a path in $\mathcal{C}(\widehat{S})$ from $\mathcal{D}_{\widehat{V}}$ to $\mathcal{D}_{\widehat{W}}$, there is immediately a pair of curves $\hat{c}_{i+2}$ and $\hat{c}_{i+3}$ in $S_{2}$ also contributing an edge in a path from $\mathcal{D}_{V}$ to $\mathcal{D}_{W}$, and this pair of paths corresponds to a single pair of curves $c_{i}$ and $c_{i+1}$ in $S$ contributing a single edge in $\mathcal{A C}(S)$. Each time a boundary compression for $\widehat{S}$ corresponds to a pair of curves intersecting $G$ that contributes an edge in a path in $\mathcal{C}(\widehat{S})$ from $\mathcal{D}_{\widehat{V}}$ to $\mathcal{D}_{\widehat{W}}$, the restriction of these curves to $S_{1}$ is a pair of arcs contributing an edge in $\mathcal{A C}(S)$.

Further, since the boundary compressions (and elimination of boundary-parallel annuli) are all being performed symmetrically, the resulting disks $D_{\widehat{V}} \in \mathcal{D}_{\widehat{V}}$ from $\widehat{S} \cap \widehat{V}$ and $D_{\widehat{W}} \in \mathcal{D}_{\widehat{W}}$ from $\widehat{S} \cap \widehat{W}$ are symmetric. That is, either $D_{\widehat{V}}$ (resp., $D_{\widehat{W}}$ ) is disjoint from $G$, so that we may assume that it sits in $V_{1}$ (resp., $W_{1}$ ), or it is symmetric across $G$ so that $D_{\widehat{V}} \cap M_{1}$ (resp., $D_{\widehat{W}} \cap M_{1}$ ) is a graph bridge disk for $\Gamma$ in $M$. In either case, this demonstrates a path in $\mathcal{A C}(S)$ from $\mathcal{D} \mathcal{G}_{V}$ to $\mathcal{D} \mathcal{G}_{W}$ of length no greater than $2(g(S)+|\partial S|-1)$.

## 3. Theorem 1.1

Bachman [2010] defined the topological index of a surface. In contrast to the distances between subcomplexes each corresponding to some disks discussed in Section 2, he exploits the homotopy type of the complex of all disks.
Definition 3.1. The surface $B$ is said to be topologically minimal if either $\mathcal{D}_{B}$ is empty, or if there exists an $n \in \mathbb{N}$ so that $\pi_{n}\left(\mathcal{D}_{B}\right) \neq 0$. If a surface $B$ is topologically minimal, then the topological index is defined to be the smallest $n \in \mathbb{N}$ so that $\pi_{n-1}\left(\mathcal{D}_{B}\right) \neq 0$, or 0 if $\mathcal{D}_{B}$ is empty.

Bachman and Johnson [2010] showed that surfaces of arbitrarily high index exist, but their manifolds all contain essential tori. We prove an analogue of this.
Theorem 1.1. There is a closed 3-manifold $M^{1}$, with an index 1 Heegaard surface $S$, such that for each $n$, the lift of $S$ to some $n$-fold cover $M^{n}$ of $M^{1}$ has topological index $n$. Moreover, $M^{n}$ is hyperbolic for all $n$.

3A. The construction. Let $n$ be a positive integer. We will construct a hyperbolic manifold containing a Heegaard surface of topological index $n$.

