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Let $X$ be a finite-dimensional Banach space. We prove that if $K$ and $S$ are locally compact Hausdorff spaces and there exists a bijective map $T: C_{0}(K, X) \rightarrow C_{0}(S, X)$ such that

$$
\frac{1}{M}\|f-g\|-L \leq\|T(f)-T(g)\| \leq M\|f-g\|+L
$$

for every $f, g \in C_{0}(K, X)$ then $K$ and $S$ are homeomorphic, whenever $L \geq 0$ and $1 \leq M^{2}<S(X)$, where $S(X)$ denotes the Schäffer constant of $X$.

This nonlinear vector-valued extension of the Amir-Cambern theorem via quasi-isometries $T$ with large $M$ was previously unknown even for the classical $\ell_{p}^{n}$ spaces, $1<p<\infty, p \neq 2$ and $n \geq 2$.

## 1. Introduction

If $K$ is a locally compact Hausdorff space and $X$ is a Banach space, we denote by $C_{0}(K, X)$ the Banach space of continuous functions vanishing at infinity on $K$, taking values in $X$, and provided with the usual supremum norm. If $X$ is the scalar field ( $\mathbb{R}$ or $\mathbb{C}$ ) we will denote this space by $C_{0}(K)$. In the case where $K$ is a compact Hausdorff space we write $C(K, X)$ instead of $C_{0}(K, X)$.

The well-known Banach-Stone theorem states that if $K$ and $S$ are locally compact Hausdorff spaces, then the existence of a linear isometry $T$ from $C_{0}(K)$ onto $C_{0}(S)$ implies that $K$ and $S$ are homeomorphic [Banach 1932; Behrends 1979; Stone 1937]. Amir [1965] and Cambern [1967] independently generalized this theorem by proving that if $C_{0}(K)$ and $C_{0}(S)$ are isomorphic under a linear isomorphism $T$ satisfying $\|T\|\left\|T^{-1}\right\|<2$, then $K$ and $S$ must also be homeomorphic. The constant 2 is the best possible for the formulation of this result [Cambern 1970; Cohen 1975].

[^0]Various authors, beginning with Jerison [1950], have considered the problem of determining geometric properties of $X$ which allow generalizations of these theorems to the $C_{0}(K, X)$ spaces; see for instance [Cidral et al. 2015].

In the present paper we strengthen the Amir-Cambern theorem by showing that the conclusion holds if the requirement that $T$ be a linear isomorphism with $\|T\|\left\|T^{-1}\right\|<2$ is replaced by the requirement that $T$ be a bijective coarse $(M, L)$ -quasi-isometry on $C_{0}(K, X)$ spaces for finite-dimensional spaces $X$ with $L \geq 0$ and $M$ satisfying $1 \leq M^{2}<S(X)$, where $S(X)$ is the following parameter introduced by Schäffer [Gao and Lau 1990; Schäffer 1976] for Banach spaces $X$ :

$$
S(X)=\inf \{\max \{\|x+y\|,\|x-y\|\}:\|x\|=1 \text { and }\|y\|=1\}
$$

Recall that a Banach space $X$ is called uniformly nonsquare [James 1964, Definition 1.1] if there exists $0<\delta<1$ such that for any $x, y \in X$, with $\|x\|=1$ and $\|y\|=1$, we have

$$
\min \{\|x+y\|,\|x-y\|\} \leq 2(1-\delta) .
$$

Then, $X$ is uniformly nonsquare if and only if $S(X)>1$ [Kato et al. 2001, Proposition 1]. Moreover, $S(\mathbb{R})=2, S(\mathbb{C})=\sqrt{2}$, and $1 \leq S(X) \leq \sqrt{2}$ for every Banach space with dimension greater than or equal to 2 [Gao and Lau 1990, Theorem 2.5]. If $X$ is a Hilbert space with dimension at least 2 then $S(X)=\sqrt{2}$, but this equality does not characterize the Hilbert spaces $X$; see for instance [Komuro et al. 2016, p.1].

A bijective map $T: C_{0}(K, X) \rightarrow C_{0}(S, X)$ is said to be a coarse $(M, L)$-quasiisometry or simply an ( $M, L$ )-quasi-isometry if for some constants $M \geq 1$ and $L \geq 0$ the inequalities

$$
\frac{1}{M}\|f-g\|-L \leq\|T(f)-T(g)\| \leq M\|f-g\|+L
$$

are satisfied for all $f, g \in C_{0}(K, X)$. This notion includes some important concepts used in the nonlinear classification of Banach spaces [Benyamini and Lindenstrauss 2000; Godefroy et al. 2014; Górak 2011; Kalton 2008].

Thus, the main aim of this work is to prove the following nonlinear vector-valued extension of the Amir-Cambern theorem via quasi-isometries.
Theorem 1.1. Let $X$ be a finite-dimensional Banach space with $S(X)>1$. Suppose that $K$ and $S$ are locally compact Hausdorff spaces and there exists a bijective ( $M, L$ )-quasi-isometry $T$ from functions $C_{0}(K, X)$ onto $C_{0}(S, X)$ satisfying

$$
M^{2}<S(X)
$$

then $K$ and $S$ are homeomorphic.
The starting point of our research toward proving Theorem 1.1 was the fact that, for the particular case where $X$ is a finite-dimensional strictly convex space [Clarkson 1936] and $M<1+\epsilon_{0}$ for some $\epsilon_{0}>0$, the theorem was proved by Jarosz [1989, Theorem 4]. However, even in the case where $X=\mathbb{R}$, the arguments presented in the
proof of [Jarosz 1989, Theorem 1] require $\epsilon_{0}$ to be very small, namely $\epsilon_{0}<10^{-30}$. In addition, if $X$ has dimension at least $2, \epsilon_{0}$ depends on the modulus of convexity of $X$ and nothing is established about it beyond its existence.

