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WITH SUB-RIEMANNIAN METRICS**

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# COLLAPSED LIMITS OF COMPACT HEISENBERG MANIFOLDS WITH SUB-RIEMANNIAN METRICS

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**We show that every collapsed Gromov–Hausdorff limit of compact Heisenberg manifolds endowed with left-invariant Riemannian/sub-Riemannian metrics is isometric to a flat torus. We say that a sequence of sub-Riemannian manifolds collapses if their total measure with respect to Popp’s volume converges to zero.**

## 1. Introduction

A sub-Riemannian manifold is a triple  $(M, \mathcal{D}, g)$ , where  $M$  is a smooth manifold,  $\mathcal{D}$  is a subbundle of the tangent bundle, and  $g$  is a metric on  $\mathcal{D}$ . In the same way to Riemannian manifolds, we can put a length structure and the associated distance function on bracket generating sub-Riemannian manifolds (see [Definition 2.2](#)). Sub-Riemannian manifolds appear as Gromov–Hausdorff limits of sequences of Riemannian manifolds. In general their sectional, Ricci and scalar curvature diverge as they converge to (non-Riemannian) sub-Riemannian manifolds. However some sub-Riemannian manifolds have the measure contraction property which reflects the Ricci curvature lower bound in a sense [[Juillet 2009](#); [Rifford 2013](#); [Rizzi 2016](#); [Barilari and Rizzi 2018](#)]. These results lead us to study sub-Riemannian manifolds as examples of the singular Gromov–Hausdorff limit spaces.

In [[Tashiro 2020](#)], the author began to study the topological type of the Gromov–Hausdorff limit space of a sequence of (sub-)Riemannian manifolds. Here we use the notation (sub-)Riemannian metrics to cover both Riemannian and (non-Riemannian) sub-Riemannian metrics. Let  $H_n$  be the  $n$ -Heisenberg Lie group,  $\mathfrak{h}_n$  the associated Lie algebra, and  $\Gamma$  a lattice in  $H_n$ . A quotient space  $\Gamma \backslash H_n$  is called a *compact Heisenberg manifold*. Let  $\mathfrak{v}$  be a subspace in  $\mathfrak{h}_n$  and  $\langle \cdot, \cdot \rangle$  a scalar product on  $\mathfrak{v}$ . It induces the left-invariant sub-Riemannian structure on  $H_n$ . Since the induced geodesic distance on  $H_n$  has the isometric action  $\Gamma$  from the left, we obtain a quotient distance on  $\Gamma \backslash H_n$ . We also call such a quotient distance on  $\Gamma \backslash H_n$  *left-invariant*. The author studied noncollapsed limits of compact Heisenberg manifolds with left-invariant (sub-)Riemannian metrics. Here we say that a sequence is *noncollapsed* if

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the total measure with respect to Popp’s volume have a strictly positive lower bound. Popp’s volume is a generalization of a canonical volume form of a Riemannian manifold (see [Section 2C](#)). We showed that the noncollapsed limit of a sequence of compact Heisenberg manifolds with left-invariant (sub-)Riemannian metrics are again diffeomorphic to a compact Heisenberg manifold of the same dimension.

In this paper, we study collapsed Gromov–Hausdorff limits of compact Heisenberg manifolds with left-invariant (sub-)Riemannian metrics. We say that a sequence of (sub-)Riemannian manifolds *collapses* if the total measure with respect to Popp’s volume converges to zero. It complements our previous result [[Tashiro 2020](#)].

**Theorem 1.1** (Main result). *Let  $\{(\Gamma_k \backslash \mathbb{H}_n, \overline{\text{dist}}_k)\}_{k \in \mathbb{N}}$  be a sequence of compact Heisenberg manifolds endowed with left-invariant (sub-)Riemannian metrics. Assume that this sequence converges in the Gromov–Hausdorff topology with a diameter upper bound  $D > 0$  and the total measure with respect to Popp’s measure converges to zero. Then the limit space is isometric to a flat torus of lower dimension.*

The idea of the proof is the following. It is well known that a compact Heisenberg manifold has a circle bundle structure  $S^1 \rightarrow \Gamma \backslash \mathbb{H}_n \rightarrow \mathbb{T}^{2n}$ . We show that if a sequence collapses, then the circle fiber also collapses to a point. Once we show that the fibers collapse, then the Gromov–Hausdorff limit is isometric to the limit of the base tori with the quotient distances. It is also known that a Gromov–Hausdorff limit of tori with flat metrics is isometric to a flat torus [[Bettiol et al. 2018](#), Proposition 3.1]. This concludes the theorem.

## 2. Preliminaries from sub-Riemannian Lie group

In this section we prepare notation on sub-Riemannian metrics on Lie groups.

**2A. Sub-Riemannian structure.** Let  $G$  be a connected Lie group,  $\mathfrak{g}$  the associated Lie algebra,  $\mathfrak{v} \subset \mathfrak{g}$  a subspace and  $\langle \cdot, \cdot \rangle$  a scalar product on  $\mathfrak{v}$ . For  $x \in G$ , denote by  $L_x : G \rightarrow G$  the left translation by  $x$ . Define a sub-Riemannian metric on  $G$  by

$$\mathcal{D}_x = L_{x*} \mathfrak{v}, \quad g_x(u, v) = \langle L_{x*}^{-1} u, L_{x*}^{-1} v \rangle.$$

Such a sub-Riemannian metric  $(\mathcal{D}, g)$  is called *left-invariant*. We sometimes write a left-invariant sub-Riemannian metric by  $(\mathfrak{v}, \langle \cdot, \cdot \rangle)$ . Moreover, if  $\dim(\mathfrak{g}/\mathfrak{v}) = k$ , we say that a sub-Riemannian metric  $(\mathfrak{v}, \langle \cdot, \cdot \rangle)$  is corank  $k$ . Notice that if  $\mathfrak{v} = \mathfrak{g}$ , i.e., corank 0, then  $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$  is a Riemannian metric.

**Remark 2.1.** From now on we shall declare the corank of sub-Riemannian metrics. If we do not declare the corank, then the word “sub-Riemannian metric” cover sub-Riemannian metrics of all corank.

For simplicity, we shall consider a Lie group with a left-invariant sub-Riemannian metric  $(G, \mathfrak{v}, \langle \cdot, \cdot \rangle)$ . The associated distance function is given as follows. We say that an absolutely continuous path  $c : [0, 1] \rightarrow G$  is *admissible* if  $\dot{c}(t) \in L_{c(t)*}\mathfrak{v}$  a.e.  $t \in [0, 1]$ . We define the length of an admissible path by

$$\text{length}(c) = \int_0^1 \sqrt{\langle \dot{c}(t), \dot{c}(t) \rangle} dt.$$

For  $x, y \in G$ , define the distance function by

$$\text{dist}(x, y) = \inf\{\text{length}(c) \mid c(0) = x, c(1) = y, c \text{ is admissible}\}.$$

In general not every pair of points in  $G$  is joined by an admissible path. This implies that the value of the function  $\text{dist}$  may be the infinity. The following *bracket generating* condition ensures that any two points are joined by an admissible path.

