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LOWER SEMICONTINUITY OF THE ADM MASS IN DIMENSIONS TWO THROUGH SEVEN

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The semicontinuity phenomenon of the ADM mass under pointed (i.e., local) convergence of asymptotically flat metrics is of interest because of its connections to nonnegative scalar curvature, the positive mass theorem, and Bartnik’s mass-minimization problem in general relativity. We extend a previously known semicontinuity result in dimension three for C^2 pointed convergence to higher dimensions, up through seven, using recent work of S. McCormick and P. Miao (which itself builds on the Riemannian Penrose inequality of H. Bray and D. Lee). For a technical reason, we restrict to the case in which the limit space is asymptotically Schwarzschild. In a separate result, we show that semicontinuity holds under weighted, rather than pointed, C^2 convergence, in all dimensions $n \geq 3$, with a simpler proof independent of the positive mass theorem. Finally, we also address the two-dimensional case for pointed convergence, in which the asymptotic cone angle assumes the role of the ADM mass.

1. Introduction

Motivated by the Bartnik minimal mass extension conjecture in general relativity [1989; 1997; 2002], as well as the study of Ricci flow on asymptotically flat manifolds [Dai and Ma 2007; Oliynyk and Woolgar 2007], in [Jauregui 2018] the author established the following result regarding how the ADM mass behaves under pointed convergence of a sequence of asymptotically flat 3-manifolds of nonnegative scalar curvature. Briefly, the ADM mass cannot increase in a local C^2 limit:

Theorem 1 [Jauregui 2018]. *Let (M_i, g_i, p_i) be a sequence of pointed asymptotically flat 3-manifolds without boundary, such that each (M_i, g_i) has nonnegative scalar curvature and contains no compact minimal surfaces. If (M_i, g_i, p_i) converges in the pointed C^2 Cheeger–Gromov sense to a pointed asymptotically flat 3-manifold (N, h, q) , then*

$$(1) \quad m_{\text{ADM}}(N, h) \leq \liminf_{i \rightarrow \infty} m_{\text{ADM}}(M_i, g_i).$$

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We recall the relevant definitions in Section 3; for now we note that pointed C^k Cheeger–Gromov convergence essentially means C^k convergence of the metric tensors on compact subsets, modulo diffeomorphisms. Examples are given in [Jauregui 2018] in which strictness holds in (1).

Theorem 1 is intimately connected to scalar curvature and to the positive mass theorem (PMT) [Schoen and Yau 1979a; Witten 1981]. In [Jauregui 2018] it was shown that (1) can fail without assuming nonnegative scalar curvature (and the absence of compact minimal surfaces). Somewhat surprisingly, a simple blow-up example in [Jauregui 2018] shows that Theorem 1 actually implies the PMT. However, to prove Theorem 1, either the PMT itself, or a stronger result, is required. The key estimate in the proof of Theorem 1 was the lower bound

$$(2) \quad m_{\text{ADM}} \geq m_H(\Sigma)$$

of the ADM mass in terms of the Hawking mass of an outward-minimizing surface Σ , established by G. Huisken and T. Ilmanen [2001]. Note that it is well known that (2) implies the PMT.

Two major questions were left unsettled in [Jauregui 2018]. First, to what extent does this lower semicontinuity property of the ADM mass hold for weaker convergence than C^2 ? Subsequently the author and D. Lee proved in [Jauregui and Lee 2017] that the theorem continues to hold if only pointed C^0 convergence is assumed. Second, does Theorem 1 generalize to higher dimensions? The primary concern of the present paper is to address the latter question.

Unfortunately, a bound directly analogous to (2) is unknown beyond dimension three: Huisken–Ilmanen’s proof in $n = 3$ uses “Geroch monotonicity” of the Hawking mass, which crucially relies on the Gauss–Bonnet theorem in one dimension lower. Generally, the missing link in establishing Theorem 1 in higher dimensions has been a useful quantitative lower bound for the ADM mass in terms of the geometry of an outward-minimizing surface. Fortunately, a recent result of S. McCormick and P. Miao [2017] provides such an estimate (see Theorem 7 below) that is sufficient for our purposes. Their work uses the Riemannian Penrose inequality in higher dimensions, due to Bray and Lee [2009] (which itself was a generalization of Bray’s original proof in dimension three [2001]). Our main result is:

Theorem 2. *Theorem 1 is true with “3” replaced by “ n ”, where $3 \leq n \leq 7$, provided the limit (N, h) is asymptotically Schwarzschild.*

The Riemannian manifolds (M_i, g_i) need not be asymptotically Schwarzschild even if their limit (N, h) is.

The restriction in Theorem 2 of $n \leq 7$ is primarily due to the fact that it is the highest dimension in which the Riemannian Penrose inequality is currently known. It was pointed out in [Bray and Lee 2009] that even the positive mass theorem

for $n \geq 8$ is insufficient to automatically extend the Riemannian Penrose inequality to $n \geq 8$. We strongly conjecture that the $n \leq 7$ restriction is unnecessary, and that the asymptotically Schwarzschild hypothesis can be replaced with asymptotic flatness; see Remark D.

Remark A. It is reasonable to attempt to extend Theorem 1 to spin manifolds in higher dimensions using Witten’s spinor technique in his proof of the PMT [1981]. However, as pointed out to the author by Bray, it is not clear how to make effective use of the hypothesis of no compact minimal surfaces in the spinor argument, and it was shown in [Jauregui 2018] that (1) can fail without this hypothesis.

For the purpose of telling a more complete story, we also include two other related results. First, assuming weighted (rather than pointed) C^2 convergence, we prove lower semicontinuity of the ADM mass in all dimensions $n \geq 3$ (Theorem 13 below). Weighted convergence assumes global control on the asymptotics of the metrics, in contrast to pointed convergence. In this case, with a stronger hypothesis than in Theorems 1 and 2, the absence of compact minimal surfaces is unnecessary and the proof is easier. However, the weighted result does not recover nor rely on the positive mass theorem. Prior results for weighted convergence were known; see Section 6 (in particular Remark E) for details.

Second, it was suggested by E. Woolgar that the author investigate the lower semicontinuity of “mass” in dimension two. This is carried out in Section 7 for pointed C^2 convergence, where the asymptotic cone angle replaces the ADM mass; see Theorem 14.

2. Motivation and examples

In this section we describe several examples to motivate the lower semicontinuity phenomenon for the ADM mass.

2.1. Lower semicontinuity of mass in Newtonian gravity. We begin here with a general discussion of why lower semicontinuity of the total mass is plausible from the point of view of Newtonian gravity. Consider a matter distribution on $\mathbb{R}^n$ described by a continuous, integrable mass density function $\rho \geq 0$. The total Newtonian mass is simply given by the integral

$$m(\rho) = \int_{\mathbb{R}^n} \rho \, dx^1 \cdots dx^n.$$

Now, if $\{\rho_i\}_{i=1}^\infty$ is a sequence of such matter distributions that converges pointwise to ρ , then by Fatou’s lemma,

$$\liminf_{i \rightarrow \infty} m(\rho_i) \geq m(\rho).$$

Any drop in the total Newtonian mass can be viewed as mass escaping out to infinity

in the limit. Such an argument does not apply to the context of general relativity, because the ADM mass is not known (or expected) to be given as the integral of a locally defined, nonnegative, geometric/physical quantity.

Convergence of ρ_i to ρ in Newtonian gravity is analogous to C^2 convergence of the Riemannian metrics in general relativity, as the scalar curvature represents energy density and is given by two derivatives of the metric. The C^0 convergence in [Jauregui and Lee 2017] can then be viewed as a general relativistic analog of convergence of the Newtonian gravitational potentials $u_i \rightarrow u$, where $\Delta u_i = 4\pi\rho_i$ and $\Delta u = 4\pi\rho$.

2.2. Blow-up example. In [Jauregui 2018], the author gave the example of a fixed asymptotically flat n -manifold (M, g) of nonnegative scalar curvature and considered the sequence of homothetic rescalings $\{(M, i^2g, p)\}$ for $p \in M$ fixed and $i = 1, 2, \dots$. This sequence converges in the pointed C^2 Cheeger–Gromov sense to Euclidean $\mathbb{R}^n$ (which has zero ADM mass), and indeed the statement of lower semicontinuity of mass implies that the ADM mass of (M, g) is nonnegative. In other words, the positive mass theorem is recovered.

The example in Section 2.1 suggests that from a Newtonian point of view, the mass-drop phenomenon can be completely accounted for by matter escaping off to infinity. But by choosing (M, g) here to be scalar-flat (i.e., vacuum) with positive ADM mass, the example of $\{(M, i^2g, p)\}$ converging to Euclidean space shows that the mass can drop by an infinite amount in the limit with no matter fields present. This can be interpreted as the energy of the gravitational field escaping to infinity.

2.3. Escaping point example. Similar to the previous example, begin with a fixed asymptotically flat n -manifold (M, g) . Now consider a sequence of points $\{p_i\}$ in M escaping to infinity. By asymptotic flatness, the sequence $\{(M, g, p_i)\}$ converges in the pointed C^2 Cheeger–Gromov sense to Euclidean $\mathbb{R}^n$. Again the statement of lower semicontinuity of ADM mass here recovers the positive mass theorem; and again by choosing (M, g) to be scalar-flat with positive ADM mass we can interpret the mass drop as gravitational energy escaping to infinity.