This result of Jarosz naturally leads us to the following problem.
Problem 1.2. When can the Amir-Cambern theorem be extended for $C_{0}(K, X)$ spaces to $(M, L)$-quasi-isometries with $M>1$ ?

Theorem 1.1 states that every finite-dimensional uniformly nonsquare space and, in particular, every finite-dimensional strictly convex space provides a positive solution to the above problem for a range $M$ depending on a geometrical property of $X$. Notice also that in the special case where $X=\ell_{p}^{n}$ (the real $n$-dimensional $l_{p}$ space, $1<p<\infty$ and $n \geq 2$ ), the following immediate corollary of Theorem 1.1 was only known when $p=2$ [Galego and Da Silva 2018, Main Theorem].
Corollary 1.3. Let $1<p<\infty$ and $n \geq 2$. Suppose that $K$ and $S$ are locally compact Hausdorff spaces and $T$ is a bijective $(M, L)$-quasi-isometry from $C_{0}\left(K, \ell_{p}^{n}\right)$ onto $C_{0}\left(S, \ell_{p}^{n}\right)$ satisfying

$$
M^{2}<\min \left\{2^{1 / p}, 2^{1-1 / p}\right\}
$$

then $K$ and $S$ are homeomorphic.
Proof. It suffices to recall that by [Gao and Lau 1990, Theorem 3.1], for every $1<p<\infty$ and $n \geq 2$, we know that

$$
S\left(\ell_{p}^{n}\right)=\min \left\{2^{1 / p}, 2^{1-1 / p}\right\}
$$

The case $X=\mathbb{R}$ of Theorem 1.1 was proved in [Galego and Porto da Silva 2016, Main Theorem]. On the other hand, Theorem 1.1 does not apply to $X=\ell_{\infty}^{n}, n \geq 2$, the real $n$-dimensional $l_{\infty}$ space, because in this case $S(X)=1$ and moreover by a well-known result of Sundaresan [1973, p.22] there are nonhomeomorphic compact Hausdorff spaces $K$ and $S$ such that $C(K, X)$ is isometric with $C(S, X)$.

Notice that, in view of Problem 1.2 and in connection with Theorem 1.1, the following question arises naturally.
Problem 1.4. Suppose that $X$ is a Banach space such that there exists $c>1$ satisfying the following property: for any locally compact Hausdorff spaces $K$ and $S$ and bijective ( $M, L$ )-quasi-isometry $T$ from $C_{0}(K, X)$ onto $C_{0}(S, X)$ with

$$
M^{2}<c
$$

it follows that $K$ and $S$ are homeomorphic.
Then:
(1) Is it true that $S(X)>1$ ?
(2) Is $c \leq S(X)$ ?
(3) Does it follow that $X$ is a finite-dimensional space?

## 2. An inequality involving the Schäffer constant

We begin the proof of Theorem 1.1 by establishing an inequality related to the Schäffer constant that will be very useful later. The constant

$$
\begin{equation*}
J(X)=\sup \{\min \{\|x+y\|,\|x-y\|\}:\|x\|=1 \text { and }\|y\|=1\} \tag{2-1}
\end{equation*}
$$

is called the nonsquare or James constant of $X$.
If $X$ is a real Banach space of finite dimension at least 2 , then according to [Casini 1986, Proposition 2.1] or [Gao and Lau 1990, Theorem 2.5]

$$
\begin{equation*}
J(X) S(X)=2 \tag{2-2}
\end{equation*}
$$

This fact also holds if $X$ is a complex Banach space, for if $X_{\mathbb{R}}$ is its natural real Banach space structure, we have that $J(X)=J\left(X_{\mathbb{R}}\right)$ and $S(X)=S\left(X_{\mathbb{R}}\right)$. So, from now on, we shall not distinguish the scalar field of $X$.

Lemma 2.1. Let $X$ be a Banach space and $x, y \in X$. Then

$$
\min \{\|x+y\|,\|x-y\|\} \leq \frac{2}{S(X)} \max \{\|x\|,\|y\|\}
$$

Proof. First assume that $X=\mathbb{R}$. Then $S(X)=2$ and for each pair $x, y \in \mathbb{R}$,

$$
\min \{|x+y|,|x-y|\}=||x|-|y|| \leq \max \{|x|,|y|\}
$$

so we are done.
Suppose now that the dimension of $X$ is at least 2 and fix $x, y \in X$. Since $S(X) \leq 2$, the lemma follows trivially in the case that $x=0$ or $y=0$. Thus, we assume that $x, y \neq 0$ and put $\hat{x}=x /\|x\|, \hat{y}=y /\|y\|$. We may also assume that

$$
\begin{equation*}
\|x\|=\max \{\|x\|,\|y\|\} \quad \text { and } \quad\|\hat{x}+\hat{y}\|=\min \{\|\hat{x}+\hat{y}\|,\|\hat{x}-\hat{y}\|\} . \tag{2-3}
\end{equation*}
$$

Next, by (2-1) and (2-2) we infer that

$$
\frac{2}{S(X)}=J(X)=\sup \{\min \{\|u+v\|,\|u-v\|\}:\|u\|=1 \text { and }\|v\|=1\}
$$

Then, by (2-3) it follows that

$$
\|\hat{x}+\hat{y}\| \leq \frac{2}{S(X)}
$$

and putting $\alpha=\|y\| /\|x\| \in(0,1]$, we note that

$$
\frac{\|x+y\|}{\|x\|}=\|\hat{x}+\alpha \hat{y}\| \leq(1-\alpha)\|\hat{x}\|+\alpha\|\hat{x}+\hat{y}\| \leq \frac{2}{S(X)},
$$

and we are also done.