**Definition 2.2** (bracket generating distribution). For a sub-Riemannian Lie group  $(G, \mathfrak{v}, \langle \cdot, \cdot \rangle)$  and an integer  $i \in \mathbb{N}$ , let  $\mathfrak{v}^i$  be the subspace in  $\mathfrak{g}$  inductively defined by

$$\mathfrak{v}^1 = \mathfrak{v}, \quad \mathfrak{v}^{i+1} = \mathfrak{v} + [\mathfrak{v}, \mathfrak{v}^i].$$

We say that a subspace  $\mathfrak{v}$  is bracket generating if there is  $r \in \mathbb{N}$  such that  $\mathfrak{v}^r = \mathfrak{g}$ . We say  $(G, \mathfrak{v}, \langle \cdot, \cdot \rangle)$  is  $r$ -step if  $\mathfrak{v}^{r-1} \subsetneq \mathfrak{v}^r = \mathfrak{g}$ .

**Theorem 2.3** (See, e.g., Theorem 3.31 in [Agrachev et al. 2020]). *Let  $(G, \mathfrak{v}, \langle \cdot, \cdot \rangle)$  be a sub-Riemannian Lie group with a bracket generating distribution. Then the following two assertions hold:*

- (1)  $(G, \text{dist})$  is a metric space.
- (2) The topology induced by  $\text{dist}$  is equivalent to the manifold topology.

In particular,  $\text{dist} : G \times G \rightarrow \mathbb{R}$  is continuous.

**Remark 2.4.** Since the sub-Riemannian structure is left-invariant, the distance function is also left-invariant, that is,  $\text{dist}(hx, hy) = \text{dist}(x, y)$  for all  $h, x, y \in G$ .

**2B. Length minimizer.** In sub-Riemannian geometry, there are two types of length minimizers; normal geodesics and abnormal geodesics. Normal geodesics are characterized as solutions to a specific differential equation, called the Hamiltonian equation. On the other hand, abnormal geodesics are not solutions to that equation. It sometimes appear in sub-Riemannian geometry, however, it is known that there is no nontrivial (i.e., nonconstant) abnormal geodesic if  $\mathfrak{v}$  is *fat* (see [Montgomery 2002]). Here we say that a bracket generating subspace  $\mathfrak{v} \subset \mathfrak{h}_n$  is fat if for all  $U \in \mathfrak{v} \setminus \{0\}$ , we have  $\mathfrak{v} + [U, \mathfrak{v}] = \mathfrak{g}$ . In the next section, we shall check that if  $G$  is the Heisenberg group, then every bracket generating subspace is fat. Therefore we omit the explanation of abnormal geodesics.

We say that a basis  $\{U_1, \dots, U_n\}$  of  $\mathfrak{g}$  is adapted if  $\{U_1, \dots, U_m\}$  is an orthonormal basis of a sub-Riemannian metric  $(\mathfrak{v}, \langle \cdot, \cdot \rangle)$ . Let  $H : T^*G \rightarrow \mathbb{R}$  be the function defined by

$$H(\lambda) = \frac{1}{2} \sum_{i=1}^m p(L_{x*}U_i)^2 \quad (\lambda = (x, p) \in T^*G).$$

This function is called the *sub-Riemannian Hamiltonian*.

We say that a Lipschitz curve  $\lambda = (x, p) : [0, T] \rightarrow T^*G$  is a solution to the Hamiltonian equation if it satisfies

$$(1) \quad \dot{x}(t) = \frac{\partial H}{\partial p}, \quad \dot{p}(t) = -\frac{\partial H}{\partial x}.$$

Such a curve  $\lambda(t)$  is called a *normal extremal*, and its projection  $x(t)$  is called a *normal geodesic*. It is known that every minimizer in sub-Riemannian manifold is either normal or abnormal geodesic. In particular, if a subspace  $\mathfrak{v}$  is fat, then any length minimizer is a normal geodesic.

**2C. Popp's volume.** On a Riemannian Lie group  $(G, g)$ , one has a canonical volume form defined by

$$d\text{vol}_R = \nu_1 \wedge \dots \wedge \nu_n,$$

where  $\{\nu_1, \dots, \nu_n\}$  is a dual coframe of an orthonormal basis. The induced measure  $m(\Omega) := \left| \int_{\Omega} d\text{vol}_R \right|$  ( $\Omega \subset G$ ) is called the *volume measure*.

In sub-Riemannian geometry, we also have a canonical volume form, called *Popp's volume* introduced in [Montgomery 2002]. For simplicity, we only consider the 2-step case.

We do not introduce the original definition of Popp's volume, however, we define it with local coordinates given in [Barilari and Rizzi 2013]. Let  $U_1, \dots, U_n$  be an adapted frame. Define the constant  $c_{ij}^l$  by

$$[U_i, U_j] = \sum_{l=1}^n c_{ij}^l U_l.$$

We call them the *structure constants*. We define the  $(n-m)$  square matrix  $B$  by

$$B_{hl} = \sum_{i,j=1}^m c_{ij}^h c_{ij}^l.$$

**Theorem 2.5** [Barilari and Rizzi 2013, Theorem 1]. *Let  $U_1, \dots, U_n$  be a local adapted frame, and  $\nu^1, \dots, \nu^n$  the dual coframe. Then Popp's volume  $d\text{vol}_{sR}$  is locally written by*

$$d\text{vol}_{sR} = (\det B)^{-\frac{1}{2}} \nu^1 \wedge \dots \wedge \nu^n.$$

The induced measure  $m(\Omega) := \left| \int_{\Omega} d\text{vol}_{sR} \right|$  ( $\Omega \subset G$ ) is called Popp's measure.

**Remark 2.6.** If a sub-Riemannian metric is corank 0, i.e., 1-step, then Popp’s volume coincides with the canonical volume form. Indeed, an adapted frame of corank 0 sub-Riemannian metric is an orthonormal basis.

### 3. Compact Heisenberg manifolds

In this section, we recall fundamental properties on compact Heisenberg manifolds.

**3A. Heisenberg groups.** For  $n \in \mathbb{N}$ , the  $n$ -Heisenberg group  $H_n$  is the  $(2n+1)$ -dimensional Lie group diffeomorphic to  $\mathbb{C}^n \times \mathbb{R}$  with the group product law

$$(w, z)(w', z') = (w + w', z + z' + \frac{1}{2}\Im(w \cdot w')),$$

where  $w \cdot w'$  is the Hermitian product on  $\mathbb{C}^n$  and  $\Im$  denotes the imaginary part. We shall denote the associated Lie algebra by  $\mathfrak{h}_n$ .