2.4. Lower semicontinuity of mass and Ricci flow. To the author’s knowledge, the ADM mass drop phenomenon under pointed convergence was first observed by T. Oliynyk and Woolgar in their study of Ricci flow on rotationally symmetric, asymptotically flat spaces [2007]; see also the work of X. Dai and L. Ma, who first showed that the ADM mass is constant along Ricci flow, thereby arguing an asymptotically flat Ricci flow cannot converge uniformly to Euclidean space [Dai and Ma 2007]. Under natural hypotheses, Oliynyk and Woolgar proved the long-time existence of Ricci flow on asymptotically flat, rotationally symmetric spaces, with pointed C^k Cheeger–Gromov convergence to Euclidean space as $t \rightarrow \infty$.

Moreover, the ADM mass is not only monotone but is in fact constant along the Ricci flow. In particular, if the initial space has positive ADM mass, then the ADM mass must drop to zero in the limit.

In light of this discussion, the author suggested in [Jauregui 2018] that using Theorem 1 (or its higher-dimensional analog) would be necessary in any proof of the PMT that involved convergence of the Ricci flow to Euclidean space. Since Theorem 1 already subsumes the PMT, this seemed to suggest that an independent Ricci flow proof of the PMT was unlikely. Nevertheless, such a proof has very recently been given by Y. Li in [2018]. His argument circumvents this apparent circular logic by establishing lower semicontinuity of the ADM mass directly for the case of a convergent Ricci flow (i.e., the technique does not apply to general pointed C^2 Cheeger–Gromov convergence). We generalize Li’s argument to weighted C^2 convergence in Section 6.

3. Background

We begin with the definition of an asymptotically flat manifold (with one end). Many slight variants appear in the literature; the version below is commonly used.

Definition 3. A smooth, connected Riemannian n -manifold (M, g) , with $n \geq 3$, possibly with compact boundary, is *asymptotically flat* (AF) if there exists a compact set $K \subset M$ and a diffeomorphism $\Phi : M \setminus K \rightarrow \mathbb{R}^n \setminus B$, for a closed ball B , such that in the “asymptotically flat” coordinates $x = (x^1, \dots, x^n)$ given by Φ , we have

$$(3) \quad g_{ij} = \delta_{ij} + O(|x|^{-\tau}), \quad \partial_k g_{ij} = O(|x|^{-\tau-1}), \quad \partial_k \partial_\ell g_{ij} = O(|x|^{-\tau-2}),$$

for some constant $\tau > \frac{n-2}{2}$ (the *order*), and the scalar curvature of g is integrable. (Indices i, j, k, ℓ above run from 1 to n , and ∂ denotes partial differentiation in the coordinate chart.)

For example, for a real number $m > 0$, the Schwarzschild metric

$$g_{ij} = \left(1 + \frac{m}{2|x|^{n-2}}\right)^{\frac{4}{n-2}} \delta_{ij}$$

on $\mathbb{R}^n$ minus a ball about the origin is asymptotically flat of order $n - 2$.

We will also need two classes of asymptotically flat manifolds with more restricted asymptotics at infinity:

Definition 4. An asymptotically flat Riemannian n -manifold (M, g) is *asymptotically Schwarzschild* if there exists an “asymptotically Schwarzschild coordinate system” $(x^1, \dots, x^n)$ on $M \setminus K$, i.e.,

$$(4) \quad g_{ij} = \left(1 + \frac{m}{2|x|^{n-2}}\right)^{\frac{4}{n-2}} \delta_{ij} + h_{ij},$$

for some real constant m , where

$$(5) \quad h_{ij} = O(|x|^{1-n}), \quad \partial_k h_{ij} = O(|x|^{-n}), \quad \partial_k \partial_\ell h_{ij} = O(|x|^{-n-1}).$$

Note that an asymptotically Schwarzschild Riemannian n -manifold is AF of order $n - 2$.

Definition 5. An asymptotically flat Riemannian n -manifold (M, g) is *harmonically flat at infinity (HF)* if there exists a “harmonically flat coordinate system” $(x^1, \dots, x^n)$ on $M \setminus K$, i.e.,

$$g_{ij} = U^{\frac{4}{n-2}} \delta_{ij},$$

on $M \setminus K$ for some function U , where $\Delta U = 0$ and $U(x) \rightarrow 1$ as $|x| \rightarrow \infty$. (Here Δ is the Euclidean Laplacian on $\mathbb{R}^n$.)

It is well known that the harmonic function U appearing in Definition 5 admits an expansion at infinity of the form

$$(6) \quad U(x) = 1 + \frac{a}{|x|^{n-2}} + O_\infty(|x|^{-n+1}),$$

where the notation $O_k(|x|^\ell)$ denotes an expression that is $O(|x|^\ell)$ for $|x|$ large and for which the γ th partial derivative (γ being a multi-index with $|\gamma| \leq k$) is $O(|x|^{\ell-|\gamma|})$. The fact that $\Delta U = 0$ implies that g as above has zero scalar curvature outside of K . Note that HF manifolds are necessarily asymptotically Schwarzschild, and that the Schwarzschild metric itself is HF.

Next, we recall the definition of ADM mass.

Definition 6. The *ADM mass* [Arnowitt et al. 1961] (cf. [Bartnik 1986; Chruściel 1986]) of an asymptotically flat manifold (M, g) of dimension n is the real number

$$m_{\text{ADM}}(M, g) = \frac{1}{2(n-1)\omega_{n-1}} \lim_{r \rightarrow \infty} \int_{S_r} \sum_{i,j=1}^n (\partial_i g_{ij} - \partial_j g_{ii}) \frac{x^j}{r} dA,$$

where dA is the induced volume form on the coordinate sphere

$$S_r = \{|x| = r\}$$

with respect to the Riemannian metric δ_{ij} , all in an AF coordinate chart.

It is straightforward to verify that for an HF manifold, the ADM mass is given by the value $2a$, where a is the constant appearing in (6), and for an asymptotically Schwarzschild manifold, the ADM mass is given by the constant m appearing in (5).

Recall that if (M, g) is asymptotically flat with boundary ∂M , then we say ∂M is *outward-minimizing* if

$$|S| \geq |\partial M|$$

for all surfaces S enclosing ∂M , where $|\cdot|$ denotes the hypersurface area (with respect to g). The following theorem was recently proved by McCormick and Miao [2017].

Theorem 7 [McCormick and Miao 2017]. *Let (M, g) be an AF manifold of dimension $3 \leq n \leq 7$, with compact, connected boundary Σ that is outward-minimizing. Assume that the scalar curvature of (M, g) is nonnegative. Let $H \geq 0$ be the mean curvature of Σ (in the direction pointing into M), let ρ be the scalar curvature of Σ with respect to the induced Riemannian metric, and suppose that*

$$\min_{\Sigma} \rho > \frac{n-2}{n-1} \max_{\Sigma} H^2.$$

Then

$$(7) \quad m_{\text{ADM}}(M, g) \geq \frac{1}{2} \left(\frac{|\Sigma|}{\omega_{n-1}} \right)^{\frac{n-2}{n-1}} \left(1 - \frac{n-2}{n-1} \frac{\max_{\Sigma} H^2}{\min_{\Sigma} \rho} \right).$$

To simplify notation later, we make the following definition.

Definition 8. Let S be a smooth, compact hypersurface in a Riemannian manifold (M, g) of dimension $n \geq 3$. Define

$$F_g(S) = \frac{1}{2} \left(\frac{|S|}{\omega_{n-1}} \right)^{\frac{n-2}{n-1}} \left(1 - \frac{n-2}{n-1} \cdot \frac{\max_S H^2}{\min_S \rho} \right),$$

where $|S|$, H , and ρ are the area, mean curvature, and scalar curvature of S with respect to the Riemannian metric induced by g .

We conclude this section with the definition of convergence used in Theorems 1 and 2.

Definition 9. Fix a nonnegative integer ℓ . A sequence of complete, connected, pointed Riemannian n -manifolds (M_i, g_i, p_i) converges in the *pointed C^ℓ Cheeger–Gromov sense* to a complete, connected, pointed Riemannian n -manifold (N, h, q) if for every $r > 0$ there exists a domain Ω containing the metric ball $B_h(q, r)$ in (N, h) , and there exist (for all i sufficiently large) smooth embeddings

$$\Phi_i : \Omega \rightarrow M_i$$

such that $\Phi_i(\Omega)$ contains the metric ball $B_{g_i}(p_i, r)$, and the Riemannian metrics $\Phi_i^* g_i$ converge in C^ℓ norm to h as tensors on Ω .

Note that no M_i need be diffeomorphic to N in the above definition, and that the asymptotics of M_i can be wildly different from those of N in the noncompact case.

4. The mass of asymptotically Schwarzschild metrics

In this section we prove that the ADM mass of an asymptotically Schwarzschild manifold can be recovered from the $r \rightarrow \infty$ limit of the expression $F_g(S_r)$, a key ingredient in the proof of Theorem 2. Before doing so (in Lemma 11), we first verify this for HF metrics in Lemma 10.