## 3. Special sets associated to ( $M, L$ )-quasi-isometries

In a recent study of ( $M, L$ )-quasi-isometries between the spaces $C_{0}(K)$ and $C_{0}(S)$ [Galego and Porto da Silva 2016], subsets $\Gamma_{\mathrm{w}}(k, \mathrm{v})$ and $\Gamma_{\mathrm{v}}(s, \mathrm{w})$ of $S$ and $K$, respectively, where $k \in K, s \in S$ and v and w are suitable elements of $\mathbb{R}$, were introduced. In this section, we introduce the definitions and a property (Proposition 3.1) of an analogous class of these sets for $\mathrm{v}, \mathrm{w} \in X$ instead of $\mathbb{R}$.

From now on, as in the hypotheses of Theorem 1.1, we fix a finite-dimensional Banach space $X$ with $S(X)>1$ and a bijective coarse ( $M, L$ )-quasi-isometry

$$
T: C_{0}(K, X) \rightarrow C_{0}(S, X)
$$

satisfying $M^{2}<S(X)$ and $L \geq 0$. One can easily see that for any $\alpha>0$, the map $f \mapsto \alpha T(f / \alpha)$ is a bijective coarse $(M, \alpha L)$-quasi-isometry, so it is possible to change the value of $L$ as we wish. Then, we may suppose that $L=1$. Moreover, notice that the map $f \mapsto T(f)-T(0)$ is a bijective coarse quasi-isometry with the same constants $(M, L)$ of $T$, with the additional property that it maps 0 to 0 . For that reason we may suppose that $T(0)=0$. Finally, notice that the map $T^{-1}$ does not necessarily have the same constants $(M, L)$ of $T$; in fact we can only guarantee that it is a bijective coarse $(M, M L)$-quasi-isometry. Thus, we may actually suppose that $L=1 / M$, and this will ensure that both the maps $T$ and $T^{-1}$ are bijective coarse ( $M, 1$ )-quasi-isometries.

Let $H$ be a locally compact Hausdorff space, $k \in H, f \in C_{0}(H, X)$ and $\mathrm{v} \in X$. Following [Galego and Porto da Silva 2016, Definition 2.2] we set

$$
\omega(k, f, \mathrm{v})=\max \{\|f\|,\|f(k)-\mathrm{v}\|\} .
$$

Let $\mathrm{v}, \mathrm{w} \in X$ satisfy $\|\mathrm{v}\| \geq M$ and $\|\mathrm{w}\|=\|\mathrm{v}\| / M-1$. Following [Galego and Porto da Silva 2016, Definition 3.1], we set

$$
\Gamma_{\mathrm{w}}(k, \mathrm{v})=\left\{s \in S:\|T f(s)-\mathrm{w}\| \leq M \omega(k, f, \mathrm{v})+1, \text { for all } f \in C_{0}(K, X)\right\} .
$$

Similarly, for $s \in S, \mathrm{w}, \mathrm{z} \in X$ with $\|\mathrm{w}\| \geq M$ and $\|\mathrm{z}\|=\|\mathrm{w}\| / M-1$, we also set $\Lambda_{\mathrm{z}}(s, \mathrm{w})=\left\{k \in K:\left\|T^{-1} g(k)-\mathrm{z}\right\| \leq M \omega(s, g, \mathrm{w})+1\right.$, for all $\left.g \in C_{0}(S, X)\right\}$.

Since it is required in the definition of the sets $\Gamma_{\mathrm{w}}(k, \mathrm{v})$ and $\Lambda_{\mathrm{z}}(s, \mathrm{w})$ that $\|\mathrm{v}\| \geq M$ and $\|\mathrm{w}\|=\|\mathrm{v}\| / M-1$ and, respectively, $\|\mathrm{w}\| \geq M$ and $\|\mathrm{z}\|=\|\mathrm{w}\| / M-1$, these restrictions on the norms of the parameters will be implicit in every usage of these sets.

It is important to have in mind that, since both $T$ and $T^{-1}$ are bijective coarse ( $M, 1$ )-quasi-isometries, for any result involving the sets $\Gamma_{\mathrm{w}}(k, \mathrm{v})$, a similar result holds for the sets $\Lambda_{\mathrm{z}}(s, \mathrm{w})$. We will use the same result label to refer to either case.

The proof of the following proposition is essentially the same as the proof of [Galego and Porto da Silva 2016, Proposition 3.2].

Proposition 3.1. There exists $r_{0}>0$, depending only on $M$, such that, for all $k \in K$ and $\mathrm{v} \in X$ with $\|\mathrm{v}\| \geq r_{0}$, there exists $\mathrm{w} \in X$ such that $\Gamma_{\mathrm{w}}(k, \mathrm{v}) \neq \varnothing$.

Proof. Let $\mathcal{V}_{k}$ denote the set of open neighborhoods of $k$. For each $U \in \mathcal{V}_{k}$ we fix $f_{U} \in C_{0}(K)$ such that the image of $f_{U}$ is contained in $[0,1], f_{U}(k)=1$ and $\left.f_{U}\right|_{K \backslash U} \equiv 0$. We consider the net $\left(\mathrm{v} \cdot f_{U}\right)_{U \in \mathcal{V}_{k}}$.