We fix the coordinates of  $H_n \simeq \mathbb{C}^n \times \mathbb{R}$  by

$$(w, z) = (x_1, \dots, x_n, y_1, \dots, y_n, z),$$

where  $w = \vec{x} + \vec{y}\sqrt{-1}$ . We also fix the basis  $\{X_1, \dots, X_n, Y_1, \dots, Y_n, Z\}$  of the Lie algebra  $\mathfrak{h}_n$  by

$$X_i = \partial_{x_i} - \frac{1}{2}y_i \partial_z, \quad Y_i = \partial_{y_i} + \frac{1}{2}x_i \partial_z, \quad Z = \partial_z.$$

A straightforward computation shows that  $[X_i, Y_i] = Z$  for all  $i = 1, \dots, n$  and the other brackets are zero.

For  $U \in \mathfrak{h}_n$ , let  $\phi_U^t : H_n \rightarrow H_n$  be the flow of the vector field  $U$  at time  $t$ . The exponential map  $\exp : \mathfrak{h}_n \rightarrow H_n$  is defined by  $\exp(U) := \phi_U^1(e)$ , where  $e$  is the identity element. It is well defined since a left-invariant vector field is complete. It is well known that the exponential map on the Heisenberg group is a diffeomorphism. This fact allows us to identify the Heisenberg group  $H_n$  to its Lie algebra  $\mathfrak{h}_n$  by

$$\exp : \mathfrak{h}_n \ni \sum_{i=1}^n (x_i X_i + y_i Y_i) + z Z \xrightarrow{\sim} (x_1, \dots, x_n, y_1, \dots, y_n, z) \in H_n.$$

Let  $(\mathfrak{v}, \langle \cdot, \cdot \rangle)$  be a left-invariant sub-Riemannian metric on  $H_n$ . A subspace  $\mathfrak{v}$  is bracket generating if and only if

$$(2) \quad \mathfrak{v} + \text{Span}(Z) = \mathfrak{h}_n.$$

In particular, the corank of a bracket generating subspace is 0 or 1. From now on we always assume the bracket generating condition (2). Moreover, by (2), we can easily check that if a subspace  $\mathfrak{v} \subset \mathfrak{h}_n$  satisfies bracket generating condition, then it is fat. Therefore the sub-Riemannian Heisenberg group does not have nontrivial abnormal minimizers.

Let  $\Gamma < H_n$  be a lattice in  $H_n$ , that is, a discrete cocompact subgroup. Since a sub-Riemannian metric  $(\mathfrak{v}, \langle \cdot, \cdot \rangle)$  is left-invariant, the left multiplication by  $\Gamma$  induces an isometric action on  $H_n$ . Therefore we can define the sub-Riemannian metric on  $\Gamma \backslash H_n$  via the quotient map. We shall denote such a quotient sub-Riemannian metric on  $\Gamma \backslash H_n$  by  $\overline{\text{dist}}$ .

**3B. Isometry classes of compact Heisenberg manifolds.** In this section, we consider isometry classes of left-invariant sub-Riemannian metrics on a compact Heisenberg manifold  $\Gamma \backslash H_n$ . The detail is in [Tashiro 2020].

First of all, we recall the isomorphism classes of compact Heisenberg manifolds. Let  $D_n$  be the set of  $n$ -tuples of integers  $\mathbf{r} = (r_1, \dots, r_n)$  such that  $r_i$  divides  $r_{i+1}$  for all  $i = 1, \dots, n$ . For  $\mathbf{r} \in D_n$ , let  $\Gamma_{\mathbf{r}} < H_n$  be the discrete subgroup defined by

$$\Gamma_{\mathbf{r}} = \langle r_1 X_1, \dots, r_n X_n, Y_1, \dots, Y_n, Z \rangle.$$

This gives a classification of lattices in the Heisenberg Lie group.

**Theorem 3.1** [Gordon and Wilson 1986, Theorem 2.4]. *For any uniform lattice  $\Gamma < H_n$ , there is an automorphism of  $H_n$  which sends  $\Gamma$  onto  $\Gamma_{\mathbf{r}}$  for some  $\mathbf{r} \in D_n$ . Moreover,  $\Gamma_{\mathbf{r}}$  is isomorphic to  $\Gamma_{\mathbf{s}}$  if and only if  $\mathbf{r} = \mathbf{s}$ .*

Next we consider isometry classes of  $\Gamma_{\mathbf{r}} \backslash H_n$  for a fixed lattice  $\Gamma_{\mathbf{r}}$ . Fix a scalar product  $\langle \cdot, \cdot \rangle_0$  on  $\mathfrak{h}_n$  such that its orthonormal basis is  $\{X_1, \dots, Y_n, Z\}$ . Let  $A$  be a matrix of the form

$$A = \begin{pmatrix} \tilde{A} & 0 \\ 0 & \rho_A \end{pmatrix},$$

where  $\tilde{A} \in \text{GL}_{2n}(\mathbb{R})$  and  $\rho_A \in \mathbb{R}$ . Moreover let  $J_n \in \text{Skew}_{2n}(\mathbb{R})$  be a skew-symmetric matrix given by

$$J_n = \begin{pmatrix} O & I_n \\ -I_n & O \end{pmatrix},$$

where  $I_n$  is the identity matrix of size  $n$ . We say that a matrix  $A$  is of *canonical form* if

$${}^t \tilde{A} J_n \tilde{A} = \begin{pmatrix} O & \text{diag}(d_1(A), \dots, d_n(A)) \\ -\text{diag}(d_1(A), \dots, d_n(A)) & O \end{pmatrix},$$

where  $d_1(A), \dots, d_n(A)$  are nondecreasing positive numbers such that the imaginary numbers  $\pm\sqrt{-1}d_1, \dots, \pm\sqrt{-1}d_n$  are the eigenvalues of  ${}^t \tilde{A} J_n \tilde{A}$ .

For a matrix  $A$  of canonical form, define the scalar product  $\langle \cdot, \cdot \rangle_A$  on  $\text{Im}(A)$  by the norm

$$\|u\|_A := \min\{\|w\|_0 \mid u = Aw\}.$$

It is equivalent to the following definition:  $\langle \cdot, \cdot \rangle_A$  is the scalar product which has an orthonormal basis  $\{\tilde{A}X_1, \dots, \tilde{A}Y_n, \rho_A Z\}$ . A pair  $(\text{Im}(A), \langle \cdot, \cdot \rangle_A)$  gives a sub-Riemannian metric on  $H_n$  of corank 0 (resp. corank 1) if  $\rho_A \neq 0$  (resp.  $\rho_A = 0$ ). If  $\rho_A = 0$ , then the subspace  $\text{Im}(A)$  is  $\mathfrak{v}_0$ , where

$$\mathfrak{v}_0 := \text{Span}\{X_1, \dots, X_n, Y_1, \dots, Y_n\}.$$

These types of metrics cover all isometry classes of left invariant (sub-)Riemannian metrics on compact Heisenberg manifolds.