Remark B. For an asymptotically flat manifold (M, g) of dimension $3 \leq n \leq 7$, the inequality

$$m_{\text{ADM}}(M, g) \geq \limsup_{r \rightarrow \infty} F_g(S_r)$$

follows from Theorem 7. However, equality need not hold. Such an example, pointed out to the author by McCormick, can be found by considering an AF manifold (M, g) of nonnegative scalar curvature and strictly positive ADM mass that contains an isometric copy of half of a Euclidean space. Such spaces were constructed by Carlotto and Schoen [2016]. For r sufficiently large, S_r intersects the Euclidean region in M , which gives $F_g(S_r) \leq 0$.

Lemma 10. *If (M, g) is an HF manifold, then*

$$(8) \quad m_{\text{ADM}}(M, g) = \lim_{r \rightarrow \infty} F_g(S_r),$$

where F_g is given in Definition 8, and S_r is the coordinate sphere $\{|x| = r\}$ in a harmonically flat coordinate system.

Except for the calculations (9) at the end of the following proof, the proof of Lemma 11 will be independent of Lemma 10.

Proof. The proof involves straightforward computations of the asymptotic behavior, for large r , of the area, mean curvature, and scalar curvature of S_r . Let U be the harmonic function as in Definition 5, with expansion (6).

First we compute the area of S_r :

$$\begin{aligned} |S_r|_g &= \int_{S_r} U^{\frac{2(n-1)}{n-2}} dA \\ &= \int_{S_r} \left(1 + \frac{2a(n-1)}{(n-2)r^{n-2}} + O(r^{1-n}) \right) dA \\ &= \omega_{n-1} r^{n-1} \left(1 + \frac{2a(n-1)}{(n-2)r^{n-2}} \right) + O(1), \end{aligned}$$

where dA is the area form on S_r induced by δ . In particular,

$$\frac{1}{2} \left(\frac{|S_r|_g}{\omega_{n-1}} \right)^{\frac{n-2}{n-1}} = \frac{1}{2} r^{n-2} \left(1 + \frac{2a}{r^{n-2}} \right) + O(r^{-1}).$$

Second we compute the mean curvature. Recall that the mean curvature of S_r with respect to δ_{ij} is $\frac{n-1}{r}$. From a well-known formula relating the mean curvatures of conformally related Riemannian metrics, letting H_r represent the mean curvature of S_r with respect to g , we have

$$\begin{aligned} H_r &= U^{-\frac{2}{n-2}} \cdot \frac{n-1}{r} + \frac{2(n-1)}{n-2} \cdot U^{-\frac{n}{n-2}} \cdot \nu(U) \\ &= \left(1 + \frac{a}{r^{n-2}} + O(r^{1-n})\right)^{-\frac{2}{n-2}} \cdot \frac{n-1}{r} \\ &\quad + \frac{2(n-1)}{n-2} \left(1 + \frac{a}{r^{n-2}} + O(r^{1-n})\right)^{-\frac{n}{n-2}} \left(-\frac{a(n-2)}{r^{n-1}} + O(r^{-n})\right) \\ &= \left(1 - \frac{2a}{(n-2)r^{n-2}} + O(r^{1-n})\right) \cdot \frac{n-1}{r} \\ &\quad + \frac{2(n-1)}{n-2} \left(1 - \frac{an}{(n-2)r^{n-2}} + O(r^{1-n})\right) \left(-\frac{a(n-2)}{r^{n-1}} + O(r^{-n})\right) \\ &= \frac{n-1}{r} - \frac{2a(n-1)^2}{(n-2)r^{n-1}} + O(r^{-n}), \end{aligned}$$

where we used the fact that the δ -unit normal ν to S_r equals $\frac{\partial}{\partial r}$. Thus,

$$H_r^2 = \frac{(n-1)^2}{r^2} - \frac{4a(n-1)^3}{(n-2)r^n} + O(r^{-n-1}).$$

Third, we compute the scalar curvature of S_r with respect to $g|_{TS_r}$. Recall that if $g_2 = e^{2\psi} g_1$ are conformally related Riemannian metrics on a manifold of dimension $n-1$, then their scalar curvatures are related by

$$R_{g_2} = e^{-2\psi} (R_{g_1} - 2(n-2)\Delta_{g_1}\psi - (n-3)(n-2)|d\psi|_{g_1}^2).$$

In particular, with $g_2 = g|_{TS_r}$, $g_1 = \delta|_{TS_r}$, and $U^{\frac{4}{n-2}} = e^{2\psi}$ on S_r , we have

$$\rho = U^{-\frac{4}{n-2}} \left(\frac{(n-1)(n-2)}{r^2} - \frac{4\Delta_r U}{U} + \frac{4|\nabla_r U|^2}{(n-2)U^2} \right),$$

where Δ_r and ∇_r are the Laplacian and (tangential) gradient on S_r with the Riemannian metric induced from δ , and $|\cdot|^2$ is taken with respect to δ . Now, we address the Laplacian term. A well known formula for smooth functions f on $\mathbb{R}^n$ is

$$\Delta f = \Delta_\Sigma f + \text{Hess}(f)(\nu, \nu) + H\partial_\nu(f),$$

where Σ is a smooth hypersurface with unit normal ν , mean curvature H in the direction of ν , and induced Laplacian Δ_Σ . Applying this to $f = U$ and $\Sigma = S_r$, we have

$$0 = \Delta_r U + \text{Hess}(U)(\partial_r, \partial_r) + \frac{n-1}{r} \cdot \frac{\partial U}{\partial r}.$$

By explicit calculation, the leading (i.e., $O(r^{-n})$) terms of $\text{Hess}(U)(\partial_r, \partial_r)$ and $\frac{n-1}{r} \cdot \frac{\partial U}{\partial r}$ cancel, implying that

$$\Delta_r U = O(r^{-n-1}).$$

Next, for the term $|\nabla_r U|$, since $1 + a/(r^{n-2})$ is constant on S_r , we see from the expansion of U that

$$|\nabla_r U|^2 = O(r^{-2n}).$$

Using these expansions, along with the expansion for U , we arrive at

$$\begin{aligned} \rho &= \left(1 + \frac{a}{r^{n-2}} + O(r^{1-n})\right)^{-\frac{4}{n-2}} \left(\frac{(n-1)(n-2)}{r^2} + O(r^{-n-1})\right) \\ &= \frac{(n-1)(n-2)}{r^2} - \frac{4a(n-1)}{r^n} + O(r^{-n-1}). \end{aligned}$$

Putting it all together, we have

$$\begin{aligned} (9) \quad F_g(S_r) &= \left(\frac{1}{2}r^{n-2} \left(1 + \frac{2a}{r^{n-2}}\right) + O(r^{-1})\right) \\ &\quad \times \left(1 - \frac{n-2}{n-1} \cdot \frac{\frac{(n-1)^2}{r^2} - \frac{4a(n-1)^3}{(n-2)r^n} + O(r^{-n-1})}{\frac{(n-1)(n-2)}{r^2} - \frac{4a(n-1)}{r^n} + O(r^{-n-1})}\right) \\ &= \left(\frac{1}{2}r^{n-2} + a + O(r^{-1})\right) \left(1 - \frac{1 - \frac{4a(n-1)}{(n-2)r^{n-2}} + O(r^{-n+1})}{1 - \frac{4a}{(n-2)r^{n-2}} + O(r^{-n+1})}\right) \\ &= \left(\frac{1}{2}r^{n-2} + a + O(r^{-1})\right) \left(\frac{4a}{r^{n-2}} + O(r^{-n+1})\right) \\ &= 2a + O(r^{-1}). \end{aligned}$$

Since the ADM mass of g equals $2a$, the proof is complete. $\square$

The next lemma is a generalization of the previous one:

Lemma 11. *If (M, g) is an asymptotically Schwarzschild manifold, then*

$$m_{\text{ADM}}(M, g) = \lim_{r \rightarrow \infty} F_g(S_r),$$

where S_r is the coordinate sphere $\{|x| = r\}$ in an asymptotically Schwarzschild coordinate system.

Proof. This follows from Lemma 15 in the Appendix and (9). $\square$

5. Proof of Theorem 2

The method of proof of Theorem 2 is similar to the proof of Theorem 1 in [Jauregui 2018].

Let $m_i = m_{\text{ADM}}(M_i, g_i)$, and note that $m_i \geq 0$ by the positive mass theorem in dimension $3 \leq n \leq 7$ ([Schoen and Yau 1979a; 1979b], cf. Section 4 of [Schoen 1989]). If $m_{\text{ADM}}(N, h) = 0$, the claim (1) follows trivially, so we may assume it is strictly positive.

Let $\epsilon > 0$. Fix an asymptotically Schwarzschild coordinate system $(x^1, \dots, x^n)$ on (N, h) , and let S_r denote the coordinate sphere $\{|x| = r\}$, a smooth, compact hypersurface in N for r sufficiently large. Let B_r denote the bounded open region in N that S_r encloses.