Claim.

$$
\lim \sup \left\|f-\mathrm{v} \cdot f_{U}\right\| \leq \omega(k, f, \mathrm{v}), \quad \text { for all } f \in C_{0}(K, X)
$$

Given $\varepsilon>0$, fix $U_{\varepsilon} \in \mathcal{V}_{k}$ such that

$$
\|f(u)-f(k)\|<\varepsilon, \quad \text { for all } u \in U_{\varepsilon} .
$$

Pick $U \in \mathcal{V}_{k}$ such that $U \subset U_{\varepsilon}$, and we shall evaluate $\left\|f-\mathrm{v} \cdot f_{U}\right\|$. If $u \in U$, then

$$
\left\|f(u)-\mathrm{v} \cdot f_{U}(u)\right\| \leq\left\|f(k)-\mathrm{v} \cdot f_{U}(u)\right\|+\varepsilon
$$

Notice that $\mathrm{v} \cdot f_{U}$ has its image contained in the segment $\{\alpha \mathrm{v}: \alpha \in[0,1]\}$, and then

$$
\left\|f(k)-\mathrm{v} \cdot f_{U}(u)\right\| \leq \max \{\|f(k)\|,\|f(k)-\mathrm{v}\|\}
$$

Therefore,

$$
\left\|f(u)-\mathrm{v} \cdot f_{U}(u)\right\| \leq \max \{\|f(k)\|,\|f(k)-\mathrm{v}\|\}+\varepsilon, \quad \text { for all } u \in U
$$

On the other hand, if $u \in K \backslash U$, then $f_{U}(u)=0$, and consequently,

$$
\begin{equation*}
\left\|f(u)-\mathrm{v} \cdot f_{U}(u)\right\|=\|f(u)\| \leq\|f\|, \quad \text { for all } u \in K \backslash U \tag{3-2}
\end{equation*}
$$

By (3-1) and (3-2), we conclude that

$$
\left\|f-\mathrm{v} \cdot f_{U}\right\| \leq \max \{\|f\|,\|f(k)-\mathrm{v}\|\}+\varepsilon
$$

and the claim is proved.
For each $U$, we fix $s_{U} \in S$ such that

$$
\left\|T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right\|=\left\|T\left(\mathrm{v} \cdot f_{U}\right)\right\| .
$$

Since $\left\|\mathrm{v} \cdot f_{U}\right\|=\|\mathrm{v}\|$ and $T(0)=0$, we have that

$$
\|\mathrm{v}\| / M-1 \leq\left\|T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right\| \leq M\|\mathrm{v}\|+1 .
$$

Then, the net $\left(T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right)_{U \in \mathcal{V}_{k}} \subset X$ is bounded and since $X$ is finite-dimensional, we may assume that $T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right) \rightarrow \mathrm{w}_{0}$, for some $\mathrm{w}_{0} \in X$. Moreover, we have

$$
\begin{equation*}
\left\|\mathrm{w}_{0}\right\| \geq\|\mathrm{v}\| / M-1 \tag{3-3}
\end{equation*}
$$

The vector $\mathrm{w}_{0}$ will be later used to define w .

Now, let us see that $\left(s_{U}\right)_{U \in \mathcal{V}_{k}}$ admits a convergent subnet. It follows by the claim that

$$
\begin{align*}
\limsup \left\|T f\left(s_{U}\right)-T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right\| & \leq \lim \sup \left\|T f-T\left(\mathrm{v} \cdot f_{U}\right)\right\|  \tag{3-4}\\
& \leq M \limsup \left\|f-\mathrm{v} \cdot f_{U}\right\|+1 \\
& \leq M \omega(k, f, \mathrm{v})+1, \text { for all } f \in C_{0}(K, X) .
\end{align*}
$$

Fix $f_{0} \in C_{0}(K, X)$ such that $\left\|f_{0}\right\|=\|\mathrm{v}\| / 2$ and $f_{0}(k)=\mathrm{v} / 2$. Then $\omega\left(k, f_{0}, \mathrm{v}\right)=$ $\|\mathrm{v}\| / 2$ and, by (3-3) and (3-4), we have
(3-5) $\quad \liminf \left\|T f_{0}\left(s_{U}\right)\right\|$

$$
\begin{aligned}
& \geq \liminf \left\|T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right\|-\lim \sup \left\|T f_{0}\left(s_{U}\right)-T\left(\mathrm{v} \cdot f_{U}\right)\left(s_{U}\right)\right\| \\
& \geq\left\|\mathrm{w}_{0}\right\|-\left(M \omega\left(k, f_{0}, \mathrm{v}\right)+1\right) \\
& \geq\|\mathrm{v}\| / M-1-(M\|\mathrm{v}\| / 2+1) \\
& =\|\mathrm{v}\|(1 / M-M / 2)-2
\end{aligned}
$$

Since $M^{2}<S(X) \leq 2$, we have that $1 / M-M / 2>0$, and then, there exists $r_{0}$ depending only on $M$ such that for $\|\mathrm{v}\|>r_{0}$, we have

$$
\liminf \left\|T f_{0}\left(s_{U}\right)\right\|>0
$$

Since $T f_{0}$ vanishes at infinity, it follows that $\left(s_{U}\right)_{U \in \mathcal{V}_{k}}$ admits a convergent subnet, so we may assume that $s_{U} \rightarrow s$. By (3-4), we derive that

$$
\begin{equation*}
\left\|T f(s)-\mathrm{w}_{0}\right\| \leq M \omega(k, f, \mathrm{v})+1, \text { for all } f \in C_{0}(K, X) \tag{3-6}
\end{equation*}
$$

Define $\mathrm{w}=\alpha_{0} \mathrm{w}_{0}$, with $\alpha_{0}=(\|\mathrm{v}\| / M-1) /\left\|\mathrm{w}_{0}\right\|$. We have that $\|\mathrm{w}\|=\|\mathrm{v}\| / M-1$ and, by (3-3), $\alpha_{0} \leq 1$.