**Theorem 3.2** [Tashiro 2020, Theorem 3.4]. *For any compact Heisenberg manifold with a bracket generating left-invariant sub-Riemannian metric  $(\Gamma \backslash H_n, \mathfrak{v}, \langle \cdot, \cdot \rangle)$ , there exists an  $n$ -tuple  $\mathbf{r} \in D_n$  and a matrix  $A$  of canonical form such that  $(\Gamma_r \backslash H_n, \text{Im}(A), \langle \cdot, \cdot \rangle_A)$  is isometric to  $(\Gamma \backslash H_n, \mathfrak{v}, \langle \cdot, \cdot \rangle)$ .*

We shall denote the induced left-invariant distance function on  $H_n$  by  $\text{dist}_A$  and a quotient distance on  $\Gamma \backslash H_n$  by  $\bar{\text{d}}\text{ist}_A$ .

**3C.  $j$ -operator.** We recall the  $j$ -operator which plays an important role in the study of nilpotent Lie groups. Let  $Z^* \in \mathfrak{h}_n^*$  be the dual covector of the vector  $Z \in [\mathfrak{h}_n, \mathfrak{h}_n] \subset \mathfrak{h}_n$ . For a matrix  $A$  of canonical form, define a skew symmetric operator  $j(A) : \mathfrak{v}_0 \rightarrow \mathfrak{v}_0$  by

$$\langle j(A)(X), Y \rangle_A = Z^*([X, Y]).$$

**Lemma 3.3** [Tashiro 2020, Lemma 4.1]. *The operator  $j(A) : \mathfrak{v}_0 \rightarrow \mathfrak{v}_0$  has a matrix representation  ${}^t\tilde{A}J_n\tilde{A}$  in the basis  $\{AX_1, \dots, AX_n, AY_1, \dots, AY_n\}$ .*

The positive number  $d_n$  can be regarded as the  $\ell^\infty$ -norm of the matrix  ${}^t\tilde{A}J_n\tilde{A}$  as an element in the Euclidean space  $\mathbb{R}^{4n^2}$ . We also mention its  $\ell^2$ -norm, the Hilbert–Schmidt norm of matrices.

**Definition 3.4.** For a matrix  $A$  of canonical form, we define  $\delta(A) = \|{}^t\tilde{A}J_n\tilde{A}\|_{HS}$ .

The following lemma is useful for later calculations.

**Lemma 3.5** [Tashiro 2020, Lemma 5.1]. *For a matrix  $A$  of canonical form, we have*

- (1)  $\delta(A) = \sqrt{2 \sum_{i=1}^n d_i(A)^2}$ ,
- (2)  $|\det(\tilde{A})| = \prod_{i=1}^n d_i(A)$ .

**3D. Geodesics on Heisenberg groups.** Let  $A$  be a matrix of canonical form. For  $i = 1, \dots, n$ , define the functions  $h_{x_i}, h_{y_i}, h_z : T^*H_n \rightarrow \mathbb{R}$  by

$$h_{x_i}(\lambda) = p(L_{g^*}AX_i), \quad h_{y_i}(\lambda) = p(L_{g^*}AY_i), \quad h_z(p) = p(L_{g^*}Z)$$



for  $\lambda = (g, p) \in T^*\mathbf{H}_n$ . Suppose that an admissible path

$$\gamma(t) = \sum_{i=1}^n x_i(t)AX_i + y_i(t)AY_i + z(t)Z$$

is length minimizing. By the Hamiltonian equation (1) with a linear modification, there is a lift  $\lambda(t)$  of  $\gamma(t)$  such that

$$\begin{cases} \dot{h}_{x_i} = d_i(A)h_z h_{y_i} & (i = 1, \dots, n), \\ \dot{h}_{y_i} = -d_i(A)h_z h_{x_i} & (i = 1, \dots, n), \\ \dot{h}_z = 0, \\ \dot{x}_i = h_{x_i} & (i = 1, \dots, n), \\ \dot{y}_i = h_{y_i} & (i = 1, \dots, n), \\ \dot{z} = \frac{1}{2} \sum_{i=1}^n d_i(A)(x_i h_{y_i} - y_i h_{x_i}) + \rho_A^2 p_z, \end{cases}$$

where we write

$$h_{x_i}(t) = h_{x_i} \circ \lambda(t), \quad h_{y_i}(t) = h_{y_i} \circ \lambda(t), \quad h_z(t) = h_z \circ \lambda(t).$$

By proving this equation, we obtain the following parametrization of length minimizers.

**Lemma 3.6** ([Eberlein 1994, Proposition 3.5] for corank 0 and [Rizzi 2016, Lemma 14] for corank 1 cases). *Let  $A$  be a matrix of canonical form and  $\lambda: [0, T] \rightarrow T^*\mathbf{H}_n$  be the normal extremal with the initial data*

$$(h_{x_1}(0), \dots, h_{y_n}(0), h_z(0)) = (p_{x_1}, \dots, p_{y_n}, p_z) \in T_e^*\mathbf{H}_n = \mathfrak{h}_n^*.$$

*Then the associated normal geodesic  $\gamma$  is given as follows.*

*If  $p_z \neq 0$ , then*

$$\begin{aligned} \begin{pmatrix} x_i(t) \\ y_i(t) \end{pmatrix} &= \frac{1}{p_z d_i(A)} \begin{pmatrix} \sin(p_z d_i(A)t) & \cos(p_z d_i(A)t) - 1 \\ -\cos(p_z d_i(A)t) + 1 & \sin(p_z d_i(A)t) \end{pmatrix} \begin{pmatrix} p_{x_i} \\ p_{y_i} \end{pmatrix}, \\ z(t) &= \rho_A^2 p_z t + \frac{1}{2p_z} \sum_{i=1}^n \left( t - \frac{1}{p_z d_i(A)} \sin(p_z d_i(A)t) \right) (p_{x_i}^2 + p_{y_i}^2). \end{aligned}$$

*Moreover, the normal geodesic fails to be length minimizing over the time*

$$T = \frac{2\pi}{|p_z| d_{i_m}(A)},$$

*where  $i_m \in \{1, \dots, n\}$  is the minimum integer such that  $(p_{x_i}, p_{y_i}) \neq (0, 0)$ .*

*If  $p_z = 0$ , then*

$$\begin{pmatrix} x_i(t) \\ y_i(t) \end{pmatrix} = \begin{pmatrix} p_{x_i} \\ p_{y_i} \end{pmatrix} t, \quad z(t) \equiv 0.$$

**Remark 3.7.** The initial data  $(p_{x_1}, \dots, p_{y_n})$  is identified with the projection of initial vector into  $\mathfrak{v}_0 \subset \mathfrak{h}_n = T_e \mathbf{H}_n$  via the identification

$$\mathbb{R}^{2n} \ni (p_{x_1}, \dots, p_{y_n}) \simeq \sum_{i=1}^n (p_{x_i} A X_i + p_{y_i} A Y_i) \in \mathfrak{v}_0.$$

For later arguments, we give an explicit distance from the identity to points in the horizontal direction and the vertical direction.