By Lemma 11 and the hypothesis that (N, h) is asymptotically Schwarzschild of positive ADM mass, we may choose a number $r_1 > 0$ sufficiently large so that

$$(10) \quad m_{\text{ADM}}(N, h) < F_h(S_{r_1}) + \frac{\epsilon}{2}, \text{ and}$$

$$(11) \quad F_h(S_{r_1}) > 0.$$

By asymptotic flatness of h , we may increase r_1 if necessary, preserving (10) and (11), to arrange that the mean curvature of S_r with respect to h is strictly positive for all $r \geq r_1$, and that hypersurface areas measured with respect to h and the Euclidean metric δ differ by at most a factor of 2 on $N \setminus B_{r_1}$ (i.e., the respective Hausdorff $(n-1)$ -measures are uniformly equivalent by factors of 2).

We apply the definition of pointed C^2 Cheeger–Gromov convergence. First, take a number $r_2 > 0$ so that the metric ball $B_h(q, r_2)$ contains B_{33r_1} . (The value $33r_1$ is chosen because later we will need a point in $B_{33r_1} \setminus B_{r_1}$ that is distance $16r_1$ from both the inner and outer boundary.) Then there exists a domain $U \subset N$, with $U \supset B_h(q, r_2) \supset B_{33r_1}$, and smooth embeddings $\Phi_i : U \rightarrow M_i$, for $i \geq \text{some } i_0$, with $\Phi_i(U) \supset B_{g_i}(p_i, r_2)$, such that

$$(12) \quad h_i := \Phi_i^* g_i \rightarrow h \text{ in } C^2 \text{ on } U.$$

(Below, we will repeatedly use the fact that $\Phi_i : (U, h_i) \rightarrow (\Phi_i(U), g_i)$ is trivially an isometry.) Taking i to be at least some $i_1 \geq i_0$, we can be sure that hypersurface areas measured with respect to h_i and h differ by at most a factor of 2 on U , by C^0 convergence. Taking i to be at least some $i_2 \geq i_1$, we can arrange that the mean curvatures of S_r with respect to h_i are strictly positive for all $r \in [r_1, 33r_1]$, using C^1 convergence of h_i to h on U .

Next, let $S_i = \Phi_i(S_{r_1})$, a smooth compact hypersurface in M_i . We want to apply Theorem 7 to the AF manifold-with-boundary obtained by removing $\Phi_i(B_{r_1})$ from M_i (whose boundary is S_i). To do so, we must verify that S_i is outward-minimizing in (M_i, g_i) . (This is not at all obvious, since S_i need not even lie in the asymptotically flat end of (M_i, g_i) .) This issue was handled in [Jauregui 2018] via a monotonicity formula for minimal surfaces in a Riemannian manifold. However, we will instead use the more robust argument in [Jauregui and Lee 2017], using the notion of almost-minimizing currents.

Lemma 12. *For $i \geq i_2$, S_i is (strictly) outward-minimizing in (M_i, g_i) .*

Proof of Lemma 12. It is well known from standard results in geometric measure theory (see [Huisken and Ilmanen 2001] for instance) that there exists a compact hypersurface $\tilde{S}_i$ enclosing S_i that has the least hypersurface area (with respect to g_i) among all compact hypersurfaces in M_i enclosing S_i . Moreover, $\tilde{S}_i$ has at least $C^{1,1}$ regularity, and $\tilde{S}_i \setminus S_i$, if nonempty, is a smooth minimal hypersurface. (This uses $n \leq 7$.) We complete the proof of the lemma by arguing that $\tilde{S}_i = S_i$, assuming henceforth that $i \geq i_2$.

If $\tilde{S}_i$ were to possess a connected component disjoint from S_i , then that component would be a compact minimal hypersurface in (M_i, g_i) , contrary to the hypothesis of Theorem 2. Thus, every connected component of $\tilde{S}_i$ intersects S_i .

Next, if $\tilde{S}_i$ happens to be contained in the compact region $\Phi_i(\bar{B}_{33r_1})$ and hence in $\Phi_i(\bar{B}_{33r_1} \setminus B_{r_1})$, there exists some point $p \in \tilde{S}_i$ at which the function

$$r \circ \Phi^{-1}|_{\tilde{S}_i}$$

achieves its maximum on $\tilde{S}_i$. Say this maximum value is $r^* \in [r_1, 33r_1]$. If $r^* > r_1$, then $\tilde{S}_i$ is smooth and minimal (with respect to g_i) near p and is tangent to $\Phi_i(S_{r^*})$. However, this contradicts the standard comparison principle for mean curvature, as $\Phi_i(S_{r^*})$ has strictly positive mean curvature with respect to g_i (because S_{r^*} has strictly positive mean curvature with respect to h_i). Thus, $r^* = r_1$, and so $\tilde{S}_i = S_i$, as claimed.

The only remaining case is that $\tilde{S}_i$ possesses a connected component, say $\tilde{S}'_i$, that is not contained in $\Phi_i(\bar{B}_{33r_1} \setminus B_{r_1})$, but that intersects $S_i = \Phi_i(S_{r_1})$. Let

$$T_i = \Phi_i^{-1}(\tilde{S}'_i \cap \Phi_i(B_{33r_1} \setminus \bar{B}_{r_1})) \subset B_{33r_1} \setminus \bar{B}_{r_1} \subset N.$$

Note that T_i is a smooth hypersurface in the AF end of N , so that we may regard $T_i \subset \mathbb{R}^n$ with $\partial T_i \subset S_{r_1} \cup S_{33r_1}$. By the connectedness of $\tilde{S}'_i$ and the continuity of r , there exists some point $q_i \in T_i \cap S_{17r_1}$, and the Euclidean distance from q_i to ∂T_i is $16r_1$. Viewing T_i naturally as an $(n-1)$ -dimensional integral current in $\mathbb{R}^n$, we claim that T_i is γ -almost-minimizing for $\gamma = 16$ (and will verify this later). Recall this means that given any ball B in $\mathbb{R}^n$ that does not intersect ∂T_i , and any integral current T with the same boundary as the restriction $T_i \llcorner B$, we have

$$|T_i \llcorner B|_\delta \leq \gamma |T|_\delta$$

for some constant $\gamma \geq 1$. (Here we are using $|\cdot|_\delta$ to denote both the Euclidean hypersurface area and the more general current mass.) The following fact is a natural generalization of the classical monotonicity formula for minimal surfaces to the class of γ -almost-minimizing currents (see [Bray and Lee 2009] for instance): for $0 \leq s < \text{dist}(q_i, \partial T_i) = 16r_1$,

$$|T_i \llcorner B(q_i, s)|_\delta \geq \gamma^{2-n} \omega_{n-1} s^{n-1}.$$

Taking the limit $s \nearrow 16r_1$, we have

$$|T_i \llcorner B(q_i, 16r_1)|_\delta \geq \gamma^{2-n} \omega_{n-1} (16r_1)^{n-1} = 16\omega_{n-1} (r_1)^{n-1},$$

taking $\gamma = 16$. Using the factor-of-two area comparisons between δ and h and between h and h_i on $U \setminus B_{r_1}$ for $i \geq i_2$, we then have

$$|T_i \llcorner B(q_i, 16r_1)|_{h_i} \geq \frac{1}{4} \cdot 16\omega_{n-1} (r_1)^{n-1}.$$

Applying Φ_i , it follows that $|\tilde{S}'_i \cap \Phi_i(\bar{B}_{33r_1})|_{g_i} \geq 4\omega_{n-1} (r_1)^{n-1}$. Since $\tilde{S}_i$ leaves $\Phi_i(\bar{B}_{33r_1})$, we obtain a strict inequality below:

$$(13) \quad |\tilde{S}_i|_{g_i} \geq |\tilde{S}'_i|_{g_i} > 4\omega_{n-1} (r_1)^{n-1}.$$

On the other hand, since $\tilde{S}_i$ by definition has at most as much g_i -area as S_i ,

$$|\tilde{S}_i|_{g_i} \leq |S_i|_{g_i} = |S_{r_1}|_{h_i} \leq 4|S_{r_1}|_\delta = 4\omega_{n-1} (r_1)^{n-1},$$

producing a contradiction with (13).

We now prove that T_i is γ -almost-minimizing in $\mathbb{R}^n$ with $\gamma = 16$, which will complete the proof of Lemma 12. Since T_i is area-minimizing with respect to h_i in $B_{33r_1} \setminus \bar{B}_{r_1}$, we know that

$$|T_i \llcorner B|_{h_i} \leq |T|_{h_i}$$

for any integral current T supported in $B_{33r_1} \setminus \bar{B}_{r_1}$, with $\partial T = \partial(T_i \llcorner B)$, where B is a Euclidean ball in $B_{33r_1} \setminus \bar{B}_{r_1}$. For $i \geq i_2$, since the Hausdorff $(n-1)$ -measures of h and h_i are uniformly equivalent by factors of two on U , this implies

$$|T_i \llcorner B|_h \leq 4|T|_h$$

for such B and T . Since T_i is contained outside S_{r_1} , we can use the comparison of areas between δ and h to see that

$$|T_i \llcorner B|_\delta \leq 16|T|_\delta$$

for such B and T . However, in the definition of γ -almost-minimizing, one may without loss of generality consider competitors T supported in $\bar{B}$, since $\bar{B}$ is convex. It follows that T_i is 16-almost-minimizing, and the proof of Lemma 12 is complete. $\square$

We continue with the proof of Theorem 2. Observe that $F_g(S)$ varies continuously with respect to C^2 perturbations of g on any neighborhood of S , since the area, mean curvature, and scalar curvature depend continuously on g and its first and second derivatives. Then by the C^2 convergence in (12), we may restrict to i at least as large as some $i_3 \geq i_2$ so that

$$(14) \quad F_h(S_{r_1}) \leq F_{h_i}(S_{r_1}) + \frac{\epsilon}{2}$$

and that

$$(15) \quad F_{h_i}(S_{r_1}) > 0$$

(since $F_h(S_{r_1}) > 0$ by (11)). Lemma 12 and (15) show that Theorem 7 may be applied to M_i minus the open region $\Phi_i(B_{r_1})$, which has (connected) boundary S_i . Thus:

$$(16) \quad F_{h_i}(S_{r_1}) = F_{g_i}(S_i) \leq m_i.$$

Then for all $i \geq i_3$, we may combine (10), (14), and (16) to arrive at

$$m_{\text{ADM}}(N, h) < m_i + \epsilon.$$

Now, taking $\liminf_{i \rightarrow \infty}$ proves Theorem 2, since $\epsilon > 0$ was arbitrary.