Using the machinery in Theorem 2.6 , let $\mathcal{L}$ be a link in $S^{3}$ with two components, $L$ and $K$, that are each 2-bridge with respect to a bridge sphere $B$ of distance at least $24 n+7$. Let $V$ and $W$ be the two 3-balls bounded by $B$. Since $\mathcal{L}$ is in bridge position, there exist disks $D_{V}$ and $D_{W}$ properly embedded in $V$ and $W$, respectively, with $(\mathcal{L} \cap V) \subset D_{V}$, and $(\mathcal{L} \cap W) \subset D_{W}$. By modifying $D_{V}$ if necessary, we can find two $\operatorname{arcs} \tau_{L}$ and $\tau_{K}$ in the interior of $V$ such that
(1) $\tau_{L} \cup \tau_{K} \subset D_{V}$,
(2) $\tau_{L} \cap \tau_{K}=\varnothing$,
(3) $\tau_{L} \cap \mathcal{L}=\partial \tau_{L} \subset L$ and $\tau_{K} \cap \mathcal{L}=\partial \tau_{K} \subset K$,
(4) the endpoints of $\tau_{K}$ are on different components of $K \cap V$, and the endpoints of $\tau_{L}$ are on different components of $L \cap V$.
Let $L^{\prime}=L \cup \tau_{L}$, let $G_{L}=\partial n\left(L^{\prime}\right)$, let $K^{\prime}=K \cup \tau_{K}$, let $G_{K}=\partial n\left(K^{\prime}\right)$, and let $\Gamma=$ $\mathcal{L} \cup \tau_{L} \cup \tau_{K}=L^{\prime} \cup K^{\prime}$. Observe that $\Gamma$ is a graph in bridge position with respect to $B$. Let $M^{\prime}=\overline{S^{3} \backslash n(\Gamma)}$, let $V^{\prime}=\overline{V \backslash n(\Gamma)}$, and let $W^{\prime}=\overline{W \backslash n(\Gamma)}=\overline{W \backslash n(\mathcal{L})}$, and $B^{\prime}=B \backslash n(\Gamma)=B \backslash n(\mathcal{L})$.

For each $i=1,2, \ldots, n$, let $M_{i}^{\prime}$ be homeomorphic to $M^{\prime}$, along with homeomorphic copies $\mathcal{L}_{i}$ of $\mathcal{L},\left(G_{L}\right)_{i}$ of $G_{L},\left(G_{K}\right)_{i}$ of $G_{K}$, and $B_{i}^{\prime}$ of $B^{\prime}$.

Then, for each $i=1,2, \ldots,(n-1)$, identify $\left(G_{K}\right)_{i}$ with $\left(G_{L}\right)_{i+1}$ and identify $\left(G_{K}\right)_{n}$ with $\left(G_{L}\right)_{1}$, all via the same homeomorphism. Call the resulting closed 3-manifold $M^{n}$. Observe that the union of the $B_{i}^{\prime}$ is a closed surface that we will call $B^{n}$. We will show that $B^{n}$ is a Heegaard surface for $M^{n}$, that $B^{n}$ has high topological index, and that $M^{n}$ is hyperbolic.
Proposition 3.2. For each $n, B^{n} \subset M^{n}$ is a genus $3 n+1$ Heegaard surface.
Proof. That the genus of $B^{n}$ is $3 n+1$ can be verified by an Euler characteristic count. It suffices, then, to verify that the complement of $B^{n}$ is two handlebodies, $V^{n}$ and $W^{n}$.

Since $\Gamma$ was in bridge position with respect to $B$, there are disks $D_{V}$ and $D_{W}$ properly embedded in $V$ and $W$, respectively, so that $\Gamma \cap V \subset D_{V}$ and $\Gamma \cap W \subset D_{W}$. Then $D_{V}$ and $D_{W}$ cut along $\Gamma$ is a collection of subdisks.

The result of cutting $V \backslash n(\Gamma)$ along all these subdisks of $D_{V}$ is a pair of 3-balls, each with two subdisks, $D_{1}^{+}$and $D_{2}^{+}$, of $n(\Gamma)$ contained in the boundary. Each identification of $\left(G_{K}\right)_{i}$ with $\left(G_{L}\right)_{i+1}($ indices $\bmod n)$ glues pairs of these subdisks along arcs, resulting in disks in $V^{n}$, and further cutting along $(n-1)$ copies of each of $D_{1}^{+}$and $D_{2}^{+}$results in a collection of 3-balls, showing that $V^{n}$ is a handlebody.

Similarly, the result of cutting $W \backslash n(\Gamma)$ along all of the subdisks of $D_{W}$ is a pair of 3-balls, each with four subdisks of $n(\Gamma)$ contained in the boundary, $D_{1}^{-}, D_{2}^{-}, D_{3}^{-}$,
and $D_{4}^{-}$. Each identification of $\left(G_{K}\right)_{i}$ with $\left(G_{L}\right)_{i+1}($ indices $\bmod n)$ glues pairs of these subdisks along arcs, resulting in disks in $W^{n}$, and further cutting along $(n-1)$ copies of each of $D_{1}^{-}, D_{2}^{-}, D_{3}^{-}$, and $D_{4}^{-}$results in a collection of 3-balls, showing that $W^{n}$ is a handlebody.