**Lemma 3.8** ([Eberlein 1994, Proposition 3.11] for corank 0 and [Tashiro 2020, Lemma 5.2] for corank 1 cases). *For  $U \in \mathfrak{v}_0$  and  $V \in [\mathfrak{h}_n, \mathfrak{h}_n]$ , we have*

$$\text{dist}_A(e, U + V) \geq \|U\|_A.$$

*Moreover, the equality holds if and only if  $V = 0$ .*

**Lemma 3.9.** *For  $z_0 \in \mathbb{R}$ , the distance from  $e$  to  $z_0 Z = (0, \dots, 0, z_0) \in \mathbf{H}_n$  is given by*

$$\text{dist}_A(e, z_0 Z) = \min \left\{ \left| \frac{z_0}{\rho_A} \right|, \frac{2}{d_n(A)} \sqrt{|z_0| \pi d_n(A) - \pi^2 \rho_A^2} \right\},$$

*with the convention*

$$\begin{cases} \left| \frac{z_0}{\rho_A} \right| = +\infty & \text{if } \rho_A = 0, \\ \frac{2}{d_n(A)} \sqrt{|z_0| \pi d_n(A) - \pi^2 \rho_A^2} = +\infty & \text{if } |z_0| \pi d_n(A) - \pi^2 \rho_A^2 < 0. \end{cases}$$

*Proof.* For the simplicity we assume  $z_0 > 0$ . First let us consider a unit speed geodesic of the initial data  $(0, \dots, 0, p_z)$ . Then a unit speed normal geodesic  $\gamma : [0, T] \rightarrow \mathbf{H}_n$  with  $\gamma(T) = z_0 Z$  needs to satisfy

$$\begin{cases} z(T) = \rho_A^2 p_z T = z_0, \\ |p_z \rho_A| = 1 \end{cases}$$

Then the length is equal to the time  $T = |z_0/\rho_A|$  with the convention  $|z_0/\rho_A| = +\infty$  if  $\rho_A = 0$ , i.e., sub-Riemannian metric of corank 1.

Next we consider geodesics of the initial data  $(p_{x_1}, \dots, p_{y_n}) \neq 0$ . Since the endpoint  $z_0 Z$  is in the center  $[\mathfrak{h}_n, \mathfrak{h}_n]$ , the initial data  $(p_{x_1}, \dots, p_{y_n}) \in \mathbb{R}^{2q} \simeq \mathfrak{v}_0$  need to be inside the eigenspace of  $\pm \sqrt{d_i(A)}$  of  $j_A$  (with the multiplicity), where we use the identification

$$\mathbb{R}^{2n} \ni (p_{x_1}, \dots, p_{y_n}) \simeq \sum_{i=1}^n (p_{x_i} A X_i + p_{y_i} A Y_i) \in \mathfrak{v}_0.$$

Indeed, by the parametrization of  $x_i(t), y_i(t)$  in Lemma 3.6, the geodesic ends at  $[\mathfrak{h}_n, \mathfrak{h}_n]$  only if the frequency of the trigonometric function is the same. Moreover, its length  $T = 2\pi/(|p_z| d_i(A))$  is independent of the choice of the initial data

$(p_{x_1}, \dots, p_{y_n})$  as long as it belongs to the same eigenspace. Therefore we can assume that the initial covector is  $(0, \dots, 0, p_{y_i}, 0, \dots, 0, p_z)$ . If such a normal geodesic is unit speed and its endpoint is  $z_0 Z$ , then it needs to satisfy

$$\begin{cases} z(T) = \frac{2\pi\rho_A^2}{d_i(A)} + \frac{\pi}{p_z^2 d_i(A)} p_{y_i}^2 = z_0, \\ p_{y_i}^2 + (\rho_A p_z)^2 = 1. \end{cases}$$

This equation has a solution only if  $z_0 \geq 2\pi\rho_A^2/d_i(A)$  with

$$p_{y_i} = \sqrt{\frac{z_0 d_i(A) - 2\pi\rho_A^2}{z_0 d_i(A) - \pi\rho_A^2}}, \quad p_z = \sqrt{\frac{\pi}{z_0 d_i(A) - \pi\rho_A^2}}.$$

Its length is

$$\frac{2\pi}{p_z d_i(A)} = \frac{2\sqrt{\pi}}{d_i(A)} \sqrt{z_0 d_i(A) - \pi\rho_A^2}.$$

Therefore the distance from  $e$  to  $z_0 Z = (0, \dots, 0, z_0)$  is the minimum of two values

$$\begin{aligned} \min \left\{ \left| \frac{z_0}{\rho_A} \right|, \frac{2\sqrt{\pi}}{d_1(A)} \sqrt{z_0 d_1(A) - \pi\rho_A^2}, \dots, \frac{2\sqrt{\pi}}{d_n(A)} \sqrt{z_0 d_n(A) - \pi\rho_A^2} \right\} \\ = \min \left\{ \left| \frac{z_0}{\rho_A} \right|, \frac{2\sqrt{\pi}}{d_n(A)} \sqrt{z_0 d_n(A) - \pi\rho_A^2} \right\}, \end{aligned}$$

where we use  $d_1(A) \leq \dots \leq d_n(A)$ .  $\square$

**3E. Popp's volume form on Heisenberg group.** In this section, we discuss Popp's volume form on the Heisenberg Lie group.