Remark C. The above proof generalizes the C^2 lower semicontinuity result from $n = 3$ in [Jauregui 2018] to $3 \leq n \leq 7$. By contrast, extending the C^0 lower semicontinuity result in [Jauregui and Lee 2017] to higher dimensions would be much more difficult. In the C^0 case, the dimension three hypothesis is relied on to a greater extent. First, the Hawking mass estimate (2) of Huisken and Ilmanen, valid only in dimension three, is used to ensure monotonicity under mean curvature flow of a certain quantity (whose details we omit here) defined by Huisken. The author is not aware of such a monotone quantity in higher dimensions. Second, in [Jauregui and Lee 2017], use is made of B. White's regularity theory for the weak (level set) version of mean curvature flow that is especially nice in ambient dimension three [2000].

Remark D. As mentioned in the introduction, we strongly conjecture that the hypothesis that the limit (N, h) is asymptotically Schwarzschild in Theorem 2 (as opposed to asymptotically flat) is unnecessary. We note this generalization would follow by establishing a density result of the following form: Given $\epsilon > 0$ and a sequence (M_i, g_i, p_i) of AF manifolds of nonnegative scalar curvature converging in the pointed C^2 Cheeger–Gromov sense to an AF manifold (N, h, q) , construct an HF perturbation $\bar{h}$ of h (with $|m_{\text{ADM}}(N, \bar{h}) - m_{\text{ADM}}(N, h)| < \epsilon$) and AF metrics $\bar{g}_i$ on M_i of nonnegative scalar curvature, with $|m_{\text{ADM}}(M_i, \bar{g}_i) - m_{\text{ADM}}(M_i, g_i)| < \epsilon$, such that $(M_i, \bar{g}_i, p_i) \rightarrow (N, \bar{h}, q)$ in the pointed C^2 Cheeger–Gromov sense. Such a result would immediately generalize Theorem 2 to remove the restriction that (N, h) is asymptotically Schwarzschild, since HF manifolds are such.

6. Lower semicontinuity for weighted C^2 convergence in all dimensions

In this section we study the behavior of the ADM mass under *weighted* C^2 convergence. This corresponds to a finer topology than that of pointed C^2 Cheeger–Gromov

convergence. In particular it is easier here to establish semicontinuity of the ADM mass and to obtain a stronger result: Theorem 13 is valid in all dimensions $n \geq 3$, requires no hypothesis on minimal surfaces, and does not rely on (nor recover) the positive mass theorem.

To describe the setup, let M be a smooth n -manifold that admits an AF metric. Fix a compact set $K \subset M$ and an AF coordinate system on $M \setminus K$ (for some AF metric). For an integer $k \geq 0$ and a real number $\tau > 0$, let $C_{-\tau}^k(M \setminus K)$ denote the class of C^k functions $f : M \setminus K \rightarrow \mathbb{R}$ for which the quantity

$$\|f\|_{C_{-\tau}^k(M \setminus K)} = \sum_{0 \leq |\gamma| \leq k} \sup_{x \in M \setminus K} |x|^{|\gamma|+\tau} |\partial^\gamma f(x)|$$

is finite, where the partial derivatives are taken with respect to the coordinate chart, and γ represents multi-indices. Thus, functions in $C_{-\tau}^k(M \setminus K)$ decay as $O(r^{-\tau})$ or faster as $r \rightarrow \infty$, with successively faster decay up through k -th-order derivatives. Define $C_{-\tau}^k(M)$ to be the set of C^k functions $f : M \rightarrow \mathbb{R}$ with $f|_{M \setminus K} \in C^k(M \setminus K)$, equipped with the norm given as the sum of $\|f\|_{C_{-\tau}^k(M \setminus K)}$ and the C^k norm of $f|_K$.

Note that if g is an AF metric on g of order τ obeying the decay conditions (3) in the fixed coordinate chart, then

$$(17) \quad g_{ij} - \delta_{ij} \in C_{-\tau}^2(M \setminus K).$$

For $k \geq 2$ and $\tau > 0$, we let $\text{Met}_{-\tau}^k(M)$ denote the set of C^k Riemannian metrics g on M satisfying (17) in the fixed coordinate chart. (The ADM mass of $g \in \text{Met}_{-\tau}^k(M)$ is well defined if $\tau > \frac{n-2}{2}$ and the scalar curvature of g is integrable [Bartnik 1986; Chruściel 1986].) We say a sequence of Riemannian metrics $\{g^\ell\}_{\ell=1}^\infty$ in $\text{Met}_{-\tau}^k(M)$ converges to $g \in \text{Met}_{-\tau}^k(M)$ as $\ell \rightarrow \infty$ if $\|g_{ij}^\ell - g_{ij}\|_{C_{-\tau}^k(M \setminus K)} \rightarrow 0$ for all i and j and the tensors $g^\ell|_K$ converge in C^k to $g|_K$ as $\ell \rightarrow \infty$.

Theorem 13. *Suppose $\{g^\ell\}_{\ell=1}^\infty$ converges to g as asymptotically flat Riemannian metrics in $\text{Met}_{-\tau}^2(M)$, where $\tau > \frac{n-2}{2}$. Then*

$$(18) \quad \lim_{\ell \rightarrow \infty} \left(m_{\text{ADM}}(M, g^\ell) - \frac{1}{2(n-1)\omega_{n-1}} \int_M R(g^\ell) dV_{g^\ell} \right) \\ = m_{\text{ADM}}(M, g) - \frac{1}{2(n-1)\omega_{n-1}} \int_M R(g) dV_g,$$

where dV_{g^ℓ} and dV_g are the volume measures of g^ℓ and g . Moreover, if there exists a compact set $K \subset M$ such that $R(g^\ell) \geq 0$ on $M \setminus K$ for all ℓ , then

$$(19) \quad \liminf_{\ell \rightarrow \infty} m_{\text{ADM}}(M, g_\ell) \geq m_{\text{ADM}}(M, g).$$

Remark E. Our (18) is well known to experts as the statement of the continuity of the Regge–Teitelboim Hamiltonian [1974]. This is related to Lemma 9.4 in [Lee and

Parker 1987], which gives continuity of the ADM under weighted $C^{1,\alpha}$ convergence if the scalar curvatures converge in L^1 . After posting this paper we became aware of Theorem 14 of [McFeron and Székelyhidi 2012], which implies Theorem 13; this result of D. McFeron and G. Székelyhidi requires local C^2 convergence and a uniform weighted $C^{1,\alpha}$ bound. Our proof below is a generalization of that of Y. Li [2018] (see the proof of Theorem 1.2 therein), who studied the behavior of the ADM mass and integral of scalar curvature in the case of a convergent Ricci flow.

Proof. Let g_0 be a background Riemannian metric on M whose expression in $M \setminus K$ in the given AF coordinate chart is δ_{ij} . Let div_0 be the divergence operator on tensors and Δ_0 the Laplacian on functions with respect to g_0 . Define the continuous operator $\mathcal{D} : \text{Met}_{-\tau}^2(M) \rightarrow C_{-\tau-2}^0(M)$ by

$$\mathcal{D}(g) = \text{div}_0(\text{div}_0 g) - \Delta_0(\text{tr}_{g_0}(g)).$$

The significance of $\mathcal{D}$ is the formula for the ADM mass of $g \in \text{Met}_{-\tau}^2(M)$ (provided $\tau > \frac{n-2}{2}$ and the scalar curvature of g is integrable):

$$(20) \quad m_{\text{ADM}}(g) = \frac{1}{2(n-1)\omega_{n-1}} \int_M \mathcal{D}(g) dV_0,$$

which follows immediately from the divergence theorem. Here, dV_0 is the volume measure of g_0 .

By the $\text{Met}_{-\tau}^2(M)$ convergence of g^ℓ to g , we have $\mathcal{D}(g^\ell) \rightarrow \mathcal{D}(g)$ in $C_{-\tau-2}^0(M)$. However, since $\tau + 2$ is generally less than the $O(r^{-n})$ threshold for integrability, we cannot immediately apply the dominated convergence theorem. (And since we have no control on the sign of $\mathcal{D}(g^\ell)$, we cannot apply Fatou's lemma.)