We will conclude the proof by showing that (3-6) is also satisfied for w instead of $\mathrm{w}_{0}$. Given $f \in C_{0}(K, X)$, notice that

$$
\|T f(s)\| \leq\|T f\| \leq M\|f\|+1 \leq M \omega(k, f, \mathrm{v})+1
$$

then, by (3-6),

$$
\|T f(s)-\mathrm{w}\| \leq \alpha_{0}\left\|T f(s)-\mathrm{w}_{0}\right\|+\left(1-\alpha_{0}\right)\|T f(s)\| \leq M \omega(k, f, \mathrm{v})+1
$$

From now on, we consider $r_{0}$ given by Proposition 3.1 to be fixed. Since $r_{0}$ depends only on $M$, this same constant works for the sets $\Lambda_{\mathrm{v}}(s, \mathrm{w})$.

## 4. The special sets $\Gamma_{w}(k, v)$ when $M^{2}<S(X)$

In this section we state a fundamental proposition concerning the special sets $\Gamma_{\mathrm{w}}(k, \mathrm{v})$ associated to the ( $M, 1$ )-quasi-isometry $T$ that we are considering.
Proposition 4.1. There exists $r_{1}>r_{0}$, depending only on $M$ and $S(X)$, such that, for all $k \in K, \mathrm{v} \in X$ and $\mathrm{v}^{\prime} \in X$ with $\|\mathrm{v}\|>r_{1}$ and $\left\|\mathrm{v}-\mathrm{v}^{\prime}\right\|<1$, if $s \in \Gamma_{\mathrm{w}}(k,-\mathrm{v})$
for some $\mathrm{w} \in X$ and $s^{\prime} \in \Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$ for some $\mathrm{w}^{\prime} \in X$, then $s=s^{\prime}$.
Proof. Suppose that $s \neq s^{\prime}$. Then, fix $g \in C_{0}(S, X)$ such that

$$
\begin{equation*}
g(s)=-\mathrm{w}, \quad g\left(s^{\prime}\right)=-\mathrm{w}^{\prime} \quad \text { and } \quad\|g\|=\max \left\{\|\mathrm{w}\|,\left\|\mathrm{w}^{\prime}\right\|\right\} \tag{4-1}
\end{equation*}
$$

By applying the definitions of the sets $\Gamma_{\mathrm{w}}(k,-\mathrm{v})$ and $\Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$, respectively, to $T^{-1} \mathrm{~g}$, we get the inequalities

$$
\begin{equation*}
2\|\mathrm{w}\|=\left\|T\left(T^{-1} g\right)(s)-\mathrm{w}\right\| \leq M \omega\left(k, T^{-1} g,-\mathrm{v}\right)+1 \tag{4-2}
\end{equation*}
$$

and

$$
\begin{equation*}
2\left\|\mathrm{w}^{\prime}\right\|=\left\|T\left(T^{-1} g\right)\left(s^{\prime}\right)-\mathrm{w}^{\prime}\right\| \leq M \omega\left(k, T^{-1} g, \mathrm{v}^{\prime}\right)+1 \tag{4-3}
\end{equation*}
$$

Since $\|\mathrm{w}\|=\|\mathrm{v}\| / M-1$, by (4-2) we obtain

$$
\begin{equation*}
\frac{2\|\mathrm{v}\|}{M} \leq M \omega\left(k, T^{-1} g,-\mathrm{v}\right)+3 \tag{4-4}
\end{equation*}
$$

and since $\left\|\mathrm{w}^{\prime}\right\|=\left\|\mathrm{v}^{\prime}\right\| / M-1$ and $\left\|\mathrm{v}-\mathrm{v}^{\prime}\right\|<1$, according to (4-3) we have

$$
\begin{equation*}
\frac{2\|\mathrm{v}\|}{M} \leq M \omega\left(k, T^{-1} g, \mathrm{v}^{\prime}\right)+3+\frac{2}{M} \tag{4-5}
\end{equation*}
$$

and again by $\left\|\mathrm{v}-\mathrm{v}^{\prime}\right\|<1$, we see that

$$
\begin{aligned}
\omega\left(k, T^{-1} g, \mathrm{v}^{\prime}\right) & =\max \left\{\left\|T^{-1} g\right\|,\left\|T^{-1} g(k)-\mathrm{v}^{\prime}\right\|\right\} \\
& \leq \max \left\{\left\|T^{-1} g\right\|,\left\|T^{-1} g(k)-\mathrm{v}\right\|\right\}+1 \\
& =\omega\left(k, T^{-1} g, \mathrm{v}\right)+1
\end{aligned}
$$

Therefore, according to (4-5) we deduce that

$$
\begin{equation*}
\frac{2\|\mathrm{v}\|}{M} \leq M \omega\left(k, T^{-1} g, \mathrm{v}\right)+3+M+\frac{2}{M} \tag{4-6}
\end{equation*}
$$

Thus, putting $\Delta=3+M+2 / M$, it follows from (4-4) and (4-6) that

$$
\frac{2\|\mathrm{v}\|}{M} \leq M \min \left\{\omega\left(k, T^{-1} g,-\mathrm{v}\right), \omega\left(k, T^{-1} g, \mathrm{v}\right)\right\}+\Delta
$$

That is, $2\|\mathrm{v}\| / M$ is less than or equal to

$$
M \min \left\{\max \left\{\left\|T^{-1} g\right\|,\left\|T^{-1} g(k)+\mathrm{v}\right\|\right\}, \max \left\{\left\|T^{-1} g\right\|,\left\|T^{-1} g(k)-\mathrm{v}\right\|\right\}\right\}+\Delta
$$

Then, by using the identity of real numbers $a, b$ and $c$,

$$
\min \{\max \{a, b\}, \max \{a, c\}\}=\max \{a, \min \{b, c\}\},
$$

with

$$
a=\left\|T^{-1} g\right\|, \quad b=\left\|T^{-1} g(k)+\mathrm{v}\right\| \quad \text { and } \quad c=\left\|T^{-1} g(k)-\mathrm{v}\right\|,
$$

we have that

$$
\frac{2\|\mathrm{v}\|}{M} \leq M \max \left\{\left\|T^{-1} g\right\|, \min \left\{\left\|T^{-1} g(k)+\mathrm{v}\right\|,\left\|T^{-1} g(k)-\mathrm{v}\right\|\right\}\right\}+\Delta
$$