## 3B. Bounding from above.

Proposition 3.3. The surface $B^{n}$ has topological index at most $n$.
Proof. Our proof will follow almost exactly the proof of Proposition 5 from [Bachman and Johnson 2010]. In each copy $M_{i}^{\prime}$ of the manifold $M^{\prime}$, we have the surface $B_{i}^{\prime}$, a copy of $B^{\prime}$, dividing the manifold into $V_{i}^{\prime}$ and $W_{i}^{\prime}$, copies of $V^{\prime}$ and $W^{\prime}$. Observe that in each $V_{i}^{\prime}$, there is exactly one essential disk, $D_{i}^{+}$with boundary contained in $B_{i}^{\prime}$, just as in [Bachman and Johnson 2010]. However, in each $W_{i}^{\prime}$, there are several essential disks with boundary contained in $B_{i}^{\prime}$. We will call this collection of disks $\mathscr{D}_{i}^{-}$. From each $\mathscr{D}_{i}^{-}$, choose a single representative $D_{i}^{-}$.

Define the subcomplex, $P$, of $\mathcal{D}_{M}$ spanned by the vertices corresponding to $\bigcup_{i}\left\{D_{i}^{+}, D_{i}^{-}\right\}$, which is homeomorphic to an $(n-1)$-sphere. Then, define a map $F: \mathcal{D}_{M} \rightarrow P$ by the identity on $P$, and by sending a vertex corresponding to a disk $D \notin \bigcup_{i}\left\{D_{i}^{+}, D_{i}^{-}\right\}$to the vertex corresponding to $D_{j}^{+}$or $D_{j}^{-}$, where either $D \in \mathscr{D}_{j}^{-}$, or $j$ is the smallest index for which an essential outermost subdisk of $D \backslash\left(\bigcup_{i} G_{i}\right)$ is contained in $V_{j}^{\prime}$ or $W_{j}^{\prime}$, respectively.

Just as in [Bachman and Johnson 2010], we claim that this map $F$ is a simplicial map that fixes each vertex of $P$. To see this, consider any two disks $D_{1}$ and $D_{2}$ connected by an edge in $\mathcal{D}_{M}$ (so that the disks are realized disjointly in $M$ ). Observe that by our construction of $M^{\prime}$ and Corollary 2.13, any disk contained in $V_{j}^{\prime}$ must intersect any disk contained in $W_{j}^{\prime}$ (whether either disk is a bridge disk, a graphbridge disk, or the boundary is contained in $\left.B_{j}^{\prime}\right)$. So, if $D_{i}^{ \pm}=F\left(D_{1}\right) \neq F\left(D_{2}\right)=D_{j}^{ \pm}$, then $i \neq j$, and $F\left(D_{1}\right)$ is joined to $F\left(D_{2}\right)$ in $P$. Thus, $F$ is a retraction onto the $(n-1)$-sphere, $P$, showing that $\pi_{n-1}\left(\mathcal{D}_{M}\right)$ is nontrivial, so the topological index of $B^{n}$ is at most $n$.
Corollary 3.4. The topological index of $B^{n}$ is well defined, and $B^{n}$ is topologically minimal.

3C. Bounding from below. We make use of an important theorem in the development of the topological index by Bachman:
Theorem 3.5 [Bachman 2010, Theorem 3.7]. Let $G$ be a properly embedded, incompressible surface in an irreducible 3-manifold M. Let B be a properly embedded surface in $M$ with topological index $n$. Then $B$ may be isotoped so that
(1) $B$ meets $G$ in $p$ saddles, for some $p \leq n$, and
(2) the sum of the topological indices of the components of $B \backslash n(G)$, plus $p$, is at most $n$.

Proposition 3.6. The surface $B^{n}$ has topological index no smaller than $n$.
Proof. Suppose $B^{n}$ had topological index $\iota<n$. Let $G$ be the union of all the genus two surfaces $G_{i}^{n}:=\left(G_{K}\right)_{i}=\left(G_{L}\right)_{i+1}($ indices $\bmod n)$ in the manifold $M^{n}$. By Theorem 3.5, $B^{n}$ can be isotoped to a surface, $B_{+}^{n}$, so that $B_{+}^{n}$ meets $G$ in $\sigma$ saddles, the sum of the topological indices of the components of $B_{+}^{n} \backslash n(G)$ is $k$, and $k+\sigma \leq \iota$. Observe that $\chi\left(B_{+}^{n} \backslash n(G)\right)=-6 n+\sigma$. We may isotope any annular components of $B_{+}^{n} \backslash n(G)$ that are boundary-parallel into $\partial n(G)$ completely into $n(G)$. Note that this will have no effect on the Euler characteristic of $B_{+}^{n} \backslash n(G)$, nor any effect on the topological index, since such a component will have topological index 0 .