We proceed instead by considering the difference between $\mathcal{D}(\cdot)$ and $R(\cdot)$ (a well-known trick), where $R : \text{Met}_{-\tau}^2(M) \rightarrow C_{-\tau-2}^0(M)$ is the scalar curvature operator. Working in the fixed chart on $M \setminus K$, for any Riemannian metric $h \in \text{Met}_{-\tau}^2(M)$ with Christoffel symbols Γ_{ij}^k , we have

$$\begin{aligned} \mathcal{D}(h) &= \partial_i \partial_j h_{ij} - \partial_j \partial_j h_{ii}, \\ \mathcal{R}(h) &= h^{jk} (\partial_i \Gamma_{jk}^i - \partial_k \Gamma_{ij}^i + \Gamma_{jk}^m \Gamma_{im}^i - \Gamma_{ij}^m \Gamma_{km}^i). \end{aligned}$$

By direct computation, $\mathcal{D}(g^\ell) - R(g^\ell)$ is $O(r^{-2-2\tau})$, where $O(r^{-2-2\tau})$ here is uniform in ℓ and moreover goes to zero in $C_{-2-2\tau}^0(M)$ as $\ell \rightarrow \infty$. Since $2+2\tau > n$, this $O(r^{-2-2\tau})$ error term is uniformly bounded by an integrable function on M . Then by the dominated convergence theorem and the pointwise convergence of $\mathcal{D}(g^\ell) - R(g^\ell)$ to $\mathcal{D}(g) - R(g)$,

$$\lim_{\ell \rightarrow \infty} \int_M (\mathcal{D}(g^\ell) - R(g^\ell)) dV_{g^\ell} = \int_M (\mathcal{D}(g) - R(g)) dV.$$

Together with (20), this proves (18).

For the last claim, assume $R(g^\ell) \geq 0$ for all ℓ on $M \setminus K$, and let

$$\mu = \liminf_{\ell \rightarrow \infty} m_{\text{ADM}}(M, g_\ell).$$

If $\mu = +\infty$, the claim follows trivially. Suppose μ is finite. Pass to a subsequence $\{(M, g^{\ell(k)})\}_k$ for which

$$\lim_{k \rightarrow \infty} m_{\text{ADM}}(M, g^{\ell(k)}) = \mu.$$

By the first part of the theorem, the sequence

$$\int_M R(g^{\ell(k)}) dV_{g^{\ell(k)}}$$

then converges, and moreover

$$(21) \quad \mu = m_{\text{ADM}}(M, g) + \frac{1}{2(n-1)\omega_{n-1}} \left(\lim_{k \rightarrow \infty} \int_M R(g^{\ell(k)}) dV_{g^{\ell(k)}} - \int_M R(g) dV_g \right).$$

By the (weighted) C^2 convergence of $g^{\ell(k)}$ to g as $k \rightarrow \infty$, we have pointwise convergence of the scalar curvatures and volume forms. In particular,

$$\int_K R(g^{\ell(k)}) dV_{g^{\ell(k)}} \rightarrow \int_K R(g) dV_g$$

as $k \rightarrow \infty$. Then, by Fatou's lemma and the hypothesis $R(g^{\ell(k)}) \geq 0$ on $M \setminus K$, the expression in parentheses in (21) is nonnegative. This completes the proof if μ is finite.

Finally, suppose $\mu = -\infty$. Then by (18), a subsequence $\{(M, g^{\ell(k)})\}_k$ has its integral of scalar curvature converging to $-\infty$. Since the scalar curvatures are nonnegative outside the compact set K , the integrals of the scalar curvatures on K also converge to $-\infty$. This contradicts the fact that these integrals converge to $\int_K R(g) dV_g$. $\square$

Remark F. Interestingly, Theorem 13 implies that for the case of weighted C^2 convergence, the mass drop is accounted for completely by the total matter (i.e., the integral of scalar curvature) escaping off to infinity, much like in the example in Section 2.1 from Newtonian gravity. This contrasts with the case of pointed C^2 Cheeger–Gromov convergence, in which the ADM mass can drop within the class of scalar-flat metrics (e.g., the examples in Sections 2.2 or 2.3, choosing (M, g) to be scalar-flat with positive ADM mass).

Remark G. Note that the lower semicontinuity of the ADM mass with respect to weighted C^2 convergence does not imply the positive mass theorem as in the blow-up example or escaping point example with pointed convergence in Section 2. In those cases, the metrics do not converge to Euclidean space in a weighted sense.

6.1. Example: mass drop with weighted convergence. We conclude this section by describing an example of AF metrics g_i , with nonnegative scalar curvature, converging in $\text{Met}_{-\tau}^2(M)$ with $\tau > \frac{n-2}{2}$ for which the ADM mass drops. Physically, the construction involves considering a sequence of shells of matter, of fixed total mass, at progressively larger radii. For $n \geq 3$, let $\rho : \mathbb{R}^n \rightarrow \mathbb{R}$ be a smooth, radially symmetric, nonnegative function supported in the annulus between radii $\frac{1}{2}$ and 1, with $\int_{\mathbb{R}^n} \rho = 1$. For $i = 1, 2, \dots$, define a sequence of smooth functions

$$\rho_i(x) = i^{-n} \rho(x/i),$$

which also satisfy $\int_{\mathbb{R}^n} \rho_i = 1$ and are supported in the annulus between radii $\frac{i}{2}$ and i .

By elliptic PDE theory (or ODE theory), there exists a unique smooth solution (for each i) to the linear elliptic problem:

$$\begin{cases} -\Delta v_i = \rho_i & \text{on } \mathbb{R}^n \\ v_i \rightarrow 0 & \text{at infinity.} \end{cases}$$

Recognizing $v_i(x) = i^{2-n} v_1(x/i)$, it is easy to see that $v_i \rightarrow 0$ in $C_{-\tau}^2(M)$ for any $\tau < n-2$ as $i \rightarrow \infty$. Fix $\tau \in (\frac{n-2}{2}, n-2)$.

For i sufficiently large, $u_i := 1 + v_i$ is positive, and the Riemannian metric $g_i := u_i^{4/(n-2)} \delta$ is asymptotically flat. Note that the scalar curvature of g_i

$$R_i = -\frac{4(n-1)}{n-2} u_i^{-\frac{n+2}{n-2}} \Delta u_i = \frac{4(n-1)}{n-2} u_i^{-\frac{n+2}{n-2}} \rho_i,$$

is integrable because it has compact support.

Now, g_i converges to the Euclidean metric in $\text{Met}_{-\tau}^2(M)$ as $i \rightarrow \infty$, and each g_i has nonnegative scalar curvature. We show now (using the divergence theorem) that the ADM mass of g_i is a positive constant, independent of i :

$$\begin{aligned} m_{\text{ADM}}(g_i) &= -\frac{2}{(n-2)\omega_{n-1}} \lim_{r \rightarrow \infty} \int_{S_r} v(u_i) dA = -\frac{2}{(n-2)\omega_{n-1}} \int_{\mathbb{R}^n} \Delta u_i dV \\ &= \frac{2}{(n-2)\omega_{n-1}} \int_{\mathbb{R}^n} \rho_i dV = \frac{2}{(n-2)\omega_{n-1}}, \end{aligned}$$

where dA and dV are the hypersurface area and the volume forms with respect to the Euclidean metric. However, the ADM mass of the limit, Euclidean $\mathbb{R}^n$, vanishes.

7. Two-dimensional case of semicontinuity of mass

In two dimensions, a natural replacement for asymptotically flat manifolds is the class of asymptotically conical surfaces, with the asymptotic cone angle playing the role of mass. The author thanks Woolgar for his suggestion to investigate the semicontinuity of mass in this setting.

Following [Isenberg et al. 2013], for $\alpha > 0$, let

$$g_\alpha = dr^2 + \alpha^2 r^2 d\theta^2,$$

a smooth Riemannian metric on $\mathbb{R}^2 \setminus \{0\}$ describing a cone. Note that g_α has vanishing Gauss curvature. Define a connected two-dimensional Riemannian manifold (M, g) to be *asymptotically conical with cone angle $2\pi\alpha > 0$* if there exists a compact set $C \subset M$ such that $M \setminus C$ is diffeomorphic to the complement of a closed ball in $\mathbb{R}^2$, on which $g - g_\alpha = O_2(r^{-\tau})$ for some constant $\tau > 0$. In particular, the Gauss curvature of g is $O(r^{-2-\tau})$ and hence integrable.

We recall here that the integral of the Gauss curvature captures the cone angle. To see this, let B_r be the compact region bounded by the coordinate circle Γ_r in (M, g) for r large. By the Gauss–Bonnet formula,

$$(22) \quad \int_{B_r} K \, dA = 2\pi \chi(B_r) - \int_{\Gamma_r} \kappa_g \, ds,$$

where κ_g is the geodesic curvature of Γ_r with respect to g . By the $O_2(r^{-\tau})$ decay of g to g_α , we have

$$\lim_{r \rightarrow \infty} \int_{\Gamma_r} \kappa_g \, ds = \lim_{r \rightarrow \infty} \int_{\Gamma_r} \kappa_{g_\alpha} \, ds = 2\pi\alpha,$$

the latter equality given by direct calculation, where κ_{g_α} is the geodesic curvature of Γ_r with respect to g_α . Taking the limit $r \rightarrow \infty$ in (22) (and noting that $\chi(B_r)$ is eventually a constant, $\chi(M)$), we have

$$(23) \quad \int_M K \, dA = 2\pi(\chi(M) - 1) + 2\pi(1 - \alpha).$$

Note that if $K \geq 0$, it follows that $\chi(M) > 0$, and using the fact that M is topologically the connect sum of $\mathbb{R}^2$ and a compact, connected surface, it follows that $\chi(M) = 1$ and that M itself is topologically $\mathbb{R}^2$.