Moreover, by applying Lemma 2.1 with $x=T^{-1} g(k)$ and $y=\mathrm{v}$ we conclude that

$$
\begin{equation*}
\frac{2\|\mathrm{v}\|}{M} \leq M \max \left\{\left\|T^{-1} g\right\|, \frac{2}{S(X)} \max \left\{\left\|T^{-1} g(k)\right\|,\|\mathrm{v}\|\right\}\right\}+\Delta \tag{4-7}
\end{equation*}
$$

On the other hand, putting $\Delta^{\prime}=2-M$ and having in mind (4-1) we also infer that

$$
\begin{equation*}
\left\|T^{-1} g\right\| \leq M\|g\|+1=M \max \left\{\|\mathrm{w}\|,\left\|\mathrm{w}^{\prime}\right\|\right\}+1 \leq\|\mathrm{v}\|+\Delta^{\prime} \tag{4-8}
\end{equation*}
$$

Therefore by (4-7) and (4-8) we conclude that

$$
\frac{2\|\mathrm{v}\|}{M} \leq \frac{2 M}{S(X)}\left(\|\mathrm{v}\|+\Delta^{\prime}\right)+\Delta
$$

that is,

$$
2\|\mathrm{v}\|\left(\frac{1}{M}-\frac{M}{S(X)}\right) \leq \frac{2 M \Delta^{\prime}}{S(X)}+\Delta
$$

Since $M^{2}<S(X)$, we have that $1 / M-M / S(X)>0$. Thus, there exists $r_{1} \geq r_{0}$, depending only on $M$ and $S(X)$, such that we have a contradiction for $\mathrm{v} \in X$ with $\|\mathrm{v}\|>r_{1}$.

We consider $r_{1}$ given by Proposition 4.1 to be fixed. Since it depends only on $M$ and $S(X)$, this same constant works for the sets $\Lambda_{\mathrm{v}}(s, \mathrm{w})$. The following consequence of the previous proposition will allow us to define, in the next section, a function $\varphi: K \rightarrow S$ which as we shall see in Section 7 will be a homeomorphism between $K$ and $S$.

Corollary 4.2. For all $k \in K, s, s^{\prime} \in S$, and $\mathrm{v}, \mathrm{v}^{\prime} \in X$, with $\|\mathrm{v}\|>r_{1},\left\|\mathrm{v}^{\prime}\right\|>r_{1}$ and $\left\|\mathrm{v}-\mathrm{v}^{\prime}\right\|<1$, if $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})$ and $s^{\prime} \in \Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$ for some $\mathrm{w}, \mathrm{w}^{\prime} \in X$, then $s=s^{\prime}$.
Proof. Since $\|-\mathrm{v}\|>r_{1} \geq r_{0}$, by Proposition 3.1 there exists $\mathrm{w}^{\prime \prime} \in X$ such that $\Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v}) \neq \varnothing$. Take $s^{\prime \prime} \in \Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v})$.

Observe that since $s^{\prime \prime} \in \Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v})$ and $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})$, it follows by Proposition 4.1 that $s^{\prime \prime}=s$. Moreover, since $s^{\prime \prime} \in \Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v})$ and $s^{\prime} \in \Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$, again by Proposition 4.1 we infer that $s^{\prime \prime}=s^{\prime}$. Hence $s=s^{\prime}$.

## 5. The functions $\varphi: K \rightarrow S$ and $\psi: S \rightarrow K$

In this section, we will begin to construct a homeomorphism between $K$ and $S$ via the following proposition.

Proposition 5.1. For all $k \in K$ there exists $s \in S$ such that for all $\mathrm{v} \in X$ with $\|\mathrm{v}\|>r_{1}$ and $\mathrm{w} \in X$, either $\Gamma_{\mathrm{w}}(k, \mathrm{v})=\{s\}$ or $\Gamma_{\mathrm{w}}(k, \mathrm{v})=\varnothing$.

Proof. Take $k \in K$ and put $A=\left\{\mathrm{v} \in X:\|\mathrm{v}\|>r_{1}\right\}$. Hence, it suffices to prove that for any $\mathrm{v}, \mathrm{v}^{\prime} \in A$, if $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})$ and $s^{\prime} \in \Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$ for some $\mathrm{w}, \mathrm{w}^{\prime} \in X$, then $s=s^{\prime}$.

Suppose thus that $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})$ and $s^{\prime} \in \Gamma_{\mathrm{w}^{\prime}}\left(k, \mathrm{v}^{\prime}\right)$ for some $\mathrm{w}, \mathrm{w}^{\prime} \in X$. We will distinguish two cases.
Case 1. $X$ is of dimension at least 2. Therefore $A$ is path-connected. So we may find points $\mathrm{u}_{0}, \ldots, \mathrm{u}_{n}$ in $A$ such that $\mathrm{u}_{0}=\mathrm{v}^{\prime}, \mathrm{u}_{n}=\mathrm{v}$ and $\left\|\mathrm{u}_{j}-\mathrm{u}_{j-1}\right\|<1$ for all $1 \leq j \leq n$. Put $s_{0}=s^{\prime}$ and $s_{n}=s$. Moreover, according to Proposition 3.1, for each $1 \leq j \leq n-1$, there exists $s_{j} \in S$ and $\mathrm{w}_{j} \in X$ such that $s_{j} \in \Gamma_{\mathrm{w}_{j}}\left(k, \mathrm{u}_{j}\right)$.