Any component, $Q$, of $B_{+}^{n} \cap n(G)$ is contained in $n\left(G_{i}^{n}\right)$ for some $i$. Any such $Q$ is a punctured sphere with, say, $d$ boundary components, has $d-2$ saddles, and we will show that at most $d-2$ of its boundary components can bound disks of $B_{+}^{n} \backslash n(G)$ that are boundary-parallel into $\partial n(G)$ in $M_{i} \backslash n(G)$ or $M_{i+1} \backslash n(G)$.

As $B_{+}^{n}$ is connected and not a sphere, all the boundary curves of $Q$ cannot bound disks. Suppose, then, that $d-1$ of the curves bound disks that are boundary-parallel into $\partial n(G)$ in $M_{i} \backslash n(G)$ or $M_{i+1} \backslash n(G)$, and let $c$ be the remaining boundary component of $Q$. As the other curves all bound disks that can be isotoped into $n\left(G_{i}^{n}\right)$, and $G_{i}^{n}$ is incompressible in $M^{n}, c$ must bound a disk in $\partial n\left(G_{i}^{n}\right)$. By pushing this disk slightly into $M_{i}$ or $M_{i+1}$, we have a compressing disk for a component of $B_{+}^{n} \backslash n(G)$ that is disjoint from all other compressing disks for that component. Thus, the disk complex for that component is contractible, contrary to the fact that it is topologically minimal. Thus, at most $d-2$ of the boundary components of $Q$ can bound disks that are boundary-parallel into $\partial n(G)$ in $M_{i} \backslash n(G)$ or $M_{i+1} \backslash n(G)$.

Therefore, the total number of disk components of $B_{+}^{n} \backslash n(G)$ that are boundaryparallel in $M^{n} \backslash n(G)$ is $\beta \leq \sigma$. So we may further isotope all $\beta$ such boundaryparallel disks into $n(G)$, and call the resulting surface $B_{0}^{n}$. Still, then, each component of $B_{0}^{n} \backslash n(G)$ is topologically minimal, the topological index will be unchanged as each boundary-parallel disk has topological index $0, B_{0}^{n} \backslash n(G)$ has no boundaryparallel disks or annuli, and

$$
\chi\left(B_{0}^{n} \backslash n(G)\right)=\chi\left(B_{+}^{n} \backslash n(G)\right)-\beta \geq \chi\left(B_{+}^{n} \backslash n(G)\right)-\sigma=-6 n
$$

First, suppose that there is some component of $B_{0}^{n} \backslash n(G)$ with Euler characteristic less than $-6 n$. In this case, because the Euler characteristic of $B_{0}^{n} \backslash n(G)$ is greater than or equal to $-6 n$, there must be a component of $B_{0}^{n} \backslash n(G)$ with positive Euler characteristic. But there are no disks, as we have eliminated boundary-parallel disks and an essential disk would be a compression of $G$ in $M^{n}$, and it cannot be a sphere, so this is impossible.

Thus, we may suppose that the Euler characteristic of each component of $B_{0}^{n} \backslash n(G)$ is bounded below by $-6 n$. Observe that each component of $G$ is an incompressible surface, so $B^{n}$ cannot be made disjoint from any component of $G$,
and so $\left(B_{0}^{n} \backslash n(G)\right) \cap M_{i}$ is nonempty for all $i$. As the sum of the topological indices of the components of $B_{0}^{n} \backslash n(G)$ is $k<n$, there must be at least one index $j$ so that every component of $\left(B_{0}^{n} \backslash n(G)\right) \cap M_{j}$ has topological index 0 . Thus, there is some component of $\left(B_{0}^{n} \backslash n(G)\right) \cap M_{j}$, and all such components are incompressible and have Euler characteristic bounded below by $-6 n$. If necessary, maximally boundary compress ( $\left.B_{0}^{n} \backslash n(G)\right) \cap M_{j}$, and isotope any resulting boundary-parallel components into $n(G)$. As $B_{0}^{n}$ cannot be isotoped away from any copy of $G_{i}^{n}$, there must be some component remaining that is incompressible, boundary-incompressible, and not boundary-parallel. Since boundary compressions only increase Euler characteristic, the resulting component has Euler characteristic bounded below by $-6 n$. Call this component $B^{\prime \prime}$.