For a matrix  $A$  of canonical form with  $\rho_A \neq 0$ , denote by  $\text{dvol}_R(A)$  the canonical Riemannian volume form. Since it is the wedge of the dual coframe of an orthonormal frame, we have

$$\text{dvol}_R(A) = \rho_A^{-1} (\det \tilde{A})^{-1} X_1^* \wedge \dots \wedge Y_n^* \wedge Z^*.$$

In particular, the total measure of a Riemannian compact Heisenberg manifold  $(\Gamma_r \backslash \mathbb{H}_n, \langle \cdot, \cdot \rangle_A)$  is

$$(3) \quad \text{meas}(\Gamma_r \backslash \mathbb{H}_n, \langle \cdot, \cdot \rangle_A) := \left| \int_{\Gamma_r \backslash \mathbb{H}_n} \text{dvol}_R(A) \right| = \prod_{i=1}^n r_i |\rho_A^{-1} (\det \tilde{A})^{-1}|.$$

Next let  $A$  be a matrix of canonical form with  $\rho_A = 0$ . Denote by  $\text{dvol}_{sR}(A)$  Popp's volume associated to the sub-Riemannian metric  $(\mathfrak{v}_0, \langle \cdot, \cdot \rangle_A)$ .

By the definition, the  $(i, j)$ -th entry of the matrix  ${}^t \tilde{A} J_n \tilde{A}$  is the structure constant  $c_{ij}$  of the basis  $\{AX_1, \dots, AY_n\}$ , that is

$$\begin{pmatrix} Z^*([AX_i, AX_j]) & Z^*([AX_i, AY_{j-n}]) \\ Z^*([AY_{i-n}, AX_j]) & Z^*([AY_{i-n}, AY_{j-n}]) \end{pmatrix} \\ = (c_{ij}) = {}^t \tilde{A} J_n \tilde{A} = \begin{pmatrix} O & \text{diag}(d_1(A), \dots, d_n(A)) \\ -\text{diag}(d_1(A), \dots, d_n(A)) & O \end{pmatrix}.$$

By [Theorem 2.5](#), Popp's volume  $\text{dvol}_{sR}(A)$  is written by

$$\text{dvol}_{sR}(A) = \delta(A)^{-1} (\det \tilde{A})^{-1} X_1^* \wedge \dots \wedge Y_n^* \wedge Z^*.$$

In particular, the total measure of a sub-Riemannian compact Heisenberg manifold  $(\Gamma_r \backslash \mathbb{H}_n, \mathfrak{v}_0, \langle \cdot, \cdot \rangle_A)$  is

$$(4) \quad \text{meas}(\Gamma_r \backslash \mathbb{H}_n, \mathfrak{v}_0, \langle \cdot, \cdot \rangle_A) := \left| \int_{\Gamma_r \backslash \mathbb{H}_n} \text{dvol}_{sR}(A) \right| = \prod_{i=1}^n r_i |\delta(A)^{-1} (\det \tilde{A})^{-1}|.$$

**3F. The circle bundle structure.** Fix a  $n$ -tuple of numbers  $\mathbf{r} \in D_n$ . We recall a circle bundle structure of a compact Heisenberg manifold  $\Gamma_r \backslash \mathbb{H}_n$ . Let  $P : \mathbb{H}_n \rightarrow \mathfrak{h}_n \rightarrow \mathfrak{v}_0$  be the composition of the logarithm map and the projection. Denote the image of the lattice  $\Gamma_r$  by  $\mathfrak{z}_r$ , which is again a lattice in  $\mathfrak{v}_0$  isomorphic to  $\mathbb{Z}^{2n}$ . Then one obtains a surjective map  $\bar{P} : \Gamma_r \backslash \mathbb{H}_n \rightarrow \mathfrak{z}_r \backslash \mathfrak{v}_0$  such that the following diagram is commutative:

$$\begin{array}{ccc} \mathbb{H}_n & \xrightarrow{P} & \mathfrak{v}_0 \\ P_{\Gamma_r} \downarrow & & \downarrow P_{\mathfrak{z}_r} \\ \Gamma_r \backslash \mathbb{H}_n & \xrightarrow{\bar{P}} & \mathfrak{z}_r \backslash \mathfrak{v}_0 \end{array}$$

Here the vertical arrows are the quotient map. The compact Heisenberg manifold  $\Gamma_r \backslash \mathbb{H}_n$  has a circle bundle structure by this map  $\bar{P}$ . For each  $b \in \mathfrak{z}_r \backslash \mathfrak{v}_0$ , we denote by  $F_b$  the fiber over  $b$ .

**Remark 3.10.** Since a sub-Riemannian metric  $\langle \cdot, \cdot \rangle_A$  is left-invariant, the diameter of a fiber is independent of the choice of a base point  $b$ . We shall denote the diameter of a fiber by  $\text{diam}(F_A)$ .

The quotient metric on  $\mathfrak{v}_0$  has an orthonormal basis  $\{\tilde{A}X_1, \dots, \tilde{A}X_{2n}\}$ . Therefore we shall denote the induced distance on  $\mathfrak{v}_0$  by  $\text{dist}_{\tilde{A}}$ , and the quotient distance on  $\mathfrak{z}_r \backslash \mathfrak{v}_0$  by  $\overline{\text{dist}}_{\tilde{A}}$ . In the next section, we use the circle bundle structure to show that the Gromov–Hausdorff limit of compact Heisenberg manifolds is isometric to that of the base flat tori.

#### 4. Gromov–Hausdorff limits of compact Heisenberg manifolds

**4A. Collapse of the circle fiber.** We say that a sequence of compact metric spaces  $\{M_k\}$  converges to a compact metric space  $N$  if the Gromov–Hausdorff distance  $d_{GH}(M_k, N)$  converges to 0. We do not use the original definition of  $d_{GH}$  since it is complicated. Instead of the original definition, we use the  $\epsilon$ -approximation map which is easier to compute.

**Definition 4.1** [Fukaya 1990, Definition 1.1]. Let  $(M, d_M), (N, d_N)$  be a compact path metric spaces. For  $\epsilon > 0$ , we say a map  $\phi : M \rightarrow N$  is an  $\epsilon$ -Hausdorff approximation if it satisfies the following:

- (i) The  $\epsilon$  neighborhood of  $\phi(M)$  in  $N$  is  $N$ .
- (ii) For  $u, v \in M$ . we have

$$|d_M(u, v) - d_N(\phi(u), \phi(v))| < \epsilon.$$

It is known that if there is  $\epsilon$ -Hausdorff approximation map between  $M, N$ , then  $d_{GH}(M, N) < 2\epsilon$ . Therefore if a metric space  $M_k$  has an  $\epsilon_k$ -approximation to  $N$  such that  $\epsilon_k \rightarrow 0$ , then the sequence  $\{M_k\}$  converges to  $N$  in the Gromov–Hausdorff topology.

We can check that the quotient map  $\bar{P}$  is an  $\epsilon$ -approximation with  $\epsilon$  equal to the diameter of the fiber.

**Lemma 4.2.** *The quotient map  $\bar{P} : (\Gamma_r \backslash H_n, \overline{\text{dist}}_A) \rightarrow \mathfrak{z}_r \backslash (\mathfrak{v}_0, \overline{\text{dist}}_{\tilde{A}})$  is a  $2 \text{diam}(F_A)$ -approximation map.*

*Proof.* Since the map  $\bar{P}$  is surjective, we only need to check the almost isometric embeddability (Definition 4.1(ii)).