For each $1 \leq j \leq n$, since $\left\|\mathrm{u}_{j}-\mathrm{u}_{j-1}\right\|<1$, Corollary 4.2 implies that $s_{j}=s_{j-1}$. By using this fact repeatedly, we conclude that $s^{\prime}=s_{1}=\cdots=s_{n-1}=s$.
Case 2. $X=\mathbb{R}$. In this case, fix $\mathrm{w}^{\prime \prime}$ such that $\Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v}) \neq \varnothing$. Then, using Proposition 4.1 we have

$$
\Gamma_{\mathrm{w}^{\prime \prime}}(k,-\mathrm{v})=\Gamma_{\mathrm{w}}(k, \mathrm{v})=\{s\} .
$$

Since $A=\left(-\infty,-r_{1}\right) \cup\left(r_{1},+\infty\right)$, there is a path in $A$ connecting $\mathrm{v}^{\prime}$ to either v or -v . Then, proceeding as in Case 1 we conclude that $s^{\prime}=s$.

Thus, we are able to define the function $\varphi: K \rightarrow S$ where $\varphi(k)$ is the element $s$ given by Proposition 5.1. By symmetry, we may also define a function $\psi: S \rightarrow K$ such that $\psi(s)$ is the element $k$ given by the symmetric version of Proposition 5.1.

To show that in fact $\varphi$ and $\psi$ are continuous and $\psi^{-1}=\varphi$ we will still need to prove another property of the sets $\Gamma_{\mathrm{w}}(k, \mathrm{v})$.

## 6. Another decisive property of the sets $\Gamma_{\mathrm{w}}(k, v)$ when $M^{2}<S(X)$

The next proposition will help us prove that functions $\varphi$ and $\psi$ defined in the previous section are homeomorphisms provided that we change the number $r_{1}$ in the statement of Proposition 5.1 by another convenient number greater than it. See Proposition 7.1.

Proposition 6.1. There exists $r_{2}>r_{1}$, depending only on $M$ and $S(X)$, such that, for all $k \in K$ and $\mathrm{v} \in X$ with $\|\mathrm{v}\|>r_{2}$, if $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})$ for some $\mathrm{w} \in X$ and $\Lambda_{\mathrm{z}}(s, \mathrm{w}) \neq \varnothing$ for some $\mathrm{z} \in X$, then $\Lambda_{\mathrm{z}}(s, \mathrm{w})=\{k\}$.

Proof. Pick $k^{\prime} \in \Lambda_{\mathrm{z}}(s, \mathrm{w})$ and we must show that $k^{\prime}=k$. Suppose the contrary and fix $f \in C_{0}(K, X)$ such that

$$
\begin{equation*}
f(k)=\frac{\mathrm{v}}{2}, \quad f\left(k^{\prime}\right)=-\frac{\|\mathrm{v}\|}{2\|\mathrm{z}\|} \mathrm{z} \quad \text { and } \quad\|f\|=\frac{\|\mathrm{v}\|}{2} . \tag{6-1}
\end{equation*}
$$

Thus,

$$
\omega(k, f, \mathrm{v})=\frac{\|\mathrm{v}\|}{2}
$$

Applying the definition of $\Gamma_{\mathrm{w}}(k, v)$ to $f$, we see that

$$
\|T f(s)-\mathrm{w}\| \leq M \omega(k, f, \mathrm{v})+1=\frac{M}{2}\|\mathrm{v}\|+1
$$

Moreover, since

$$
\|T f\| \leq M\|f\|+1=\frac{M}{2}\|\mathrm{v}\|+1
$$

it follows that

$$
\omega(s, T f, \mathrm{w}) \leq \frac{M}{2}\|\mathrm{v}\|+1
$$

So, by applying the definition of $\Lambda_{\mathrm{z}}(s, \mathrm{w})$ to $T f$, we have
(6-2) $\left\|f\left(k^{\prime}\right)-\mathrm{z}\right\|=\left\|T^{-1}(T f)\left(k^{\prime}\right)-\mathrm{z}\right\| \leq M \omega(s, T f, \mathrm{w})+1 \leq \frac{M^{2}}{2}\|\mathrm{v}\|+M+1$.
On the other hand, since $\|\mathrm{w}\|=\|\mathrm{v}\| / M-1$ and $\|\mathrm{z}\|=\|\mathrm{w}\| / M-1$ we obtain

$$
\|\mathrm{z}\|=\left(\frac{\|\mathrm{v}\|}{M}-1\right) \frac{1}{M}-1=\frac{\|\mathrm{v}\|}{M^{2}}-\frac{1}{M}-1
$$

Furthermore, according to (6-1), $f\left(k^{\prime}\right)$ and z have opposite directions. Then

$$
\begin{equation*}
\left\|f\left(k^{\prime}\right)-\mathrm{z}\right\|=\left\|f\left(k^{\prime}\right)\right\|+\|\mathrm{z}\|=\frac{\|\mathrm{v}\|}{2}+\frac{\|\mathrm{v}\|}{M^{2}}-\frac{1}{M}-1 \tag{6-3}
\end{equation*}
$$

Therefore, putting $\Delta^{\prime \prime}=M+2+1 / M$, by (6-2) and (6-3) we conclude that

$$
\begin{equation*}
\left(\frac{1}{2}+\frac{1}{M^{2}}-\frac{M^{2}}{2}\right)\|\mathrm{v}\| \leq \Delta^{\prime \prime} \tag{6-4}
\end{equation*}
$$

Since $M^{2}<S(X) \leq 2$, it can be easily seen that

$$
\frac{1}{2}+\frac{1}{M^{2}}-\frac{M^{2}}{2}>0
$$

So, there exists $r_{2} \geq r_{1}$ depending only on $M$ and $S(X)$ such that the inequality (6-4) fails to be true for $\mathrm{v} \in X$ with $\|\mathrm{v}\|>r_{2}$, completing the proof of the proposition.