By Lemma 2.9 and Corollary 2.13 , in $M_{j}$ with $B_{j}$ a copy of $B^{\prime}$, we have

$$
d_{\mathcal{C}}\left(B_{j}, \mathcal{L}\right) \leq 2 d_{\mathcal{B D}}\left(B_{j}, \mathcal{L}\right) \leq 2\left(1+d_{\mathcal{G}}\left(B_{j}, \Gamma\right)\right)
$$

By Theorem 1.2, $d_{\mathcal{G}}\left(B_{j}, \Gamma\right) \leq 2\left(2 g\left(B^{\prime \prime}\right)+\left|\partial B^{\prime \prime}\right|-1\right)$. By our choice of $\mathcal{L}$ and the fact that $\chi(S)=2-2 g(S)-|\partial S|$, we have

$$
24 n+7 \leq d_{\mathcal{C}}\left(B_{j}, \mathcal{L}\right) \leq 2+2 d_{\mathcal{G}}\left(B_{j}, \Gamma\right) \leq 8 g\left(B^{\prime \prime}\right)+4\left|\partial B^{\prime \prime}\right|-2=-4 \chi\left(B^{\prime \prime}\right)+6
$$

On the other hand we have just shown that $-6 n \leq \chi\left(B^{\prime \prime}\right)$, a contradiction. Thus, the topological index of $B^{n}$ cannot be less than $n$.

3D. Hyperbolicity. We have now shown that $M^{n}$ contains a surface of topological index $n$. To prove Theorem 1.1 it remains to show that $M^{n}$ is hyperbolic.

Proposition 3.7. For all $n, M^{n}$ is hyperbolic.
Proof. Consider an essential surface $S$ in $M^{n}$ with Euler characteristic bounded below by 0 , chosen to intersect $G$ minimally. If $S \cap G=\varnothing$, we arrive at a contradiction to Theorem 1.2 as $S$ would lie in one of the copies of $M^{\prime}$. If $S \cap G \neq \varnothing$, the incompressibility and boundary-incompressibility of $G$ guarantees that the curves of $S \cap G$ are essential in $S$. Thus $S \cap M_{i}^{\prime}$ is a collection of one or more planar surfaces for some $i$. This again contradicts Theorem 1.2. Thus, in particular, $M^{n}$ is prime and atoroidal for all $n$. Then, as $G$ is an incompressible surface in $M^{n}$, we conclude that $M^{n}$ is hyperbolic.

Now the proof of Theorem 1.1 follows.
Proof of Theorem 1.1. Let $M^{n}$ and $B^{n}$ be as in Section 3A. We note that $M^{n}$ is an $n$-fold cover of $M^{1}$. By Proposition 3.2, $B^{n}$ is a genus $3 n+1$ Heegaard surface. By Propositions 3.3 and $3.6, B^{n}$ has topological index $n$, and by Proposition 3.7, $M^{n}$ is hyperbolic.

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Volume 296 No. 2 October 2018
Congruence subgroups and super-modular categories ..... 257
Parsa Bonderson, Eric C. Rowell, Zhenghan Wang and Qing ZHANG
On the Chow ring of the stack of truncated Barsotti-Tate Groups ..... 271
Dennis Brokemper
Hyperbolic manifolds containing high topological index surfaces ..... 305
Marion Campisi and Matt Rathbun
Length spectra of sub-Riemannian metrics on compact Lie groups ..... 321
András Domokos, Matthew Krauel, Vincent Pigno, Corey Shanbrom and Michael VanValkenburgh
The action of the Hecke operators on the component groups of modular ..... 341 Jacobian varietiesTaekyung Kim and Hwajong Yoo
Liouville theorems, volume growth, and volume comparison for Ricci ..... 357 shrinkers
Li MA
Presentations of generalisations of Thompson's group V ..... 371
Conchita Martínez-PÉrez, Francesco Matucci and Brita Nucinkis
Localization functors and cosupport in derived categories of commutative ..... 405
Noetherian rings
Tsutomu Nakamura and Yuji Yoshino
Zeta integrals for $\mathrm{GSp}(4)$ via Bessel models ..... 437
Ralf Schmidt and Long Tran
Toric surfaces over an arbitrary field ..... 481
Fei Xie
Erratum for the article The Johnson-Morita theory for the rings of Fricke ..... 509
characters of free groups
TaKao Satoh


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