Let  $u_1, u_2 \in \Gamma_r \backslash H_n$  be points in the compact Heisenberg manifold. By definition of the distance on the quotient space, there are  $v_1, v_2 \in \Gamma_r \backslash H_n$  such that

$$\overline{\text{dist}}_A(v_1, v_2) = \overline{\text{dist}}_{\tilde{A}}(\bar{P}(u_1), \bar{P}(u_2)).$$

By the triangle inequality, we have

$$\begin{aligned} |\overline{\text{dist}}_A(u_1, u_2) - \overline{\text{dist}}_{\tilde{A}}(\bar{P}(u_1), \bar{P}(u_2))| &\leq \overline{\text{dist}}_A(u_1, v_1) + \overline{\text{dist}}_A(u_2, v_2) \\ &\leq 2 \text{diam}(F). \end{aligned}$$

This proves almost isometric embeddability. □

**Proposition 4.3.** *Let  $(\Gamma_{r(k)} \backslash H_n, \overline{\text{dist}}_{A_k})$  be a sequence of compact Heisenberg manifolds which has a uniform upper bound of the diameter. Assume that the diameter of the fibers  $\text{diam}(F_{A_k})$  converges to 0. Then its Gromov–Hausdorff limit is isometric to that of base flat tori  $(\mathfrak{z}_r \backslash \mathfrak{v}_0, \overline{\text{dist}}_{\tilde{A}_k})$ .*

*In particular, the limit is isometric to a flat torus of lower dimension.*

*Proof.* Since the diameter of the base flat tori is also uniformly bounded, we can assume that the sequence of base flat tori subconverges to a flat torus  $(N, d)$  (possibly a point). It is a consequence of [Bettiol et al. 2018, Proposition 3.1]. Then there are  $\epsilon_k$ -approximation map  $\varphi_k : (\mathfrak{zr} \setminus \mathfrak{v}_0, \overline{\text{dist}}_{A_k}) \rightarrow (N, d)$ . By Lemma 4.2, the composition  $\varphi_k \circ \bar{P}$  is  $(2 \text{diam}(F_{A_k}) + \epsilon_k)$ -approximation. By the assumption, the Gromov–Hausdorff limit of  $(\Gamma_{r(k)} \setminus \mathbb{H}_n, \overline{\text{dist}}_{A_k})$  is isometric to  $(N, d)$ .  $\square$

**4B. Collapse of the fiber.** Let  $\{(\Gamma_{r(k)} \setminus \mathbb{H}_n, \overline{\text{dist}}_{A_k})\}$  be a sequence of compact sub-Riemannian Heisenberg manifolds with the diameter upper bound by  $D > 0$ . In this section, we show that if the sequence collapses, then the diameter of the circle fibers converge to zero.

The fiber over  $b \in \mathfrak{zr} \setminus \mathfrak{v}_0$  is written by  $F_b = \{\Gamma_{r(k)} z_0 Z \cdot h_b \mid z_0 \in \mathbb{R}\}$ , where we fix  $h_b \in P_{\Gamma_{r(k)}}^{-1}(\bar{P}^{-1}(b)) \subset \mathbb{H}_n$ . In particular, the subset  $\{z_0 Z \cdot h_b \mid z_0 \in [0, 1)\} \subset \mathbb{H}_n$  is a representative of  $F_b$ . By the left-invariance of the restricted distance on  $F_b$ , its diameter is the distance from  $h_b$  to  $\frac{1}{2}Z \cdot h_b$  and is independent of the choice of  $h_b$ .

The above argument shows the following lemma.

**Lemma 4.4.** *The diameter of the fibers  $\text{diam}(F_{A_k})$  is given by*

$$\text{diam}(F_{A_k}) = \text{dist}_{A_k}\left(e, \frac{1}{2}Z\right).$$

Let us pass to the estimate of the diameter. First we consider a sequence  $\{\Gamma_{r(k)}\}_{k \in \mathbb{N}}$  such that  $r(k_1) \neq r(k_2)$  for any  $k_1 \neq k_2$ . This implies that the sequence of numbers  $\{r_n(k)\}$  diverges.

**Proposition 4.5.** *Assume that  $\text{diam}(\Gamma_{r(k)} \setminus \mathbb{H}_n, \langle \cdot, \cdot \rangle_{A_k}) \leq D$  and  $r_n(k)$  diverge to the infinity. Then the diameter of the fibers  $\text{diam}(F_{A_k})$  converge to zero.*

*Proof.* Let  $\gamma_{n,k} = \frac{1}{2}r_n(k)X_n \in \mathbb{H}_n$ . Since  $\gamma_{n,k}$  is on the plane  $\mathfrak{v}_0$ , by Lemma 3.8, a length minimizer from  $e$  to  $\gamma_{n,k}$  in  $\mathbb{H}_n$  is the straight segment  $\ell(t) := tX_n$ ,  $t \in [0, \frac{1}{2}r_n(k)]$ . Moreover its projection by  $P_{\Gamma_{r(k)}}$  is a length minimizer from  $\Gamma_{r(k)}e$  to  $\Gamma_{r(k)}\gamma_{n,k}$ . Indeed, any element in  $\Gamma_{r(k)}\gamma_{n,k}$  is written by

$$r_n(k)\left(m + \frac{1}{2}\right)X_n + E,$$

where  $m \in \mathbb{Z}$  and  $E$  is an element in  $\mathfrak{h}_n \simeq \mathbb{H}_n$  transverse to  $X_n$ . Clearly a length minimizer from  $\Gamma_{r(k)}e$  to  $\Gamma_{r(k)}\gamma_{n,k}$  is realized when

$$m = 0, -1 \quad \text{and} \quad E = 0.$$

This shows that the projection of the straight segment  $\ell(t)$  is length minimizing in  $\Gamma_r \setminus \mathbb{H}_n$ .