As we did to $r_{0}$ and $r_{1}$, we may fix $r_{2}$ given by the Proposition 6.1 , and it is clear that this constant also works for the for the sets $\Lambda_{\mathrm{v}}(s, \mathrm{w})$.

## 7. The topological spaces $K$ and $S$ are homeomorphic

Observe that the statements of Proposition 3.1, Corollary 4.2, Proposition 5.1 and Proposition 6.1 remain true if we change $r_{0}$ and $r_{1}$ to $r_{2}$. Consider thus $\varphi$ and $\psi$ defined as at the end of Section 5. To complete the proof of Theorem 1.1, we prove the following proposition.

Proposition 7.1. The functions $\varphi: K \rightarrow S$ and $\psi: S \rightarrow K$ are continuous and $\psi=\varphi^{-1}$.

Proof. First we will show that $\psi=\varphi^{-1}$. Fix $k \in K$. By the definition of $\varphi(k)$ there are $\mathrm{v}, \mathrm{w} \in X$ with $\|\mathrm{v}\|>\left(r_{2}+1\right) M$ such that

$$
\varphi(k) \in \Gamma_{\mathrm{w}}(k, \mathrm{v})
$$

Thus, $\|\mathrm{w}\|>r_{2}$ and by Proposition 3.1 there exists $\mathrm{z} \in X$ satisfying $\Lambda_{\mathrm{z}}(\varphi(k), \mathrm{w}) \neq \varnothing$. Then, according to Proposition 6.1 we know that

$$
\Lambda_{\mathrm{z}}(\varphi(k), \mathrm{w})=\{k\}
$$

Therefore, it follows by the definition of $\psi$ that $\psi(\varphi(k))=k$. Hence $\psi \circ \varphi=\operatorname{Id}_{K}$. Analogously we deduce that $\varphi \circ \psi=\operatorname{Id}_{S}$.

We will now prove that $\varphi$ is continuous. The proof that $\psi$ is continuous is analogous. Observe that it suffices to prove that for each net $\left(k_{j}\right)_{j \in J}$ of $K$ converging to $k \in K$, the net $\left(\varphi\left(k_{j}\right)\right)_{j \in J}$ admits a subnet converging to $\varphi(k)$.

Assume then that $\left(k_{j}\right)_{j \in J}$ is a net of $K$ converging to $k$. For all $j \in J$ take $\mathrm{v}_{j}$ and $\mathrm{w}_{j}$ such that $\left\|\mathrm{v}_{j}\right\|=c$, for some $c>r_{2}$, and

$$
\begin{equation*}
\varphi\left(k_{j}\right) \in \Gamma_{\mathrm{w}_{j}}\left(k_{j}, \mathrm{v}_{j}\right) \tag{7-1}
\end{equation*}
$$

Since the nets $\left(\mathrm{v}_{j}\right)_{j \in J}$ and $\left(\mathrm{w}_{j}\right)_{j \in J}$ are contained in compact sets, we may assume that there are $\mathrm{v}, \mathrm{w} \in X$ such that $\mathrm{v}_{j} \rightarrow \mathrm{v}$ and $\mathrm{w}_{j} \rightarrow \mathrm{w}$.

For each $f \in C_{0}(K, X)$ we have

$$
\begin{equation*}
\omega\left(k_{j}, f, \mathrm{v}_{j}\right) \rightarrow \omega(k, f, \mathrm{v}) \tag{7-2}
\end{equation*}
$$

and according to (7-1),

$$
\begin{equation*}
\left\|T f\left(\varphi\left(k_{j}\right)\right)-\mathrm{w}_{j}\right\| \leq M \omega\left(k_{j}, f, \mathrm{v}_{j}\right)+1, \quad \text { for all } j \in J \tag{7-3}
\end{equation*}
$$

Fix $f_{1} \in C_{0}(K, X)$ satisfying $\left\|f_{1}\right\|=\|\mathrm{v}\| / 2$ and $f_{1}(x)=\mathrm{v} / 2$. Then (7-3) implies

$$
\begin{aligned}
\left\|T f_{1}\left(\varphi\left(k_{j}\right)\right)\right\| & \geq\left\|\mathrm{w}_{j}\right\|-\left\|T f_{1}\left(\varphi\left(k_{j}\right)\right)-\mathrm{w}_{j}\right\| \\
& \geq \frac{c}{M}-M \omega\left(k_{j}, f_{1}, \mathrm{v}_{j}\right)-2
\end{aligned}
$$

for every $j \in J$. Notice that $\omega\left(k, f_{1}, \mathrm{v}\right)=\|\mathrm{v}\| / 2=c / 2$, so by (7-2) we have

$$
\liminf _{j \in J}\left\|T f_{1}\left(\varphi\left(k_{j}\right)\right)\right\| \geq\left(\frac{1}{M}-\frac{M}{2}\right) c-2
$$

and since $c>r_{2} \geq r_{0}$ and recalling (3-5), we obtain

$$
\liminf _{j \in J}\left\|T f_{1}\left(\varphi\left(k_{j}\right)\right)\right\|>0
$$

Since $T f_{1}$ vanishes at infinity, this implies that $\left(\varphi\left(k_{j}\right)\right)_{j \in J}$ admits a subnet converging to some $s \in S$, so we assume that $\varphi\left(k_{j}\right) \rightarrow s$. Hence, by (7-2) and (7-3),

$$
\|T f(s)-\mathrm{w}\| \leq M \omega(k, f, \mathrm{v})+1, \quad \text { for all } f \in C_{0}(K, X)
$$

which means that $s \in \Gamma_{\mathrm{w}}(k, \mathrm{v})=\{\varphi(k)\}$. Consequently $s=\varphi(k)$.

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