We define the mass of an asymptotically conical surface to be

$$m_{\text{cone}}(M, g) = 1 - \alpha,$$

which we note is a dimensionless quantity. The positive mass theorem is then immediate: $K \geq 0$ implies $m_{\text{cone}} \geq 0$, and equality holds if and only if $K \equiv 0$ and M is homeomorphic to $\mathbb{R}^2$, which holds if and only if (M, g) is isometric to the Euclidean plane.

Below is the statement of C^2 pointed lower semicontinuity of the mass in two dimensions (i.e., upper semicontinuity of the cone angle). Note that no hypothesis on closed geodesics (the analogs of compact minimal hypersurfaces) is necessary.

Theorem 14. *Suppose (M_i, g_i, p_i) converges in the pointed C^2 Cheeger–Gromov sense to (N, h, q) as pointed asymptotically conical Riemannian 2-manifolds. Suppose each (M_i, g_i) has nonnegative Gauss curvature. Then*

$$(24) \quad m_{\text{cone}}(N, h) \leq \liminf_{i \rightarrow \infty} m_{\text{cone}}(M_i, g_i).$$

An example for which strict inequality holds in (24) can be found using the blow-up or escaping point examples in Sections 2.2 and 2.3, beginning with an asymptotically conical surface with nonnegative Gauss curvature and $\alpha < 1$.

Proof. Let $\epsilon > 0$. By the C^2 convergence, h itself has nonnegative Gauss curvature K_h , so in particular $\chi(N) = 1$. Then by (23),

$$m_{\text{cone}}(N, h) = \frac{1}{2\pi} \int_N K_h dA_h.$$

Since K_h is integrable, we may choose $r > 0$ sufficiently large so that the coordinate ball $B_r \subset N$ satisfies

$$m_{\text{cone}}(N, h) < \frac{1}{2\pi} \int_{B_r} K_h dA_h + \frac{\epsilon}{2}.$$

Choosing $U \supset B_r$ and obtaining appropriate embeddings $\Phi_i : U \rightarrow M_i$ such that $h_i := \Phi_i^* g_i$ converges in C^2 to h , we may take i sufficiently large so that

$$(25) \quad \frac{1}{2\pi} \int_{B_r} K_h dA_h - \frac{\epsilon}{2} < \frac{1}{2\pi} \int_{B_r} K_{h_i} dA_{h_i} = \frac{1}{2\pi} \int_{\Phi_i(B_r)} K_{g_i} dA_{g_i}.$$

Since (M_i, g_i) has nonnegative Gauss curvature, the right-hand side in (25) is an underestimate for $m_{\text{cone}}(M_i, g_i)$. Thus,

$$m_{\text{cone}}(N, h) < m_{\text{cone}}(M_i, g_i) + \epsilon$$

for i sufficiently large. From this, the result follows. □

We leave it as an open problem to study the behavior of the cone angle under weaker forms of convergence, such as pointed C^0 Cheeger–Gromov, pointed Gromov–Hausdorff, or pointed Sormani–Wenger intrinsic flat convergence [Sormani and Wenger 2011].

Appendix: Geometry of asymptotically Schwarzschild metrics

The purpose of this appendix is to prove the following asymptotic estimates for large coordinate spheres in an asymptotically Schwarzschild manifold. These were used in the proof of Lemma 11.

Lemma 15. *Let $(M, \tilde{g})$ be an asymptotically Schwarzschild manifold of dimension $n \geq 3$ and ADM mass m . Let S_r be the coordinate sphere of large radius r in M . Let*

$\tilde{\rho}$ be the scalar curvature of S_r with respect to the metric induced from $\tilde{g}$, and let $\tilde{H}$ be the mean curvature of S_r with respect to $\tilde{g}$. Then:

$$(26) \quad \tilde{\rho} = \frac{(n-1)(n-2)}{r^2} - \frac{2(n-1)m}{r^n} + O(r^{-n-1}).$$

$$(27) \quad \tilde{H} = \frac{n-1}{r} - \frac{(n-1)^2 m}{(n-2)r^{n-1}} + O(r^{-n}).$$

Proof. Let g be the Schwarzschild metric of mass m , and let h be as in (5), i.e.,

$$g = \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{4}{n-2}} \delta, \quad \tilde{g} = g + h,$$

in the end of M .

We first address the scalar curvature of S_r . Let γ and $\tilde{\gamma}$ be the Riemannian metrics on S_r induced by g and $\tilde{g}$, respectively. The coordinate sphere S_r has constant scalar curvature with respect to the metric induced by δ equal to $(n-1)(n-2)/(r^2)$. Since the conformal factor relating g to δ is constant on S_r , the scalar curvature of (S_r, γ) can be found by rescaling:

$$(28) \quad \rho = \left(1 + \frac{m}{2r^{n-2}}\right)^{-\frac{4}{n-2}} \cdot \frac{(n-1)(n-2)}{r^2} = \frac{(n-1)(n-2)}{r^2} - \frac{2(n-1)m}{r^n} + O(r^{-2(n-1)}).$$

We proceed to estimate the scalar curvature of $(S_r, \tilde{\gamma})$ as follows. Introduce spherical coordinates $(r, \phi^1, \dots, \phi^{n-1})$ on the asymptotically flat end of M :

$$\begin{aligned} x^1 &= r \cos(\phi^1), \\ x^2 &= r \sin(\phi^1) \cos(\phi^2), \\ &\vdots \\ x^{n-1} &= r \sin(\phi^1) \sin(\phi^2) \cdots \cos(\phi^{n-1}), \\ x^n &= r \sin(\phi^1) \sin(\phi^2) \cdots \sin(\phi^{n-1}). \end{aligned}$$

We use Greek indices for the directions tangent to S_r , i.e., ϕ^α for $\alpha = 1, \dots, n-1$ for the coordinates on S_r and $\partial_\alpha = \frac{\partial}{\partial \phi^\alpha}$ for their derivatives. Note that $\delta(\partial_\alpha, \partial_\beta)$ is $O(r^2)$.

First, express γ and $\tilde{\gamma}$ in spherical coordinates on S_r :

$$(29) \quad \gamma_{\alpha\beta} = g(\partial_\alpha, \partial_\beta), \quad \tilde{\gamma}_{\alpha\beta} = \tilde{g}(\partial_\alpha, \partial_\beta) = \gamma_{\alpha\beta} + h_{\alpha\beta},$$

where $h_{\alpha\beta} = h(\partial_\alpha, \partial_\beta)$ is $O(r^{3-n})$ by (5). Both $\gamma_{\alpha\beta}$ and $\tilde{\gamma}_{\alpha\beta}$ are $O(r^2)$. Also, we have the inverse metrics

$$(30) \quad \gamma^{\alpha\beta} = O(r^{-2}),$$

$$(31) \quad \tilde{\gamma}^{\alpha\beta} = \gamma^{\alpha\beta} + O(r^{-n-1}).$$

Note that the derivatives tangent to S_r satisfy

$$(32) \quad \begin{aligned} \partial_\mu \gamma_{\alpha\beta} &= O(r^2), \\ \partial_\mu h_{\alpha\beta} &= O(r^{3-n}), \end{aligned}$$

$$(33) \quad \partial_\mu \tilde{\gamma}_{\alpha\beta} = O(r^2),$$

with the same orders for second derivatives. Similarly,

$$(34) \quad \partial_\mu \gamma^{\alpha\beta} = O(r^{-2}),$$

$$(35) \quad \partial_\mu \tilde{\gamma}^{\alpha\beta} = O(r^{-2}).$$

Next, let Γ and $\tilde{\Gamma}$ denote the Christoffel symbols of (S_r, γ) and $(S_r, \tilde{\gamma})$, respectively, and define

$$\Psi_{\alpha\beta}^\mu = \tilde{\Gamma}_{\alpha\beta}^\mu - \Gamma_{\alpha\beta}^\mu.$$

By (30) and (32), we have

$$(36) \quad \Gamma_{\alpha\beta}^\mu = O(1).$$

Using (34) as well,

$$(37) \quad \partial_\nu \Gamma_{\alpha\beta}^\mu = O(1).$$

Next, we need decay on Ψ and $\partial\Psi$. Using (29)–(31),

$$\begin{aligned} \Psi_{\alpha\beta}^\mu &= \tilde{\gamma}^{\mu\nu} (\partial_\beta \tilde{\gamma}_{\alpha\nu} + \partial_\alpha \tilde{\gamma}_{\beta\nu} - \partial_\nu \tilde{\gamma}_{\alpha\beta}) - \gamma^{\mu\nu} (\partial_\beta \gamma_{\alpha\nu} + \partial_\alpha \gamma_{\beta\nu} - \partial_\nu \gamma_{\alpha\beta}) \\ &= O(r^{-2}) (\partial_\beta h_{\alpha\nu} + \partial_\alpha h_{\beta\nu} - \partial_\nu h_{\alpha\beta}) + O(r^{-n-1}) (\partial_\beta \tilde{\gamma}_{\alpha\nu} + \partial_\alpha \tilde{\gamma}_{\beta\nu} - \partial_\nu \tilde{\gamma}_{\alpha\beta}). \end{aligned}$$