Since the length of the straight segment  $\ell(t)$  is  $\left\| \frac{1}{2}r_n(k)X_n \right\|_{A_k}$ , we obtain

$$(5) \quad \begin{aligned} \left\| \frac{1}{2}r_n(k)X_n \right\|_{A_k} &= \text{dist}_{A_k}(e, \gamma_{n,k}) = \overline{\text{dist}}_{A_k}(\Gamma_{r(k)}e, \Gamma_{r(k)}\gamma_{n,k}) \\ &\leq \text{diam}(\Gamma_{r(k)} \setminus \mathbb{H}_n, \overline{\text{dist}}_{A_k}) \leq D. \end{aligned}$$

By the same argument we also show that

$$(6) \quad \left\| \frac{1}{2} Y_n \right\|_{A_k} \leq D.$$

On the other hand, let  $c : [0, 4] \rightarrow H_n$  be a path inductively defined by

$$c(t) = \begin{cases} -t \sqrt{\frac{r_n(k)}{2}} X_n & \text{for } t \in [0, 1], \\ c(1) \cdot \left( -(t-1) \frac{1}{\sqrt{2r_n(k)}} Y_n \right) & \text{for } t \in [1, 2], \\ c(2) \cdot \left( (t-2) \sqrt{\frac{r_n(k)}{2}} X_n \right) & \text{for } t \in [2, 3], \\ c(3) \cdot \left( (t-3) \frac{1}{\sqrt{2r_n(k)}} Y_n \right) & \text{for } t \in [3, 4]. \end{cases}$$

The endpoint of  $c$  is  $c(4) = \frac{1}{2} Z$ , and the length is

$$\begin{aligned} \text{length}(c) &= \left\| \sqrt{2r_n(k)} X_n \right\|_{A_k} + \left\| \sqrt{\frac{2}{r_n(k)}} Y_n \right\|_{A_k} \\ &= \sqrt{2r_n(k)} \|X_n\|_{A_k} + \sqrt{\frac{2}{r_n(k)}} \|Y_n\|_{A_k} \\ &\leq \sqrt{2r_n(k)} \frac{2D}{r_n(k)} + \sqrt{\frac{2}{r_n(k)}} 2D \\ &= \frac{4\sqrt{2}D}{\sqrt{r_n(k)}}. \end{aligned}$$

Here the third inequality follows from (5) and (6). Hence we obtain

$$\text{diam}(F_{A_k}) = \text{dist}_{A_k} \left( e, \frac{1}{2} Z \right) \leq \text{length}(c) \leq \frac{4\sqrt{2}D}{\sqrt{r_n(k)}}.$$

Since  $r_n(k)$  diverges to the infinity, the diameters of the fibers converge to zero.  $\square$

Next we consider a sequence consisting of a fixed isomorphism type  $\Gamma_r \backslash H_n$ . We start from Riemannian case.

**Proposition 4.6.** *Let  $\{\Gamma_r \backslash H_n, \overline{\text{dist}}_{A_k}\}$  be a sequence of compact Heisenberg manifolds with left-invariant Riemannian metrics with the diameter upper bound. If the total measure in the canonical Riemannian volume converges to zero, then the diameter of the fibers  $\text{diam}(F_{A_k})$  converges to zero.*

*Proof.* By (3), if the total measure converges to zero, then either/both of the following two cases holds:

- (a)  $|\rho_{A_k}|^{-1} \rightarrow 0$ , or
- (b)  $|\det(\tilde{A}_k)|^{-1} \rightarrow 0$ .

In the case (a), by using Lemmas 3.9 and 4.4, we have

$$\begin{aligned} \text{diam}(F_{A_k}) &= \text{dist}_{A_k}(e, \tfrac{1}{2}Z) = \min \left\{ \left| \frac{1}{2\rho_{A_k}} \right|, \frac{2}{d_n(A_k)} \sqrt{\frac{\pi d_n(A_k)}{2} - \pi^2 \rho_{A_k}^2} \right\} \\ &\leq \left| \frac{1}{2\rho_{A_k}} \right| \rightarrow 0 \quad (k \rightarrow \infty). \end{aligned}$$

In the case (b), by using Lemmas 3.5, 3.9 and 4.4, we have

$$\begin{aligned} \text{diam}(F_{A_k}) &= \min \left\{ \left| \frac{1}{2\rho_{A_k}} \right|, \frac{2}{d_n(A_k)} \sqrt{\frac{\pi d_n(A_k)}{2} - \pi^2 \rho_{A_k}^2} \right\} \leq \sqrt{\frac{2\pi}{d_n(A_k)}} \\ &\leq \sqrt{\frac{2\pi}{\sqrt[n]{|\det(\tilde{A}_k)|}}} \rightarrow 0 \quad (k \rightarrow \infty). \end{aligned}$$

In both cases, the diameter of the fiber  $\text{diam}(F_{A_k})$  converges to zero. This concludes the proposition.  $\square$

A similar argument follows also for sub-Riemannian metrics of corank 1.

**Proposition 4.7.** *Let  $\{\Gamma_r \backslash \mathbb{H}_n, \overline{\text{dist}}_{A_k}\}$  be a sequence of compact Heisenberg manifolds with left-invariant sub-Riemannian metrics of corank 1. If the total measure in Popp's volume converges to zero, then the diameter of the fibers converges to zero.*

*Proof.* By (4), if the total measure converges to zero, then either/both of the following two cases holds:

- (a)  $\delta(A_k)^{-1} \rightarrow 0$ , or
- (b)  $|\det(\tilde{A}_k)|^{-1} \rightarrow 0$ .

In the case (a), by using Lemmas 3.5, 3.9 and 4.4, we have

$$\begin{aligned} \text{diam}(F_{A_k}) &= \text{dist}_{A_k}(e, \tfrac{1}{2}Z) = \min \left\{ +\infty, \frac{2}{d_n(A_k)} \sqrt{\frac{\pi d_n(A_k)}{2}} \right\} \\ &= \sqrt{\frac{2\pi}{d_n(A_k)}} \leq \frac{2\sqrt{n\pi}}{\delta(A_k)} \rightarrow 0 \quad (k \rightarrow \infty). \end{aligned}$$

In the case (b), again by using Lemmas 3.5, 3.9 and 4.4, we have

$$\text{diam}(F_{A_k}) = \sqrt{\frac{2\pi}{d_n(A_k)}} \leq \sqrt{\frac{2\pi}{\sqrt[n]{|\det(\tilde{A}_k)|}}} \rightarrow 0 \quad (k \rightarrow \infty).$$

In both cases, the diameter of the fiber  $\text{diam}(F_{A_k})$  converges to zero. This concludes the proposition.  $\square$

Now we are prepared to prove the main theorem.



*Proof of Theorem 1.1.* Suppose that there are infinitely many isomorphic classes of lattices  $\Gamma_{r_k}$  in the sequence. Then by [Proposition 4.5](#), the diameter of the fibers converges to 0, and by [Proposition 4.3](#), the Gromov–Hausdorff limit is isometric to a flat torus of lower dimension.

Assume there are finitely many isomorphic classes of lattices in the sequence. By taking a subsequence, we can assume that the lattices are isomorphic to  $\Gamma_r$  for a fixed  $r$  in  $D_n$ . By [Propositions 4.6](#) and [4.7](#), if the total measure converges to 0, then the diameter of the fiber converges to 0. Again by [Proposition 4.3](#), the Gromov–Hausdorff limit is isometric to a flat torus of lower dimension.  $\square$

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