Since $h_{\alpha\beta}$ and $\partial_\mu h_{\alpha\beta}$ are $O(r^{3-n})$, and also by (33), we have

$$\Psi_{\alpha\beta}^\mu = O(r^{1-n}),$$

and a similar calculation, using (35), shows

$$\partial_\nu \Psi_{\alpha\beta}^\mu = O(r^{1-n}).$$

Finally:

$$\begin{aligned} \tilde{\rho} &= \tilde{\gamma}^{\beta\mu} (\partial_\alpha \tilde{\Gamma}_{\beta\mu}^\alpha - \partial_\mu \tilde{\Gamma}_{\alpha\beta}^\alpha + \tilde{\Gamma}_{\beta\mu}^\nu \tilde{\Gamma}_{\alpha\nu}^\alpha - \tilde{\Gamma}_{\alpha\beta}^\nu \tilde{\Gamma}_{\mu\nu}^\alpha) \\ &= (\gamma^{\beta\mu} + O(r^{-n-1})) \\ &\quad \times [\partial_\alpha (\Gamma_{\beta\mu}^\alpha + \Psi_{\beta\mu}^\alpha) - \partial_\mu (\Gamma_{\alpha\beta}^\alpha + \Psi_{\alpha\beta}^\alpha) \\ &\quad + (\Gamma_{\beta\mu}^\nu + \Psi_{\beta\mu}^\nu) (\Gamma_{\alpha\nu}^\alpha + \Psi_{\alpha\nu}^\alpha) - (\Gamma_{\alpha\beta}^\nu + \Psi_{\alpha\beta}^\nu) (\Gamma_{\mu\nu}^\alpha + \Psi_{\mu\nu}^\alpha)] \\ &= \rho + O(r^{-n-1}), \end{aligned}$$

having used (30), (31), (36), and (37). Combining this with (28), (26) follows.

For the second part of the proof, we must compute the mean curvature of large coordinate spheres S_r with respect to $\tilde{g}$. We approach this through the first variation of area. Let ω_0 , ω , and $\tilde{\omega}$ be the area forms of S_r induced by δ , g and $\tilde{g}$, respectively. The respective mean curvature vectors $\mathbf{H}_0$, $\mathbf{H}$, $\tilde{\mathbf{H}}$ of S_r with respect to these metrics are characterized by the first variation of area formulas as follows:

$$(38) \quad D_X \omega_0 = \delta(X, -\mathbf{H}_0) \omega_0 = \delta\left(X, \frac{n-1}{r} \cdot \partial_r\right) \omega_0,$$

$$(39) \quad D_X \omega = g(X, -\mathbf{H}) \omega,$$

$$(40) \quad D_X \tilde{\omega} = \tilde{g}(X, -\tilde{\mathbf{H}}) \tilde{\omega},$$

where D_X denotes an infinitesimal deformation of S_r in the direction of X , where X is a tangent vector field to M along S_r .

We again use spherical coordinates as in the first part of the proof. Note that (ϕ^α) give coordinates on S_r that are orthogonal with respect to δ , and hence with respect to the conformal metric g . In addition to the estimates of $\gamma_{\alpha\beta}$, $h_{\alpha\beta}$ and their tangential derivatives used in the first part of the proof, we also need estimates on the radial derivatives. By the decay of g and h , as well as by (30), we obtain

$$\partial_r \gamma_{\alpha\beta} = O(r^{-1}), \quad \partial_r \gamma^{\alpha\beta} = O(r^{-3}), \quad \partial_r h_{\alpha\beta} = O(r^{2-n}).$$

We begin by computing the mean curvature H of S_r with respect to g ; this is well known, but we include it for completeness. The area forms ω_0 and ω on S_r are related by

$$\omega = \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{2(n-1)}{n-2}} \omega_0.$$

Then, using (38), elementary calculations show

$$(41) \quad \begin{aligned} D_r \omega &= \frac{2(n-1)}{n-2} \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{2(n-1)}{n-2}-1} \cdot \left(\frac{(2-n)m}{2r^{n-1}}\right) \omega_0 + \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{2(n-1)}{n-2}} D_r \omega_0 \\ &= \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{2(n-1)}{n-2}} \cdot \left[\frac{n-1}{r} - \frac{m(n-1)}{r^{n-1}} \left(1 + \frac{m}{2r^{n-2}}\right)^{-1}\right] \omega_0, \end{aligned}$$

where $D_r = D_{\partial_r}$. Now, using (39), we have

$$(42) \quad \begin{aligned} D_r \omega &= g(\partial_r, -\mathbf{H}) \omega \\ &= \left(1 + \frac{m}{2r^{n-2}}\right)^{\frac{2n}{n-2}} H \omega_0, \end{aligned}$$

where $H = |\mathbf{H}|_g$. Now, combining (41) and (42), elementary calculations show

$$(43) \quad H = \frac{n-1}{r} - \frac{(n-1)^2 m}{(n-2)r^{n-1}} + O(r^{-n}).$$

Now, we proceed to estimate the mean curvature with respect to $\tilde{g}$. Define a function $\Phi > 0$ on the asymptotically flat end of M so that

$$(44) \quad \tilde{\omega} = \sqrt{\Phi} \omega \quad \text{on } S_r,$$

that is,

$$\Phi = \frac{\det(\tilde{\gamma}_{\alpha\beta})}{\det(\gamma_{\alpha\beta})}.$$

Using Jacobi's formula for the derivative of the determinant, along with the known decay of $\gamma_{\alpha\beta}$, and $\tilde{\gamma}_{\alpha\beta}$ and their derivatives, we have the following asymptotics of Φ :

$$(45) \quad \Phi = 1 + O(r^{1-n}),$$

$$(46) \quad \partial_\mu \Phi = O(r^{1-n}),$$

$$(47) \quad \partial_r \Phi = O(r^{-n}).$$

In order to compute $\tilde{H}$, we compute tangential and radial variations of $\tilde{\omega}$ beginning with (44):

$$(48) \quad \begin{aligned} D_\mu \tilde{\omega} &= \frac{1}{2}(\partial_\mu \Phi) \Phi^{-1/2} \omega + \sqrt{\Phi} D_\mu \omega \\ &= \frac{1}{2}(\partial_\mu \Phi) \Phi^{-1/2} \omega + \sqrt{\Phi} g(\partial_\mu, -\mathbf{H}) \omega \\ &= O(r^{1-n}) \omega, \end{aligned}$$

where we have used the fact that $\mathbf{H}$ is g -orthogonal to S_r , as well as (39) and (45)–(46). Next, for the radial directions:

$$(49) \quad \begin{aligned} D_r \tilde{\omega} &= \frac{1}{2}(\partial_r \Phi) \Phi^{-1/2} \omega + \sqrt{\Phi} g(\partial_r, -\mathbf{H}) \omega \\ &= g(\partial_r, -\mathbf{H}) \omega + O(r^{-n}) \omega, \end{aligned}$$

having used (45), (47), and $H = O(r^{-1})$. The goal is to combine the last two statements with (40). Specifically, we estimate (40) as follows:

$$\begin{aligned} D_X \tilde{\omega} &= (g + h)(X, -\tilde{\mathbf{H}}) \sqrt{\Phi} \omega \\ &= g(X, -\tilde{\mathbf{H}}) \omega + O(r^{-n}) |X|_g \omega, \end{aligned}$$

having used the decay of h , (45), and $|\tilde{\mathbf{H}}|_g = O(r^{-1})$. Define $\mathbf{Y} = \tilde{\mathbf{H}} - \mathbf{H}$. Then applying (49) and the last equation (with $X = \partial_r$) and applying (48) and the last equation (with $X = \partial_\mu$) produces

$$(50) \quad g(\partial_r, \mathbf{Y}) = O(r^{-n}),$$

$$(51) \quad g(\partial_\mu, \mathbf{Y}) = O(r^{1-n}).$$

By expanding $|Y|_g^2$ in the g -orthogonal basis $(\partial_r, \partial_\mu)$ of TM along S_r , and using (50)–(51), we obtain

$$(52) \quad |Y|_g^2 = O(r^{-2n}).$$

Finally, letting $\tilde{H} = |\tilde{H}|_{\tilde{g}}$, we use the triangle inequality to show

$$\begin{aligned} |\tilde{H} - H| &\leq ||\tilde{H}|_{\tilde{g}} - |H|_{\tilde{g}}| + ||H|_{\tilde{g}} - |H|_g| \\ &\leq |Y|_{\tilde{g}} + ||H|_{\tilde{g}} - |H|_g| \\ &= (g(Y, Y) + h(Y, Y))^{\frac{1}{2}} + |(g(H, H) + h(H, H))^{\frac{1}{2}} - g(H, H)^{\frac{1}{2}}| \\ &= |Y|_g + |Y|_g O(r^{1-n}) + H \cdot O(r^{1-n}) \\ &= O(r^{-n}), \end{aligned}$$

by (52). Combining this with (43), (27) follows. $\square$

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